Searching for new physics with ATLAS Rough guide to data analysis

Roland Jansky, University of Geneva

Teacher Program - 16th July 2019



Overview



- LHC and ATLAS detector
- Physics objects
- Analysis Boosted diboson search
- Summary Discussion

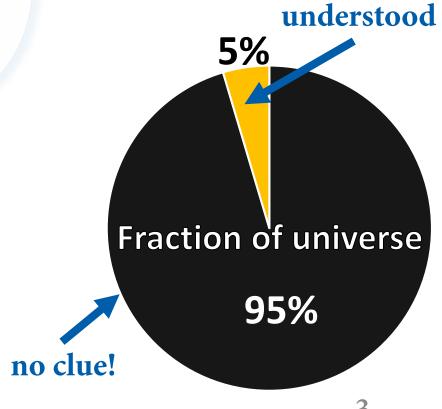


Roughly

- Ever wondered ..
 - .. what am I and everything around me made of?
 - .. how was our universe created?

.. and what is it made of?

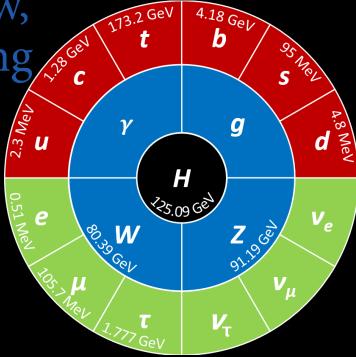
We do!
 This is why we do particle physics.





What particles?

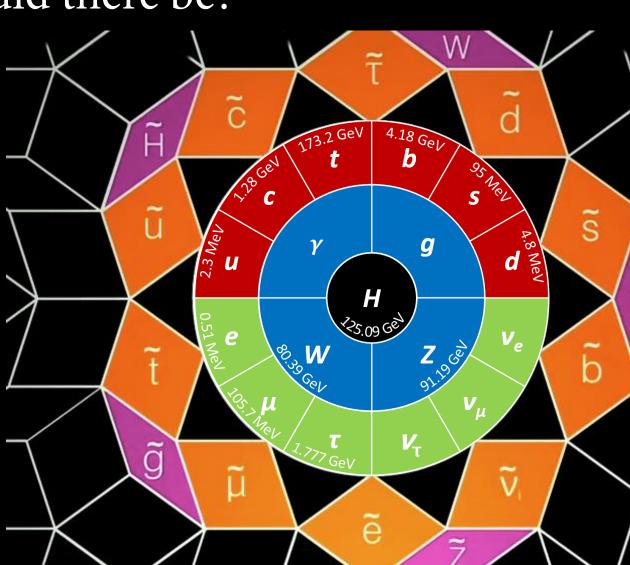
• These particles we know, and they are the building block of the 5%





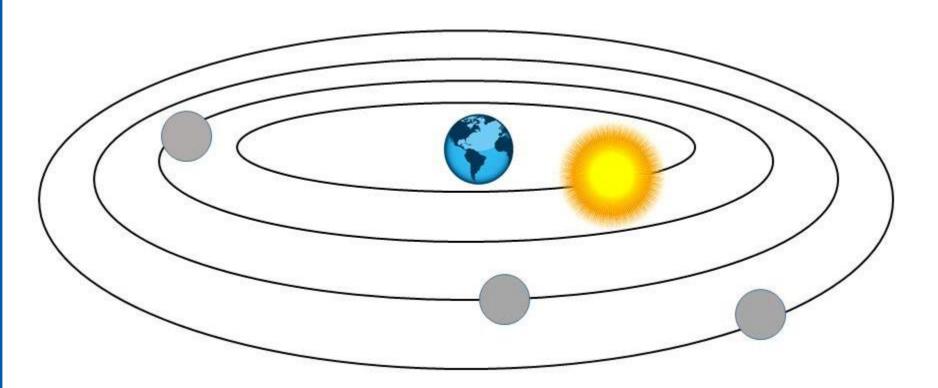
• What else could there be?

• Are these the 95%?





• Sun goes around earth, earth around sun... sounds all the same to me.



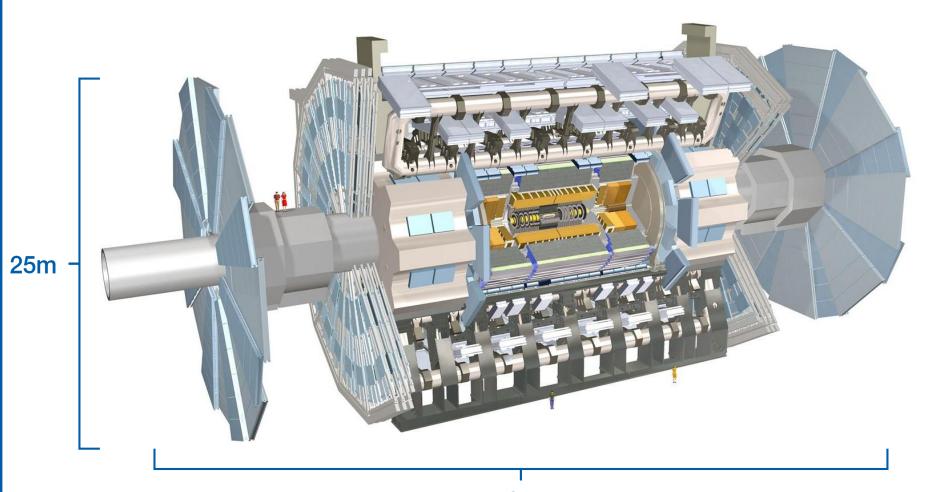
Large Hadron Collider





ATLAS Detector





Physics Objects

ATLAS Detector & Objects





Missing energy

• Hadronic jet

Neutrino Proton Neutron Muon Electromagnetic Calorimeter Electron Solenoid magnet Photon **Transition** Radiation Tracking Tracker Pixel/SCT detector

ATLAS Detector & Objects

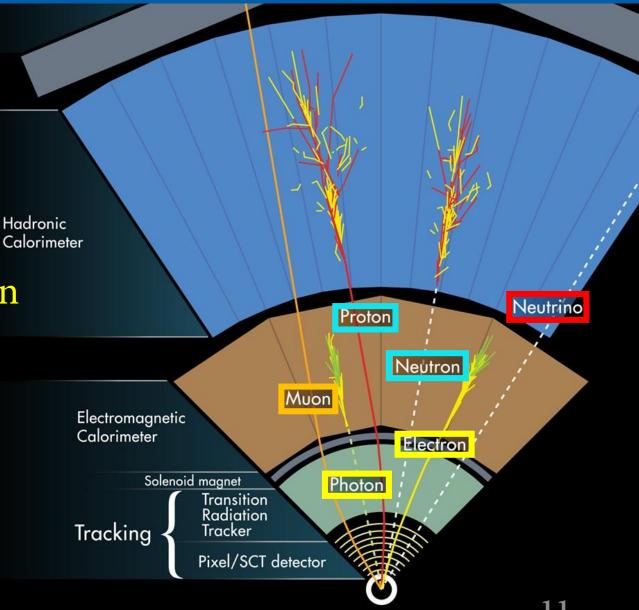


Physic objects:

- Muon
- Electron/Photon
- Hadronic jet
- Missing energy

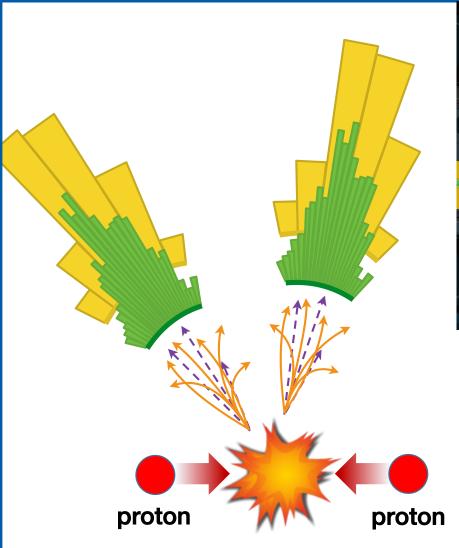
Build from:

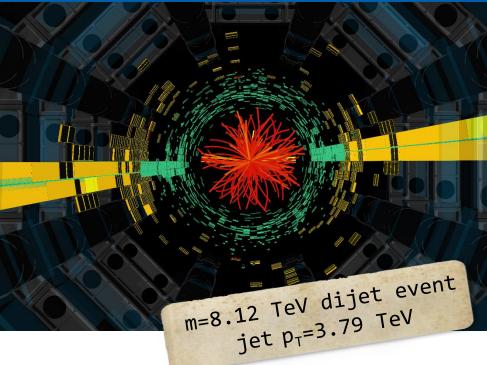
- Jets
- Tracks



Energy Frontier: Jets





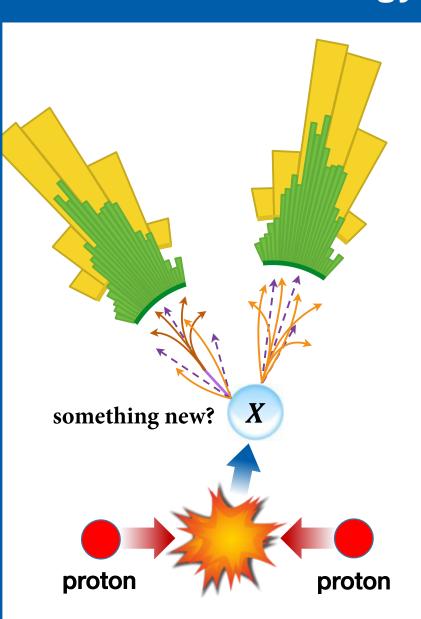


- Newly opened energy regime: $\sqrt{s} = 13$ TeV.
- Invariant mass

$$m = \sqrt{(\sum E)^2 - \|\sum p\|^2}.$$

Energy Frontier: Jets







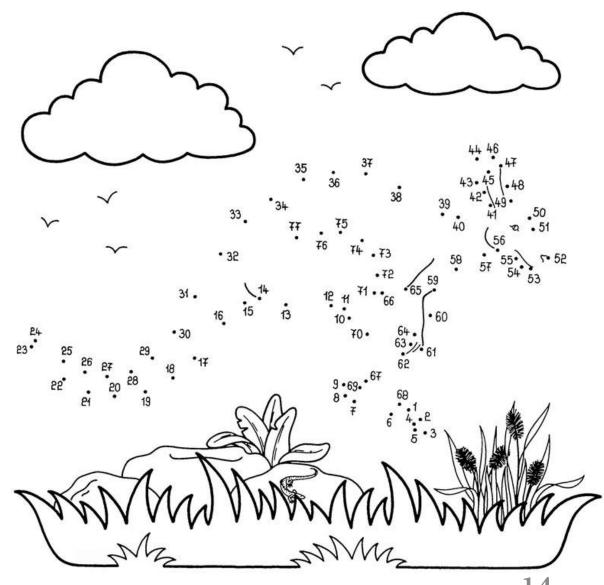
- Newly opened energy regime: $\sqrt{s} = 13$ TeV.
- Invariant mass

$$m = \sqrt{(\sum E)^2 - \|\sum p\|^2}.$$

Track reconstruction - Concept



• Nowadays finding particle tracks is like this ..



Track reconstruction - Concept

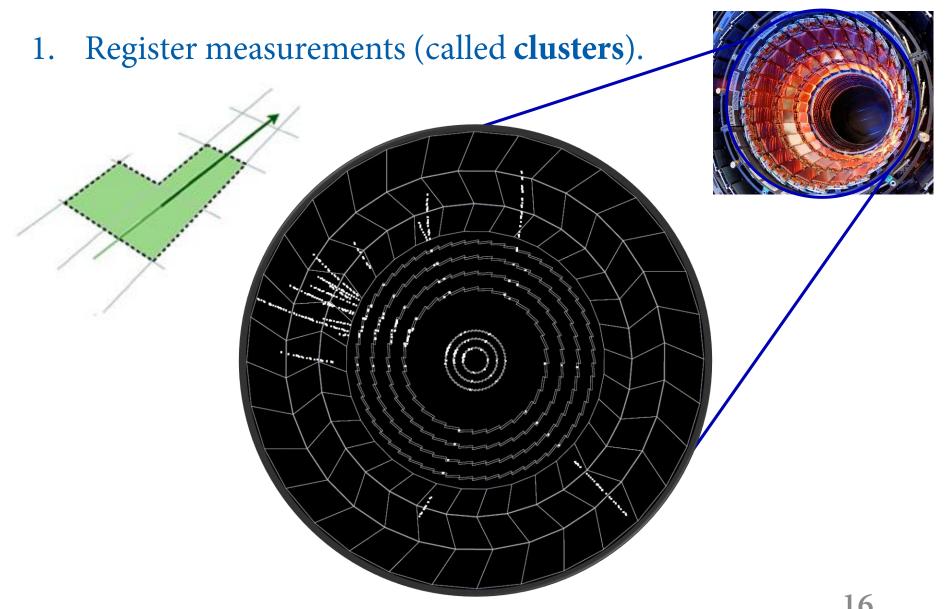


- Nowadays finding particle tracks is like this ..
- But without the numbers!



Track reconstruction – Step by step





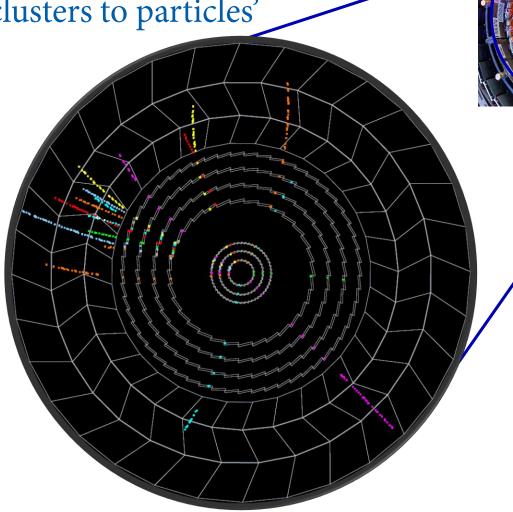
Track reconstruction – Step by step



1. Register measurements (called **clusters**).

2. Associate clusters to particles'

tracks.



Track reconstruction - Step by step

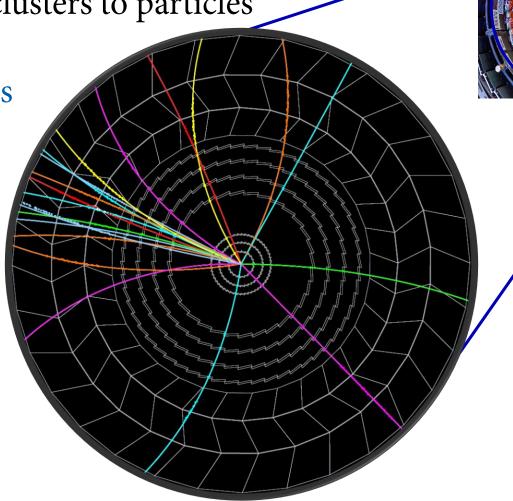


1. Register measurements (called **clusters**).

Associate clusters to particles'

tracks.

3. Fit particles trajectory.



Track reconstruction – Step by step



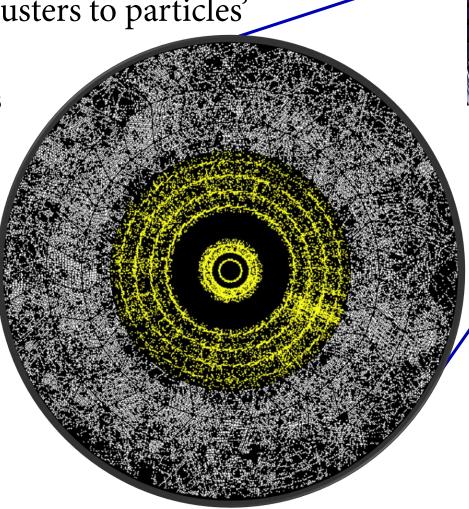
1. Register measurements (called **clusters**).

2. Associate clusters to particles'

tracks.

3. Fit particles trajectory.

How it looks in reality



Track reconstruction – Step by step

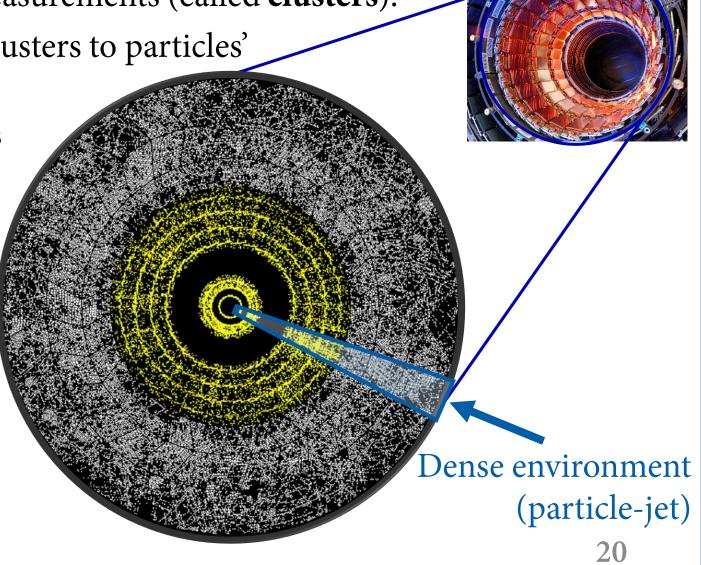


Register measurements (called clusters).

Associate clusters to particles'

tracks.

Fit particles trajectory.



Example Analysis

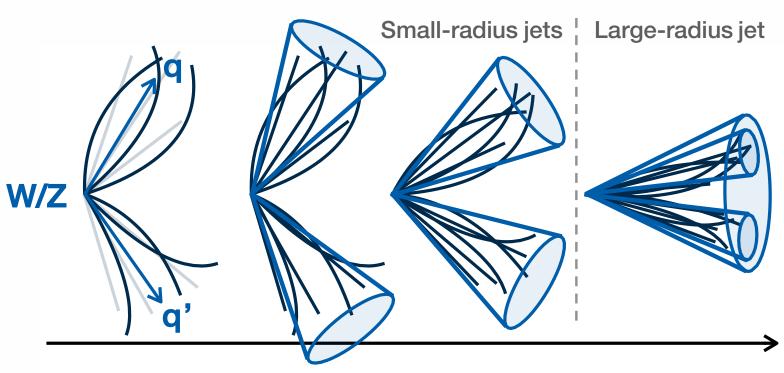
Prerequisites for analysis



- 1.Collect data: Detector, trigger, DAQ
- 2. Reconstruction of physics objects
- 3. Simulation: Generate events, detector simulation

Fatjets

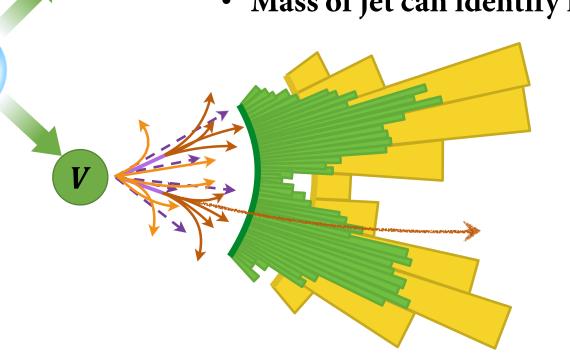




Boosted jets: Increasing transverse momentum, p_T



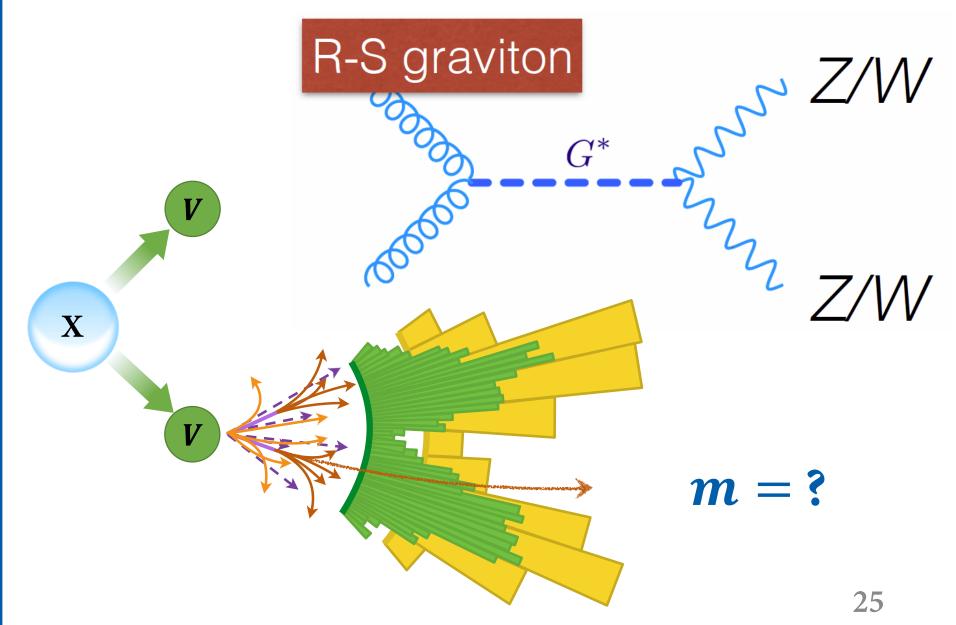
- Heavy (>1 TeV) resonances to pairs of vector bosons (V = W/Z) predicted by several extensions of the SM.
- $V \rightarrow$ quark-pair decays most abundant.
 - → Great probe for new physics!
- Mass of jet can identify initiating particle.



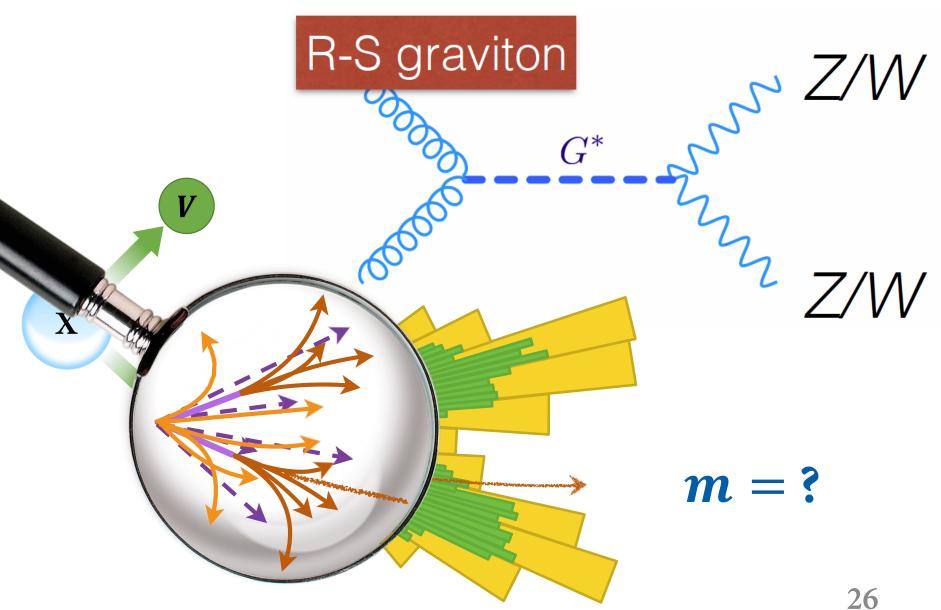
X

$$m = ?$$

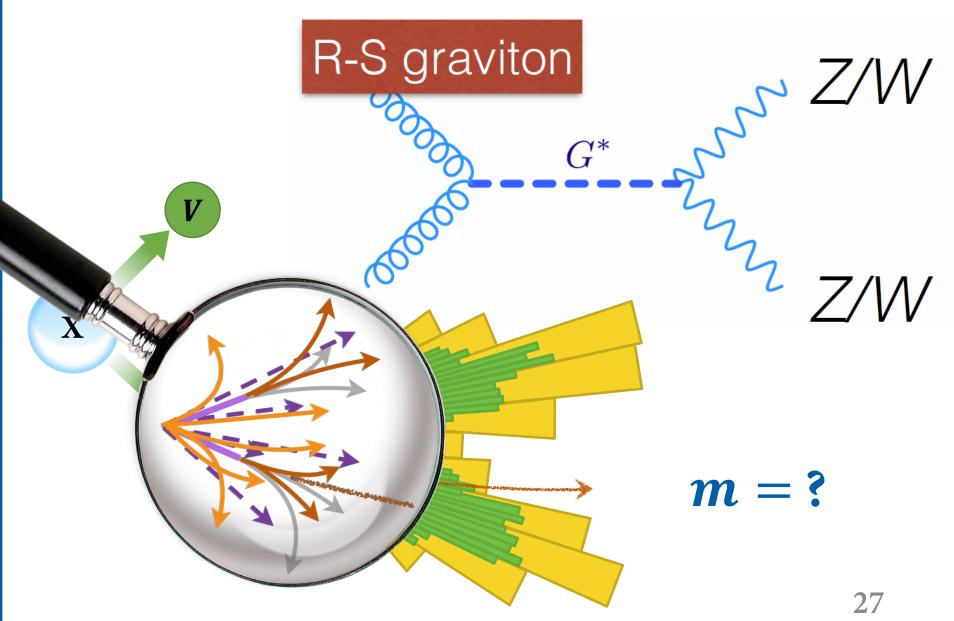






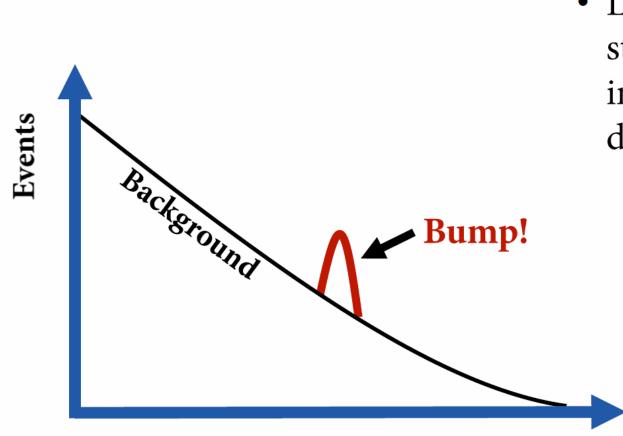






Boosted diboson search strategy





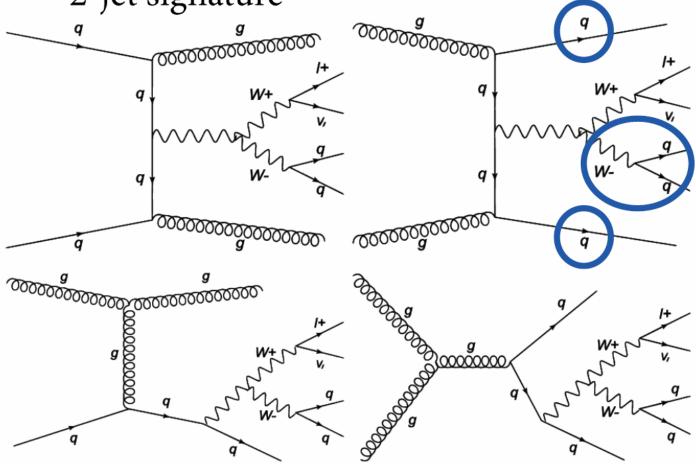
 Look for bump in steeply falling invariant mass distribution.

Backgrounds



Main background:

Standard model processes that can give the same
 2-jet signature



How to measure a cross-section



Cross section
$$\sigma = \frac{N}{\mathcal{L}} \rightarrow \sigma = \frac{N_{obs} - N_{bkg}}{\mathcal{L} \cdot \epsilon \cdot A \cdot \mathcal{B}}$$

N(obs) = Observed number of events

N(bkg) = Estimated number of background

L = Integrated luminosity

 $\varepsilon = efficiency$

A = acceptance

B= Branching ratio

How to measure a cross-section



$$\sigma = \frac{N_{obs} - N_{bkg}}{\mathcal{L} \cdot \epsilon \cdot A \cdot \mathcal{B}}$$

N(obs) Direct from data

N(bkg) (from data and MC, most critical part of analysis)

L (Someone else calculates this!)

 ε = efficiency (from Monte Carlo)

A = acceptance (from Monte Carlo)

B = Branching ratio (from Particle data group)

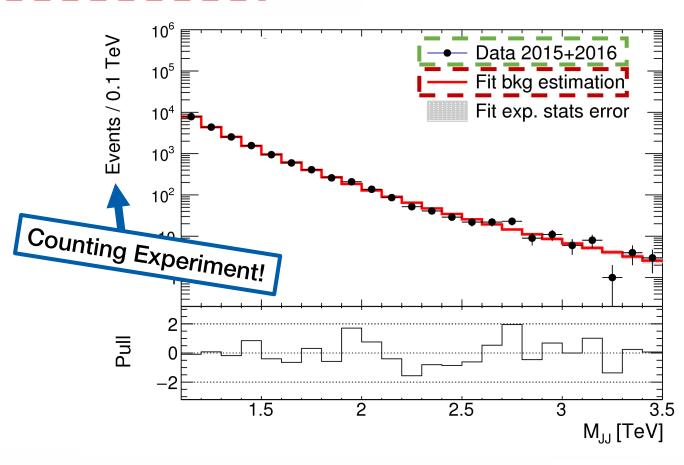
How to measure a cross-section



$$N(obs) = Observed number of events$$

$$\sigma = \frac{N}{\mathcal{L}} \rightarrow \sigma = \frac{N_{obs} - N_{bkg}}{\mathcal{L} \cdot \epsilon \cdot A \cdot \mathcal{B}}$$

N(bkg) = Estimated number of background

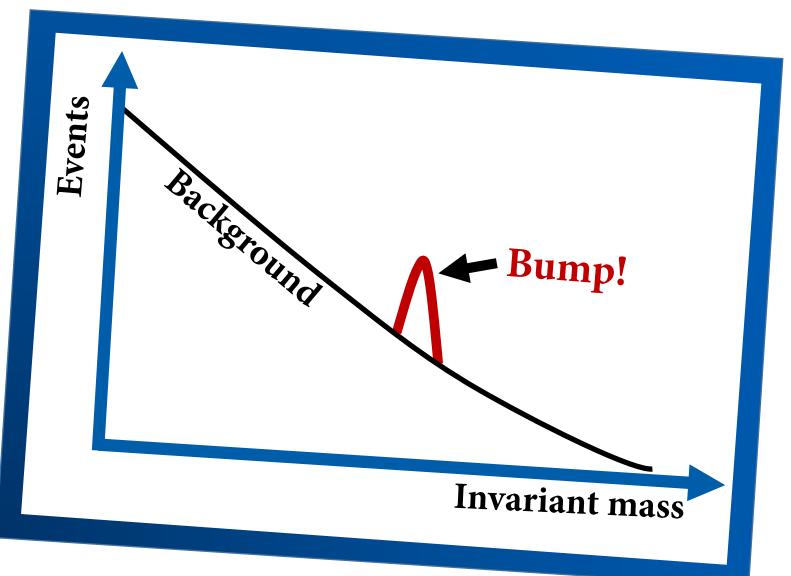




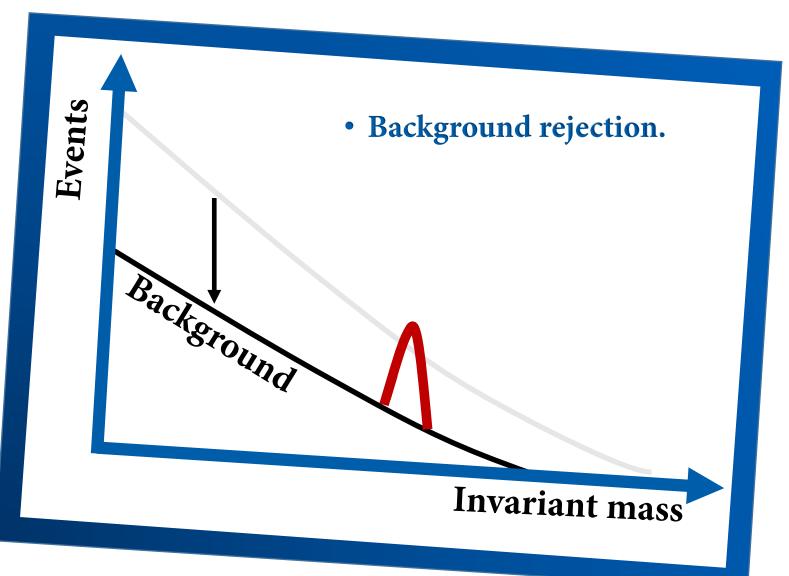
$$\sigma = \frac{N_{obs} - N_{bkg}}{\mathcal{L} \cdot \epsilon \cdot A \cdot \mathcal{B}}$$

- Minimise the uncertainty on σ !
- Maximise probability for signal detection, minimise probability for arriving at a fake signal detection.
- High signal to background : N(obs) >> N(bkd)
- High signal efficiency εΑ
- Reliable, robust method to determine N(bkg).
- Most important is the measurement of the uncertainty on N(bkg)
- Use Monte Carlo to help decide selection criteria that attempt to minimise the uncertainty on σ or significance of a discovery.

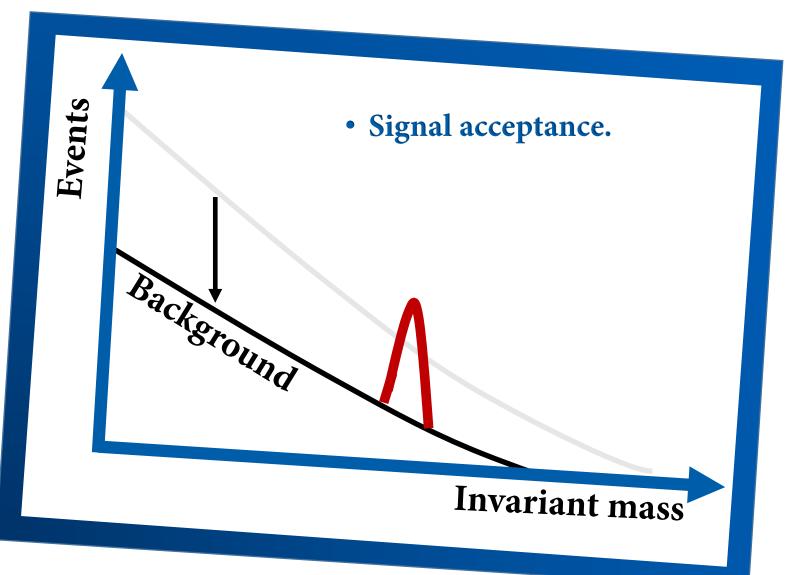










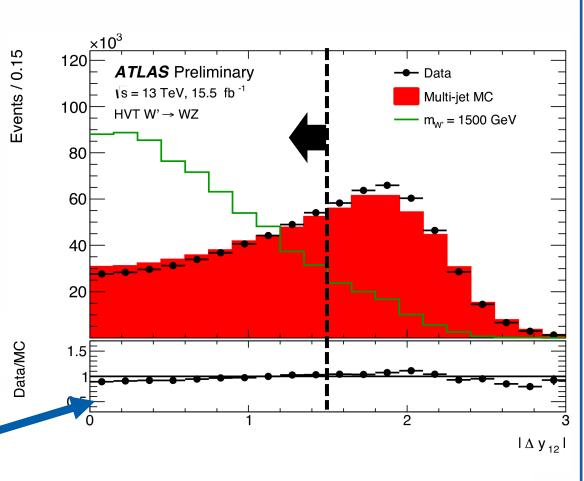


Event Selection



- Try to maximize fraction of signal events versus background events.
- One example is the use of kinematic cuts.

Cut on separation of two jets in rapidity

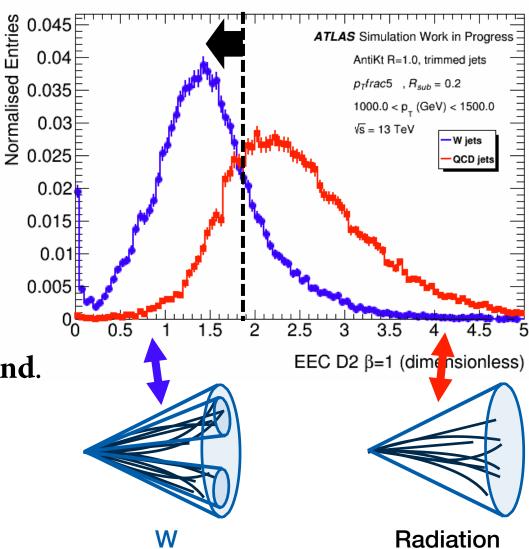


Boson tagging



 Utilize different properties of jets from W/Z-bosons with respect to the background to "tag" them.

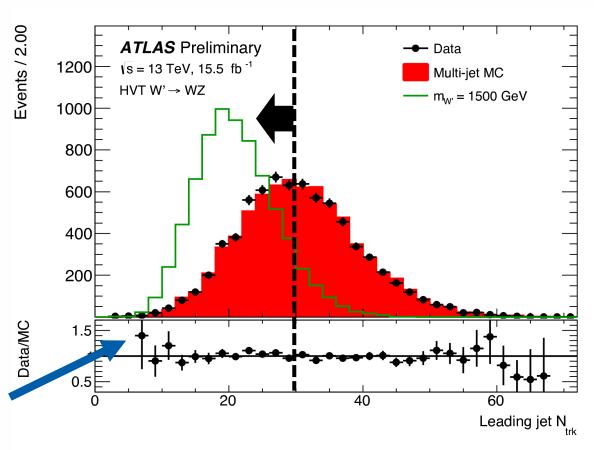
• "2-prong" for **signal**, "1-prong" for **background**.



Boson tagging



 Utilize different properties of jets from W/Z-bosons with respect to the background to "tag" them.



Cut on number of tracks in jet

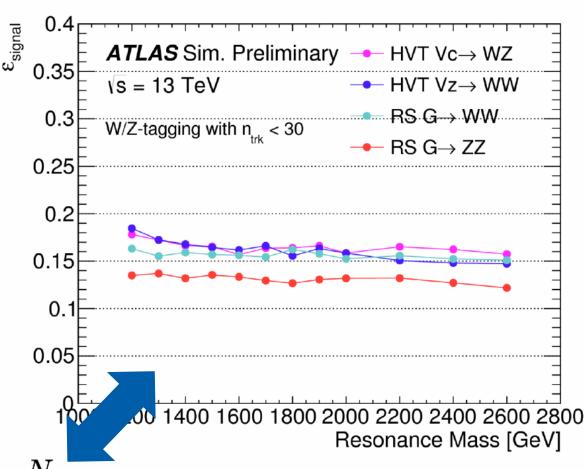
• Selection on jet mass: require to be at W/Z mass!

Signal efficiency



 After fixing selections of analysis, calculate expected signal efficiency and yield.

$$oldsymbol{arepsilon} \cdot A = rac{N_{Selected}}{N_{All}}$$



$$\sigma = rac{N}{\mathcal{L}}
ightarrow \sigma = rac{N_{obs} - N_{bkg}}{\mathcal{L} \cdot (\epsilon \cdot A) \cdot \mathcal{B}}$$

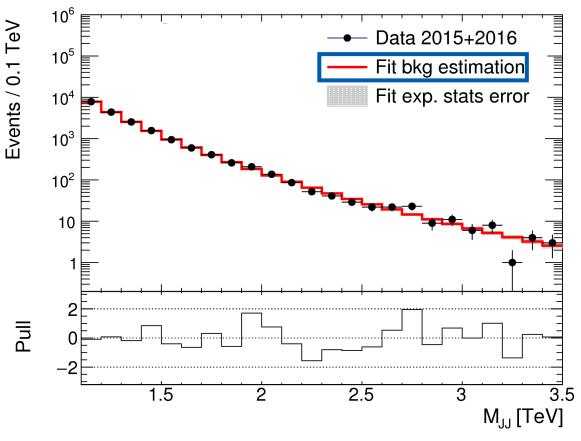
Background Description



• Fit background using parametric

function:
$$\frac{dn}{dx} = p_1 (1 - x)^{p_2 - \xi p_3} x^{-p_3}$$
$$x = \frac{m_{JJ}}{13 \text{ TeV}}, \xi \text{ decorrelation factor}$$

$$\sigma = \frac{N}{\mathcal{L}} \rightarrow \sigma = \frac{N_{obs} - N_{bkg}}{\mathcal{L} \cdot \epsilon \cdot A \cdot \mathcal{B}}$$



Statistical Uncertainties

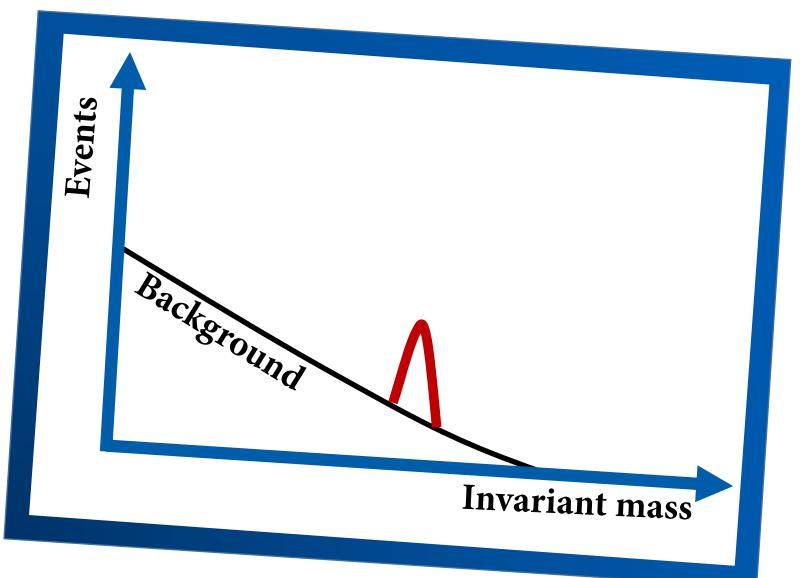


- Arise from stochastic fluctuations arising from the fact that a measurement is based on a finite set of observations
- Repeated measurements will give a set of observations that will differ from each other.
- Statistical uncertainty is a measure of this variation
- Poisson fluctuations associated with random variations in the system one is examining

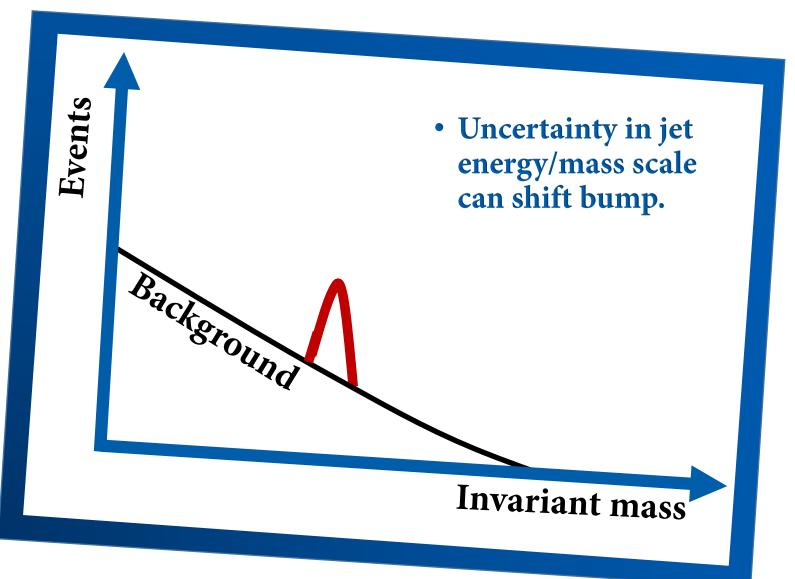


- Arise from uncertainties associated with the measurement apparatus
- What are the assumptions underlying the measurement?
 - How accurate is the Monte Carlo Simulation?
 - Models for the signal and the background
 - E.g. acceptance, model parameters
 - What can we think of that has the potential to affect our measurement?

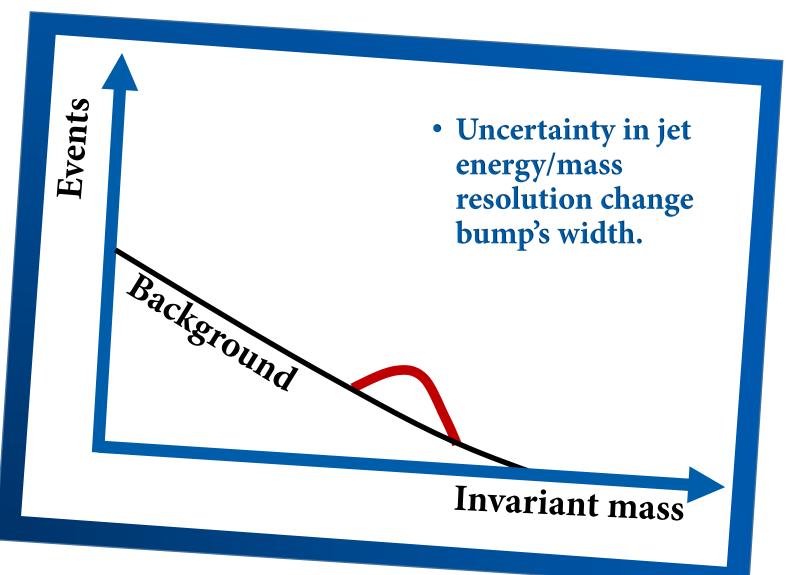










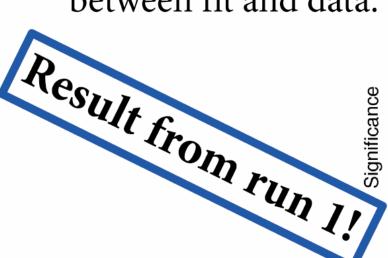


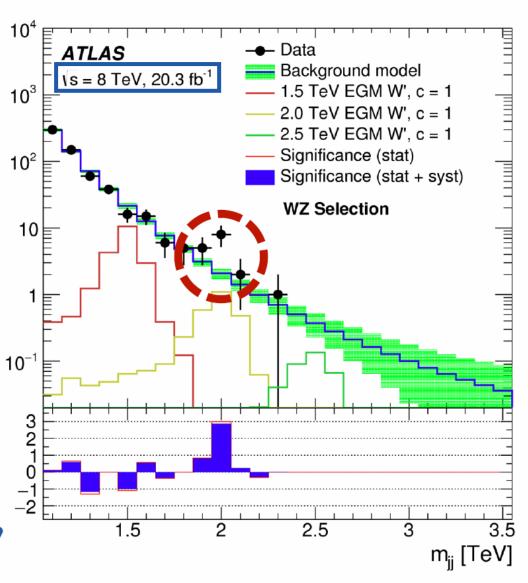
Results!

Events / 100 GeV



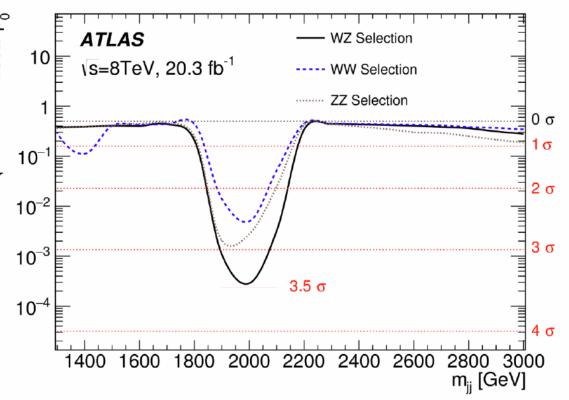
- 1. Finally, look at signal region
- 2. Fit background
- 3. Check for difference between fit and data.







- Estimate of pvalue/significance
 of observed events,
 assuming probability
 density for random
 variable
- Assume: N_O follows Poisson distribution



• Poisson probability: $\alpha = \sum_{n=N_o} \frac{\exp(-N_b) (N_b)^n}{n!}$



WZ Selection

WW Selection

- Estimate of p
 - valug/gignificance
 - of ot
 - dens

assu:

- varia
- Assu Poiss

- Does not consider uncertainties or
- possible other intervals where to measure N_O
 - local significance versus global significance

s=8TeV, 20.3 fb⁻¹

• Poisson probability: $\alpha = \sum_{n=N_0} \frac{\exp(-i\mathbf{v}_b)(i\mathbf{v}_b)}{n!}$

00 3000 [GeV]

n





1-2σ





3σ

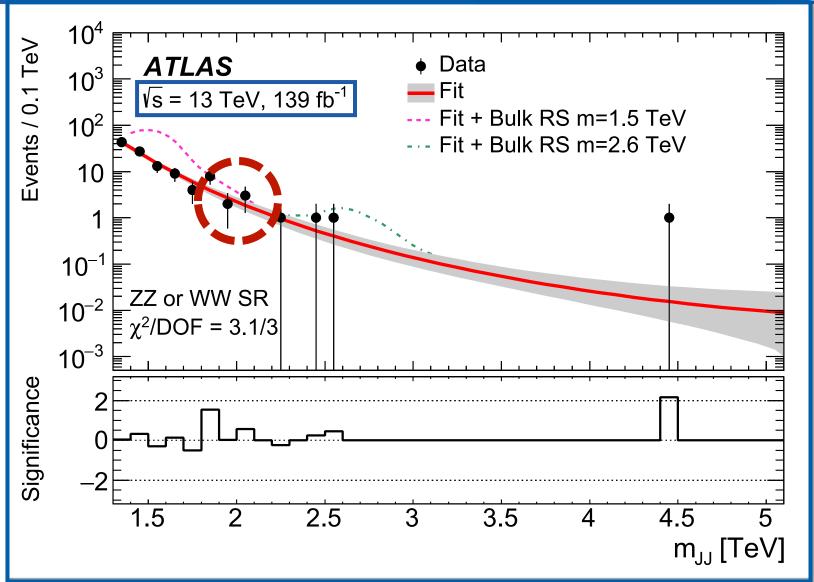




5σ

More Results!



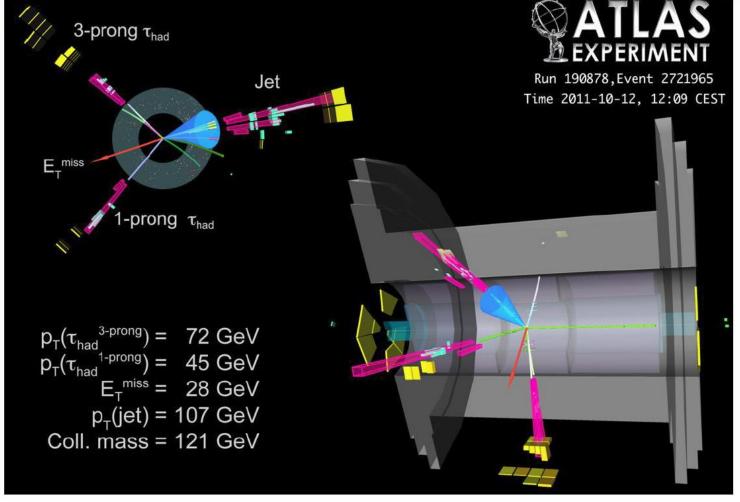


Thank you – Discussion!

BACKUP

Taus





ullet Essentially thin jets $au^+ o \pi^+
u_ au$ $au^+ o \pi^+ \pi^+ \pi^-
u_ au$