

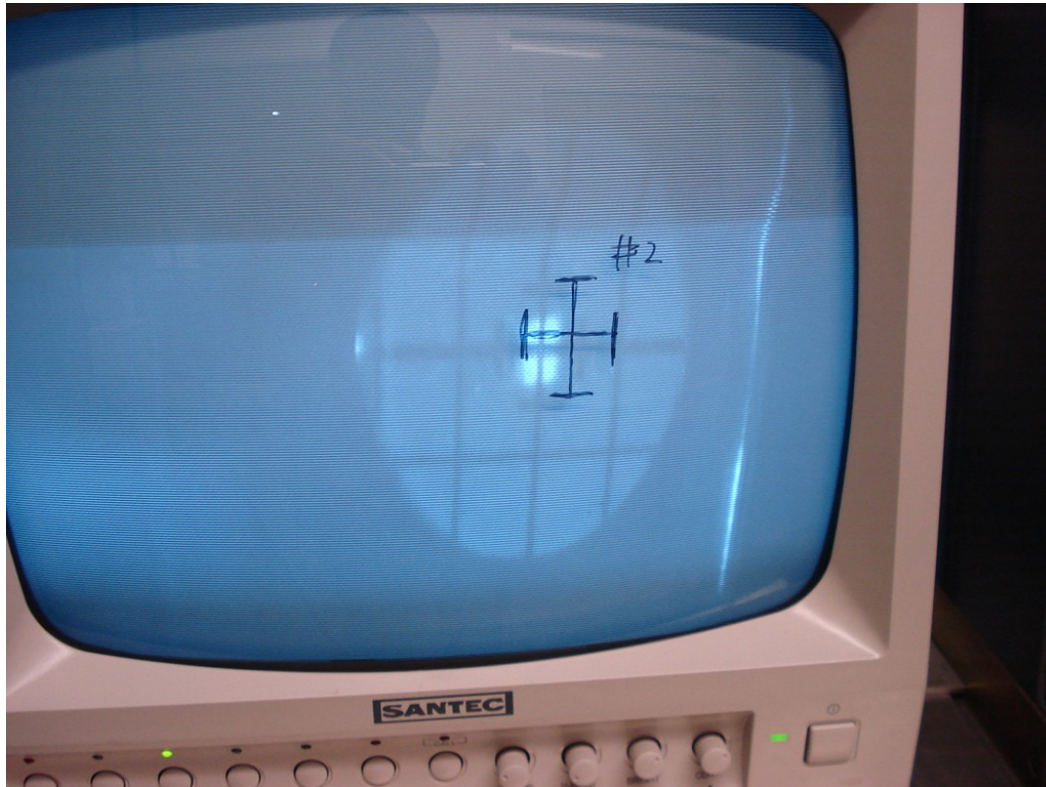
Cameras at GSI / FAIR

Hardware – Software – Operation

Harald Bräuning
Beam Instrumentation, GSI

Scintillating Screen Readout at GSI prior to 2013

Image Readout

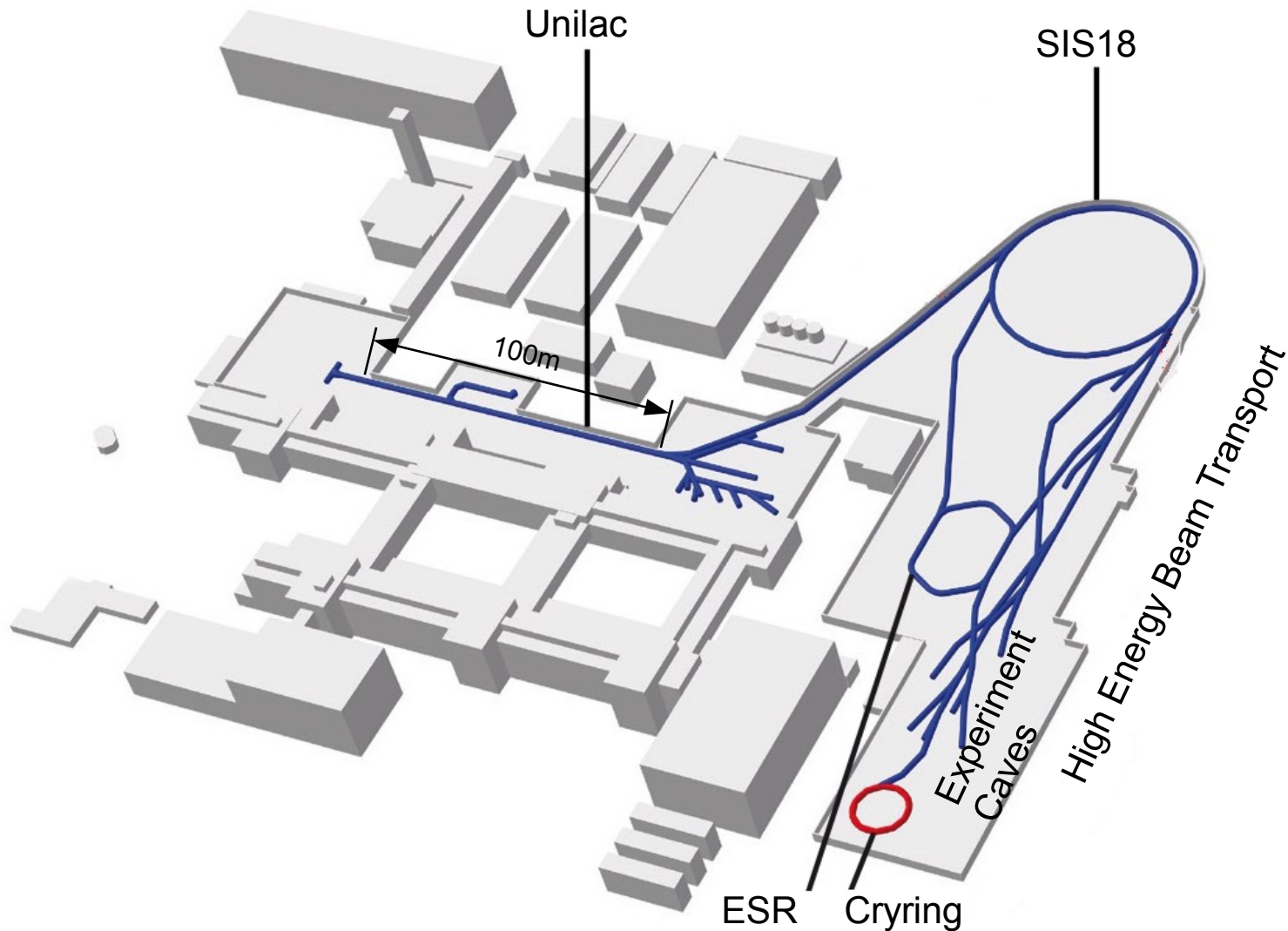


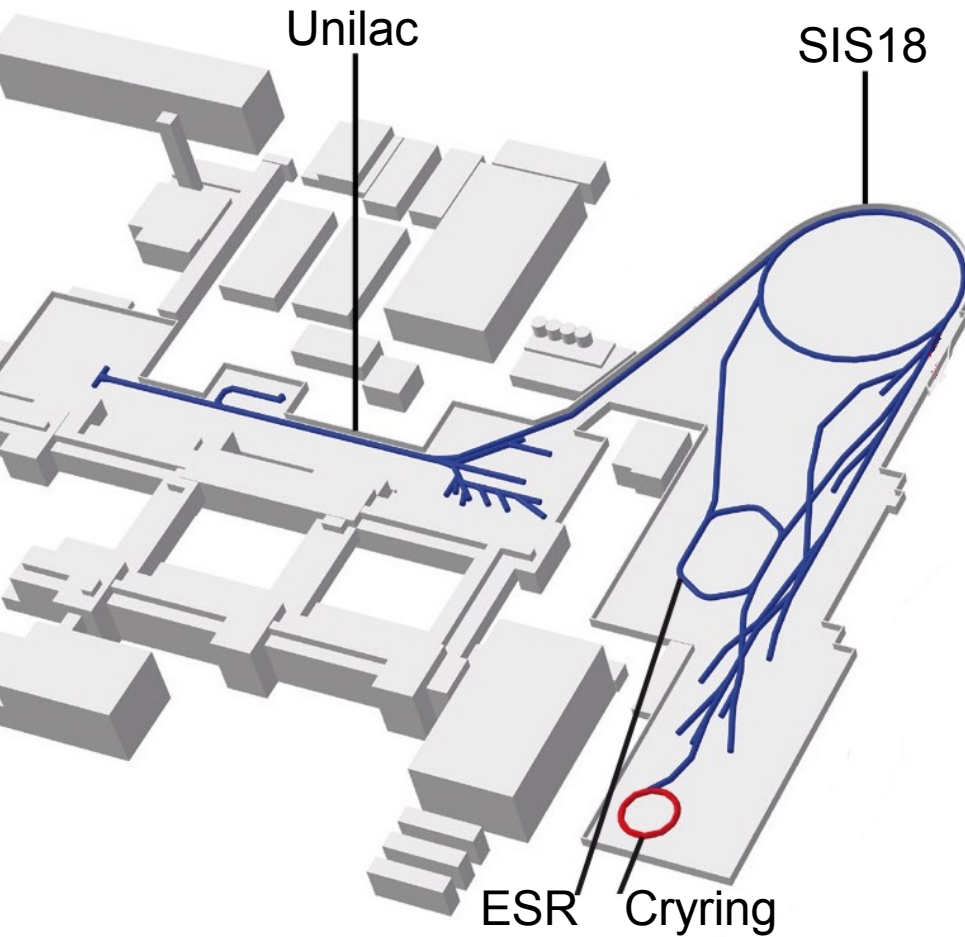
Transport Protocol
from Experiment Cave
to Main Control Room



Lots of room for improvement . . .

GSI accelerates all ions from protons up to uranium



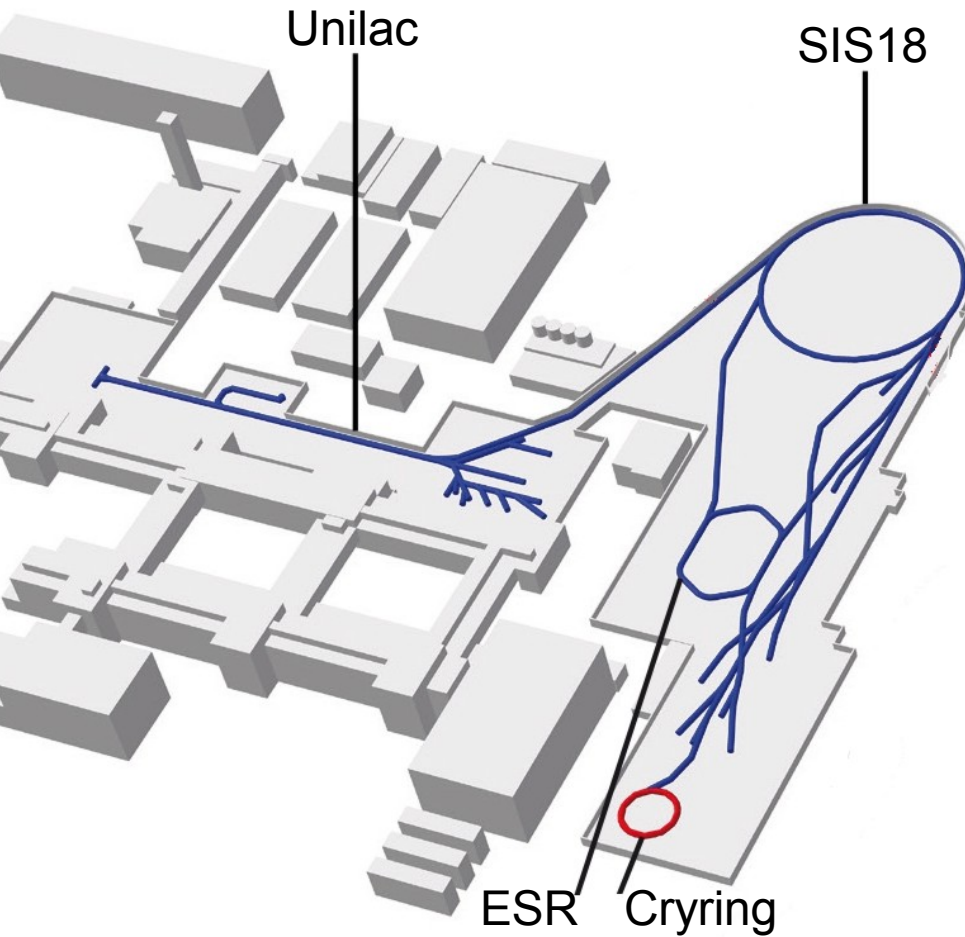


Unilac

- energies up to 11.4 MeV/u
- up to 10^{12} particles per ms pulse
- up to 50 Hz repetition rate
- beam size: mm – cm

SIS18

- energies up to 4 GeV/u
- electron cooler
- up to 10^{11} particles
- fast extraction (1 μ s)
- slow extraction up to 10 s
- beam size (incl. HEFT): mm – cm



ESR

- primarily storage ring
- stochastic and electron cooling
- deceleration to 4 MeV/u
- fast extraction to Cryring (few μs)
- slow extraction up to 60s and more

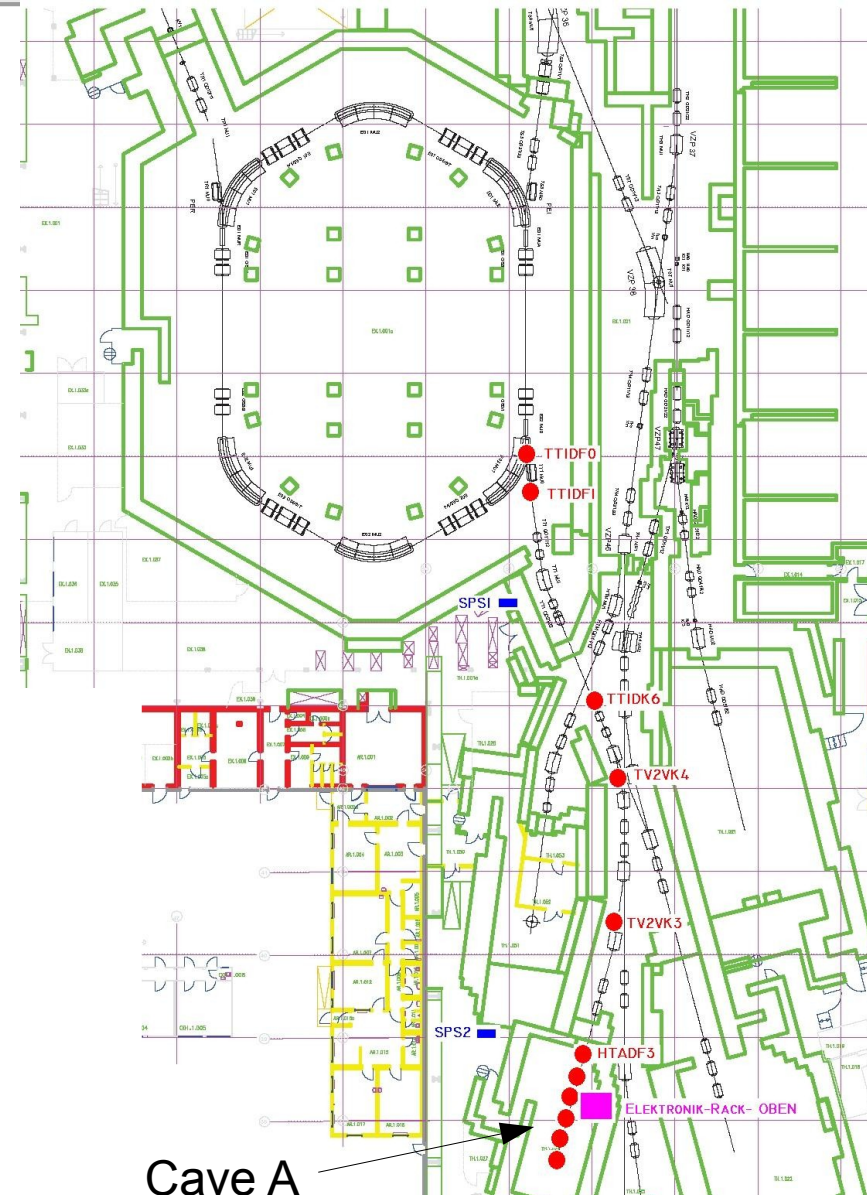
Cryring

- recent addition (from Stockholm)
- test bench for FAIR control system
- primarily storage ring
- energy range 0.3 – 14 MeV/u
- electron cooling
- 2 injectors
 - Linac for light ions at 0.3 MeV/u
 - cooled heavy ions from ESR at 4MeV/u

Up..., Up..., Upgrade

2013: Upgrade Cave A

- driven by atomic physics experiments
- improve beam diagnostics on beamline from ESR to Cave A
 - low energy ions
 - low intensity
- required for optimizing beam transport and emittance / collimation
- 6 new scintillating screens on path from ESR to Cave A
- 5 experiment screens in Cave A (only temporarily installed)
- digital readout

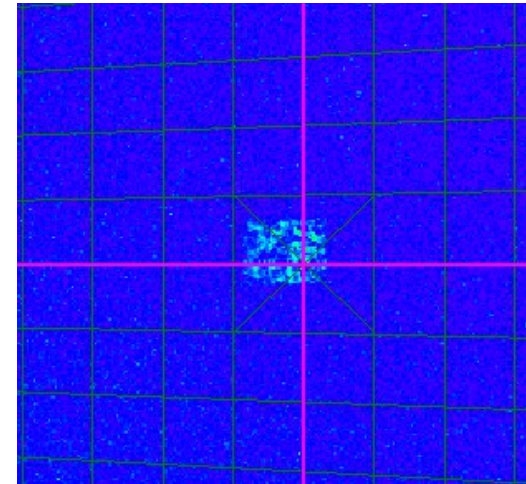


2013: Upgrade Cave A

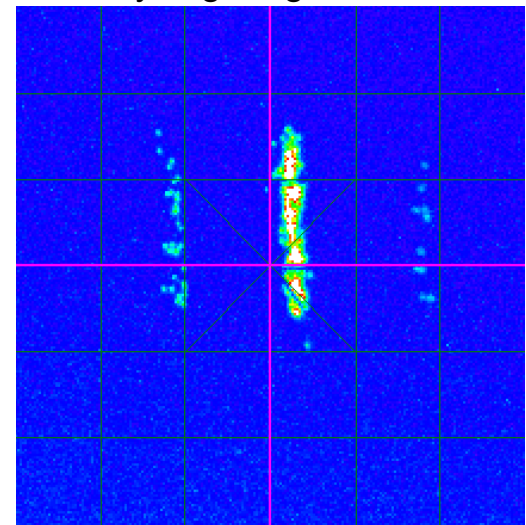
Requirements from experiments:

- slow and fast extraction from ESR
- ions up to uranium
- down to about 10^4 particles per second
- energies 4 MeV/u up more than 200 MeV/u
- simultaneous view in experimental hut and main control room
- storage of images for later analysis
- measurement of beam position and approximate FWHM in SI units
- free run and triggered image acquisition

Cave A: 190MeV/u U^{89+}
collimated beam on 1st experiment screen



charge state distribution on screen
after analysing magnet

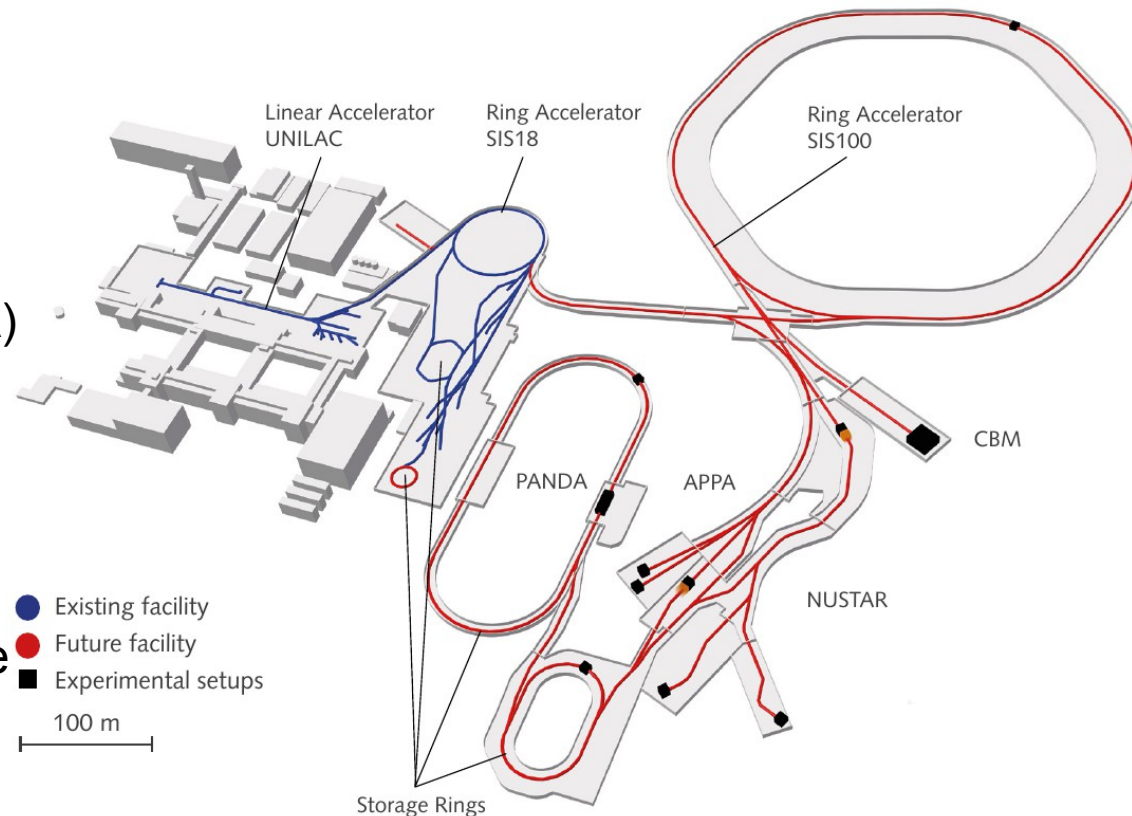


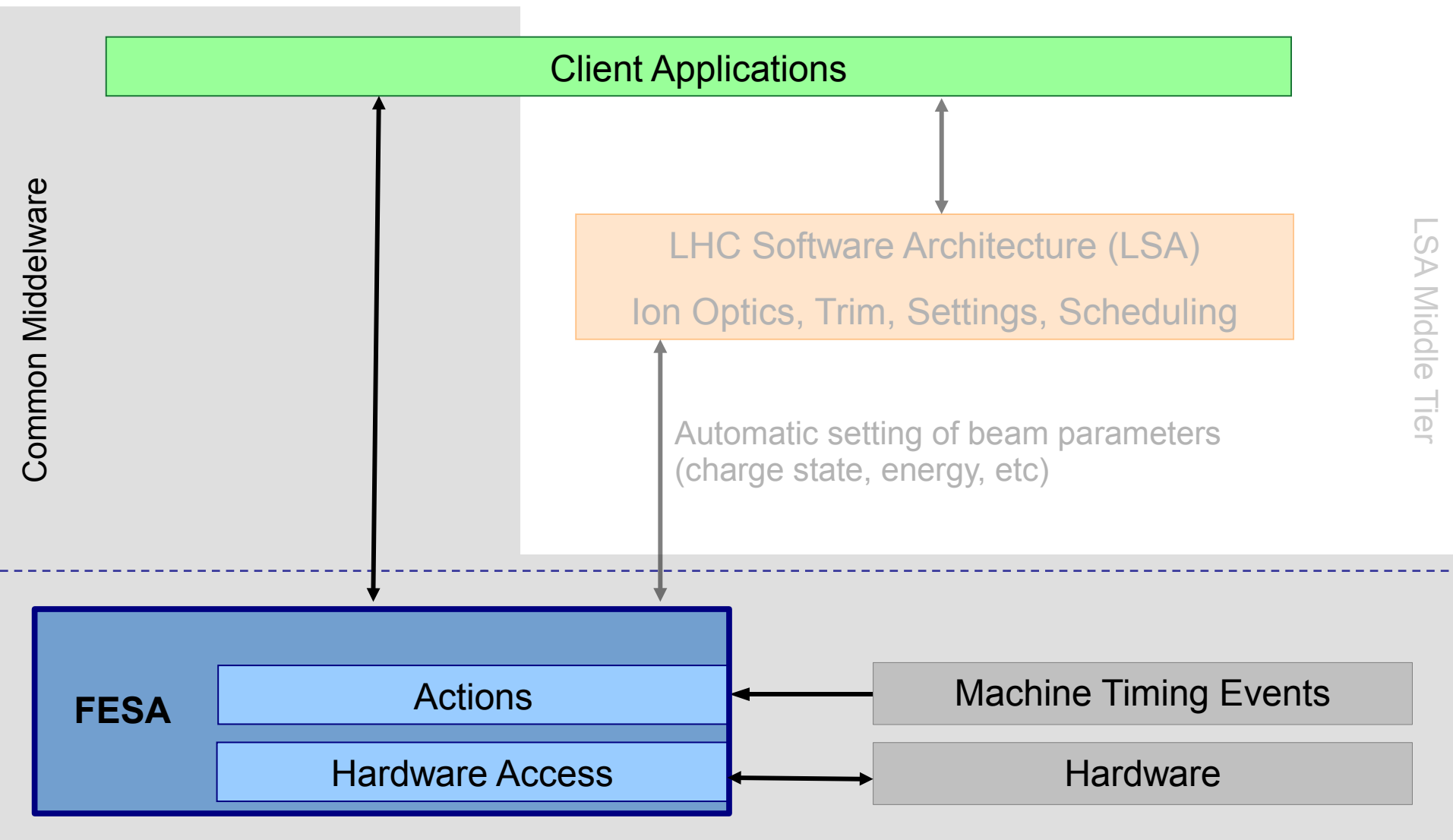
2013: Upgrade Cave A

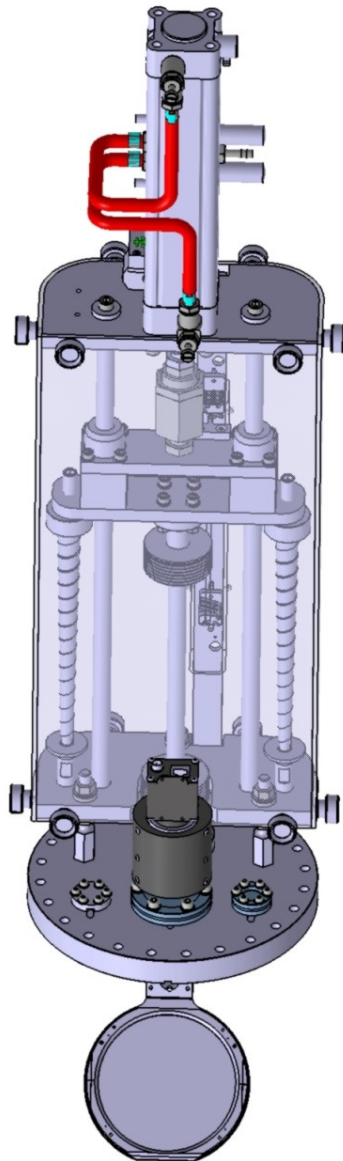
Prototype for scintillating screen readout in the FAIR accelerator complex!

Constraints imposed by the FAIR Control System:

- Client – Server architecture
- Server (Frontend Controller)
 - Linux operating system
 - based on Cern's FrontEnd Software Architecture (FESA)
 - C++
- Client (GUI, ...)
 - based on Java / JavaFX
 - number of clients is indefinite

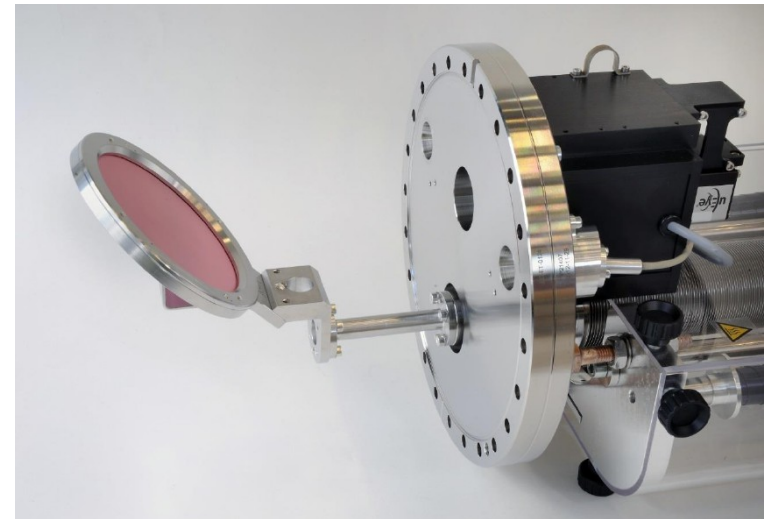






Linear Feedthrough

- mostly driven by pressurized air
- some driven by stepper motors



Camera

Remote Controlled Lens
LED for target illumination

Scintillating screen in standardized holder



iDS UI-5240SE-M (monochrome)

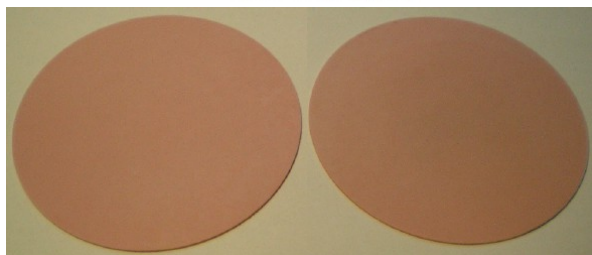
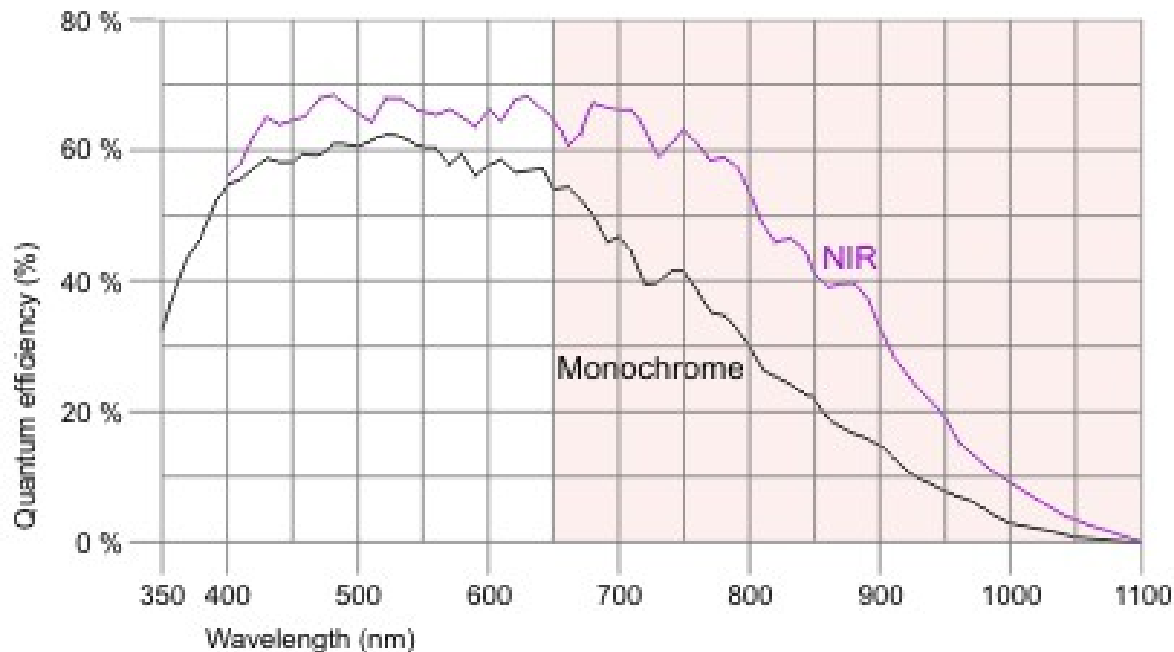
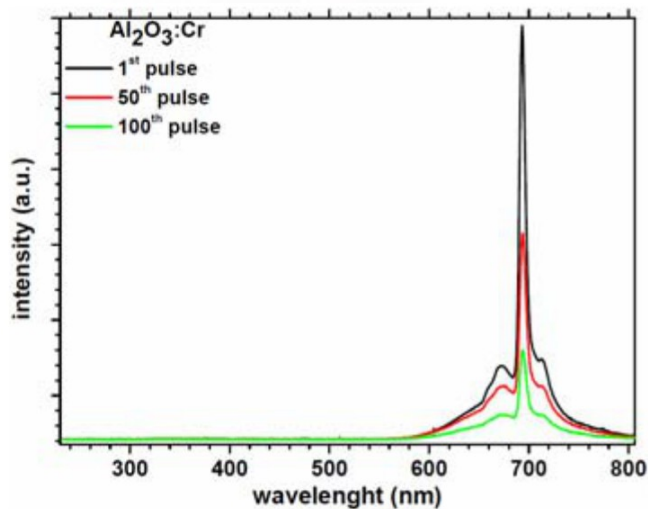
e2v Image Sensors:

- high sensitivity
- good radiation tolerance
 - used in a space environment

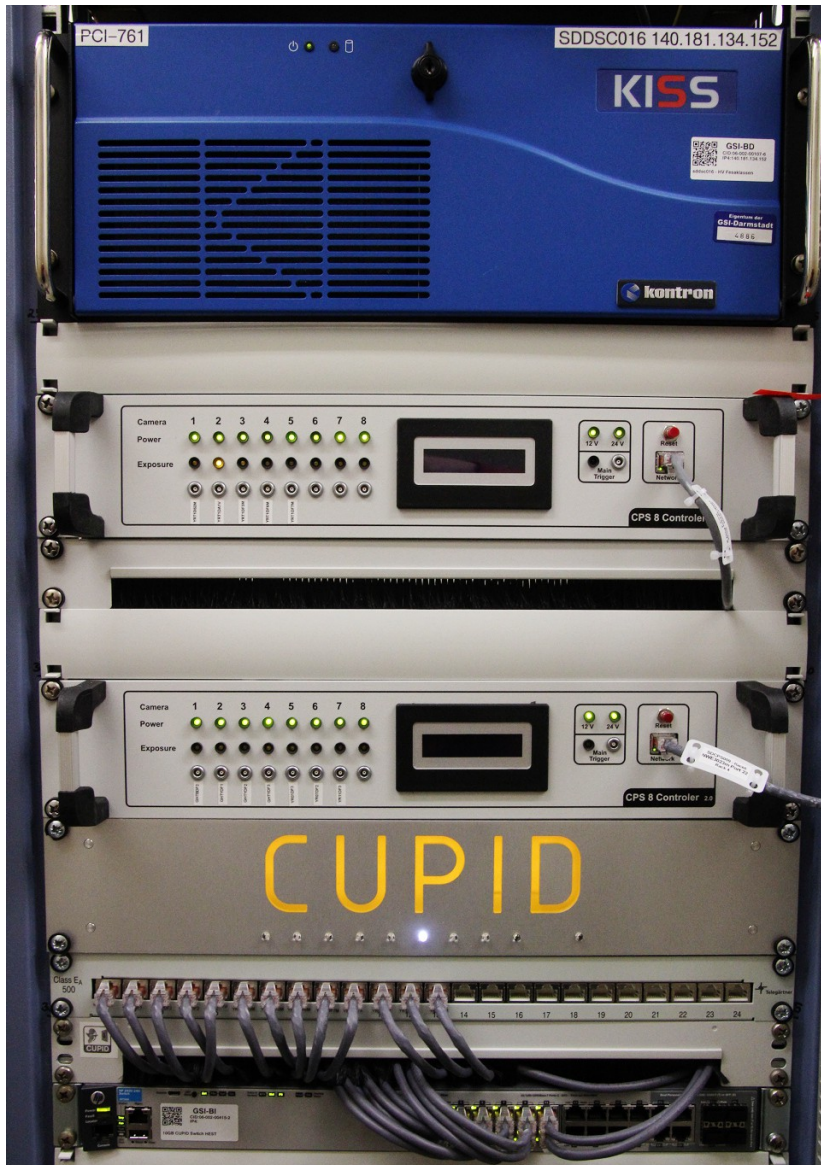
	specification	remarks
interface	GigE	
sensor	CMOS (e2v)	selection criteria
pixel	1280 x 1024	prog. AOI
pixel pitch	5.3 μ m	
shutter	global	
max. framerate	50fps	\leq 10fps
exposure time	9 μ s – 2s	1ms – 1s
binning	h + v (2x)	
analog gain boost	2x	
ADC	10bit	8bit readout
I/O	trigger input	trigger by event
	strobe output	monitor

<http://ids-imaging.com>

iDS UI-5240SE-M (monochrome)



Standard scintillating screen for **FAIR**:
chromium doped aluminum oxide Al₂O₃:Cr (0.04% mass)



Industrial PC

- data acquisition for cameras
 - via 10 Gbit ethernet switch (local network)
 - camera configuration
 - camera readout
- via standard LAN (accelerator network)
 - control of CPS8 controllers
- Fair Timing Receiver Node
 - hardware trigger (LVTTL)
 - based on machine event
 - distributed via CPS8 controller
 - currently: all cameras = one trigger
 - future: one camera = one trigger

10 Gbit Ethernet Switch

New Systems: μ TCA based

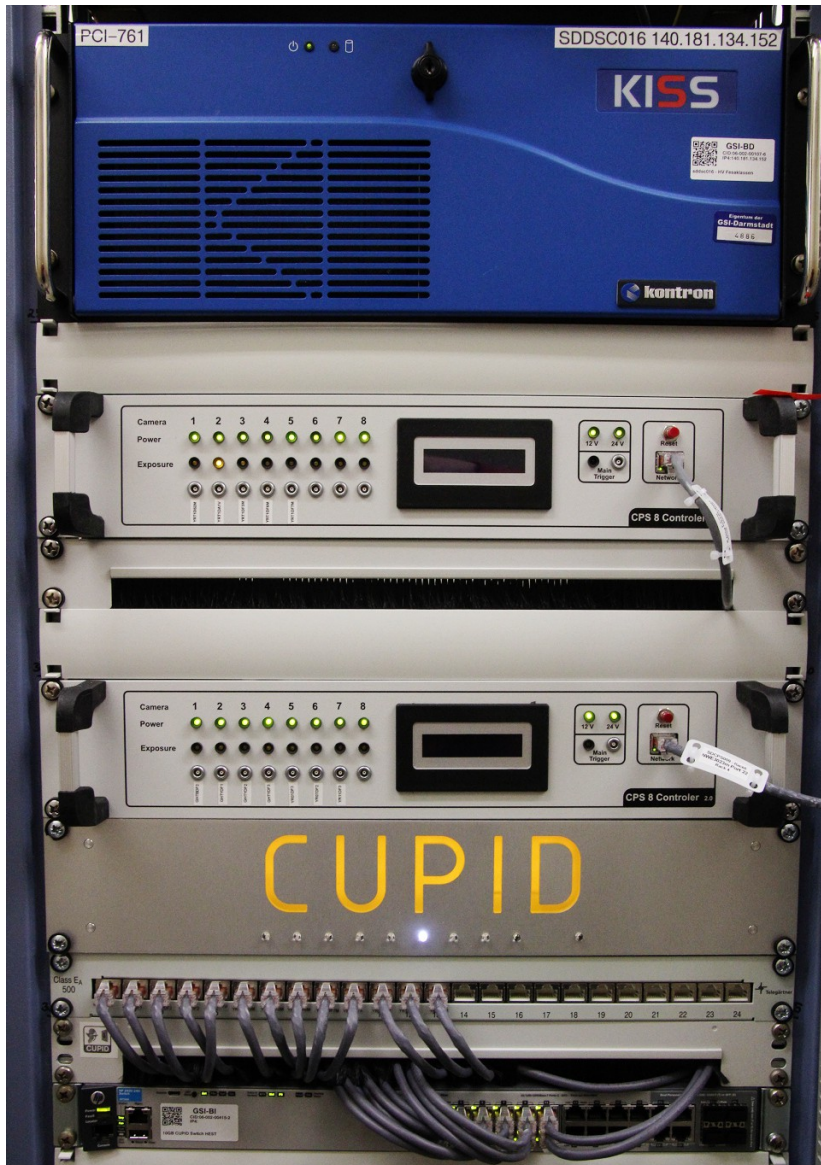
- compact modular system
 - 8 Port Gbit ethernet switch
 - data acquisition from cameras
 - multiple switches in principle possible
- Fair Timing Receiver Node
- disadvantages:
 - complicated configuration of μ TCA backplane ethernet lines
 - at first suboptimal configuration:
 - system worked
 - 30s discovery time of cameras after camera power cycle (typical with optimal configuration: 2 – 3s)



Fair Timing Receiver Node



8 Port Gbit Ethernet Switch



CPS8 Controller

- build in-house
- Atmel Microcontroller (Arduino) based
- simple ethernet based access
- camera power control
- camera power status
- camera trigger
 - software trigger
 - hardware trigger distribution
 - currently: all cameras = one trigger
 - future: one camera = one trigger
- further options like burst mode could be implemented
- front panel indicators
 - camera power
 - camera exposure (camera strobe output)

Remote Controlled Lenses

- mainly to adjust image intensity via iris
- occasionally focus in case of different screen positions
 - i.e. Crying: different correct beam position on injection screen depending on source path

Pentax -ER Series

- iris control by DC voltage (1.5 – 5.5V)
- iris closes when power is cut off
- manual focus
(usually sufficient)

Linos MeVis-Cm

- intended as replacement
- motorized iris
- motorized focus
- encoders for precise and reproducible adjustment

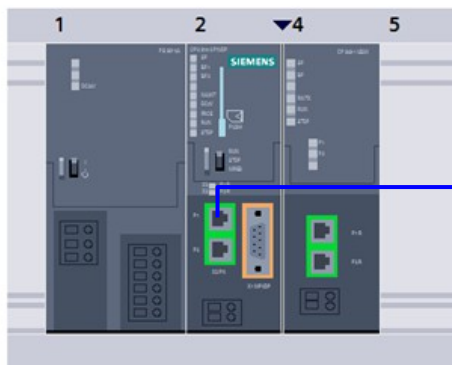


DISCONTINUED
(but we have 60 pcs in reserve)

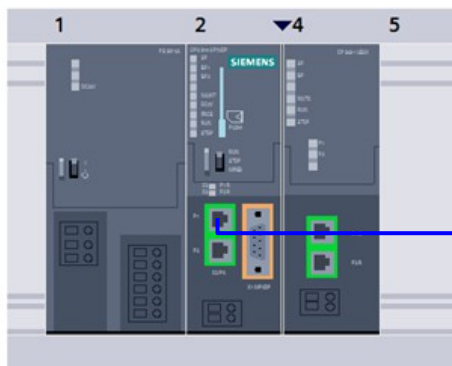
DISCONTINUED

Remote Controlled Lenses

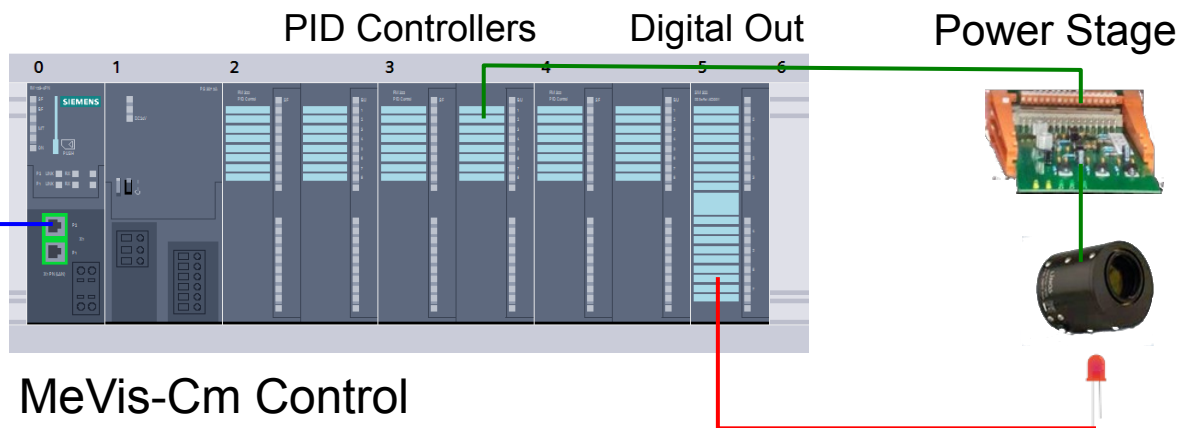
Controller



Programmable Logic Controller (PLC)



Satellites



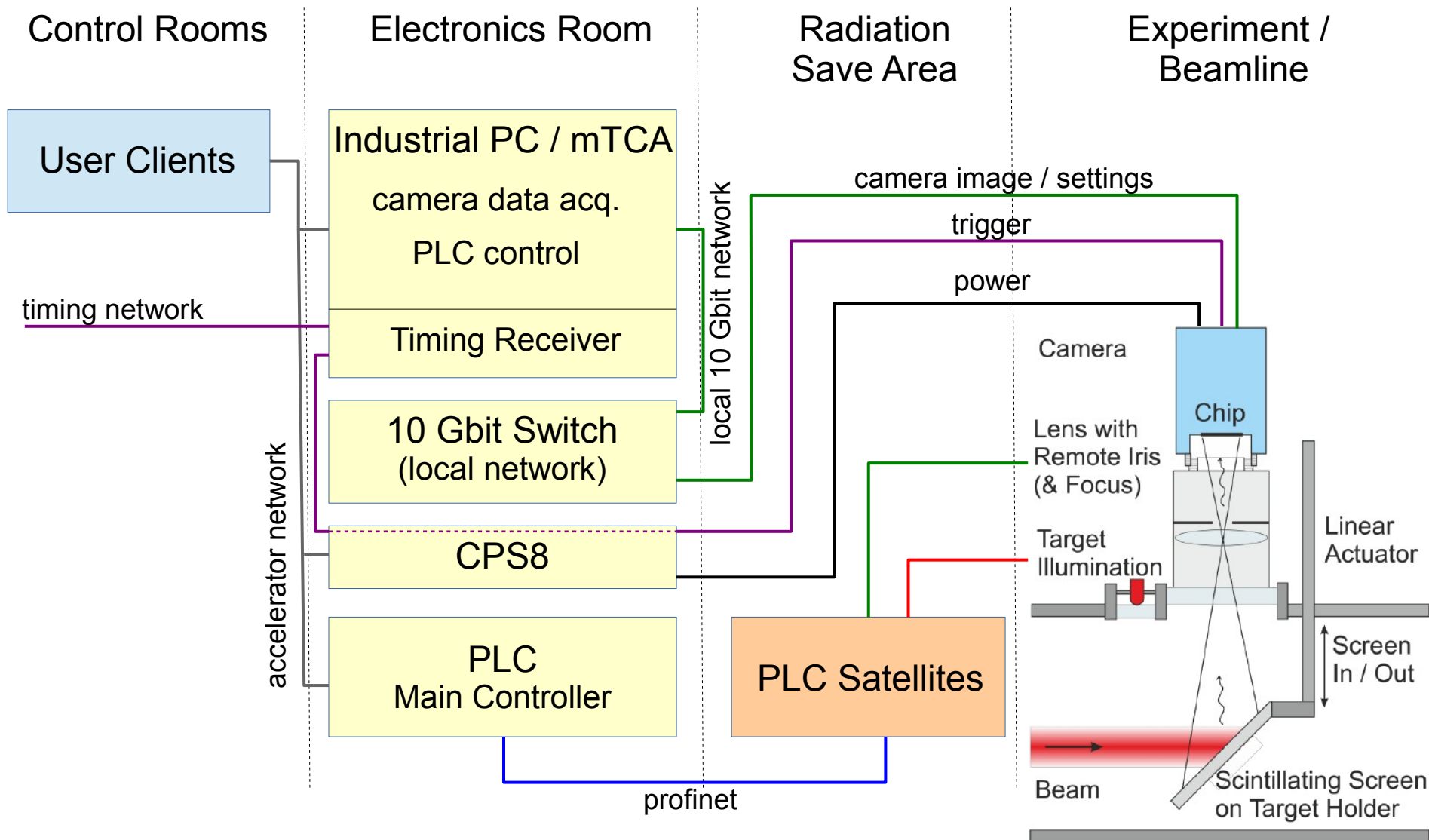
MeVis-Cm Control

Digital Out
Analog Out

Pentax Control



Complete System Overview



Analog Cameras

- legacy cameras already installed
- Thermo Fischer RadHard camera (MegaRAD3)

Pleora iPort Analog-Pro External Frame Grabber

- Gbit ethernet based
- GigE Vision and GenICam compatible

Analog cameras run continuously

- rate reduction in software to 10Hz
- trigger by software
 - all frames are discarded but next frame after trigger



Client – User Application



English 2019-02-18 00:08:34

SIS GS06DFV GTE1DF1V GTE2DF4V GTH2DFAV

GTH2DFAV

Cyclename: ---

Acq Time: 2019-02-18 00:07:49.562

Stop Reset

Timing

Basic Expert

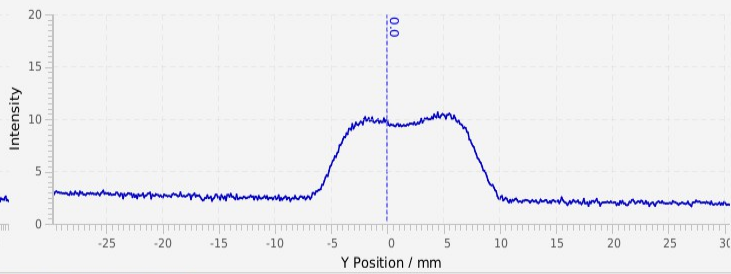
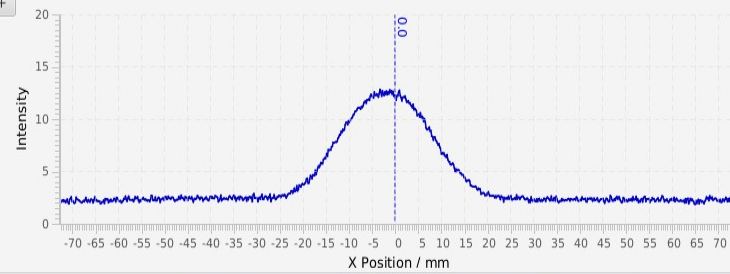
Iris: closed open

Set

LED: Switch On

Profile Trend

20.00 - +



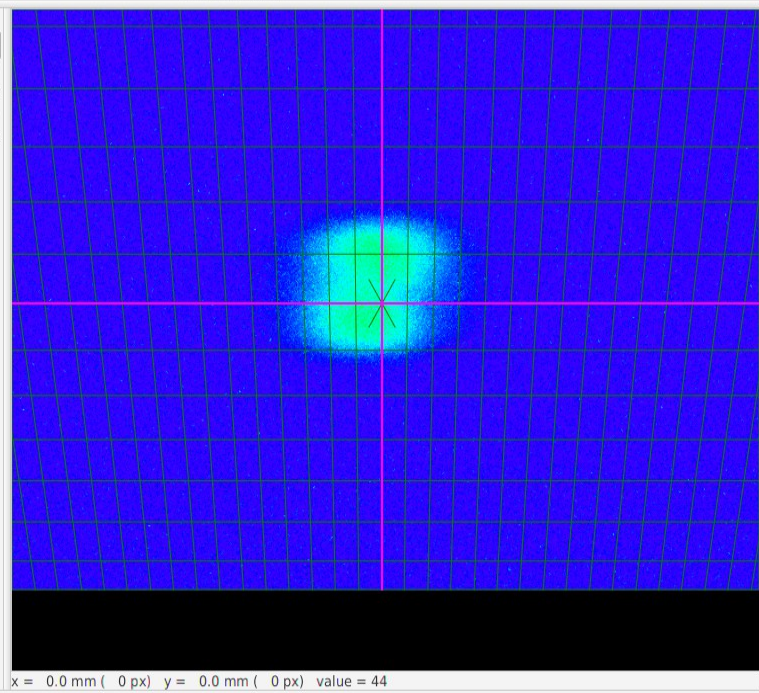
Display

Mode: Rainbow

Brightness: 1x 2x 4x

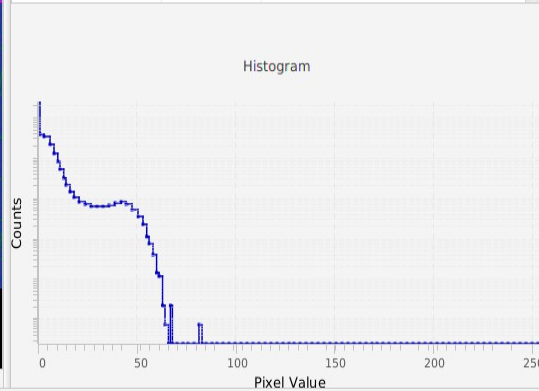
Zoom: Fit 1x 2x 3x

Show Grid Show Marker Center



Info

Integral	1939796
est. Background	4
est. Brightness	-9004
Profile Max. X	-3.3 mm
Center X	-2.3 mm
FWHM X	18.3 mm
Profile Max. Y	4.4 mm
Center Y	2.3 mm



Camera: Active Status Details

Plc: Power Status Details

INFO [18 Feb 2019 00:08:33.186] (SaveDataService.java) - http://clipboard.acc.gsi.de/dav/bi/data//GTH2DFAV/2019-02-18_00-07-49_tcl1028_GTH2DFAV_Spill_12C6p_1450AMeV_dvoptics_00030_Y.dat

Data Acquisition on the Frontend: Server for Multiple clients

Image Acquisition and Processing

- image acquisition
- software crop
- rotation (90°, 180°, 270°)
- mirror
- simple image scaling
- projections
- simple analysis neglecting further perspective distortion
 - histogram
 - position of brightest pixel
 - center-of-brightness
 - FWHM

Camera / Software Settings (if supported)

- acquisition mode (free running / triggered)
- exposure time
- binning
- gain boost
- contrast
- brightness
- rotation / mirror
- area-of-interest (fixed during runtime)

Perspective Distortion

scintillating screen is typically mounted under 45° with respect to the optical axis

- short distance leads to visible perspective distortion
- position (x,y) in SI units can be calculated for each pixel by

$$x'_p = x_p - x_{p0}$$

$$y'_p = y_p - y_{p0}$$

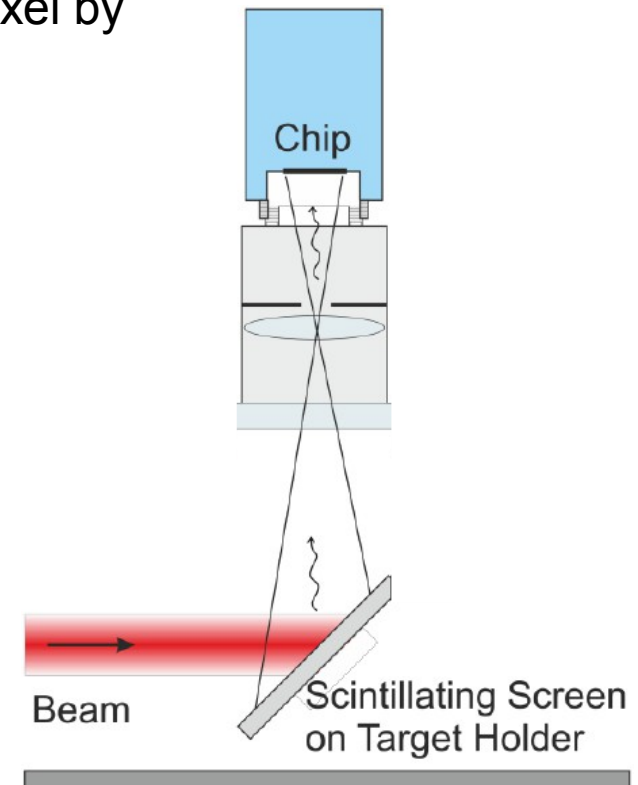
$$x = (s_x + \Delta s_{xx} x'_p + \Delta s_{xy} y'_p) x'_p$$

$$y = (s_y + \Delta s_{yx} x'_p + \Delta s_{yy} y'_p) y'_p$$

- we do not rectify the image!

x_p, y_p = pixel position; x_{p0}, y_{p0} = pixel position of screen center

$s, \Delta s$ = scale factors



Perspective Distortion

scintillating screen is typically mounted under 45° with respect to the optical axis

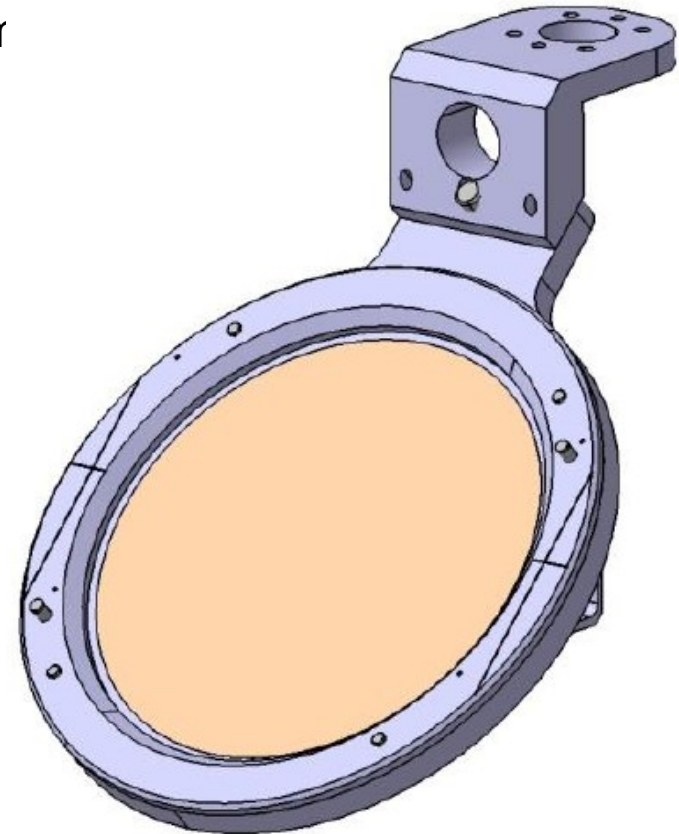
- standard target holder contains alignment marks
- all scale factors are determined from the alignment n
- vertically mounted assemblies
 - $\Delta s_{xx} = 0$ and $\Delta s_{yx} = 0$
- horizontally mounted assemblies
 - $\Delta s_{xy} = 0$ and $\Delta s_{yy} = 0$

$$x'_p = x_p - x_{p0}$$

$$y'_p = y_p - y_{p0}$$

$$x = (s_x + \Delta s_{xx} x'_p + \Delta s_{xy} y'_p) x'_p$$

$$y = (s_y + \Delta s_{yx} x'_p + \Delta s_{yy} y'_p) y'_p$$



Perspective Distortion

perspective distortion is solely handled by the client

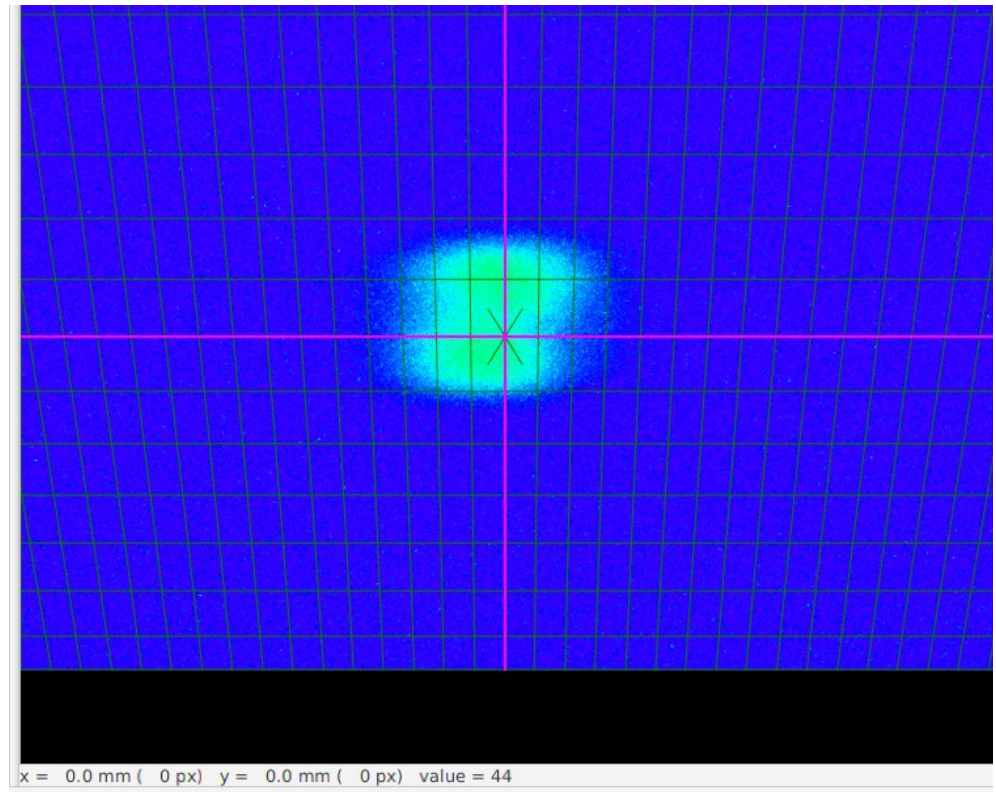
- overlay a grid showing the perspective distortion
- display pixel coordinates in SI units taking perspective into account

$$x'_p = x_p - x_{p0}$$

$$y'_p = y_p - y_{p0}$$

$$x = (s_x + \Delta s_{xx} x'_p + \Delta s_{xy} y'_p) x'_p$$

$$y = (s_y + \Delta s_{yx} x'_p + \Delta s_{yy} y'_p) y'_p$$



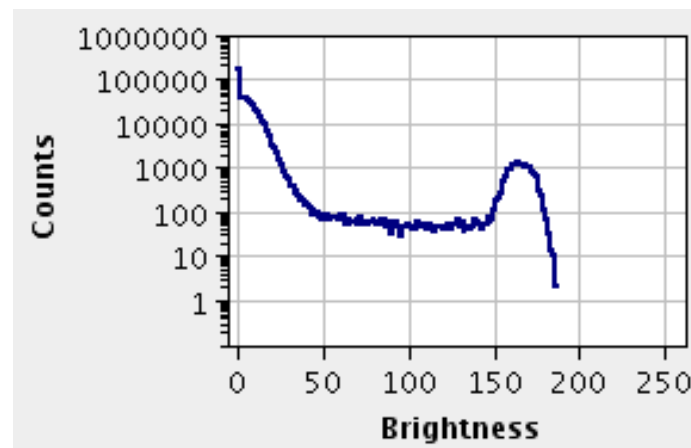
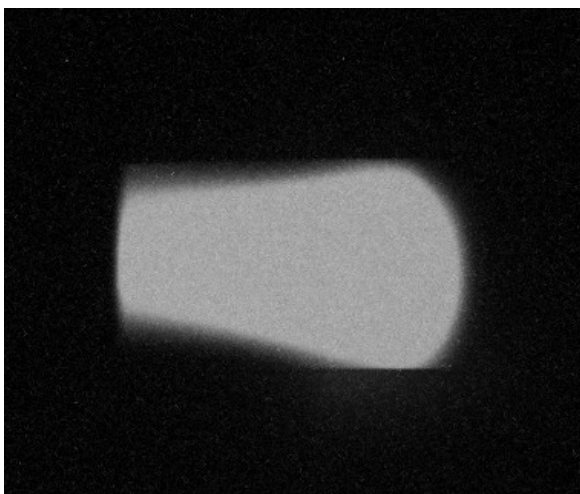
iDS Ueye

- operational: 34 cameras
- stable operation
- no degradation due to radiation visible so far
- well supported under Linux
- firmware update in situ possible



Problem (more a really not understood / further investigated observation)

- saturation with max pixel value <8bit (255) for short pulses (few μ s length)



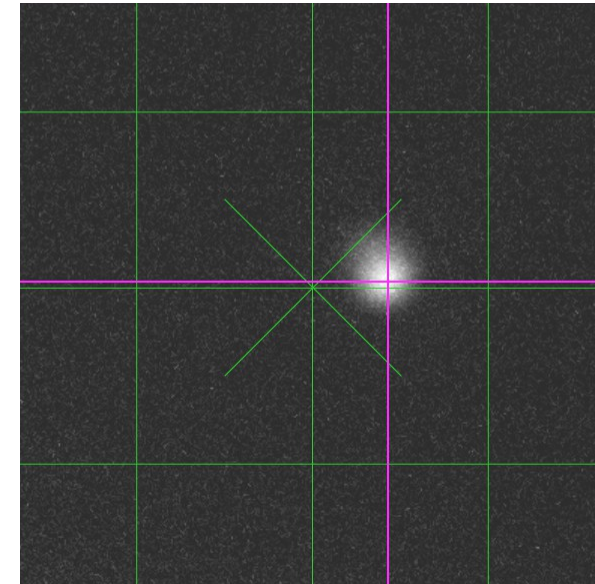
Pleora iPort Analog-Pro

- operational: 3 cameras
- well supported under Linux
- some stability problems
 - frame grabber stops sending images
 - maybe due to too many dropped packets?
 - bad μ TCA configuration?
 - frame grabber internal counter, which stops data receiver on too man packet resends?



Special thanks to...

- André Petit – PLC programming
- Rolf Lonsing – PLC and electronics
- Christian Schmidt – CPS8 controller box
- Christoph Dorn and group – mechanics
- Beata Walaseck-Höhne - Coordination



view into the Crying ion source

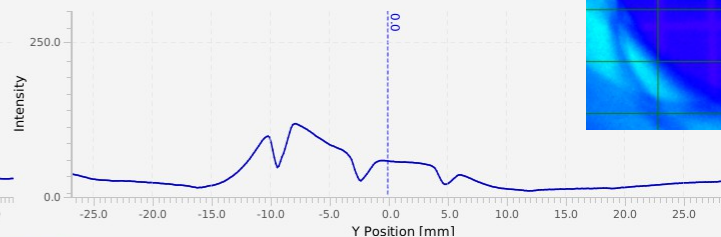
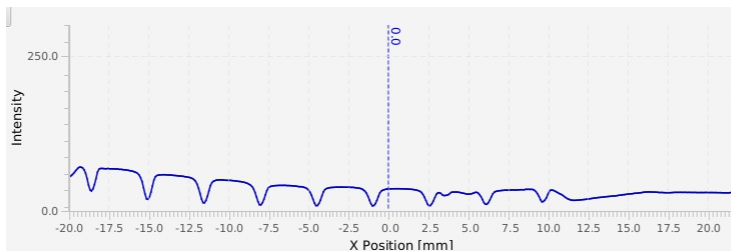
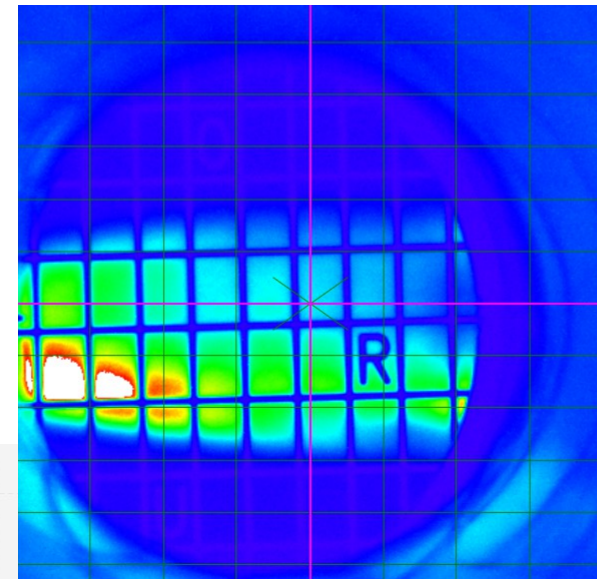
Thank You for Your Attention...

Full Width Half Maximum is calculated on the profiles

1. Simple Algorithm

- find position and value of brightest pixel
- find value of dimmest, non-zero pixel
- go to both sides of brightest pixel until value drops below half of distance between maximum value and minimum value

Fails on older scintillating screens with etched-on grid!

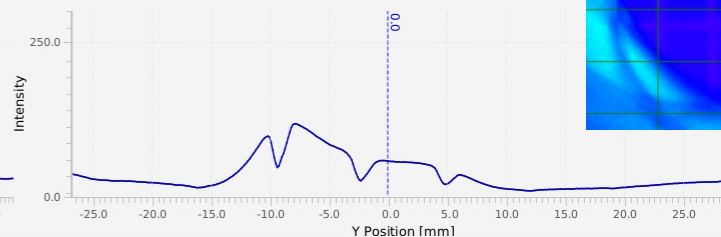
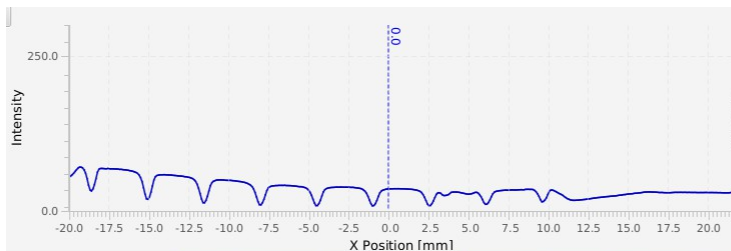
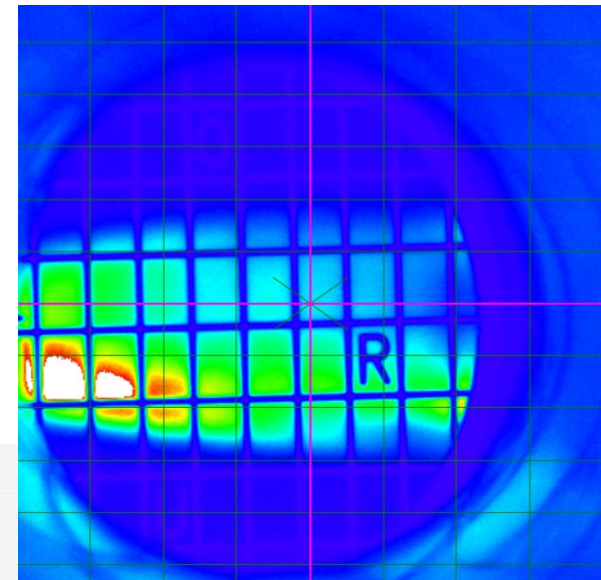


Full Width Half Maximum is calculated on the profiles

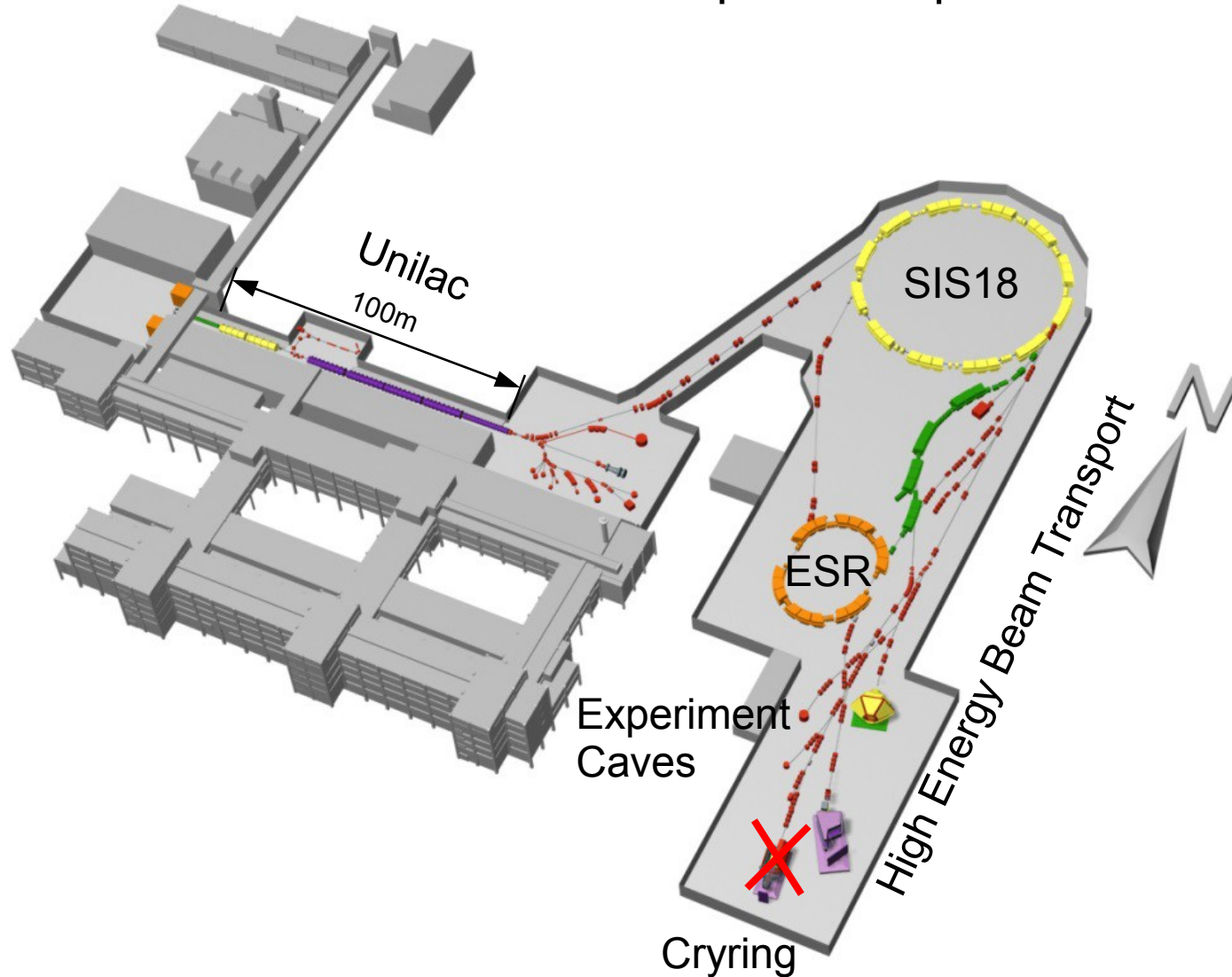
2. Standard Deviation

- find position and value of brightest pixel
- find value of dimmest, non-zero pixel
- calculate standard deviation of profile's center-of-brightness
 - use only data points with

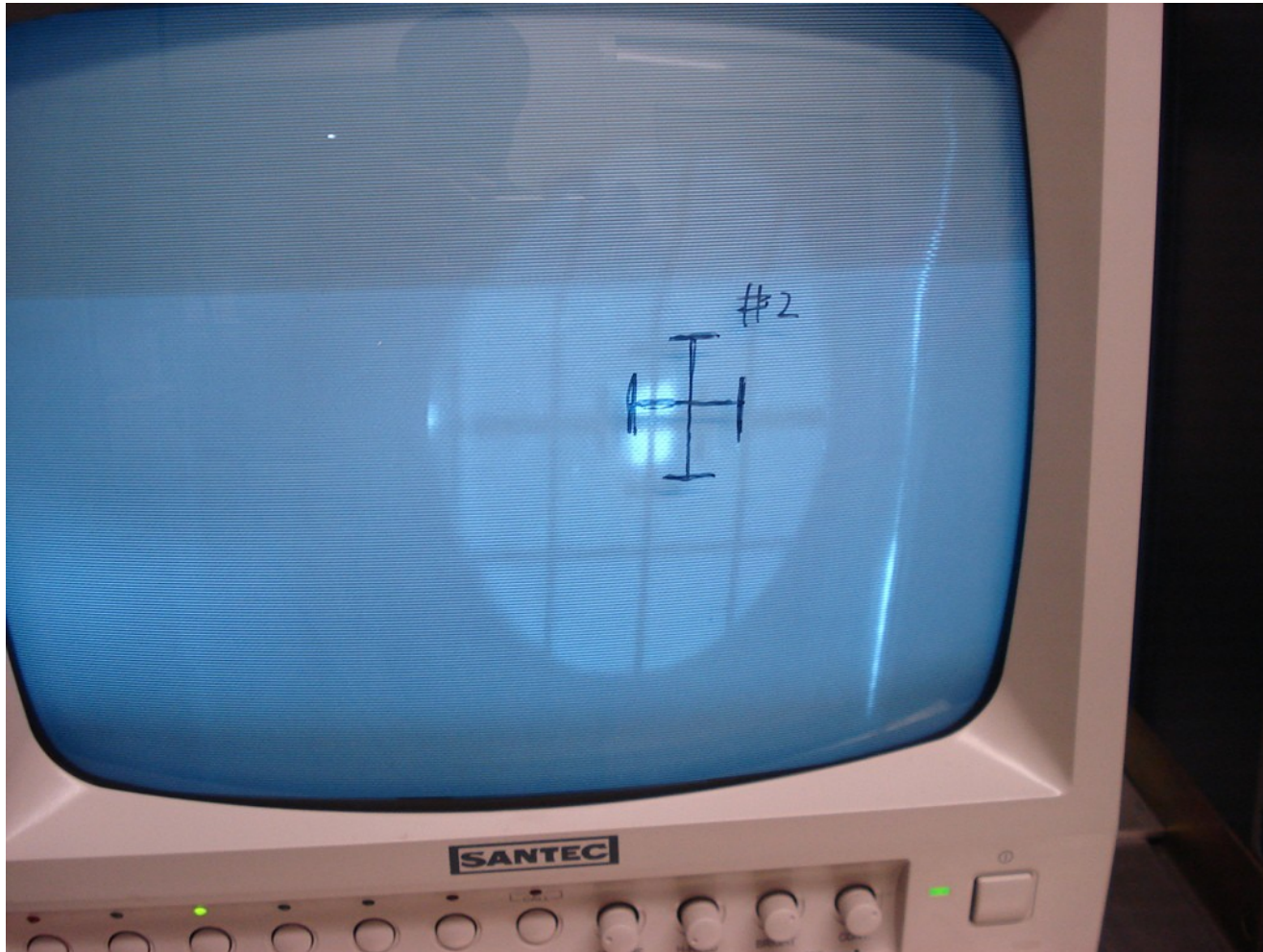
$$v > v_{min} + (v_{max} - v_{min})/4$$



GSI accelerates all ions from protons up to Uranium



Scintillating Screen Readout at GSI prior to 2013



Lots of room for improvement . . .