# Point Cloud Strategies for Boosted Tops

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**Boosted Objects for New Physics Searches** 

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Based on work with Eric Metodiev and Jesse Thaler

<u>1712.07124</u> <u>1810.05165</u>

https://energyflow.network

## Boosted Event Topologies at the LHC



### Why Boosted Tops?

Many models of new physics contain boosted Standard Model final states

e.g. Z'  $\rightarrow$  tt, cascade decays, various SUSY scenarios

Boosted tops provide a way of testing and benchmarking multi-prong substructure techniques



Modern boosted top tagging is extremely effective! <u>Current CMS default</u> – AK8 PUPPI jets, b tagged subjets, Soft Drop mass cuts,  $\tau_{32}$  cut

[CMS-B2G-17-017, <u>1810.05905</u>]

Goal of this talk: Demonstrate alternative, bottom up approaches to top tagging that go back to the basics and attempt to harness the power of the ML revolution







# Jets as Point Clouds

# **Energy Flow Polynomials**

# **Energy Flow Networks**







# Jets as Point Clouds

# **Energy Flow Polynomials**

# **Energy Flow Networks**

### What is a let?

An unordered, variable length collection of particles

 $J(\{p_1^{\mu}, \dots, p_M^{\mu}\}) = J(\{p_{\pi(1)}^{\mu}, \dots, p_{\pi(M)}^{\mu}\}), \qquad \underbrace{M \ge 1}_{M \ge 1}, \qquad \underbrace{\forall \, \pi \in S_M}_{M \ge M}$ 

Multiplicity

Due to quantum-mechanical indistinguishability

Due to probabilistic nature of jet formation

### $p_i^{\mu}$ represents all the particle properties:

- Four-momentum  $(E, p_x, p_y, p_z)_i^{\mu}$
- Other quantum numbers (e.g. particle id, charge) •
- Experimental information (e.g. vertex info, quality criteria, PUPPI weights) •

Contrast with jet images d dimensional particles,  $N \times N$  pixels  $dN^2$  jet image inputs, dM point cloud inputs

Particles are the medium in which theory and experiment meet

Azimuthal Angle  $\phi$ 

Pseudorapidity  $\eta$ 

Success of CMS Particle Flow validates particles as fundamental objects in particle physics

### Point Clouds

#### Point cloud: "A set of data points in space" – Wikipedia

LIDAR data from self-driving car sensor

### Particle Collision Events as Point Clouds

Point cloud: "A set of data points in space" – Wikipedia





### Particle Collision Events as Point Clouds



**Processing Point Clouds** 

# Methods for processing point clouds/jets should respect the appropriate symmetries

Variable constituent multiplicity requires at least one of:

Preprocessing to another representation (jet images, N-subjettiness, etc.) Truncation to an (arbitrary) fixed size Recurrent NN structure

Particle permutation symmetry requires:

Permutation symmetric observables Permutation symmetric architectures

# **Processing Point Clouds**



Slide from Markus Stoye's talk

## 

#### Two key choices when analyzing jets

	How to represent the jet	How to analyze that representation		
•	Single expert observable	Threshold cut		
•	A few expert observables	<ul> <li>Multidimensional likelihood</li> </ul>		
•	Many expert observables Fixed Processing	<ul> <li>Boosted decision tree (BDT), shallow neural network (NN)</li> </ul>		
•	Jet images	<ul> <li>Convolutional NN (CNN)</li> </ul>		
•	N-subjettiness basis	<ul> <li>Dense neural network (DNN)</li> </ul>		
•	Energy flow polynomials	<ul> <li>Linear classification</li> </ul>		
•	List of particles	<ul> <li>Recurrent NN (RNN)</li> </ul>		
•	Clustering tree Flexible Processing	Recursive NN		
•	Set of particles	<ul> <li>Energy flow network</li> </ul>		

# Jet Representations +---- Analysis Tools

Two key choices when analyzing jets

How	to	re	present	the	iet
				4	

• Single expert observable

• A few expert observables

Many expert observables

N-subjettiness basis

Jet images

**Fixed Processing** 

How to	analyze	that	represe	ntation

- Threshold cut
- Multidimensional likelihood
- Boosted decision tree (BDT), shallow neural network (NN)
- Convolutional NN (CNN)
- Dense neural network (DNN)
- Energy flow polynomials
   Iinear classification
  - List of particles
    Clustering tree
    Set of particles
    Recurrent NN (RNN)
    Recursive NN
    Energy flow network







# Jets as Point Clouds

# **Energy Flow Polynomials**

Fixed point cloud processing

# **Energy Flow Networks**

## Energy Flow Polynomials (EFPs)

[PTK, Metodiev, Thaler, 1712.07124]



Generalizes many well-known and studied classes of energy correlators observables

A family of energy correlators with angular structures determined by multigraphs

$$\mathbf{Multigraph \ correspondence}$$

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### Linear Basis of IRC-Safe Observables

One can show via the Stone-Weierstrass approximation theorem that any IRC-safe observable is a linear combination of EFPs

$$\mathcal{S} \simeq \sum_{G \in \mathcal{G}} s_G \text{EFP}_G, \quad \mathcal{G} \text{ a set of multigraphs}$$

$$\bigwedge$$

$$Multivariate \ combinations \ of \ EFPs \ only \ require linear \ methods \ to \ achieve \ full \ generality$$

$$\bigwedge$$

$$Strategy: \text{Learn coefficients } s_G \text{ via linear regression or classification}$$

## Familiar Observables as EFPs



# Even angularities are exact linear combinations of EFPs

#### EFPs organized by degree d – number of edges



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# Computation Complexity of EFPs – Variable Elimination

Naive computation complexity of an energy correlator is  $\mathcal{O}(M^N)$ 

For ~100 particles this becomes intractable for N > 4

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EnergyCorrelator fjcontrib package gives up in this case



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EnergyCorrelator fjcontrib package gives up in this case



Variable elimination (VE) algorithm can speedup EFPs by finding efficient elimination ordering

$$\frac{2}{1 \cdot 3 \cdot 5} = \left( \sum_{i_1=1}^{M} \sum_{i_2=1}^{M} \sum_{i_3=1}^{M} z_{i_1} z_{i_2} z_{i_3} \theta_{i_1 i_2}^2 \theta_{i_2 i_3} \right) \left( \sum_{i_4=1}^{M} \sum_{i_5=1}^{M} z_{i_4} z_{i_5} \theta_{i_4 i_5}^4 \right) \quad \text{Disconnected is product} \\
= \sum_{i_1=1}^{M} \sum_{i_2=1}^{M} \sum_{i_3=1}^{M} \sum_{i_4=1}^{M} \sum_{i_5=1}^{M} \sum_{i_6=1}^{M} \sum_{i_6=1}^{M} \sum_{i_7=1}^{M} \sum_{i_8=1}^{M} z_{i_1} z_{i_2} z_{i_3} z_{i_4} z_{i_5} z_{i_6} z_{i_7} z_{i_8} \prod_{j=2}^{T} \theta_{i_1 i_j} \\
= \sum_{i_1=1}^{M} \sum_{i_1=1}^{M} \sum_{i_2=1}^{M} \sum_{i_3=1}^{M} \sum_{i_6=1}^{M} \sum_{i_6=1}^{M} \sum_{i_6=1}^{M} \sum_{i_6=1}^{M} \sum_{i_7=1}^{M} \sum_{i_8=1}^{M} z_{i_1} z_{i_2} z_{i_3} z_{i_4} z_{i_5} z_{i_6} z_{i_7} z_{i_8} \prod_{j=2}^{T} \theta_{i_1 i_j} \\
= \sum_{i_1=1}^{M} \sum_{i_1=1}^{M} \sum_{i_2=1}^{M} \sum_{i_2=1}^{M} \sum_{i_2=1}^{M} \sum_{i_6=1}^{M} \sum_{i_6=1}^{M} \sum_{i_6=1}^{M} \sum_{i_6=1}^{M} \sum_{i_7=1}^{M} \sum_{i_8=1}^{M} z_{i_1} z_{i_2} z_{i_3} z_{i_4} z_{i_5} z_{i_6} z_{i_7} z_{i_8} \prod_{j=2}^{T} \theta_{i_1 i_j} \\
= \sum_{i_1=1}^{M} \sum_{i_1=1}^{M} \sum_{i_2=1}^{M} \sum_{i_2=1}^{M} \sum_{i_2=1}^{M} \sum_{i_6=1}^{M} \sum_{i_6=1}^{M}$$

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### **EFPs for Boosted Tops**









# Jets as Point Clouds

# **Energy Flow Polynomials**

# **Energy Flow Networks**

Flexible/learnable point cloud processing

(EFNs for Q/G talk on Thursday @ ML4Jets!)

### Symmetric Function Parametrization

A general permutation-symmetric function is *additive* in a latent space

Deep Sets: Namespace for additive symmetric function parametrization

**Deep Sets** 

[1703.06114]

Manzil Zaheer<sup>1,2</sup>, Satwik Kottur<sup>1</sup>, Siamak Ravanbhakhsh<sup>1</sup>, Barnabás Póczos<sup>1</sup>, Ruslan Salakhutdinov<sup>1</sup>, Alexander J Smola<sup>1,2</sup> <sup>1</sup> Carnegie Mellon University <sup>2</sup> Amazon Web Services

**Deep Sets Theorem [63].** Let  $\mathfrak{X} \subset \mathbb{R}^d$  be compact,  $X \subset 2^{\mathfrak{X}}$  be the space of sets with bounded cardinality of elements in  $\mathfrak{X}$ , and  $Y \subset \mathbb{R}$  be a bounded interval. Consider a continuous function  $f: X \to Y$  that is invariant under permutations of its inputs, i.e.  $f(x_1, \ldots, x_M) =$  $f(x_{\pi(1)}, \ldots, x_{\pi(M)})$  for all  $x_i \in \mathfrak{X}$  and  $\pi \in S_M$ . Then there exists a sufficiently large integer  $\ell$  and continuous functions  $\Phi: \mathfrak{X} \to \mathbb{R}^{\ell}$ ,  $F: \mathbb{R}^{\ell} \to Y$  such that the following holds to an arbitrarily good approximation:<sup>1</sup>

$$f(\{x_1, \dots, x_M\}) = F\left(\sum_{i=1}^M \Phi(x_i)\right).$$
 (2.1)

# Symmetric Function Parametrization

A general permutation-symmetric function is *additive* in a latent space

Deep Sets: Namespace for additive symmetric function parametrization



### **Deep Sets for Particle Jets**

[PTK, Metodiev, Thaler, 1810.05165]

Particle Flow Network (PFN)

$$\operatorname{PFN}(\{p_1^{\mu}, \dots, p_M^{\mu}\}) = F\left(\sum_{i=1}^M \Phi(p_i^{\mu})\right)$$

Fully general latent space



$$\operatorname{EFN}(\{p_1^{\mu},\ldots,p_M^{\mu}\}) = F\left(\sum_{i=1}^M z_i \Phi(\hat{p}_i)\right)$$

```
IRC-safe latent space
```

Particles

Observable



# Approximating $\Phi$ and F with Neural Networks

Employ neural networks as arbitrary function approximators

Use fully-connected networks for simplicity

Default sizes  $-\Phi$ : (100, 100,  $\ell$ ), F: (100, 100, 100)



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## Top Jet Samples and Other Methods

#### Common top and QCD dijet samples for standardized benchmarking

 $p_T \in [550, 650]$  GeV, AK8 jets, fully-merged, Delphes simulation, 2m jets total

Approach	AUC	Acc.	1/eB @ (eS=0.3)	Contact	Comments
LoLa	0.979	0.928		G. Kasieczka S. Leiss	Preliminary number, based on LoLa
LBN	0.981	0.931	863	M. Rieger	Preliminary number
CNN	0.981	0.93	780	D. Shih	Model from (1803.00107)
P-CNN (1D CNN)	0.980	0.930	782	H. Qu, L. Gouskos	Preliminary, use kinematic info only
6-body N-subs. (+mass and pT) NN	0.979	0.922	856	K. Nordstrom	Based on 1807.04769
8-body N-subs. (+mass and pT) NN	0.980	0.928	795	K. Nordstrom	Based on 1807.04769
Linear EFPs	0.980	0.932	380	PTK, E. Metodiev	d<= 7, chi <= 3 EFPs with FLD. Based on 1712.07124
Particle Flow Network (PFN)	0.982	0.932	888	PTK, E. Metodiev	Median over ten trainings. Based on Table 5 in 1810.05165
Energy Flow Network (EFN)	0.979	0.927	619	PTK, E. Metodiev	Median over ten trainings. Based on Table 5 in 1810.05165

## **Classification Performance**



Latent space dimension  $\ell$  = 256

EFN/PFN rotation and reflection preprocessing helpful

EFPs are comparable to EFN and even better at high signal efficiency

### **EFN Latent Dimension Sweep**



# Energy Flow Network Visualization

EFN observables are two-dimensional geometric functions

Visualize EFN observables as *filters* in the translated rapidity-azimuth plane



Jet images as EFN filters

[Cogan, Kagan, Strauss, Schwartzman, 2014] [de Oliviera, Kagan, Mackey, Nachman, Schwartzman, 2015]

#### Moments as EFN filters



[Donoghue, Low, Pi, 1979] [Gur-Ari, Papucci, Perez, 2011]

# **Energy Flow Network Visualization**



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*l* = 8





ℓ = I6

 $\ell = 4$ 



*ℓ* = 32



*ℓ* = 64



*ℓ* = 128



#### With rotation/reflection preprocessing





ℓ = I6

*ℓ* = 32



*l* = 64



*l* = 128









# Jets as Point Clouds

Jets have the same symmetries as point clouds Respecting symmetries key for maximal performance

# **Energy Flow Polynomials**

Linear basis of IRC-safe observables Incredibly simple architecture competes with modern ML

# **Energy Flow Networks**

Excellent performance, fascinating visualizations via IRC safety

(EFNs for Q/G talk on Thursday @ ML4Jets!)

### EnergyFlow Python Package

Implements variable elimination for efficient EFP computation

Contains EFN and PFN implementations in Keras

CNN, DNN architectures included for easy model comparison

Several detailed examples demonstrating how to train models and make visualizations



Do	ocs » Home
N	lelcome to EnergyFlow
En Po (Pl	ergyFlow is a Python package for a suite of particle physics tools for computing Energy Flow lynomials (EFPs) and implementing Energy Flow Networks (EFNs) and Particle Flow Networks FNs). Here are several of the features and functionalities provided by the EnergyFlow package:
•	Energy Flow Polynomials: EFPs are a collection of jet substructure observables which form a complete linear basis of IRC-safe observables. EnergyFlow provides tools to compute EFPs on events for several energy and angular measures as well as custom measures.
•	Energy Flow Networks: EFNs are infrared- and collinear-safe models designed for learning from collider events as unordered, variable-length sets of particles. EnergyFlow contains customizable Keras implementations of EFNs.
•	Particle Flow Networks: PFNs are general models designed for learning from collider events as unordered, variable-length sets of particles, based on the Deep Sets framework. EnergyFlow contains customizable Keras implementations of PFNs.
Be su ad the	yond the primary functions described above, the EnergyFlow package also provides useful pplementary features. These include a large quark/gluon jet dataset, implementations of ditional machine learning architectures useful for collider physics, and many examples exhibiting e usage of the package.
•	Jet Tagging Datasets: A dataset of 2 million simulated quark and gluon jets is provided.
•	Additional Architectures: Implementations of other architectures useful for particle physics are also provided, such as convolutional neural networks (CNNs) for jet images.
	Detailed Examples: Examples showcasing EFPs, EFNs, PFNs, and more. Also see the EFP Demo.

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# Thank You!

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### **Classification Performance**

