

INCLUDING MOMENTUM AND STRESS IN A SYSTEMATIC FRAMEWORK FOR UNDERSTANDING THE EVOLUTION OF A HEAVY-ION COLLISION

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work in progress with Jefferson de Souza and Jorge Noronha

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INTRODUCTION

- Heavy-ion collision: complicated, non-linear evolution
- Simple observed relations, e.g.,

$$v_n = \kappa_n \varepsilon_n$$

- Until now: only considered energy / entropy in initial state
- Goal: include effects from other components of $T^{\mu\nu}$.
- Motivation: determine relevant aspects, quantify contribution & interplay with eccentricity (important in small systems?)

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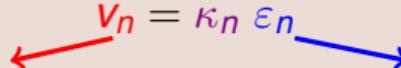
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The diagram illustrates the relationship between three states: Final State, Response, and Initial State. A red arrow points from 'Final State' to 'Response', with the equation $v_n = \kappa_n \varepsilon_n$ written above it. A blue arrow points from 'Response' to 'Initial State'.

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- ① Reminder: $v_n = \kappa_n \varepsilon_n$ as leading term in systematic expansion
- ② Ansatz for adding $T^{\mu\nu}$ contributions
- ③ Numeric validation

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CUMULANT EXPANSION: ENERGY DENSITY

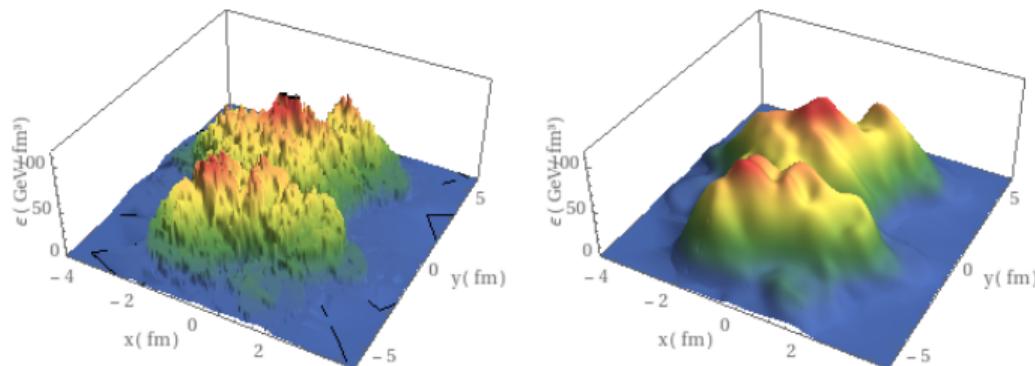
- $E \frac{dN}{d^3 p} \Big|_{\text{final}} = \frac{N}{2\pi} \sum_{n=-\infty}^{\infty} V_n e^{-in\phi}$
- Assumption 1: $V_n = \mathcal{F} \left(T^{\mu\nu} \Big|_{\tau=\tau_0}, j^\mu \Big|_{\tau=\tau_0} \right)$
 - $T^{\mu\nu}, j^\mu$ at some time τ_0 determines final observable
- Assumption 2: Hierarchy of scales
 - Structure at large length scales more important

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CUMULANTS

- Separate scales with Fourier transform

$$e^{W(\vec{k})} \equiv \int d^2x \ e^{i\vec{k}\cdot\vec{x}} T^{\tau\tau}(x, y)$$

- Isolate large scales with Taylor series around $k = |\vec{k}| = 0$

$$W(\vec{k}) = \sum_{m=0}^{\infty} W_m(\phi_k) k^m = \sum_{n=-\infty}^{\infty} \sum_{m=|n|}^{\infty} W_{n,m} k^m e^{in\phi_k}$$

- System fully characterized by *ordered* set $\{W_{n,m}\}$
- Smaller $m \implies$ larger length scales \implies can truncate at some $m = m_{\max}$.
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- $V_n \simeq f(\{W_{n,m}\}_{m \leq m_{\max}})$

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- $V_n = f(\{W_{n,m}\})$
- Power series in anisotropic ($n \neq 0$) cumulants:

$$V_n \simeq V_n^{(\text{est})} = \begin{aligned} &\text{linear} \\ &+ \text{quadratic} \\ &+ \text{cubic} + \dots \end{aligned}$$

- Double expansion — small m ; lower powers of anisotropic cumulants W
- (No guidance for which type of correction more important)

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$$V_n \simeq V_n^{(\text{est})} = \kappa_{n,n} W_{n,n} + \kappa_{n,n+2} W_{n,n+2} + \kappa_{n,n+4} W_{n,n+4}$$

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- V_n dimensionless, $W_{n,m}$ dimensionful
- \Rightarrow compare $W_{n,m}$ to relevant scale(s) to make dimensionless ratios
- E.g., lowest isotropic cumulant $W_{0,2} = \langle r^2 \rangle_\epsilon - |\langle r e^{i\phi} \rangle_\epsilon|^2$
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ECCENTRICITY SCALING

- Lowest order estimators:

$$V_2^{(\text{est})} = \kappa_2 \mathcal{E}_{2,2}$$

$$V_3^{(\text{est})} = \kappa_3 \mathcal{E}_{3,3}$$

- Can be systematically improved (see talk by Mauricio Hippert)

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- (α, β) = transport coefficients

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THOUGHT EXPERIMENT

- Consider a system with only $T^{\tau\tau}$ at some time τ_0
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- At a slightly different time $\tau = \tau_0 + \delta\tau$:

$$T^{\tau\tau}(\tau) = T^{\tau\tau}(\tau_0) + \delta\tau \partial_\tau T^{\tau\tau}|_{\tau_0} + \frac{\delta\tau^2}{2} \partial_\tau^2 T^{\tau\tau}|_{\tau_0} + O(\delta\tau^3)$$

- Other components are generated via conservation of energy/momentum

$$\partial_\tau T^{\tau\tau} = -\partial_i T^{\tau i}$$

$$\partial_\tau^2 T^{\tau\tau} = -\partial_i \partial_\tau T^{\tau i} = \partial_i \partial_j T^{ij}$$

- Final V_n still determined by $\rho(\vec{x}) = T^{\tau\tau}(\tau_0) \simeq T^{\tau\tau}(\tau) + \delta\tau \partial_i T^{\tau i}(\tau_0) - \frac{\delta\tau^2}{2} \partial_i \partial_j T^{ij}(\tau_0)$

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$$\partial_\tau T^{\tau\tau} = -\partial_i T^{\tau i}$$

$$\partial_\tau^2 T^{\tau\tau} = -\partial_i \partial_\tau T^{\tau i} = \partial_i \partial_j T^{ij}$$

- Final V_n still determined by $\rho(\vec{x}) = T^{\tau\tau}(\tau_0) \simeq T^{\tau\tau}(\tau) + \delta\tau \partial_i T^{\tau i}(\tau_0) - \frac{\delta\tau^2}{2} \partial_i \partial_j T^{ij}(\tau_0)$

ADDITIONAL JUSTIFICATION

THOUGHT EXPERIMENT

- Consider a system with only $T^{\tau\tau}$ at some time τ_0
- Cumulant expansion of $\rho(\vec{x}) = T^{\tau\tau}(\tau_0)$ predicts final V_n
- At a slightly different time $\tau = \tau_0 + \delta\tau$:

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- Final V_n still determined by $\rho(\vec{x}) = T^{\tau\tau}(\vec{x}) + \alpha \partial_i T^{\tau i}(\vec{x}) - \beta \partial_i \partial_j T^{ij}(\vec{x})$

GENERALIZED ESTIMATORS

- With this ansatz, we find,

$$V_2^{(\text{est})} = \kappa_2 \mathcal{E}_{2,2}(\alpha, \beta) = -\kappa_2 \frac{\langle r^2 e^{i2\phi} \rangle_\epsilon - 2\alpha \langle r e^{i\phi} \rangle_u - 4\beta \langle 1 \rangle_c - (\langle r e^{i\phi} \rangle_\epsilon - \alpha \langle 1 \rangle_u)^2}{\langle r^2 \rangle_\epsilon - |\langle r e^{i\phi} \rangle_\epsilon|^2}$$

$$\begin{aligned} V_3^{(\text{est})} &= \kappa_3 \mathcal{E}_{3,3}(\alpha, \beta) = -\kappa_3 \frac{\langle r^3 e^{i3\phi} \rangle_\epsilon - 3\alpha \langle r^2 e^{i2\phi} \rangle_u - 12\beta \langle r e^{i\phi} \rangle_c - 2 (\langle r e^{i\phi} \rangle_\epsilon - \alpha \langle 1 \rangle_u)^3}{(\langle r^2 \rangle_\epsilon - |\langle r e^{i\phi} \rangle_\epsilon|^2)^{\frac{3}{2}}} \\ &\quad + \kappa_3 \frac{(\langle r e^{i\phi} \rangle_\epsilon - \alpha \langle 1 \rangle_u) (3\langle r^2 e^{i2\phi} \rangle_\epsilon - 6\alpha \langle r e^{i\phi} \rangle_u - 12\beta \langle 1 \rangle_c)}{(\langle r^2 \rangle_\epsilon - |\langle r e^{i\phi} \rangle_\epsilon|^2)^{\frac{3}{2}}} \end{aligned}$$

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$$U(\vec{x}) \equiv T^{\tau x} + iT^{\tau y}$$

$$C(\vec{x}) \equiv \frac{1}{2} (T^{xx} - T^{yy}) + iT^{xy}$$

$$\langle \dots \rangle_\epsilon = \frac{\int d^2x \dots T^{\tau\tau}(\vec{x})}{\int d^2x T^{\tau\tau}(\vec{x})}$$

$$\langle \dots \rangle_u = \frac{\int d^2x \dots U(\vec{x})}{\int d^2x T^{\tau\tau}(\vec{x})}$$

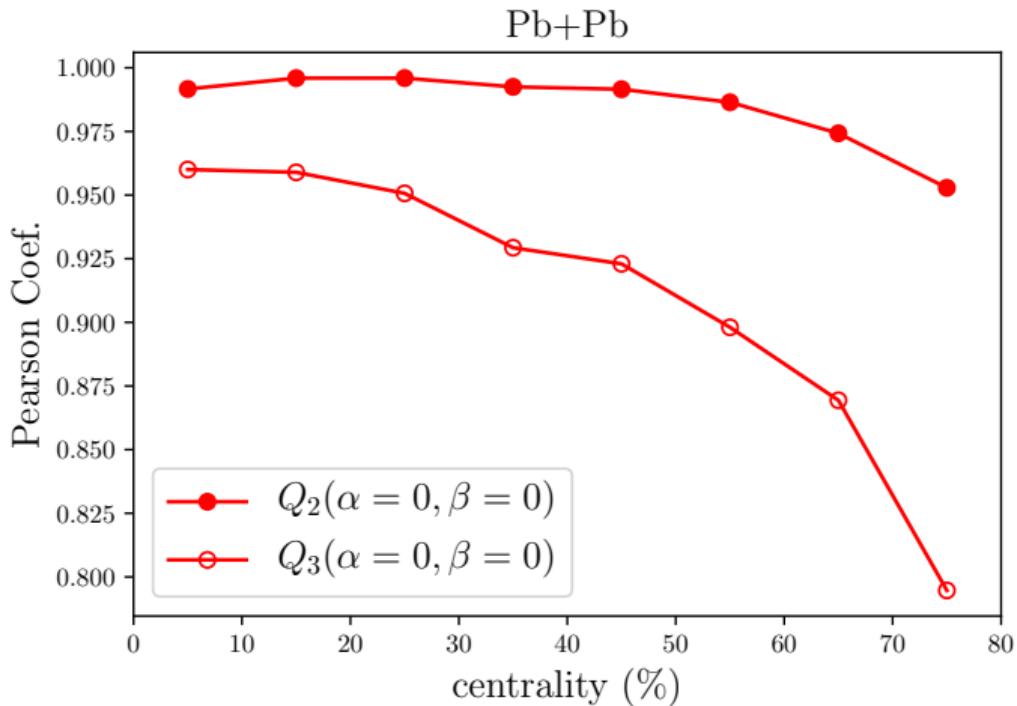
$$\langle \dots \rangle_c = \frac{\int d^2x \dots C(\vec{x})}{\int d^2x T^{\tau\tau}(\vec{x})}$$

NUMERICAL VALIDATION

DOES IT WORK?

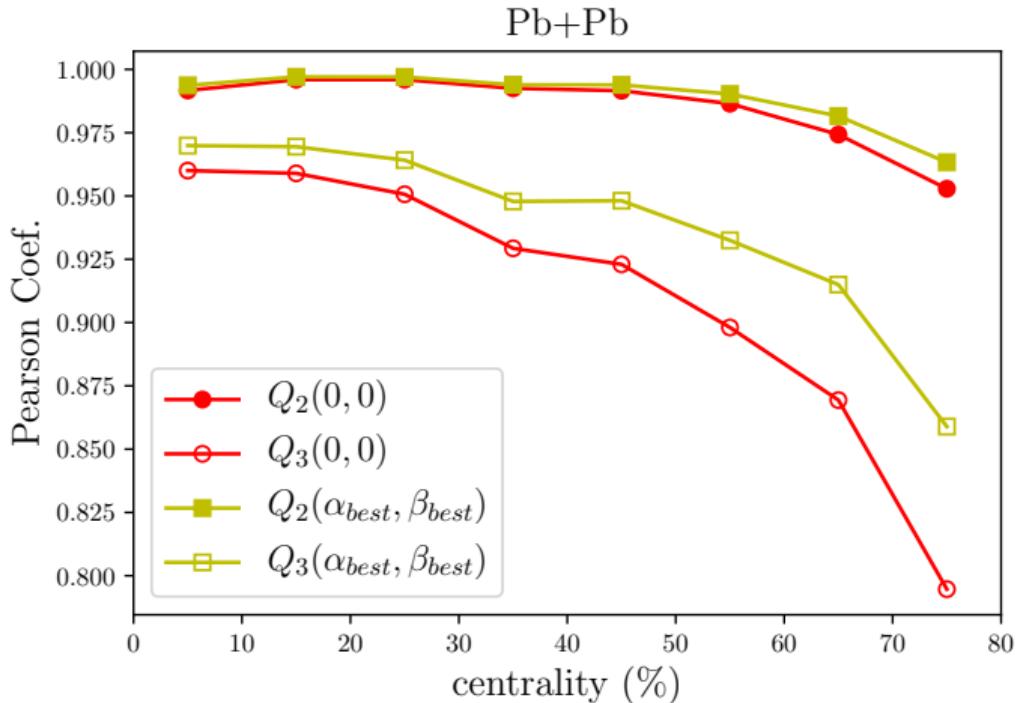
- Check with numerical simulations
 - ① Adjustable toy model (see backup slides)
 - ② Realistic simulations — IP-Glasma + MUSIC + UrQMD
- Quantify the quality of estimator statistically
- Q_n = linear correlation between V_n and $V_n^{(\text{est})}$
 - $Q_n = 1 \implies$ perfect estimator
 - $Q_n = 0 \implies$ no (linear) correlation

NUMERICAL VALIDATION



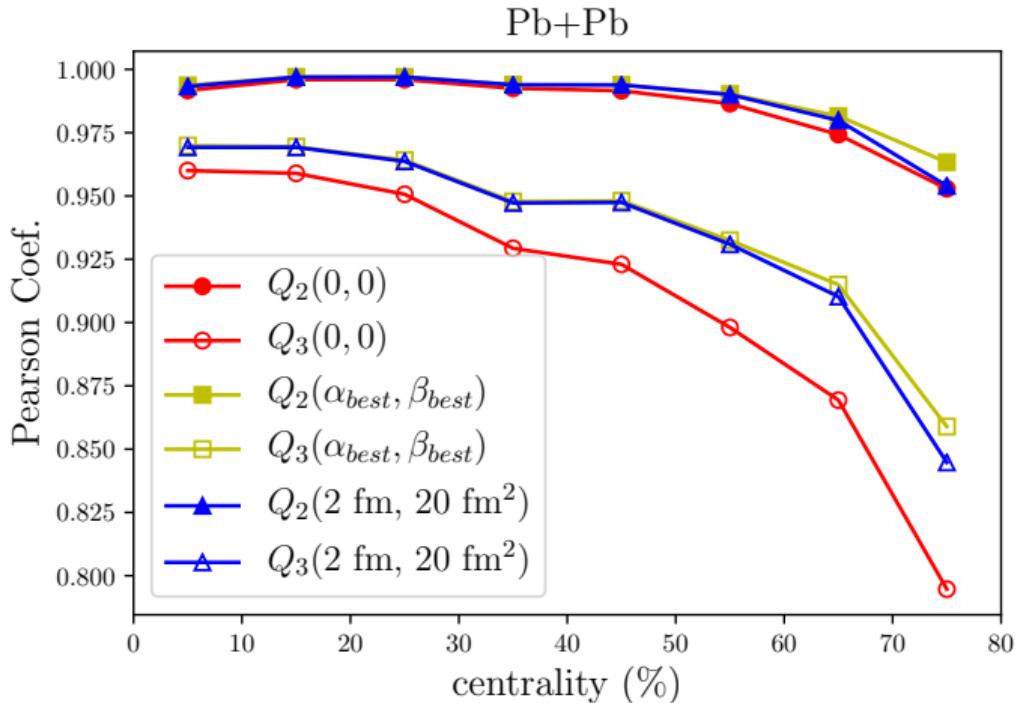
- Traditional \mathcal{E}_n a good estimator
 $\implies T^{\mu\nu}$ contributions small*
- (*Note: Pb-Pb, zero initial viscous tensor)
- Accounting for $T^{\mu\nu}$ improves estimator
- (α, β) independent of harmonic, small dependence on centrality

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SUMMARY

- Cumulant expansion
 - Assuming hierarchy of scales, can make direct connection between final and initial state, isolate effects of system evolution
 - Can be systematically improved — higher cumulants (smaller length scales) and non-linear terms can be relevant.
- Can generalize to include effects of initial $T^{\mu\nu}$
 - Determine the relevant aspects
 - Interplay between spatial and momentum components
- Hybrid hydrodynamic simulations give validation to proposed framework.

ACKNOWLEDGEMENTS



Grants:
16/24029-6, 17/05685-2, 18/24720-6



EXTRA SLIDES

TOY MODEL TESTS

$$T^{00}(\vec{x}) = A e^{-\frac{r^2}{2\sigma^2}(1+a_n \cos n\phi)}$$

$$U(\vec{x}) = T^{0x} + iT^{0y} = |U| e^{\phi_u}$$

$$|U| = r B e^{-\frac{r^2}{2\rho^2}(1-b_n \cos n\phi)}$$

$$\phi_u = \phi - c_n \sin n\phi$$

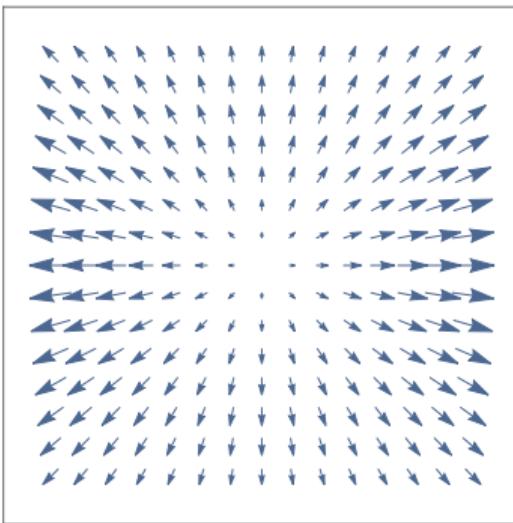
$$C(\vec{x}) = \frac{1}{2}(T^{xx} - T^{yy}) + iT^{xy} = |C| e^{i2\phi_c}$$

$$|C| = r^2 P e^{-\frac{r^2}{2\rho^2}(1-p_n \cos n\phi)}$$

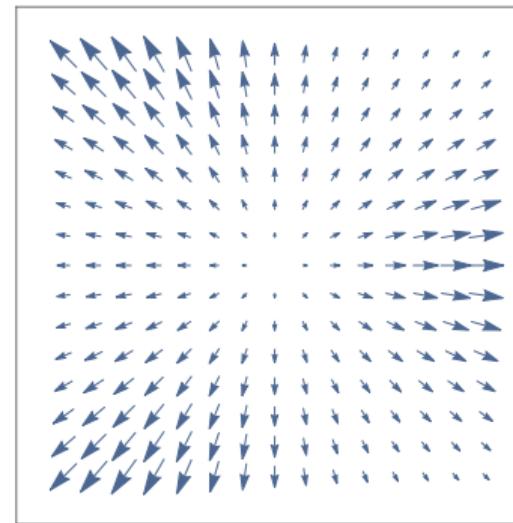
$$\phi_c = \phi - q_n \sin n\phi$$

TOY MODEL MOMENTUM DENSITY

$$|U| = rBe^{-\frac{r^2}{2\rho^2}(1 - b_n \cos n\phi)}$$



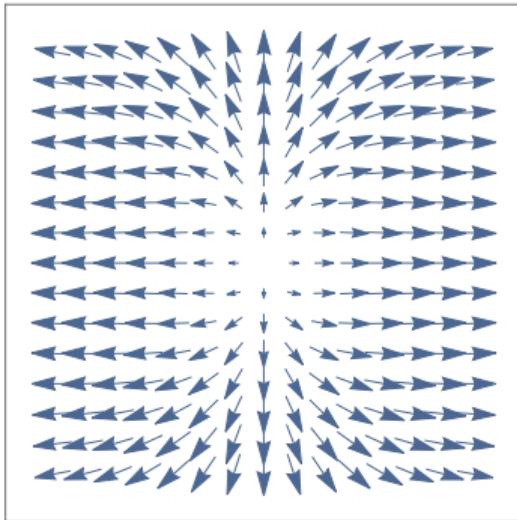
$$b_2 \neq 0$$



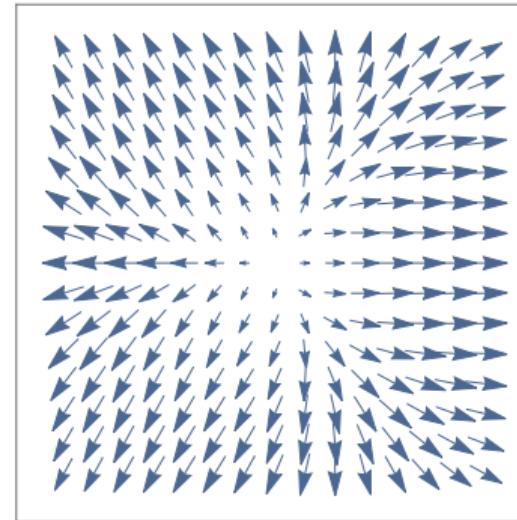
$$b_3 \neq 0$$

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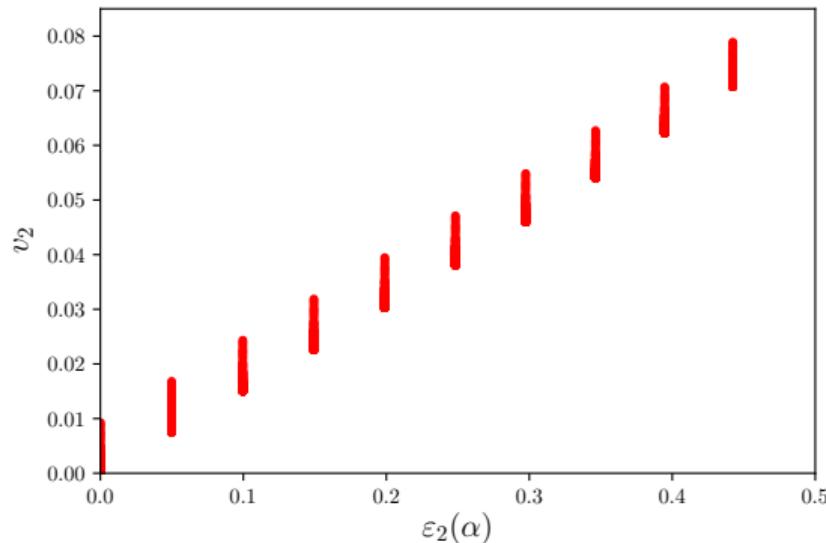


$$c_2 \neq 0$$



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TOY MODEL TESTING



$$v_2 = \kappa_2 \epsilon_2 (\alpha = 0.0 \text{ fm}, \beta = 0.0 \text{ fm}^2)$$

$$T^{00} = A e^{-\frac{r^2}{2\sigma^2}} (1 + a_2 \cos 2\phi)$$

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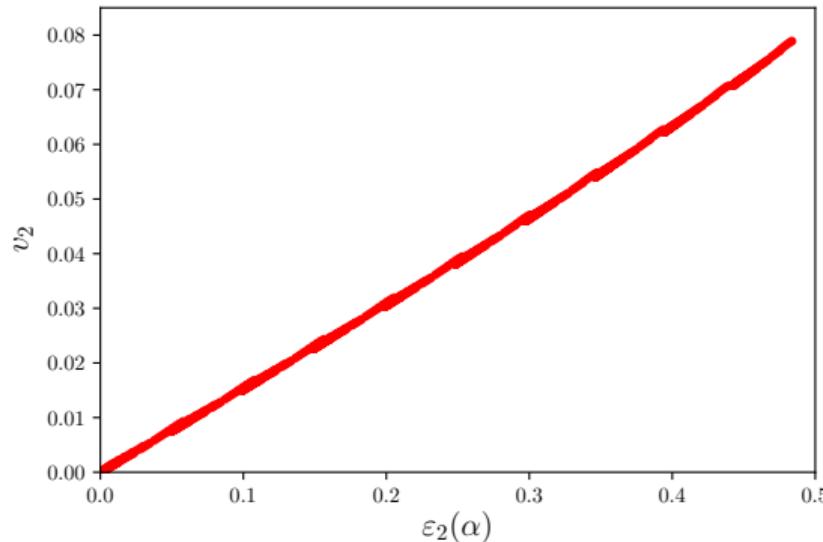
$$|C| = r^2 P e^{-\frac{r^2}{2\rho^2}} (1 - p_2 \cos 2\phi)$$

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$B \text{ (fm}^{-5}\text{)}$	a_2	b_2	c_2
$\{0.0 - 4.0\}$	$\{0.0 - 0.45\}$	$\{0.0 - 0.6\}$	$\{0.0 - 0.4\}$

$P \text{ (fm}^{-6}\text{)}$	p_2	q_2
0	0	0

TOY MODEL TESTING



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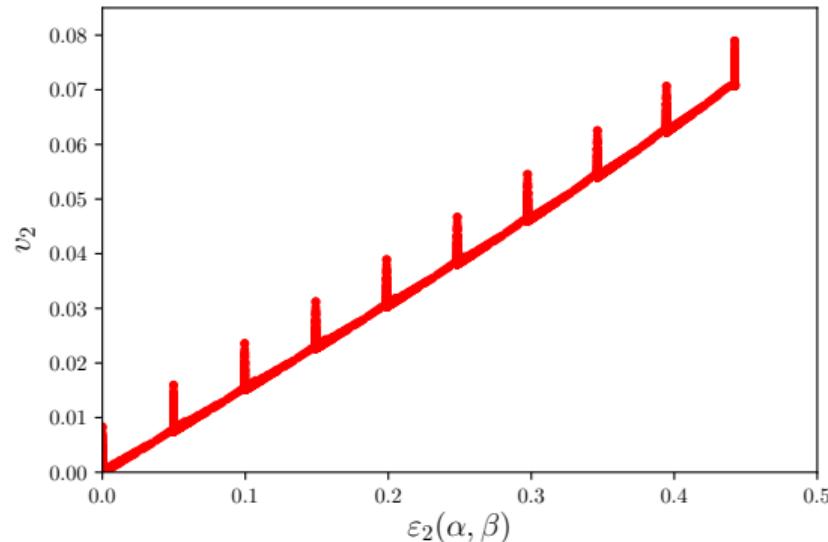
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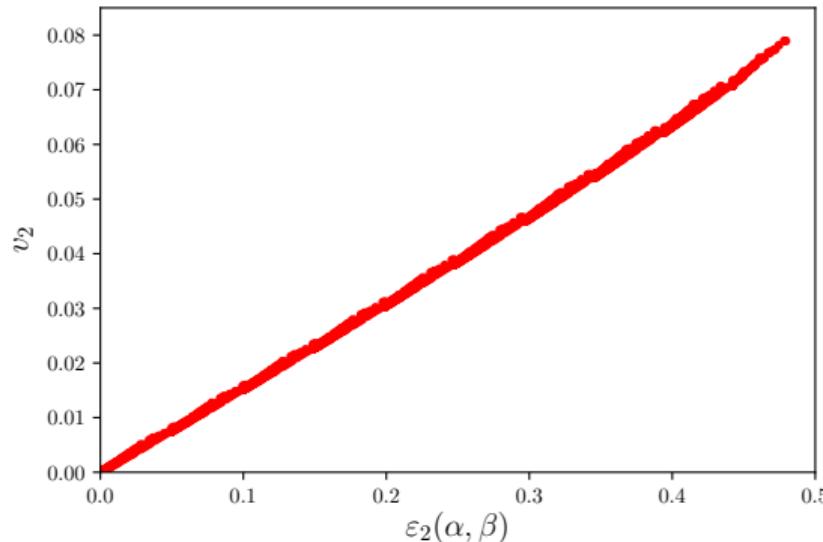
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TOY MODEL TESTING



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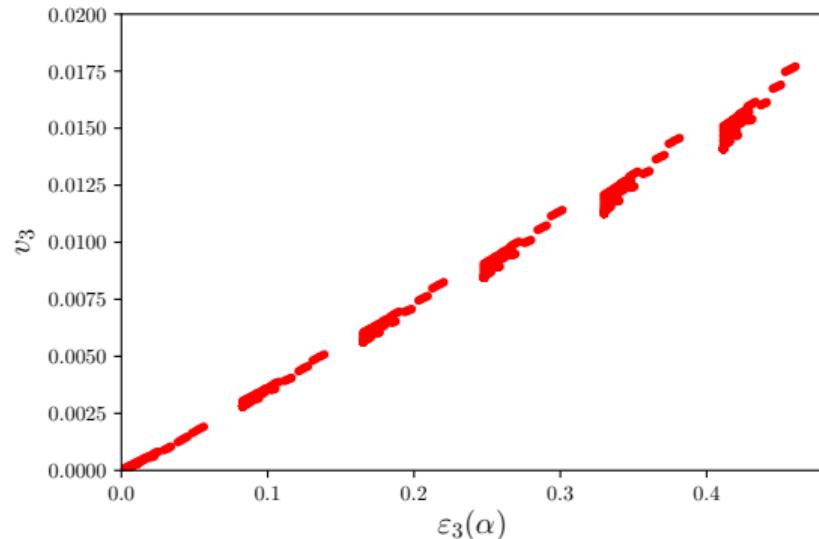
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