

The background of the slide is a photograph of a blue, corrugated metal mesh structure, likely part of a particle detector. The mesh consists of many parallel lines that create a grid-like pattern. The lighting is bright, creating a strong glare in the center of the image.

Effect of the mesh geometry on Micromegas discharges

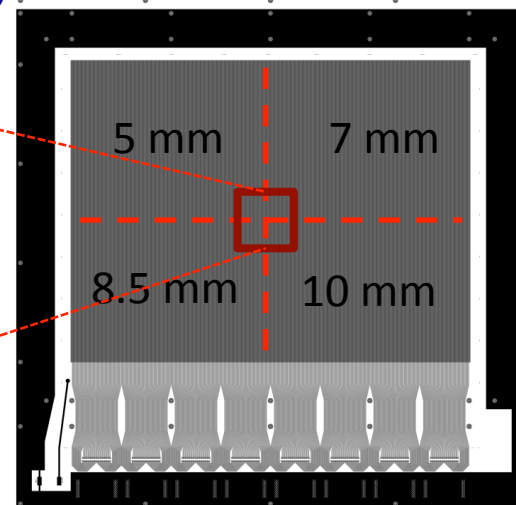
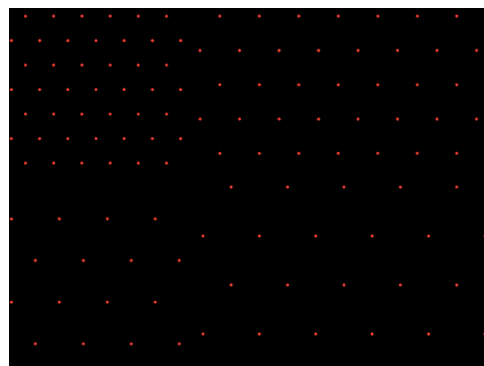
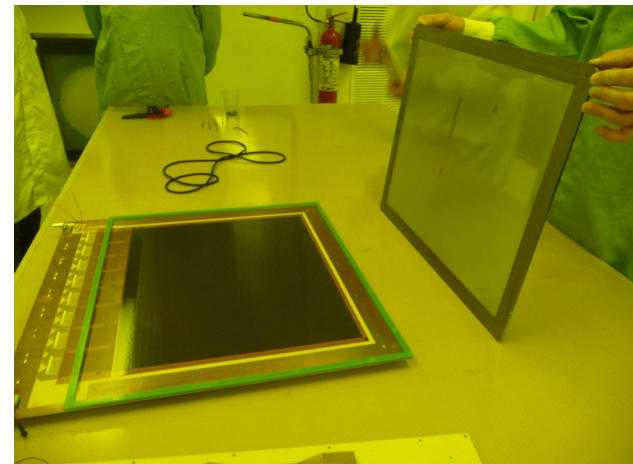
M. Alviggi, P. Iengo, M. Iodice,
G. Sekhniaidze

Thanks to R. De Oliveira, R. Hertenberger for useful discussions

- RD51 week, CERN -

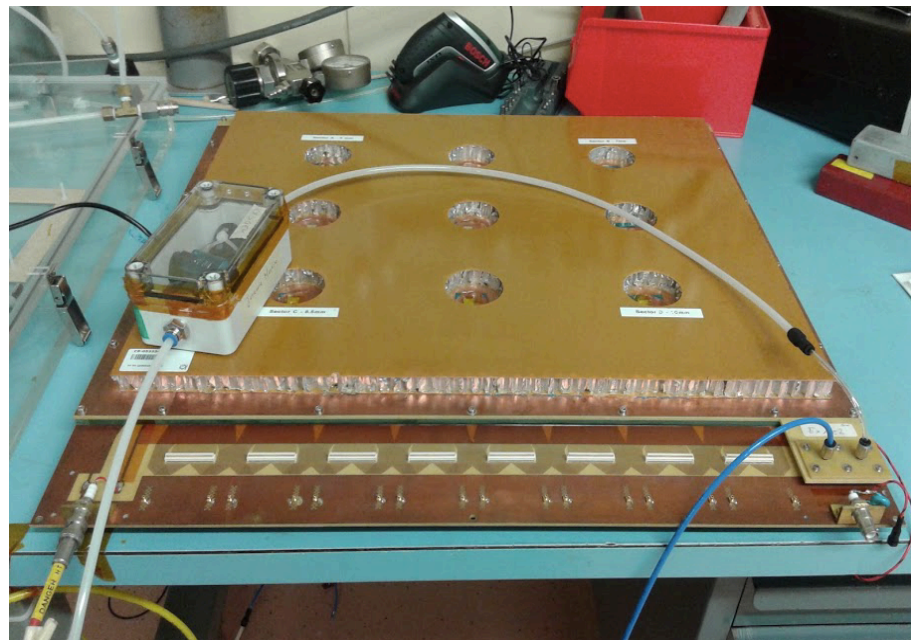
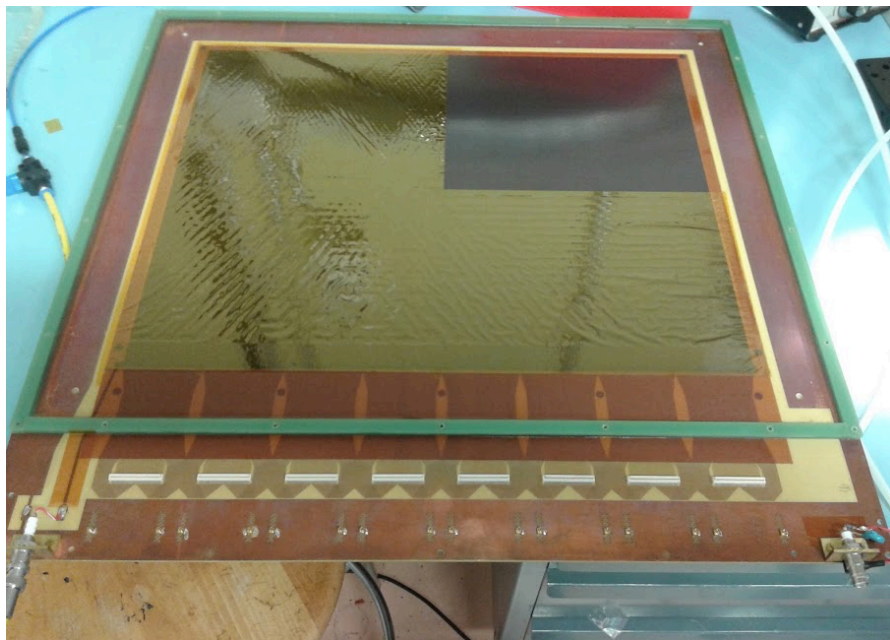
- Detector description
- Tested meshes and expected results
- Challenges and procedures
- Results
 - Current and 'discharge spike rate' vs HV
 - Gain and rate from signal vs HV
 - Current and 'discharge spike rate' vs Gain
 - Rate from signal vs Gain
- Conclusions

- ExMe (exchangeable mesh) detector
 - Designed and built at CERN in 2014 (J. Wotschack, P. lengo, R. De Oliveira, G. Sekhniaidze) to help selection of mesh type and pillar spacing for the ATLAS NSW project
 - Mesh stretched on iron frame → easy to replace
 - 4 sectors with different pillar spacing: 5/7/8.5/10 mm
 - Circular pillars (300 μ m diameter)
 - Otherwise similar to ATLAS MM (screen-printed resistive lines on Kapton, same width/pitch as ATLAS)



Exchangeable Mesh detector (ExMe)

- Only sector with 7mm pillar spacing active
- Other sectors passivated with 12.5 um kapton film on top of the pillars
- RH, P, T measured at the gas output of the detector



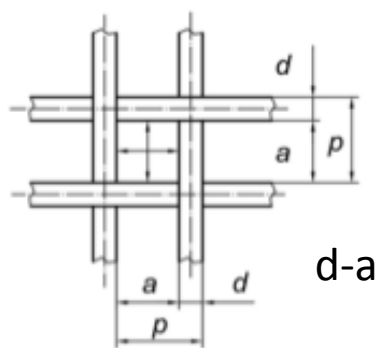
Tested meshes

Type (d-a um)	Comment	Old: purchased in 2014 New: newly purchased in 2018
30-71 C	Calendered - new	
18-45 C	Calendered - old	
18-45 N	Non calendered - new	
30-71 P	Non calendered, Hand polished - old	
28-50 N	Non calendered - old	
30-80 C	Calendered - old	

Test sequence



Plain weave



Calendered mesh

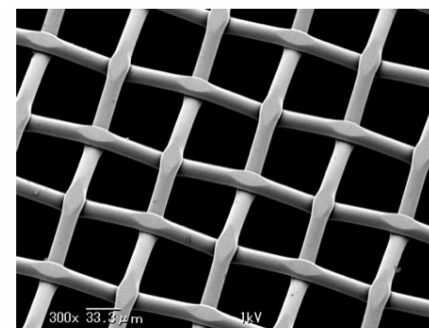
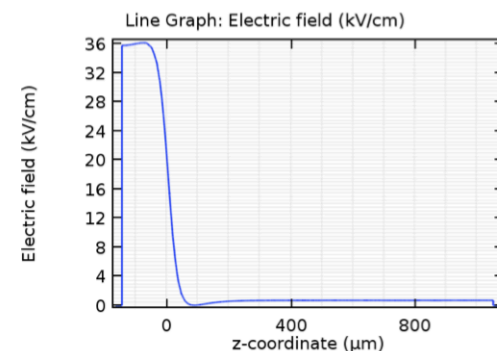
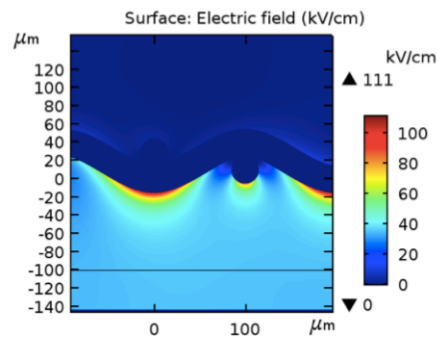


PHOTO A: M30 360-16μm calendered mesh

- Max achievable voltage → breakdown
- Average voltage → gain/working point
- See presentation by D. Bhattacharya from yesterday

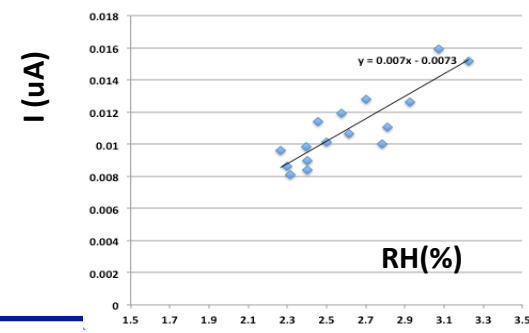
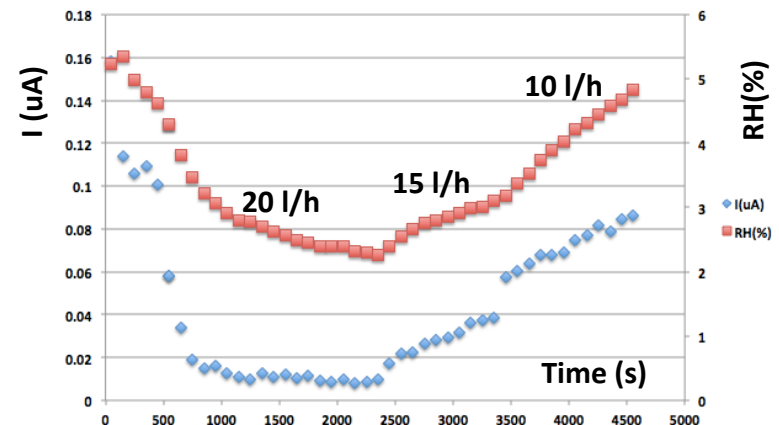
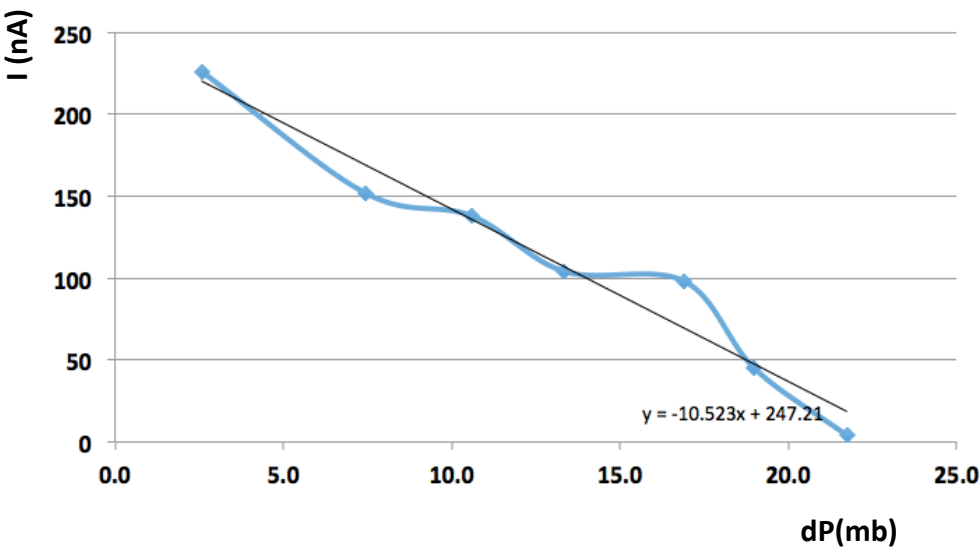


Type	Max (kV/cm)	Average (kV/cm)	Ave/max (%)
18-45 C*	89.2	40.5	45.4
30-85 C*	88	39.5	44.88
18-45 N	112	38.75	34.59
28-50 N	104	38.25	36.77
30-71 C*	84	40	47.5
30-71 N	104	37.25	35.81

* Ideal calendering

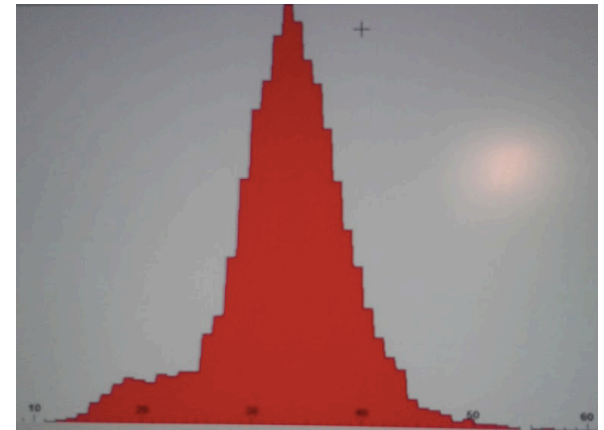
Experimental issues

- Discharges at breakdown triggered by defects/geometry or external dust → crucial to ensure the same level of cleanliness as the detector is opened/closed to replace the mesh
- Current values affected by T/P and RH → measurements done trying to keep constant overpressure (few mb) and RH (~3%)

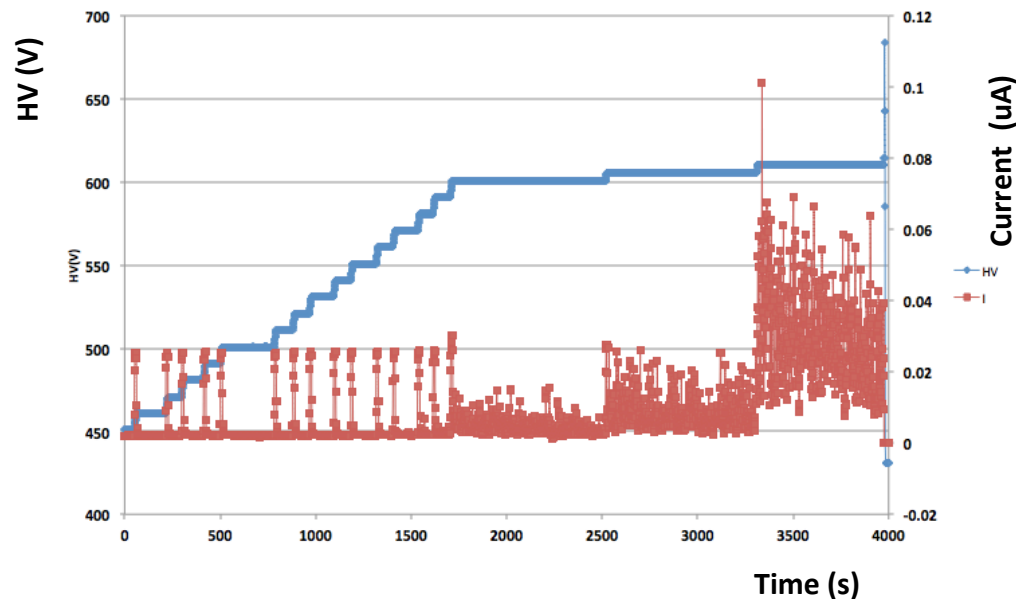


Test procedure

- HV scan in dry air
- HV scan in Ar:CO₂ (93:7) w/ and w/o ⁵⁵Fe source
- Gain measurement (⁵⁵Fe peak position with Ampteck MCA)
- Rate measurements
 - Measured by taking signals from 1 Panasonic connector (128 channels → 51.2 mm)
 - DAQ: Pre-ampl → amplifier (Ortec) → discriminator → scaler
 - Irradiated region ~ 2 mm diameter → rate ~ 3 kHz/cm²
- $V_{\text{drift}} = 300\text{V}$

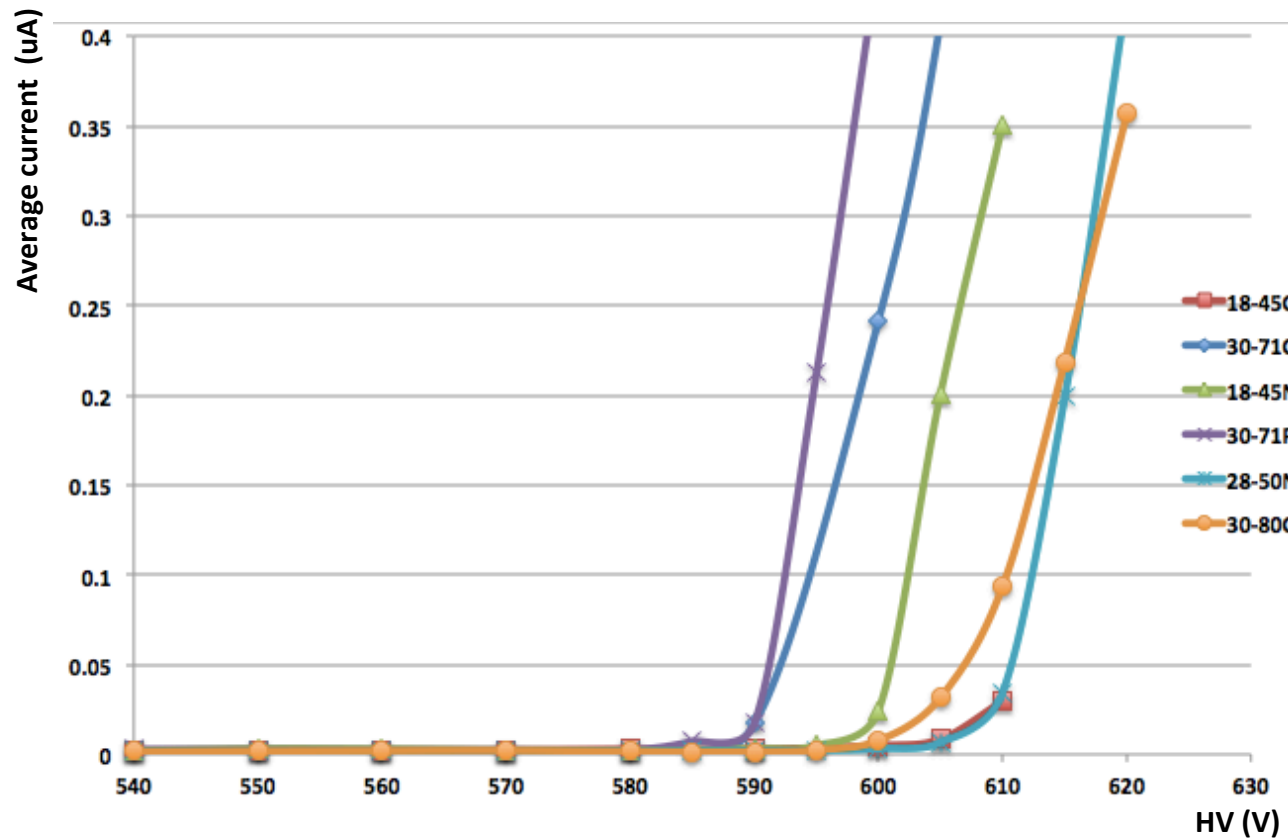


- HV scan performed w/ and w/o Fe source
 - From 450 V up to the max achievable (600 to 620 V with 5-10 V steps)
 - No significant difference in currents measured w/ and w/o source → currents mostly from discharges, not from 'signals'
 - Current value measured every sec



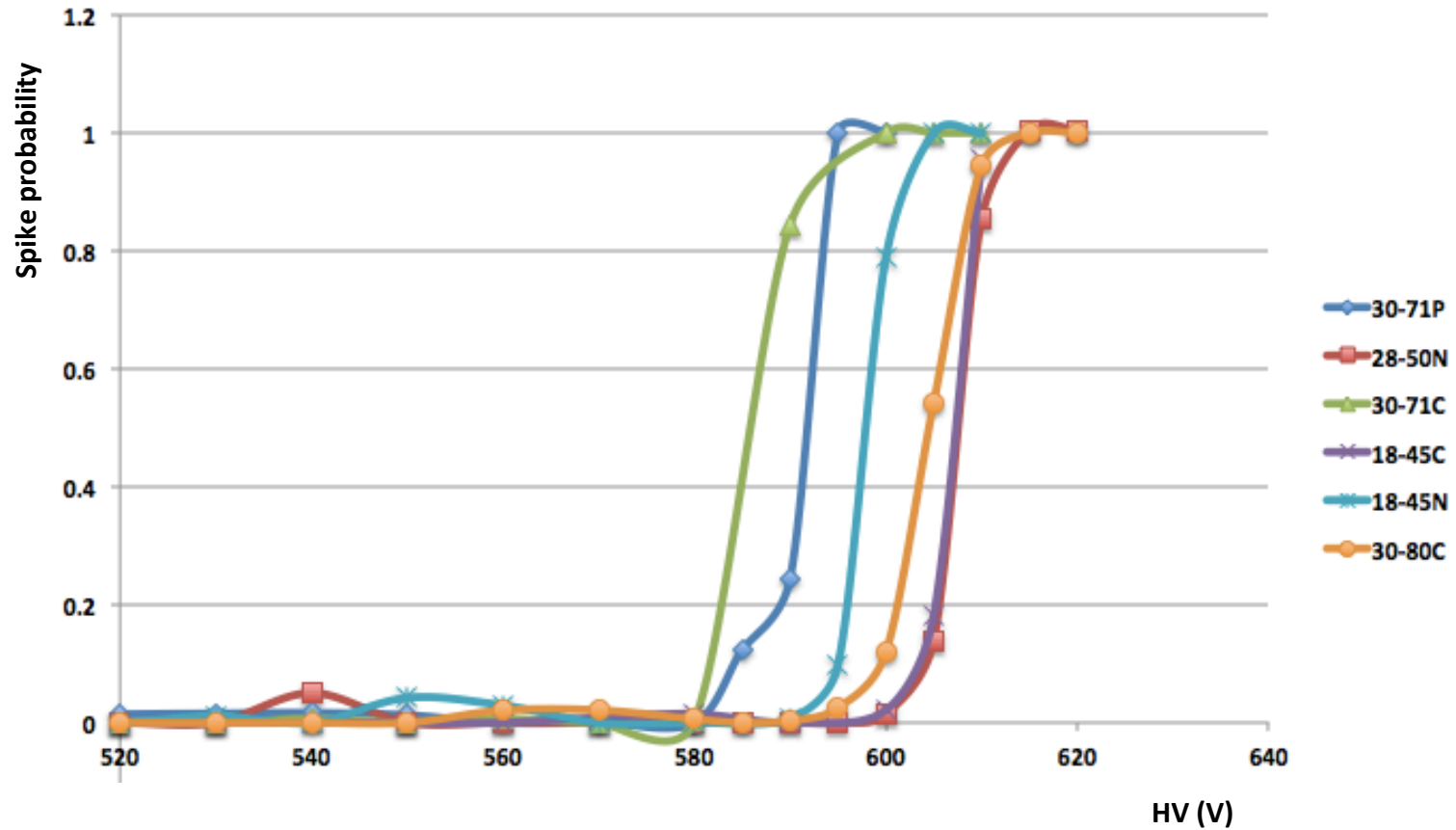
Current vs HV

- ^{55}Fe source on (as in all following slides)
- Current is averaged over the period at constant voltage (removing points during transient)

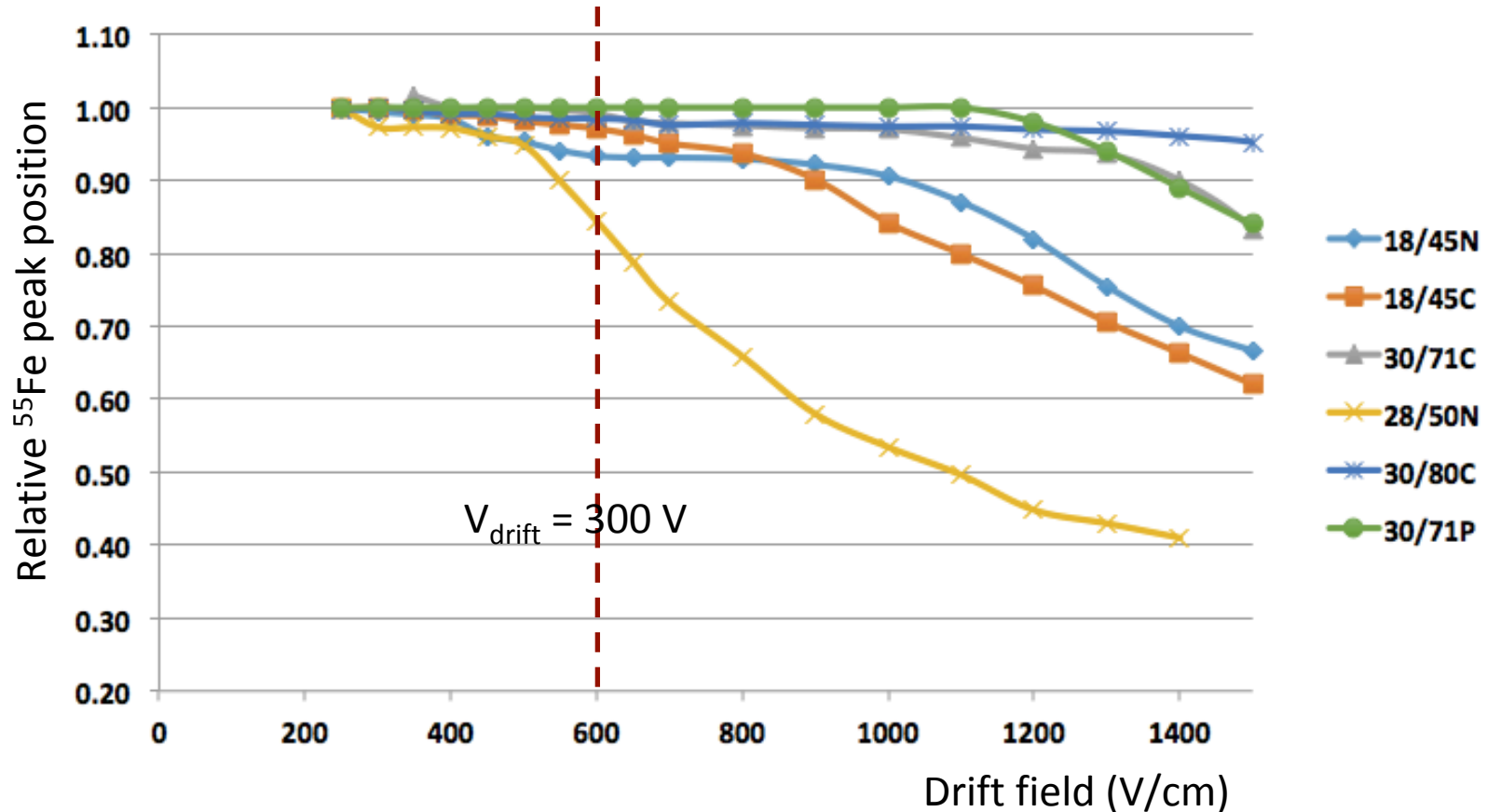


Spike probability vs HV

- A spike is (arbitrarily) defined as a current value > 10 na

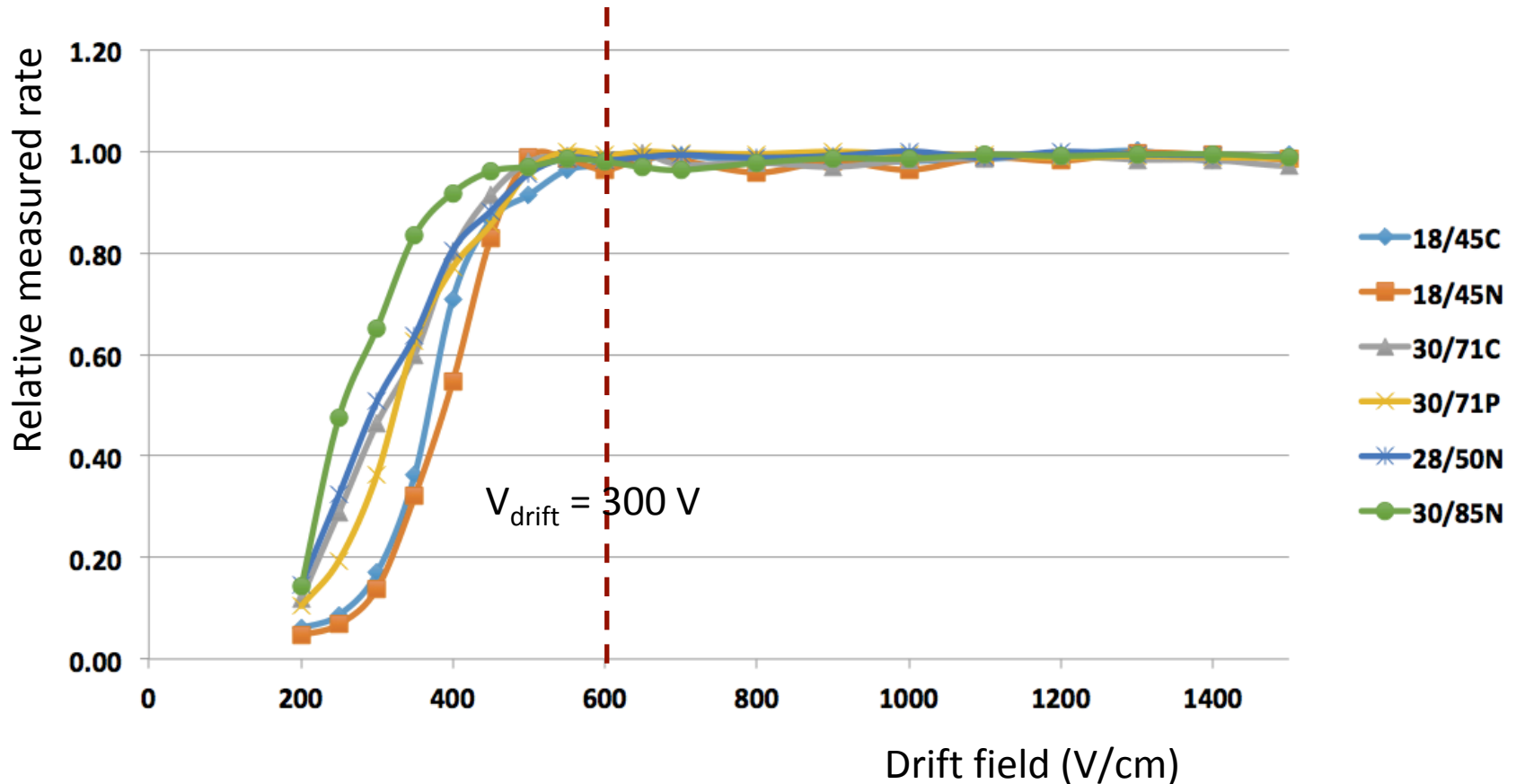


- Drift scan: at $V_{\text{drift}}=300\text{V}$ all mesh except 28-50N have a relative transparency $>90\%$



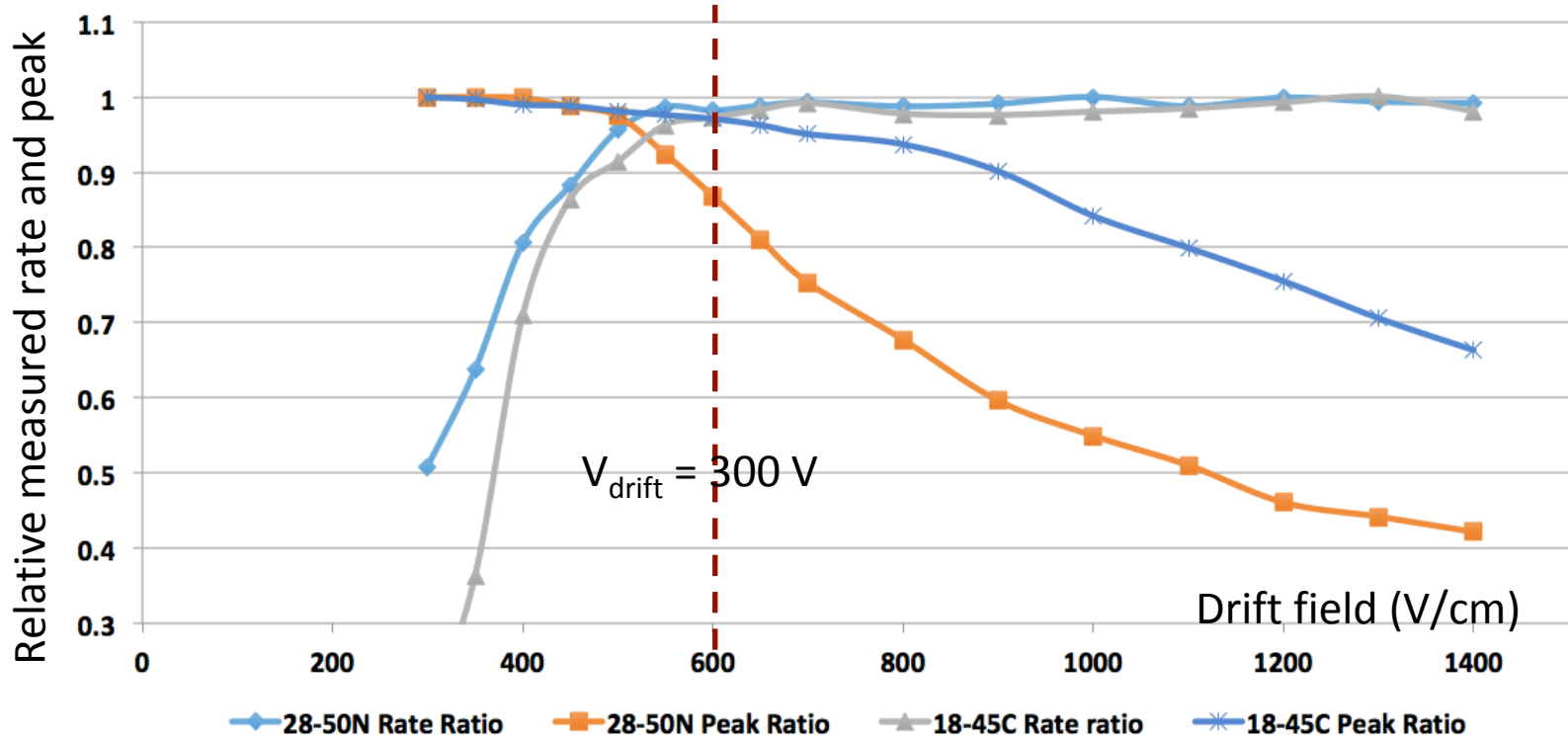
Rate vs V_{drift}

- Drift scan: at $V_{\text{drift}}=300\text{V}$ all meshes are inside the plateau of the rate measurement

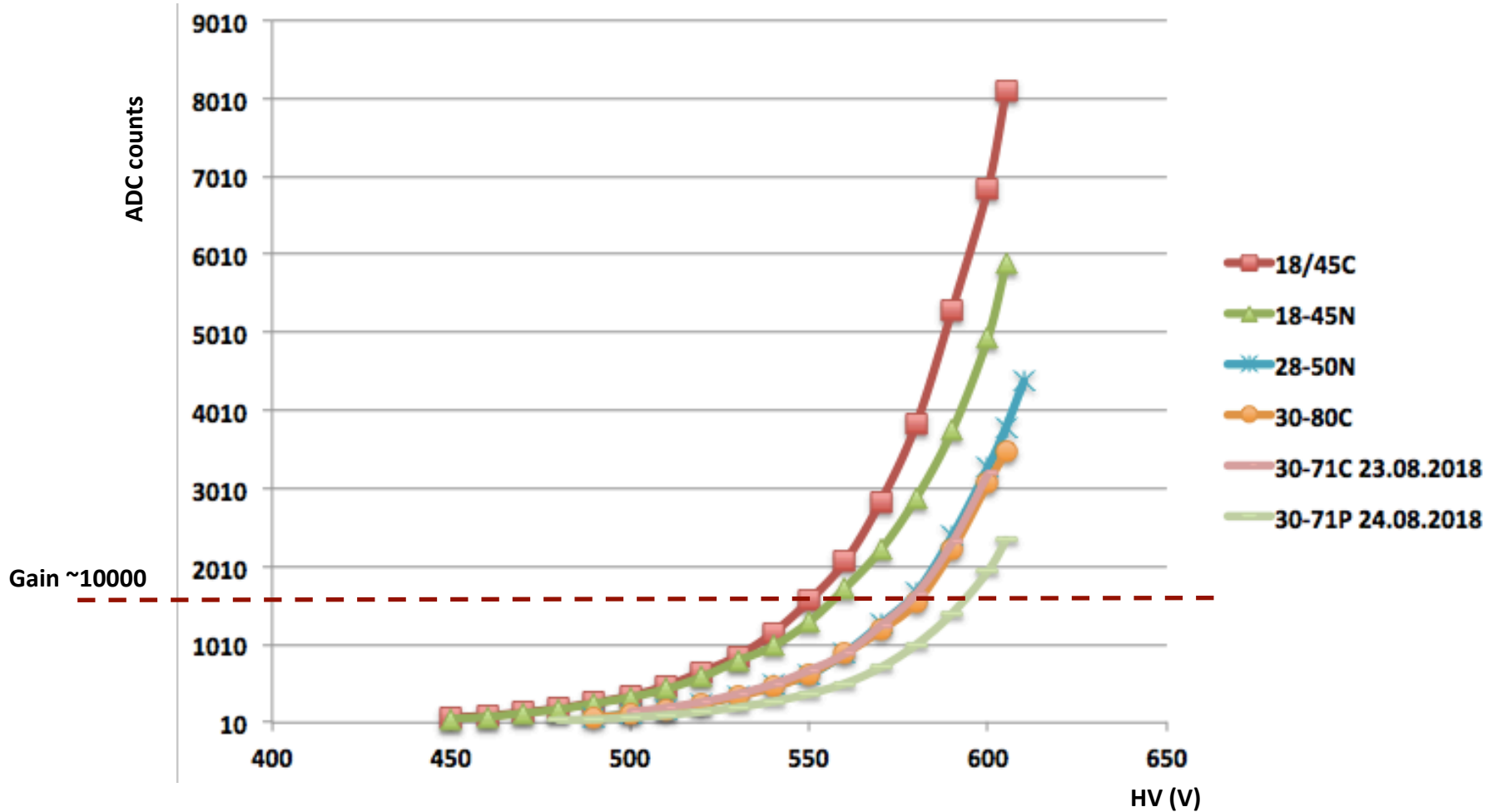


V_{drift} scan for 28-50

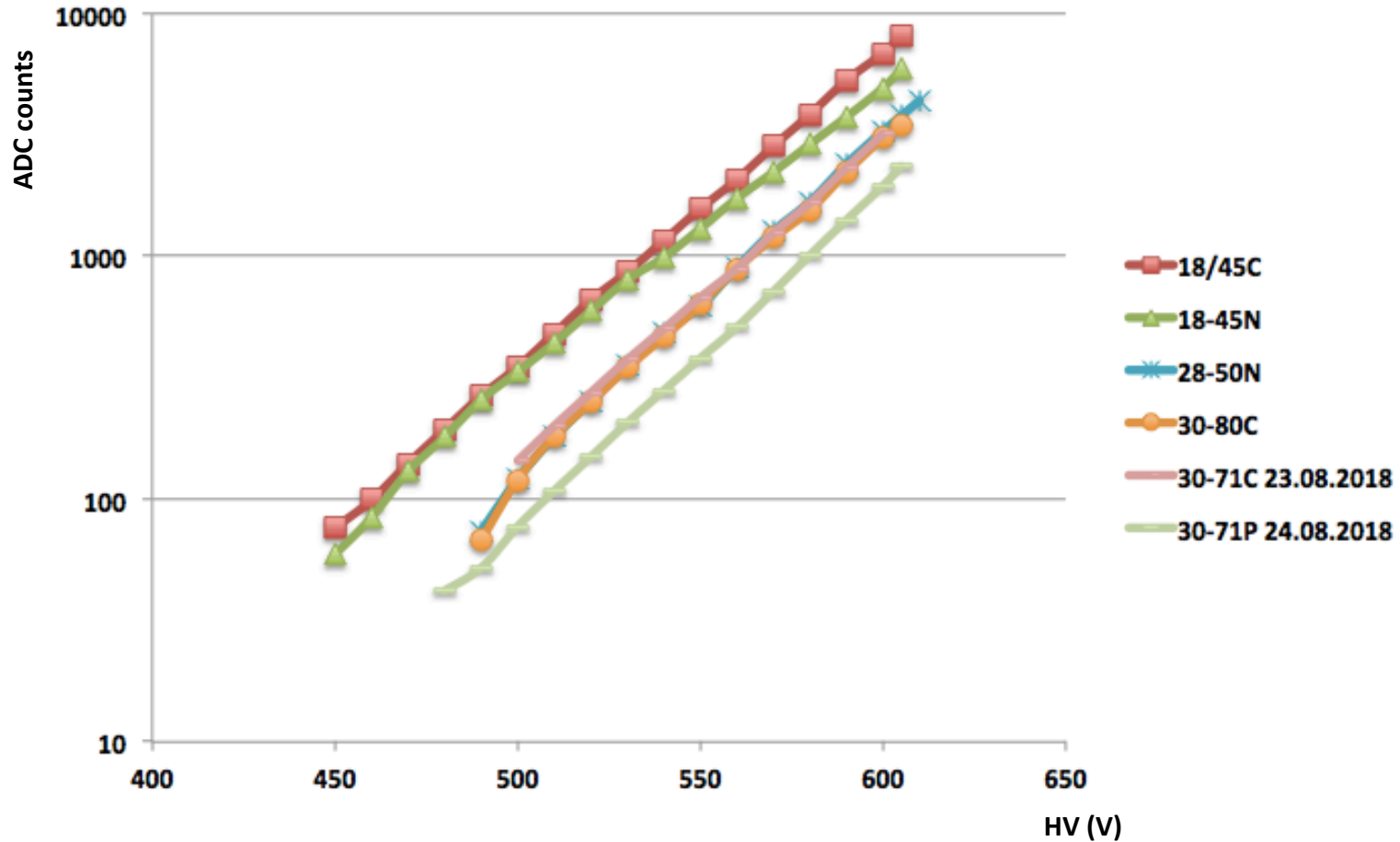
- Not possible to maximize both rate and transparency for 28-50



- Gain

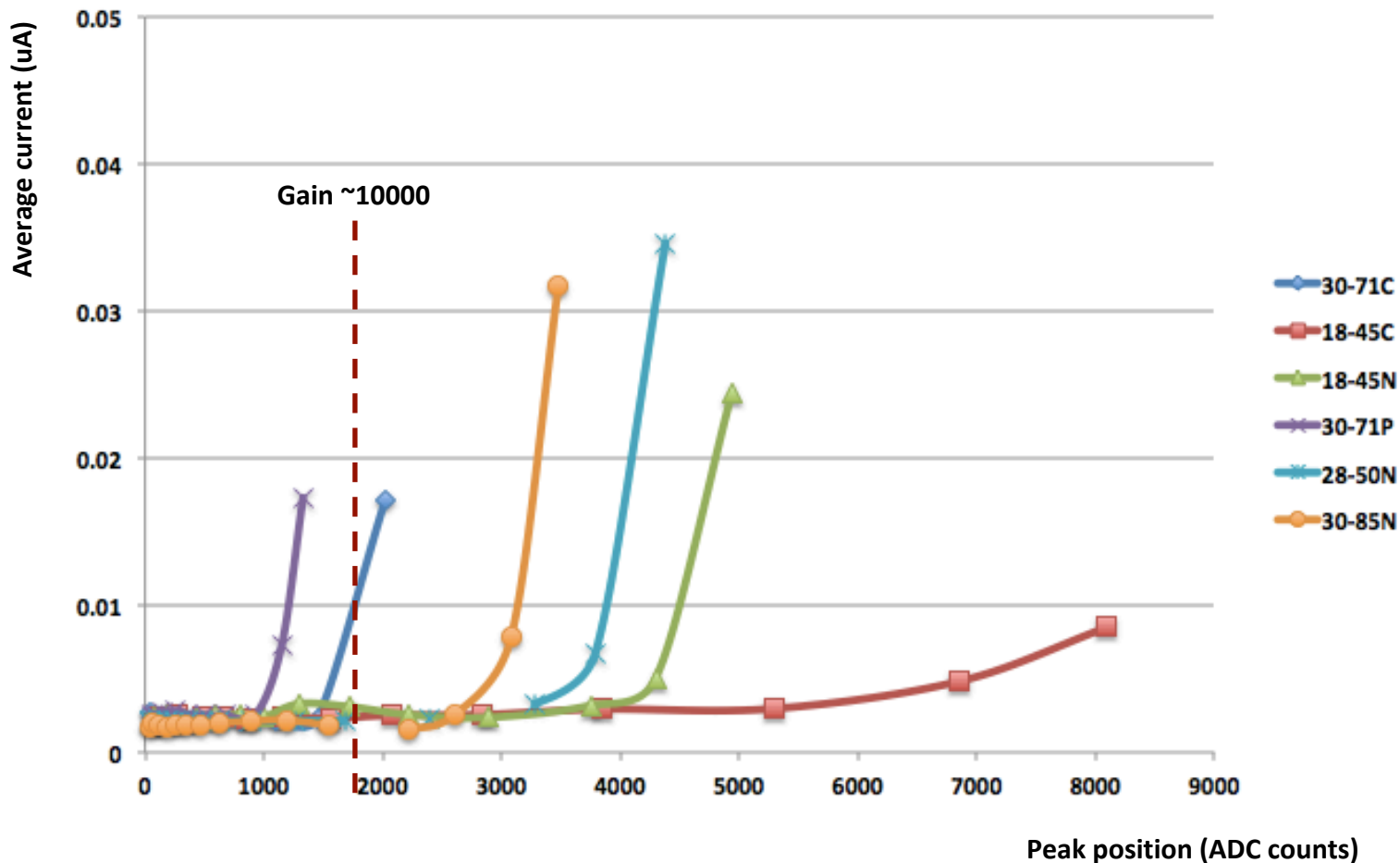


- Log scale



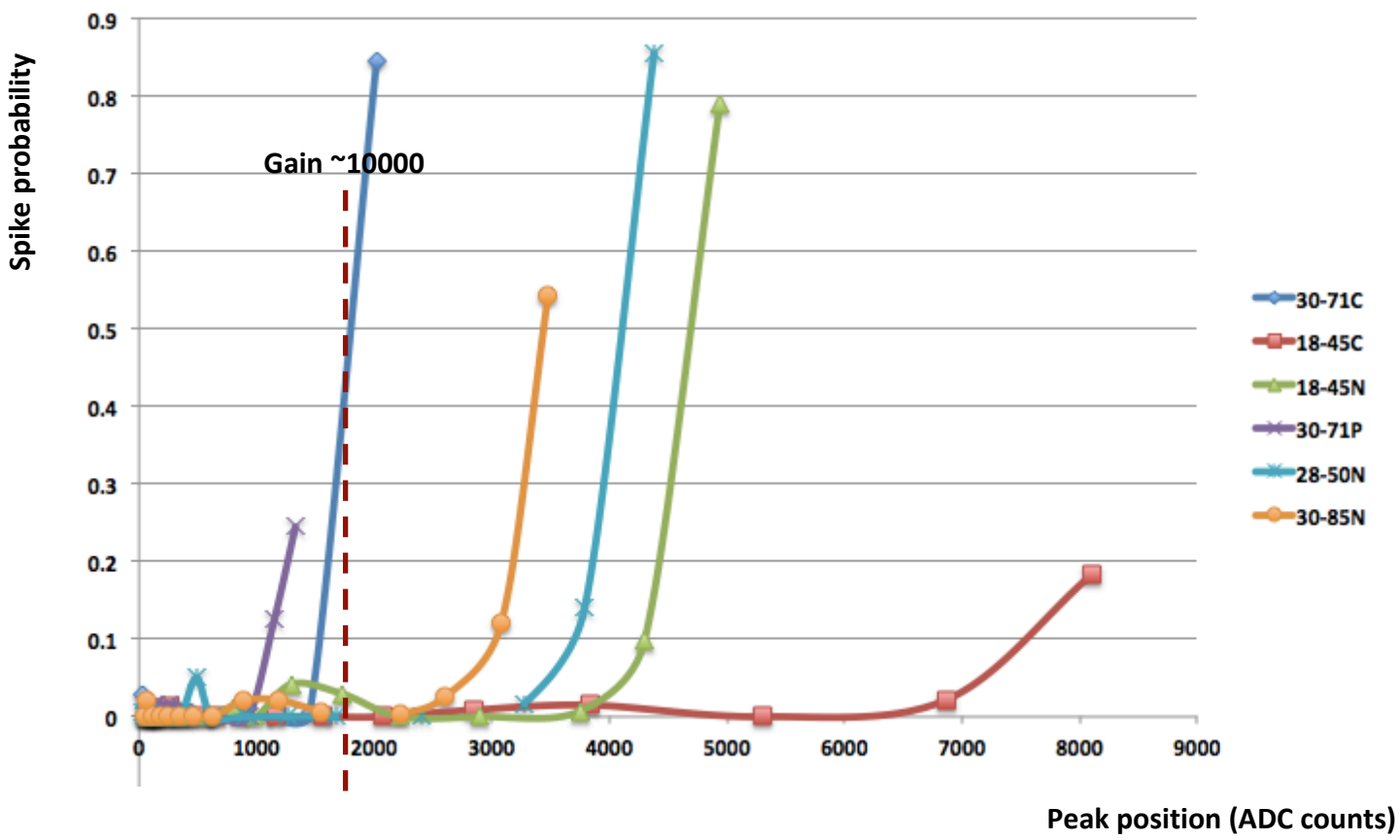
Current vs peak position

- Current is averaged over the period at constant voltage (removing points during transient)



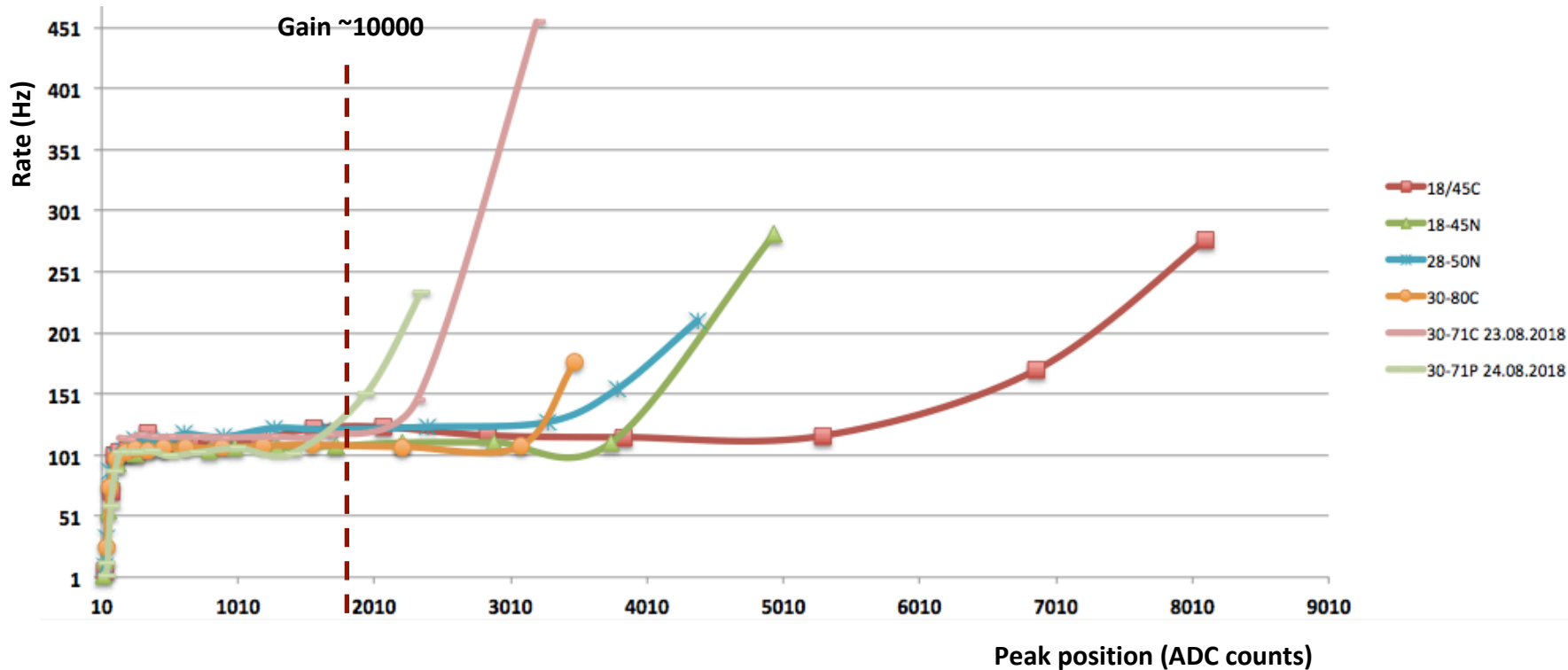
Spike probability vs peak position

- A spike is (arbitrarily) defined as a current value $> 10 \text{ na}$

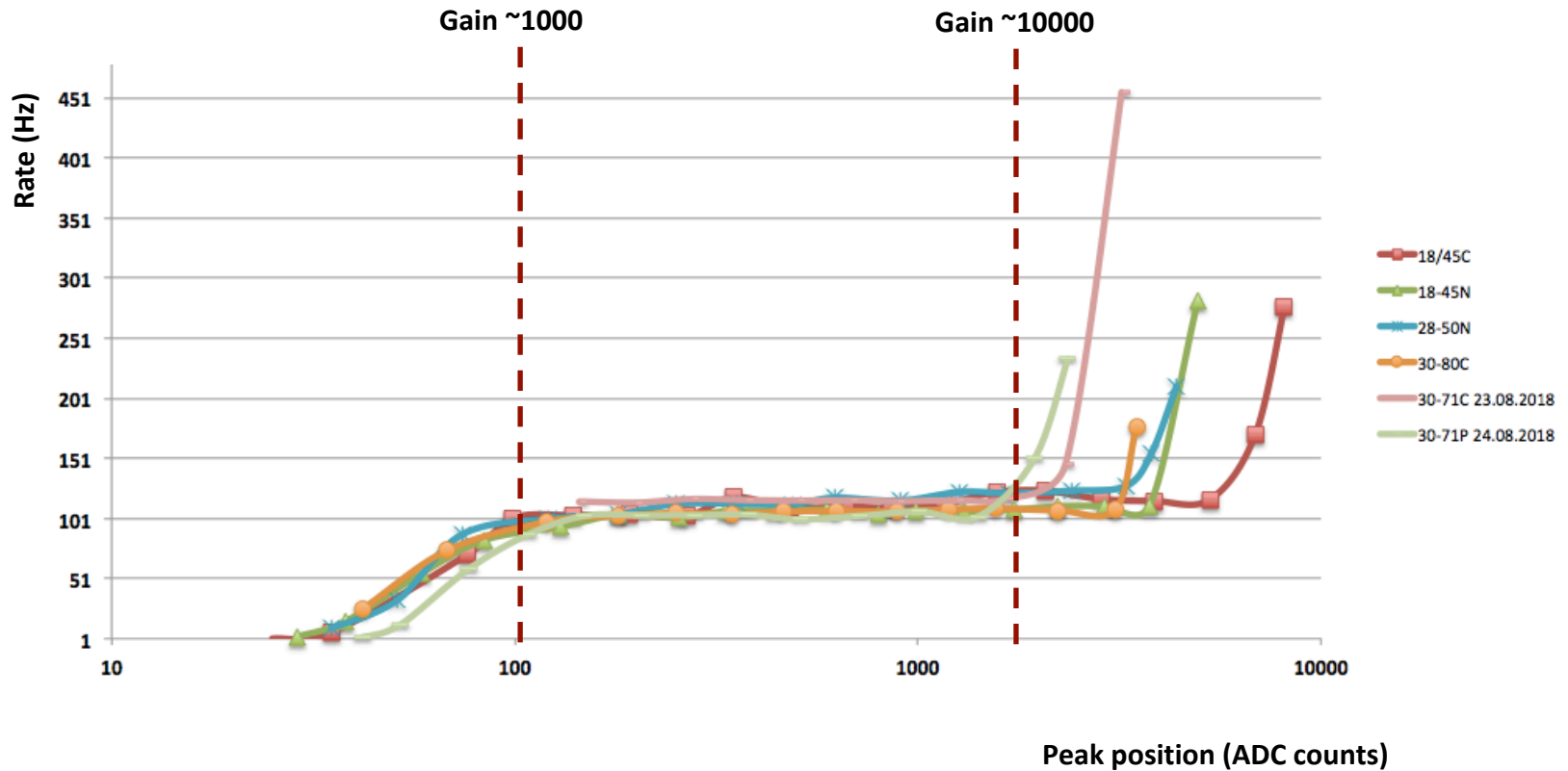


Rate vs peak position

- Linear scale



- Log scale

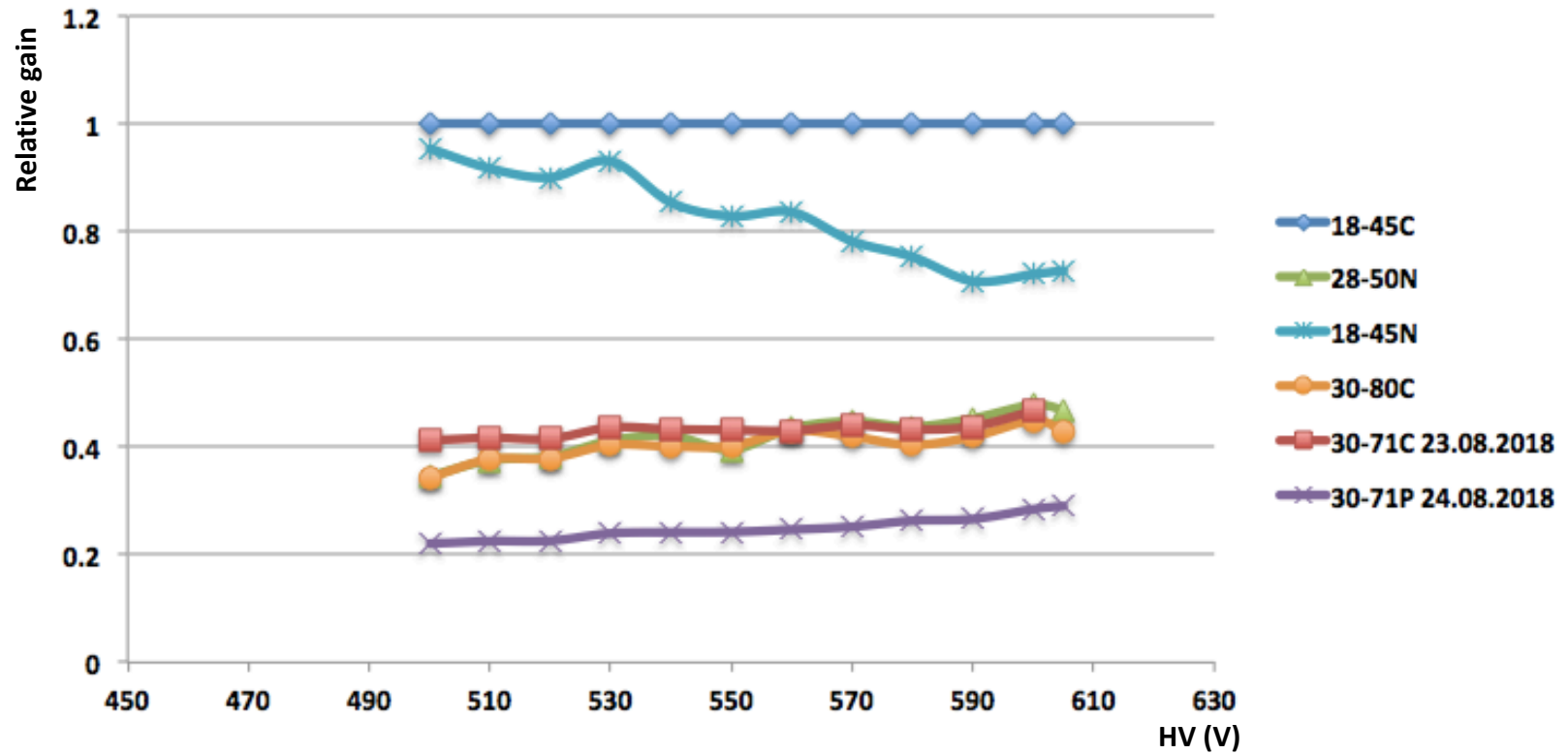


- We have studied the impact of mesh geometries on the HV stability of MM detectors
- Clear dependence of stability on geometry
 - Smaller openings give larger stability region (field uniformity)
 - Calendered meshes perform better
- Experimental results in (qualitative) agreement with prediction
 - 18-45 C found to be the best tested mesh
 - 30-71 C worst than 30-80 C (might be because of local defects)
- Selection of the right mesh should not only look to gain and transparency. The full picture is relevant, including breakdown

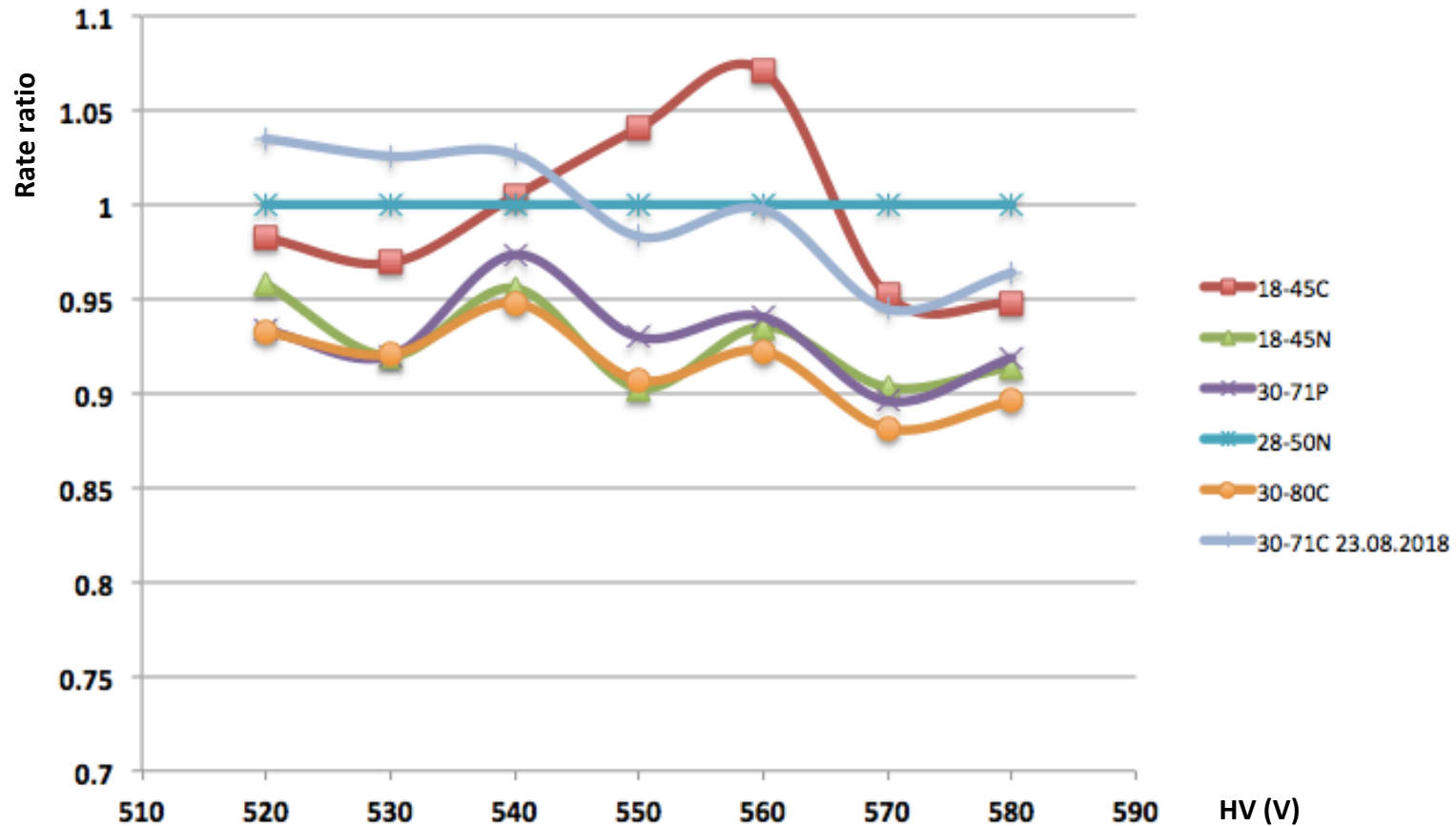
Additional Material

Gain comparison

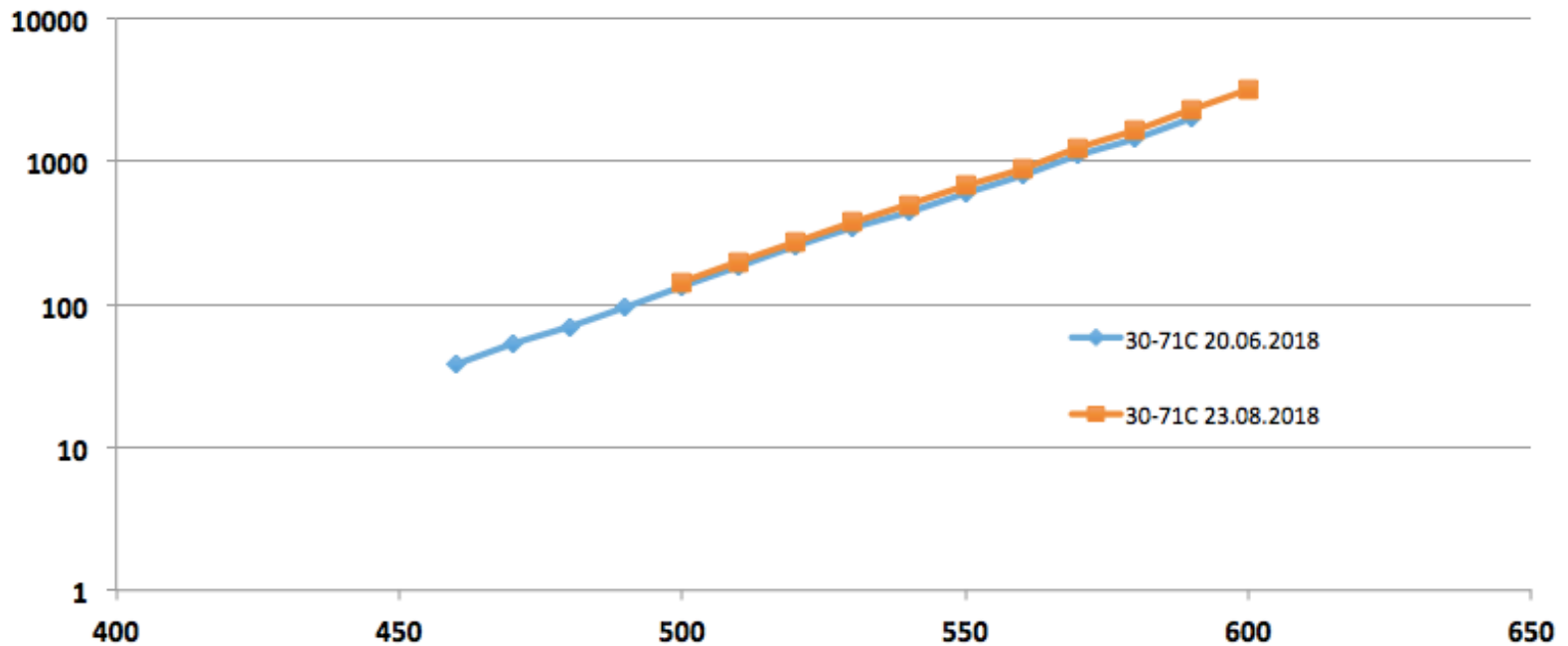
- 18-45 C (highest gain) taken as reference



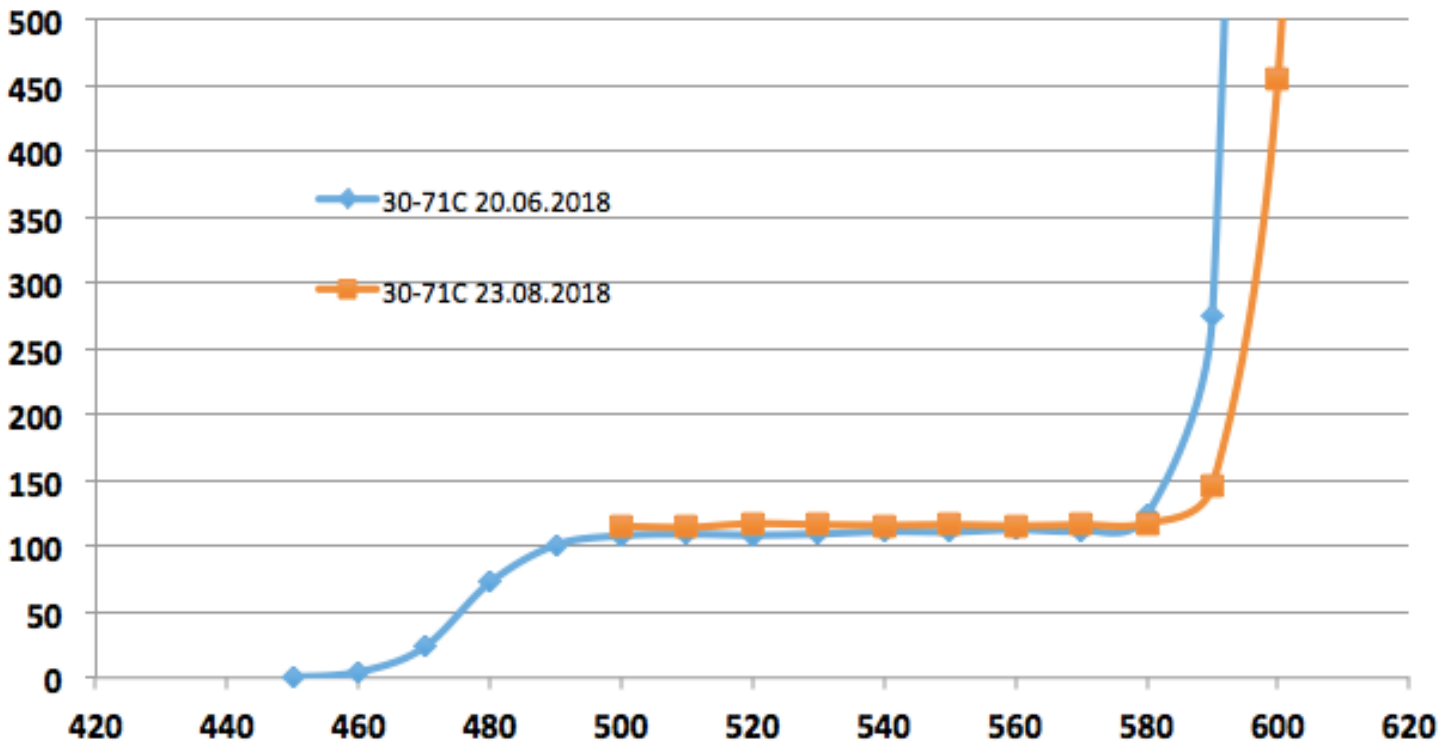
- 28-50N taken as reference



- Repeated measurements with the same mesh: peak position vs HV



- Repeated measurements with the same mesh: rate vs HV



- Repeated measurements with the same mesh: rate vs peak position

