

Tracking for the IDEA detector

Niloufar Alipour Tehrani

WG11 Detector Design Meeting

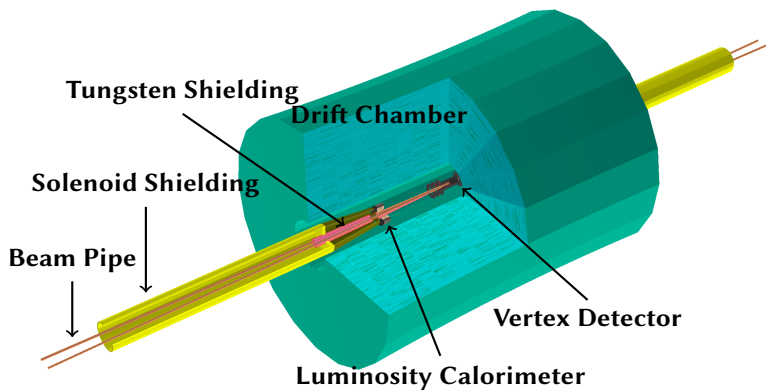
CERN
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Introduction

- ▶ Hough transform (HT): feature extraction in image analysis, computer vision, ...
 - ▶ Identification of lines, ellipses, circles
 - ▶ Can be used for the pattern recognition of the tracks in the drift chamber
 - ▶ The HT can be combined with Tricktrack (c.f. FCCSW) which is used for seeding in the VXD and limit the search region in the drift chamber.
 - ▶ Longer term plan \Rightarrow implementation in ACTS
- ▶ In this talk:
 - ▶ Detection of single particle tracks using the HT
 - ▶ First results of tracking with incoherent pair background

The IDEA detector as simulated & visualized with FCCSW



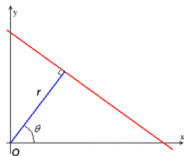
Hough Transform principle: identification of a simple line

- ▶ Represented as a point (b, m) in the parameter space space

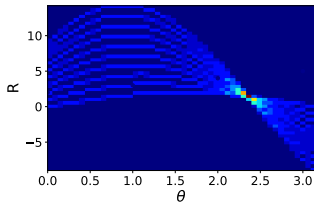
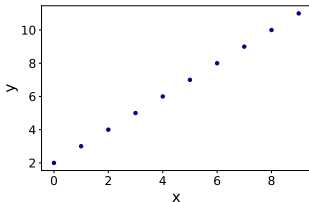
$$y = m \cdot x + b \quad (1)$$

- ▶ Hough space: (r, θ)

$$r = x \cdot \cos(\theta) + y \cdot \sin(\theta) \quad (2)$$



- ▶ A line corresponds to local maxima in the Hough space.



HT & Conformal mapping: identification of circles

- ▶ A track in B field \Rightarrow helix (circle in (x, y) plane)
- ▶ Use conformal mapping to map the circle into line and then apply HT

- ▶ Circle equation with center (a, b) and radius R

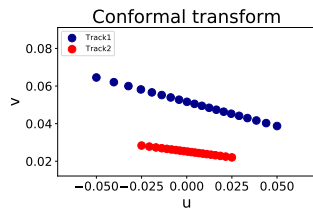
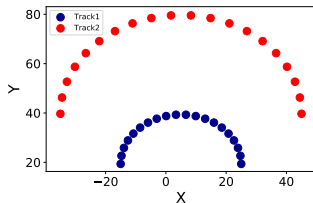
$$(x - a)^2 + (y - b)^2 = R^2 \quad (3)$$

- ▶ Conformal mapping: transform the circle into a straight line

$$u = \frac{x}{x^2 + y^2}, \quad v = \frac{y}{x^2 + y^2} \quad (4)$$

- ▶ If $R^2 = a^2 + b^2$, straight lines are of the form:

$$v = \frac{1}{2b} - u \frac{a}{b} \quad (5)$$



Identification of circles (2)

- ▶ Hough Transform for a straight line

$$\rho = u \cdot \cos(\phi) + v \cdot \sin(\phi) \quad (6)$$

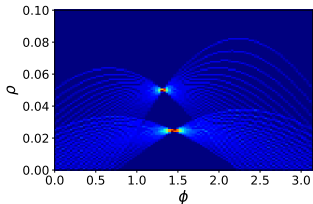
- ▶ The bending radius of the tracks: R

$$R = \frac{1}{2 \cdot \rho} \quad (7)$$

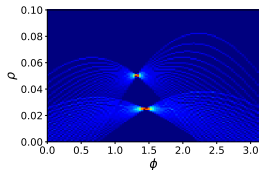
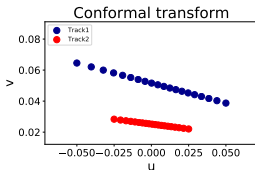
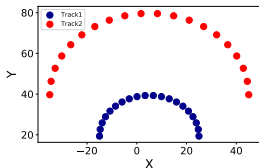
- ▶ The center of the circle (a, b)

$$a = \frac{\cos(\phi)}{2 \cdot \rho} \quad (8)$$

$$b = \frac{\sin(\phi)}{2 \cdot \rho} \quad (9)$$

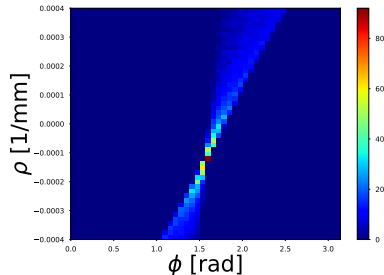
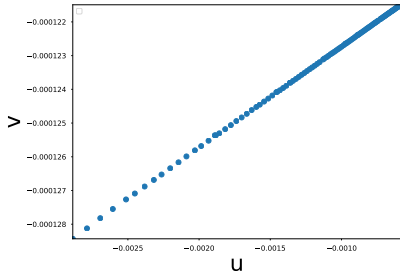
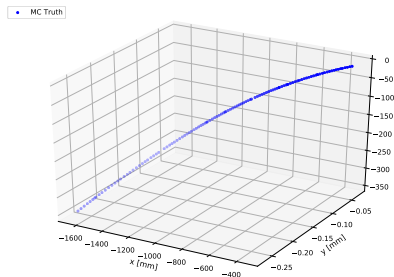


Summary



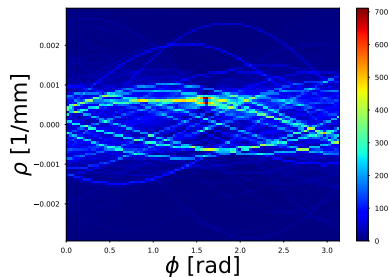
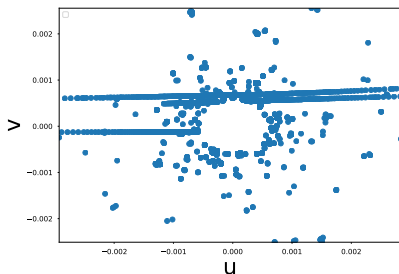
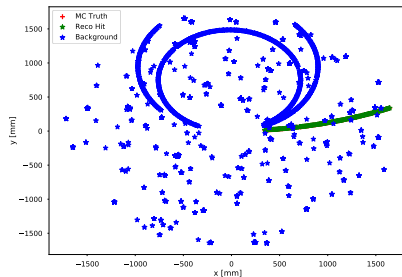
Hough transform: single tracks

- ▶ Particle gun: 2.4 GeV muon
- ▶ $B = 2 \text{ T}$
- ▶ Bending radius: 4 m
- ▶ MC Truth position corresponds to the intersection of the track with the wire
- ▶ Reconstructed hit: MC hit smeared with the single-hit resolution ($\sigma_{x,y} = 0.1 \text{ mm}$ and $\sigma_z = 1 \text{ mm}$)



A particle track combined with the background

- ▶ Particle gun: 2.4 GeV muon
- ▶ 1 BX of incoherent pair background at the top stage

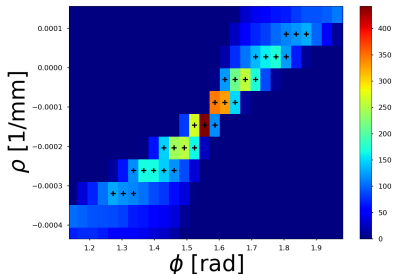


- ▶ All the tracks (event & background tracks) are visible in the Hough space.

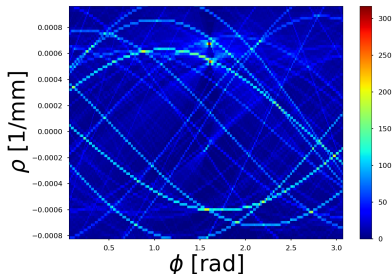
Finding the crossing points in the Hough space

- ▶ Visually, the tracks are detected easily in the Hough space
- ▶ Automatic detection of the crossing points (or the maxima)
 - ▶ The bin size needs to be optimized

▶ HT without background



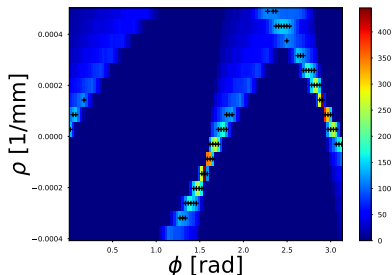
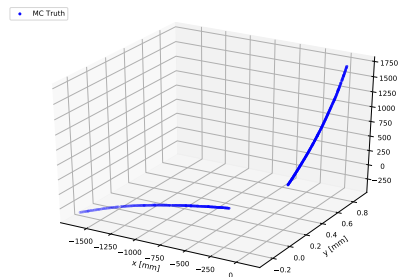
▶ HT with background



- ▶ In the Hough space, select only bins more than 112 hits (total number of layers in the DCH)
- ▶ Cluster positions with the highest number of hits \Rightarrow tracks
- ▶ The background can be also reduced by a timing cut

Example: 2 particle tracks

- ▶ Particle gun: 2.4 GeV muon



- ▶ DBSCAN clustering algorithm used with a distance of $\sqrt{2}$ (c.f. scikit-learn)
- ▶ 4 clusters detected
- ▶ To do: remove the "ghost" clusters/tracks

Conclusions

- ▶ A first implementation of the Hough Transform is available
- ▶ Single particles tracks are well detected
 - ▶ Visually and also by the detection of the crossing point (maximum) in the Hough space
 - ▶ Information on the bending radius of the track is obtained directly
- ▶ Parameters to be optimized for finding the maxima in the Hough space
 - ▶ Clustering for finding the maxima
 - ▶ For the pair background, a timing cut to be applied