

BPM Resolution Studies at PETRA III

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DESY (MDI)

- Introduction
- Comments on BPM Resolution
- „Three BPM“ Correlation & Principal Components Analysis
- Resolution Studies at PETRA III
- Conclusion

PETRA III @ DESY



HELMHOLTZ RESEARCH FOR GRAND CHALLENGES

● PETRA history

- 1978 – 1986: e^+e^- collider (up to 23.3 GeV / beam)
- 1988 – 2007: pre-accelerator for HERA (p @ 40 GeV, e @ 12 GeV)
- since 2007: dedicated 3rd generation light source, commissioned in 2009 TDR: DESY 2004-035
 - **14 beamlines** (15 experimental stations) operating in parallel
- from 2014: staged extension project W. Drube et al., 2016 <https://doi.org/10.1063/1.4952814>
 - **up to 12 additional beamlines** (presently not all of them in operation)



Extension Hall East
Ada Yonath

Max von Laue Hall

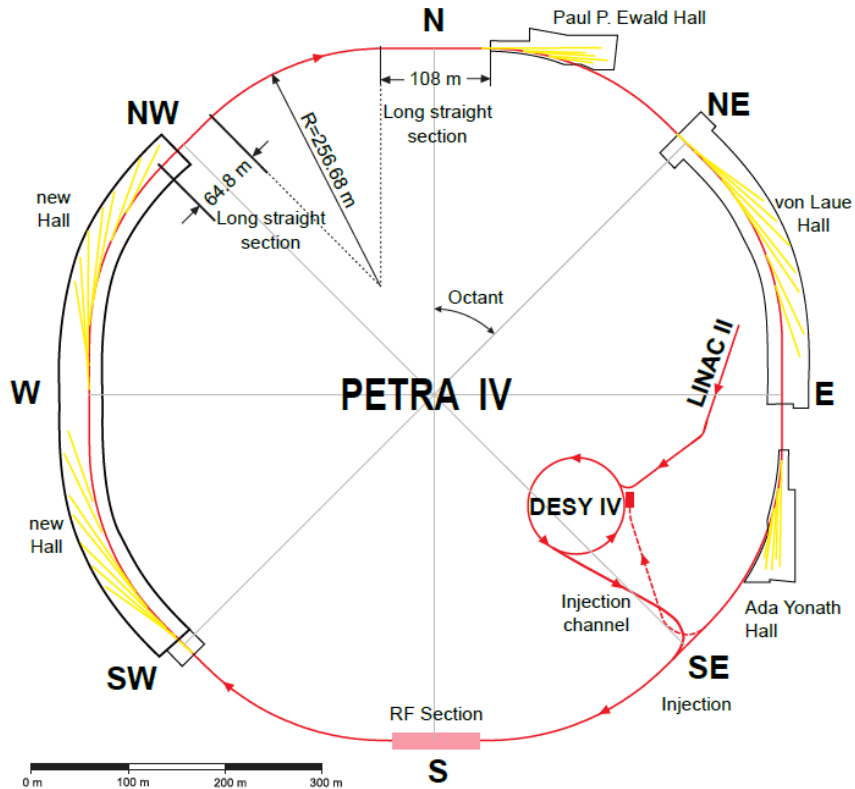
Extension Hall North
Paul P. Ewald

PETRA IV: Overview



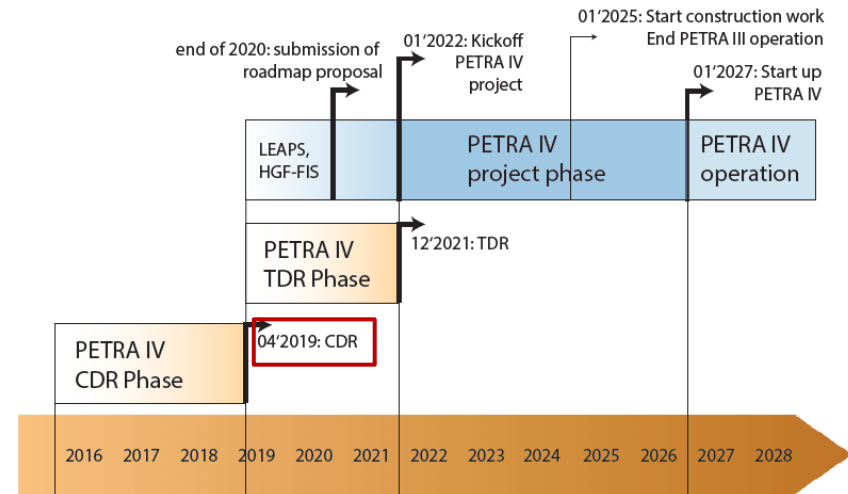
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PETRA IV storage ring and pre-accelerators



- use of existing accelerator tunnel
 - asymmetric ring structure
- additional experimental hall
 - 29 straight ID sections

time line



Design parameter	PETRA III	PETRA IV
Energy / GeV	6	6
Circumference / m	2304	2304
Operation mode	Continuous Timing	Brightness Timing
Emittance (horz. / vert.) / pm rad	1300 / 10	< 20 / 4 < 50 / 10

presently

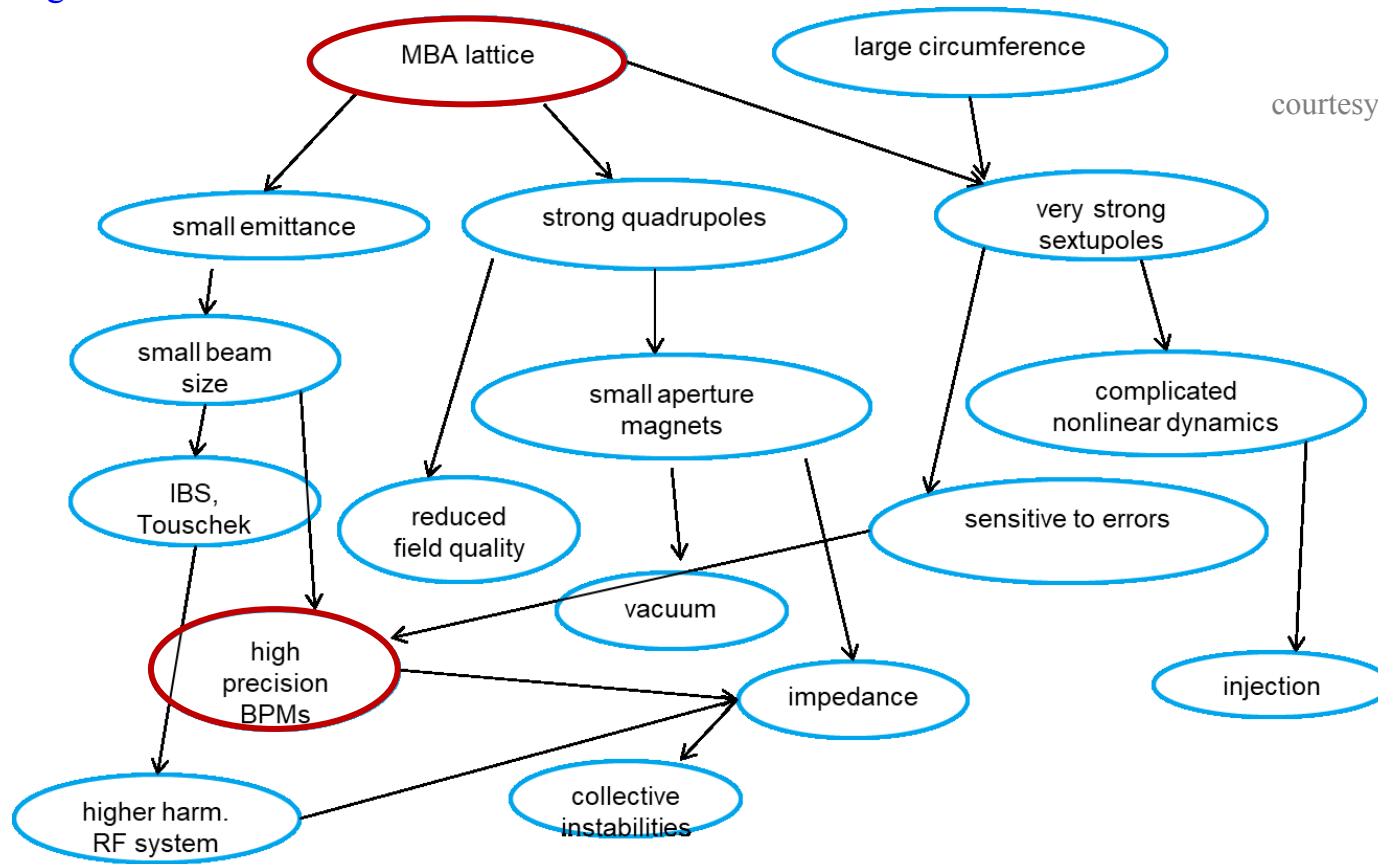
- preparation of *Conceptual Design Report*

PETRA IV: Diffraction Limited Light Source



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DLS design



BPM resolution requirements

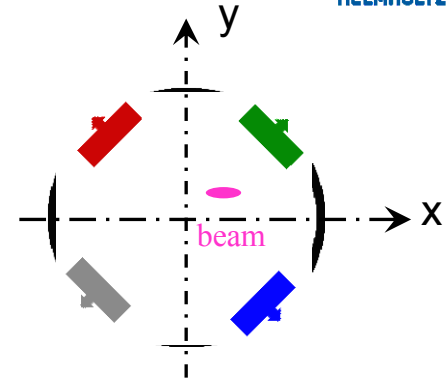
- › single bunch / single turn **< 20 μm** (assuming 0.5 mA in single bunch \rightarrow 2.5×10^{10} particles bunch)
- › closed orbit **< 100 nm** (rms, 200 mA in 1600 bunches) at 300 Hz BW

BPM Resolution

- position determination in circular accelerator

$$x = K_x \frac{(P_1 + P_4) - (P_2 + P_3)}{P_1 + P_2 + P_3 + P_4}$$

$$y = K_y \frac{(P_1 + P_2) - (P_3 + P_4)}{P_1 + P_2 + P_3 + P_4}$$



- position resolution (small displacements from center)

$$\sigma_{x,y} \propto K_{x,y} \frac{1}{\sqrt{SNR}}$$

$K_{x,y}$: monitor constant

SNR : signal-to-noise ratio

- depends on

- pickup geometry → beam pipe diameter
- button size → small correction
- geometry (button size) → signal strength
- infrastructure → cable length & attenuation
- read-out electronics



main focus: read-out electronics

- goal

- performance test → existing *Libera Brilliance* readout electronics @ PETRA III

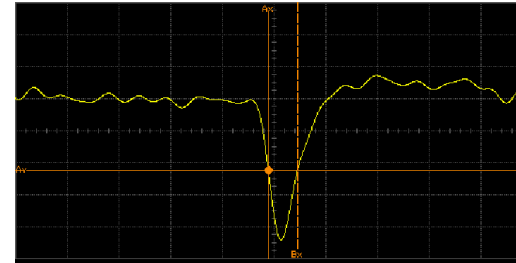
BPM Resolution Measurements

- modern ADCs optimized for cw signals

- signal from BPM button → far away from cw signal



BPM resolution with beam generated signals



- BPM signal measurement with beam → 2 kinds of jitter

- beam jitter

- real *change of beam angle* and *position* caused by fluctuations in accelerator

- (ground motion, energy fluctuation, kicks, ...)

- seen by *several* / *all* BPMs simultaneously

- (**correlation** via beam optics)

- noise of BPM electronics

- quantity to be measured

- **no correlation** between adjacent BPM readings



correlation analysis in order to disentangle both jitter sources

- common methods for correlation analysis

- „three BPM“ correlation method

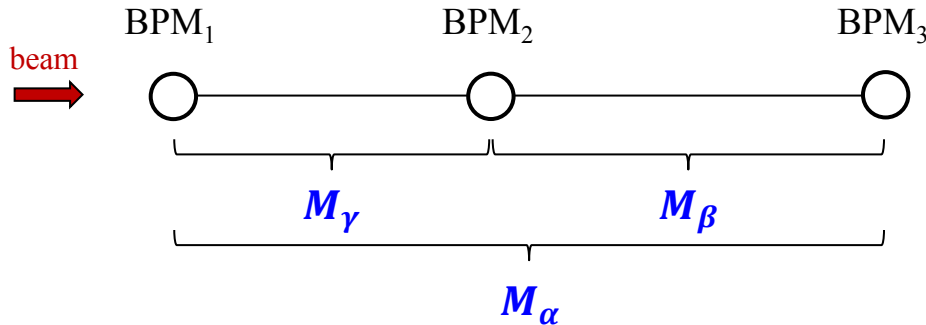
- Principal Components Analysis (PCA)



brief review

„Three BPM“ Correlation Method

- principle setup: 3 adjacent BPMs



- connection via transport matrices

- no non-linear elements between BPMs

$$\begin{pmatrix} y_3 \\ y'_3 \end{pmatrix} = \begin{pmatrix} \alpha_{11} & \alpha_{12} \\ \alpha_{21} & \alpha_{22} \end{pmatrix} \begin{pmatrix} y_1 \\ y'_1 \end{pmatrix}$$

$$= \begin{pmatrix} \beta_{11} & \beta_{12} \\ \beta_{21} & \beta_{22} \end{pmatrix} \begin{pmatrix} y_2 \\ y'_2 \end{pmatrix}$$

$$\begin{pmatrix} y_2 \\ y'_2 \end{pmatrix} = \begin{pmatrix} \gamma_{11} & \gamma_{12} \\ \gamma_{21} & \gamma_{22} \end{pmatrix} \begin{pmatrix} y_1 \\ y'_1 \end{pmatrix}$$

- BPM reads position information

$$\left. \begin{aligned} y_2 &= \gamma_{11}y_1 + \gamma_{12}y'_1 \\ y_3 &= \alpha_{11}y_1 + \alpha_{12}y'_1 \end{aligned} \right\}$$

$$y_2 = \left(\gamma_{11} - \frac{\alpha_{11}\gamma_{12}}{\alpha_{12}} \right) y_1 + \frac{\gamma_{12}}{\alpha_{12}} y_3 \Rightarrow y_2 = X_{21}y_1 + X_{23}y_3$$

- difference: measured position vs. expectation

$$\Delta = y_2 - X_{21}y_1 - X_{23}y_3$$

- calculate variance (error propagation)

$$\sigma_\Delta^2 = \sigma_{y_2}^2 + X_{21}^2 \sigma_{y_1}^2 + X_{23}^2 \sigma_{y_3}^2$$

- all BPM readings with same error

$$\sigma_{y_1} \sim \sigma_{y_2} \sim \sigma_{y_3} = \sigma_{BPM}$$

$$\Rightarrow \sigma_{BPM} = \frac{\sigma_\Delta}{\sqrt{1 + X_{21}^2 + X_{23}^2}}$$

- $\sigma_\Delta \rightarrow$ N consecutive position measurements

$$\sigma_{BPM} = \sqrt{\frac{1}{N-1} \frac{\sum_{i=1}^N \{y_{2,i} - (X_{21}y_{1,i} + X_{23}y_{3,i})\}^2}{1 + X_{21}^2 + X_{23}^2}}$$

„Three BPM“ Correlation Method (2)



procedure

- › N consecutive position measurements with 3 adjacent BPMs
- › determination of transfer matrix elements X_{21} , X_{23}
 - straight forward: calculation according to beam optics
 - model independent: **Moore-Penrose** pseudo inverse (least-square estimate for X)

$$\begin{pmatrix} y_{2,1} \\ \vdots \\ y_{2,N} \end{pmatrix} = \begin{pmatrix} 1 & y_{1,1} & y_{3,1} \\ \vdots & \vdots & \vdots \\ 1 & y_{1,N} & y_{3,N} \end{pmatrix} \begin{pmatrix} X_0 \\ X_{21} \\ X_{23} \end{pmatrix}$$

constant
offset ≈ 0
↓

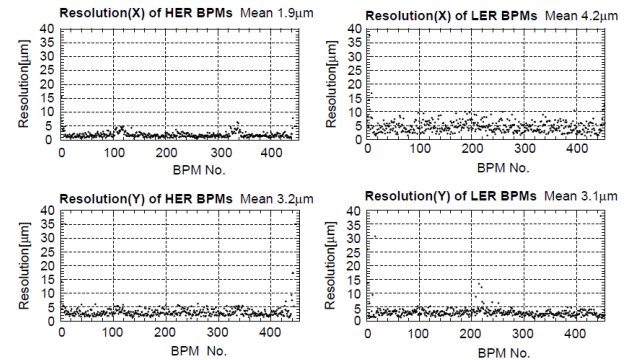
› BPM resolution

→ evaluate formula
$$\sigma_{BPM} = \sqrt{\frac{1}{N-1} \frac{\sum_{i=1}^N \{y_{2,i} - (X_{21}y_{1,i} + X_{23}y_{3,i})\}^2}{1 + X_{21}^2 + X_{23}^2}}$$

› successive application to all BPMs

→ grouping three adjacent BPMs

example: KEK-B M. Arinaga et al., NIM A499 (2003) 100



restrictions

- › no non-linear elements → difficult at DLS
- › same error of BPM readings → not possible at PETRA III
- › sometimes weak correlations with neighbour BPMs
 - large uncertainty in BPM resolution (especially with Moore-Penrose)

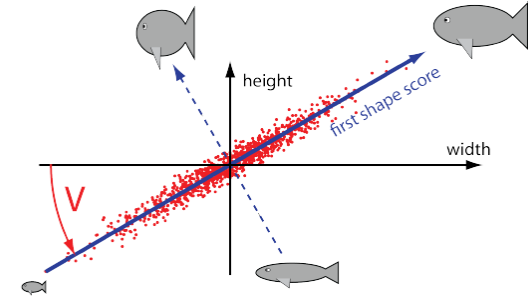
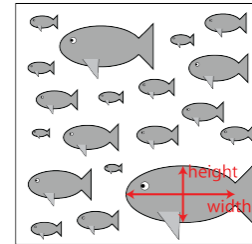


phase advance $\neq n/2 \pi$
 $n = \pm 1, 3, 5, \dots$

Principal Components Analysis (PCA)

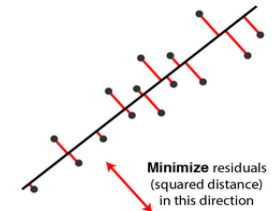
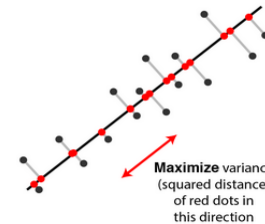
method of multivariate statistics

- › conversion of set of correlated variables into set of linearly uncorrelated ones
 - principal components (PC)
- › cleansing of correlations in data sets
 - structuring of large data sets, compression, ...



principal axis determination

- › orientation of first principal axis
 - axis rotation such that overall data variance is maximized (requires centering of data)
 - alternative: minimize projections (hint: χ^2)
- › orientation of second (third, ...) principal axis
 - remove contribution of 1st PC from data
 - repeat rotation and variance maximization



condition: uncorrelated with (i.e., perpendicular to) first principal component

mathematics behind

- › form covariance matrix C → real & symmetric matrix
- › diagonalization of C → $C = V\Lambda V^T$
 - V : formed by orthonormal eigen vectors
- › eigen vectors → principal components
- eigen values (Λ) → amount of variance for PC
- › sort eigen vectors according to eigen values

Principal Components Analysis (2)

alternative numerical method → Singular Value Decomposition (SVD)

› instead of *diagonalization* of *covariance matrix*

→ SVD of *data matrix* M

› relation between *singular* and *eigen values*:

$$\rightarrow \Lambda = \frac{\Sigma^2}{n-1}$$

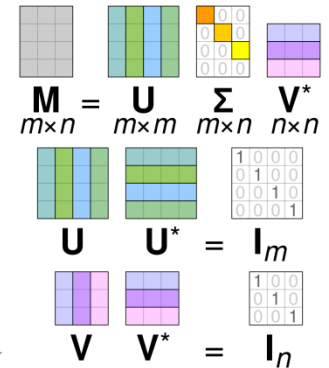
› advantage

→ SVD numerically more stable (formation of MM^T can cause loss of precision → Läuchli matrix)

→ benefit: SVD provides additional information (accelerator physics)

$$M = U \cdot \Sigma \cdot V^T$$

(M real: $V^* \rightarrow V^T$)



courtesy: Wikipedia

application to BPM data

› construction of BPM matrix M

→ BPM data centered

→ normalization: $\propto \frac{1}{\sqrt{nm}}$

C.X. Wang, SLAC-R-547 (2003)

$$M = \begin{matrix} \xrightarrow{\text{orbit (space coordinate)}} \\ \begin{pmatrix} BPM_1(\text{turn}\#1) & \cdots & BPM_n(\text{turn}\#1) \\ \vdots & \ddots & \vdots \\ BPM_1(\text{turn}\#m) & \cdots & BPM_n(\text{turn}\#m) \end{pmatrix} \\ \downarrow \text{turns (time coordinate)} \end{matrix}$$

› exploration of SVD matrix properties

→ U : column vectors contain information about *temporal* pattern (tune, ...)

→ V : column vectors contain information about *spatial* pattern (orbit / β function, ...)

comment: U/V as temporal/spatial vectors → depends on orientation of matrix M

PCA Example

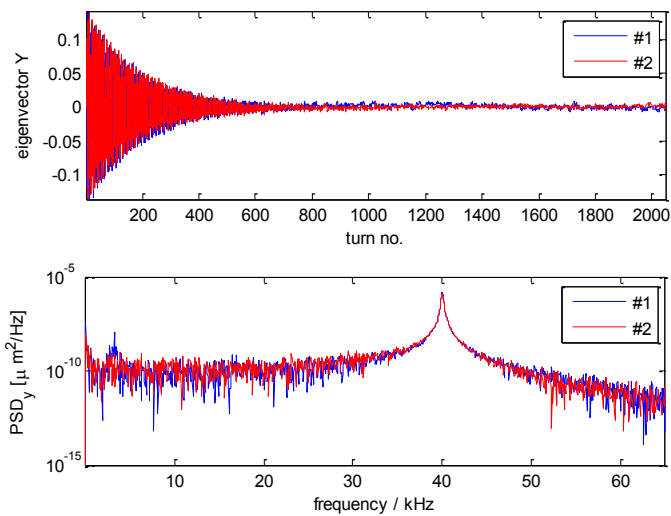
test measurement @ PETRA III

- fill pattern: 960 bunches @ 5.6 mA
- single vertical kick with excitation kicker
- 2048 turns recorded

temporal modes

- information about tune

→ FFT of u_1, u_2

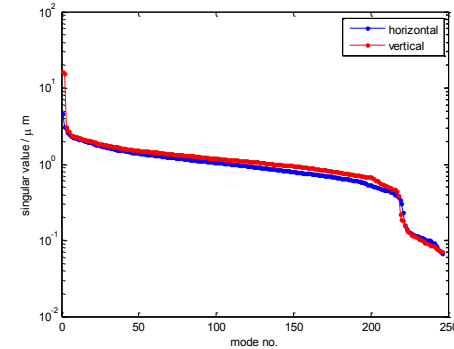


BPM resolution

- singular values $\sigma_1, \sigma_2, \dots = 0$ → calculate cleaned orbit data

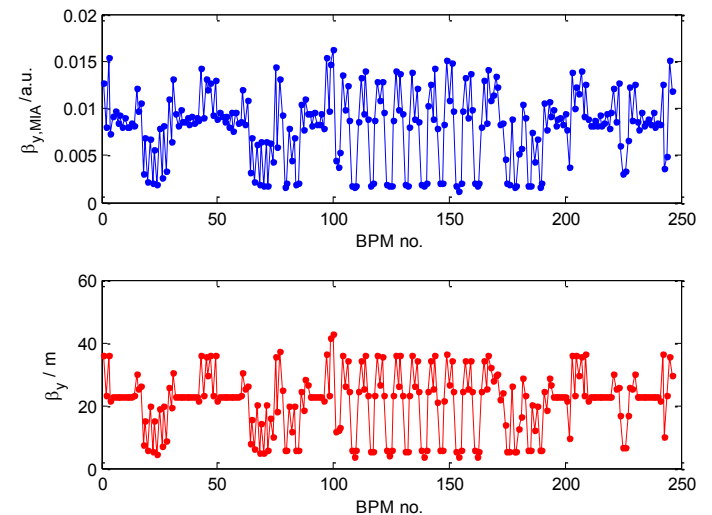
SVD analysis

- dominant modes (singular values) → mode 1 & 2



spatial modes

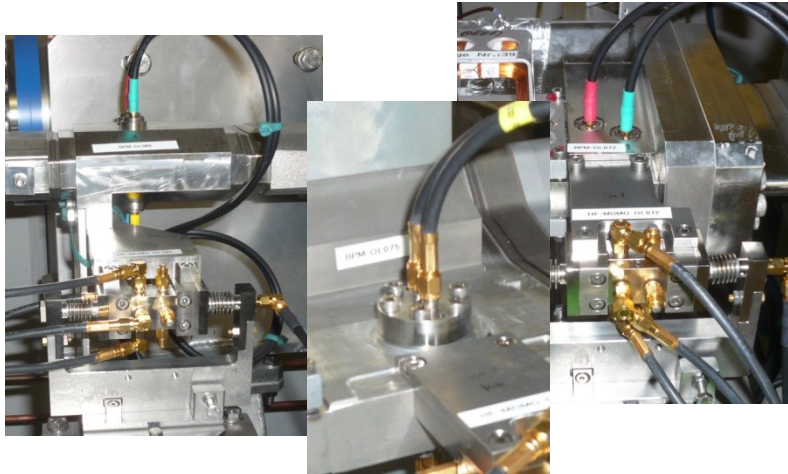
- information about beam optics → $\beta \propto (v_1^2 + v_2^2)$



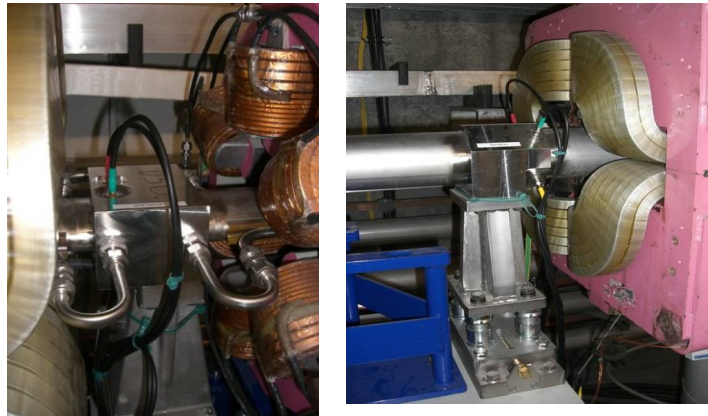
PETRA III BPM System

- 11 different pickup types:

- Max von Laue hall



- standard octants:



- 3 different cable types

RFA $\frac{1}{2}$ ", $\frac{3}{8}$ ", $\frac{7}{8}$ " – 50 Ω



cable lengths: 10m ... 200m



246 individual settings

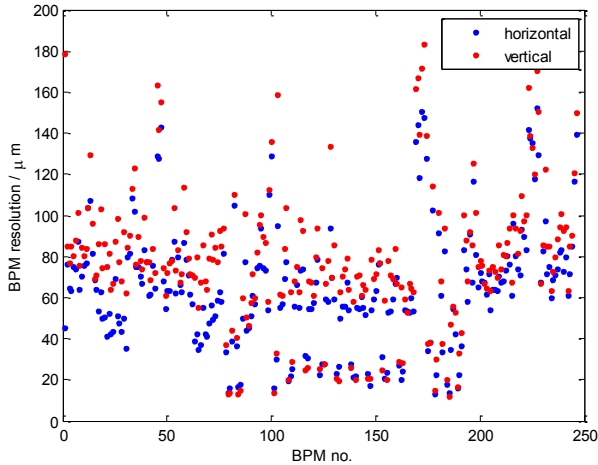


- normalize to $K_{x,y} = 10$ mm
- $RMS_{x,y} = f(\text{signal power})$

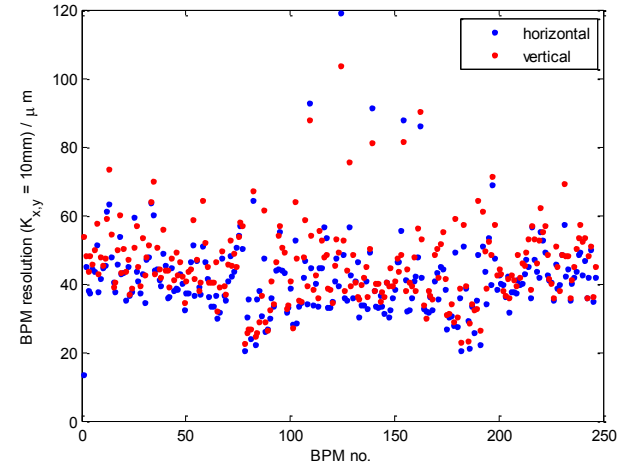
BPM Resolution Studies

- resolution studies @ PETRA III
 - single bunch with Q_b varying
 - single vertical kick with excitation kicker
 - 2048 turns

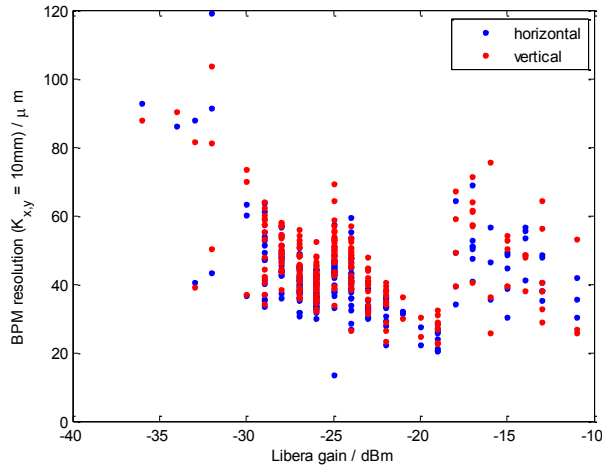
PCA for
beam jitter
removement



$K_{x,y}$
normalization



plot as function
of signal power

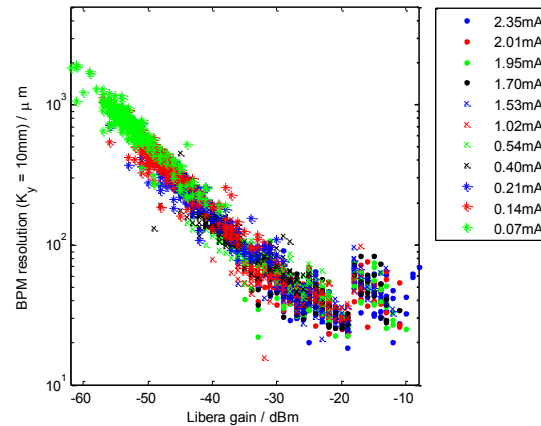
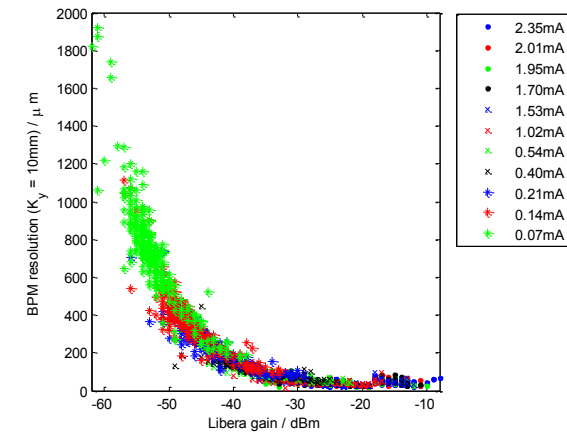


combination of
measurements for
various Q_b

TbT Single Bunch Resolution

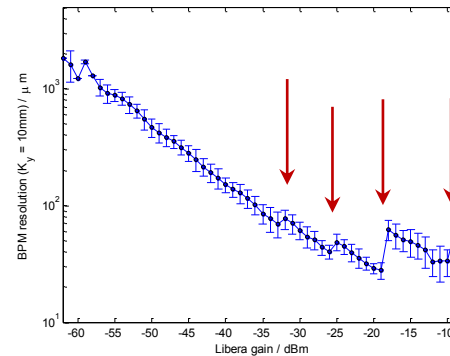
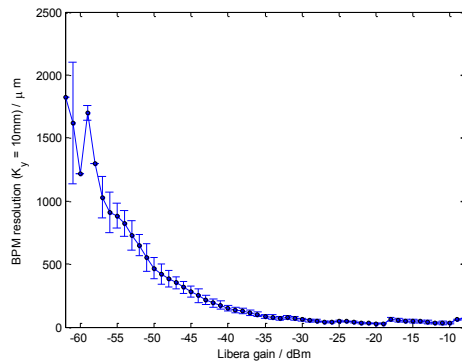
● machine studies at PETRA III with existing BPM system

➤ Libera Brilliance (Instrumentation Technologies)



Default Gain Scheme for 500 MHz Libera Brilliance

W [dBm]	A1	A2	h	t	X [mm]	Y [mm]
0	31	00	0.5	10	0	0
-1	31	00	0.5	10	0	0
-2	31	00	0.5	10	0	0
-3	31	00	0.5	10	0	0
-4	31	00	0.5	10	0	0
-5	31	00	0.5	10	0	0
-6	31	00	0.5	10	0	0
-7	31	00	0.5	10	0	0
-8	31	00	0.5	10	0	0
-9	31	00	0.5	10	0	0
-10	21	00	0.5	10	0	0
-11	21	00	0.5	10	0	0
-12	21	00	0.5	10	0	0
-13	21	00	0.5	10	0	0
-14	21	00	0.5	10	0	0
-15	21	00	0.5	10	0	0
-16	21	00	0.5	10	0	0
-17	21	00	0.5	10	0	0
-18	21	00	0.5	10	0	0
-19	11	00	0.5	10	0	0
-20	11	00	0.5	10	0	0
-21	11	00	0.5	10	0	0
-22	11	00	0.5	10	0	0
-23	11	00	0.5	10	0	0
-24	11	00	0.5	10	0	0
-25	7	00	0.5	10	0	0
-26	7	00	0.5	10	0	0
-27	7	00	0.5	10	0	0
-28	7	00	0.5	10	0	0
-29	7	00	0.5	10	0	0
-30	7	00	0.5	10	0	0
-31	7	00	0.5	10	0	0
-32	7	00	0.5	10	0	0
-33	0	00	0.5	10	0	0
-34	0	00	0.5	10	0	0



$$\min(RMS_{x,y}) \approx 30 \mu\text{m}$$

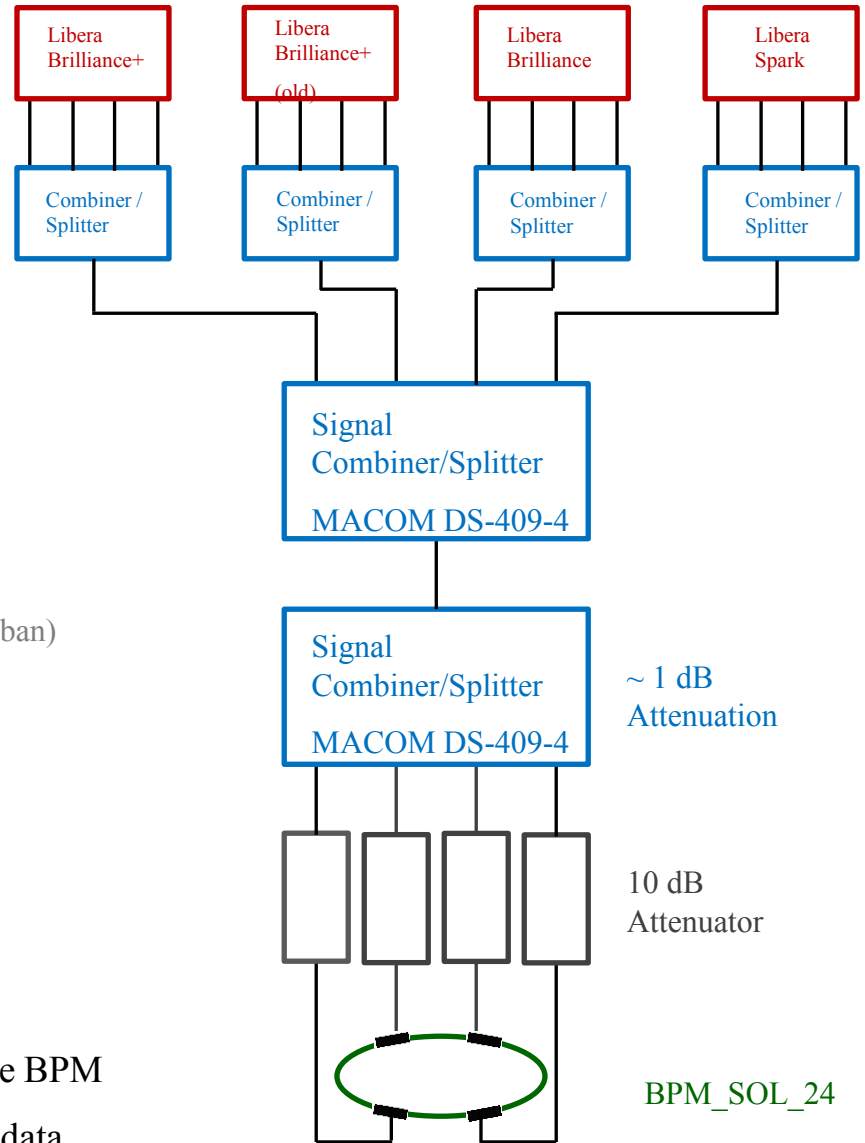


Libera Brilliance resolution not sufficient for PETRA IV

● PETRA IV CDR: rely on successor model → Libera Brilliance+

Test of Read-out Electronics

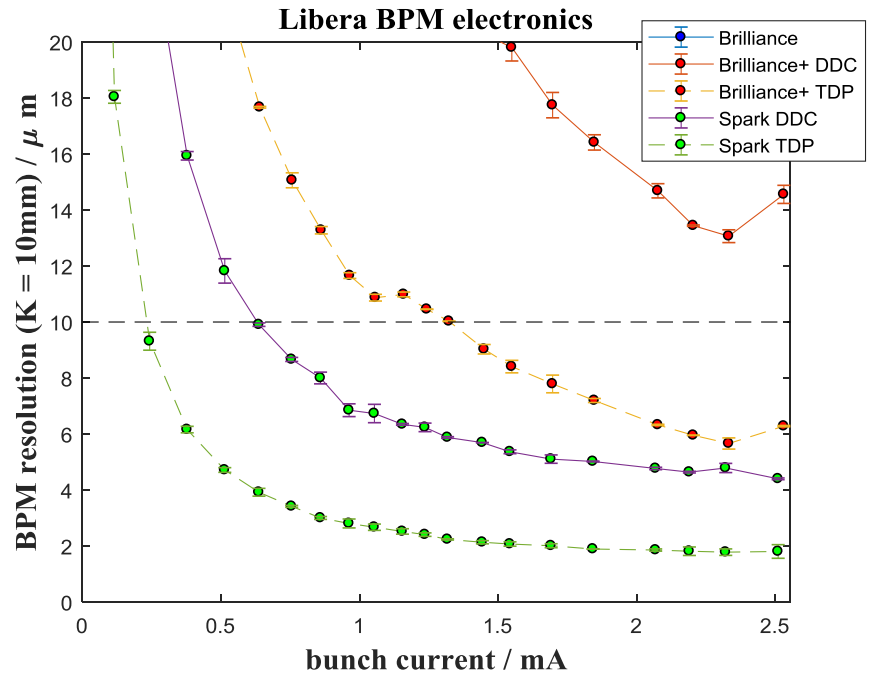
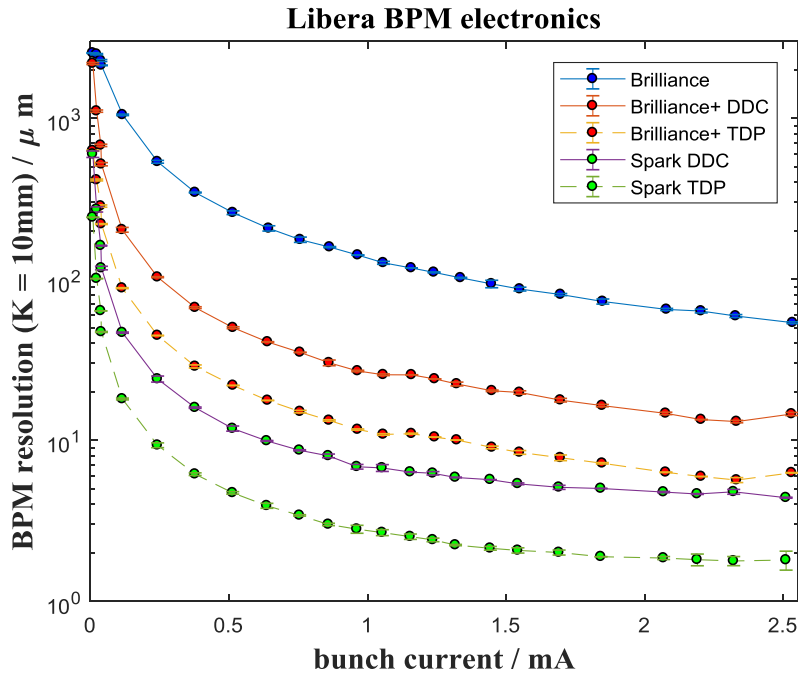
- beam test @ PETRA III: december 2018
 - › Libera Brilliance
 - BPM_SOL_24, in use at PETRA III
 - › Libera Brilliance+
 - CDR: PETRA IV system
 - one system bought for DORIS / Olympus
 - one system recently bought
 - › Libera Spark
 - new platform, no long-term stabilization
 - borrowed from I-Tech (thanks to Peter Leban)
- BPM TbT resolution determination
 - › orbit data contain contributions due to
 - correlated beam jitter
 - noise of BPM electronics
- disentangle contributions
 - › correlation analysis → does not work for single BPM
 - › eliminate correlated jitter → sum & split orbit data



Resolution Comparison



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Libera Brilliance+

digital down conversion (DDC)

$\sigma < 10 \mu\text{m}$ never achieved

$\sigma = 19.8 \mu\text{m}$ @ $I_B = 1.549 \text{ mA}$ (-29 dB)

→ correct for attenuation: $I_B = 0.38 \text{ mA}$ ($\approx -42 \text{ dB}$)

time domain processing (TDP)

$\sigma = 10.3 \mu\text{m}$ @ $I_B = 1.323 \text{ mA}$ (-30 dB)

→ correct for attenuation: $I_B = 0.38 \text{ mA}$



DDC mode	$< 20 \mu\text{m}$ (rms)	→	$I_B \approx 0.4 \text{ mA}$
TDP mode	$\approx 10 \mu\text{m}$ (rms)	→	$I_B \approx 0.4 \text{ mA}$

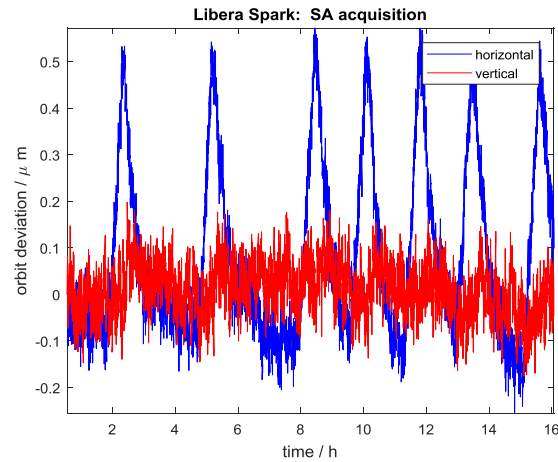
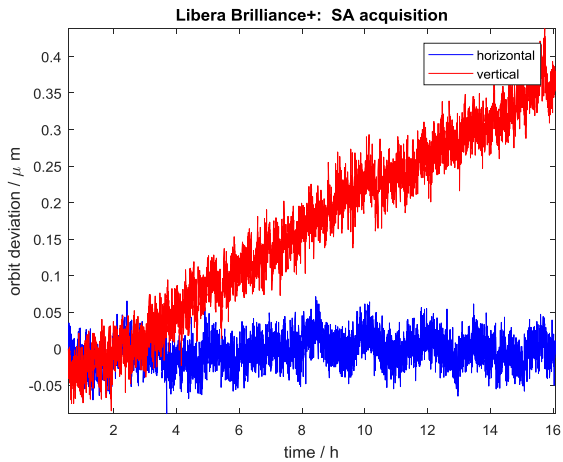
would fulfil requirements

→ but Libera Spark is better...

Closed Orbit & Stability

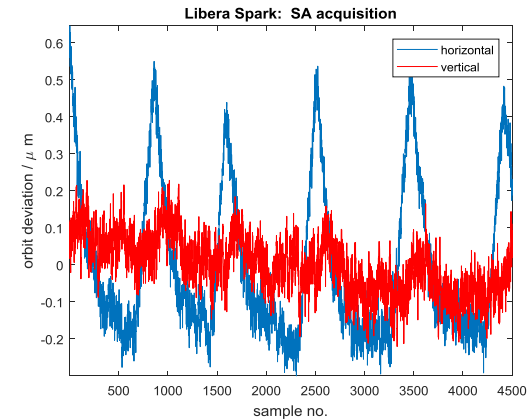
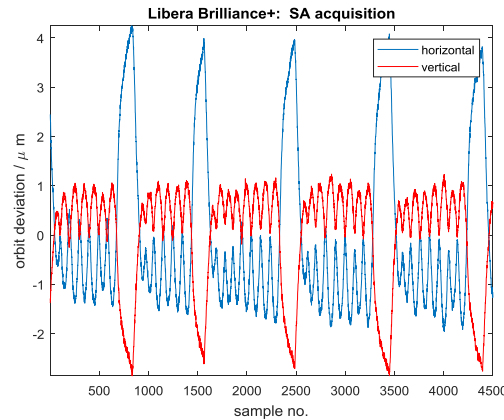
long term stability

- user operation: 480 bunches in 100 mA, top-up
- all Liberas in closed orbit (SA) mode → drift compensation (digital signal conditioning, DSC) on



Spark:
no DSC available

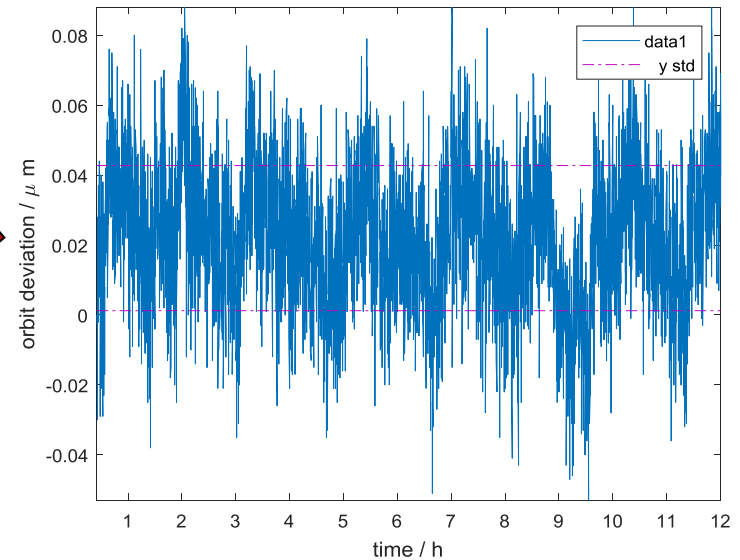
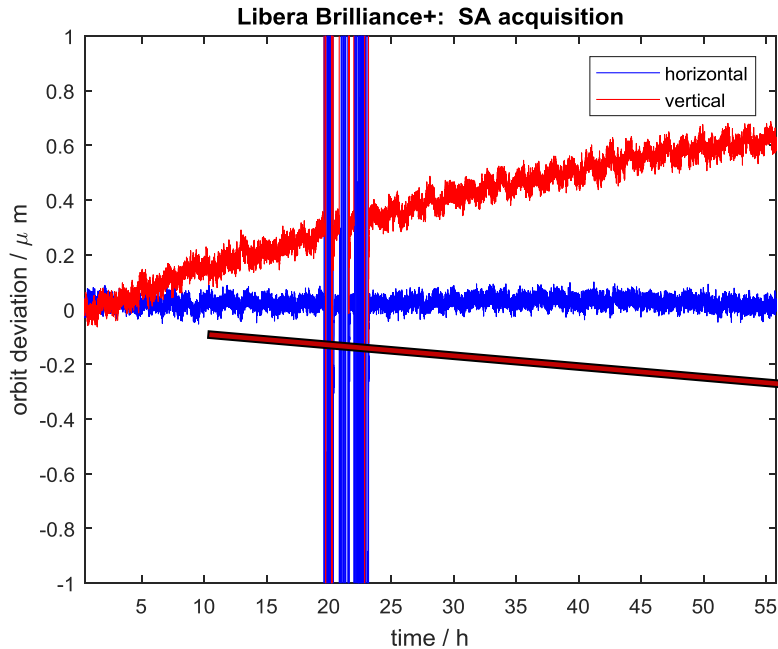
Brilliance+ without DSC



good climatization (hutches, racks) mandatory

Closed Orbit Resolution

- specification: $< 100\text{nm (rms)}$ in *brightness mode* (200mA in 1600 bunches) @ BW 300 Hz



horizontal orbit

first 12 hours (before beam dump):

$\sigma_{rms} = 20.76\text{ nm}$ in SA mode (BW 4Hz, $K_{x,y} = 10\text{mm}$; BW 4Hz → see Brilliance+ User Manual, p.34)

→ scaling with band width:

× $\sqrt{300/4} = 8.66$

→ $\sigma_{rms} = 180\text{ nm}$ (@ BW 300Hz)

Name of the data flow	Type	Buffer size*	Rate	Bandwidth
ADC rate data	on demand	1 M atoms (8 MB)	ADC freq.	~20 MHz
Turn-by-Turn (DDC)	on demand	2 M atoms (64 MB)	rev.freq	0.35*rev.freq
Turn-by-Turn (TDP)	on demand	2 M atoms (64 MB)	rev.freq	
Fast Acquisition data	stream		10 kS/s	2 kHz
Slow Acquisition data	stream		10 S/s	4 Hz

Conclusion

● BPM resolution studies

- › require correlation analysis in order to disentangle noise and beam generated jitter
 - „three BPM“ correlation method & PCA

● correlation analysis

- › „three BPM“ correlation method → not suitable for PETRA III BPM system
- › PCA → powerful tool, not only for resolution studies (e.g. BPM performance evaluation @ SSRF, ...)
 - model independent, but limited by mode mixing

Z.-C. Chen et al., Chinese Physics **38** (2014) 077004

Nucl. Sci and Tech. **25** (2014) 020102



next step: Independent Component Analysis (ICA)

● Libera Brilliance

- › single bunch resolution → specs not fulfilled for PETRA IV

● Libera Brilliance+

- › single bunch resolution → specs fulfilled @ bunch current $I_B \approx 0.4$ mA and monitor constant $K_{x,y} = 10$ mm

DDC mode < 20 μ m (rms), TDP mode ≈ 10 μ m (rms)

- › closed orbit → specs not fulfilled (< 100 nm @ 300 Hz bandwidth)

$\sigma_{y,rms} \approx 180$ nm @ 300 Hz bandwidth and $K_{x,y} = 10$ mm

● Libera Spark

- › single bunch resolution much better → closed orbit: needs stabilization