LEIR INJECTION BPMs update

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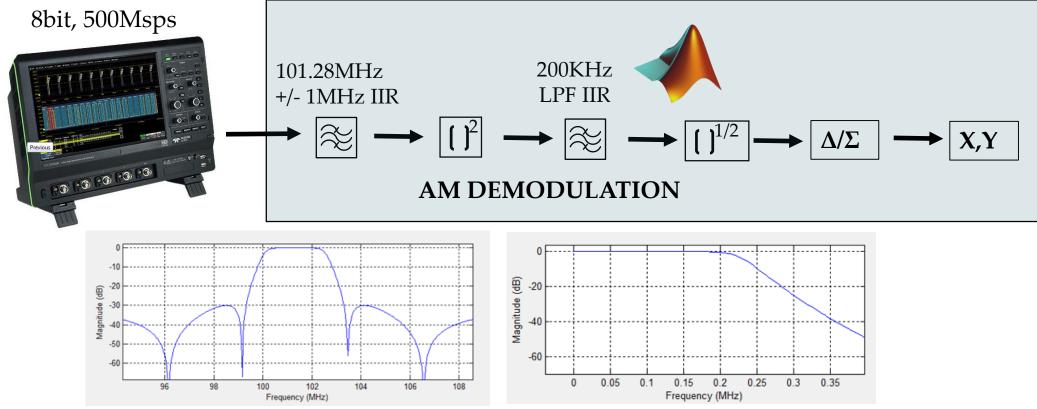
Specifications

The required accuracy of the average beam position during the pulse should be better than 0.5 mm with a precision of 0.2 mm for a minimum intensity of 0.5e+10 charges (4uA) at a b of 0.094 for the 200 us spills. The accuracy should be maintained over +/- 15 mm of aperture (around the centre of the beam pipe assuming a maximum beam size of 10 mm). The system should not suffer any saturation effects up to 40uA. **During a pulse, the position data should be available at 1us intervals, with the same accuracy.**

SPECIFICATION FOR THE AVERAGE POSITION

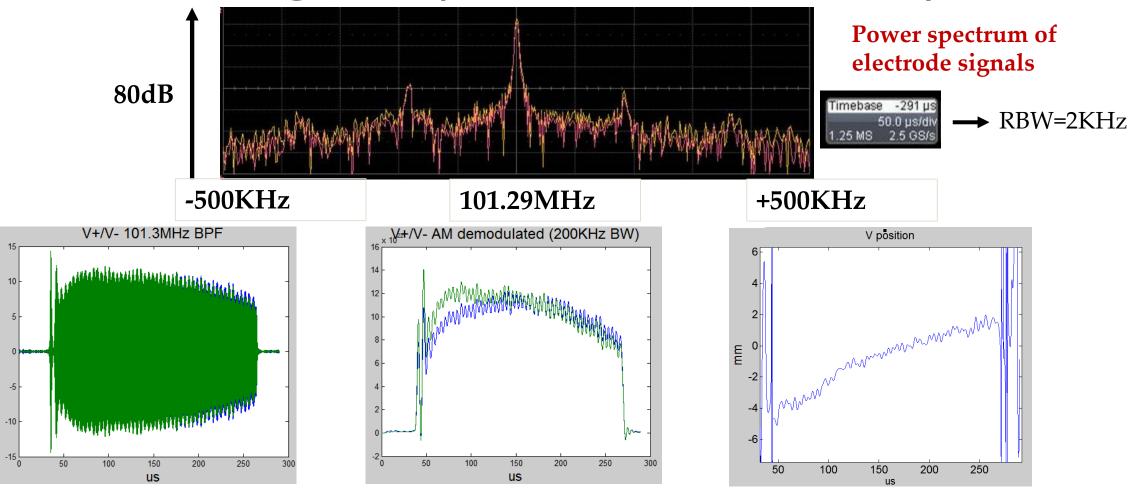
Accuracy	<0.5mm	depends on the electrical and mechanical offset
Precision	<0.2mm	depends on S/N \rightarrow tradeoff between BW and precision

101MHz acquisition



- LECROY 8 bit scope running @ 500Msps + matlab DSP
- 20dB amplifier in front of the scope to have sufficient signal level
- S/N ratio probably dominate by the scope (12bit scope, now broken, should perform quite better)

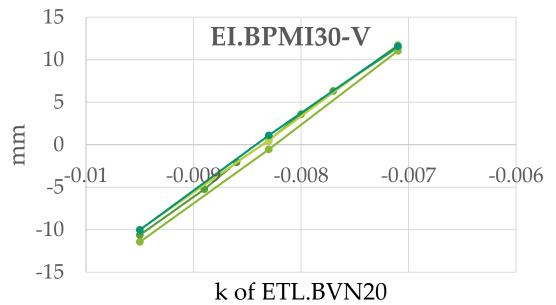
EI.BPMI30 signals (last BPM in the line)



- Bunching stay almost constant all along the line
- At this conditions, resolution expected to be better than 0.5mm over 5us time average

Dipole scan (HF measurement)

Dipole scan (+/- 10mm) for different settings of the debuncher (actually working as rebuncher) (phase off up to 20° and amplitude down to 80%)



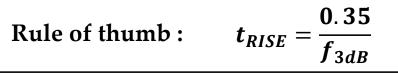
- Position values are the average over the central region of the LINAC pulse
- Measurements are (at first sight) indipendent of clearing voltage and magnetic field
- BPM response stay linear over the range
- With the debuncher off the signals become very weak (not shown)
- Similar scans for ITE.10, ITE.20, ETL.20 and EI.10 were successful

Error (precision) estimation

 $Position = S \cdot \frac{\Delta_M}{\Sigma_M} = S \cdot \frac{\Delta_{BEAM} + \Delta_{NOISE}}{\Sigma_{REAM} + \Sigma_{NOISE}} \cong S \cdot \frac{\Delta_{BEAM}}{\Sigma_{BEAM}} + S \cdot \frac{\Delta_{NOISE}}{\Sigma_{BEAM}}$ error $error = S \cdot \frac{n_{+} - n_{-}}{(V_{+} + V_{-})} = S \cdot \left(\frac{\sqrt{2} \cdot n}{2 \cdot V}\right) = \frac{S}{\sqrt{2}} \cdot SNR^{-1} \qquad \begin{cases} (V_{+} + V_{-}) + n_{+} + n_{-} \cong V_{+} + V_{-} \\ E[n_{+}n_{-}] = 0 \end{cases}$ Precision vs SNR 0.75 mm With $S \cong 40mm$ 0.5 0.25 0 30 35 40 45 50 55 60

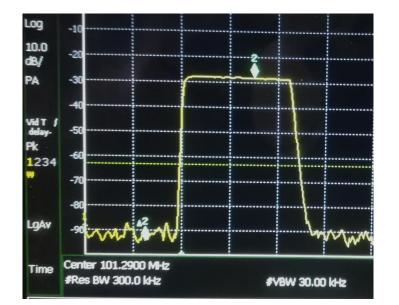
dB





Position rate (from specifications): **2µs**

Minumum bandwidth= 175kHz

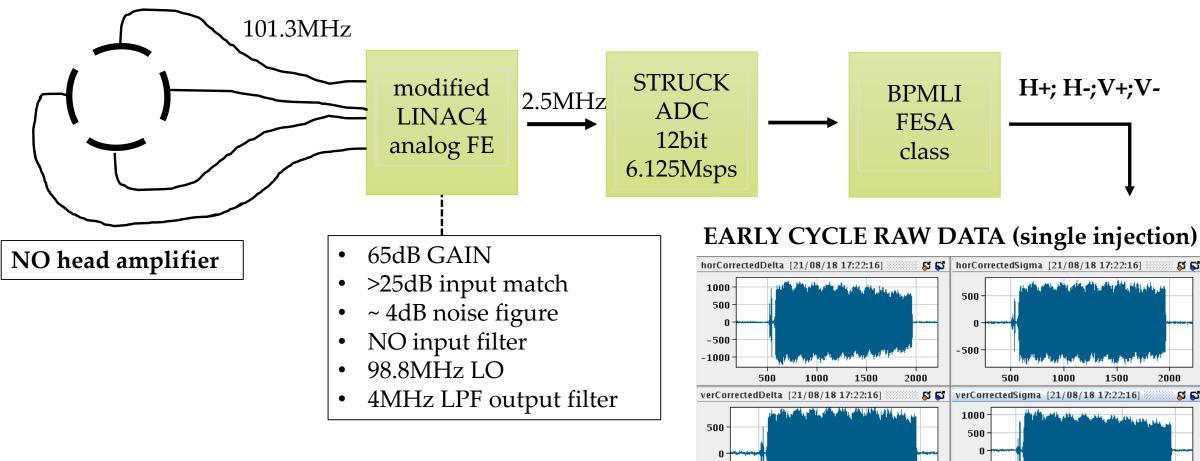


@300kHz RBW **S/N \approx 60dB** for EI.30 and ITE.10

BPM	Cable len. [m]	Att[dB]
ITE.10	121	3
ETL.22	99	2.5
EI.30	41	1

- @300kHz RBW **S/N ≈ 60dB** for EI.30 and ITE.10
- With these buncher settings the requested precision is reasonable

EI.BPM30 from 20th August



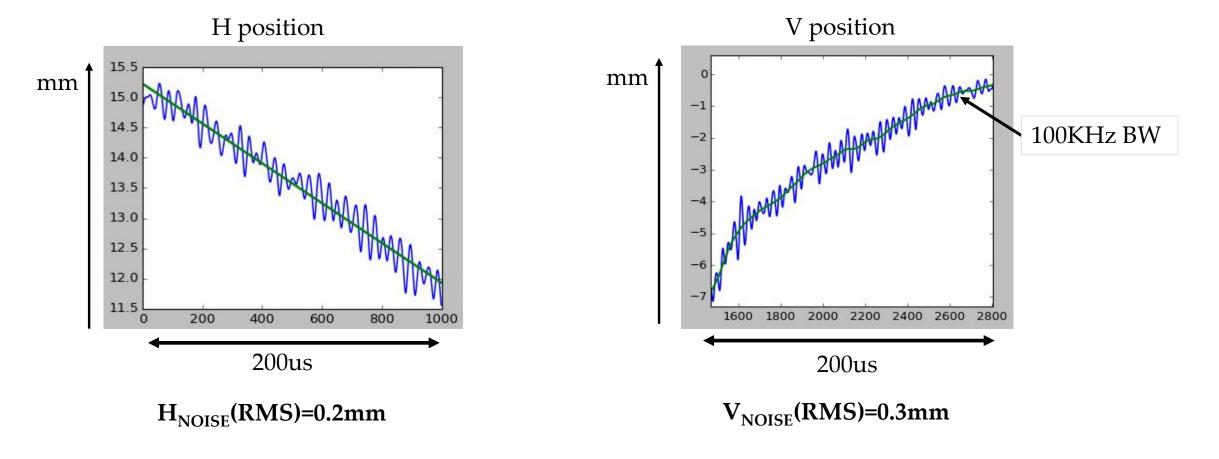
-500

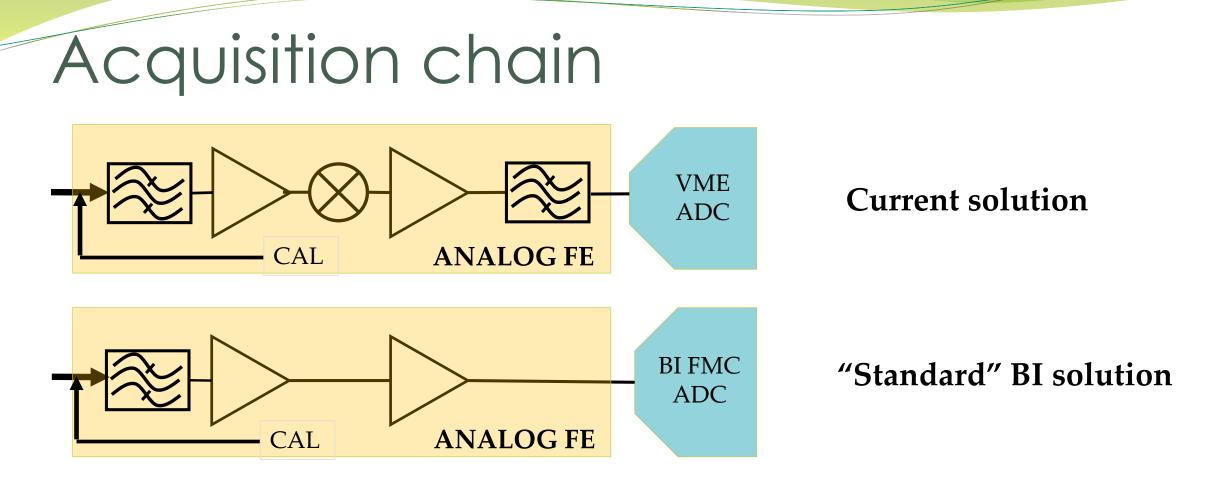
• 5dB better performance expected from a dedicated analog front end

-500

-1000

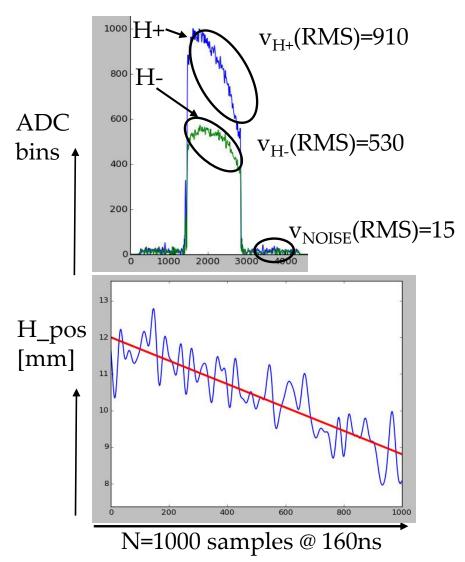
EI.BPM30 EARLY CYCLE @ 300KHz BW (~1µs rise time)





- In both cases a custom analog front end (~60db gain & calibration) is needed
- Narrow BW (<10MHz) → undersampling is a good choice for lower cost (in that case we would undersample and oversample at the same time)
- 125MSps / 16bit mezzanine used in LEIR orbit (but on BE/RF carrier) can be a solution

Precision calculation with linear fitting



$$SNR \approx 20 \cdot log\left(\frac{\frac{910 + 530}{2}}{15}\right) = 33dB$$

(010 + 700)

[a,b]=np.polyfit(linspace(0,N-1,N), H_pos[s:s+N], 1)
H_fit=linspace(b,b+a*N,N)
H_pos_error=(sqrt(mean((H_pos[s:s+N]-H_fit)**2)))

$$H_{pos_{ERROR}}(RMS) = \sqrt{\frac{1}{N} \cdot \sum (H_{pos} - H_{fit})^2} = 0.5mm$$

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