GPLs for Feynman integrals with unrationalizable algebraic symbol letters

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Robert M. Schabinger GPLs for integrals with intrinsically algebraic symbols

Outline

Background Finding Suitable Direct Integration Variables Weight-Four Result For Bhabha Integral What To Look At Next

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Background

- \bullet Difficulty With Algebraic $\epsilon\,\mathbf{d}\mathrm{ln}$ Differential Equations
- First Non-Trivial Example From Bhabha Scattering
- Polynomial Reduction

Pinding Suitable Direct Integration Variables

- Variable Changes From Polynomial Reduction
- Partial Rationalization Of The Kinematics
- Variable Change Via Parametrization By Lines
- ⁽³⁾ Weight-Four Result For Bhabha Integral
- What To Look At Next

Difficulty With Algebraic ϵ dln Differential Equations First Non-Trivial Example From Bhabha Scattering Polynomial Reduction

Difficulty With Algebraic ϵ dln Differential Equations

For
$$(w, z, m^2)$$
 and (w, z, m^2) , (w, z, m^2)

have the unrationalizable symbol letter:

$$r = \sqrt{(1+w^2z^2)(w+z)^2 + 2w\,z(w-z)^2 + 4w\,z^2(1+w^2)}$$

The algebraic part of the symbol alphabet reads:

$$\begin{aligned} \mathcal{L}_A &= \{r, -(1-w)(z-w)(1-w\,z) + r\,(1+w), \\ &-(1-w)\left(4w\,z + (w+z)(1+w\,z)\right) - r\,(1+w), \\ r^2 - 2w\,z^2(1-w)^2 + r\,(w+z)(1+w\,z), \\ r^2(1-z)^2 + 2z^2(z+w^2)(1+w^2z) + r\,(1-z)(1+z)\left(2w\,z - (w+z)(1+w\,z)\right) \} \end{aligned}$$

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Difficulty With Algebraic ϵ dln Differential Equations

Bonciani *et. al.*, JHEP **09** (2016) 091
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Construction of useful ϵ dln differential equations not straightforward!

J. M. Henn, Phys. Rev. Lett. 110 (2013) 251601

Difficulty With Algebraic ϵ dln Differential Equations First Non-Trivial Example From Bhabha Scattering Polynomial Reduction

Factorization Of Algebraic Functions Is Not Canonical

$$\begin{aligned} -(1-w)(z-w)(1-wz)+r(1+w) &= \\ & \frac{2w(1+z)(z+w^2)(2+z-w+wz(w+z)+r)}{2w^2+z-w+wz(w+z)+r} \\ -(1-w)(4wz+(w+z)(1+wz))-r(1+w) &= \\ & \frac{-8zw^2(1+z)^3(1+w^2z)(2w^2+z-w+wz(w+z)+r)}{(2+z-w+wz(w+z)+r)(-(w+z)(1-wz)+r)(-(z-w)(1+wz)+r)} \\ r^2-2wz^2(1-w)^2+r(w+z)(1+wz) &= \\ & \frac{-z^2(2+z-w+wz(w+z)+r)^2(2w^2+z-w+wz(w+z)+r)^2}{8(1+z)^2(1+w^2z)^2(-(w+z)(1-wz)+r)^2(-(z-w)(1+wz)+r)^{-2}} \\ r^2(1-z)^2+2z^2(z+w^2)(1+w^2z)+r(1-z)(1+z)(2wz-(w+z)(1+wz)) \\ &= \frac{2z^2(1+w^2z)^2(-(w+z)(1-wz)+r)^2}{(-(z-w)(1+wz)+r)^2} \end{aligned}$$

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First Non-Trivial Example From Bhabha Scattering

- J. M. Henn and V. A. Smirnov, JHEP 1311 (2013) 041;
- J. M. Henn, Amplitudes 2017 talk; C. Duhr, Amplitudes 2018 talk

From planar, massive Bhabha electron-positron scattering:

$$\int_{1}^{3} \int_{4}^{3} (s,t,m^{2}) = -e^{2\gamma_{E}\epsilon}\Gamma(1+2\epsilon) \left[\prod_{i=1}^{5} \int_{0}^{\infty} \mathrm{d}\alpha_{i}\right] \delta(1-\alpha_{5}) \mathcal{U}^{-1+3\epsilon} \mathcal{F}^{-1-2\epsilon}$$

$$\mathcal{U} = \alpha_1 \alpha_2 + \alpha_1 \alpha_3 + \alpha_1 \alpha_5 + \alpha_2 \alpha_3 + \alpha_2 \alpha_4 + \alpha_2 \alpha_5 + \alpha_3 \alpha_4 + \alpha_4 \alpha_5$$

$$\mathcal{F} = -s \alpha_2 \alpha_4 \alpha_5 - t \alpha_1 \alpha_2 \alpha_3 + m^2 (\alpha_4 + \alpha_5) \mathcal{U} - m^2 (\alpha_1 \alpha_2 \alpha_4 + \alpha_1 \alpha_2 \alpha_5 + \alpha_1 \alpha_3 \alpha_4 + \alpha_1 \alpha_3 \alpha_5 + \alpha_1 \alpha_4 \alpha_5 + \alpha_2 \alpha_3 \alpha_4 + \alpha_2 \alpha_3 \alpha_5 + \alpha_3 \alpha_4 \alpha_5)$$

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$$\mathcal{F} = -s \alpha_2 \alpha_4 \alpha_5 - t \alpha_1 \alpha_2 \alpha_3 + m^2 (\alpha_4 + \alpha_5) \mathcal{U} - m^2 (\alpha_1 \alpha_2 \alpha_4 + \alpha_1 \alpha_2 \alpha_5 + \alpha_1 \alpha_3 \alpha_4 + \alpha_1 \alpha_3 \alpha_5 + \alpha_1 \alpha_4 \alpha_5 + \alpha_2 \alpha_3 \alpha_4 + \alpha_2 \alpha_3 \alpha_5 + \alpha_3 \alpha_4 \alpha_5)$$

No evaluation in terms of standard multiple polylogarithms known!

Difficulty With Algebraic ϵ dln Differential Equations First Non-Trivial Example From Bhabha Scattering Polynomial Reduction

What Polynomial Reduction Has To Offer

F. Brown, Commun. Math. Phys. 287 (2009) 925; arXiv:0910.0114; E. Panzer, arXiv:1506.07243 implemented in HyperInt, E. Panzer, Comput. Phys. Commun. 188 (2015) 148

• For Feynman parameter integrals, can conceptualize polynomial reduction as an efficient "simulation" of each direct integration step (in terms of GPLs) of each possible integration order.

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not *linearly reducible*, can integrate out α_1 or α_3 only

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Variable Changes From Polynomial Reduction Partial Rationalization Of The Kinematics Variable Change Via Parametrization By Lines

Polynomial Reduction Is Still Useful In The Absence Of Linear Reducibility

Can easily find a good variable change by studying the irreducible polynomials which could appear after integrating out α_1 :

$$\begin{aligned} \mathcal{L}_{\alpha_{1}} &= \left\{ 1 + \alpha_{2} + \alpha_{3}, m^{2} - t \,\alpha_{2} \,\alpha_{3}, \alpha_{2} \left(1 + \alpha_{3} \right) + \left(1 + \alpha_{2} + \alpha_{3} \right) \alpha_{4}, \\ m^{2} \alpha_{2} &+ \left(m^{2} + \left(2 \, m^{2} - s \right) \alpha_{2} \right) \alpha_{4} + m^{2} \left(1 + \alpha_{2} + \alpha_{3} \right) \alpha_{4}^{2}, \\ \alpha_{2}^{2} \left(m^{2} + t \,\alpha_{3} \left(1 + \alpha_{3} \right) \right) + \left(2 \, m^{2} - s + t \,\alpha_{3} \right) \left(1 + \alpha_{2} + \alpha_{3} \right) \alpha_{2} \,\alpha_{4} \\ &+ m^{2} \left(1 + \alpha_{2} + \alpha_{3} \right)^{2} \alpha_{4}^{2} \right\} \end{aligned}$$

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 \implies the first variable change for $P_{7,11}$, $\alpha_4 = \frac{x_4 \alpha_2}{1 + \alpha_2 + \alpha_3}$, looks promising E. Panzer, arXiv:1506.07243

Variable Changes From Polynomial Reduction Partial Rationalization Of The Kinematics Variable Change Via Parametrization By Lines

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In contrast to the $P_{7,11}$ analysis, all other polynomials are still fine:

$$L_{\alpha_{1}} = \left\{ 1 + \alpha_{2} + \alpha_{3}, m^{2} - t \alpha_{2} \alpha_{3}, \alpha_{2} (1 + \alpha_{3} + x_{4}), \\ \frac{\alpha_{2}}{1 + \alpha_{2} + \alpha_{3}} \left(m^{2} (1 + \alpha_{2} + \alpha_{3}) + (m^{2} + (2 m^{2} - s) \alpha_{2}) x_{4} + m^{2} \alpha_{2} x_{4}^{2} \right), \\ \alpha_{2}^{2} (m^{2} + t \alpha_{3} (1 + \alpha_{3}) + (2 m^{2} - s + t \alpha_{3}) x_{4} + m^{2} x_{4}^{2}) \right\}$$

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 \implies GPLs with rational weights and arguments after α_2 integration

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Variable Changes From Polynomial Reduction Partial Rationalization Of The Kinematics Variable Change Via Parametrization By Lines

How To Proceed For The Final Two Integrations?

Rerunning the polynomial reduction in HyperInt, we get stuck again:

$$\begin{aligned} \mathcal{L}_{\alpha_{1}\alpha_{2}} &= \left\{ 1 + \alpha_{3}, 1 + \alpha_{3} + x_{4}, m^{2} + t \alpha_{3} + t \alpha_{3}^{2}, m^{2} + \left(2 m^{2} - s\right) x_{4} + m^{2} x_{4}^{2}, \\ m^{2} \left(1 + x_{4}\right) - s + \left(m^{2} (2 + x_{4}) - s\right) \alpha_{3}, m^{2} + \left(2 m^{2} - s\right) x_{4} + m^{2} x_{4}^{2} \\ &+ t (1 + x_{4}) \alpha_{3} + t \alpha_{3}^{2} \right\} \end{aligned}$$

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How to proceed without leaving the space of GPLs?

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How to proceed without leaving the space of GPLs?

- $m^2 + t \alpha_3 + t \alpha_3^2$ and $m^2 + (2m^2 s) x_4 + m^2 x_4^2$ no issue, dealt with via kinematic variable changes.
- $m^2 + (2m^2 s)x_4 + m^2x_4^2 + t(1 + x_4)\alpha_3 + t\alpha_3^2$ requires a non-trivial change of variables which maps the domain of the final integration parameter onto [0, 1].

Variable Changes From Polynomial Reduction Partial Rationalization Of The Kinematics Variable Change Via Parametrization By Lines

Kinematic Variable Changes Eliminate Some Roots

S. Caron-Huot and J. M. Henn, JHEP 1406 (2014) 114

$$s = -\frac{4m^2(v_2 - v_1)^2}{(1 - v_1)(1 + v_1)(1 - v_2)(1 + v_2)} \quad \text{and} \quad t = -\frac{m^2(v_2 - v_1)^2}{v_1 v_2}$$

get rid of two square roots which would otherwise arise:

$$m^{2} + t \alpha_{3} + t \alpha_{3}^{2} = \frac{m^{2} (v_{1} - (v_{2} - v_{1})\alpha_{3}) (v_{2} + (v_{2} - v_{1})\alpha_{3})}{v_{1}v_{2}}$$

and

$$\frac{m^2 + (2m^2 - s)x_4 + m^2x_4^2}{m^2((1+v_1)(1-v_2) + (1-v_1)(1+v_2)x_4)((1-v_1)(1+v_2) + (1+v_1)(1-v_2)x_4)}{(1-v_1)(1+v_1)(1-v_2)(1+v_2)}$$

Variable Changes From Polynomial Reduction Partial Rationalization Of The Kinematics Variable Change Via Parametrization By Lines

Variable Change Via Parametrization By Lines

E. Panzer, JHEP **1403** (2014) 071; M. Besier *et. al.*, Commun. Num. Theor. Phys. **13** (2019) 253 For technical reasons, set $\alpha_3 = \frac{x_3}{1-x_3}$. The x_3 integration leads to

$$\sqrt{1 + \frac{2(4\,m^2 - 2\,s - t)}{4\,m^2 - t}x_4 + x_4^2}$$

This obstruction is removed by finding a rational parametrization of:

$$1 + \frac{2(4m^2 - 2s - t)}{4m^2 - t}x_4 + x_4^2 = \rho^2.$$

Parametrizing the algebraic variety by lines, $\rho = y_4 \left(x_4 - x_4^{(0)} \right) + \rho^{(0)}$, through the rational point $\left(x_4^{(0)}, \rho^{(0)} \right) = \left(-\frac{2(4 m^2 - 2 s - t)}{4 m^2 - t}, 1 \right)$ leads to:

$$x_4 = \frac{2y_4\left(1 + \frac{4m^2 - 2s - t}{4m^2 - t}y_4\right)}{(1 - y_4)(1 + y_4)}$$

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Weight-Four Result For Bhabha Integral

From these considerations, I was able to directly evaluate at $\mathcal{O}(\epsilon^0)$ in terms of GPLs with the root $\sqrt{p_1(v_1, v_2)p_2(v_1, v_2)p_3(v_1, v_2)p_4(v_1, v_2)}$

$$p_1(v_1, v_2) = 1 + v_1 - v_2(1 - v_1)$$

$$p_2(v_1, v_2) = 1 + v_2 - v_1(1 - v_2)$$

$$p_3(v_1, v_2) = v_1(1 - v_1) + v_2(1 - v_2) + v_1v_2(2 - v_1 - v_2)$$

$$p_4(v_1, v_2) = v_1(1 + v_1) + v_2(1 + v_2) - v_1v_2(2 + v_1 + v_2)$$

in the weights of the most complicated GPLs. From GiNaC:

C. Bauer et. al., J. Symb. Comput. 33 (2002) 1;

J. Vollinga and S. Weinzierl, Comput. Phys. Commun. 167 (2005) 177

$$(-1/36, -8/35, 2) \approx -6.317550089475753330169497\ldots + \mathcal{O}(\epsilon)$$

confirmed with FIESTA 4, A. Smirnov, Comput. Phys. Commun. 204 (2016) 189

What To Look At Next

Direct integration methods are very powerful!

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- Look at the polylogarithmic families of integrals from Higgs plus jet production @ LHC to see if we can cope in the presence of (presumably) multiple unrationalizable square roots.
- Learn about elliptic multiple polylogarithm reduction identities by comparing the solution for the Bhabha integral of this talk with the solution given last year in terms of eMPLs.