



3D convolutional GAN for fast simulation

HSF Fast Simulation topical meeting

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A DL engine for fast simulation

Provide a tool that can be configured and trained for different detectors

Start with time consuming detectors

Next generation highly granular calorimeters

Train on Monte Carlo data Optimise training time





Our plan

- Are generative models accurate enough?
- Can we sustain the increase in detector complexity?
- How generic is this approach?
- Can we "adjust" architecture to fit a larger class of detectors?
- What resources are needed?



- A first proof of concept
- Understand performance and validate accuracy



- Prove generalisation is possible
- Understand and optimise computing resources

Can it be integrated in a "standard" simulation workflow?



- Pre-processing
- Interfaces to simulation engine

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Proof of concept, benchmarking and validation





CLIC calorimeter simulation

Data is essentially a 3D image

Electromagnetic calorimeter detector design^(*) (Linear Collider Detector studies)

 1.5 m inner radius, 5 mm×5 mm segmentation: 25 tungsten absorber layers + silicon sensors

1M single particle samples (e, γ , π) with flat energy spectrum (10-500) GeV

- . Orthogonal to detector surface (25x25x25 pixels)
- 2. +/- 30° random incident angle (51x51x25 pixels)



Highly segmented Sparse.





3D convolutional GAN

Similar discriminator and generator models

3D convolutions (keep X,Y symmetry)

~1M parameters total

Condition training on input variables (energy, angle)

Auxiliary regression tasks assigned to the discriminator: cross check

Custom losses

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Validation and optimisation

Detailed GAN vs GEANT4 comparison (More than 200 Plots!)

High level quantities (shower shapes)

Calorimeter response (single cell response)

Particle properties (primary particle energy)

Optimisation on

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Network Architecture (Layers, filters, kernels, initialisation)

Losses definition

Data pre-processing

Results agree within a few % to Geant4 (sometimes labelled "DATA" in next slides ③)

Run TriForce classification and regression engine on GAN generated data (Matt Zhang, https://github.com/BucketOfFish/Triforce_CaloML)

We run on Caltech ibanks GPU cluster thanks to Prof M. Spiropulu ⁷

Electrons shower shapes





Deposited energy and sampling fraction



Computing resources & Generalisation

Distributed training Hyper-parameter scans





Computing performance

Distributed training is needed

Inference:

- Geant4: 17 s/particle **vs** 3DGAN: 7 ms/particle
- → speedup factor > 10000!!
- Testing inference on accelerators (GPUs, FPGAs) and dedicated hardware

Training:

- 45 min /epoch on Tesla P100
- Introduce data parallel training based on MPI
- **Test several libraries**
- Run on HPC clusters and Cloud (HNSciCloud providers)



Distributed training

- Cloud deployment via docker + Kubernetes/Kubeflow (R. Rocha CERN IT-CM)
- Frameworks
 - Horovod
 - mpi_learn
- Hardware
 resources
 - Cloud (HNSciCloud)
 - HPC centers (Oakridge – TACC)



6.75

4.5

2.25

Speedup



Generalisation

Electrons enter the calorimeter within a 60°-120° angle range



Wider/asymmetric image size (51x51x25) Minimal architecture changes "by hand"

- Adjust convolution parameters
- Additional terms in the loss function:
 - Angle-related term
 - Constrain energy spectrum



Angle dependence (I)

Spit calorimeter in 3 layers along its depth (cells: 1-8, 8-16, 24-25)

Measure energy deposited in layers wrt total









Angle dependence (II): shower shapes

Shower Shapes

Position along X axis

Shower Shapes

Position along Y axis

Shower Shapes





120° incident angle



Angle dependence (III)

Sampling fraction annd number of hits



Internal correlations

3DGAN can correctly reproduce most G4 internal correlations





Generalisation

Training and architecture hyper-parameters optimisation

 How much can we generalise our network to other calorimeters? Different geometries, read-out patterns, energy scales
 Tuning the right architecture cannot be done by hand Full parameter scan is resource/time consuming.

Test different optimisation approaches:

Sequential Model-Based Optimization

Optimize intial architecture candidate, defining a finite set of states to explore

Reinforcement Learning

Network accuracy is the **reward function**. Architecture or hyper-parameter modification are **actions** Evolutionary Algorithms

19

Can allow simulataneous weights training and architecture optimisation

mpi-learn integrates a optimisation engine (mpi-opt)

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Summary & Plans

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3D GAN: first step towards customizable simulation tool Agreement to Monte Carlo within few percent Work in SFT to test integration in simulation framework Meta-optimization and hyper-parameters scans are key Test of several distributed training approaches Understand / optimize performance at scale We are working heavily on "technological/computing" aspects in collaboration with industry (Intel, IBM, Google)

Test different platforms for inference and training: CPUs, accelerators (GPUs, FPGAs)



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Discriminator regression on input energy



5% error on auxiliary energy regression



Conditioning and auxiliary tasks

Loss is linear combination of 3 terms:

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Combined cross entropy (real/fake)

Mean absolute percentage error for regression tasks



Physics performance







https://github.com/vlimant/mpi_opt

https://github.com/vlimant/mpi_learn

mpi-opt

Parallelise optimisation with mpi-learn Bayesian optimiser Evolutionary approach

- One master runs optimisation (skopt)
- N_G groups of nodes train on a parameter-set
 - One training master
 - N_W training workers
- Can also run in "sub-masters mode"
 - Sub-masters perform intermediate averaging





Parallel optimiser

One master running communication of parameter set

 N_{SK} workers running the bayesian optimization

N_G groups of nodes training on a parameter-set on simultaneously

- One training master
- N_w training workers

prevent working groups to be idle while the optimisation fit is performed

openlab

K-folding cross validation

Estimate performance over different validation parts of the training dataset Account for variance from multiple sources

- One master runs the bayesian optimization.
- Receives the average fom over N_F folds of the data
- N_G groups of nodes training on a parameter-set simultaneously
- N_F groups of nodes running one fold each
 - One training master
 - N_w training workers

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