Inputs and Procedures of Jet Reconstruction in ATLAS



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Introduction

- Jets are important for almost all ATLAS analyses
- Most use anti- k_T jets with R=0.4 (small-R) or R=1.0 (large-R)
 - Some use both
 - Also looking at other sizes in some cases
- How we build and calibrate jets has wide-reaching impact
 > What is(are) the best choice(s)?
- Jet energy scale uncertainty and jet energy resolution dominate many searches and measurements
 - Work to reduce these uncertainties as much as possible



Jet Reco and Calibration Chain



- 1. Inputs
- 2. Jet reconstruction
- 3. Pile-up corrections
- 4. MC-based calibration
 - Match truth to reco jets, then calculate reco/truth "response"
 - Correct the jet 4-momentum to truth level
- 5. In-situ calibration for data



Jet Reco and Calibration Chain



- 1. Inputs
- 2. Jet reconstruction
- 3. Pile-up corrections
- 4. MC-based calibration
 - Match truth to reco jets, then calculate reco/truth "response"
 - Correct the jet 4-momentum to particle level
 - 4.1 (small-R) Global sequential calibration
 - Reduce flavor dependence and correct various detector effects
- 5. In-situ calibration for data



Outline



- 1. Small-R, update on jet energy scale/resolution (JES/JER)
- 2. Large-R, in-situ calibration with 80 fb⁻¹
- 3. Large-R, alternative inputs and grooming strategies



Small-R JES/JER

Taking advantage of particle flow jets

Small-R JES/JER Jet Inputs PERF-2014-07, PERF-2015-09

- Topocluster: calorimeters only
 - 4σ-above-noise seed cells, iteratively add all
 2σ neighbors and cells surrounding them
 - These are called EM-scale topoclusters
 - Topocluster are corrected to point at the primary vertex (origin correction)
- Particle flow (PFlow): Subtract matched tracks' momentum from topoclusters
 - Remaining clusters and tracks form PFlow objects
 - Only PFlow objects matched to primary vertex tracks are used for jet building
 - Great performance for low p_T







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PFlow/EM-scale Jets Resolution

JETM-2018-005



- ATLAS jet usage is moving toward PFlow
- It is now the primary option in ATLAS
 - Better response
 - Better resolution at low p_T , and comparable to EM-scale at high p_T
- EM-scale topocluster jets still used by some analyses





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Large-R, In-situ Calibration

Updated with 80 fb⁻¹

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In-situ Calibration JES

JETM-2019-05, Eur. Phys. J. C 79 (2019) 135

- Derived from a jet recoiling against a well-measured object:
 - 1. Z boson or γ as reference objects
 - 2. Several lower- p_T small-R jets for high- p_T jets
- Combining three techniques to cover the full p_T range
 - Z+jet method runs out of statistics ~450 GeV
 - γ +jet is used until ~1 TeV
 - Use multijet method above that threshold
- Combine methods in overlapping regions
 - Overall uncertainty can be reduced as overlapping regions agree and each method's uncertainties are mostly independent





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Large-R Jet In-situ Calibration JES Uncertainty JETM-2019-05, Eur. Phys. J. C 79 (2019) 135

- Large reduction compared to without in-situ calibration
 - Total uncertainty depends on the assumption of the topology (W, Z, or top) and flavor (quark or gluon initiated) composition of the jets





Large-R Jet In-situ Calibration In-situ Calibration—JMS/JMR

- Eur. Phys. J. C 79 (2019) 135
- For large-R jets, we also need in-situ calibration for the mass
- Two methods for in-situ mass calibration:
 - 1. Forward-folding: Use high purity top sample, shift and stretch jet mass resolution function so that the simulation matches the data
 - 2. $R_{track}^{m} = \frac{m_{track}}{m_{calo}}$: Tracker provides an independent (charged only) measurement of a jet, so any deviation of the double ratio, $\frac{R_{MC}}{R_{Data}}$, from 1 provides an estimate of the scale uncertainty
- Forward-folding has smaller uncertainty, but R_{track} covers a much broader p_T and mass range





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Large-R, Alternative Inputs and Jet Grooming

Inputs, constituent-level pile-up suppressions, and grooming scan

Alternative Inputs and Jet Grooming Large-R Jet Inputs

- Topocluster: calorimeters only
 - 4 σ -above-noise seed cells, add all 2 σ neighbors and cells surrounding them
 - Calibrate to account for EM and HAD differences, dead material and out-of-cluster deposits to get Local Cell Weighting (LCW) topoclusters
 - Topocluster are corrected to point at the primary vertex (origin correction)
- Particle flow (PFlow): Subtract matched tracks' momentum from topoclusters
 - Remaining clusters and hard-scatter tracks form PFlow objects
 - Remove PFlow object matched to non-primary vertex tracks
 - Great performance for low p_T
- Track-CaloCluster (TCC): Use energy from topoclusters and angle from tracks
 - For multiple-to-multiple matching, energy is shared among tracks to create multiple TCC objects
 - Remove TCC objects with non-primary vertex tracks
 - Great performance for high p_T



Alternative Inputs and Jet Grooming **Pile-up Correction**

From inputs:

- Topocluster: noise suppression
- PFlow/TCC: charged objects not associated with primary vertex are rejected Simulation Preliminary
- Constituents-level (topocluster) correction:
 - Voronoi Subtraction (VS): correct constituent's energy by $\rho \cdot A_{\text{Voronoi}}^{5}$
 - *ρ*: transverse momentum density
 - Constituent Subtraction (CS): Add ghosts with $p_T^g = \rho \cdot A_q$ then:

otherwise:

If
$$p_{\mathrm{T,i}} \ge p_{\mathrm{T,k}}^g$$
: $p_{\mathrm{T,i}} \longrightarrow p_{\mathrm{T,i}} - p_{\mathrm{T,k}}^g$,
 $p_{\mathrm{T,k}}^g \longrightarrow 0 \text{ GeV};$
otherwise: $p_{\mathrm{T,k}}^g \longrightarrow p_{\mathrm{T,k}}^g - p_{\mathrm{T,i}},$
 $p_{\mathrm{T,i}} \longrightarrow 0 \text{ GeV},$

- SoftKiller (SK): p_T cut so half of $\eta \phi$ grid spaces are empty
- PUPPI: p_T cut based on information from nearby constituents
- Jet-level: Grooming

New!	<	Grooming Algorithm	Name	Parameters Tested
		Soft Drop	SD	$(z_{\text{cut}}, \beta) \in [0.1] \times [0, 0.5, 1]$
		Bottom-up Soft Drop	BUSD	$(z_{\text{cut}}, \beta) \in [0.05, 0.1] \times [0, 0.5, 1]$
		Recursive Soft Drop	RSD	$(z_{\text{cut}}, \beta, N) \in [0.05, 0.1] \times [0, 0.5, 1] \times [2, 3, 5, \infty]$
		Pruning	Pruned	$(z_{\text{cut}}, R_{\text{cut}}) \in [0.15] \times [0.25]$
		Trimming	Trimmed	$(f_{\text{cut}}, R_{\text{sub}}) \in [5, 9]\% \times [0.1, 0.2]$



Based on previous study (ATL-PHYS-PUB-2017-020)

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Alternative Inputs and Jet Grooming Large-R Jet Performance Study

- Three inputs (Topocluster, PFlow, TCC)
- Many pile-up suppression techniques
 - Some of them can also be combined
 - Based on previous study (<u>ATL-PHYS-PUB-2017-020</u>), we choose:
 - Constituent Subtraction + SoftKiller (CS+SK)
 - Voronoi Subtraction + SoftKiller (VS+SK)
 - PUPPI for PFlow only
- Two methods:
- Compare the impact of different pile-up mitigation techniques on individual clusters with and without pile-up included in simulation ("DigiTruth")
- 2. Scan over choices of input, constituent-level pile-up suppression, and grooming, and compare them with ATLAS' standard trimmed jet
 - Compare the performance. Specifically:
 - Pile-up stability
 - Topology dependence
 - Tagging performance





- Showing $E^{DigiTruth}$ (no pile-up) over E^{reco} (with pile-up)
 - $E^{DigiTruth}$ does include underlying event \rightarrow 1 is not necessary the ideal value
- Majority of clusters tend to be dominated by hard-scatter (HS) or pile-up (PU)
 - So we will call $\frac{E^{DigiTruth}}{E^{reco}}$ > 0.5 a HS cluster and < 0.5 a PU cluster
- CS+SK is removing pile-up; HS clusters are more pronounced

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- All algorithms remove more pile-up than hard-scatter clusters
- Standard ATLAS trimming is doing well





- Quantifying the effect of pile-up on the W mass:
 - 1. Take the mass distribution of W-jet sample in a N_{PV} bin
 - 2. Fit a Gaussian on the W mass peak
 - 3. Plot either the central value or the width as a function of N_{PV}
 - Fit a line and measure the slope 4.

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Alternative Inputs and Jet Grooming WMass Peak Values Slope

ATL-PHYS-PUB-2019-027



- Row: grooming algorithm (e.g. standard ATLAS trimming)
- Column: jet constituent type
- Number: Slope (also color coded)
- Prefer zero (pile-up stable)



Alternative Inputs and Jet Grooming ' Mass Peak Values Slope

ATL-PHYS-PUB-2019-027



LCTopo

PFlow is more stable than topocluster, even unmodified

Also reduce the width



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Jet Constituent Type

Alternative Inputs and Jet Grooming Mass Peak Values Slope

ATL-PHYS-PUB-2019-027



But still benefit from constituent pile-up suppression

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Alternative Inputs and Jet Grooming WMass Peak Values Slope

ATL-PHYS-PUB-2019-027



- Peak values increase with pile-up in PFlow
- The opposite is true for TCC
 - TCC over-subtract the pile-up
 - TCC use all tracks for cluster splitting, so more clusters are removed by matching with pile-up tracks



Alternative Inputs and Jet Grooming WMass Peak Values Slope

ATL-PHYS-PUB-2019-027



• Since TCC is already over-subtracting, adding constituent pile-up suppressions make it worse

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- Quantifying the mass scale calibration's dependence on jet topology
- Take the ratio of the average mass response $(\frac{m^{reco}}{m^{truth}})$ of W-jets over QCD jets



Alternative Inputs and Jet Grooming TOPOOGY Dependence ATL-PHYS-PUB-2019-027



- Prefer one (no topology dependence)
- Constituent pile-up suppression make it worse, but there are good option available, especially for PFlow



Alternative Inputs and Jet Grooming Tagging Performance

- Perform a simple two-variable tagger:
 - 68% signal mass window cut
 - One-side cut on D_2 (W) or τ_{32} (top)
- Compare background rejection (1/background efficiency) vs. signal efficiency





Summary

- ATLAS is moving towards particle flow for small-R jets
 - Better pile-up suppression, better resolution
- In-situ JES calibration for large-R jets is done with 80 fb⁻¹ of data
 - Reduce the JES uncertainty significantly (from 8% to 1% !)
- Study the impact on the large-R jet performance with various choices of inputs, constituent pile-up suppression, and grooming algorithms
 - PFlow jets outperform LCW topocluster jets across the board
 - TCC can be better than PFlow for high- p_T jets, but poor performance at low- p_T
 - Both PFlow and topocluster benefit from pile-up suppression at constituent level
 - Among the choices in this study, CS+SK did best
 - Standard ATLAS trimming does well, but some SoftDrop configurations show possible improvement



Backup

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ATLAS Detector



- Inner tracker
 - Inside solenoid magnet
- EM+Hadronic calorimeters
 - Muon spectrometer
 - With toroid magnet



Large-R In-situ Calibration In-situ Calibration — Small-R

JETM-2018-006



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I I I T T T

10³

 p_{τ}^{3} 2×10³ p_{τ}^{jet} [GeV]

∎γ+jet ${}^{\bullet}Z \rightarrow ee + jet$

 $\nabla Z \rightarrow \mu \mu + jet$

In-situ Calibration



https://atlas.web.cern.ch/A tlas/GROUPS/PHYSICS/PL OTS/JETM-2019-02/

• PFlow jet p_T response derived from $Z \rightarrow ee$, $Z \rightarrow \mu\mu$, γ , and multijet using MPF technique

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Large-R Jet In-situ Calibration JES Uncertainty

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- Total uncertainty depends on the assumption of the topology (W, Z, or top) and flavor (quark or gluon initiated) composition of the jets
- Large reduction compared to without in-situ calibration

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- Forward-folding has smaller uncertainty, but R_{track} covers a much boarder p_T and mass range



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Alternative Inputs and Jet Grooming **Pile-up** Stability—D₂ ATL-PHYS-PUB-2017-020



- Quantifying the effect of pile-up on tagging observable (D_2) :
 - 1. Take the D_2 distribution of W-jet sample in the low pile-up (N_{PV} < 15) bin
 - 2. Find a cut with 50% efficiency
 - 3. Apply the cut in bins of N_{PV} and plot the efficiencies
 - 4. Fit a line and measure the slope

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N_{PV}

Alternative Inputs and Jet Grooming D₂ Cut Efficiency Slope



- Shown only W-jet with D_2 , but result are consistent with top and τ_{32}
- Prefer zero (pile-up stable)
- Generally, efficiency decreases with pile-up, except TCC

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Pile-up Stability—Jet Topology



- Prefer one
- Constituent pile-up suppression make it worse, but there are good option available, especially for PFlow

