
Frame-Independent Angular Distributions as Density Matrix Invariants



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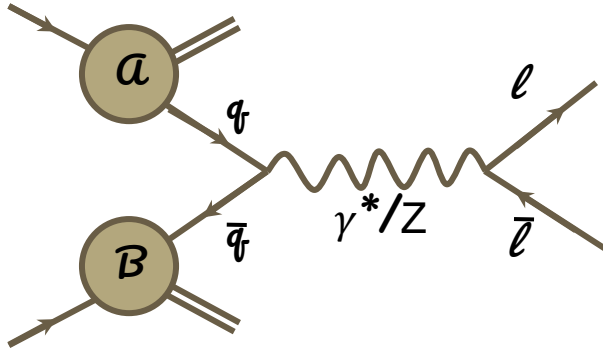
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Outline

- Drell-Yan angular distributions and frame dependence; geometric model
- Hadronic tensor as density matrix (of virtual photon) and its invariants
- Counting and constraining the invariants
- Applications
- Conclusions

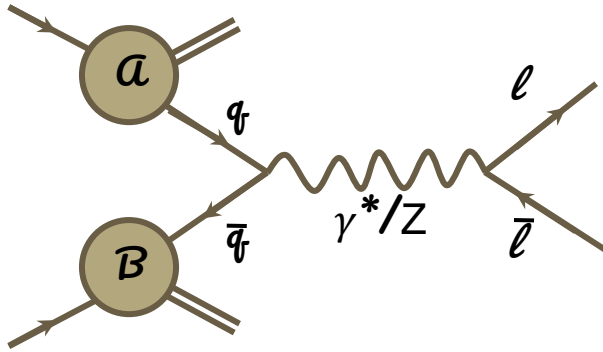
Angular distribution

general form of angular distribution (wrt particular frame)



$$\begin{aligned} \frac{1}{\sigma} \frac{d\sigma}{d\Omega} = & \frac{3}{4\pi} \frac{1}{3 + \lambda_\theta} \left(1 + \lambda_\theta \cos^2 \theta + \lambda_{\theta\phi} \sin 2\theta \cos \phi \right. \\ & + \lambda_\phi \sin^2 \theta \cos 2\phi + \lambda_{\perp\phi} \sin^2 \theta \sin 2\phi \\ & + \lambda_{\perp\theta\phi} \sin 2\theta \sin \phi + 2A_\theta \cos \theta \\ & \left. + 2A_\phi \sin \theta \cos \phi + 2A_{\perp\phi} \sin \theta \sin \phi \right) \end{aligned}$$

Angular distribution



general form of angular distribution :

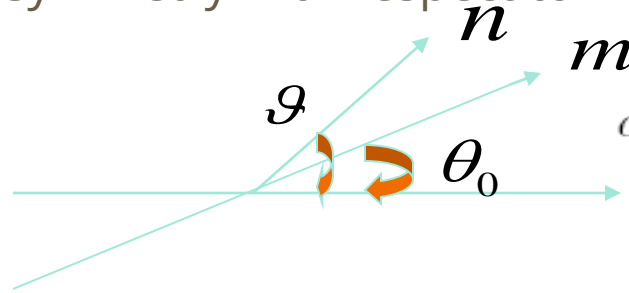
$$\begin{aligned} \frac{1}{\sigma} \frac{d\sigma}{d\Omega} = & \frac{3}{4\pi} \frac{1}{3 + \lambda_\theta} \left(1 + \lambda_\theta \cos^2 \theta + \lambda_{\theta\phi} \sin 2\theta \cos \phi \right. \\ & + \lambda_\phi \sin^2 \theta \cos 2\phi + \lambda_{\perp\phi} \sin^2 \theta \sin 2\phi \\ & + \lambda_{\perp\theta\phi} \sin 2\theta \sin \phi + 2A_\theta \cos \theta \\ & \left. + 2A_\phi \sin \theta \cos \phi + 2A_{\perp\phi} \sin \theta \sin \phi \right) \end{aligned}$$

Invariants

- Facilitate comparison b/w experiments, theory and experiment
- Reveal systematic biases

Kinematic azimuthal asymmetry from polar one (OT'05)

Only polar asymmetry with respect to m !



$$d\sigma \propto 1 + \lambda_0 (\vec{n}\vec{m})^2 = 1 + \lambda_0 \cos^2 \theta_{nm}^2$$

$$\cos \theta_{nm} = \cos \theta \cos \theta_0 + \sin \theta \sin \theta_0 \cos \phi$$

- azimuthal angle appears with new
- λ_0 - invariant!

$$\lambda = \lambda_0 \frac{2 - 3 \sin^2 \theta_0}{2 + \lambda_0 \sin^2 \theta_0}$$

$$\nu = \lambda_0 \frac{2 \sin^2 \theta_0}{2 + \lambda_0 \sin^2 \theta_0}$$

Generalized Lam-Tung relation

- Relation between coefficients (high school math sufficient!)

$$\lambda_0 = \frac{\lambda + \frac{3}{2}\nu}{1 - \frac{1}{2}\nu}$$

- Reduced to standard LT relation for transverse polarization ($\lambda_0 = 1$)
- LT - contains two very different inputs:
kinematical asymmetry+transverse polarization
- Non-coplanarity – violation of LT
(talk of W.-C. Chang)

General approach: the number of independent invariants

- 8 parameters describe distribution
 - 3 Euler angles parameterize rotation
- **$8 - 3 = 5$ independent invariants**

Hadronic tensor in terms of observables

$$\frac{1}{\sigma} \frac{d\sigma}{d\Omega} \propto W^{\mu\nu} L_{\mu\nu}$$

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$$q_\mu W^{\mu\nu} = 0 \quad \longrightarrow \quad W^{ij} = \begin{pmatrix} d_1 & a_1 + ia_2 & b_1 + ib_2 \\ a_1 - ia_2 & d_2 & c_1 + ic_2 \\ b_1 - ib_2 & c_1 - ic_2 & d_3 \end{pmatrix}$$

Hadronic tensor in terms of observables

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$$L_{ij} \propto \delta_{ij} - n_i n_j + ig \epsilon_{ijk} n^k$$

Hadronic tensor in terms of observables

$$\begin{aligned}\frac{1}{\sigma} \frac{d\sigma}{d\Omega} &\propto (d_1 + \frac{1}{2}d_2 + \frac{1}{2}d_3) + (-d_1 + \frac{1}{2}d_2 + \frac{1}{2}d_3) \cos^2 \theta \\ &- a_1 \sin 2\theta \cos \phi + \frac{1}{2}(d_3 - d_2) \sin^2 \theta \cos 2\phi \\ &- b_1 \sin 2\theta \sin \phi - c_1 \sin^2 \theta \sin 2\phi \\ &- 2a_2 \sin \theta \sin \phi + 2b_2 \sin \theta \cos \phi - 2c_2 \cos \theta\end{aligned}$$

compare with the general expression

$$\begin{aligned}\frac{1}{\sigma} \frac{d\sigma}{d\Omega} &= \frac{3}{4\pi} \frac{1}{3 + \lambda_\theta} \left(1 + \lambda_\theta \cos^2 \theta + \lambda_{\theta\phi} \sin 2\theta \cos \phi \right. \\ &+ \lambda_\phi \sin^2 \theta \cos 2\phi + \lambda_{\perp\phi} \sin^2 \theta \sin 2\phi \\ &+ \lambda_{\perp\theta\phi} \sin 2\theta \sin \phi + 2A_\theta \cos \theta \\ &+ \left. 2A_\phi \sin \theta \cos \phi + 2A_{\perp\phi} \sin \theta \sin \phi \right)\end{aligned}$$

Hadronic tensor in terms of observables

$$W^{ij} = \frac{2}{3 + \lambda_\theta} \begin{pmatrix} \frac{1 - \lambda_\theta}{2} & -\lambda_{\theta\phi} - iA_{\perp\phi} & -\lambda_{\perp\theta\phi} + iA_\phi \\ -\lambda_{\theta\phi} + iA_{\perp\phi} & \frac{1 + \lambda_\theta - 2\lambda_\phi}{2} & -\lambda_{\perp\phi} - iA_\theta \\ -\lambda_{\perp\theta\phi} - iA_\phi & -\lambda_{\perp\phi} + iA_\theta & \frac{1 + \lambda_\theta + 2\lambda_\phi}{2} \end{pmatrix}$$

(normalization condition $\text{Tr } W = 1$)

Hadron tensor in terms of observables

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(normalization condition $\text{Tr } W = 1$)

$$W = \frac{1}{3} \cdot \mathbf{1} + W_s + iW_a$$

Spin 1: symmetric and antisymmetric part do not mix: rotational invariants can be found as eigenvalues of matrices:

$$W, W_s, W_a, W_s W_a, W_s W_a W_s, \dots$$

Set of characteristic equations for

$\overline{W_x}$, W_x , $W_x + iW_x$ and $W_x W_x$

$$w^{(x)} \left(w^{(x)^2} + 4U_1 \right) = 0$$

$$w^{(x)^3} - \frac{4}{3}U_2 w^{(x)} - \frac{8}{27}T = 0$$

$$w^3 - \left(4U_1 + \frac{4}{3}U_2 \right) w - \frac{8}{27}(T + R) = 0$$

$$w^{(xx)} \left(w^{(xx)^2} + \frac{16}{9}M \right) = 0$$

Invariants

$$U_1 = \frac{A_\theta^2 + A_\phi^2 + A_{\perp\theta\phi}^2}{(3 + \lambda_\theta)^2}, \quad U_2 = \frac{\lambda_\theta^2 + 3(\lambda_\phi^2 + \lambda_{\theta\phi}^2 + \lambda_{\perp\phi}^2 + \lambda_{\perp\theta\phi}^2)}{(3 + \lambda_\theta)^2}$$

$$T = \frac{(\lambda_\theta + 3\lambda_\phi)(2\lambda_\theta^2 - 6\lambda_\theta\lambda_\phi + 9\lambda_{\theta\phi}^2) + 9(\lambda_\theta\lambda_{\perp\theta\phi}^2 - 2\lambda_\theta\lambda_{\perp\phi}^2 + 6\lambda_{\theta\phi}\lambda_{\perp\theta\phi}\lambda_{\perp\phi} - 3\lambda_\phi\lambda_{\perp\theta\phi}^2)}{(3 + \lambda_\theta)^3}$$

$$R = \frac{1}{(\lambda_\theta + 3)^3} (54(A_\theta A_\phi \lambda_{\theta\phi} + A_\theta A_{\perp\phi} \lambda_{\perp\theta\phi} + A_{\perp\phi} A_\phi \lambda_{\perp\phi}) + 9\lambda_\theta (2A_\theta^2 - A_{\perp\phi}^2 - A_\phi^2) + 27\lambda_\phi (A_\phi^2 - A_{\perp\phi}^2))$$

$$M = \frac{1}{(3 + \lambda_\theta)^4} \{ A_\theta^2 (\lambda_\theta^2 - 9\lambda_\phi^2 - 9\lambda_{\perp\phi}^2) - A_\phi^2 (2\lambda_\theta (\lambda_\theta + 3\lambda_\phi) + 9\lambda_{\perp\theta\phi}^2) + A_{\perp\phi}^2 (6\lambda_\theta\lambda_\phi - 2\lambda_\theta^2 - 9\lambda_{\theta\phi}^2) + 6A_\theta A_{\perp\phi} (\lambda_{\perp\theta\phi} (\lambda_\theta - 3\lambda_\phi) + 3\lambda_{\theta\phi}\lambda_{\perp\phi}) + 6A_\phi [A_\theta (\lambda_{\theta\phi} (\lambda_\theta + 3\lambda_\phi) + 3\lambda_{\perp\theta\phi}\lambda_{\perp\phi}) + A_{\perp\phi} (3\lambda_{\theta\phi}\lambda_{\perp\theta\phi} - 2\lambda_\theta\lambda_{\perp\phi})] \}$$

Restrictions on Invariants

Positivity condition together with normalization lead to the following inequalities:

$$\begin{aligned}0 &\leq w_{1,2,3} \leq 1 \\0 &\leq w_1w_2 + w_1w_3 + w_2w_3 \leq \frac{1}{3} \\0 &\leq w_1w_2w_3 \leq \frac{1}{27}\end{aligned}$$

Constraints for Invariants

Positivity condition together with normalization lead to the following inequalities:

$$\begin{aligned}0 &\leq w_{1,2,3} \leq 1 \\0 &\leq w_1w_2 + w_1w_3 + w_2w_3 \leq \frac{1}{3} \\0 &\leq w_1w_2w_3 \leq \frac{1}{27}\end{aligned}$$

$$U_1 + \frac{1}{3}U_2 \leq \frac{1}{12} \quad \rightarrow \quad U_1 \leq \frac{1}{12}, \quad U_2 \leq \frac{1}{4}$$

$$-\frac{1}{8} \leq R + T \leq \frac{3}{8}$$

Positivity domain and geometric model for PHENIX J/Ψ data

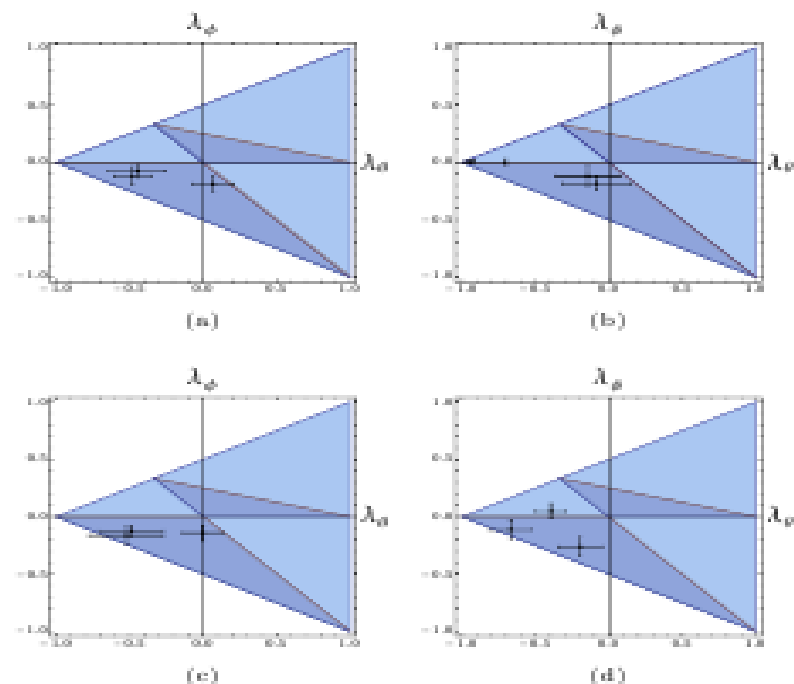
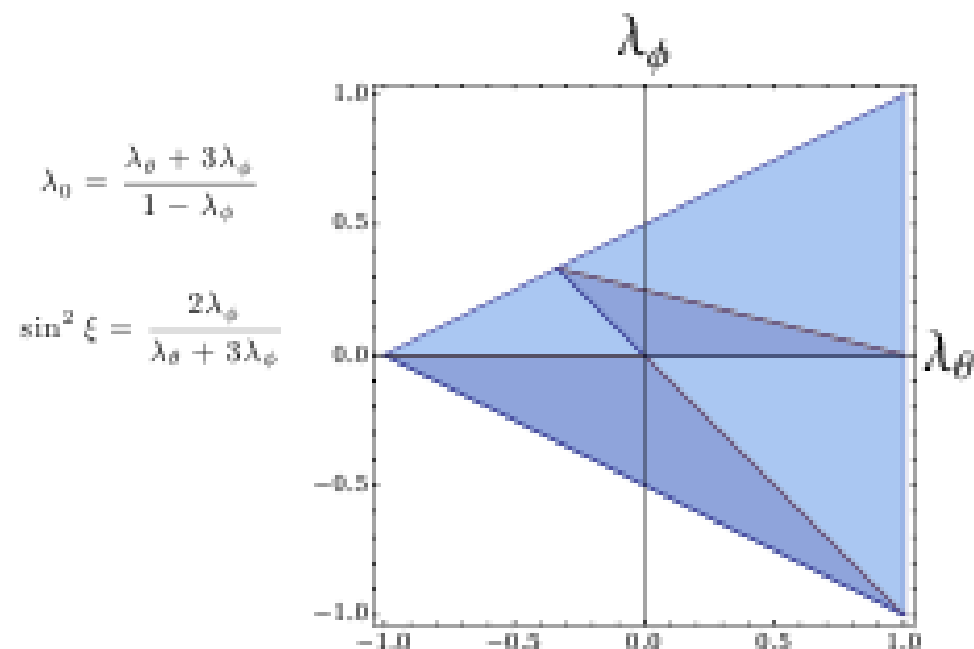


FIG. 2. Angular coefficients λ_θ and λ_ϕ measured by PHENIX [3]: (a) – HX frame, (b) – CS frame, (c) – GJ frame, (d) – GJP frame. Different points correspond to different values of transverse momentum. Only statistical errors are shown.

How invariant are they?

TABLE V. The values of invariants U_2 and T calculated for angular coefficients measured by PHENIX collaboration [4] in $J/\psi \rightarrow \mu^- \mu^+$ decays for $1.2 < y < 2.2$ in four reference frames at different values of p_T : (2 – 3 GeV), (3 – 4 GeV) and (4 – 10 GeV). Only statistical errors are taken into account.

p_T [GeV/c]	U_2			T		
	2 – 3	3 – 4	4 – 10	2 – 3	3 – 4	4 – 10
HX	3.0 ± 2.5	2.8 ± 1.7	1.2 ± 0.8	4.8 ± 6.5	1.7 ± 3.7	1.3 ± 1.4
CS	$> (6.2 \pm 0.4)$	1.0 ± 0.8	0.5 ± 0.8	$> (15.2 \pm 1.5)$	-0.1 ± 1.6	-0.3 ± 0.8
GJB	5.0 ± 3.6	3.8 ± 3.6	1.0 ± 0.6	10.5 ± 12.1	0.7 ± 6.9	0.9 ± 0.8
GJF	8.7 ± 4.4	3.0 ± 1.7	4.3 ± 2.2	24.3 ± 20.1	3.3 ± 3.5	7.4 ± 7.1

Invariants discussed in literature

→ Faccioli et al. (PRL 105 (2010) 061601)

$$\mathcal{F} = \frac{1 + \lambda_\theta + \lambda_\phi}{3 + \lambda_\theta}$$



rotations along
the y-axis in
the dilepton
rest frame

→ Faccioli et al. (PRD 81 (2010) 111502), Palestini (PRD 83 (2011) 031503)

$$(\lambda_0 \text{ (OT'05)}) = \tilde{\lambda} = \frac{\lambda_\theta + (3/2)\lambda_\phi}{1 - (1/2)\lambda_\phi} = \frac{3\mathcal{F} - 1}{1 - \mathcal{F}}$$



Faccioli et al. (PRD 83 (2011) 056008)

$$G = \frac{1 + \lambda_\theta - \lambda_\phi}{3 + \lambda_\theta}$$



along the x-
axis

→ Faccioli et al. (PRD 83 (2011) 056008)

$$\lambda_\theta$$



along the z-
axis

→ Ma,Qiu,Zhang (arXiv: 1703.04752 (2017))



general
method

Connection to invariants from arXiv: 1703.04752

$$\tilde{U}_1 = \frac{3}{\pi} U_1$$

$$\tilde{U}_2 = \frac{1}{5\pi} U_2$$

$$\tilde{W}_3 = \frac{1}{70\pi^2} (T + 7R)$$

$$\tilde{W}_4 = \frac{9}{20\pi} \tilde{U}_1^2 + \frac{15}{28\pi} \tilde{U}_2^2 + \frac{27}{14\pi} \tilde{U}_1 \tilde{U}_2 - \frac{9}{35\pi^3} \frac{1}{144} (45U_1 + 10R + 36M)$$

$$\tilde{W}_5 = \frac{5}{2\pi} \left(\frac{3}{7} \tilde{U}_1 + \frac{5}{11} \tilde{U}_2 \right) \tilde{W}_3 + \frac{3}{539\pi^4} \left(U_1 \left(-\frac{143}{4} + 429U_2 - 297T \right) + \frac{7}{3} U_2 R \right)$$

Invariants in terms of eigenvalues

$$w_1^{(a)}w_2^{(a)} + w_1^{(a)}w_3^{(a)} + w_2^{(a)}w_3^{(a)} = w_2^{(a)}w_3^{(a)} = 4U_1$$

$$w_1^{(s)}w_2^{(s)} + w_1^{(s)}w_3^{(s)} + w_2^{(s)}w_3^{(s)} = -\frac{4}{3}U_2$$
$$w_1^{(s)}w_2^{(s)}w_3^{(s)} = \frac{8}{27}T$$

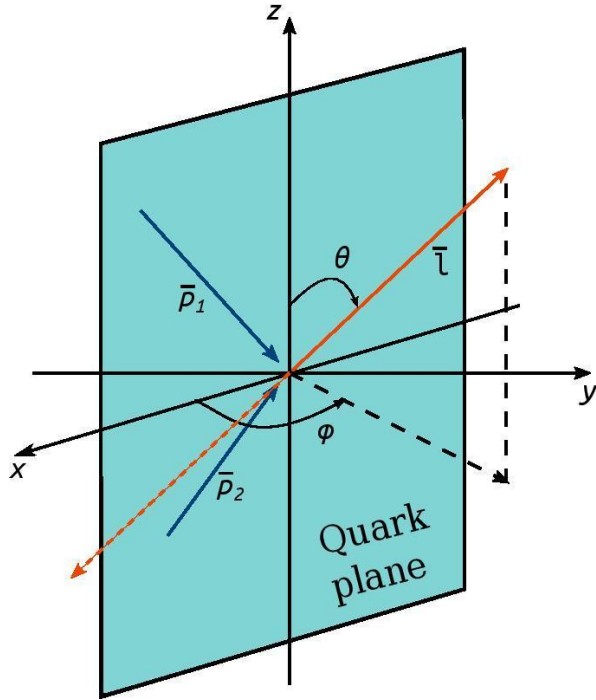
$$w_1w_2 + w_1w_3 + w_2w_3 = -4U_1 - \frac{4}{3}U_2$$
$$w_1w_2w_3 = \frac{8}{27}(T + R)$$

$$w_1^{(as)}w_2^{(as)} + w_1^{(as)}w_3^{(as)} + w_2^{(as)}w_3^{(as)} = w_2^{(as)}w_3^{(as)} = 4M$$

Special case

- Gottfried-Jackson frame - $z \parallel$ quark momenta
- Collins-Soper frame - $z \parallel$ bisection

related by
rotation
along the y-
axis



$$\frac{1}{\sigma} \frac{d\sigma}{d\Omega} = \frac{1}{3 + \lambda_\theta} \left(1 + \lambda_\theta \cos^2 \theta + \lambda_{\theta\phi} \sin 2\theta \cos \phi + \lambda_\phi \sin^2 \theta \cos 2\phi \right)$$

$$W^{ij} = \frac{1}{3 + \lambda_\theta} \begin{pmatrix} 1 - \lambda_\theta & -2\lambda_{\theta\phi} & 0 \\ -2\lambda_{\theta\phi} & 1 + \lambda_\theta - 2\lambda_\phi & 0 \\ 0 & 0 & 1 + \lambda_\theta + 2\lambda_\phi \end{pmatrix}$$

$$w_1 = \frac{1 + \lambda_\theta + 2\lambda_\phi}{3 + \lambda_\theta} \quad w_{2,3} = \frac{1 - \lambda_\phi \pm \sqrt{(\lambda_\theta - \lambda_\phi)^2 + 4\lambda_{\theta\phi}^2}}{3 + \lambda_\theta}$$

Faccioli invariant

Other special rotations

$$W^{ij} = \frac{1}{3 + \lambda_\theta} \begin{pmatrix} 1 - \lambda_\theta & -2\lambda_{\theta\phi} & -2\lambda_{\perp\theta\phi} \\ -2\lambda_{\theta\phi} & 1 + \lambda_\theta - 2\lambda_\phi & -2\lambda_{\perp\phi} \\ -2\lambda_{\perp\theta\phi} & -2\lambda_{\perp\phi} & 1 + \lambda_\theta + 2\lambda_\phi \end{pmatrix} \quad \bar{e}_x = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \quad \bar{e}_z = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$



$$e_x^\mu W_{\mu\nu} e_x^\nu = \frac{1 + \lambda_\theta - \lambda_\phi}{3 + \lambda_\theta} = G$$

$$e_z^\mu W_{\mu\nu} e_z^\nu = \frac{1 - \lambda_\theta}{3 + \lambda_\theta} \Rightarrow \lambda_\theta = \text{invariant}$$

CONCLUSIONS/OUTLOOK

- Invariants may be expressed via eigenvalues of density matrix and its components
- Corresponds to general structure of quantum theory
- May/should be used for data analysis (errors are currently large)

- Incorporating to calculations
- Higher spin
- Crossed processes