GBTx emulation for BM@N/MPD data acquisition systems

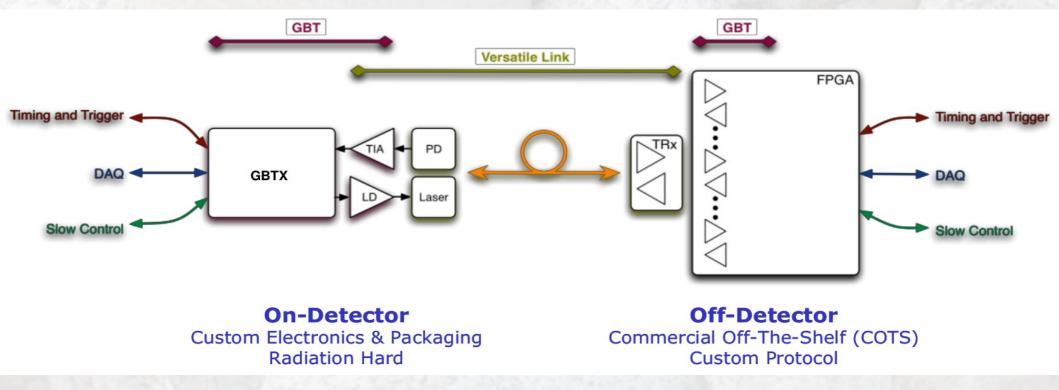
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The material presented is the result of the work of the teams from WUT (W.M. Zabołotny, A.P. Byszuk, M. Gumiński, G. Kasprowicz, K. Poźniak, R.Romaniuk) and GSI/FAIR (D. Emschermann, C.J. Schmidt)

What is GBTX?

 GBTX is a radiation tolerant ASIC, able to provide multiple high-speed links for highenergy physics experiments



GBTX in DAQ

- For DAQ applications the GBTX provides so called E-Links
 - The user data frame with length of 80 bits (with FEC) or 112 bits (without FEC) is delivered every 25 ns
 - This data may be used to implement so-called E-Links SPI-like synchronous links, working at clock frequency between 40 and 320 MHz and with data rate between 80 and 320 Mb/s (DDR operation is possible)
- Additional slow control is possible via a dedicated SCA chip connected to simple synchronous serial interface

GBTX with SMX2 in DAQ

- In CBM experiment, in STS and MUCH detectors the GBTX works with STS-MUCH-XYTER2 (SMX2) ASICs (developed at AGH) to as front-end electronics.
- A dedicated protocol has been designed (AGH, WUT, GSI/FAIR) for:
 - Control of FEE (including link synchronization and transmission of synchronous commands)
 - Transmission of acquired hit data
- The protocol may be also adapted/reused by other systems in other FEE ASICs (e.g. SPADIC for TRD detector in CBM)

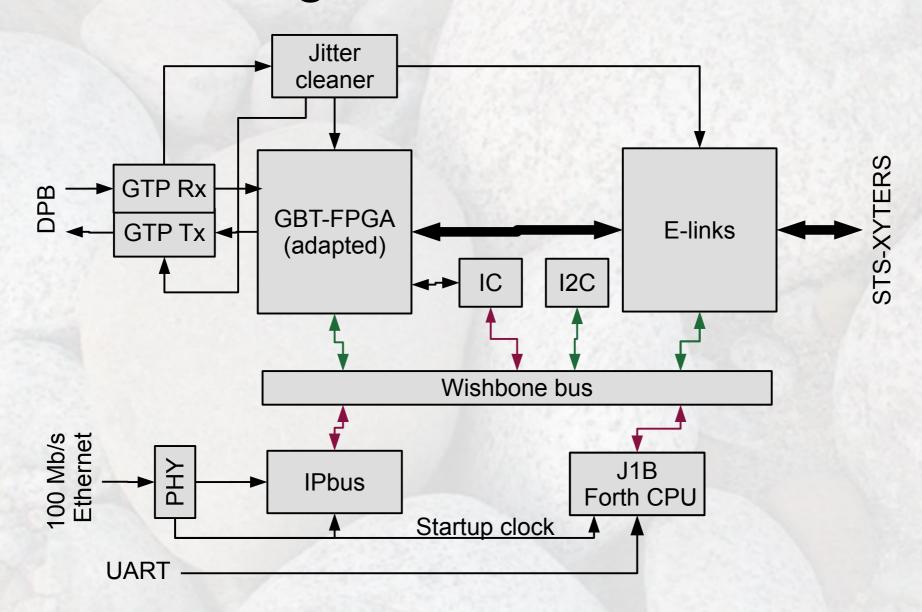
Problems with GBTX

- The original GBTX ASIC is manufactured in a special radiation-hard technology, therefore it is subject to export restrictions
 - The original chip can't be used in many countries outside EU, including China, India and Russia
 - That affects collaboration at development of detectors and DAQ chains for CBM
 - That also impairs the synergy between CBM and NICA related to usage of SMX2 front-end ASICs

Possible solution - GBTxEMU

- A viable solution is to recreate the most important functionalities of the GBTX in the FPGA
 - The initial plans assumed no standard FEC in downlink direction
- The most important functionality is a possibility to transfer the data via E-Link to and from the FEE.
 - The initial plans assumed no phase adjustment in E-Links
- Additional slow control functionalities may be implemented using free pins of FPGA

Block diagram of the GBTxEMU



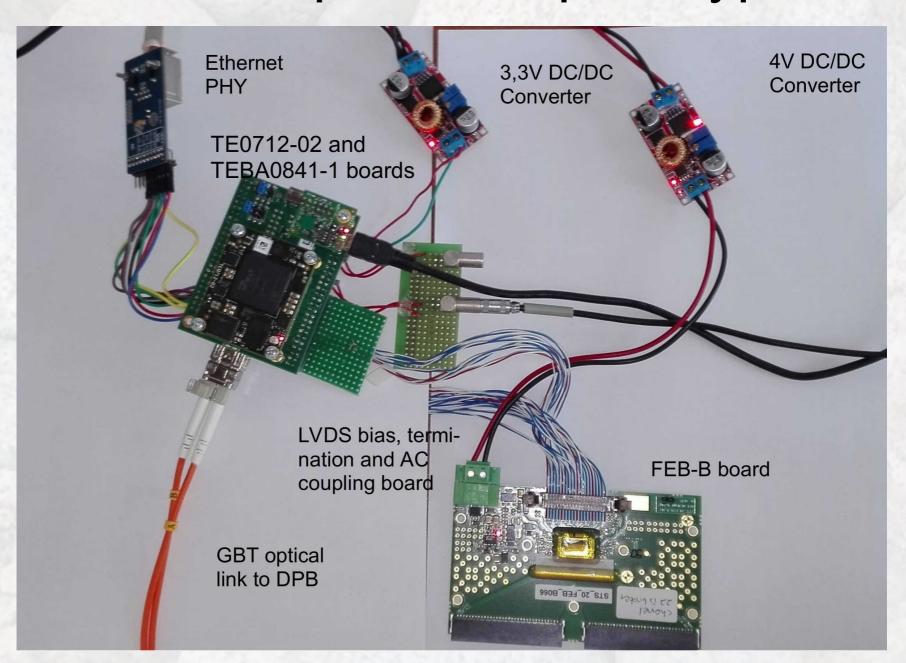
GBTxEMU – basic components

- GBT-FPGA slightly adapted from the original core provided by the CERN team
- IC core slightly adapted from original core provided by the CERN team
- J1B Forth Soft CPU, developed by James Bowman, reused after some modifications
- Wishbone used as an internal bus with possibility to work with multiple masters (IPbus, J1B, IC)
- IPbus adapted for operation with 100Mb/s link
- E-Links dedicated core developed for GBTxEMU

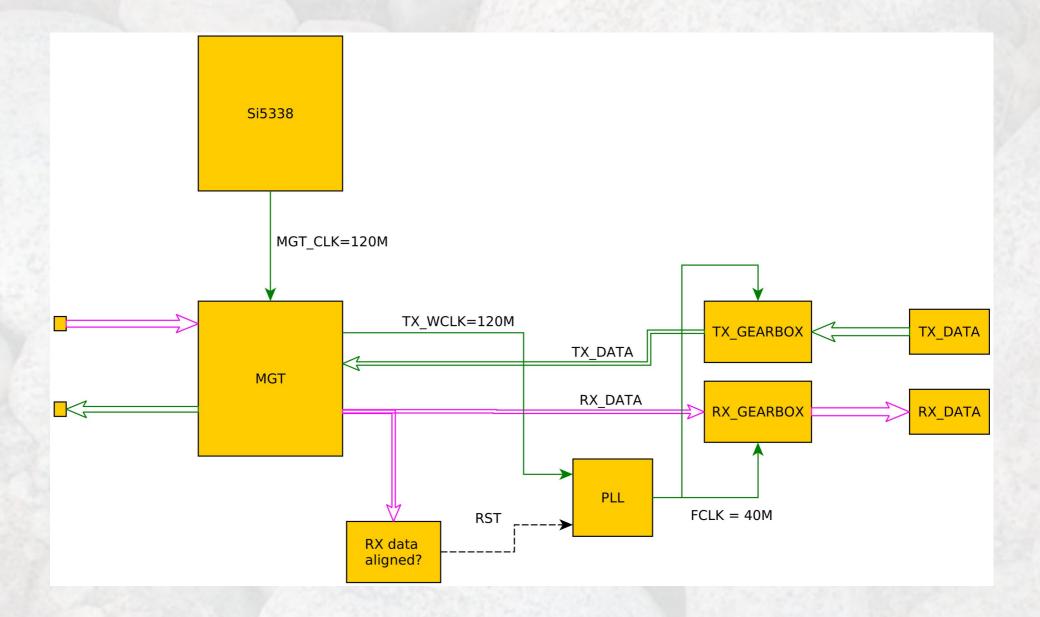
Selection of the hardware platform

- The heart of the GBTxEMU is an Artix 7-based board TE0712-2-200 from Trenz Electronic GmbH
 - Xilinx Artix-7 XC7A200T-1FBG484I FPGA
 - 4 GTP transceivers up to 6.4Gb/s
 - 100 Mb/s Ethernet
 - Programmable Low Jitter PLL (Silicon Labs Si5338)
 - 158 I/Os (78 differential pairs) available for user
- For initial experiments, the TEBA0841 board has been used

Test setup for first prototype



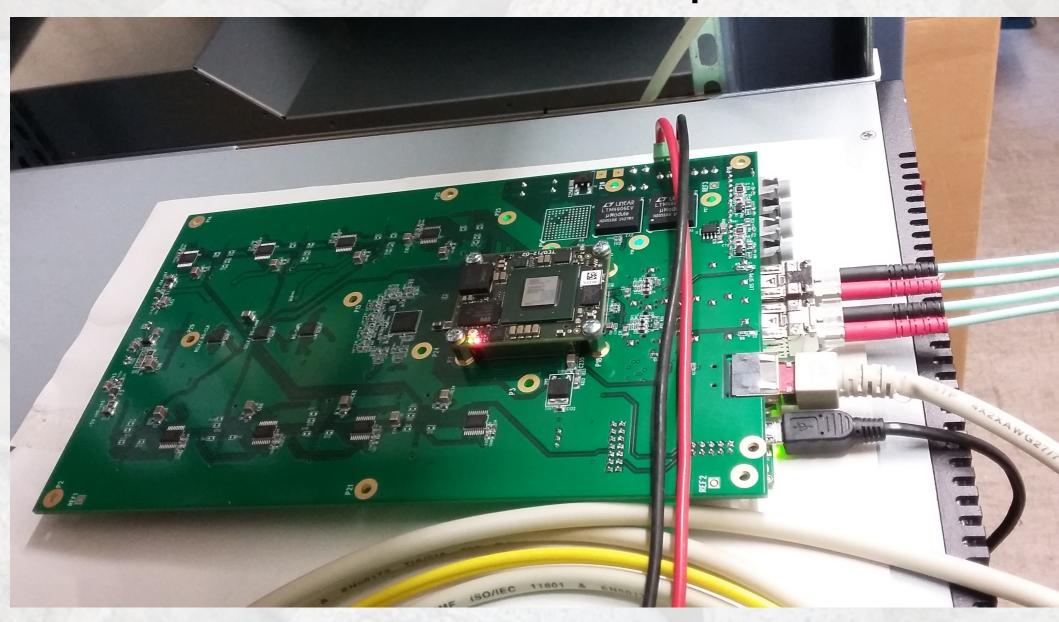
Clock structure with software JC



Dedicated GBTxEMU baseboard

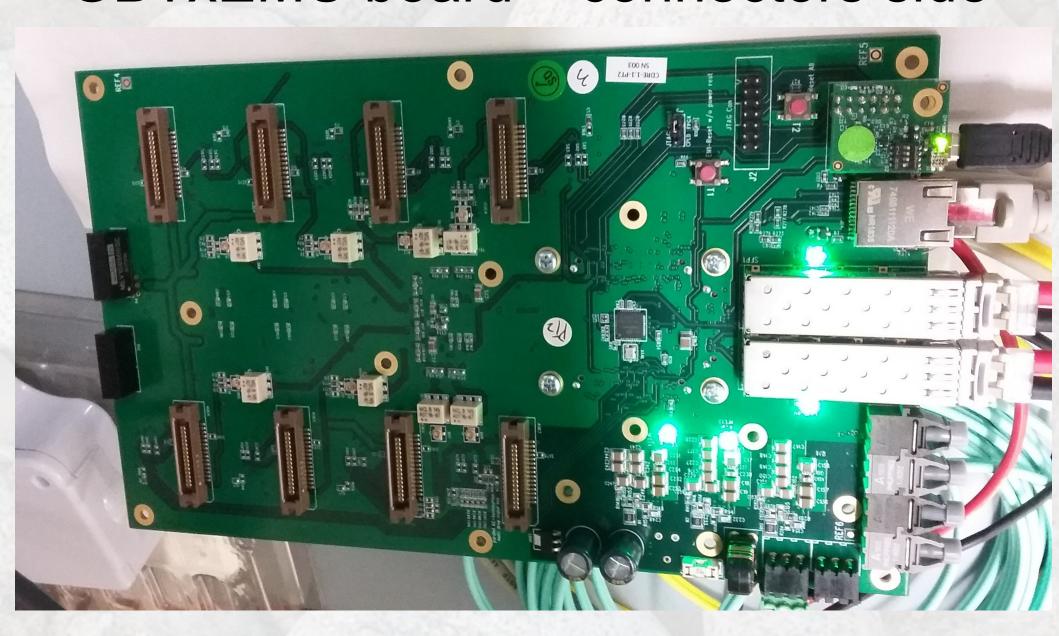
- The dedicated baseboard for TE0712-2 has been developed at GSI
 - It offers hardware jitter cleaner based on Si5344 chip
 - It is equipped with two SFP+ cages
 - It provides 8 ZIF connectors for FEE connections

GBTxEMU board - component side



Board developed at GSI

GBTxEMU board - connectors side



Board developed at GSI

2 GBTxEMU with 2 FEB-8

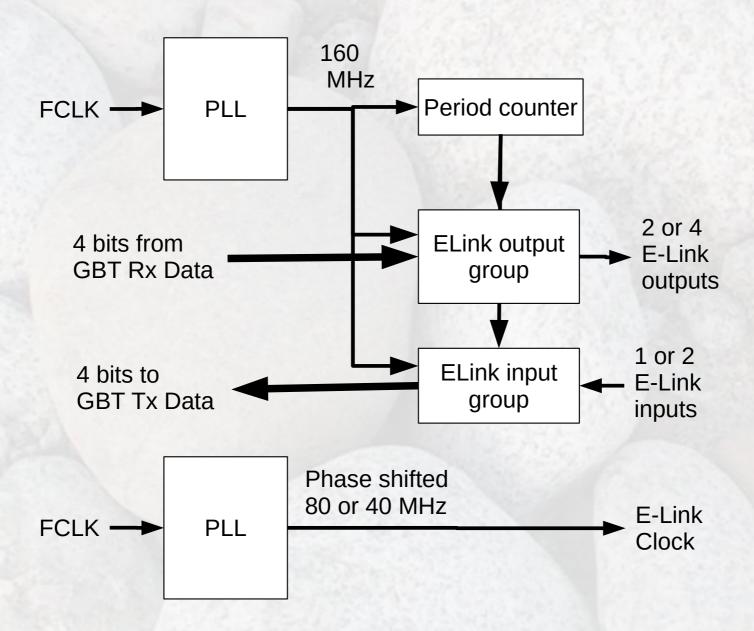


Test stand in GSI

The dedicated E-Link IP core

- GBTxEMU supports communication at two possible E-Link clock frequencies – 40 MHz or 80 MHz.
 - @ 40 MHz, the downlink bitrate is 40Mb/s, and uplink bitrate is 80 Mb/s (with 56 possible input channels)
 - @ 80 MHz, the downlink bitrate is 80Mb/s, and uplink bitrate is 160 Mb/s (with 28 possible input channels)
- Limited control of E-Link clock phase and delay of input data is possible

Block diagram of E-Link implementation



NICA days 2019

Operation of E-Links at different speed

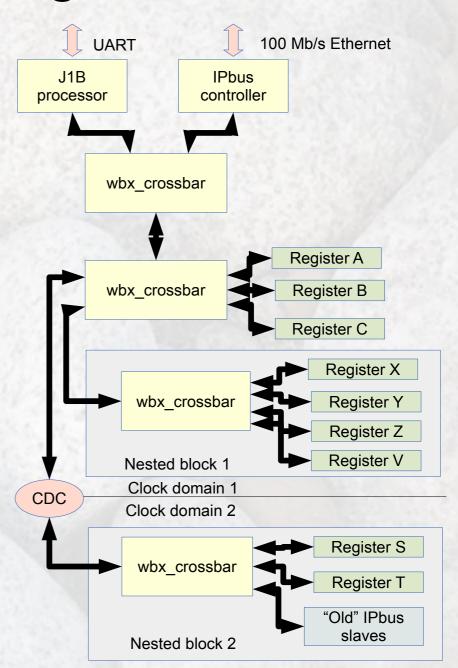


Control of GBTxEMU

- The GBTxEMU may be controlled via various channels
 - IPbus, if 100Mb/s Ethernet connection is available
 - Optical GBT link, after the link is configured (requires automatic configuration by J1B CPU)
 - UART connected directly to J1B CPU (for debugging and testing mainly)

Flexible design

- GBTxEMU uses the internal Wishbone bus with address space managed by the AGWB system.
- It enables easy adding of new internal blocks, and parameterization of the internal structure.
- Application of J1B enables interactive debugging and development of initialization procedure (thanks to use of Forth language).



Results

- Correct operation of GBTxEMU connected to AFCK boards with specially modified DPB firmware has been achieved.
 - Forward Error Correction in downlink direction is available.
 - The deterministic latency in downlink direction is achievable, allowing transmission of trigger and synchronous commands.
- The GBTxEMU automatically initializes the GBT link and accepts control commands via IC interface.
- Synchronization of E-Links for communication with STS-XYTER (SMX2.1) ASICs is possible both at 40 MHz and at 80 MHz E-Link clock frequency.
- Transmission of commands and reception of hit data from SMX2.1 ASICs is possible.

Conclusions

- GBTxEMU may be used instead of GBT-based CROB boards in DAQ chains, delivering the clock and bidirectional data transmission.
- The maximum confirmed uplink rate is 160Mb/s (twice less than in original GBTX).
- Assessment of long-term reliability is needed.
- Further investigations on more flexible adjustment of E-Link clock and input data delay are possible.
- For full utilization of available ZIF connectors at 160Mb/s, a
 possibility of providing the second uplink via the second SFP+
 cage should be investigated.
- Further work an a light version of DPB for GBTxEMU (GERI board) is needed

