



# ALICE continuous readout and data reduction strategy for Run3 and 4

R.Shahoyan for the ALICE collaboration,

CHEP 2019, Adelaide, 05/11/2019





- Aim of the hardware upgrade in Run3/4 is to boost amount of collected collisions by factor ~100
- Operating ALICE will require cardinal change in approach to data processing  $\Rightarrow O^2$  framework
- Main challenges for handling the data to come:
  - The volume and the rate of data to store
    - $\Rightarrow$  requires combination of data reduction and compression by factor >35

 $(\sim 3.5 \text{ T/s} \rightarrow <100 \text{ GB/s}) \Rightarrow \sim 50 \text{ PB/y from Pb-Pb and reference pp data}$ 

- Computing power to process these data
  - ⇒ requires drastic improvements in reconstruction code (factor ~10 already achieved wrt Run2) and adapting heaviest operations to GPU processing
- Lot of other challenges (not covered in this talk), most important being coping with Space-Charge Distortions in the TPC (up to 15 cm for space-points with target precision of ~500 μm)



■ In Run2 ALICE operated at Pb-Pb interaction rates ~7-10 kHz (inspected ~1 nb<sup>-1</sup>) with trigger rate < 1 kHz



![](_page_3_Figure_0.jpeg)

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- LHC plans to deliver 50 kHz Pb-Pb interaction rate after LS2
- ALICE plans for Run3&4: collect 13 nb<sup>-1</sup> of Pb-Pb collisions at 5 TeV (of which 3 nb<sup>-1</sup> with reduced field)
- Main limitations to work at these rates:
  - Principal tracking detector, TPC has ~90 µs drift time + at least ~200 µs gating grid to collect the ion backflow
     → trigger rate limited to ~3 kHz (< 1 kHz accounting for bandwidth)</li>
- At high multiplicities (dN/dη ~ 2000 + pile-up) very low S/B for rare probes: dedicated (HLT) trigger is not realistic

![](_page_3_Picture_7.jpeg)

![](_page_4_Figure_0.jpeg)

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![](_page_4_Picture_7.jpeg)

Use continuous readout at least for TPC (no gating grid), increase bandwidth Read out all events, store compressed data and inspect all events offline

![](_page_5_Picture_0.jpeg)

## ALICE HW upgrades

![](_page_5_Picture_2.jpeg)

![](_page_5_Figure_3.jpeg)

![](_page_6_Picture_0.jpeg)

## ALICE HW upgrades

![](_page_6_Picture_2.jpeg)

nner Barrel

Outer Barrel

GEM 1 GEM 2 GEM 3 E<sub>T2</sub> GEM 3 E<sub>T3</sub> GEM 4 Pad plane TPC MWPC readout → 4 layer GEM
(Intrinsic ion backflow ~99% blocking)
5MHz continuous sampling

New Si Inner Tracker: 10 m<sup>2</sup> of MAPS with 29x27µm<sup>2</sup> pixel size 3 inner layers ~0.3% X0 each. Closer to the beam 50-500 kHz continuous readout

New beam pipe of smaller radius

Fast Interaction Trigger (FIT) detector Scintillator (FV0, FDD) + Cerenkov (FT0) detectors to provide Min.Bias trigger for detectors with triggered R/O

![](_page_6_Figure_8.jpeg)

Detectors can be read out in continuous or triggered modes, except triggered-only EMCal, PHOS/CPV, TRD (~40kHz) and HMPID (2.5 kHz)

![](_page_6_Figure_10.jpeg)

FD.A FD.C FD.C FD.C

![](_page_6_Picture_12.jpeg)

Muon Forward Tracker to match muons before and after the absorber. Same Si chips as new ITS

![](_page_7_Picture_0.jpeg)

![](_page_7_Picture_2.jpeg)

![](_page_7_Picture_4.jpeg)

![](_page_8_Picture_0.jpeg)

![](_page_8_Picture_2.jpeg)

![](_page_8_Figure_3.jpeg)

![](_page_9_Picture_0.jpeg)

Costa, T1,

ш.

Assessment of the ALICE O<sup>2</sup> readout servers,

Distribution of timing info, heartbeat trigger

![](_page_9_Picture_2.jpeg)

![](_page_9_Figure_3.jpeg)

10

![](_page_10_Picture_0.jpeg)

![](_page_10_Picture_2.jpeg)

![](_page_10_Figure_3.jpeg)

EPN will be used to perform calibrations from data accumulated at the synchronous stage and populate the CCDB (Condition and Calibration Data Base)

Together with GRID will participate in the final reconstruction and distribute Analysis Object Data (AOD) over Analysis Facilities

![](_page_10_Figure_6.jpeg)

![](_page_11_Picture_0.jpeg)

![](_page_11_Picture_2.jpeg)

Heart Bea issued in continu triggered modes to all detectors	at (HB) uous & sPhysics trigger can be sent to upgraded detectors will be sent to non-upgraded detectorsHBF and TF rates program Typical values: - HB: 1 per orbit, 89.4 $\mu$ - TF: 1 every ~20 ms: ~ - $\rightarrow$ 1 TF = ~256 HBF	<ul> <li>HB allows synchronization and TF sampling from detectors with continuous and triggered readouts</li> <li>Synchronized with LHC clock</li> </ul>
Continuo	us & Triggered read-out	HB Frame is the smallest chunk of
(Front-end &)		data which is inspected by CTP and can be dropped if the quality is bad.
	Heart Beat Frames (HBF): data stream delimited by two HBs Trigger data fragments	• FLP sees all data for part of the detector (except small detectors)
FLP	Sub-Time Frame (STF) in FLP 0: grouping of (~256) consecutive HBFs from one FLP FLP 1	<ul> <li>Set of same HBFs (STF) sent to the next EPN for aggregation to TF</li> </ul>
		• Single EPN sees non-consecutive TFs
EPN	<b>Time Frame (TF):</b> grouping of all STFs from all FLPs for the same time period from triggered or continuously read out detectors	⇒ collisions happening in last HBF may have their TPC clusters (drift ~ HBF) in next TF on other EPN ⇒ <0.5% data loss

![](_page_12_Picture_0.jpeg)

![](_page_12_Picture_2.jpeg)

Based on ALFA platform: common project of ALICE and FAIR, derived from FairRoot

See <u>ALFA: A framework for building distributed applications</u>, M. Al-Turany, T5, 11:30, 4 Nov.

![](_page_12_Figure_5.jpeg)

- Key feature:
  - message-queues based parallel processing done by separate <u>Devices</u> (processes)
- FairMQ supports multiple transport engines (ZMQ, nanomsg) over different protocols (Ethernet, Infiniband, shared memory access)
- Technicalities of messages exchange are hidden in the Data Processing Layer (DPL)
- DPL allows to wrap algorithms to <u>Devices</u> with particular Input and Output message type specifications.
- <u>Workflows</u> are built for group of <u>Devices</u> by automatic matching of their Inputs and Outputs

Data Analysis using ALICE Run3 Framework, G.Eulisse, T6, 11:45, 5 Nov.

Running synchronous detector reconstruction in ALICE using declarative workflows, M. Richter, TX, 16:30, 5 Nov.

![](_page_13_Picture_0.jpeg)

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#### ITS,TPC,TOF clustering $\rightarrow$ ITS, TPC tracking $\rightarrow$ ITS-TPC matching $\rightarrow$ TOF matching

![](_page_13_Figure_4.jpeg)

Workflow topology is built at run time by DPL

![](_page_14_Picture_0.jpeg)

DCS

CRU

CRU

CRU

RU

![](_page_14_Picture_2.jpeg)

Aims: Raw data reduction/compression to Compressed Time Frame (CTF), calibration data accumulation, QC

- Zero-suppression,
- Common mode correction
- Raw data reformatting
- Accumulation of TPC digital currents
- ...
- Low level QC
- Sub-TimeFrame building

Charge integrated by every TPC pad (or their group) in ~ 1 ms intervals. Used in TPC calibration to map <u>fluctuations</u> of Collected charge @ RO planes  $\rightarrow$  Space charge  $\rightarrow$  Drift line distortions

Due to the slow ion drift, the history for ~ 160 ms (~8000 Pb-Pb collisions) is needed to calibrate ~5ms interval  $\Rightarrow$  the only cross-TF data stream

![](_page_15_Picture_0.jpeg)

![](_page_15_Picture_2.jpeg)

Aims: Raw data reduction/compression to Compressed Time Frame (CTF), calibration data accumulation, QC

![](_page_15_Figure_4.jpeg)

EPN

- Full TPC clusterization and tracking (GPU)
- Full ITS+MFT clusterization (CPU)
- Full FIT & ZDC reconstruction (may be considered also on FLP)

![](_page_15_Figure_9.jpeg)

![](_page_16_Picture_0.jpeg)

CRU

CRU

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0

![](_page_16_Picture_2.jpeg)

#### Aims: Raw data reduction/compression to Compressed Time Frame (CTF), calibration data accumulation, QC

DCS

## EPN

- Full TPC clusterization and tracking (GPU)
- Full ITS+MFT clusterization (CPU)
- Full FIT & ZDC reconstruction (may be considered also on FLP)
- Partial ITS tracking + ITS/TPC/TRD/TOF matching (CPU, GPU possible) as much as needed for QC and calibration:

![](_page_16_Figure_10.jpeg)

![](_page_17_Picture_0.jpeg)

RU

CRU

CRU

CRU

![](_page_17_Picture_2.jpeg)

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EPN

~2 kHz of 50-100% centrality events (<mult> = ~14% of MB) provide enough statistics for per <u>1 minute</u> Run2-like TPC distortion calibrations (most statistics hungry)

- $\Rightarrow$  4% of collisions (~0.6% of all tracks) @ IR=50 kHz
- Refit ITS-TRD-TOF and interpolate to TPC pad-rows as a reference of the true track position
- Collect  $\Delta Y$ ,  $\Delta Z$  between **distorted clusters** and **references** in sub-volumes (voxels) of TPC
- Extract 3D vector of distortions in every voxel (offline)

See poster Space point calibration of the ALICE TPC with track residuals, O.Schmidt, T1

![](_page_17_Figure_15.jpeg)

#### For the QC see The ALICE data quality control system, P. Konopka, T1, 15:15

![](_page_18_Picture_0.jpeg)

![](_page_18_Picture_2.jpeg)

#### Aims: Raw data reduction/compression to Compressed Time Frame (CTF), calibration data accumulation, QC

DCS

Full TPC clusterization and tracking (GPU)

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- $\Rightarrow$  4% of collisions (~0.6% of all tracks) @ IR=50 kHz
- Accumulation of data for offline calibrations
- On-the-fly calibrations (e.g. TRD, TPC V-drift) with feed-back for reconstruction of following TFs
- Entropy and data reduction, entropy compression (ANS<sup>\*</sup>), writing CTF

QC within EPN devices and on dedicated QC servers

Aggregation of accumulated calibration data from EPNs CCDB updates

![](_page_19_Picture_0.jpeg)

![](_page_19_Picture_1.jpeg)

![](_page_19_Picture_2.jpeg)

- Principal difference wrt Run1,2:
  - Whole TF (~1000 Pb-Pb) reconstructed in one shot
  - In absence of triggers (reference for drift time estimate)
     Z position of clusters is not defined

![](_page_19_Picture_6.jpeg)

![](_page_20_Picture_0.jpeg)

![](_page_20_Picture_1.jpeg)

![](_page_20_Picture_2.jpeg)

- Principal difference wrt Run1,2:
  - Whole TF (~1000 Pb-Pb) reconstructed in one shot
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     Z position of clusters is not defined
- Cluster correction depends on their Z-position
  - perform initial calibration assuming cluster belongs to  $|\eta| = 0.45$  track from the IP

![](_page_20_Figure_8.jpeg)

After matching TPC track to ITS (fixes TPC clusters Z) recalibrate cluster positions before the refits.

In the synchronous stage will be running on the GPU, for details see: <u>GPU-based reconstruction and data compression at ALICE during LHC Run3</u>, D.Rohr, TX, today, 14:15

![](_page_21_Picture_0.jpeg)

## **TPC tracking**

![](_page_21_Picture_2.jpeg)

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![](_page_21_Figure_8.jpeg)

After matching TPC track to ITS (fixes TPC clusters Z) recalibrate cluster positions before the refits.

Improved version of Run1,2 HLT tracking:

- Per sector track finding:
  - Track seeding using Cellular Automaton:
    - Finding straight-line hit triplets on adjacent rows
    - Concatenating compatible triplets to seeds, fitting

![](_page_21_Figure_15.jpeg)

• Track following (Kalman filter)

- Merging between sectors and over central electrode
- Inside/outside refit with cluster reattachment
- Looping track legs merging (found from p<sub>T</sub>>~15 MeV/c)

In the synchronous stage will be running on the GPU, for details see: <u>GPU-based reconstruction and data compression at ALICE during LHC Run3</u>, D.Rohr, TX, today, 14:15

![](_page_22_Picture_0.jpeg)

![](_page_22_Picture_2.jpeg)

- Fast primary vertex finding with tracklets from 3 inner layers
- Standalone track-finding in ITS using Cellular Automaton

![](_page_22_Figure_5.jpeg)

- Multiple passes for prompt (constrained to vertex) long, incomplete and off-vertex tracks (in asynchronous phase)
- Runs both on CPU and GPU

![](_page_22_Figure_8.jpeg)

![](_page_23_Picture_0.jpeg)

![](_page_23_Picture_2.jpeg)

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![](_page_23_Figure_5.jpeg)

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- ITS-TPC track-to-track matching
- ITS in Run3 has long integration time (~2 − 20 µs)
   → may see multiple collisions in single frame Matching resolves interaction time to ~100 ns
- ITS-TPC refitted outwards and matched to TRD and TOF
- Afterburner (<u>in asynchronous phase only</u>): matching <u>remaining</u> ITS clusters of TPC tracks with Z constrained by different interaction times from FIT

![](_page_23_Figure_12.jpeg)

![](_page_24_Picture_0.jpeg)

ALICE

**Unassigned clusters** 

Reconstructed Tracks

Noisy TPC pads

**Removed Clusters** 

Fit failed

- Target in ideal case: reject ~50% of clusters
- Two alternative scenarios:
- A: Keep all clusters except those from identified
  - 1) (looping) tracks  $p_T < 50$  MeV/c (not needed for physics)
  - 2) extra legs of loopers  $50 < p_T < 200 \text{ MeV/c}$
  - 3) segments of tracks with high inclination to pad-rows ( $\phi$ >70°)

currently only ~13% rejection rate achieved

- in principle, ~39% rejection achievable if
  - merging of looper legs improved
- looper tagging can be extended to p<sub>T</sub><10 MeV (~15% of clusters) (track radii < 6cm, Hough transform is tested)</li>
- **B**: Keep only clusters attached or in the vicinity of tracks interesting for physics ( $p_T > 50 \text{ MeV/c}$ , principal leg for loopers) <u>currently</u> ~37% rejection achieved

in principle, ~52% rejection achievable in case of ideal loopers legs merging

![](_page_25_Picture_0.jpeg)

## **TPC data compression**

![](_page_25_Picture_2.jpeg)

We aim for efficient storing of raw clusters (pad, row, time) data in view of later reconstruction with best possible calibration.

- $\frac{1}{2}$  ~ 50% of clusters can be attached to tracks  $\Rightarrow$  minimize entropy by exploring correlation between these clusters:
- Find tracks with clusters transformed and corrected with best available calibration
- Transform again raw clusters of the track using fast linear transformation and refit tracks in distorted coordinates
- Starting with distorted track parameters perform Kalman update / extrapolation from row to row
- Transform extrapolations back to raw coordinates and store residuals
- Additional benefit: cluster to track association is stored intrinsically
- Data rounded to relevant (logarithmic) precision and encoded with ANS compression

![](_page_25_Figure_11.jpeg)

![](_page_26_Picture_0.jpeg)

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![](_page_26_Picture_2.jpeg)

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Decoding: perform inverse procedure using the same linear transformation:

- recover cluster coordinates from stored residuals + current track position
- do Kalman update with cluster
- extrapolate to next layer...

![](_page_26_Figure_15.jpeg)

See: <u>GPU-based reconstruction and data compression at ALICE during LHC Run3</u>, D.Rohr, TX, today, 14:15

![](_page_27_Picture_0.jpeg)

![](_page_27_Picture_2.jpeg)

- ITS will ship ~30 GB/s data in continuous readout with ~6µs strobe (~10<sup>10</sup> fired pixels/s with noise 10<sup>-7</sup> /channel)
- Data are redundant: ~50% of fired pixels are fired in 2 consecutive strobes (TOT ≈ strobe)
   ⇒ Mask repeatedly fired pixels and store clusterized data.
- Profit from the highly non-uniform frequency of different cluster patterns (low entropy)
- Build table of patterns sorted in frequency, for each pattern pre-calculate its properties:
  - Offset of **COG** wrt **reference pixel** (e.g. corner of cluster bounding box)

![](_page_27_Picture_8.jpeg)

- Mean error between COG and MC hit position
- (in future) error vs impact angles
- Encoding: store reference pixel column/row and pattern ID
- During decoding directly obtain cluster position w/o actual COG calculation

![](_page_27_Figure_13.jpeg)

![](_page_27_Figure_14.jpeg)

![](_page_28_Picture_0.jpeg)

![](_page_28_Picture_2.jpeg)

![](_page_28_Figure_3.jpeg)

![](_page_29_Picture_0.jpeg)

![](_page_29_Picture_2.jpeg)

![](_page_29_Figure_3.jpeg)

![](_page_30_Picture_0.jpeg)

![](_page_30_Picture_2.jpeg)

![](_page_30_Figure_3.jpeg)

![](_page_31_Picture_0.jpeg)

## Data rates (in GB/s) at online stage

![](_page_31_Picture_2.jpeg)

![](_page_31_Figure_3.jpeg)

For remaining detectors data compression consists of

- reformatting raw data (TRD, TOF)
- Storing signal extracted from ADC samples (EMCal, PHOS: 30 10-bit samples → 2 floats per cell)
- Storing clusters discarding pads data (MUON, feasibility still being evaluated)

Two alternative scenarios for TPC data lossy compression (both will be implemented)

- A. Reject only clusters or identified noise and background tracks (loopers):
   Rejects: 12.5% 39.1%
- B. Keep only clusters attached or in the proximity of identified signal tracks.
   Rejects: 37.3% 52.5%

![](_page_32_Picture_0.jpeg)

![](_page_32_Picture_2.jpeg)

#### November 4:

- ALFA: A framework for building distributed applications, M. Al-Turany, T5, 11:30 Jiskefet, a bookkeeping application for ALICE, M.Teitsma, T4, 11:45 AliECS: a New Experiment Control System for the ALICE Experiment, T. Mrnjavac, T1, 14:00 The ALICE data quality control system, P. Konopka, T1, 15:15 November 5: Assessment of the ALICE O<sup>2</sup> readout servers, F. Costa, T1, 11:00 A VecGeom navigator plugin for Geant4, S. Wenzel, T2, 11:30 Design of the data distribution network for the ALICE Online-Offline (O<sup>2</sup>) facility, G. Neskovic, T1, 12:00 Data Analysis using ALICE Run3 Framework, G.Eulisse, T6, 11:45 System simulations for the ALICE ITS detector upgrade, S. Nesbo, T2, 12:15 GPU-based reconstruction and data compression at ALICE during LHC Run3, D.Rohr, TX, 14:15 Running synchronous detector reconstruction in ALICE using declarative workflows, M. Richter, TX, 16:30 Running ALICE Grid Jobs in Containers - A new approach to job execution for the next generation ALICE, M.Melnik, T7, 17:45 Using multiple engines in the Virtual Monte Carlo package, B.Volkel, T2, 17:45 **Posters:** Fast and Efficient Entropy Compression of ALICE Data using ANS Coding, M.Lettrich, T1
- Space point calibration of the ALICE TPC with track residuals, O. Schmidt, T1
- The evolution of the ALICE O<sup>2</sup> monitoring system, A. Wegrzynek, T1

![](_page_33_Picture_0.jpeg)

![](_page_33_Picture_1.jpeg)

![](_page_34_Picture_0.jpeg)

![](_page_34_Picture_1.jpeg)

## BACKUP

![](_page_34_Picture_3.jpeg)

![](_page_35_Picture_0.jpeg)

![](_page_35_Picture_2.jpeg)

![](_page_35_Figure_3.jpeg)

Distribution of timing info, heartbeat trigge

![](_page_36_Picture_0.jpeg)

## CRU and FLP minimum needs per detector

![](_page_36_Picture_2.jpeg)

Detector	Throughput	Number of		Number of FLPs with		
	GB/s)	read-out boards		2 CRUs or	3 CRUs or	4 CRUs or
		CRU	CRORCs	CRORCs	$\operatorname{CRORCs}$	CRORCs
ACO $(*)$	0.01		1	1	1	1
CPV	0.09	1		1	1	1
$\operatorname{CTP}$	0.02	1		1	1	1
DCS		1		1	1	1
EMC $(*)$	4.00		4	2	2	1
FIT	0.12	2		1	1	1
HMP $(*)$	0.06		4	2	2	1
ITS	40.0	24		12	8	6
MCH	2.2	32		16	11	8
MFT	10.0	11		6	4	3
MID	0.03	2		1	1	1
PHS $(*)$	2.0		4	2	2	1
TOF	2.50	4		2	2	1
TPC	570.0	360		180	120	90
TRD	4.0	36		18	12	10
ZDC	0.06	1		1	1	1
Total	635	475	13	247	170	127

![](_page_37_Picture_0.jpeg)

![](_page_37_Picture_1.jpeg)

![](_page_37_Figure_2.jpeg)

Figure 3.1: Detector read-out and interfaces of the O<sup>2</sup> system with the trigger, detector electronics and DCS.

![](_page_38_Picture_0.jpeg)

![](_page_38_Picture_2.jpeg)

![](_page_38_Figure_3.jpeg)