



Amendment to HL-LHC circuits specifications

D. Gamba, S. Kostoglou, J. Coello De Portugal, R. De Maria,
M. Giovannozzi, R. Tomas Garcia, M. Cerqueira Bastos, M. Martino

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Requests and References

- **Requests** from WP6b:
 - Verify **new PC specifications**.
 - Can the HL-LHC **120A PCs** be classified as **class 4 (instead of 3)**, as the LHC ones?
 - Can the HL-LHC **RQSX** circuits be powered by a **600A PC**?
 - **instead of 200A** -> i.e. 3 times more “noisy”
 - Can the HL-LHC **RTB8** circuit be powered by a **600A PC**?
 - **instead of 300A** -> i.e. 2 times more “noisy”
 - Do we need to create a **new class “1-2”** for HL-LHC 2kA?
 - Can we **replace “remote” by “on request” PC calibrations**?
- **Additional questions** within WP2:
 - What is the **maximum separation collapse speed** we can achieve?
- **References:**
 - **WP2** original document [CERN-ACC-2017-0101](#)
 - New specifications by **EPC**: EDMS [#2048827](#)
 - **Amendment** on Overleaf (read-only) [link](#)

New specifications (w.r.t. old ones)

Optimistic value could be **0.12**

!!! preliminary – Dec2018 !!!

New class

PC class:	0 ^a	1 ^a	1-2	2	3	4
Setting resolution [ppm]	0.5	0.5	0.5	1	1	1
Initial uncertainty after cal. [2×r.m.s. ppm]	2	2	2	5 (3)	10 (7)	20 (10)
Linearity [. max ppm]	2	2	2	5	10 (8)	10 (9)
Stability during a fill (12 h) [+ max (2×r.m.s.) ppm]	1	2	7	5 (15.5)	5 (34)	20 (40)
Short term stability (20 min) [2×r.m.s. ppm]	0.2	0.4	0.3	1 (1.2)	2	5
Noise (0.1-500 Hz) [2×r.m.s. ppm]	3	5	4	10 (7)	15	25 (19)
Fill-to-fill repeatability [2×r.m.s. ppm]	0.5 (0.7)	1 (1.6)	7	2 (14.5)	5 (32)	10 (38)
Long term fill-to-fill stability [+ max (2×r.m.s.) ppm]	10 (9.5)	10 (9.5)	11.5	20 (26.5)	50 (56)	100 (64)

- Take into account **better estimate of ambient temperature** variation at the location where PC are typically installed
- All values (but “Noise”) are for $f < 0.1$ Hz.
 - At higher frequency the PC works in voltage-regulation.
 - Assumption:** the effective (e.g. dumped by inductance etc.) **B field jitter** due to voltage ripple at any frequency is \ll **current jitter at low f** .
 - ...still one should be **careful to resonances**...
- Introduced a new possible **PC class (1-2)**
 - Is a class 2 PC with a different ADC module.
 - Significant additional cost** (about 200 kCHF more in total) if we “buy” it!

Main parameters for each (main) circuit

Before given as I_{max}

Circuit name	I_{rated} [A]	PC class	Short term stability [ppm $2 \times$ r.m.s.]	Stability during a fill (12 h) [ppm $2 \times$ r.m.s.]	Long term fill-to-fill stability [ppm $2 \times$ r.m.s.]
RB ^a	13000	1	0.4	2	10 (9.5)
RQ(D/F) ^a	13000	1	0.4	2	10 (9.5)
RQX	18000	0	0.2	1	10 (9.5)
RTQX1	2000	2	1 (1.2)	5 (15.5)	20 (26.5)
RTQXA1 ^b	120 (60)	4	5	20 (40)	100 (64)
RTQX3	2000	2	1 (1.2)	5 (15.5)	20 (26.5)
RCBX	2000	2	1 (1.2)	5 (15.5)	20 (26.5)
RQSX ^d	200 (600)	3	2	5 (34)	50 (56)
RC(S/O)X	120	3 (4)	2 (5)	5 (40)	50 (64)
RC(D/T)X	120	3 (4)	2 (5)	5 (40)	50 (64)
RD(1/2)	13000	0	0.2	1	10 (9.5)
RCBRD	600	3	2	5 (34)	50 (56)
RQ(4/5) ^a	6000	2	1 (1.2)	5 (15.5)	20 (26.5)
RCBY ^a	120	4	5	20 (40)	100 (64)
RQ6 ^a	6000	2	1 (1.2)	5 (15.5)	20 (26.5)
RCBC ^a	120	4	5	20 (40)	100 (64)
RTB8 ^c	300 (600)	3	2	5 (34)	50 (56)

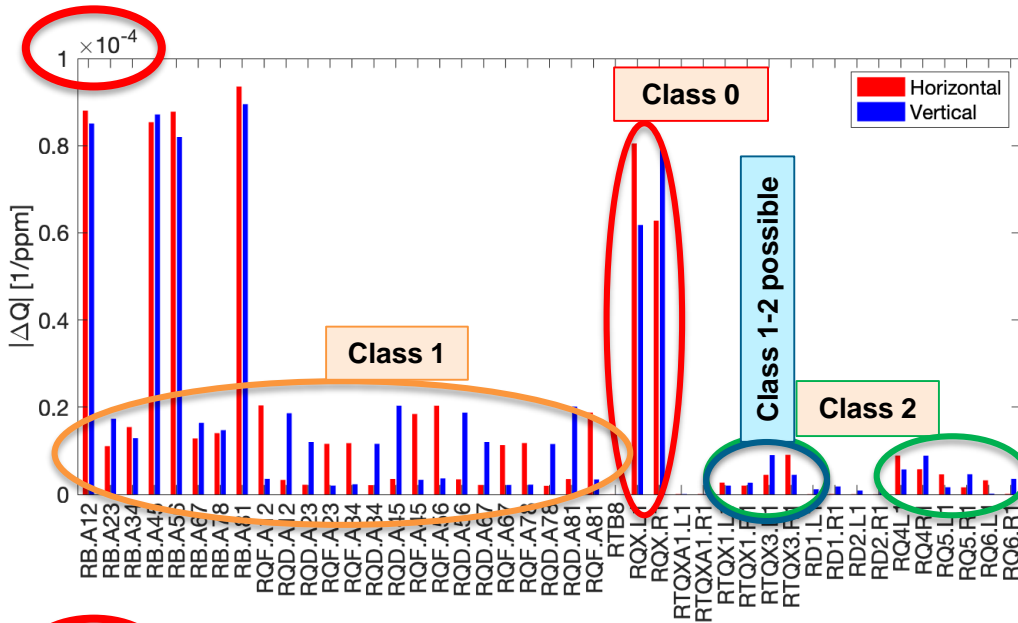
^a Existing circuit assumed not to be upgraded.

^b The rated current for this circuit has not been defined yet. The proposed value is compatible with the use of the trim as $I_{max} = 35$ A in operation.

^c A standard 600 A PC of class 3 is assumed even though $I_{max} = 250$ A in operation.

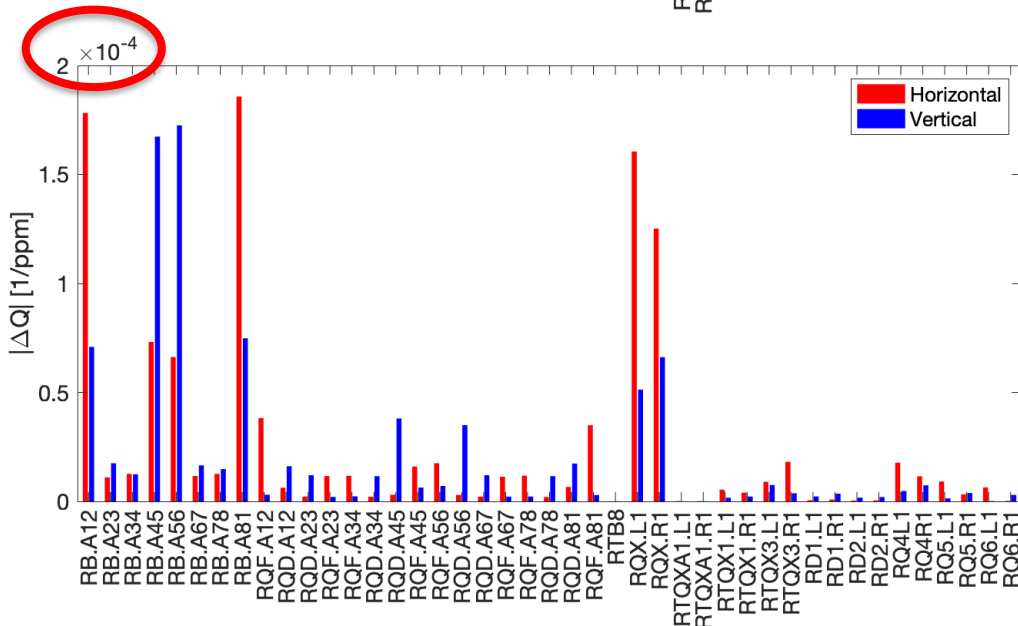
^d A standard 600 A PC of class 3 is assumed even though $I_{max} = 200$ A in operation.

Optics sensitivity: impact on tune



HL-LHC 1.3 **baseline** optics
Beta* = 15cm

- “ATS” arcs as important as triplet in IR1/5
- Already presented in previous WP2 meetings ([99th](#)) and [CERN-ACC-2017-0101](#)



HL-LHC 1.3 **flat** optics
Beta* = 7.5-18cm

- Checking if flat optics (not baseline) are more demanding.
- Clearly asymmetric due to asymmetric betas
 - (IR5 H = IR1 V and vice versa)

Expected tune stability

- Old specifications vs. new specifications (15cm beta)

Class 1-2 on new 2kA PCs

	Tune jitter [10^{-5} r.m.s.]					
	20min.		12h fill		Long term	
	Old	New	Old	New	Old	New
x	4.1 (2.8 ⁺)	4.2 (2.9 ⁺ 4.1*)	23.9	26.6 (24.4*)	138	116 (114*)
y	4.1 (2.8 ⁺)	4.1 (2.9 ⁺ 4.0*)	23.4	26.3 (24.2*)	135	113 (112*)
Target	< 1		n.a.		n.a.	

⁺ Assuming to upgrade arc dipoles in sectors 8-1, 1-2, 4-5, 5-6 to class 0.

* Assuming to use Class 0 on ATS arc dipoles, QX3 and RCBX circuits.

Class 0 on ATS arc dipoles

- New specifications. Round (15 cm) vs Flat (7.5-18cm)

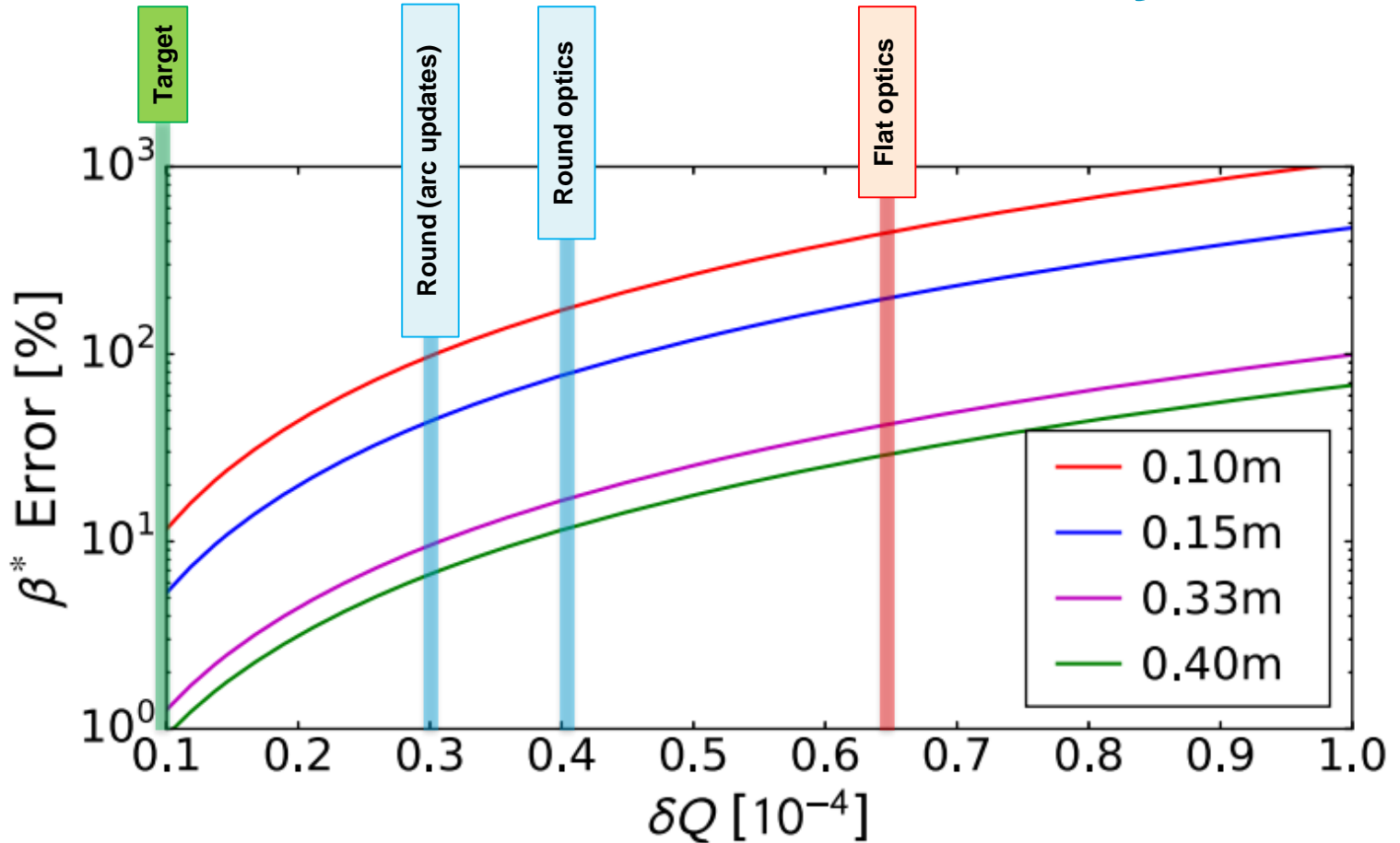
	Tune jitter [10^{-5} r.m.s.]					
	20min.		12h fill		Long term	
	15 cm	7.5 cm	15 cm	7.5 cm	15 cm	7.5 cm
x	4.2 (2.9 ⁺)	6.4 (4.3 ⁺)	26.6	40.7	116	177
y	4.1 (2.9 ⁺)	6.3 (4.2 ⁺)	26.3	39.9	113	172
Target	< 1		n.a.		n.a.	

⁺ Assuming to upgrade arc dipoles in sectors 8-1, 1-2, 4-5, 5-6 to class 0.

"Far" from target...

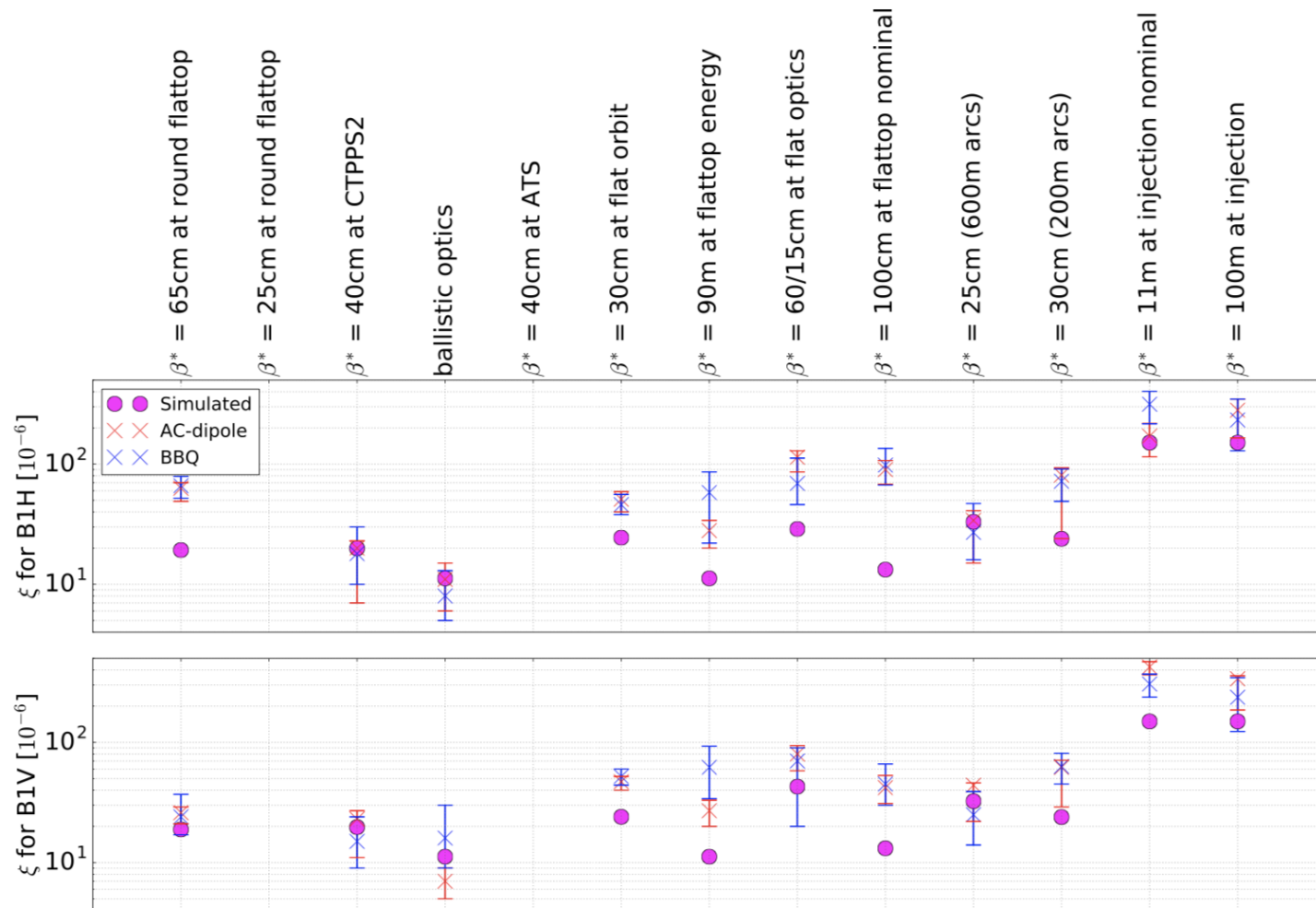
Order 10^{-3} over one year

Reminder: β^* vs tune stability



- **The smaller β^* the more difficult** to measure/correct the optics
 - => danger for luminosity reach/imbalance.
 - Smaller β^* only toward the end of the fill with β^* levelling.

LHC experience: how far are we from PC noise limit?

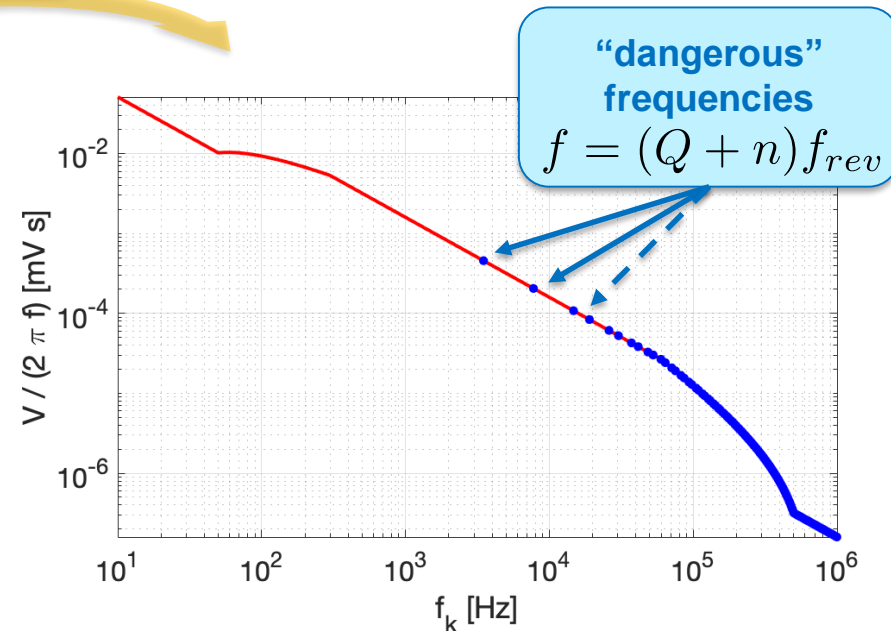
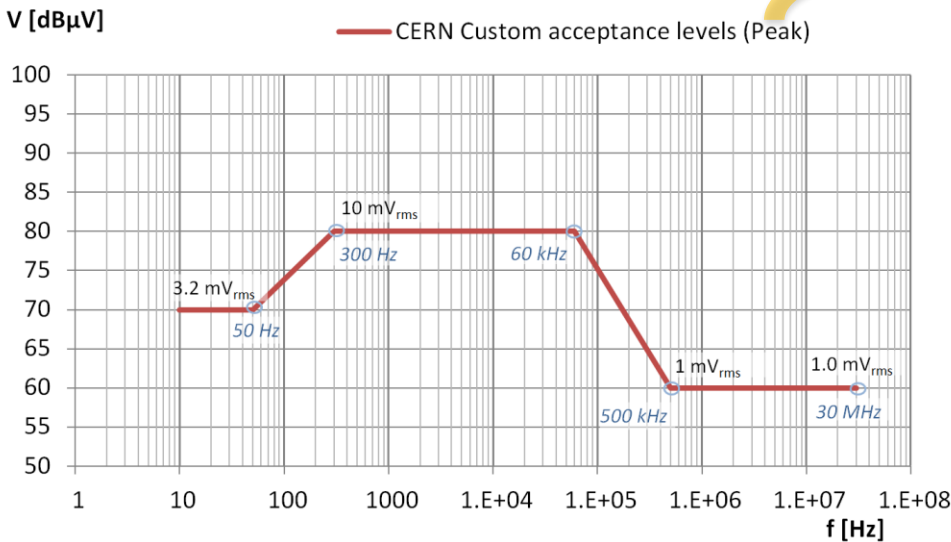


- Simulations seems to be consistent with observed tune jitter.

Observation: voltage ripple

$$\frac{dB(f)}{B_{nom}} = \begin{cases} \frac{dI(f)}{I_{nom}} & \text{for } f \leq f_0 \\ T_{Vacuum}(f) \times T_{VtoB}(f) & \text{for } f > f_0 \end{cases}$$

with: $T_{VtoB}(f) = T''_{VtoB}(f) \times \frac{dV(f)}{2\pi f L_{DC} I_{nom}}$



- This only give **acceptance levels**, it should be populated only by a few lines
- **No information between 0.1 and 10 Hz**
 - **We always assume that there are no lines there, but is it true?**

Voltage ripple -> current (from Gabarit)

Assuming acceptance level equal to **3.2 mV** down to **0.1 Hz**
+ Simplified model

$$\frac{dI(f)}{I_{rated}} \leq \frac{dV(f)}{\sqrt{(2\pi f L_{DC})^2 + R_{DC}^2 I_{rated}}}$$

Circuit name	I_{rated} [A]	L [mH]	R [mΩ]	$\Delta I / I_{rated}$	$\Delta I / I_{rated}$
				@0.1Hz @3.2mV [ppm rms]	@10Hz @3.2mV [ppm rms]
RB ^a	13000	15708	1	<0.1	<<0.1
RQ(D/F) ^a	13000	263	1	1.5	<0.1
RQX	18000	255	0.3	1.1	<0.1
RTQX1	2000	69	1.4	37	0.4
RTQXA1 ^b	120 (60)	34.5	n.a.	4213	42
RTQX3	2000	69	1.4	37	0.4
RCBX	2000	29	1.5	101	1
RQSX ^d	200 (600)	1247	10	20.4	0.2
RC(S/O)X	120	118	13	354	3.6
RC(D/T)X	120	52	13	755	8
RD(1/2)	13000	25	0.2	16	0.2
RCBRD	600	600	1	18	0.2
RQ(4/5) ^a	6000	74	0.6	18	0.2
RCBY ^a	120	5270	n.a.	10	0.1
RQ6 ^a	6000	21	0.5	52	0.5
RCBC ^a	120	2840	n.a.	20	0.2
RTB8 ^c	300 (600)	127	12.9	158	1.6

Realistic?

Extreme! PC should normally still be in current regulation... (not specified anywhere(?))

Would be unacceptable values!

Voltage ripple -> current (from PC “Noise”)

Assuming “Noise” value is measured with **L = 1mH** (or less)
+ Simplified model

$$\frac{dI(f)}{I_{rated}} \leq Noise \times \frac{1[mH]}{L[mH]}$$

Careful:
at high fL might actually decrease...

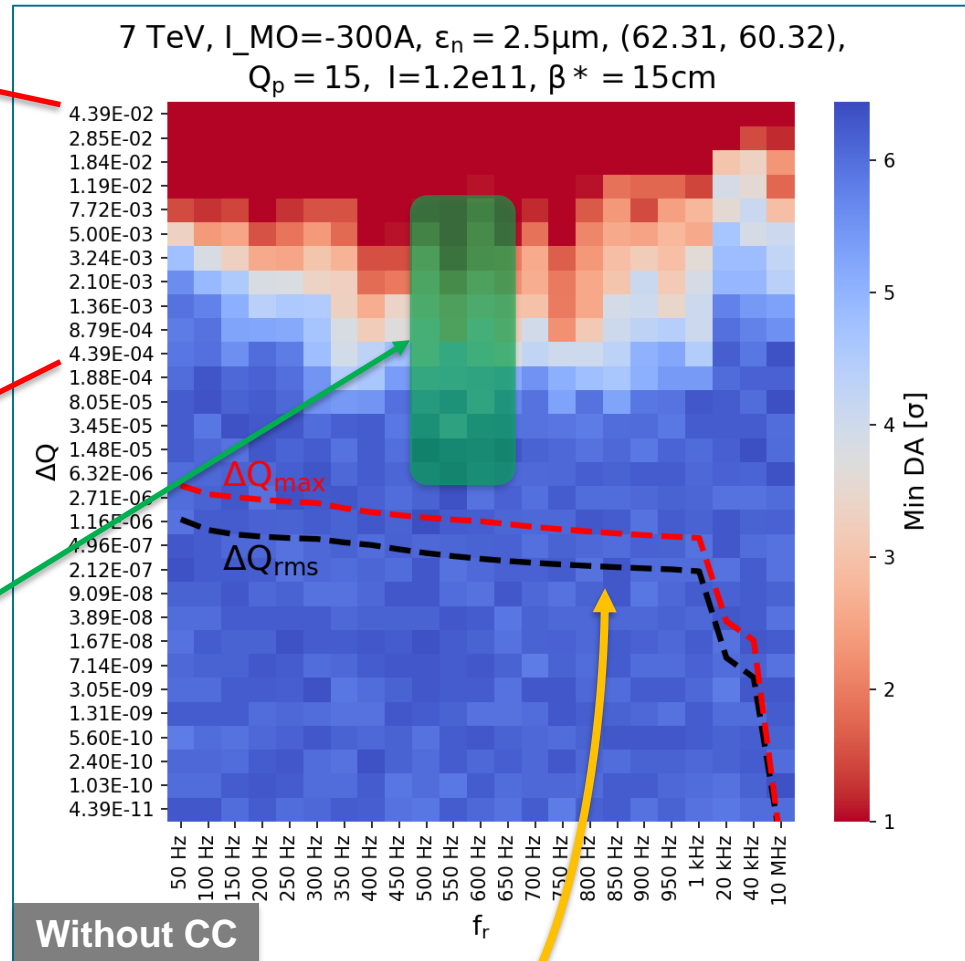
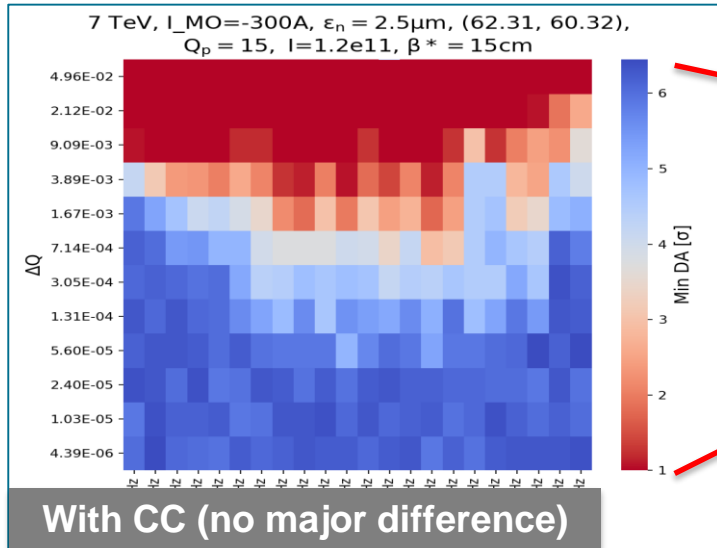
PC class:	0 ^a	1 ^a	1-2	2	3	4
Noise (0.1-500 Hz) [2×r.m.s. ppm]	3	5	4	10 (7)	15	25 (19)

Circuit name	I_{rated} [A]	L [mH]	PC class	Short term stability	Noise	Scaled Noise
RB ^a	13000	15708	1	0.4	5	<0.1
RQ(D/F) ^a	13000	263	1	0.4	5	<0.1
RQX	18000	255	0	0.2	3	<0.1
RTQX1	2000	69	2	1.2	7	0.1
RTQXA1 ^b	60	34.5	4	5	19	0.6
RTQX3	2000	69	2	1.2	7	0.1
RCBX	2000	29	2	1.2	7	0.2
RQSX ^d	600	1247	3	2	15	<0.1
RC(S/O)X	120	118	4	5	19	0.2
RC(D/T)X	120	52	4	5	19	0.4
RD(1/2)	13000	25	0	0.2	3	0.1
RCBRD	600	600	3	2	15	<0.1
RQ(4/5) ^a	6000	74	2	1.2	7	0.1
RCBY ^a	120	5270	4	5	19	<0.1
RQ6 ^a	6000	21	2	1.2	7	0.3
RCBC ^a	120	2840	4	5	19	<0.1
RTB8 ^c	600	127	3	2	15	0.1

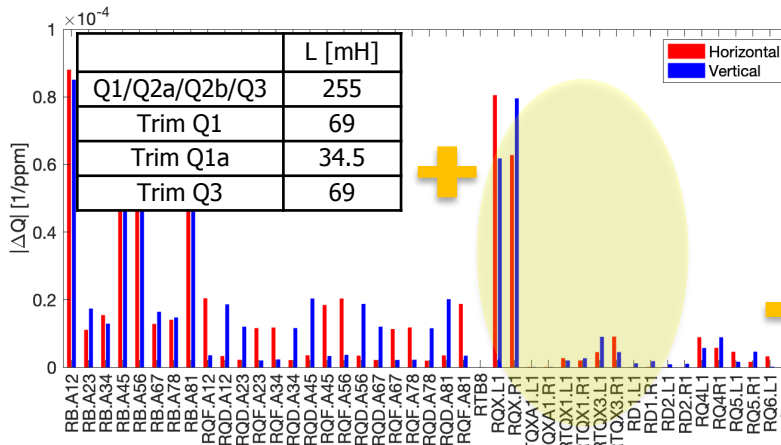
More reasonable values... but but but...

Dynamic Aperture studies

Preliminary
by S. Kostoglou



Similar study in **LHC**, gives similar reduction of DA @600Hz for $\Delta Q = 2e-4$.



$$\frac{dI(f)}{I_{rated}} \leq \frac{dV(f)}{(2\pi f L_{DC}) I_{rated}}$$

Seems like
we are safe!

Careful: at high fL might actually decrease...

Also: Expected Orbit Stability

- Old specifications vs. new specifications (15cm beta*):

	$\Delta(x^* y^*) [10^{-2} \sigma_{beam} \text{ r.m.s.}]$					
	20min.		12h fill		Long term	
	Old	New	Old	New	Old	New
IP1 H	0.3 (0.2 ⁺)	0.3 (0.3 ⁺ 0.3*)	1.3	2.6 (2.1*)	8.8	8.2 (7.7*)
IP1 V	0.2 (0.2 ⁺)	0.2 (0.2 ⁺ 0.2*)	1.1	2.3 (1.8*)	6.2	4.7 (4.0*)
IP5 H	0.3 (0.3 ⁺)	0.3 (0.3 ⁺ 0.3*)	1.8	2.7 (2.2*)	11.2	8.9 (8.4*)
IP5 V	0.2 (0.2 ⁺)	0.2 (0.2 ⁺ 0.2*)	1.2	2.3 (1.8*)	6.4	4.8 (4.1*)

⁺ Assuming to upgrade arc dipoles in sectors 8-11, 1-2, 4-5, 5-6 to class 0.

^{*} Assuming to use class 1-2 PC for RTQX1, RTQX3 and RCBX circuits.

- New specifications. Round (15 cm) vs Flat (7.5-18cm)

	$\Delta(x^* y^*) [10^{-2} \sigma_{beam} \text{ r.m.s.}]$					
	20min.		12h fill		Long term	
	15 cm	7.5 cm	15 cm	7.5 cm	15 cm	7.5 cm
IP1 H	0.3 (0.3 ⁺)	0.3 (0.3 ⁺)	2.6	3.0	8.2	9.2
IP1 V	0.2 (0.2 ⁺)	0.3 (0.3 ⁺)	2.3	2.7	4.7	5.1
IP5 H	0.3 (0.3 ⁺)	0.4 (0.4 ⁺)	2.7	3.3	8.9	10.5
IP5 V	0.2 (0.2 ⁺)	0.3 (0.3 ⁺)	2.3	2.6	4.8	5.1

⁺ Assuming to upgrade arc dipoles in sectors 8-11, 1-2, 4-5, 5-6 to class 0.

Negligible
<<1% lumi loss

Order 3%σ during fill

Order 10%σ over one year

Other topic: orbit separation collapse

Other topic: orbit separation collapse

- +/- 0.75 mm **separation knob** requires **very little strength** compared to total available.
- Ramp/acceleration rate were chosen from orbit feedback considerations

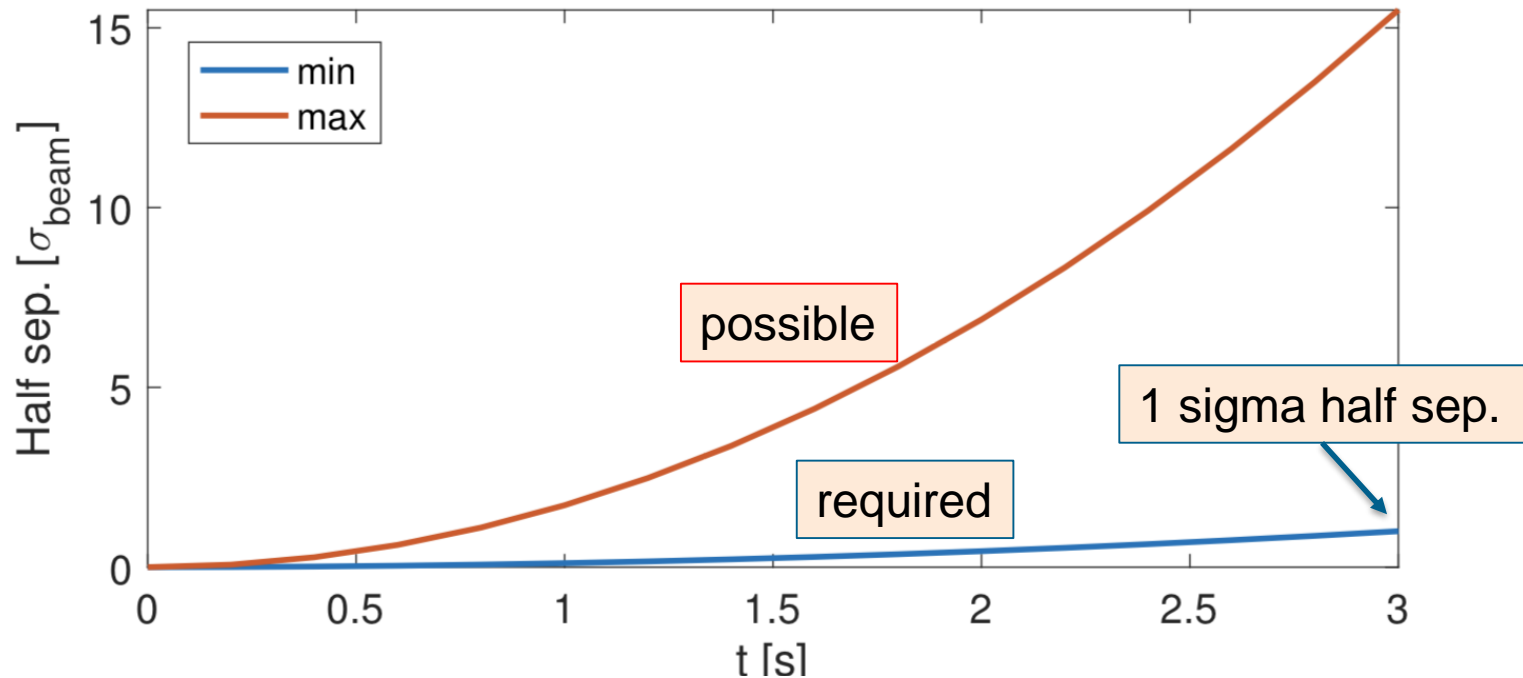
Circuit name	Half-separation [Tm]	$\int B_{nom} dl$ [Tm]	I_{nom} [A]	Ramp rate [A/s]	Acceleration [A/s ²]
RCBX1	0.08	2.5	1600	15	5
RCBX2	0.08	2.5	1600	15	5
RCBX3	0.20	4.5	1600	15	5
RCBRD4	0.10	5	430	2	1
RCBY4	0.02	2.79	88	0.67	0.25



From orbit feedback considerations

Other topics: orbit separation collapse

- Requirement: from 2 to 0 beam sigma in less than 3 seconds
- Here assuming round beta* = 70cm



Circuit name	Ramp rate [A/s]		Acceleration [A/s ²]	
	Required	Max	Required	Max
RCBX1	0.70	10.8	0.23	3.6
RCBX2	0.70	10.8	0.23	3.6
RCBX3	0.97	15	0.32	5
RCBRD4	0.12	1.81	0.04	0.60
RCBY4	0.01	0.13	<0.01	0.04

(My) Conclusions

- New PC specs **not too different** from old ones.
 - No major impact on tune jitter/orbit in using:
 - class 4 PCs for 120A circuits
 - RQSX powered by a 600A PC
 - RTB8 powered by a 600A PC
 - No sizable improvement from adopting **class 1-2**
 - Proposed to “skip” this class and **save money**.
- Over **one year**: 10^{-3} tune jitter; $10\% \sigma$ beam orbit jitter
 - No need of a **remote calibration** system for **class 0** PCs
- Specs. in **0.1 – a few Hz** range are a bit **dodgy**
 - **Should maybe improve definitions/constraints.**
 - From “Noise” guess everything seems fine
 - **“High” frequency regime seems to be fine.**
 - **To be kept under control** with new findings...
- Orbit separation **collapse** can be executed **much faster than required**
 - (at least from a circuit/PC point of view)