

Overview on camera sensor technology

Walter Tutsch, PCO AG

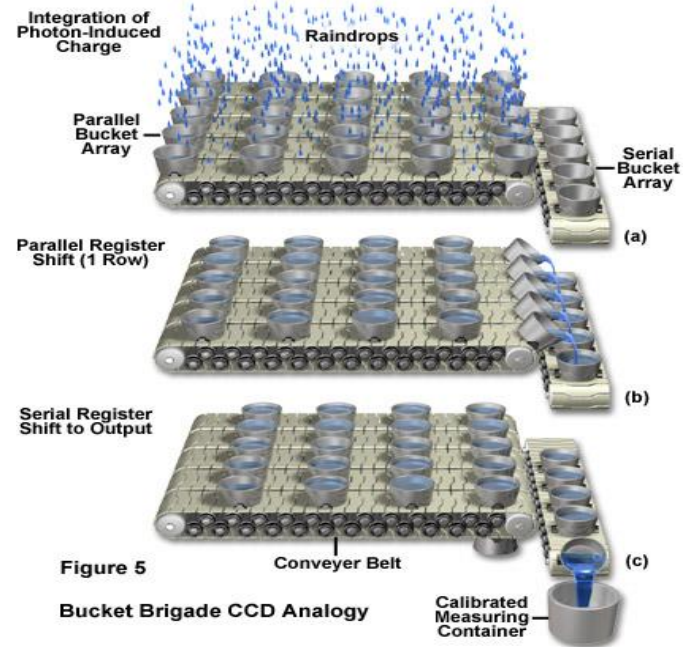
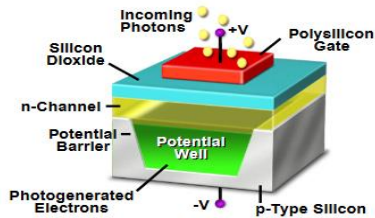
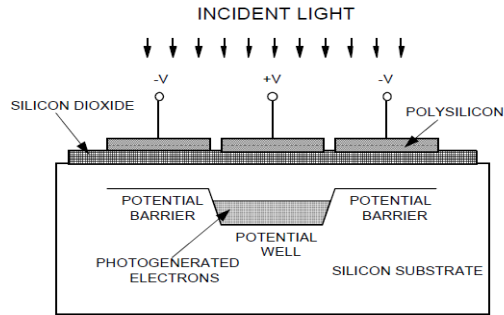
Krakow 2019, April 1st

- **CCD**
- **EMCCD**
- **scientific CMOS**
- **fast data interfaces: CameraLink HS**
- **sCMOS application in MCP based intensified cameras**
- **Summary**

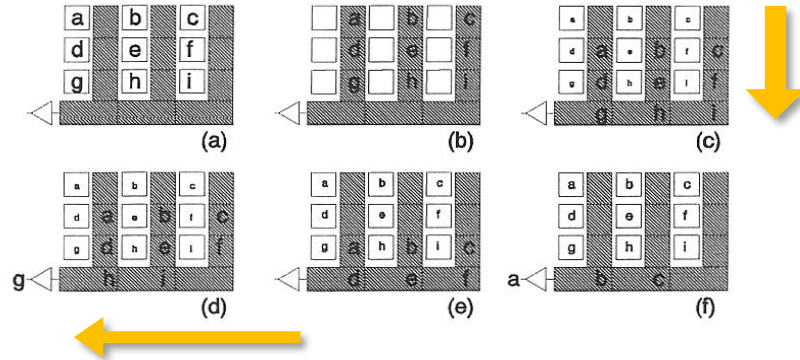
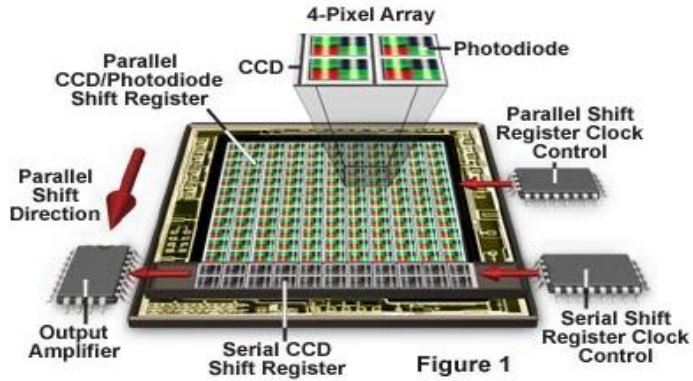
CCD

Charged-Coupled Device

Single Pixel Elements (Photodiodes) collect charges.
Parallel & serial charge shift to (single) A/D converter.



Architecture of an interline transfer CCD Sensor



PRO

- **low spatial noise**
(homogeneous images due to single ADC)
- **low dark current**
(thermally generated electrons)
- **high linearity** (signal intensity has a linear response to incident photons)
- **binning possible**
(addition of charges before readout)
- **suitable for long exposure times**
($> 10\text{s}$)
- **short exposure times**
(interline transfer CCD: $\sim 500\text{ns}$ / $1\ \mu\text{s}$)

CONTRA

- **slow readout (= slow frame rate)**
- **smear / blooming (low protection against oversaturation of pixels)**
- **manufacturing process is costly (compared to CMOS sensors)**



Sony ICX285



Kodak KAI-4022

A letter from Sony...

Notice of discontinuation of Sony Semiconductor Corporation's Kagoshima wafer production line (CCD 200mm line)

January 30, 2015

Dear Valued Customers:

Thank you for your all of effort as always. Let us begin by expressing our gratitude for the business we have established together thus far.

As noted below, recently we have reviewed the business situation in Device Solution Business Group under Sony Corporation.

We are afraid we will discontinue operations of the CCD 200mm wafer line at Kagoshima Technology Center in Sony Semiconductor. By the end of March 2017, we will cease production of devices currently being manufactured on this line.

We would kindly like to ask for your cooperation in working with us for the final production of each device on this line. Please contact the appropriate sales persons in Device Solution Business Group under Sony Corporation if needed. We really thank you again, and hope to keep working together for even future business.

Sincerely,

Production Line: **Kagoshima Technology Center CCD 200mm wafer line**
(Related Devices : Please refer to the attached form.)

Schedule: LTB Quantity to be due by **End of August 2015**
(The demand with the responsibility to buy)

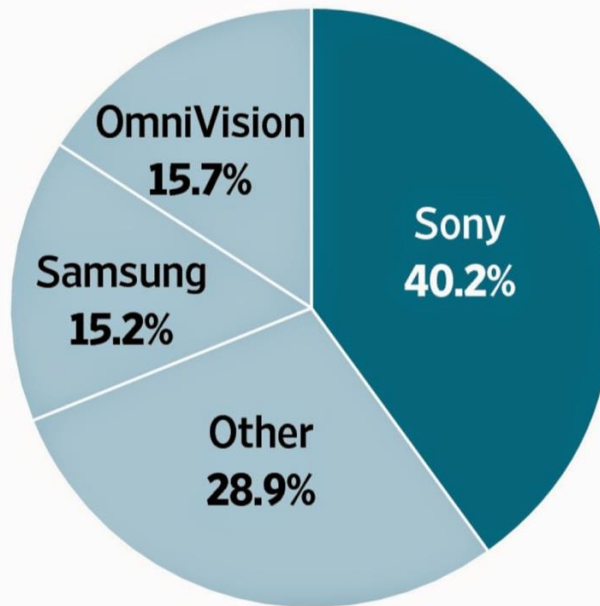
Discontinue operations at wafer line by **End of March 2017**

Last shipment of the finished product by **End of March 2020**
(Acceptance day of the last order by **End of September 2019**)



Yasuhiro Ueda
SVP, Corporate Executive
Senior General Manager
Image Sensor Business Division
Device Solutions Business Group
Sony Corporation

Top sellers of image sensors



Note: 2014 estimates

Source: Techno Systems Research

THE WALL STREET JOURNAL.

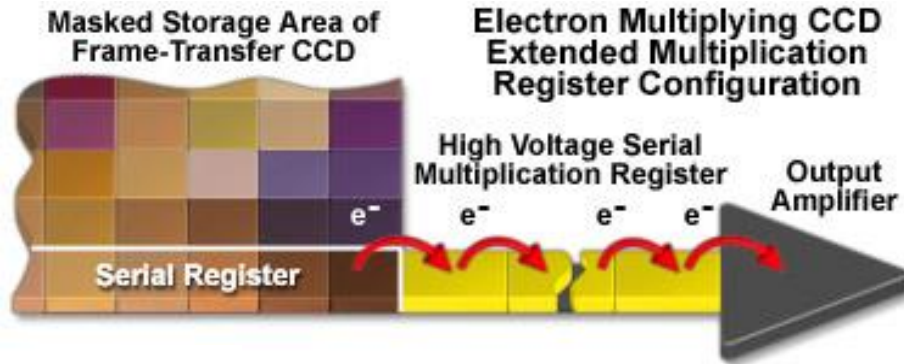
**Sony announces end
of CCD production**

EMCCD

Electron-Multiplying Charged-Coupled Device

Pixel design similar to standard CCD sensor

Before readout, the charges are multiplied (impact ionization) in the „high voltage multiplication register“.

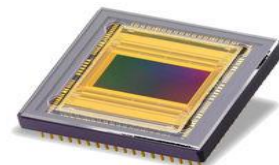


PRO

- **multiplication of signal electrons increases signal to noise ratio**
(read noise is not multiplied)
- **user selectable gain**
(multiplication can be adjusted based on the needs of the application)
- **extremely sensitive**
QE up to ~95% with back illuminated emCCD
(single photon detection possible)

CONTRA

- **additional noise source due to multiplication process** (statistical variation of the overall number of electrons generated by multiplication register)
- **dark current**
(thermally induced electrons are multiplied)
- **deep cooling necessary**
- **high gain = low dynamic range** (even small signal which is highly multiplied will saturate the pixel / ADC)



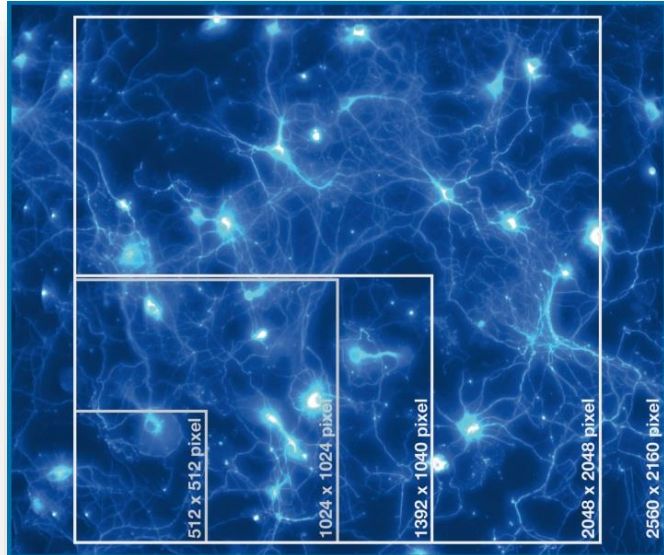
e2v L3Vision™

sCMOS

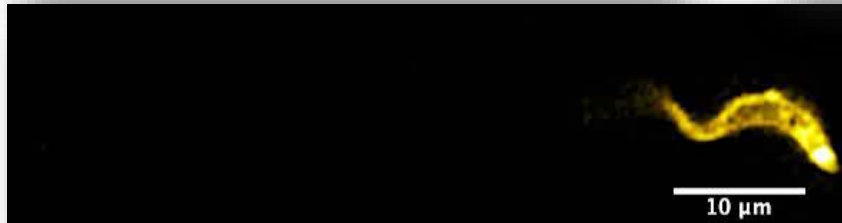
scientific complementary metal oxide semiconductor detectors

sCMOS: What makes a CMOS sensor a sCMOS ?

high resolution



high dynamic range



high frame rate and high sensitivity

– max. 150 photons & 200 fps

How to design a sensor with such a high **Intra-Scene Dynamic** ?

$$\text{dyn}_{\text{image sensor}} = \frac{\text{full well capacity [e-]}}{\text{readout noise [e - rms]}}$$

There are two „tuning knobs“:

1. Design pixel with high full well capacity
2. Reduce the readout noise to a minimum

1. Pixel with high full well capacity

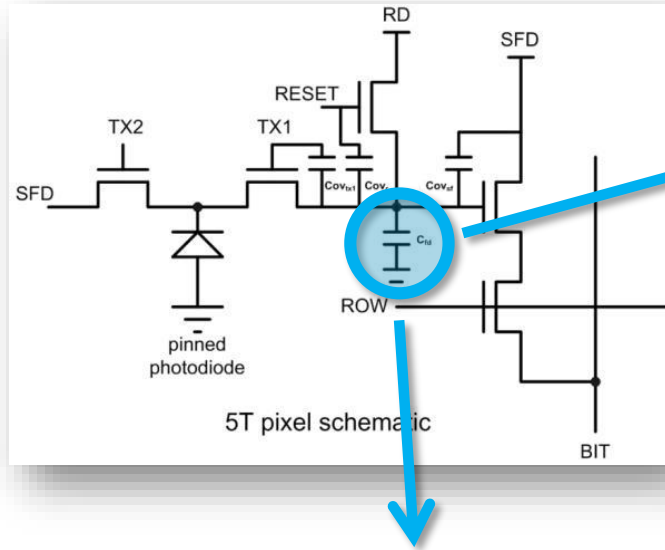
- from a simple geometric aspect, full well capacity is correlated to the pixel size:

➡ the higher the desired full well capacity is, the larger the pixel size has to be, **BUT...**

- large pixel show higher dark current
- large full well capacities require sufficiently large capacitors for intermediate storage and transfer of the photo electrons but ...
- large capacitors reduce the gain in $\mu\text{V}/e^-$
- large capacitors increase **kTC noise** which is the main source of readout noise

➡ This is like a dead race !

2. Reduce the readout noise to a minimum



Check list for the Floating Diffusion capacity

- must be large enough to hold full well
- small enough to avoid too high kTC noise
- small to allow for high gain ($\mu\text{V}/e^-$)

quick calculation for CIS2521:

- total capacity $C \sim 4\text{fF}$, maximum voltage $U \sim 1.2\text{V}$
 $Q_{\text{FW}} = C \times U \Rightarrow Q_{\text{FW}} = 29.600 e^-$ o.k.
- $Q_n = \sqrt{k_B T C}$, $Q_n (k_B, 300\text{K}, 4\text{fF}) = 25e^- \text{ rms}$ o.k.
- $1.2\text{V}/29.600e^- = 40\mu\text{V}/e^-$ o.k.

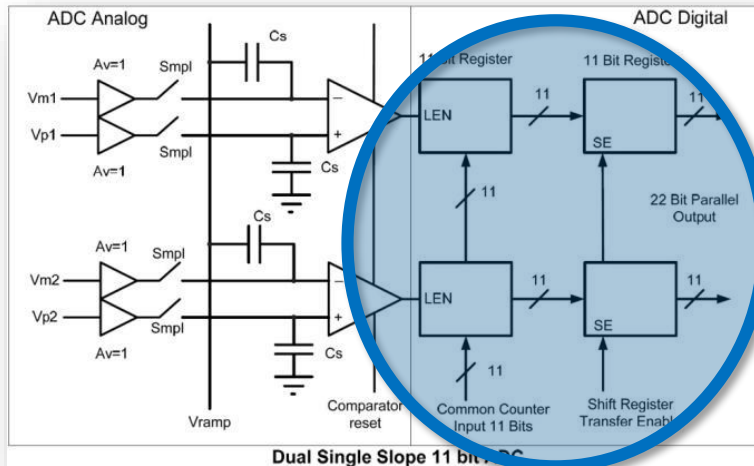
How do I get rid of the remaining 25e- rms kTC noise and reach the 1 – 2 e- rms level of sCMOS ?

Reset (kTC) noise can be minimized by correlated double sampling (CDS)
= subtraction of signal level and previous reset level

$$\text{dyn}_{\text{sCMOS image sensor}} = \frac{\text{full well capacity [e-]}}{\text{readout noise [e-rms]}} = \frac{30.000 \text{ [e-]}}{1 \text{ [e-rms]}} = 30.000 \text{ (89.5dB)}$$

How to digitize the 16bit intra-scene dynamic range of the sensor ?

technical limit: A/D converters implemented on a sCMOS sensor can not exceed 11bit dynamic because of power consumption, size, heat dissipation...



- The row output signal is fed into two 11bit A/D converters in parallel.
- One gets the original (low gain) signal,
- the other gets the original signal amplified x 30 (high gain).
- The outputs of both 11bit A/D converters can be matched together to cover the full 16bit dynamic range.

Additional benefit of the parallel 11bit readout:

Two 11bit A/D converters can be operated at a lower frequency than a single 16 bit A/D converter (at constant output frame rate)

11bit conversion with „low“ frequency produces less noise as it allows for longer setting times in the comparator of the ADC

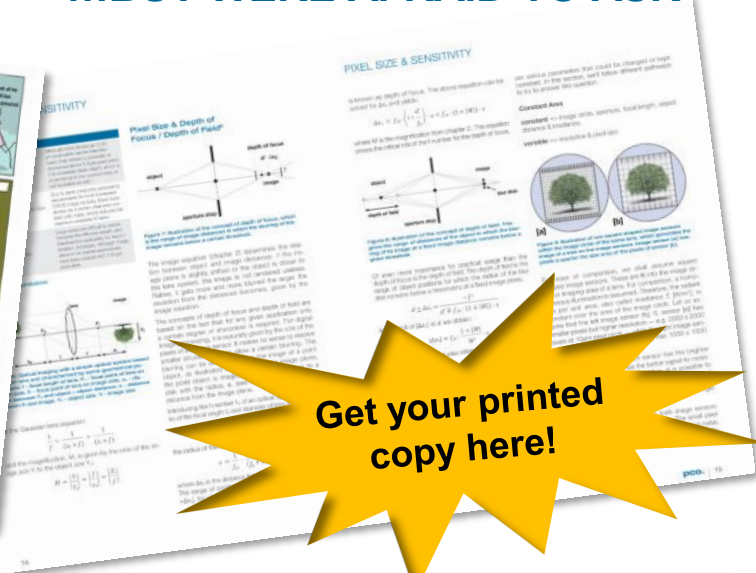
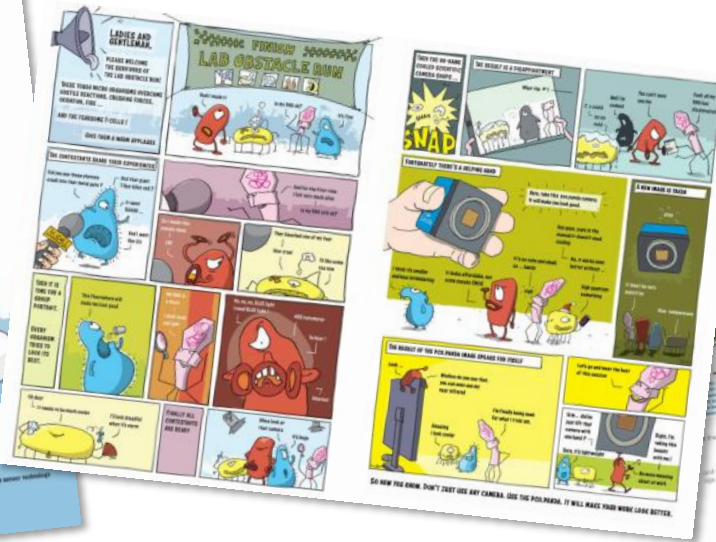
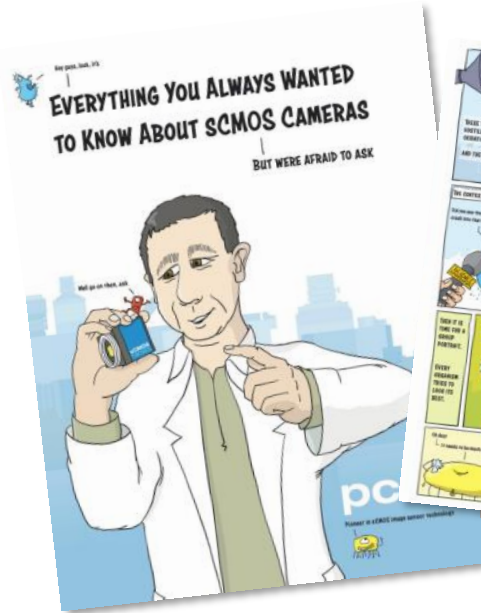
What makes a conventional CMOS sensor a scientific CMOS ?

It's mainly the adjustment and fine tuning of CMOS transistors to the needs of extreme sensitive and precise pixel readout in combination with dynamic enhancing ADC techniques and QE improvements (fill factor + micro lens).

more knowledge in our sCMOS eBook...

"EVERYTHING YOU ALWAYS WANTED TO KNOW ABOUT sCMOS CAMERAS

...BUT WERE AFRAID TO ASK"



Get your printed copy here!

Detailed explanations of topics like dynamic range, sensitivity, resolution and a lot more of sensor and imaging relevant content.

Scientific CMOS image sensors

BAE Fairchild & GPixel

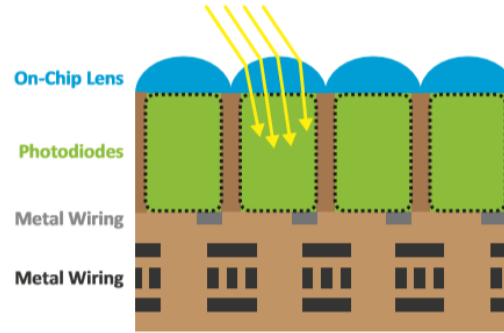
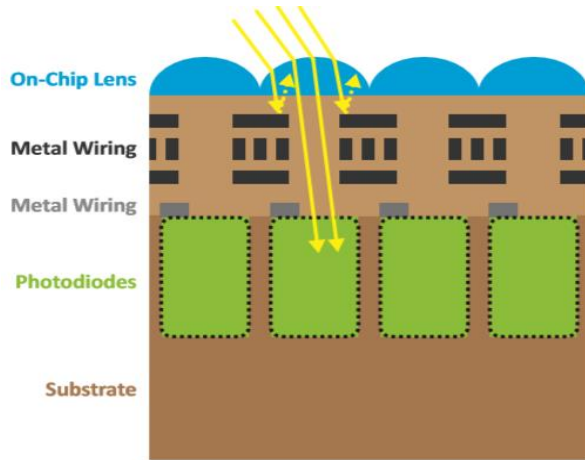
image sensor	CIS2521	CIS2020	CIS2020A	GSENSE2020e	GSENSE2020BSI	GSENSE400BSI	LTN4625A	GMAX0505
manufacturer	BAE Fairchild	BAE Fairchild	BAE Fairchild	GPixel Inc	GPixel Inc	GPixel Inc	BAE Fairchild	GPixel Inc
resolution [pixel]	2560 x 2160	2048 x 2048	2048 x 2048	2048 x 2048	2048 x 2048	2048 x 2048	4608 x 2592	5120 x 5120
pixel pitch [μm^2]	6.5 x 6.5	6.5 x 6.5	6.5 x 6.5	6.5 x 6.5	6.5 x 6.5	11.0 x 11.0	5.5 x 5.5	2.5 x 2.5
active area [mm^2]	16.6 x 14.4	13.3 x 13.3	13.3 x 13.3	13.3 x 13.3	13.3 x 13.3	22.5 x 22.5	25.3 x 14.3	12.8 x 12.8
diagonal	21.98 mm	18.83 mm	18.83 mm	18.83 mm	18.83 mm	31.86 mm	29.06 mm	18.10 mm
readout noise	< 2e-	1e-	1e-	< 2e-	< 1.6e-	1.6e-	2	1.6
frame rate (full)	100 fps	100 fps	100 fps	94 fps	47 fps @ HDR	48 fps	240 fps	150 fps @ 10bit
rolling shutter	X	X	X	X	X	X	X	-
global reset	X	-	-	X	X	-	X	-
global shutter	X	-	-	X	-	-	X	X
QE (peak)	> 60%	> 70%	> 80%	72%	95%	95%	> 50%	71%
dynamic range	> 1 : 15000	1 : 30000	1 : 30000	1 : 22387	1 : 50119	1 : 44668	1 : 25119	1 : 10000
fullwell capacity	30000 e-	30000 e-	30000 e-	45000 e-	55000 e-	89000 e-	40000 e-	16500 e-
power consumption	2 W	1.5 W	1.5 W	0.8 W (RS)	0.85 W	0.65 W	2 W @ 60 fps	1.9 W
monochrome	X	X	X	X	X	X	X	X
color	X	-	-	X	-	-	X	X

image sensor
size drawn to
scale



back illuminated sCMOS

Why is a backside illuminated sensor more sensitive than a front side illuminated ?



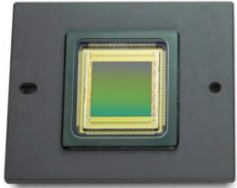
The wafer is processed with the image sensors reversed, and a large part of the substrate is physically and chemically etched away. The image sensors are then effectively illuminated from the back, and the light reaches the photodiodes more directly.

sCMOS Cameras

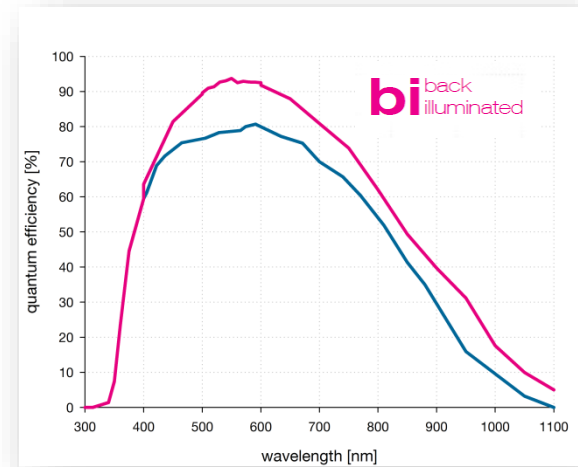
new front- and back illuminated image sensors

pcO.

...allow for ultra compact non-cooled cameras with



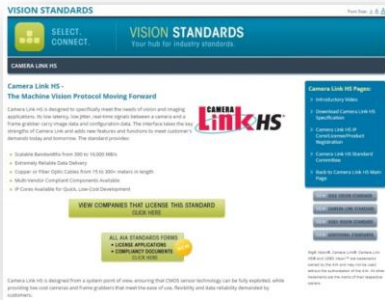
- monochrome or color sensor
- ultra-compact size: 65 x 65 x 65 mm³
- latest 16 bit sCMOS sensor technology front & back illuminated
- high resolution 2048 x 2048 pixel
- pixel size: 6.5 x 6.5 μm²
- low readout noise 2.1 e- med
- dynamic range of 21 500 : 1
- quantum efficiency up to 95 % (bi)
- exposure times from 10 μs to 5 s
- maximum frame rate 40 fps @ full resolution
- USB 3.1 Gen1 interface
- power over USB



- **more resolution**
 - pixel not too small (optical resolution and dynamic range)
 - pixel not too large (dark current, „Lag“ and readout noise)
- **more sensitivity**
 - Backside Thinning, QE > 90%
- **higher dynamic**
 - elaborate collection technologies deploying e.g. additional „buckets“
- **more speed**
 - more parallel A/D converter and faster digital readout
- **reduced readout noise**
 - charge domain CDS
- **more additional functions**
 - Multi-Tap-Readout

fast optical interfaces: CameraLink HS standard

pco.edge 5.5 : a high performance cooled sCMOS camera
5.5 MPix with 16bit digitization and 100 fps generates 1.1 GByte/s data load



Parameter	Camera Link HS
Data Rate	1.2 GByte/s per channel, number of channels scalable
Cable Length	nearly unlimited
Cable Type	MMF and SMF lightguide, insensitive towards electro-magnetic radiation, light weight, cost-effective
Hardware	standard network technology, Ethernet
IP Core	IP-Core in FPGAs, committee-IP-Core guarantees compatibility
Data Safety	X-Protocoll: Forward Error Correction (FEC)
Trigger Ability	Frame grabber can generate various trigger events at low jitter, various signal run times can be compensated by trigger-over-cable (from V2.0)
Sustainability	cost-effective hardware due to standard network technology

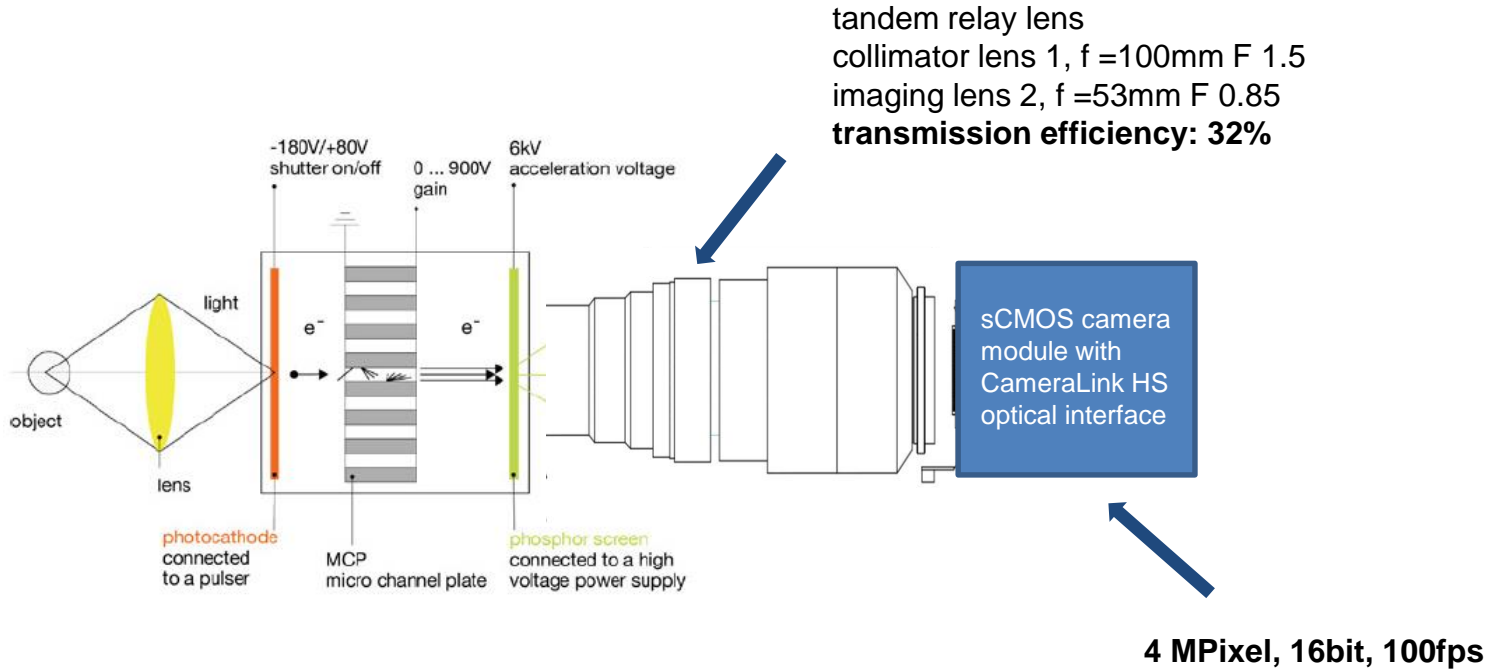
fast optical interfaces: CameraLink HS standard

pcO.



- per Camera Link HS channel appr. 1.2 GByte/s
- 4x pco.edge CLHS cameras directly on a single grabber
- 1x PCIe Gen3 (x8) slot required on PC side

■ Principle of image intensification



MCP based intensified cameras

knowledge base

- More about the principles of image intensification and optical coupling:
pco.dicam C1 intensified 16bit sCMOS whitepaper available from our website

pco.dicam C1
intensified 16bit sCMOS camera

intensified sCMOS
whitepaper

16bit sCMOS
expression ratio gain

10bit sCMOS
full resolution

pco.dicam C1

intensified sCMOS topography camera & 2nd plate

express ratio 8bit & 16bit with 10 bit sCMOS

pco.

intensified sCMOS
pco.dicam C1 - intensified 16bit sCMOS camera

Content	Page
1 Motivation for image intensification	3
2 Principle of image intensification	3
2.1 Photo-cathode	4
2.2 Micro Channel Plate (MCP)	5
2.3 Phosphor	6
2.4 Functional schematic of an intensified camera	6
3 Comparison of optical coupling methods	6
3.1 Fiber coupling	6
3.2 Single lens coupling - and why PCC avoids it	10
3.3 Window lens coupling - and why it & PCC avoids it	11
3.4 Coupling	12
3.5 Camera module	13
3.6 Head generator intensified imaging - the new pco.dicam C1	13
3.7 Unintensified image quality through lens coupling	13
3.8 16M bit & 16bit resolution	13
3.9 Camera lens FOV	13
3.10 Additional selection ratio gain	14
3.11 Optical fiber and 17 lens camera	14

intensified sCMOS
2 Principle of image intensification

Figure 1
Relative Intensity (%)
Micro Channel Plate (MCP)
Gain

Figure 2
Relative Intensity (%)
Gain

2.3 Phosphor
The phosphor is the P20 component of the image intensifier and is responsible for the optical output. Its function is to convert light to visible light. It is a thin layer of phosphor. Like the photo-cathode, the phosphor is a thin layer of the same substance. Contrary to the photo-cathode, the phosphor does not contain the electron multiplier.

2.4 Functional schematic of an intensified camera
The functional schematic of an intensified camera consists of a photo-cathode, a Micro Channel Plate (MCP), a phosphor, and a camera module. The photo-cathode is a thin layer of the same substance as the MCP. The MCP is a stack of micro-channel plates. The phosphor is a thin layer of phosphor. The camera module is a camera module.

3 Comparison of optical coupling methods
It has been a long and controversial discussion about the best way to connect the optical coupling between the photo-cathode and the camera module. The different methods to connect them are fiber optic coupling, lens coupling, and window lens coupling. The fiber optic coupling is the most common method. The window lens coupling is the most common method. The lens coupling is the most common method.

3.1 Fiber coupling
Fiber coupling is a method of connecting the photo-cathode and the camera module. It consists of a fiber optic cable that connects the photo-cathode to the camera module. The fiber optic cable is a thin layer of glass that carries the light from the photo-cathode to the camera module.

3.2 Single lens coupling
Single lens coupling is a method of connecting the photo-cathode and the camera module. It consists of a single lens that connects the photo-cathode to the camera module. The single lens is a thin layer of glass that carries the light from the photo-cathode to the camera module.

3.3 Window lens coupling
Window lens coupling is a method of connecting the photo-cathode and the camera module. It consists of a window lens that connects the photo-cathode to the camera module. The window lens is a thin layer of glass that carries the light from the photo-cathode to the camera module.

3.4 Coupling
Coupling is a method of connecting the photo-cathode and the camera module. It consists of a coupling that connects the photo-cathode to the camera module. The coupling is a thin layer of glass that carries the light from the photo-cathode to the camera module.

3.5 Camera module
Camera module is a method of connecting the photo-cathode and the camera module. It consists of a camera module that connects the photo-cathode to the camera module. The camera module is a thin layer of glass that carries the light from the photo-cathode to the camera module.

3.6 Head generator intensified imaging
Head generator intensified imaging is a method of connecting the photo-cathode and the camera module. It consists of a head generator that connects the photo-cathode to the camera module. The head generator is a thin layer of glass that carries the light from the photo-cathode to the camera module.

3.7 Unintensified image quality through lens coupling
Unintensified image quality through lens coupling is a method of connecting the photo-cathode and the camera module. It consists of a lens that connects the photo-cathode to the camera module. The lens is a thin layer of glass that carries the light from the photo-cathode to the camera module.

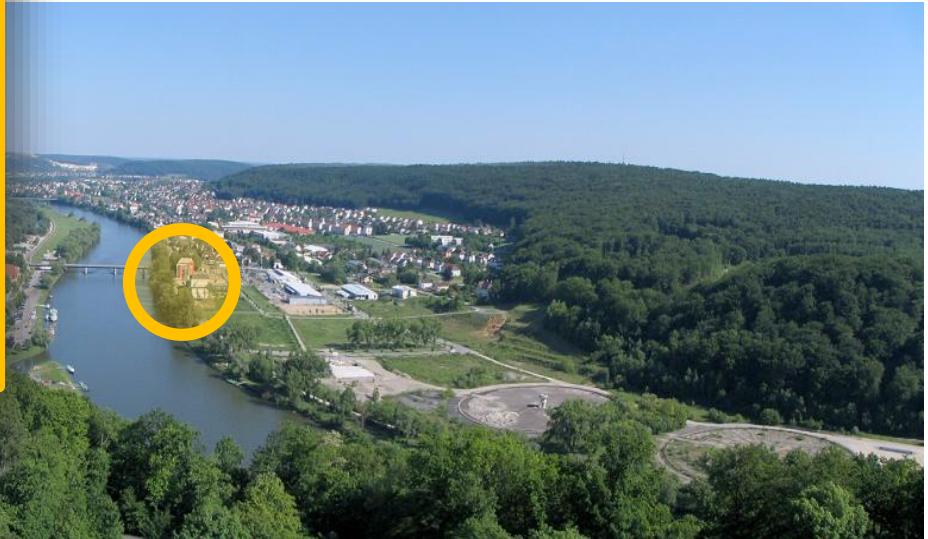
3.8 16M bit & 16bit resolution
16M bit & 16bit resolution is a method of connecting the photo-cathode and the camera module. It consists of a camera module that connects the photo-cathode to the camera module. The camera module is a thin layer of glass that carries the light from the photo-cathode to the camera module.

3.9 Camera lens FOV
Camera lens FOV is a method of connecting the photo-cathode and the camera module. It consists of a camera lens that connects the photo-cathode to the camera module. The camera lens is a thin layer of glass that carries the light from the photo-cathode to the camera module.

3.10 Additional selection ratio gain
Additional selection ratio gain is a method of connecting the photo-cathode and the camera module. It consists of a camera module that connects the photo-cathode to the camera module. The camera module is a thin layer of glass that carries the light from the photo-cathode to the camera module.

3.11 Optical fiber and 17 lens camera
Optical fiber and 17 lens camera is a method of connecting the photo-cathode and the camera module. It consists of an optical fiber and a 17 lens camera that connects the photo-cathode to the camera module. The optical fiber and 17 lens camera is a thin layer of glass that carries the light from the photo-cathode to the camera module.

- There are still a few high end CCD and emCCD sensors available, some of them for very special applications like image acquisition in deep uv. But Sony's decision shows that we can't expect much further development in CCDs.
- sCMOS sensors show today (except for their dark current behaviour) much better performance data than good conventional CCD sensors, so that they have already replaced CCDs in many „low-light“ applications.
- CameraLink HS as a new data interface standard is now available to make full use of sCMOS speed.
- Even established technologies like MCP based intensified cameras benefit from sCMOS sensors.



Since 1987 PCO develops and manufactures high end CCD, CMOS & sCMOS camera systems for scientific and industrial research, measurement, quality control and OEM applications.

Thank you!

pcO.





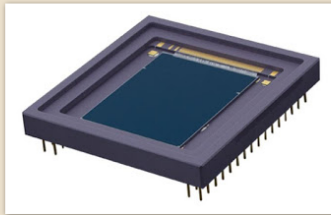
Teledyne e2v Releases 4MP BSI Rad-Hard Sensor

Teledyne e2v has released a new image sensor, the CIS120, for harsh environments such as space applications. Samples have been available since February 2019 along with a full test and demonstration system.

Key specifications of the CIS120 include a resolution of 2048 x 2048 and BSI 10µm square pixels with a QE of 90% at 550 nm (typical). The sensor offers both a rolling shutter mode with a frame rate of 30 fps (8 bit) and a global shutter mode with a frame rate of 20 fps (12 bit).

Key features include:

- Good latch-up immunity and high SEU threshold by design and is resistant to ionising radiation by process choice
- Pixel read timing is set by an on-chip sequencer to simplify use and to reduce pin count
- A column parallel ADC is controlled by its own sequencer
- Resolution can be set anywhere from 8 to 14 bits
- Four LVDS channels output the image data and are controlled by the readout sequencer to scan along each row in turn.
- All configuration settings are programmed over an SPI. This includes shutter mode, ADC resolution and bias current values
- Package options include ceramic PGA and metal and ceramic three-side butting designs for use in mosaic focal planes
- CIS120 is stitched, so other sizes are possible from 2048 x 1024, up to 2048 x 8192 pixels, without the cost of new masks as well as other customer-specific requirements such as anti-reflective coatings
- An increased charge capacity of 100 ke⁻ is possible by a metal pattern change



TYPICAL PERFORMANCE

Number of pixels	2048 × 2048
Pixel size	10 µm × 10 µm
Image area	20.48 × 20.48 mm
Linear charge capacity	35 ke ⁻ /pixel
Conversion gain	40 µV/e ⁻
Quantum efficiency @ 550 nm (BI)	90 %
Dark current at 20 °C	50 e ⁻ /pixel/s
Readout noise	4 e ⁻ rolling shutter 11 e ⁻ global shutter
ADC resolution	8, 10, 12 or 14 bit
Frame rate (rolling shutter and full frame)	30 fps @ 8bit, 20 fps @ 12bit
Outputs, LVDS or sub-LVDS	4 data + 2 sync
Output data rate	260 Mbps/channel
Setup and control bus	SPI
Clocks	4 MHz and 130 MHz
Power supplies	3.3V and 1.8V
Power consumption	<280 mW (sub-LVDS) <350 mW (LVDS)
Die size (width × height)	22.20 × 28.35 mm

SPECTRAL RESPONSE

A typical back illuminated spectral response (QE) with the 'Multilayer-2' AR coating is shown below:

