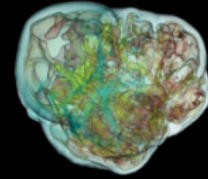


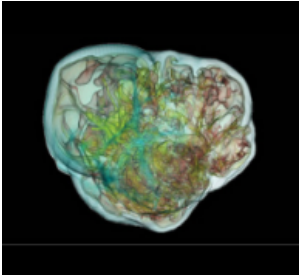
SuperNova Early Warning System

SNEWS 2.0 Workshop



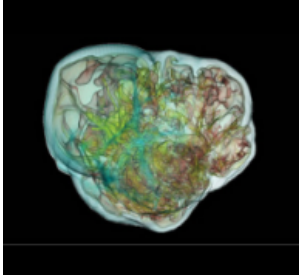
PANEL I

Moderator: Lindley Winslow (MIT)



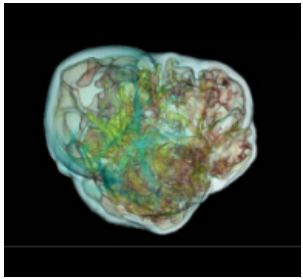
PANEL Members

- **Alexis Coleiro (Université Paris Diderot)**
- **Koji Ishidoshiro (Tohoku University)**
- **Vincent Fischer (UC Davis)**
- **Volodymyr Takhistov (UCLA)**
- **Xunjie Xu (MPIK, Heidelberg)**



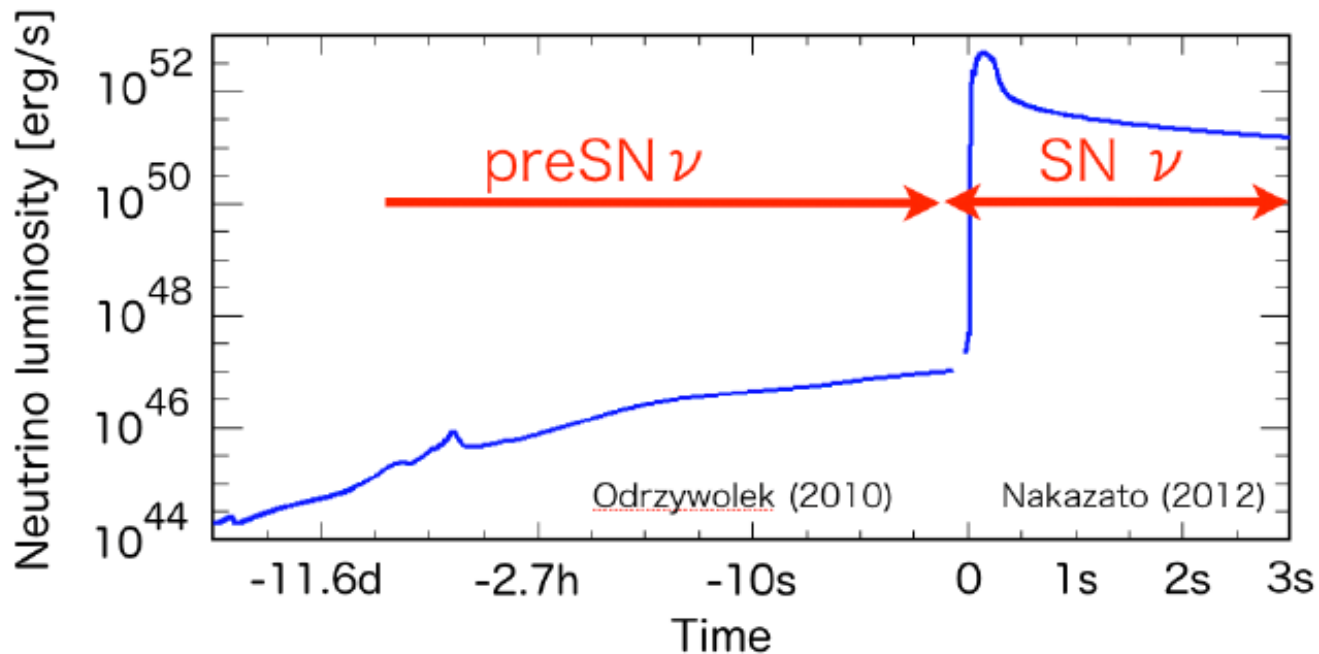
Panel I - Topics

- **What are the best strategies for a pre-supernova alert?**
 - **Does it make sense to combine information, and how?**
- **What are the best pointing strategies?**
 - **Does it make sense to combine information for triangulation or other means?**
 - **How do we implement this is in SNEWS?**



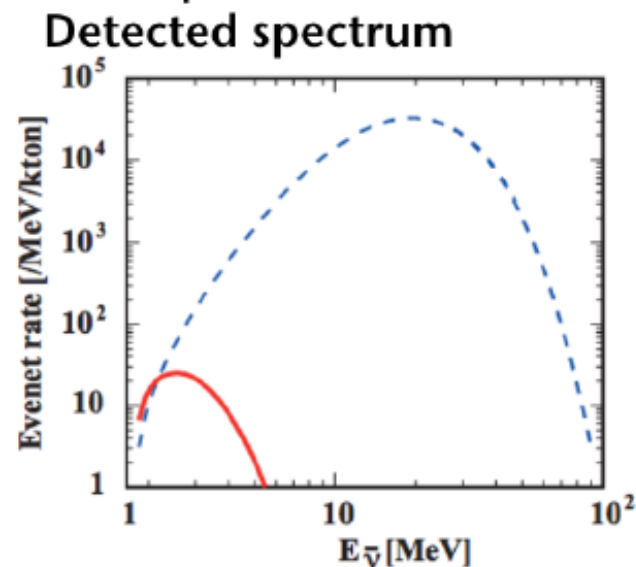
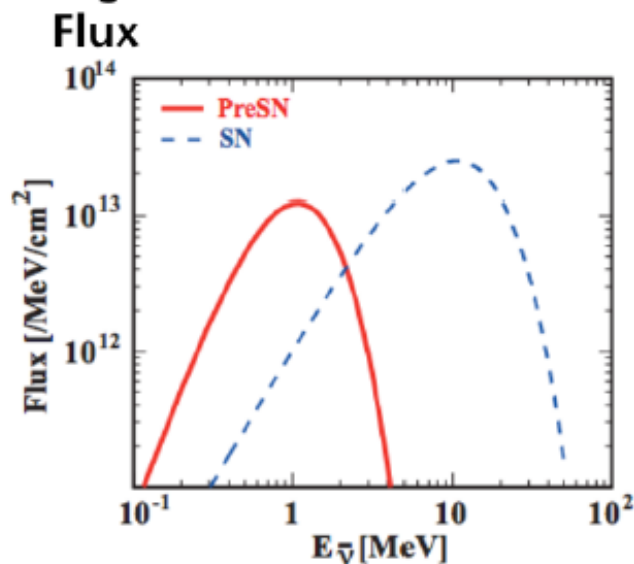
Pre-Supernova Signal

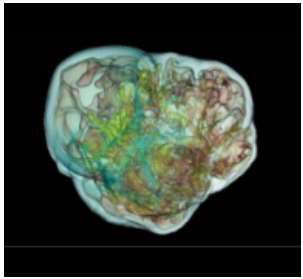
Pre-supernova neutrinos



Assumption: $d=200$ pc (Betelgeuse)

Integration in the last 48 hours before collapse



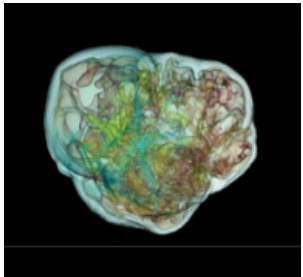


DM Experiments for SN

Comments for Panel I

(Volodymyr Takhistov, UCLA)

- Should start thinking of large DM experiments as “effective neutrino detectors”
 - **Some features:** coherent scattering enhancement & very low thresholds
→ complementarity with dedicated neutrino telescopes
 - **Pre-SN detection:**
 - don't suffer from oscillation effects or IBD energy threshold
→ signal information not identical to “standard” pre-SN detection approach
 - O(100) ton Argon/Xenon experiments are great pre-SN detectors
(much smaller with improved threshold)
- *** could implement pre-SN alarm via simple software trigger (e.g. 12-hr interval windows)
- **SN pointing:** capabilities not great



KamLAND Pre-Supernova Alarm

Panel discussion (Koji Ishidoshiro)

Combined alarm

- Possible SNEWS update
- Use of significance (σ) and FAR
- Key: **realtime BG estimation**.

Notice: Official reactor data with 2-3 weeks delay.

We can obtain on/off status as figure from the web pages in JAPAN.

-> Rough BG estimation might be possible. (error? delay? reliability?)

Pointing of pre-supernova neutrino

- Use of **delayed-prompt vector**

See JCAP08(2015)032, Scientific Reports 4, 4708 (2014), arXiv:1208.3628

Experimental demonstration and calibration: required

KL has not found any anisotropy of the delayed-prompt vector.

Chance with the IsoDAR experiment.

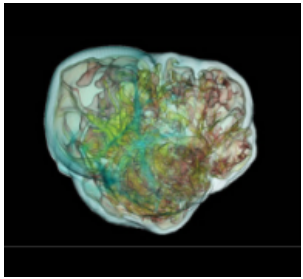
Check of the consistency between JCAP08(2015)032 and KLGsim.

Developments of ${}^6\text{Li}$ -LS and imaging detector for directional measurement

- **Comparison with the observed signal from the expected signal.**

Unfortunately or fortunately, the number of possible targets are small.

Updates of theoretical model and **precise distance**: required



Pre-Supernova Pointing

Presupernova neutrinos and pointing strategies in liquid scintillator detectors

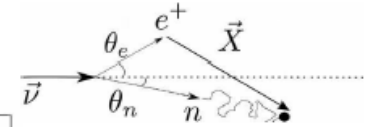
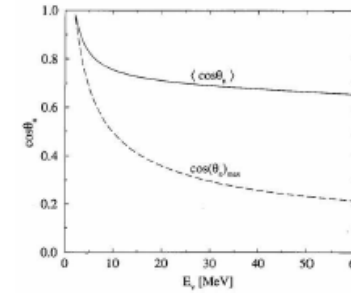
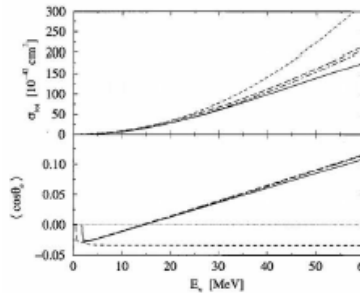


Presupernova neutrinos

- KamLAND (1 kt) → 3σ at < 690 pc (25 M_\odot)
- **Adding** several detectors will **increase** the detection range and significance:
 - Current LLS in **SNEWS** ~ 1.5 kt
 - All LLS expected in **2020** ~ 2.5 kt
 - **JUNO** (20 kt) will be a **game changer**
- Time correlation not as important since preSN neutrinos arrive ~days before the SN neutrinos
- Efficient pre-detection requires all LLS to:
 - Be **part of SNEWS**
 - Have a KamLAND-like **pre-SN trigger**
 - Have a good detection **efficiency < 5 MeV**
→ Unfortunately rules out LVD and NOvA

Supernova pointing with IBD

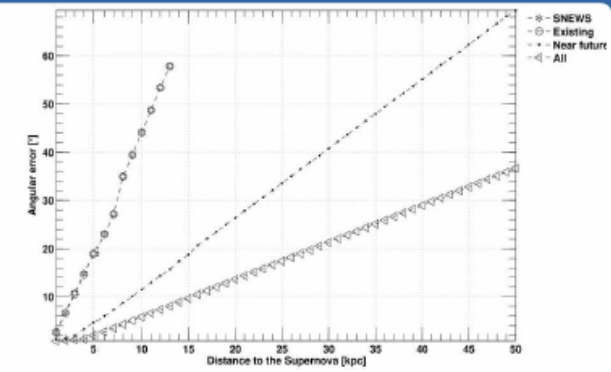
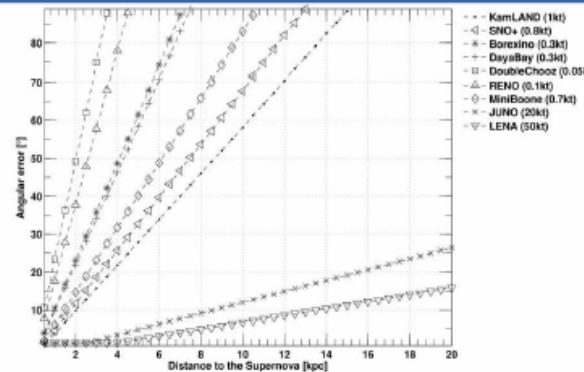
- **Angular distributions of e^+ and $n \neq$ isotropic**
- Mostly relevant for large statistics (> 1000 evts)

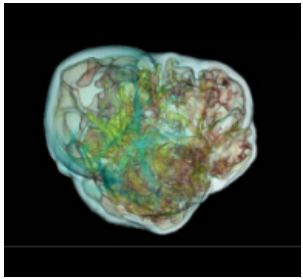


From JCAP 08 (2015) 032

Combining several LLS for pointing

- **Pointing efficiency** of LLS can be expressed as a **function of # detected events**
- Low capabilities compared to e-scattering in SK
- **Combining** detectors help reach **acceptable accuracies** (~12° at 10 kpc if JUNO added)
- Combined pointing:
 - Requires **fast online reconstruction** in (E, X)
 - Frequent **calibration** of each detector
 - **# of evts and preferred direction** (with significances) sent to **SNEWS server** and combined





Pointing Status



MAX-PLANCK-INSTITUT
FÜR KERNPHYSIK



MAX-PLANCK-GESELLSCHAFT

Neutrino astronomy with supernova neutrinos — the triangulation method

Xun-Jie Xu
Max-Planck-Institut für Kernphysik, Heidelberg

xunjie.xu@gmail.com

Talk at the SNEWS 2.0 workshop <https://snews2.0.sno.ubc.ca/>

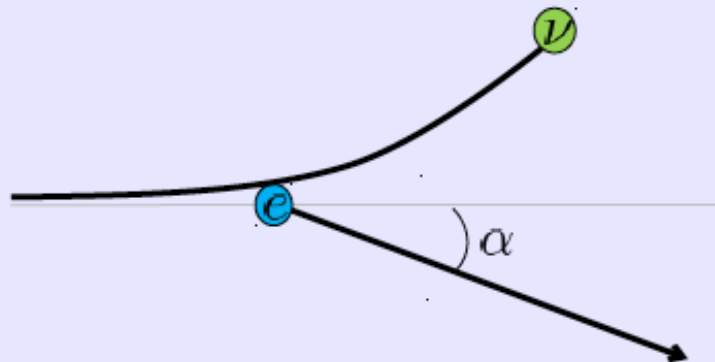
Based on: 1802.02577 (JCAP), in collaboration with Vedran Brdar and Manfred Lindner

Introduction

Two methods

Forward scattering

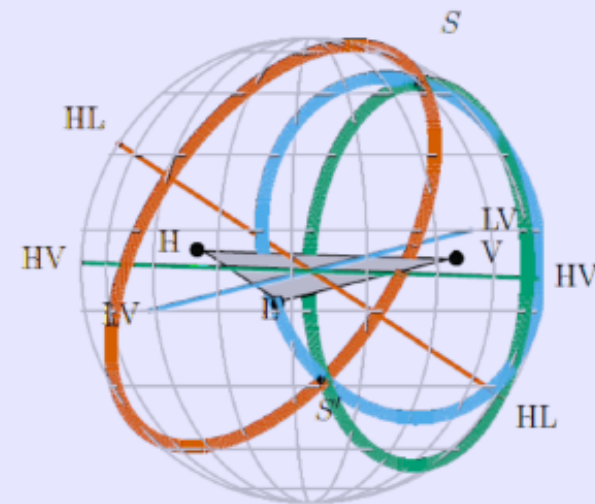
In $\nu + e$ scattering, α can be very small if E_ν is high.



$$\cos \alpha = \frac{E_\nu + m_e}{E_\nu} \left(\frac{T}{T + 2m_e} \right)^{1/2}$$

Triangulation

Need 3 or more detectors;
Measure $\Delta t \sim d/c \sim 40$ ms;
Only time information required;
Benefit from IBD (x-sec, bkg.).



The triangulation method

Consider:

- an **instantaneous** neutrino pulse
- two detectors

Arrival time difference:

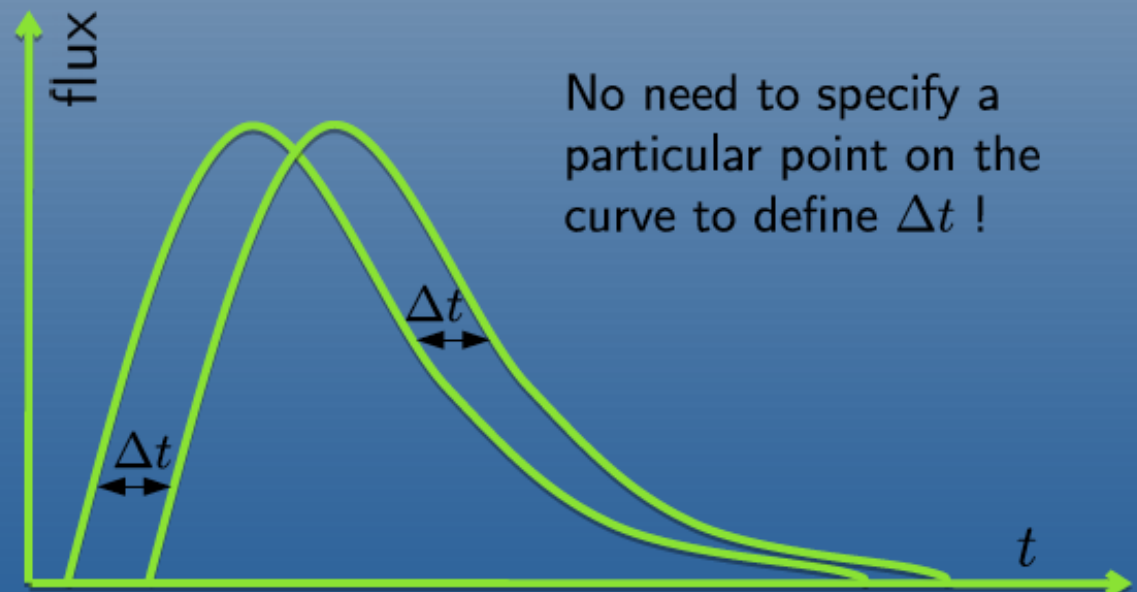
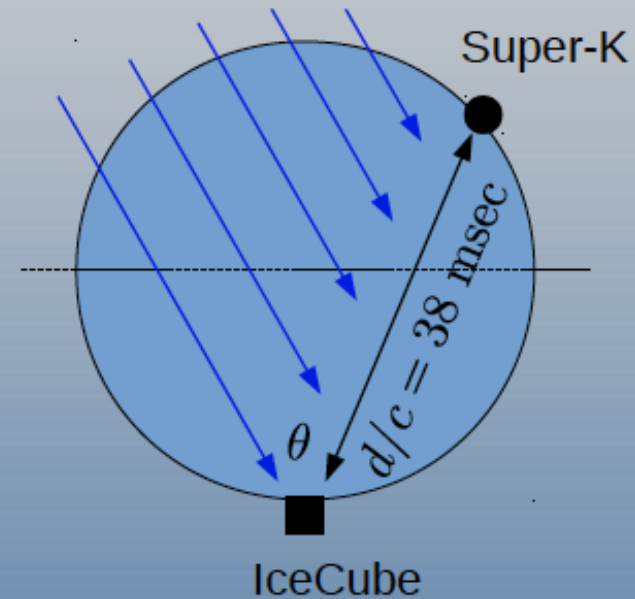
$$\Delta t = \frac{d}{c} \cos \theta$$

However, **instantaneous**



How to define Δt properly?

— defined as time shift



Previous conclusion:

$$\left. \begin{array}{l} \text{SNO: } \delta t = 15 \text{ ms} \\ \text{Super-K: } \delta t = 3 \text{ ms} \end{array} \right\} \delta(\cos \theta) = 0.5$$



HEP 1 records found Search

1. **Can a supernova be located by its neutrinos?**
John F. Beacom, P. Vogel (Caltech). Nov 1998. 10 pp.
Published in **Phys.Rev. D60 (1999) 033007**
DOI: [10.1103/PhysRevD.60.033007](https://doi.org/10.1103/PhysRevD.60.033007)
e-Print: [astro-ph/9811350](https://arxiv.org/abs/astro-ph/9811350) | [PDF](#)

[References](#) | [BibTeX](#) | [LaTeX\(US\)](#) | [LaTeX\(EU\)](#) | [Harvmac](#) | [EndNote](#)
[ADS Abstract Service](#); [OSTI.gov Server](#)

[Detailed record](#) - [Cited by 118 records](#) 100+

Today we have:

- more detectors
- better knowledge of the flux

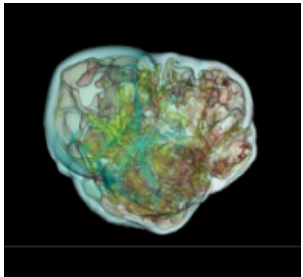
Our result

SN → neutron star:

$1.5^\circ \sim 3.5^\circ$

SN → black hole:

$0.2^\circ \sim 0.5^\circ$

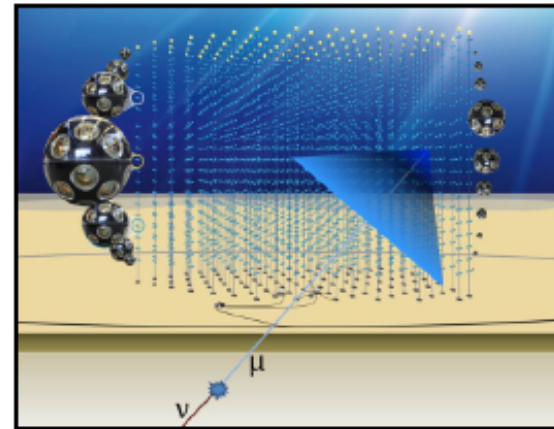
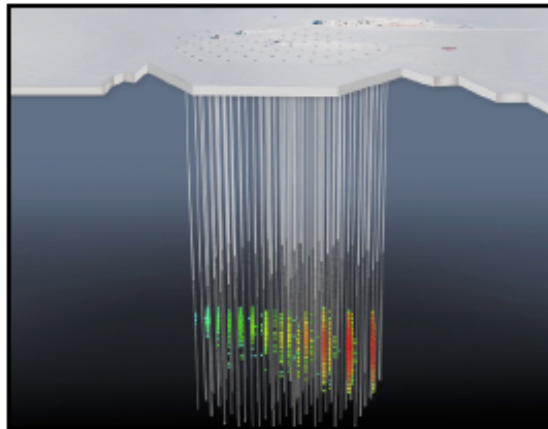


Time Series Data

What can we gain by exchanging time series instead of only alarms ?

Study (mostly) by Marta Colomer & Massimiliano Lincetto

joint KM3NeT/IceCube working group set up after neutrino CCSN workshop held in Orsay (France) in July 2018.



Long string ice- or water-based Cherenkov neutrino detectors.

Do not reconstruct IBD interactions event-by-event but sensitive to an increase of the detection rate over the full array.

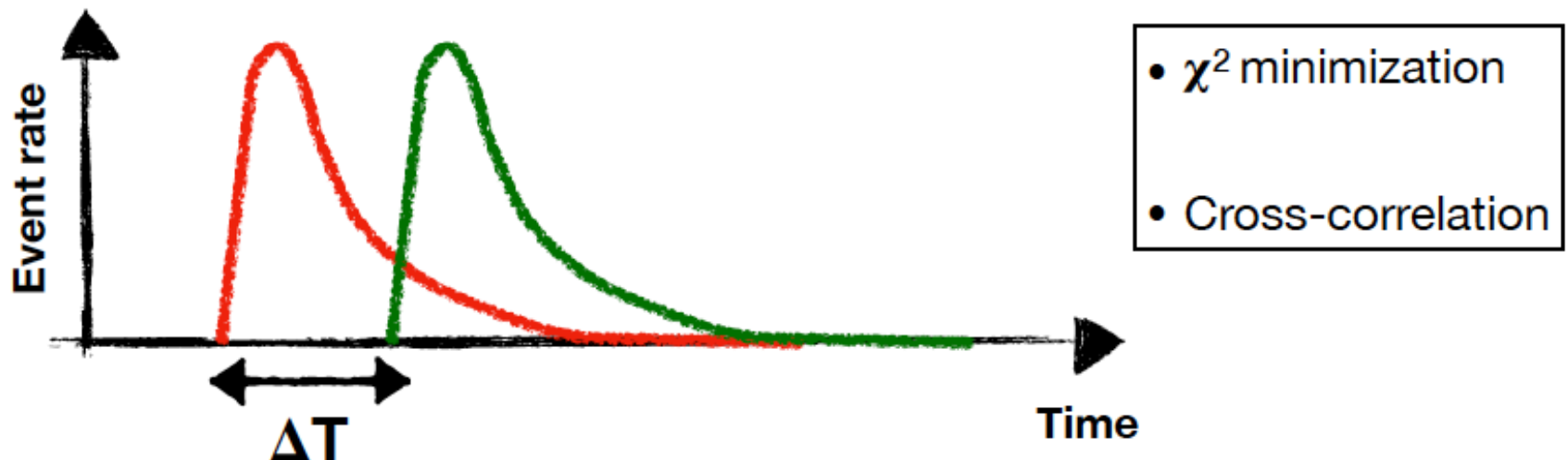
Why/how estimating time difference at two detectors ?

Why ?

- ΔT = time difference of CCSN neutrino arrival at two detectors.
- Arrival time difference at 3 or more detectors \rightarrow infer CCSN direction + constrain t_0 for GW searches (see e.g. *Nakamura et al., 2016*).

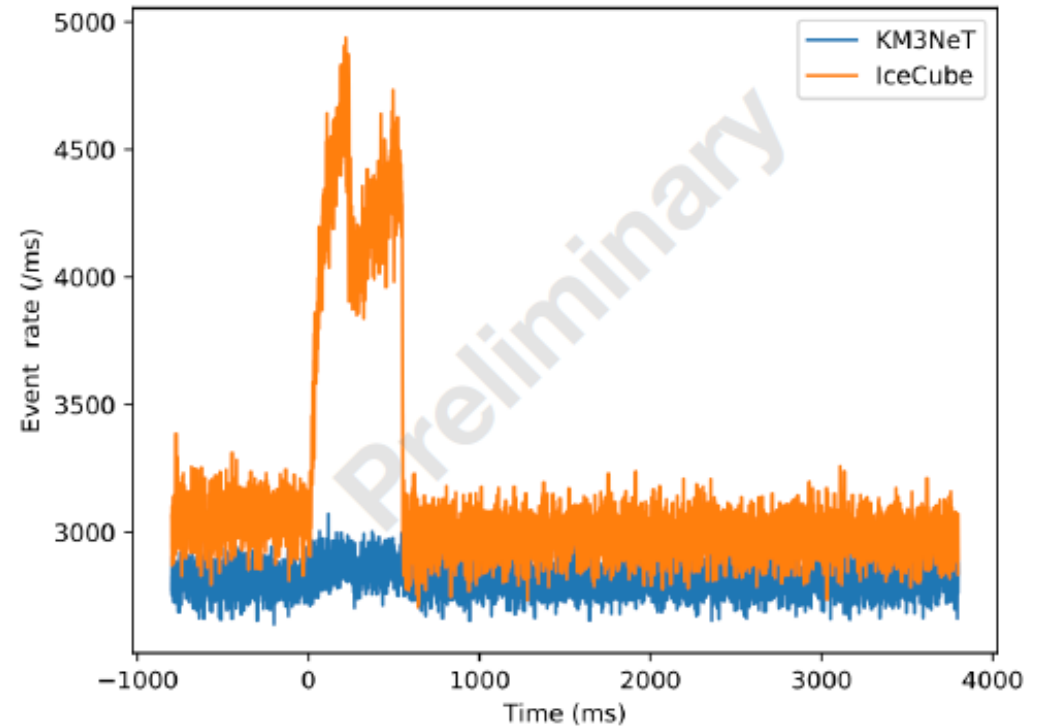
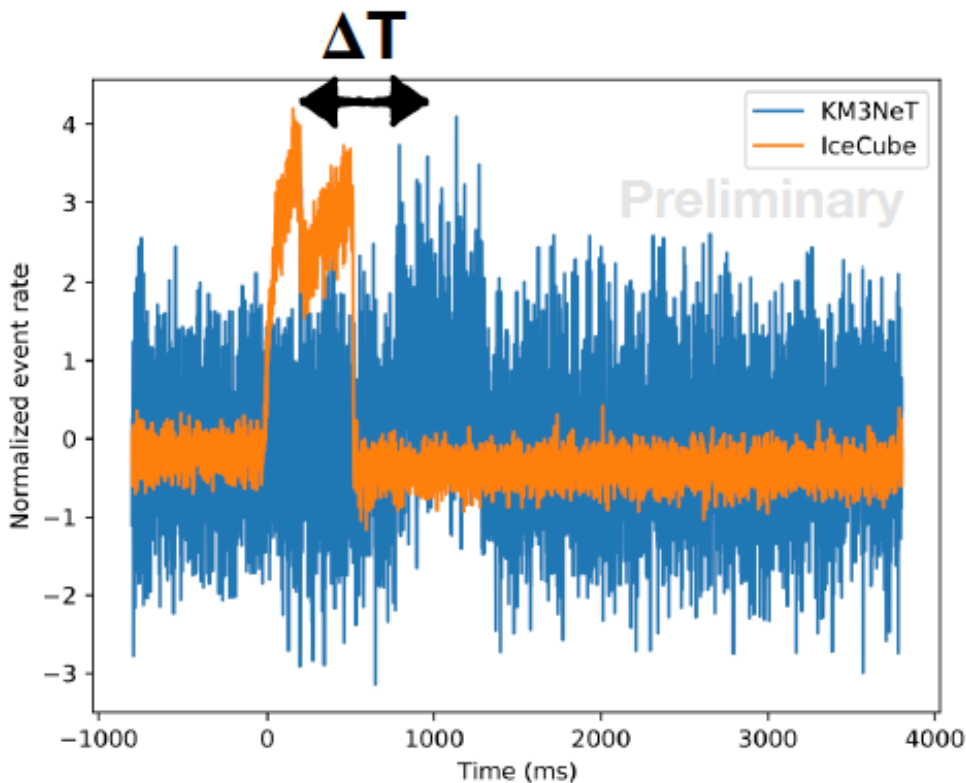
How ?

- Fit t_0 independently from each experimental lightcurve \rightarrow compute ΔT
- Lightcurve matching: fit directly the shift between pairs of experiments



Ongoing work

- Detector lightcurves can be different (baselines, energy threshold, interaction channel)
- Preliminary results: IceCube / KM3NeT (ARCA):
~7ms of uncertainty on ΔT for a CCSN at 10 kpc.



- Need to prove lightcurve matching works better than independent t_0 fitting.
- SNEWS infrastructure ? / data sharing agreement ?
- Extend this preliminary work to other experiments (sensitive to IBD)