

Pymosa: A smaller and faster Mimosa26 telescope redout

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Plans and Status

Legend:

Bonn milestone
Readiness in %

DESY (?)
milestone
Readiness in %

- Legacy mode:** Like current readout, 2 frames hardware trigger veto, send two frames per TLU trigger → Same speed, good for cross checking setup

EUDAQ 1.x / 2.0
producer
40 %

EUDAQ 1.x /
2.0 converter
0 %

Documentation
40 %

(Adjustable) TLU
trigger veto
90 %

Mimosa26
tuning
0 %

EUDAQ 1.x / 2.0
Integration
(online monitor
etc.)
0 %

- Fast mode:** ~ 1 frame hardware trigger veto, send one frame per TLU trigger → Double the speed

Create start of
frame time
stamps
90 %

TLU to frame
time stamps
correlation
60 %

Enhance of
Mimosa data
interpreter
70 %

System tests
with particle
beam
40 %

- Continuous mode:** No trigger veto, sending hits multiple times per trigger or use requested trigger range feature of EUDAQ2, event building in software → one order of magnitude more speed

Realtime data
duplication
0 %

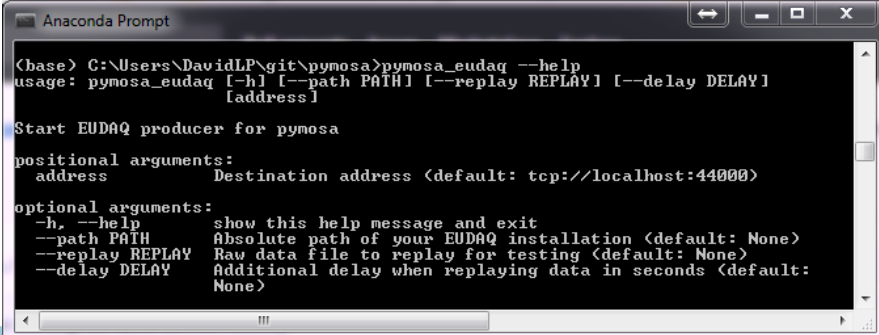
System tests
with particle
beam
40 %

EUDAQ 2.0
Integration
0 %

EUDAQ 1.x / 2.0 producer

- ▶ Fixing bug / add feature in Python interface for EUDAQ 1.x producer:
<https://github.com/eudaq/eudaq/pull/470>
<https://github.com/eudaq/eudaq/pull/472>
- ▶ EUDAQ 2.0 producer has much better Python integration (Yi Liu)
- ▶ Add python producer to pymosa: <https://github.com/SiLab-Bonn/pymosa/blob/eudaq/pymosa/eudaq.py>
- ▶ Replay data feature for testing and debugging (tbd)
- ▶ Real-time data interpretation for event sending (ongoing)
- ▶ Command line interface to ease usage: „pymosa_eudaq”

Example: command line interface



```
(base) C:\Users\DavidLP\git\pymosa>pymosa_eudaq --help
usage: pymosa_eudaq [-h] [--path PATH] [--replay REPLAY] [--delay DELAY]
                  [address]

Start EUDAQ producer for pymosa

positional arguments:
  address                Destination address <default: tcp://localhost:44000>

optional arguments:
  -h, --help            show this help message and exit
  --path PATH           Absolute path of your EUDAQ installation <default: None>
  --replay REPLAY       Raw data file to replay for testing <default: None>
  --delay DELAY         Additional delay when replaying data in seconds <default:
                        None>
```

EUDAQ 1.x / 2.0 converter

- ▶ Since we have to do on the fly data interpretation we would like to send hits and not raw data
- ▶ Shall we encode hits as a „raw data event“ for EUDAQ 1.x?
- ▶ Python EUDAQ 1.x interface only supports raw data event sending, is there a hit data sending in EUDAQ 2.0?

Documentation

- ▶ To be hosted on the github project wiki: <https://github.com/SiLab-Bonn/pymosa/wiki>
- ▶ To help users to setup pymosa
- ▶ Starting to write installation / usage instructions here: <https://github.com/SiLab-Bonn/pymosa/wiki/Eudaq-integration>

Snippet from wiki page

Usage of pymosa

A simple command line interface is provided to start the pymosa producer:

```
pymosa_eudaq --help
```

Please read the help output for program parameters.

If you did not add the EUDAQ directory to the `PYTHONPATH` explicitly after installation (see above) you can give the path when running `pymosa_eudaq`, e.g.:

```
pymosa_eudaq --path /home/user/git/eudaq
```

TLU trigger veto

- ▶ Needed to fake triggered readout as it is done now
- ▶ It is faked triggered readout since we still read all Mimosa26 data
- ▶ We just send events with trigger; done in software and real-time
- ▶ Trigger veto in hardware implemented
- ▶ First test: saw expected reduced trigger rate due to veto

- ▶ Mechanism: Use trigger acknowledge signal from TLU FSM in FPGA
 - After accepting one trigger have to set acknowledge (indicate ready for next trigger)
 - Usually (continuous M26 readout): Set acknowledge immediately after accepting trigger
 - For **legacy/fast mode**: wait programmable time until trigger is acknowledged ($2 \times 115.2 \text{ us}$)
 - Result: Faked triggered readout with **1 trigger / 2 frames** (programmable)

Mimosa26 tuning

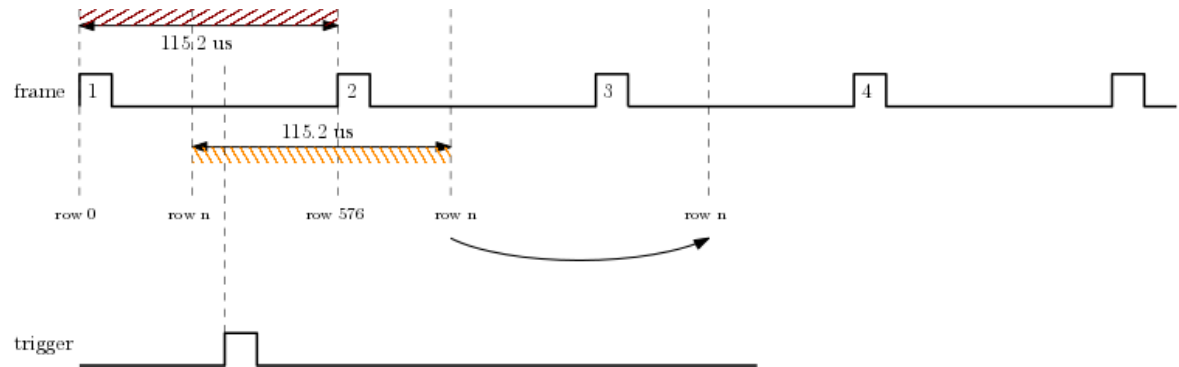
- ▶ Needed to be able to use new system with any telescope, when we do not want to translate the existing config files for all telescope
- ▶ Needed to mask noisy pixels that can deplete data bandwidth of continuous readout → main tuning goal is to reduce data rate
- ▶ Advantage: recover tuning degradation over time, „best“ possible tuning for the test beam conditions
- ▶ We are not really able to give the threshold setting in multiples of the noise value (as it is done now?)
- ▶ Tuning algorithm to be discussed and tested

Start of frame time stamps


- ▶ We create a time stamp in the raw data stream with 40 MHz when the new Mimosa26 frame readout starts
- ▶ Using the Marker (MKD) signal of Mimosa26
 - Four clock cycles high if new frame readout starts

Time stamps correlation

- ▶ We create a time stamp in the raw data stream with 40 MHz when the new Mimoso26 frame readout starts
- ▶ We create a time stamp in the raw data stream with 40 MHz when we have a TLU trigger word
- ▶ This allows us to assign with 115 us window a (or multiple) trigger to a Mimoso26 Row
- ▶ Proof of principle with test beam data at ELSA already done



Enhance of Mimosa data interpreter

- ▶ Make code readable
 - ▶ Add unit tests for code quality
 - ▶ Add code documentation
 - ▶ Ongoing (Jens & Yannick)
 - ▶ Test speed for real-time data interpretation
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Real-time data duplication

- ▶ Since EUDAQ test beam data analysis is event based we can duplicate hits for overlapping events
 - ▶ Needs a good time reference and offline data correlation in software to this reference
 - ▶ Software work needed here
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