

# Tensor Networks

How physicists can tackle exponentially hard problems

March 4 – 7, 2019 | Patrick Emonts | Max Planck Institute of Quantum Optics



# Overview

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Introduction

Matrix Product States

iTEBD

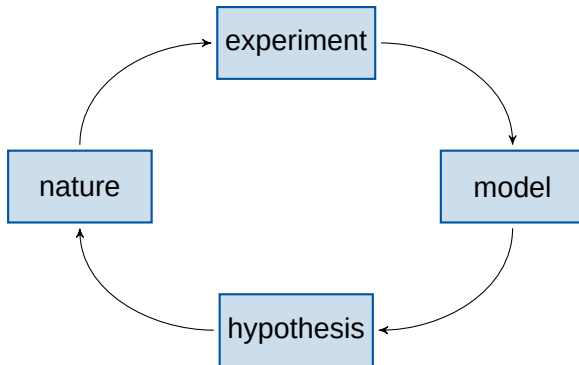
References

# Section 1

## Introduction

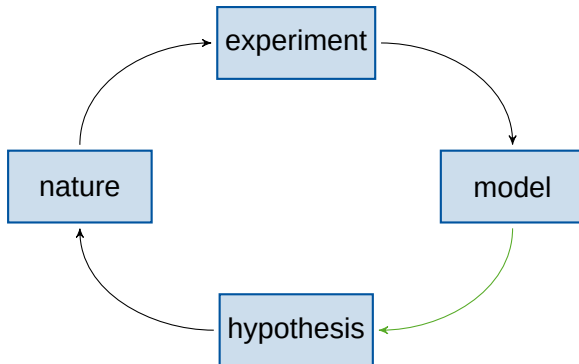
## Motivation

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## Motivation

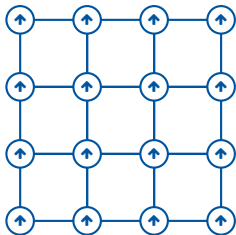
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## How complex is this problem?

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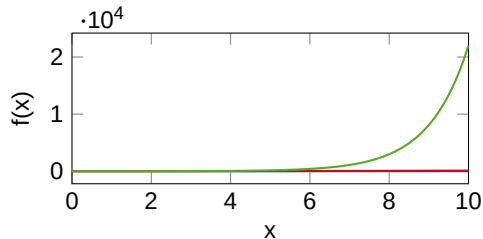
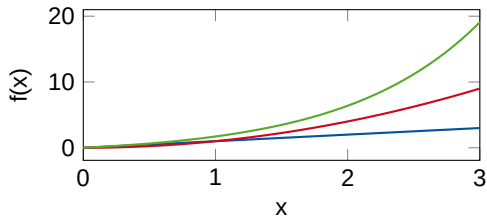
We take a system that can take two states  and 



Number of possibilities

$$Z = 2^N$$

## How bad is exponential scaling?

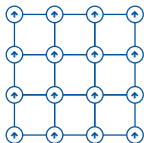


### Physical example

- $10^{23}$  Number of atoms in 12 g of carbon
- $10^{80}$  Number of atoms in the visible universe

## Quantum Mechanics in 2 slides – Slide 1

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Hilbert space  $\mathcal{H}$  vector space of all possible configurations

state  $|\psi\rangle$  vector in  $\mathcal{H}$  that describes the state of the system

Hamilton operator  $H$  Linear operator that describes the energy of the system

### Note on Notation: Bra and Ket vectors

$|\psi\rangle$  is a column vector

$$\begin{bmatrix} \psi_0 \\ \psi_1 \\ \psi_2 \end{bmatrix}$$

$\langle\psi|$  is a row vector

$$\begin{bmatrix} \bar{\psi}_0 & \bar{\psi}_1 & \bar{\psi}_2 \end{bmatrix}$$



## Quantum Mechanics in 2 slides – Slide 2

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Schrödinger equation

$$i \frac{d}{dt} |\Psi(t)\rangle = H |\Psi(t)\rangle$$

time-independent Schrödinger equation (time-ind. Hamiltonian)

$$H |\Psi\rangle = E |\Psi\rangle$$

## Quantum Mechanics in 2 slides – Slide 2

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### Schrödinger equation

$$i \frac{d}{dt} |\psi(t)\rangle = H |\psi(t)\rangle$$

### time-independent Schrödinger equation (time-ind. Hamiltonian)

$$H |\psi\rangle = E |\psi\rangle$$

### Expectation values

Probability theory

$$\langle X \rangle = P(X)X$$

Quantum mechanics

$$\langle E \rangle = \frac{\langle \psi | H | \psi \rangle}{\langle \psi | \psi \rangle}$$

## Expressing spins with matrices

### Definitions

$$|\uparrow\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$|\downarrow\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$S_z = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

### Calculating with spins

$$\begin{aligned} S_z |\uparrow\rangle &= \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \\ &= \frac{1}{2} |\uparrow\rangle \end{aligned}$$

## Combining multiple spins

Consider a system consisting of two spins that can two values (  $\downarrow$  and  $\uparrow$  )

Hilbert space  $\mathcal{H}$

$$\mathcal{H} = \text{span} \{ |\downarrow_1\rangle |\downarrow_2\rangle, |\downarrow_1\rangle |\uparrow_2\rangle, |\uparrow_1\rangle |\downarrow_2\rangle, |\uparrow_1\rangle |\uparrow_2\rangle \}$$

Spins on different sites are combined by tensor products

$$|\downarrow_1\rangle |\downarrow_2\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \otimes \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

$$|\downarrow_1\rangle |\uparrow_2\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \otimes \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

$$|\uparrow_1\rangle |\downarrow_2\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \otimes \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}$$

$$|\uparrow_1\rangle |\uparrow_2\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \otimes \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

## Letting spins interact

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### Interaction of two spins

$$H = -J (S_1^z \otimes S_2^z)$$

### Matrix representation

$$\begin{aligned} H &= -J \left( \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \right) \otimes \left( \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \right) \\ &= -\frac{J}{4} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \otimes \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = -\frac{J}{4} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \end{aligned}$$

## Calculating an expectation value

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### Preparation of a state

$$\begin{aligned} |\psi\rangle &= \sqrt{0.5} |\uparrow_1\rangle |\downarrow_2\rangle + \sqrt{0.5} |\downarrow_1\rangle |\uparrow_2\rangle \\ &= \sqrt{0.5} |\uparrow_1 \downarrow_2\rangle + \sqrt{0.5} |\downarrow_1 \uparrow_2\rangle \\ &= \sqrt{0.5} |\uparrow \downarrow\rangle + \sqrt{0.5} |\downarrow \uparrow\rangle \\ &= \begin{pmatrix} 0 \\ \sqrt{0.5} \\ \sqrt{0.5} \\ 0 \end{pmatrix} \end{aligned}$$

## Calculating an expectation value

### Preparation of a state

$$\begin{aligned} |\psi\rangle &= \sqrt{0.5} |\uparrow_1\rangle |\downarrow_2\rangle + \sqrt{0.5} |\downarrow_1\rangle |\uparrow_2\rangle \\ &= \sqrt{0.5} |\uparrow_1 \downarrow_2\rangle + \sqrt{0.5} |\downarrow_1 \uparrow_2\rangle \\ &= \sqrt{0.5} |\uparrow \downarrow\rangle + \sqrt{0.5} |\downarrow \uparrow\rangle \\ &= \begin{pmatrix} 0 \\ \sqrt{0.5} \\ \sqrt{0.5} \\ 0 \end{pmatrix} \end{aligned}$$

### Expectation value

$$\begin{aligned} \langle H \rangle &= \langle \psi | H | \psi \rangle / \langle \psi | \psi \rangle \\ &= \langle \psi | H | \psi \rangle \\ &= -\frac{J}{4} (0 \quad \sqrt{0.5} \quad \sqrt{0.5} \quad 0) \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ \sqrt{0.5} \\ \sqrt{0.5} \\ 0 \end{pmatrix} \\ &= \frac{J}{4} \end{aligned}$$

## Summary – Introduction

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### Computation

- Computational complexity of many-body systems scales exponentially with the system size
- We cannot solve those systems exactly and have to use approximate methods

### Physics

- Quantum mechanical systems evolve according to the Schrödinger equation
- We are interested in the ground-state  $|\psi\rangle$  and expectation values  $\langle E \rangle = \frac{\langle \psi | H | \psi \rangle}{\langle \psi | \psi \rangle}$



## Section 2

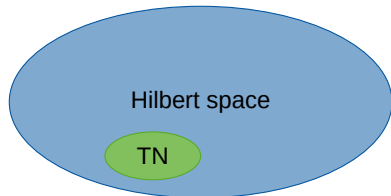
# Matrix Product States

# Tensor Networks

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## Idea

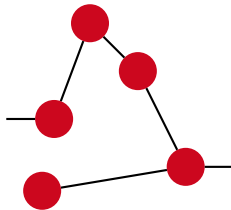
Use an Ansatz with polynomially many parameters although the Hilbert space has exponentially many states



We explore only a small part of the Hilbert space

## What is a tensor network?

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## Pictorial representation

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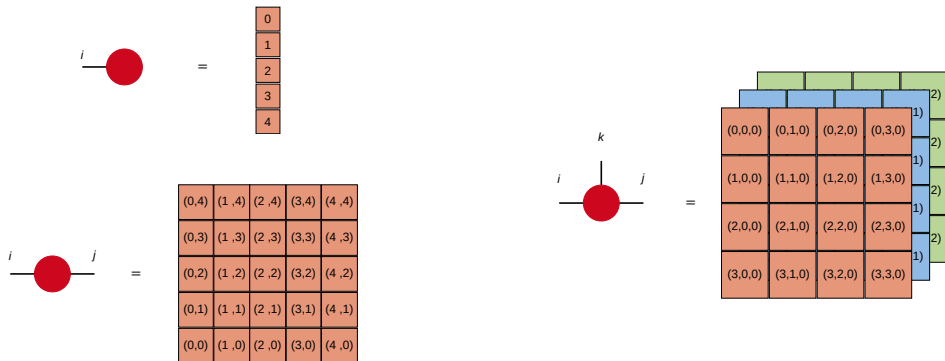
vector 

matrix 

tensor 

- The number of legs determines the number of indices of the object
- A connection  $\Leftrightarrow$  Contraction of indices

# Pictorial representation as Arrays



## Calculations with pictures

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### Matrix-Vector Multiplication

$$\mathbf{v}_i = \sum_{j} A_{ij} \mathbf{b}_j$$

$$\overset{i}{\text{---}} \text{v} = \overset{i}{\text{---}} \text{A} \overset{j}{\text{---}} \text{b}$$

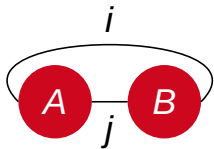
### Matrix-Matrix Multiplication

$$C_{kl} = \sum_{i} A_{ki} B_{il}$$

$$\overset{k}{\text{---}} \text{C} \overset{l}{\text{---}} = \overset{k}{\text{---}} \text{A} \overset{i}{\text{---}} \text{B} \overset{l}{\text{---}}$$

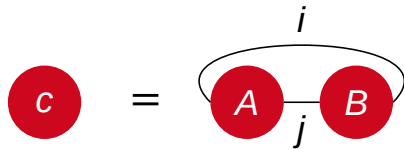
## Calculations with pictures – Quiz

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## Calculations with pictures – Quiz

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### Trace

$$\begin{aligned} c &= \sum_{i,j} A_{ij} B_{ji} \\ &= \text{Tr}[AB] \end{aligned}$$



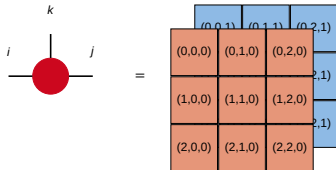
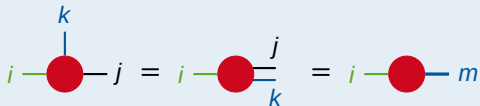
# Tensor manipulations – Grouping

## Tensor to Matrix

$$A_{i,j,k} = A_{i,(jk)}$$

$$= A_{i,m}$$

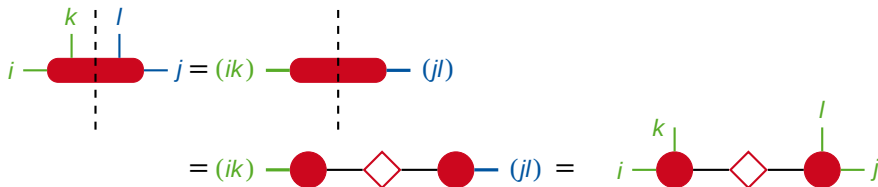
## Pictorial language



## Tensor manipulations – Splitting

### Splitting of tensor

$$A = U \cdot S \cdot V^\dagger$$



# Singular Value Decomposition

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## Singular Value Decomposition

$$M = U \cdot S \cdot V^\dagger,$$

$M$  arbitrary  $m \times n$  matrix

$U$  unitary  $m \times m$  matrix

$S$  diagonal  $m \times n$  matrix

$V$  unitary  $n \times n$  matrix

## SVD – Truncation

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Full SVD



Truncated SVD



### 💡 Note 💡

The shape of  $M$  does not change since we are only manipulating an index which we contract.

## SVD – Example

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Original Image



Truncated Image (20 SV)



## Back to formulas: What is a Tensor Network?

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A general quantum mechanical state

$$|\psi\rangle = \sum_{\sigma_1 \dots \sigma_n} c_{\sigma_1, \sigma_2, \dots, \sigma_n} |\sigma_1 \sigma_2 \dots \sigma_n\rangle$$

Example:  $|\psi\rangle = \sqrt{0.5} |\uparrow_1\rangle |\downarrow_2\rangle + \sqrt{0.5} |\downarrow_1\rangle |\uparrow_2\rangle$

$$\mathcal{H} = \text{span}\{ |\downarrow_1\rangle |\downarrow_2\rangle, \\ |\downarrow_1\rangle |\uparrow_2\rangle, \\ |\uparrow_1\rangle |\downarrow_2\rangle, \\ |\uparrow_1\rangle |\uparrow_2\rangle \}$$

$$c_{\downarrow_1, \downarrow_2} = 0$$

$$c_{\downarrow_1, \uparrow_2} = \sqrt{0.5}$$

$$c_{\uparrow_1, \downarrow_2} = \sqrt{0.5}$$

$$c_{\uparrow_1, \uparrow_2} = 0$$

## Back to formulas: What is a Tensor Network?

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A general quantum mechanical state

$$|\psi\rangle = \sum_{\sigma_1 \dots \sigma_n} c_{\sigma_1, \sigma_2 \dots \sigma_n} |\sigma_1 \sigma_2 \dots \sigma_n\rangle$$

Problem

The coefficients depend on the configuration of all spins. Thus, there are exponentially many coefficients.

## Back to formulas: What is a Tensor Network?

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### A general quantum mechanical state

$$|\psi\rangle = \sum_{\sigma_1 \dots \sigma_n} c_{\sigma_1, \sigma_2 \dots \sigma_n} |\sigma_1 \sigma_2 \dots \sigma_n\rangle$$

### Problem

The coefficients depend on the configuration of all spins. Thus, there are exponentially many coefficients.

### A fancy way to write a quantum mechanical state

$$|\psi\rangle = \sum_{\sigma_1 \dots \sigma_n} \underbrace{\sum_{a_1, \dots, a_{n-1}} A_{a_1}^{\sigma_1} A_{a_1, a_2}^{\sigma_2} \dots A_{a_{n-2}, a_{n-1}}^{\sigma_{n-1}} A_{a_{n-1}}^{\sigma_n}}_{c_{\sigma_1, \sigma_2 \dots \sigma_n}} |\sigma_1 \sigma_2 \dots \sigma_n\rangle$$



## Tensor Networks – Thinking about Indices

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### A Tensor Network State

$$|\psi\rangle = \sum_{\sigma_1 \dots \sigma_n} \sum_{a_1, \dots, a_{n-1}} A_{a_1}^{\sigma_1} A_{a_1, a_2}^{\sigma_2} \dots A_{a_{n-2}, a_{n-1}}^{\sigma_{n-1}} A_{a_{n-1}}^{\sigma_n} |\sigma_1 \sigma_2 \dots \sigma_n\rangle$$

### Dimensions of object $A$

$\sigma$ : physical index: (↑, ↓)

$$A_{a_j, a_{j+1}}^{\sigma}$$

$a$ : virtual index

Dimension of physical index

$d$  ( $\sim 10$ )

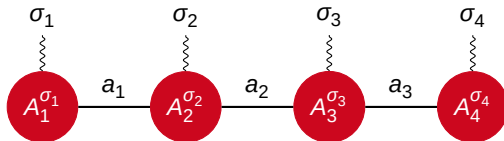
Dimension of virtual index

$D$  ( $\sim 100$ )

# Matrix Product States

## A Tensor Network State

$$|\psi\rangle = \sum_{\sigma_1 \dots \sigma_n} \sum_{a_1, \dots, a_{n-1}} A_{a_1}^{\sigma_1} A_{a_1, a_2}^{\sigma_2} \dots A_{a_{n-2}, a_{n-1}}^{\sigma_{n-1}} A_{a_{n-1}}^{\sigma_n} |\sigma_1 \sigma_2 \dots \sigma_n\rangle$$



- Dimension: 1D
- Typical quantities
  - correlations
  - expectation values of observables

## Matrix Product States – How to get the Tensors?

A general quantum mechanical state

$$|\psi\rangle = \sum_{\sigma_1 \dots \sigma_n} c_{\sigma_1, \sigma_2, \dots, \sigma_n} |\sigma_1 \sigma_2 \dots \sigma_n\rangle$$

$$c_{\sigma_1, \sigma_2, \dots, \sigma_n} = \text{[Red box with 5 wavy lines above it]}$$

Matrix Product state

$$|\psi\rangle = \sum_{\sigma_1 \dots \sigma_n} \sum_{a_1, \dots, a_{n-1}} A_{a_1}^{\sigma_1} A_{a_1, a_2}^{\sigma_2} \dots A_{a_{n-2}, a_{n-1}}^{\sigma_{n-1}} A_{a_{n-1}}^{\sigma_n} |\sigma_1 \sigma_2 \dots \sigma_n\rangle$$

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$$c_{\sigma_1, \sigma_2, \dots, \sigma_n} = \text{[Red bar with wavy lines and a dashed vertical line]}$$

Matrix Product state

$$|\psi\rangle = \sum_{\sigma_1 \dots \sigma_n} \sum_{a_1, \dots, a_{n-1}} A_{a_1}^{\sigma_1} A_{a_1, a_2}^{\sigma_2} \dots A_{a_{n-2}, a_{n-1}}^{\sigma_{n-1}} A_{a_{n-1}}^{\sigma_n} |\sigma_1 \sigma_2 \dots \sigma_n\rangle$$

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$$c_{\sigma_1, \sigma_2, \dots, \sigma_n} = \text{Diagram}$$

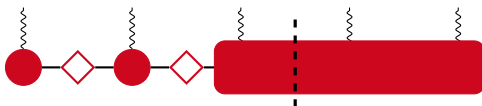
Matrix Product state

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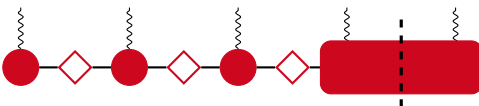
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Matrix Product state

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Matrix Product state

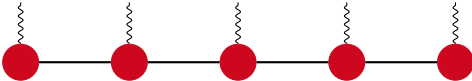
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## Matrix Product States – How to get the Tensors?

A general quantum mechanical state

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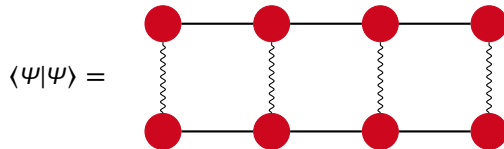
$$c_{\sigma_1, \sigma_2, \dots, \sigma_n} =$$


Matrix Product state

$$|\psi\rangle = \sum_{\sigma_1 \dots \sigma_n} \sum_{a_1, \dots, a_{n-1}} A_{a_1}^{\sigma_1} A_{a_1, a_2}^{\sigma_2} \dots A_{a_{n-2}, a_{n-1}}^{\sigma_{n-1}} A_{a_{n-1}}^{\sigma_n} |\sigma_1 \sigma_2 \dots \sigma_n\rangle$$

## Matrix Product States – Bra, Ket and Norms

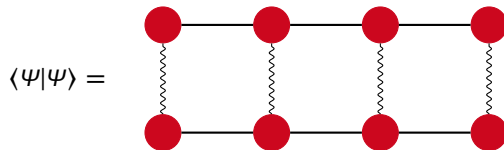
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## Matrix Product States – Why contraction order matters!

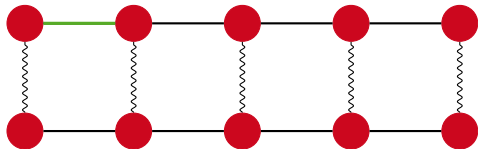
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Different contraction orders yield different contraction complexities



## Matrix Product States – Why contraction order matters!

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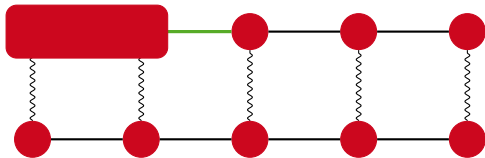


### Number of operations

- $\mathcal{O}(D^2d^2)$

## Matrix Product States – Why contraction order matters!

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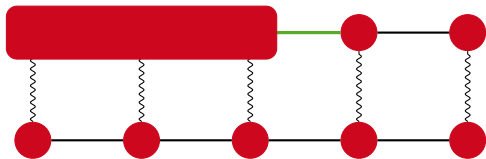


### Number of operations

- $\mathcal{O}(D^2d^2)$
- $\mathcal{O}(D^2d^3)$

## Matrix Product States – Why contraction order matters!

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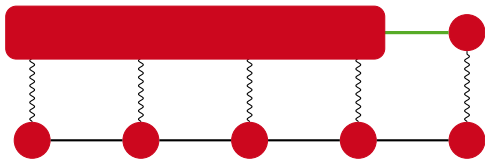


### Number of operations

- $\mathcal{O}(D^2d^2)$
- $\mathcal{O}(D^2d^3)$
- $\mathcal{O}(D^2d^4)$

## Matrix Product States – Why contraction order matters!

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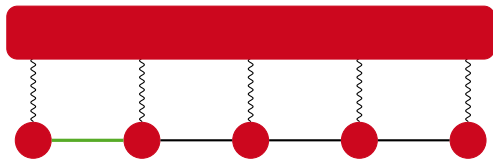


### Number of operations

- $\mathcal{O}(D^2d^2)$
- $\mathcal{O}(D^2d^3)$
- $\mathcal{O}(D^2d^4)$
- $\mathcal{O}(Dd^5)$

## Matrix Product States – Why contraction order matters!

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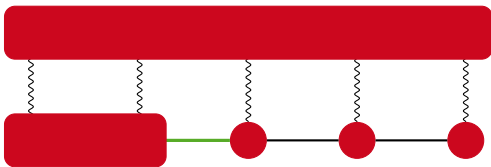
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## Matrix Product States – Why contraction order matters!

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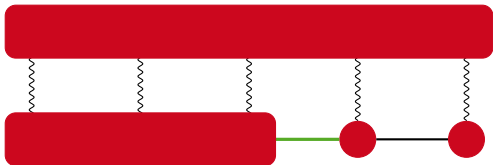


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## Matrix Product States – Why contraction order matters!

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- $\mathcal{O}(D^2d^4)$
- $\mathcal{O}(Dd^5)$
- $\mathcal{O}(D^2d^2)$
- $\mathcal{O}(D^2d^3)$
- $\mathcal{O}(D^2d^4)$
- $\mathcal{O}(Dd^5)$
- $\mathcal{O}(d^6)$

## Matrix Product States – Why contraction order matters!

---



### Number of operations

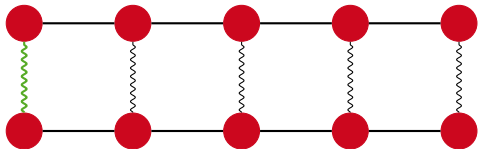
- $\mathcal{O}(D^2d^2)$
- $\mathcal{O}(D^2d^3)$
- $\mathcal{O}(D^2d^4)$
- $\mathcal{O}(Dd^5)$
- $\mathcal{O}(D^2d^2)$
- $\mathcal{O}(D^2d^3)$
- $\mathcal{O}(D^2d^4)$
- $\mathcal{O}(Dd^5)$
- $\mathcal{O}(d^6)$

**! Don't try this at home !**

The number of matrix elements needed scales exponentially with the number of sites  $N$ .

## Matrix Product States – Why contraction order matters!

---

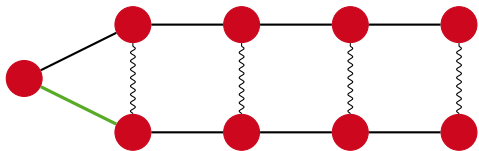


### Number of operations

- $\mathcal{O}(D^2d)$

## Matrix Product States – Why contraction order matters!

---

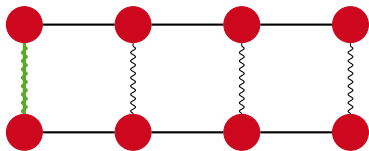


### Number of operations

- $\mathcal{O}(D^2d)$
- $\mathcal{O}(D^3d)$

## Matrix Product States – Why contraction order matters!

---



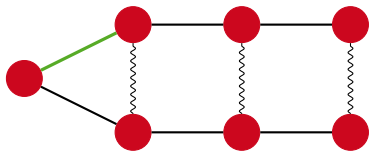
### Number of operations

- $\mathcal{O}(D^2d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$



## Matrix Product States – Why contraction order matters!

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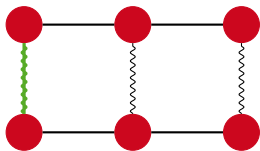


### Number of operations

- $\mathcal{O}(D^2d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$

## Matrix Product States – Why contraction order matters!

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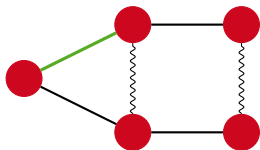


### Number of operations

- $\mathcal{O}(D^2d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$

## Matrix Product States – Why contraction order matters!

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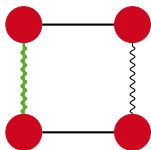


### Number of operations

- $\mathcal{O}(D^2d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$

## Matrix Product States – Why contraction order matters!

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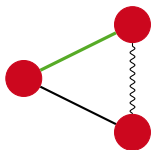


### Number of operations

- $\mathcal{O}(D^2d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$

## Matrix Product States – Why contraction order matters!

---



### Number of operations

- $\mathcal{O}(D^2d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^2d)$

## Matrix Product States – Why contraction order matters!

---



### Number of operations

- $\mathcal{O}(D^2d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^2d)$
- $\mathcal{O}(Dd)$

## Matrix Product States – Why contraction order matters!

---



### Number of operations

- $\mathcal{O}(D^2d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^3d)$
- $\mathcal{O}(D^2d)$
- $\mathcal{O}(Dd)$

### Complexity

The number of matrix elements does not depend on the number of sites  $N$  at all and the procedure scales linearly in time with  $N$ .

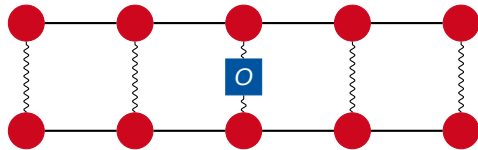
## Matrix Product States – Calculation of an expectation value

### Expectation values

$$\langle O \rangle = \frac{\langle \psi | O | \psi \rangle}{\langle \psi | \psi \rangle}$$

$$\langle O_i \rangle = \frac{\langle \psi | O_i | \psi \rangle}{\langle \psi | \psi \rangle}$$

$$\langle \psi | O | \psi \rangle =$$

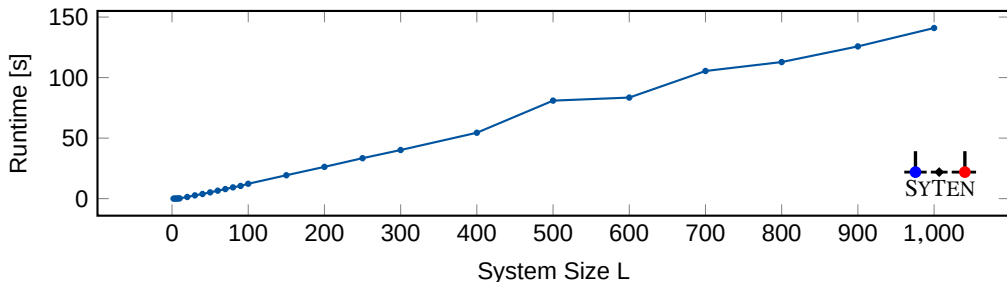




## Example – DMRG calculation

### Spin 1 Heisenberg chain

$$H = \sum_i S_i^x S_{i+1}^x + S_i^y S_{i+1}^y + S_i^z S_{i+1}^z$$



Data provided by Claudius Hubig, MPQ

## Summary – MPS

---

- MPS is an Ansatz to describe many-body states with polynomially many parameters
- The pictorial description simplifies the formulation of calculations and algorithms
- We have to be careful about the order of contractions

## Section 3

### iTEBD

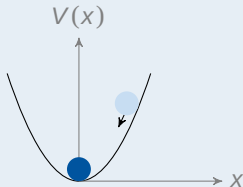
# Minimization of energy

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## Goal

Find the groundstate of a Hamiltonian  $H$ , i.e. find the state with the smallest energy eigenvalue.

## Classical mechanics



## Quantum mechanics

Find  $|\psi_{\min}\rangle$  such that

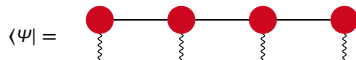
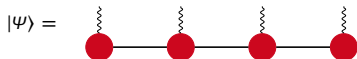
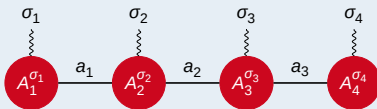
$$E_{\min} = \frac{\langle \psi_{\min} | H | \psi_{\min} \rangle}{\langle \psi_{\min} | \psi_{\min} \rangle}$$

is minimal.

## Reminder – Tensor network notation

### A Tensor Network State

$$|\psi\rangle = \sum_{\sigma_1 \dots \sigma_n} \sum_{a_1, \dots, a_{n-1}} A_{a_1}^{\sigma_1} A_{a_1, a_2}^{\sigma_2} \dots A_{a_{n-2}, a_{n-1}}^{\sigma_{n-1}} A_{a_{n-1}}^{\sigma_n} |\sigma_1 \sigma_2 \dots \sigma_n\rangle$$



## Reminder – Calculation of energies

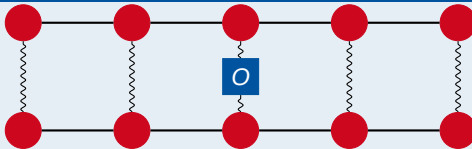
---

### Expectation value

$$\langle E \rangle = \frac{\langle \Psi | H | \Psi \rangle}{\langle \Psi | \Psi \rangle}$$

### Calculation of an observable

$$\langle \Psi | O | \Psi \rangle =$$



# Energy minimization via imaginary time evolution

---

## Motivation

The ground state is the state with the smallest energy. All other states are suppressed more quickly by an exponential.

## Time evolution in imaginary time

$$\begin{aligned} |\psi_0\rangle &= \lim_{\delta \rightarrow \infty} \frac{\exp(-H\delta) |\psi\rangle}{\|\exp(-H\delta) |\psi\rangle\|} \\ &= \lim_{\delta \rightarrow \infty} \frac{U(\delta) |\psi\rangle}{\|U(\delta) |\psi\rangle\|} \end{aligned}$$

## Trotterization of an operator

---

### Evolution operator

$$U(\delta) = e^{-\delta H}$$

### Ising Model

$$H = \sum_i S_i^z S_{i+1}^z = \sum_i h_{i,i+1}$$



$$H_{\text{even}} = \sum_{i \text{ even}} h_{i,i+1}$$

$$H_{\text{odd}} = \sum_{i \text{ odd}} h_{i,i+1}$$



## Trotterization of an operator

---

### Evolution operator

$$U(\delta) = e^{-\delta H}$$

### Ising Model

$$H = \sum_i S_i^z S_{i+1}^z = \sum_i h_{i,i+1}$$



$$H_{\text{even}} = \sum_{i \text{ even}} h_{i,i+1}$$

$$H_{\text{odd}} = \sum_{i \text{ odd}} h_{i,i+1}$$

$$H = H_{\text{even}} + H_{\text{odd}}$$

# Trotterization of an operator

---

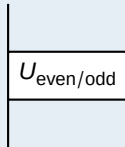
## Evolution operator

$$U(\delta) = e^{-\delta H}$$

## Trotterization of an operator

$$\begin{aligned} U(\delta) &= e^{-\delta H} \\ &= e^{-\delta H_{\text{even}}} e^{-\delta H_{\text{odd}}} e^{-\delta^2 [H_{\text{even}}, H_{\text{odd}}]} \\ &\approx e^{-\delta H_{\text{even}}} e^{-\delta H_{\text{odd}}} \end{aligned}$$

## Pictorial representation



## Making life easy: infinite systems

---

### General MPS



### Translationally invariant MPS



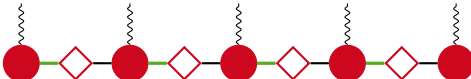
## Back to the start: An MPS with diagonal matrices

---

We started with

$$C_{\sigma_1, \sigma_2, \dots, \sigma_N} = \text{[Red Bar]}$$


and got

$$C_{\sigma_1, \sigma_2, \dots, \sigma_N} = \text{[MPS Diagram]}$$


## The iTEBD algorithm

---

We start with an infinite system that consists of two sites A and B



### Disclaimer

This algorithm is proven to be numerically unstable. You should NOT use it in research, it is shown here due to its simplicity.

## The iTEBD algorithm

---

We start with an infinite system that consists of two sites A and B



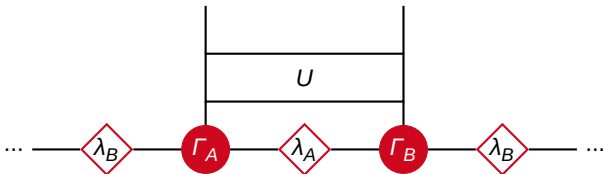
### Disclaimer

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## The iTEBD algorithm

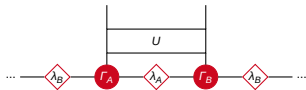
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- Apply the operator  $U$  to sites A and B

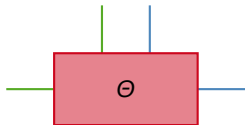


# The iTEBD algorithm

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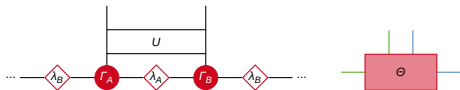
- Apply the operator  $U$  to sites A and B
- Contract all indices and group indices (blue and green)





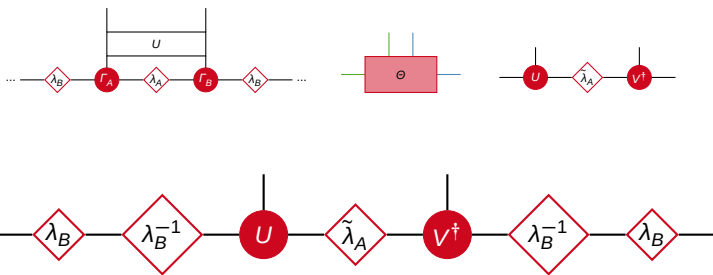
# The iTEBD algorithm

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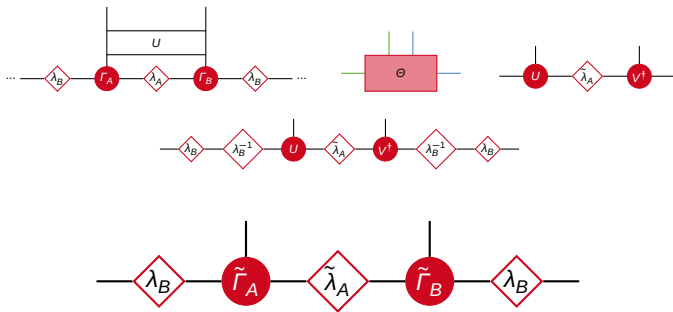
- Apply the operator  $U$  to sites A and B
- Contract all indices and group indices (blue and green)
- Compute SVD of the tensor

# The iTEBD algorithm



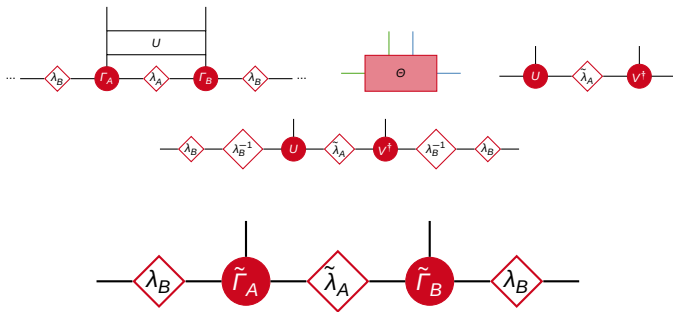
- Apply the operator  $U$  to sites A and B
- Contract all indices and group indices (blue and green)
- Compute SVD of the tensor
- Reintroduce  $\lambda_B$

# The iTEBD algorithm



- Apply the operator  $U$  to sites A and B
- Contract all indices and group indices (blue and green)
- Compute SVD of the tensor
- Reintroduce  $\lambda_B$
- Update  $\Gamma_A$  and  $\Gamma_B$

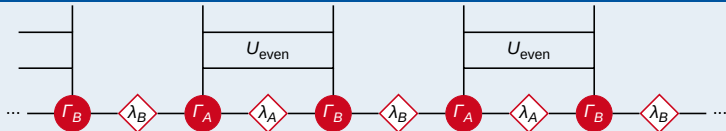
# The iTEBD algorithm



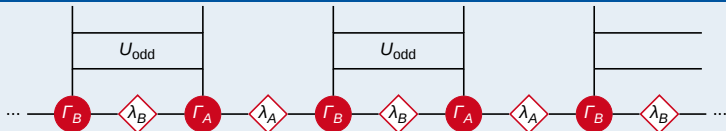
- Apply the operator  $U$  to sites A and B
- Contract all indices and group indices (blue and green)
- Compute SVD of the tensor
- Reintroduce  $\lambda_B$
- Update  $\Gamma_A$  and  $\Gamma_B$
- Repeat the procedure with the sites B and A

## Application on odd an even sites

### Application to even sites



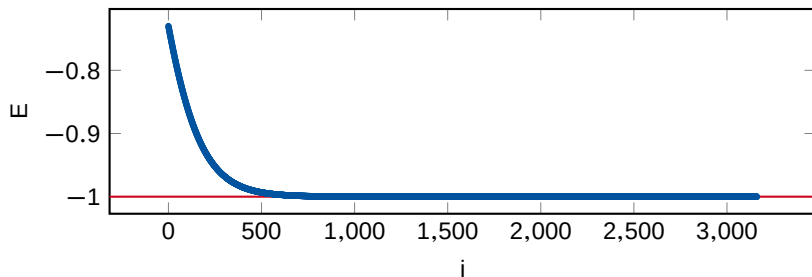
### Application to odd sites



## Results for an Ising spin system

### Ising Model

$$H = \sum_i S_i^z S_{i+1}^z = \sum_i h_{i,i+1}$$



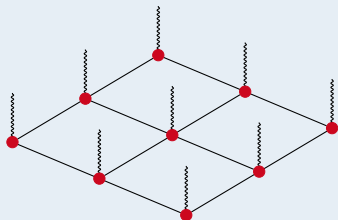
### Parameters

- $D = 1$
- $\delta = 0.001$

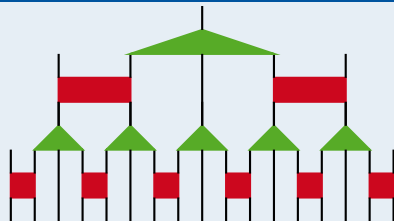
# Outlook

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## PEPS



## MERA



# Tensor Networks

How physicists can tackle exponentially hard problems

March 4 – 7, 2019 | Patrick Emonts | Max Planck Institute of Quantum Optics





## Section 4

## References

## References I

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