# **Deep learning in Lattice 1+1d Scalar Field Theory**

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In collaboration with:

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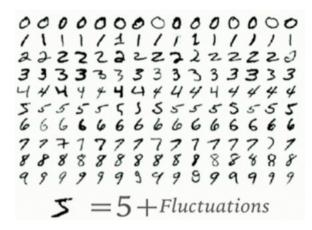


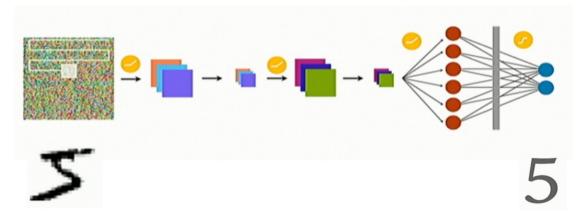




#### Introduction

 Convolutional Neural Network has proved to be extremely powerful in Pattern Recognition, Image Classification





• Discriminative learning (prediction): Classification, Regression Generative modelling (generation): RBM, VAE, GAN

# 1+1d $\lambda \phi^4$ field (prepare training set)

#### regularization of continuum Action:

$$S^{\text{lat}} = \sum_{x} \left\{ (4 + m^2) \phi^*(x) \phi(x) + \lambda [\phi^*(x) \phi(x)]^2 - \sum_{\nu=1,2} \left[ e^{\mu \delta_{\nu,2}} \phi^*(x) + \hat{\nu}) + e^{-\mu \delta_{\nu,2}} \phi^*(x) \phi(x - \hat{\nu}) \right] \right\}$$

### **Partition sum:**

$$\mathcal{Z} = \int D[\phi] exp\left(-S^{\mathrm{lat}}[\phi]
ight)$$

#### **Dualization approach:**

$$\mathcal{Z} = \sum_{\{k,\ell\}} \prod_{n} \left\{ e^{\mu k_t(n)} \cdot W[s(n)] \cdot \delta[\nabla \cdot k(n)] \cdot \prod_{\nu} A[k_{\nu}(x), \ell_{\nu}(x)] \right\}$$

$$W[s(n)] = \int_0^\infty dr \, r^{s(n)+1} \, e^{-(4+m^2)r^2 - \lambda r^4}$$
$$s(n) = \sum_{\nu} \left[ |k_{\nu}(n)| + |k_{\nu}(n-\hat{\nu})| + 2(\ell_{\nu}(n) + \ell_{\nu}(n-\hat{\nu})) \right]$$

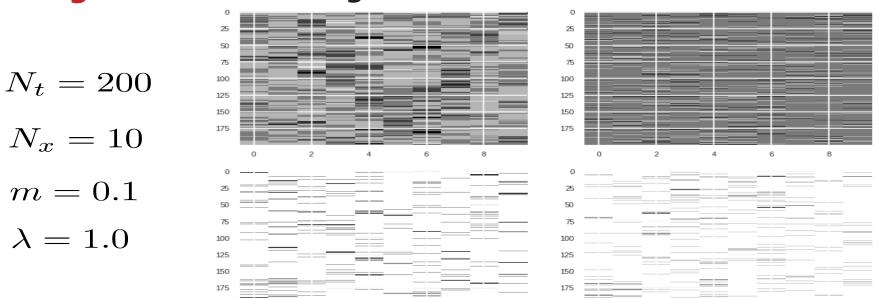
$$s(n) = \sum_{\nu} [|k_{\nu}(n)| + |k_{\nu}(n - \hat{\nu})| + 2(\ell_{\nu}(n) + \ell_{\nu}(n - \hat{\nu})]$$

$$A[k_{\nu}(x), \ell_{\nu}(x)] = \frac{1}{(\ell_{\nu}(n) + |k_{\nu}(n)|)! \ \ell_{\nu}(n)!}$$
**C. Gattringer** and T. Kloiber, Nucl. Phys. B869 (2013) 56-73

**O. Orasch** and C. Gattringer, Int. J.Mod.Phys.A33(2016) no.01,1650010,

# **Configurations - Dualization approach**

Configurations - 4 integer-valued variables :  $k_t$ ,  $k_x$ ,  $l_t$ ,  $l_x$ 



### **Divergence constraint:**

$$\nabla \cdot k(n) = \sum [k_{\nu}(n) - k_{\nu}(n - \hat{\nu})] = 0$$

# Observables: m and $|\phi|^2$

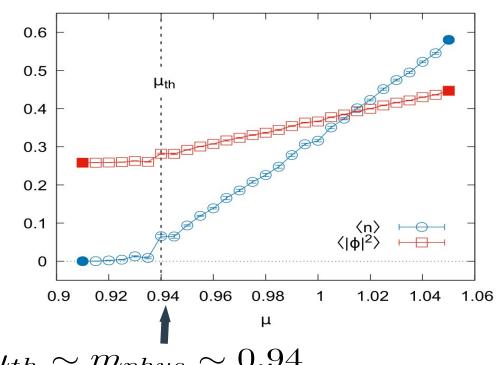
#### **Grand canonical ensemble**

$$\langle n \rangle = \frac{T}{L} \frac{\partial \log \mathcal{Z}}{\partial \mu}$$

$$n = \frac{1}{N_x N_t a} \sum_n k_t(n)$$

$$\langle |\phi|^2 \rangle = \frac{T}{L} \frac{\partial \log \mathcal{Z}}{\partial (m^2)}$$
$$|\phi|^2 = \frac{1}{N_x N_t} \sum_n \frac{W[s(n) + 2]}{W[s(n)]}$$

#### Condensation sets in at



# **Exploring NN application here**

(1) Classification : detect 'phase transition' status based on configs (identify **order parameter**)

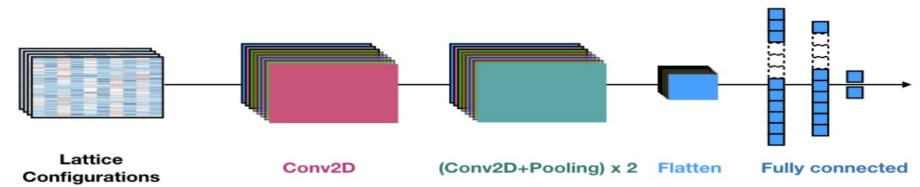
(2) Regression : physical observables regression (identify **thermodynamics**)

(3) GAN(generate): Learn to generate new configurations

Generate configs with proper distribution

(identify partition function)

#### **DCNN Architechture - Classification**

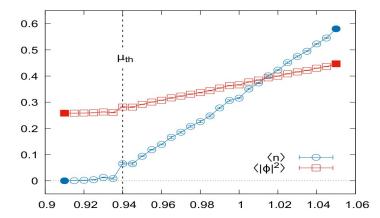


# Training set consists of two ensembles of configurations @

$$\mu = 0.91$$
 with label  $y = (0, 1)$ 

#### and

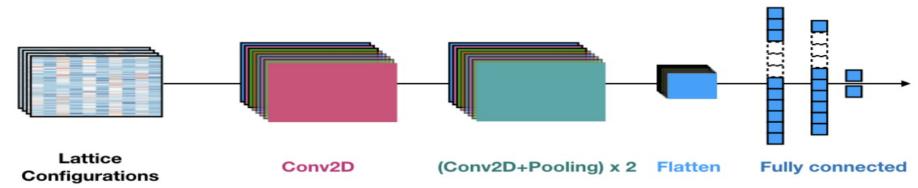
$$\mu = 1.05$$
 with label  $y = (1,0)$ 



**QM 2019, Wuhan** 

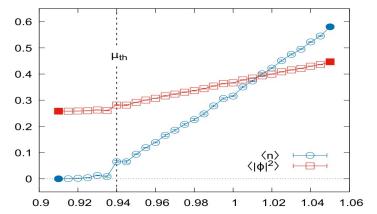
05 Nov, Kai Zhou

#### **DCNN Architechture - Classification**

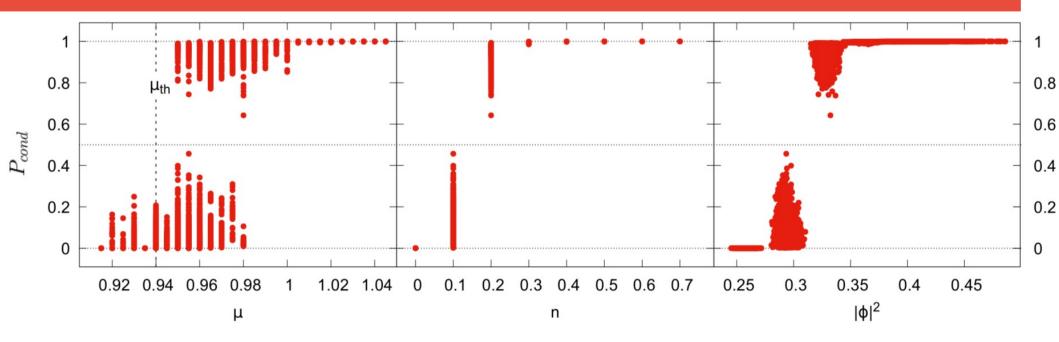


Testing set consists of different ensembles of configurations @ different chemical potential

$$0.91 < \mu < 1.05$$



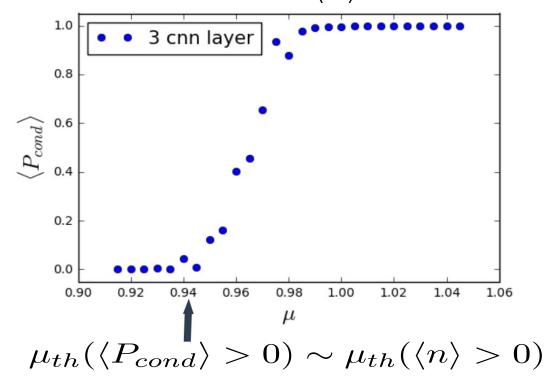
## Condensation probability from DCNN



# Strong correlation between P\_cond and observables : n , squared field

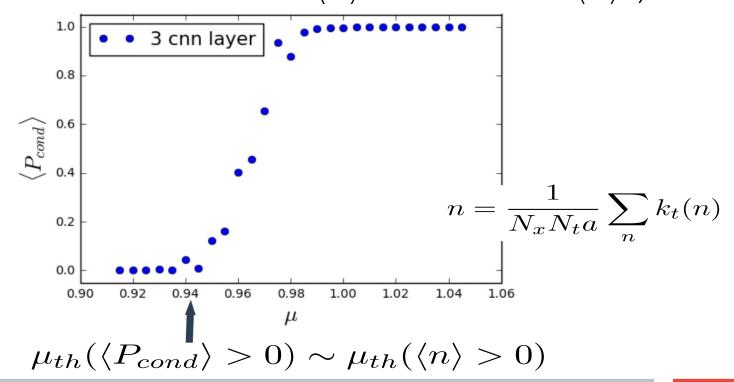
# **Ensemble average cond-probability**

Classifier of the phases:  $\langle n \rangle = 0$  and  $\langle n \rangle \neq 0$ 



# **Ensemble average cond-probability**

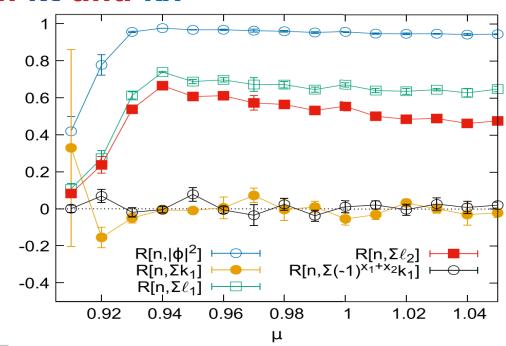
Classifier of the phases:  $\langle n \rangle = 0$  and  $\langle n \rangle \neq 0$ 



#### **Discard kt information**

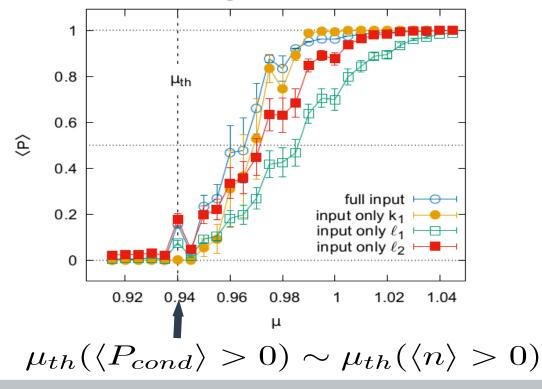
# There's finite correlation between kt and $\ell$ variable, But, No correlation between kt and kx

$$R[A, B] \equiv \frac{\langle AB \rangle - \langle A \rangle \langle B \rangle}{\sqrt{\langle A^2 \rangle - \langle A \rangle^2} \sqrt{\langle B^2 \rangle - \langle B \rangle^2}}$$



## **Ensemble average cond-probability**

## The same transition point came out, even use only kx!



# **Beyond conventional analysis:**

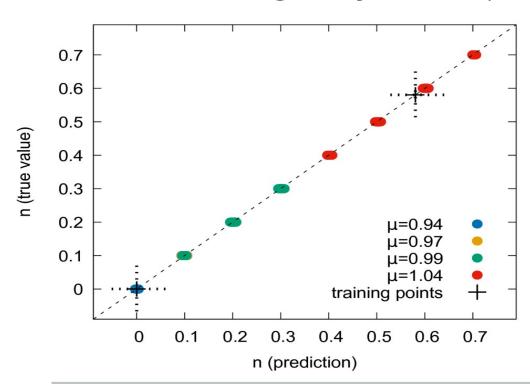
Indicating existence of novel correlation between kx and n

#### **Regression for particle density** n

Note, for training, only used  $\mu = 0.91$ 

$$\mu = 0.91$$
 and

and  $\mu = 1.05$ 



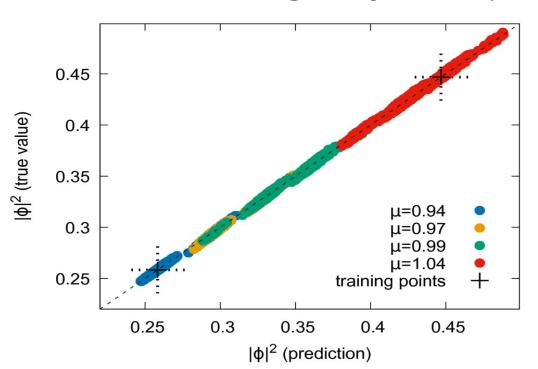
$$n = \frac{1}{N_x N_t a} \sum_{n} k_t(n)$$

RMSE < 0.003

# **Regression for squared field**

Note, for training, only used  $~\mu=0.91~$  and  $~\mu=1.05$ 

 $||\phi|^2$ 



$$|\phi|^2 = \frac{1}{N_x N_t} \sum_n \frac{W[s(n) + 2]}{W[s(n)]}$$

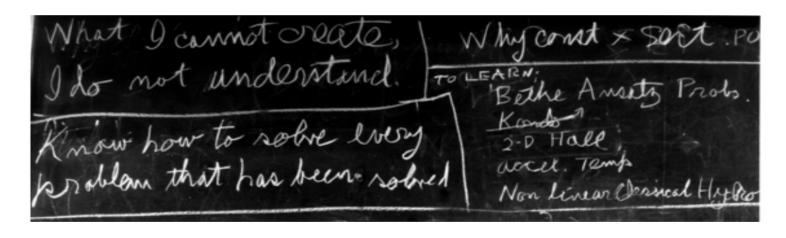
$$W[s(n)] = \int_0^\infty dr \, r^{s(n)+1} \, e^{-(4+m^2)r^2 - \lambda r^4}$$

$$s(n) = \sum_{\nu} \left[ |k_{\nu}(n)| + |k_{\nu}(n - \hat{\nu})| + 2(\ell_{\nu}(n) + \ell_{\nu}(n - \hat{\nu})) \right]$$

RMSE < 0.005

#### **Generate** new ones





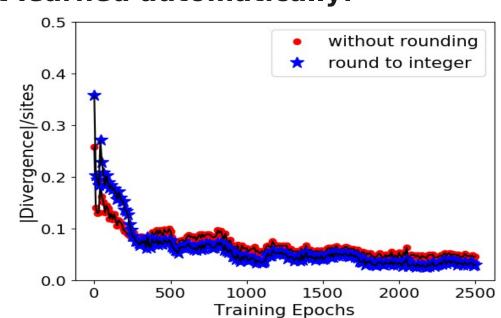
"What I can not create, I do not understand"

# **GAN** - generate proper configurations

#### The divergence condition get learned automatically:

'Physical' configs can be generated

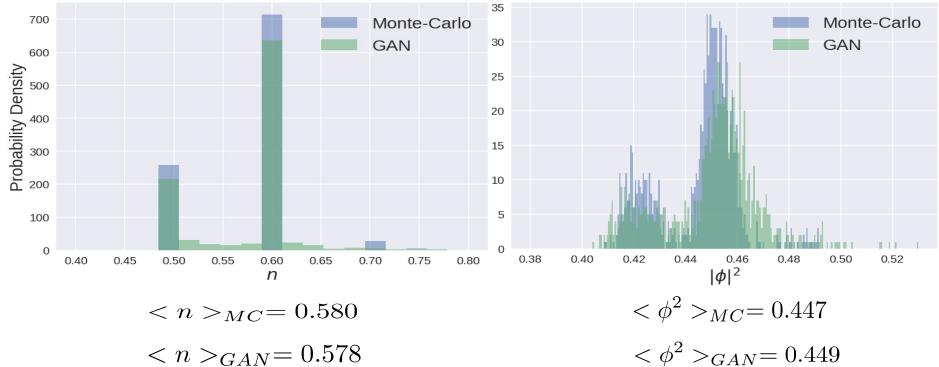
$$\nabla \cdot k(n) = \sum_{\nu} [k_{\nu}(n) - k_{\nu}(n - \hat{\nu})] = 0$$



Automatically capture the implicit physical constraint!

#### **Distribution for observables**

#### Histogram distribution with 1k configuratoins (after 6k trainig epochs):

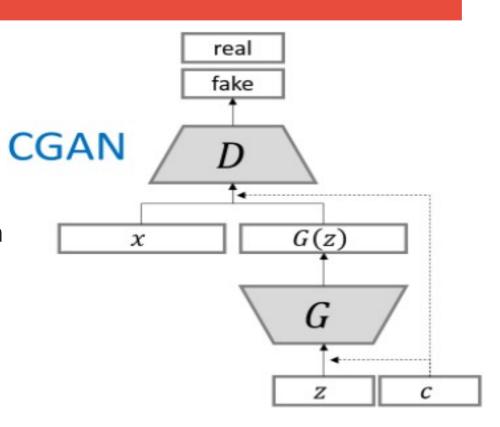


### add conditional information of n

make GAN conditional on particle density n:

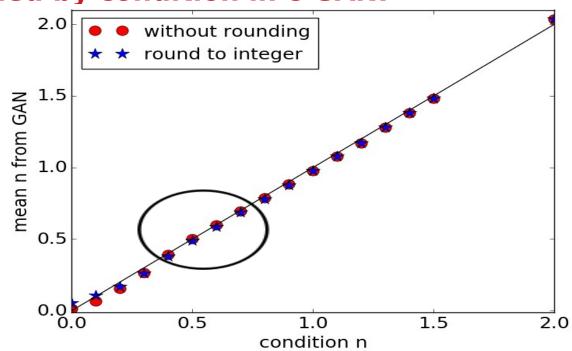
We train GAN using one ensemble with  $\mu=1.05$  labeled as well with n (including n=0.4, 0.5, 0.6, 0.7)

Once trained, we specify different n values in generation stage



### **Conditional GAN - control n**

mean value for n and squared field of generated ensemble is controlled by condition in c-GAN.



## **Summary**

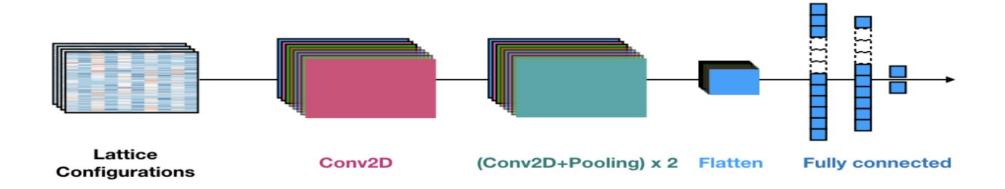
```
(1) Classification: pin down phase 'transition' point
                   (identify order parameter)
(2) Regression: learn physical observable (non-linear regression)
                   (identify thermodynamics)
(3) GAN(generative): use GAN to generate new physical configuration
                    Capture/reproduce data distribution ( use for storage )
                    limited grand canonical --> canonical ensemble
                    limited configs. --> explore phase diagram
                    (identify partition function)
```

**Needs more exploration!** 

**QM 2019, Wuhan** 

# Thanks!

### **DCNN Architechture - Classification**



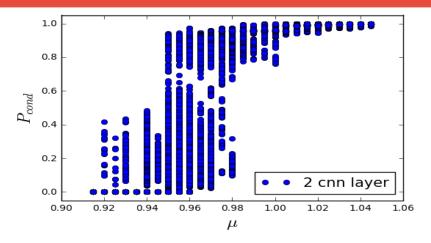
$$\mathcal{L} = -\frac{1}{N} \sum_{i=1}^{N} [y_i \log \hat{y}_i + (1 - y_i) \log(1 - \hat{y}_i)] + \lambda \|\theta\|_2^2$$

 $\alpha_{lr} = 0.0001$ 

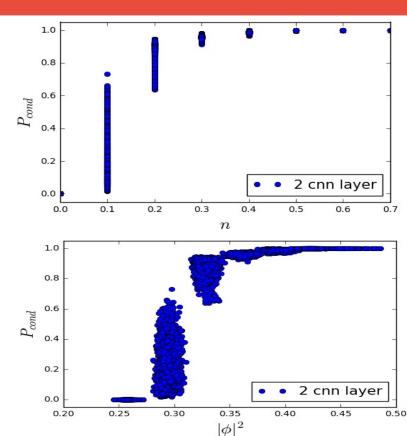
With

AdaMax optimization scheme

# **Condensation probability from CNN**



Deleting one CNN layer off gives slightly worse distinguish ability



# **GAN - Nash Equilibrium**

#### Zero-sum game - Nash equilibrium

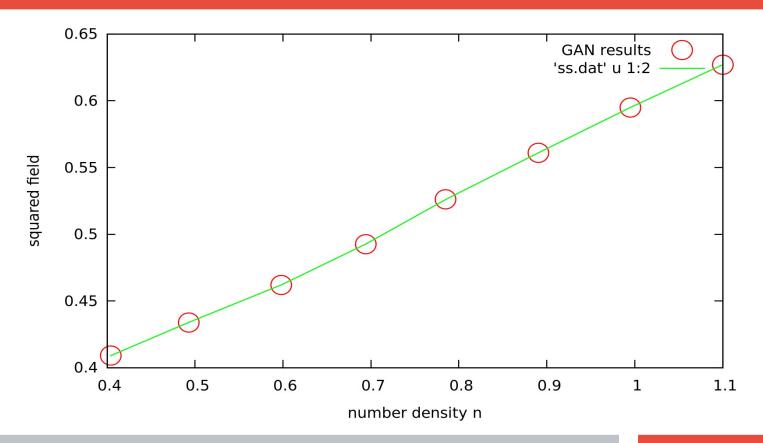
$$G^* = \arg\min_{G} \max_{D} (-\mathcal{L}_D(G, D))$$

$$\mathcal{L}_D = -\mathbb{E}_{\hat{x} \sim p_r(\hat{x})}[\log(D(\hat{x}))] - \mathbb{E}_{z \sim p(z)}[\log(1 - D(G(z)))]$$

$$\mathcal{L}_G = \mathbb{E}_{z \sim p(z)}[\log(1 - D(G(z)))]$$

$$D^*(\hat{x}) = \frac{p_r(\hat{x})}{p_r(\hat{x}) + p_g(\hat{x})}$$

## **GAN** - distribution



**QM 2019, Wuhan** 

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