## **FairMQ**

## State Machine Update & Other Developments

**Alexey Rybalchenko** 

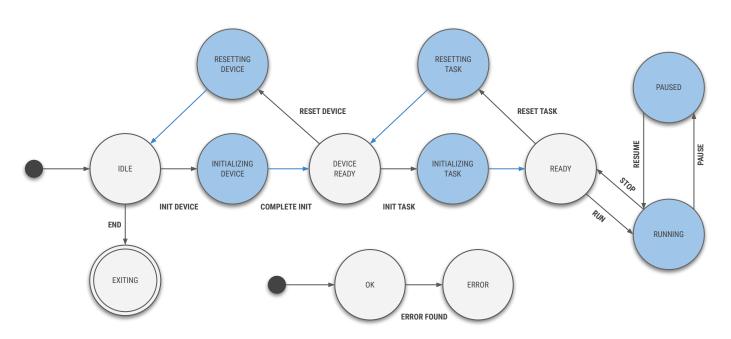
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#### **FairMQ State Machine**

Based on Boost Meta State Machine (MSM).



#### Issues:

- Channels can only be created before state machine runs (before InitializingDevice state).
- A user state handler could hang while the state machine has already transitioned to the next state.
- FairMQDevice and FairMQStateMachine are too tightly coupled.



# FairMQStateMachine::State::INITIALIZING\_DEVICE FairMQStateMachine::State::DEVICE\_READY FairMQStateMachine::State::INITIALIZING\_TASK FairMQStateMachine::State::READY FairMQStateMachine::State::READY FairMQStateMachine::State::PAUSED FairMQStateMachine::State::RESETTING\_TASK FairMQStateMachine::State::RESETTING\_DEVICE FairMQStateMachine::State::PAUSED FairMQStateMachine::State::PAUSED FairMQStateMachine::State::PAUSED

#### **Transitions:**

FairMQStateMachine::State::**OK**FairMOStateMachine::State::**ERROR** 

FairMQStateMachine::Event::INIT\_DEVICE
FairMQStateMachine::Event::RUN
FairMQStateMachine::Event::RUN
FairMQStateMachine::Event::STOP
FairMQStateMachine::Event::RESET\_TASK
FairMQStateMachine::Event::RESET\_DEVICE
FairMQStateMachine::Event::END
FairMQStateMachine::Event::END

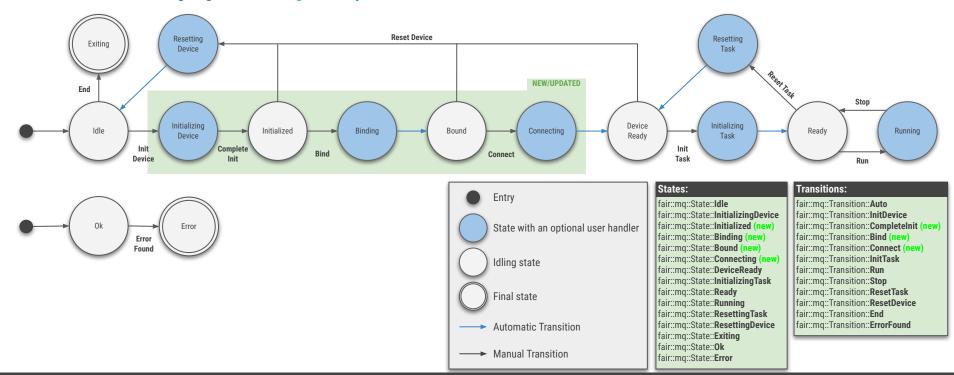
## **FairMQ State Machine Updates (1)**

#### **Split InitializingDevice state into InitializingDevice + Binding + Connecting:**

- Initializing Device state for config plugin to apply any kind of config and/or create channels.
- Binding & Connecting states to perform dynamic port configuration.

#### **Removed Paused state:**

Did the same as going from Running to Ready and back.



## FairMQ State Machine Updates (2)

- Previously a user state handler could hang while the state machine has already transitioned to the next state.
  - E.g.: Controller initiates STOP transition to change the state from RUNNING to READY. Handler for the RUNNING state (Run() method) could ignore this and/or hang for any reason.
    - $\rightarrow$  Previously the controller would still see the state as READY and only fail on following transitions, which is misleading.
    - $\rightarrow$  Now the transition to the new state happens only once the handler for the previous completes.

The check that the handler has to make is no longer <code>CheckCurrentState(RUNNING)</code>, but <code>NewStatePending()</code>. Old one still works, but is deprecated.

- Deprecate WaitForEndOfState(transition) interface in favor of WaitForState(state)/WaitForNextState(). Only relevant for custom main() without any control plugin.
- <u>Minor modernization</u>: converted state & transition names from enums to enum classes and changed their names from UPPERCASE to CamelCase to avoid confusion with MACROs.
  - Breaking change for custom main() that doesn't use our plugins.
  - Backwards-compatibility provided for FairMQDevice::ChangeState() and FairMQDevice::CheckCurrentState().

## **Upgrade Instructions**

### DPL (or its users) and/or any device users that use our supplied config & control plugins

- No breaking changes (relevant ones).
- Replace the deprecated methods (will remain in FairMQ for at least two stable releases):
  - CheckCurrentState(RUNNING)
    + NewStatePending()
- Remove use of Pause() (unused as far as we can see).

## Control plugin writers (PluginServices API)

#### Add transitions for new states, e.g.:

```
ChangeDeviceState(DeviceStateTransition::InitDevice);
+ while (WaitForNextState() != DeviceState::InitializingDevice) {}
+ // apply potential config changes here ...
+ ChangeDeviceState(DeviceStateTransition::CompleteInit);
+ while (WaitForNextState() != DeviceState::Initialized) {}
+ ChangeDeviceState(DeviceStateTransition::Bind);
+ while (WaitForNextState() != DeviceState::Bound) {}
+ // read bound channel properties here ...
+ ChangeDeviceState(DeviceStateTransition::Connect);
while (WaitForNextState() != DeviceState::DeviceReady) {}
ChangeDeviceState(DeviceStateTransition::InitTask);
while (WaitForNextState() != DeviceState::Ready) {}
ChangeDeviceState(DeviceStateTransition::Run);
while (WaitForNextState() != DeviceState::Running) {}
```

Old code compiles, but will not transition beyond

InitializingDevice().

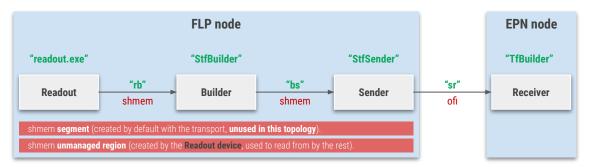
#### Users with custom main() doing own state control

- Update to new enum class types.
- Replace use of WaitForEndOfState(transition) with WaitForState(state).
- Add transitions for new states (see middle column).

### New Example: "Readout"

#### **Includes 2 topologies:**

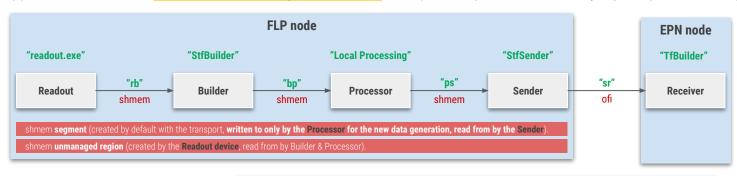
(1) A simpler one, where the data created by the Readout is the same that is sent out to EPN.



A playground/mockup for us to quickly test our developments in a scenario similar to FLP->EPN data flow.

Involves only transfers of dummy data and potential copies/copy avoidance.

(2) Same as above, but the Processor creates a new generation of data that is put in the general shared memory segment (not the unmanaged region used by the readout).





https://github.com/FairRootGroup/FairMQ/tree/dev/examples/readout

## **FairMQ: Further Minor Updates**

Added cmd device option --max-run-time <num seconds>, which, if greater than 0 (default), will change state to Ready after Running has been going for the specified number of seconds.

Many improvements to our test suite and tools:

- execute child processes via boost::process+boost::asio,
- improve process tools (support input and/or signaling to the process),
- add many more tests to cover exceptional cases (error states, exceptions, signal handling),
- improve the output of the tests.

Improved help output for interactive controller plugin.

