

# SwissFEL Undulator section BBA and optimisation

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CLIC Week 2019

22.1.2019

CERN, Geneva

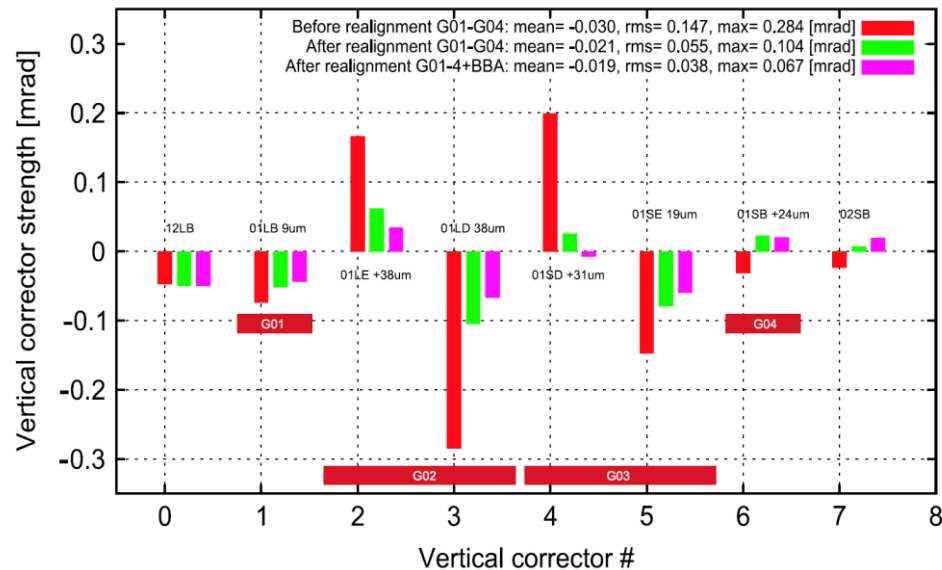
# Introduction: Success story of Swiss Light Source (1/3)

- Vertical emittance tuning at SLS
  - $\varepsilon_y \sim 1$  pm achieved for the first time\*, which is similar to ILC/CLIC damping ring specification
  - Procedure:
    - Re-survey in the tunnel
    - Remote girder re-alignment
    - Systematic coupling and vertical dispersion correction
    - Random optimisation

\* M. Aiba, M. Boge, N. Milas and A Streun, NIM-A, 694, pp.133-139 (2012)

# Introduction: Success story of Swiss Light Source (2/3)

- Girder alignment with circulating beam + orbit feedback!
  - Remote alignment based on tunnel survey data
  - Immediate reduction in vertical corrector strengths: **Before**, **after** girder alignment and **After Quad-BPM BBA**



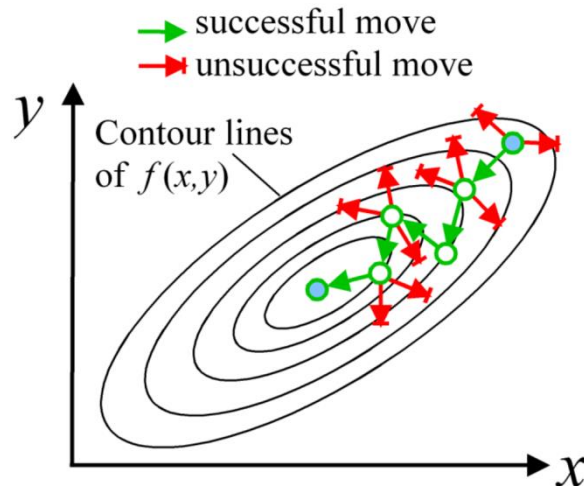
Corrector strength is as informative as BPM:

Necessity of corrector indicates existence of misalignments!

# Introduction: Success story of Swiss Light Source (3/3)

- Random optimisation after all the systematic corrections

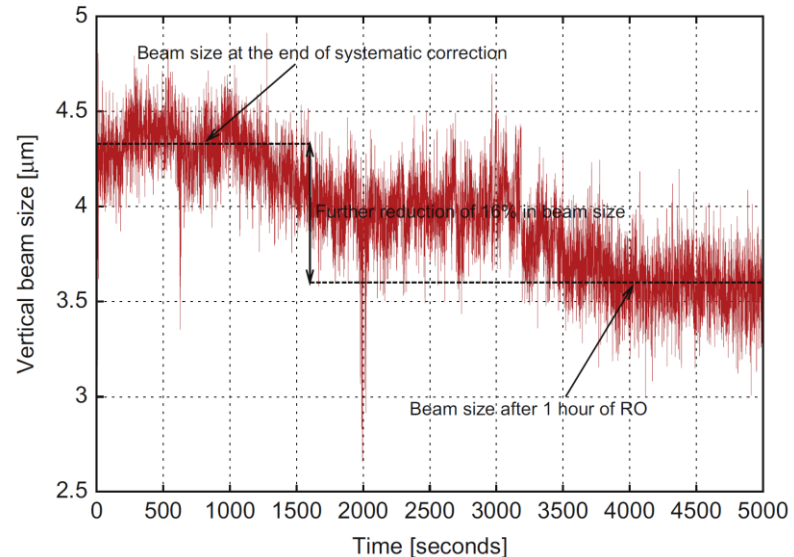
Example: 2 knobs ( $x, y$ )



SLS emittance tuning:

Figure of merit = Ver. Beam size

Knobs = 24 non-dispersive skew quads



1.3  $\mu\text{m}$   
 ↓  
 0.9  $\mu\text{m}$ !

Systematic corrections may never be perfect due to measurement errors, knob errors (hysteresis) etc. Random optimisation can cover these deficiencies!

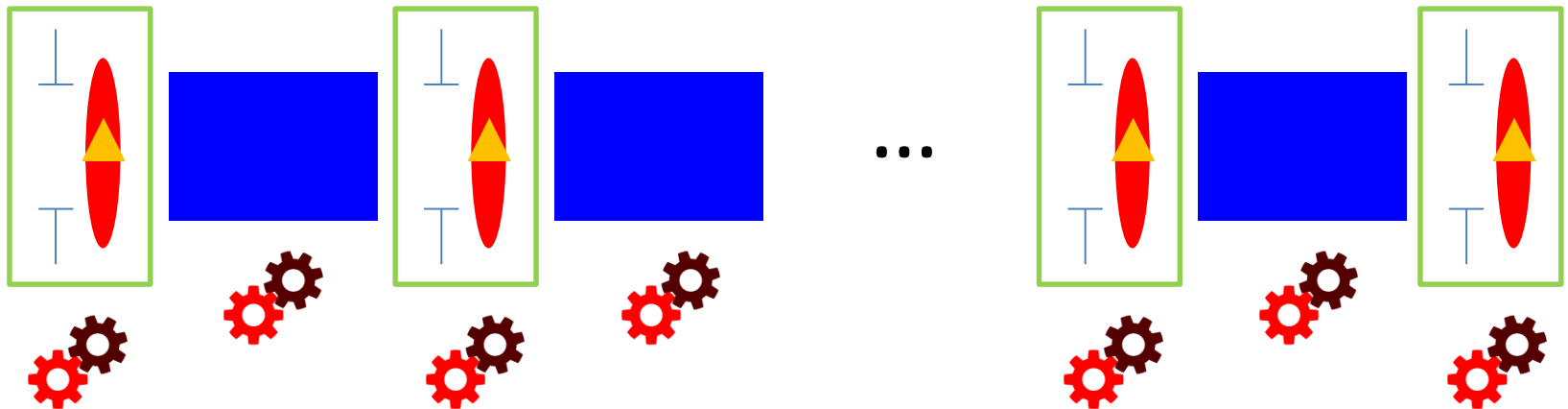
# BBA of SwissFEL undulator section (1/6)

- Goal:
  - Trajectory straightness of  $2\sim 3\ \mu\text{m}$ ! (at 5.8 GeV e-beam energy) over 13 undulator modules
- Procedure:
  - “Corrector based alignment”, inspired by SLS experience, to align BPMs using electron beam\*
  - Undulator alignment with “Alignment quad” using electron beam
  - Random optimisation using photon beam (laser pulse energy) as the optimization target

\* cf. Photon-beam-based alignment, e.g. Fermi, SACLA  
DFS-like electron-beam-based alignment, e.g. LCLS

# BBA of SwissFEL undulator section (2/6)

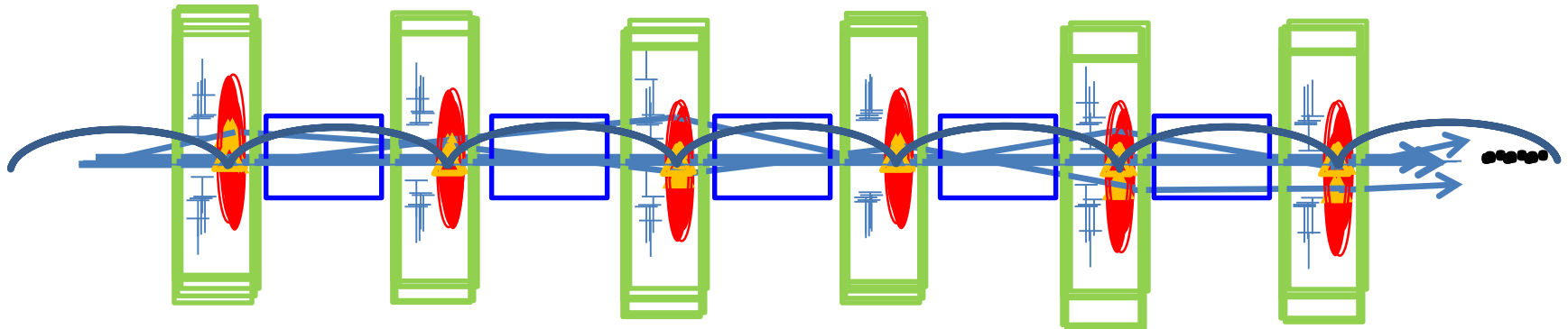
- Aramis undulator section
  - Fully periodic with 13 undulators, ~60 m
  - Quad+Corrector and BPM between each undulator
  - Cavity BPM, resolution of 1  $\mu\text{m}$  or higher
  - Undulators and Q+BPM units are both motorized



# BBA of SwissFEL undulator section (3/6)

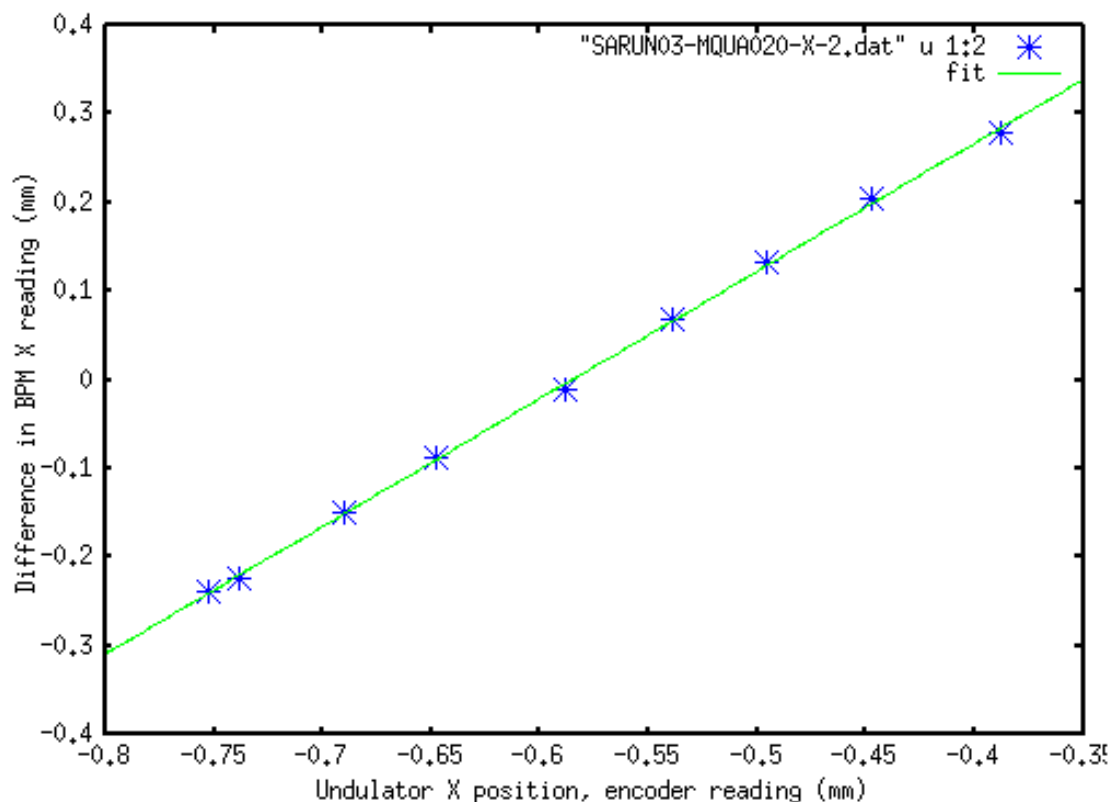
- Corrector-based BPM alignment

First the quadrupoles are aligned to the undulator centre  
 → the deviation of corrector strength w.r.t. the average value  
 → the quadrupoles are aligned to the undulator centre  
 → to take into account periodic/uniform field error (e.g. geomagnetism)



# BBA of SwissFEL undulator section (4/6)

- Undulator alignment using “Alignment quad”



Undulator centre in the horizontal plane was found to be around -0.58 mm.  
Note that the encoder has its own reference and -0.58 mm is not alignment error.



# BBA of SwissFEL undulator section (5/6)

- First BBA in October, 2017 (Beam energy  $\sim 1.8$  GeV)
  - 16th, evening
    - Quad-BPM relative alignment (3~4 hours)
    - BPM BBA (10 min)
  - 17th-18th
    - Beam setup, preparing for lasing
  - 18th, evening
    - Undulator alignment ( $\sim 8$  hours)
  - 19th
    - Beam setup for lasing  $\rightarrow 17 \mu\text{J}$  photon pulse energy
  - 19th, evening
    - Random optimisation: BPM offsets (soft Epics channels) were varied, with a trajectory feedback loop running, to maximise photon pulse energy (1~2 hours)  
 $\rightarrow 37 \mu\text{J}$
    - Phase shifter adjustment(1~2 hours)  $\rightarrow 50 \mu\text{J}$  (Gain curve saturated)

Within  $\sim 16$  hours (0.5+1+0.5 shifts), the first undulator section BBA was done. Note that the time consuming parts (Q-BPM alignment, Undulator alignment) are basically “one-time operation” or at least valid for long time once done.

# BBA of SwissFEL undulator section (6/6)

- Precision of systematic BBA
  - Found from the trajectory change through Random optimisation

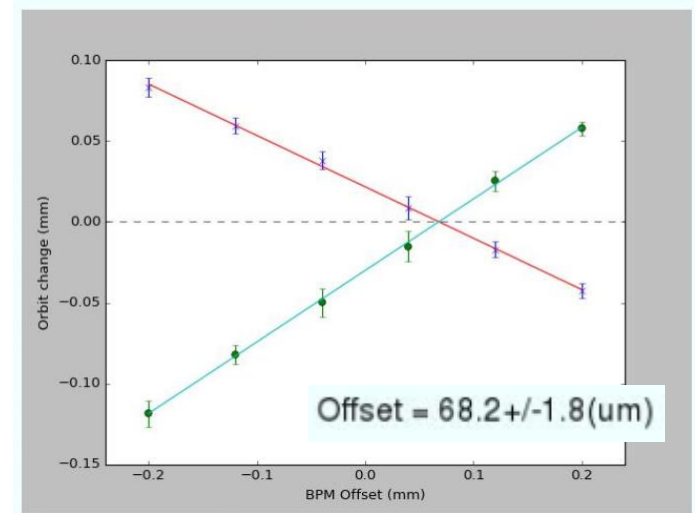
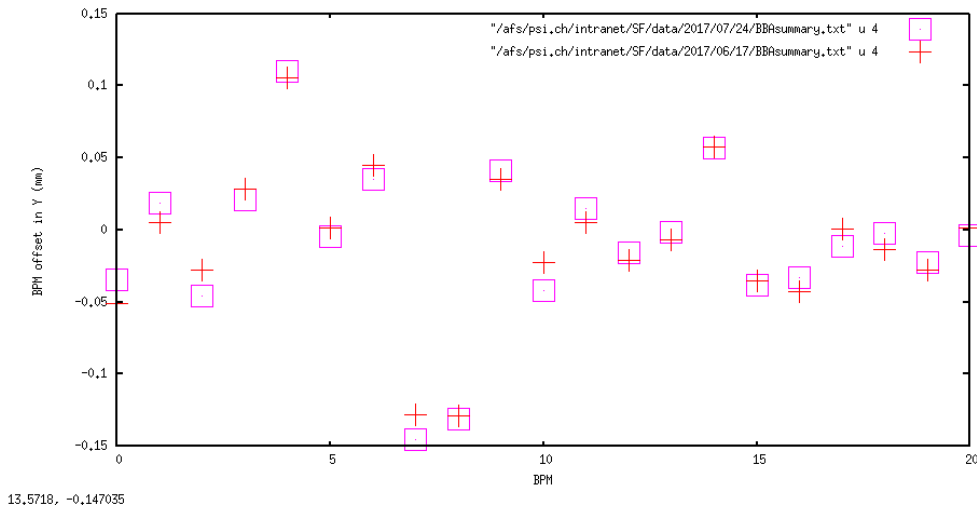
Energy (GeV)	1.8	2.45	5.8
Horizontal ( $\mu\text{m}$ )	19.1	16.4	<b>5.9~6.9</b>
Vertical ( $\mu\text{m}$ )	20.4	11.2	<b>4.7~6.3</b>

Precision for 5.8 GeV beam is scaled  
from the results of 1.8 GeV and 2.45 GeV beams

Very good precision (as expected from simulation, see backup slide) was achieved.

Once lasing with detectable pulse energy can be obtained, Random optimisation (or any other algorithm) can realise almost perfect orbit at the end.

# Alignment precision – some numbers



- Left: (Injector) BPM-Quad offsets, measured in June and July 2017
  - No significant change over time
  - RMS offset of 53  $\mu\text{m}$  (Precision of Fiducialisation+Survey)
- A large vertical misalignment ( $\sim 300 \mu\text{m}$ ) in one of Quad-BPM pairs was found from BBA and fixed in the tunnel (re-alignment)
- Right: Typical offset measurement result
  - Typical statistical error is a few  $\mu\text{m}$

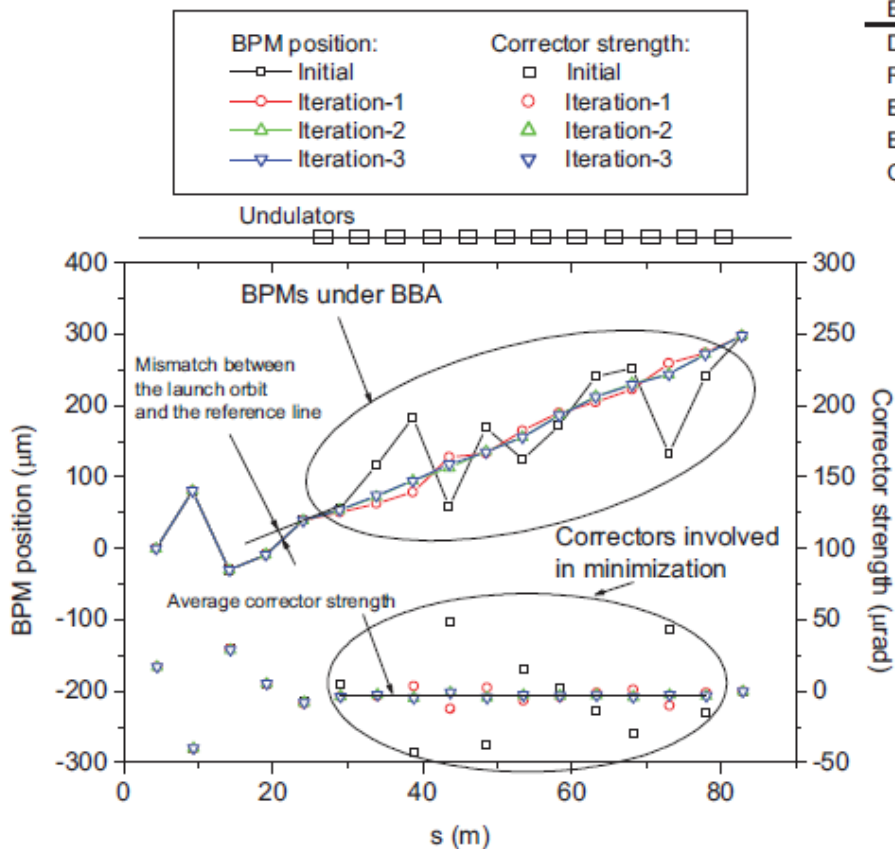
# Summary

- SwissFEL undulator section BBA
  - Unique approach “Corrector-based alignment” was applied to align inter-undulator BPMs
  - Undulator alignment using “Alignment quad” was successful
  - Empirical optimisation is quite useful for delicate machine tunings, for instance  $\mu\text{m}$ -level BBA

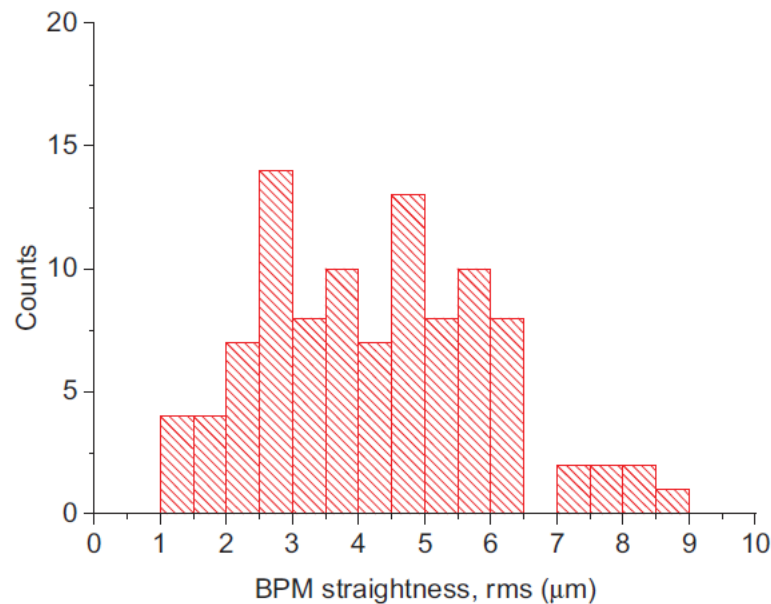


Backup slides

# Simulation\*



Error source	Value	Remarks
DC dipolar kick	$\sim 3 \mu\text{rad/unit}$	$\sim 1/3$ of the geomagnetism
Random dipolar kick	$\pm 1 \mu\text{rad (U)}$	At both ends of undulator
BPM noise	$1 \mu\text{m rms (G)}$	
BPM-Quad misalignment	$\pm 5 \mu\text{m (U)}$	
Corrector str. error	$50 \text{ nrad rms (G)}$	



\* M. Aiba and M. Boge, Proc. of FEL, pp.293-296 (2012)

# Flattening corrector strength

## BBA: Undulator Section BPMs

Response matrix BBA

Choose plane: **BBA: Undulator Section BPMs**

Horizontal

Response matrix: Response matrix BBA

Section: 3-13 / Source: Model

Beam energy at Aramis beam line (MeV):

Show corrector currents

Take energy from machine

Move BPMs

Message:

Response matrix BBA

Choose plane: **BBA: Undulator Section BPMs**

Horizontal

Response matrix: Response matrix BBA

Section: 3-13 / Source: Model

Beam energy at Aramis beam line (MeV):

Show corrector currents

Take energy from machine

Move BPMs

Message:

Response matrix BBA

Choose plane: **BBA: Undulator Section BPMs**

Horizontal

Response matrix: Response matrix BBA

Section: 3-13 / Source: Model

Beam energy at Aramis beam line (MeV):

Show corrector currents

Take energy from machine

Move BPMs

Message:

Corrector ID	Corrector current (I)
2	0.06
3	0.25
4	0.25
5	0.25
6	0.25
7	0.25
8	0.25
9	0.24
10	0.25
11	0.26
12	0.24
13	0.25
14	-0.08

Application started

Help Exit

# FEL pointing

- Pointing of FEL is controlled by moving the entire undulator section as a “single block”
- Example – The undulator section points slightly down in the vertical plane:

