Low Loss Design of a Flux-Modulated Motor Considering Air-Gap Harmonics

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Abstract

Since the permanent magnet (PM) loss has a great influence on the temperature rise of the motor and the irreversible demagnetization, the reduction of the PM loss is significant for the performance of PM motors. In this paper, a new method based on adjustable ratio magnetic motive force (MMF) is proposed to realize the reduction of the PM loss of a flux-modulated permanent magnet (FMPM) machine with PMs on the stator. By analytical method, it can be concluded that the air-gap harmonics are greatly affected by MMF. Thus, the air-gap harmonics can be reduced by adjusting the MMF, which contributes to the decreasing of the PM loss. By the proposed method, the rated on-load PM loss of the investigated motor is reduced by 36.2% while the output torque almost keeps unchanged.

Conclusions

In this paper, an adjustable ratio MMF is proposed to reduce MMF harmonics, and then reduce flux density harmonics and PM loss. The principle of this method has been explained by using 2-D MMF model, and the great impact of the proportion of MMF on harmonics is highlighted by analytical method. The impact factor of PM loss (ζ) is introduced and the adjustable ratio MMF and low PM loss design can be realized by optimizing parameter ζ. Furthermore, parameter ζ also affects other performances, so the machine is optimized taking PM loss, output torque and cogging torque into account. The optimal machine has much lower PM loss and $P_2$, under different rotational speed and input current. Running at rated condition, PM loss and $P_2$ are reduced by 36.2% and 23.7% respectively with output torque declining by 3.1%. This paper provides a new method for low loss design from the perspective of harmonic reduction.

Results

The high PM loss area of the optimal motor is almost eliminated completely, and low PM loss design is achieved.

Performance comparison. (a) Under different speed. (b) Under different current. (c) Under same torque

The performances of two motors are compared in detail. Fig. (a) and Fig. (b) indicate that under different rotation speed and input current, PM loss is reduced greatly while the output torque almost keeps unchanged. Fig. (3) shows that when the same torque is obtained, PM loss is still much lower.