Silicon Strip Sensor Simulation in the CMS Monte Carlo Framework



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Outline

- Overview of the CMS tracker simulation
- Overview of recent activities
- Cross-talk measurement
- Front-end electronic pulse shape
- S/N trend
- Dead time & inefficiencies
- Hit resolution

Overview of the CMS strip simulation



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Overview of the CMS strip simulation



Recent activities on the CMS strip simulation



DB Offline DB conditions have been updated in 2018

Cross-talk parameters have been updated APV shape change under validation

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"Cross-talk" measurement

Mainly due to interstrip capacitive coupling, a cross-talk induces signals on strip neighbors to the one under which a particle went through

Example of a « one strip » cluster :



- Measurements obtained from cosmics data with 0 T using DAQ in Virgin Raw mode (no zero suppression)
 - \rightarrow Lorentz Angle null
 - \rightarrow Remove threshold bias
- Methodology:
 - Selection of tracks perpendicular to the sensor
 - Correction for timing delays
 - Fit of the leading strip charge and its neighbors.

$$\eta_i \equiv rac{q_{\pm i}}{q_{seed}} = rac{x_i}{(1-2x_1-2x_2)}
onumber \ x_i = rac{\eta_i}{1+2\eta_1+2\eta_2}$$

"Cross-talk" measurement



Radius

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Front-end electronics pulse shape



The amplitude of the charge measured at a given bunch crossing in a FE channel depends on

- The time-of-flight on the incoming particle
- The OOT contributions from other BX

→ To reflect this behaviour, it is required to inject the knowledge on the timing response of the FE electronics

Front-end electronics (APV) pulse shape

Physical signal

→ Can be estimated through external dedicated program

Electronic response

 \rightarrow Is measured with dedicated runs where a charge is locally injected on the FE chip



Motivation for an update:

- \rightarrow Use a more realistic physic signal
- → As the FE preamplifier parameters have been changed in 2016, the electronic response has been modified
- Tails of the cluster charge and cluster width distributions contributions are sensitive to the FE pulse shape description
- Required for a good modelling of the OOT contributions

Evolution of S/N during Run II



- Noise is regularly monitored and updated thanks to dedicated runs
- Noise in MC has been updated to reflect detector changes
- S/N ratio is regularly monitored (within LHC fill, ...)

- Fit the S/N distribution with a convolution of *Laudau & Gaussian* functions
- MPV is reported
- Results obtained with FE chips (APVs) working in *deconvolution* mode (weighted average of 3 consecutive samplings)

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Evolution of S/N during Run II



Dead time & inefficiencies

- Nuclear interactions can induce « **Heavy Ionizing Particle** » events where a charge deposit much larger than MIPs (10-1000x) can **saturate the electronics** and induce a **dead time**.
- HIP probability has been measured in the Tracker (per interaction and per unit of volumn).
- HIP events are responsable for the small **hit inefficiency** (<2%) that has been independently measured as function of pile-up (or luminosity).



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Dead time & inefficiencies



- HIP effects were known and studied prior to data-taking
- The current simulation framework include the possibility to introduce inefficiencies
- Ongoing work done to include our current knowledge of the inefficiencies in the simulation

Hit resolution

The hit resolution achieved is better that pitch/ $\sqrt{12}$ thanks to the charge sharing and the barycenter algorithm



The hit resolution remains almost unchanged since the beginning of Run I

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Conclusions

- The CMS tracker simulation structure remained almost unchanged since Run I
- □ In general, the data/MC agreements are good and sufficient to describe properly downstream quantities (tracking, …)
- Nevertheless, efforts were done during Run II to further improve our simulation and updates were done through:
 - DB conditions (noise, gain)
 - Parameters (cross-talk, APV pulse shape)
- Radiation damage effects injected in the simulation are thus
 - □ Gain (optical chain) \rightarrow decreased
 - □ Noise → increased
- Dead time & inefficiencies
 - Measurements have been done
 - We expect to inject that knowledge in the simulation soon

□ Hit resolution almost unchanged since the beginning of Run I



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Hit resolution



The resolution is measured as function of the predicted cluster width which depends on the trajectory

 $\frac{thickness}{pitch} |\tan\theta\cos\phi + \tan\theta_L|$

- In the reconstruction, we need to inject a « Cluster Position Error » (CPE).
- Parametrization have been made separately for small and large width clusters.
- For cluster with less than 5 strips, the CPE depends on the predicted cluster width.
- Hit resolution measurements validate this parametrization.