

# ATLAS BEAM CONDITIONS MONITOR SIMULATION

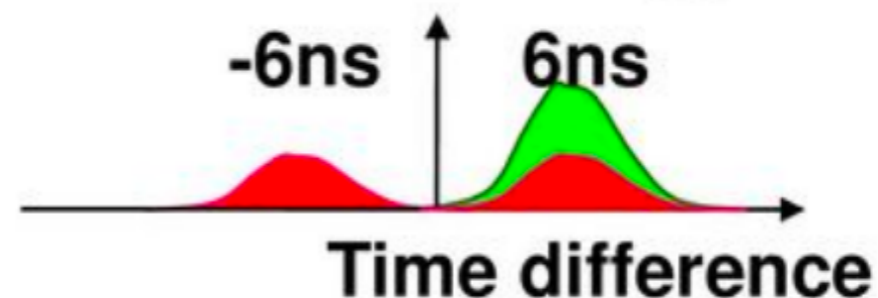
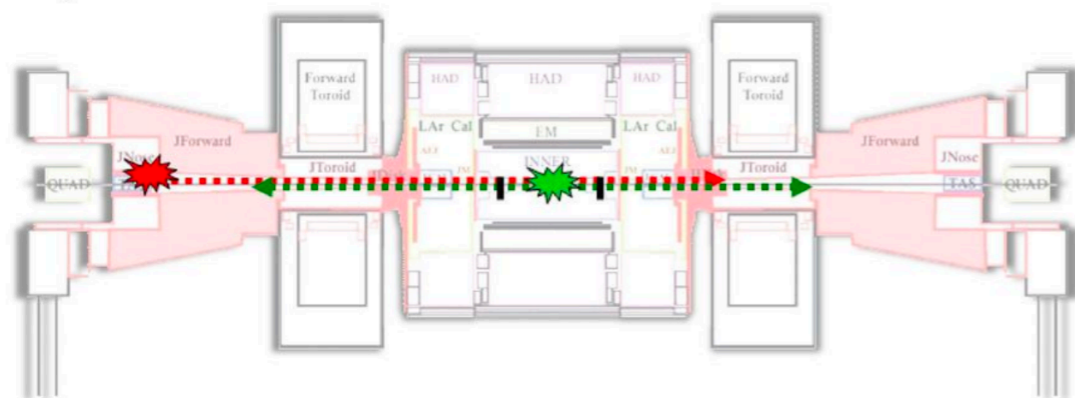
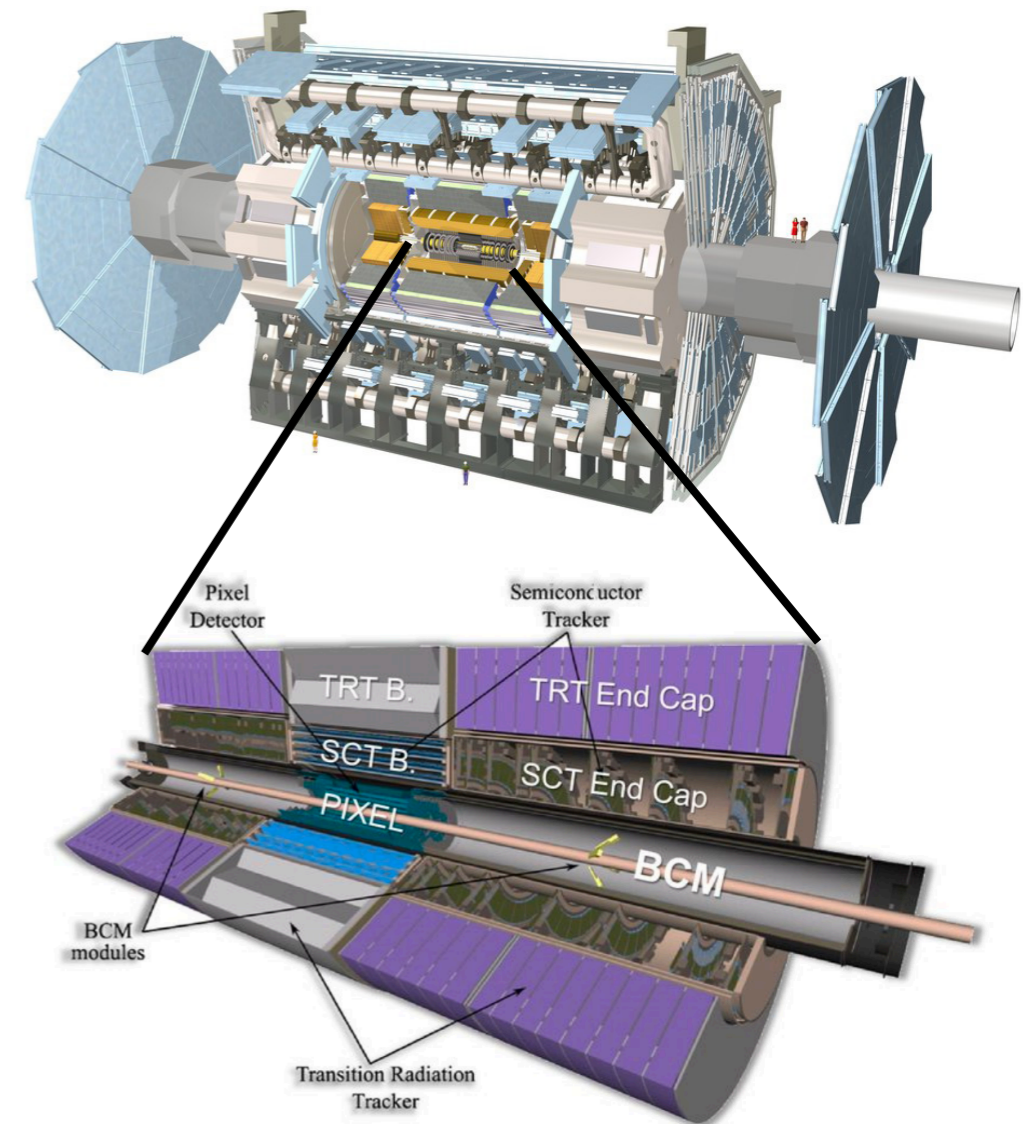
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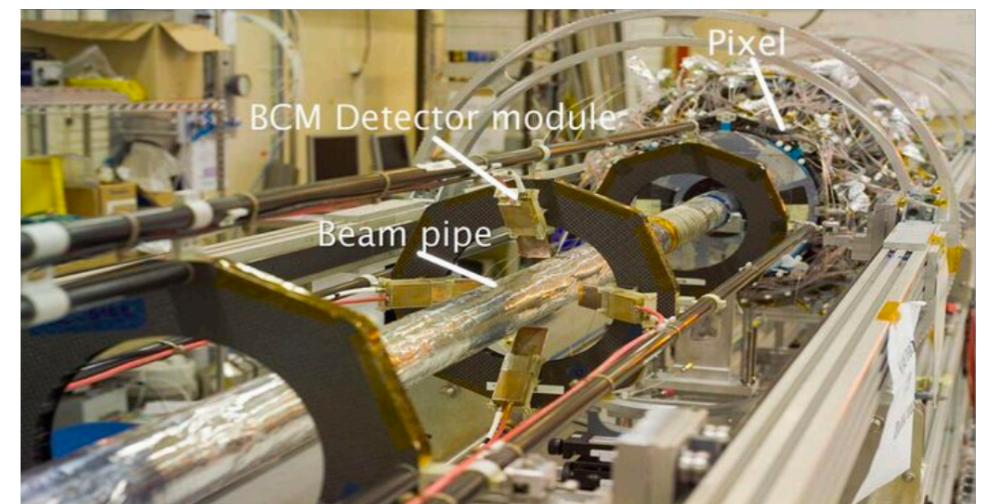
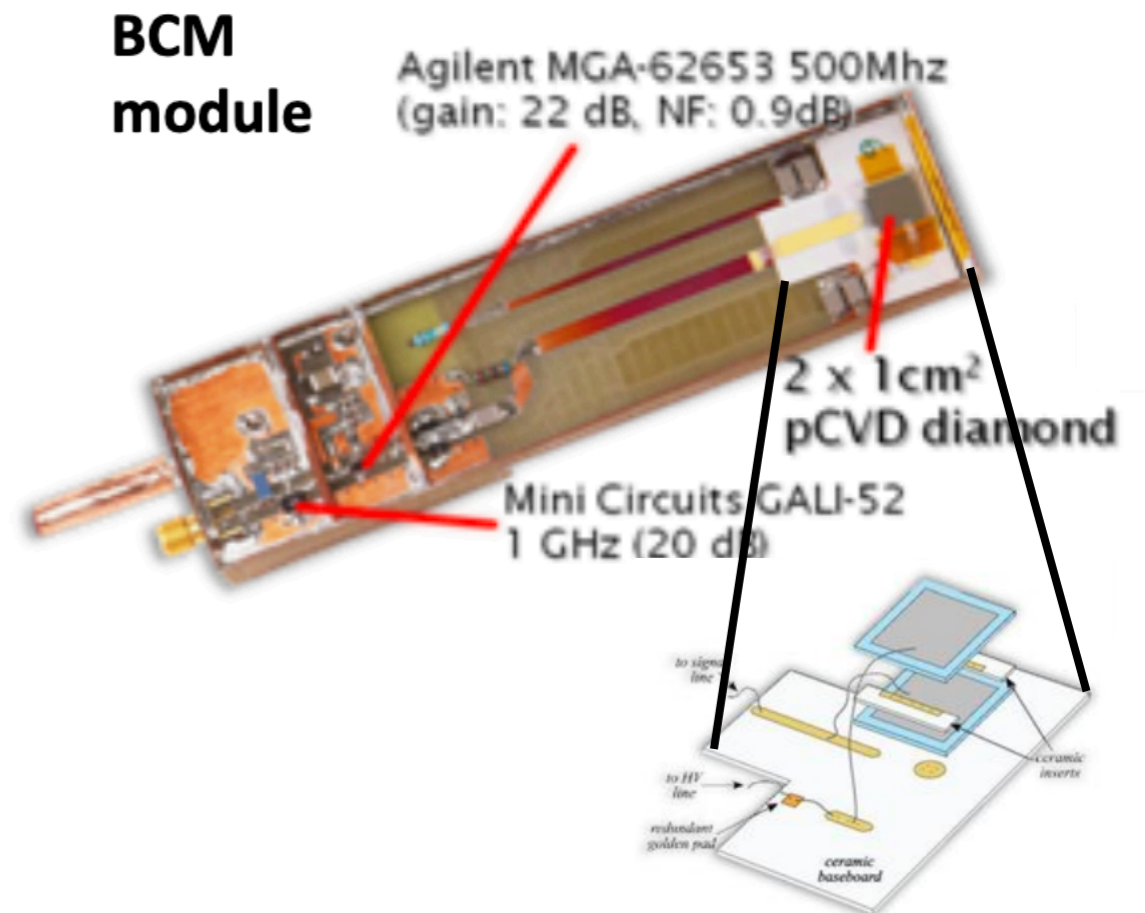
# Beam conditions monitor (BCM)

- BCM is a device for monitoring the rate of non-collision and collision events
- Preventing detector damage in case of a magnet failure or error during injection phase
- Luminosity measurement
- Two BCM stations installed at both sides of interaction point:  $z_{\text{BCM}} = \pm 1,84 \text{ m}$  ( $= \pm 6,25 \text{ ns}$ )
- Time measurement employed to separate collision and non-collision particles
- Fast processing times needed (fast signal rise time, narrow width and short baseline restoration)



# BCM modules

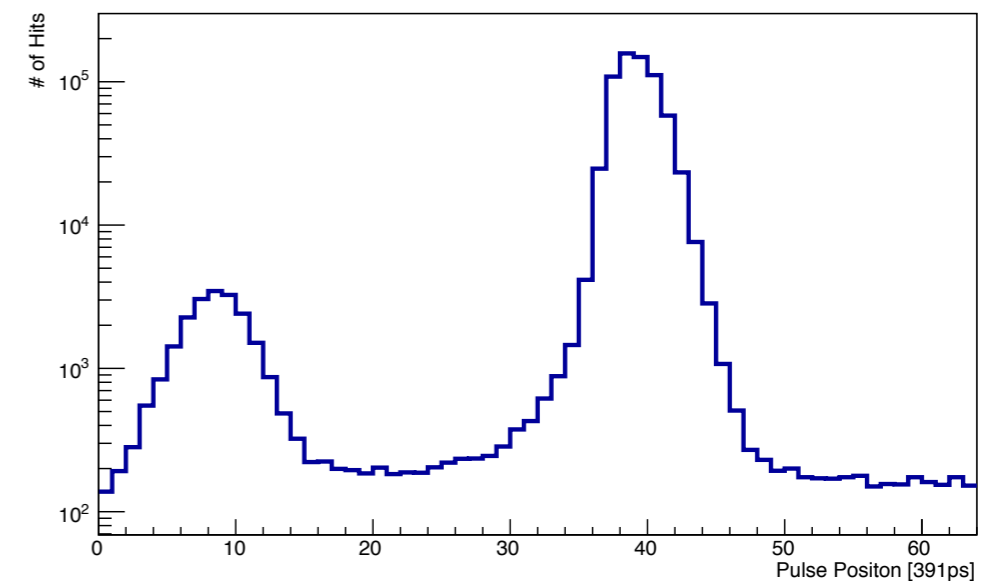
- 4 modules placed symmetrically around the beam pipe at  $\varphi = 0^\circ$ ,  $\varphi = 90^\circ$ ,  $\varphi = 180^\circ$  and  $\varphi = 270^\circ$
- Mounted at angle  $45^\circ$  towards the beam pipe in order to increase the signal
- BCM sensors located in the endpoint of the module:  $r = \sim 55$  mm,  $\eta = \sim 4.2$
- Sensors are made of pCVD diamonds:
  - High charge mobility
  - Radiation hardness
  - Almost negligible leakage current
- Box is made of G10, with the inner sides covered with a  $35 \mu\text{m}$  thick Cu layer  $\rightarrow$  Shielding of the amplifiers from EMI



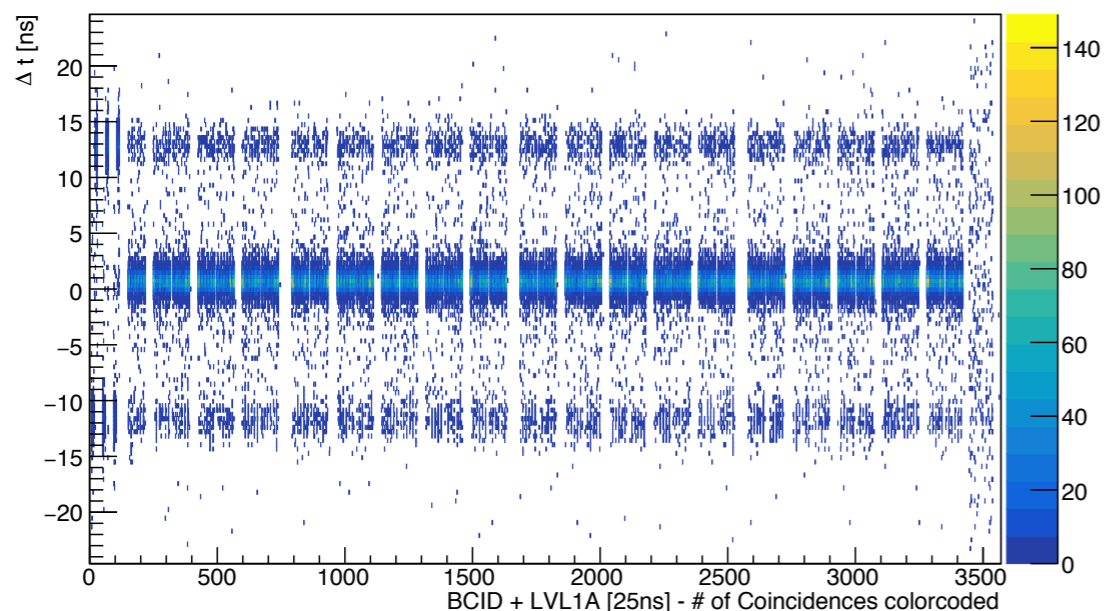
# BCM data - time distributions

- Good separation of signal and background in pulse position of a single module and  $\Delta t$  of the pulses from the two BCM stations (two sides):
  - Collision events at  $\Delta t = 0$
  - Beam-halo and beam-gas scattering at  $\Delta t = \pm 12.5$  ns
  - Background due to soft particles

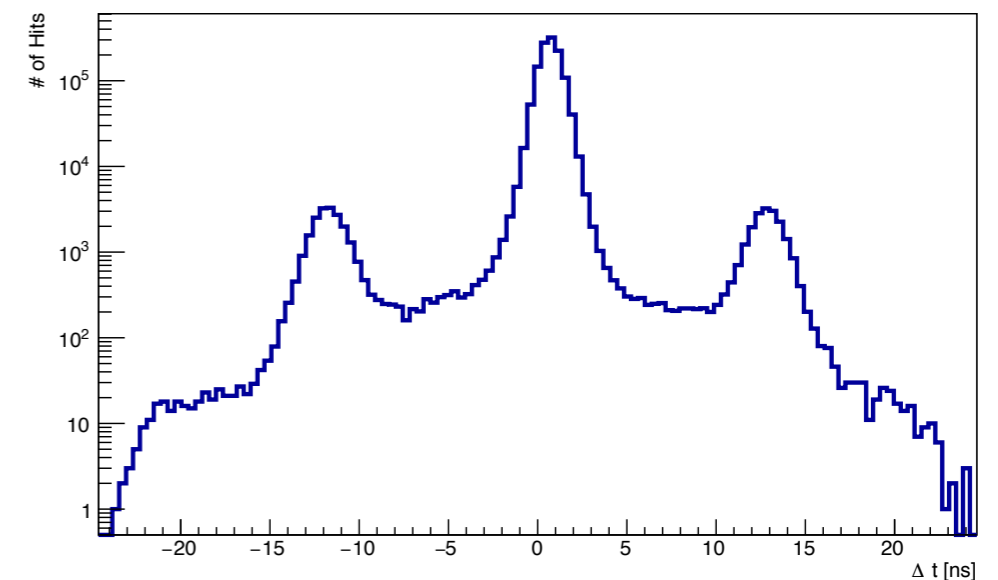
Pulse Position: ROD\_0\_LUMI (Run #: 364521, Run type: Physics)



$\Delta t = t_C - t_A$  Aligned vs BCID: ROD\_0\_LUMI (Run #: 364521, Run type: Physics)



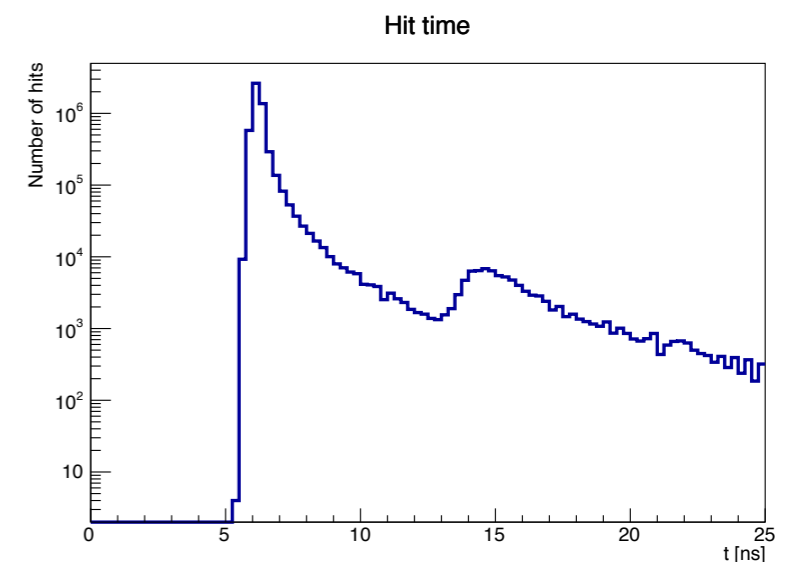
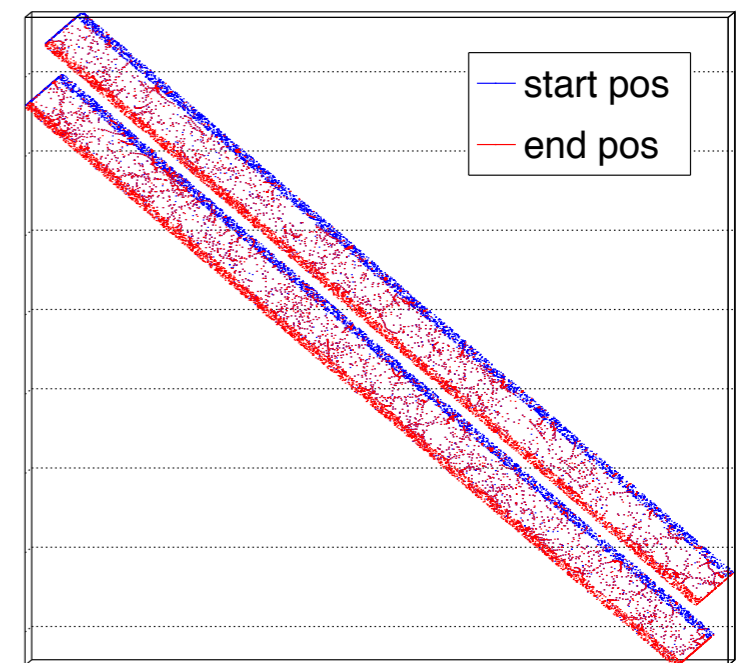
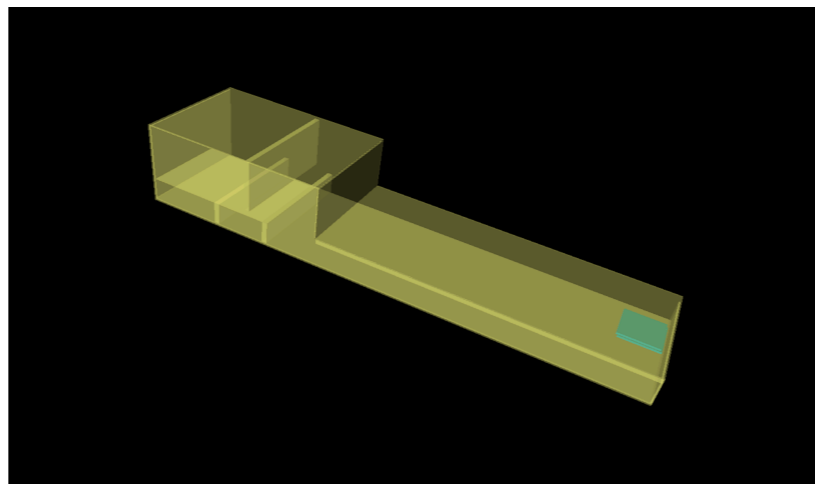
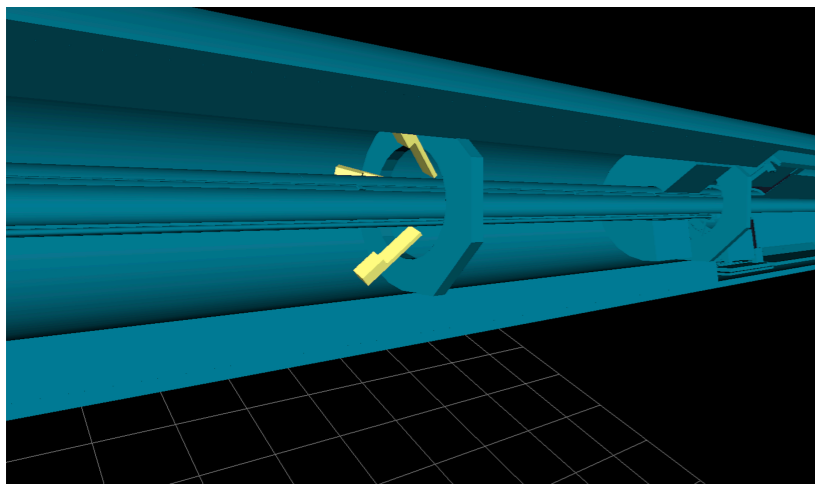
Hits vs  $\Delta t = t_C - t_A$ : ROD\_0\_LUMI (Run #: 364521, Run type: Physics)





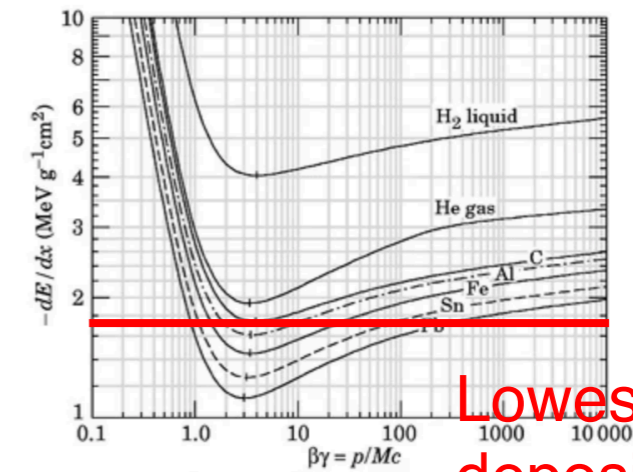
# BCM simulation

- BCM volumes included in the ATLAS simulation
  - Studies of the BCM performance → design of the BCM for high luminosity run (BCM')
  - Scattering of particles on the BCM modules
- Only diamond volumes are sensitive
- Output contains information about: hit start/end position, energy loss, time, truth particle, BCM module and diamond ID



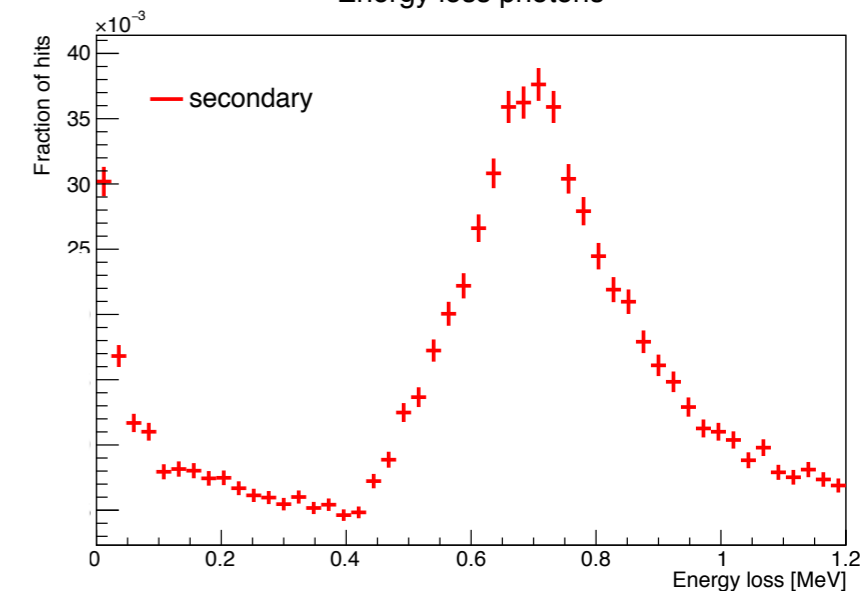
# BCM simulation

Particle type	Percentage of primaries	Percentage of secondaries
Photons	0,0%	67,9%
Pions	6,5%	11,4%
Electrons	3,2%	4,7%
Protons	0,2%	1,4%
Rest	1,1%	6,7%
Total	8,0%	92,0%

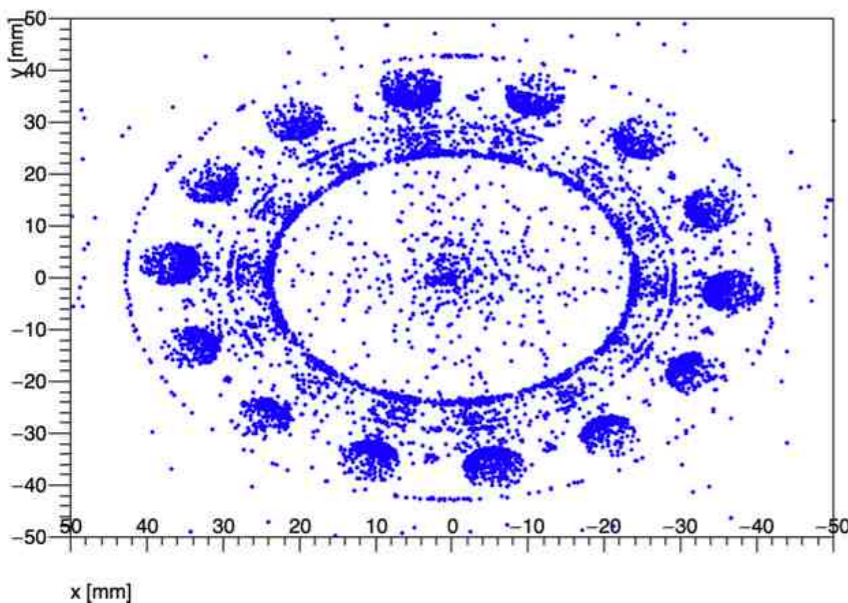


Lowest energy deposit per cm

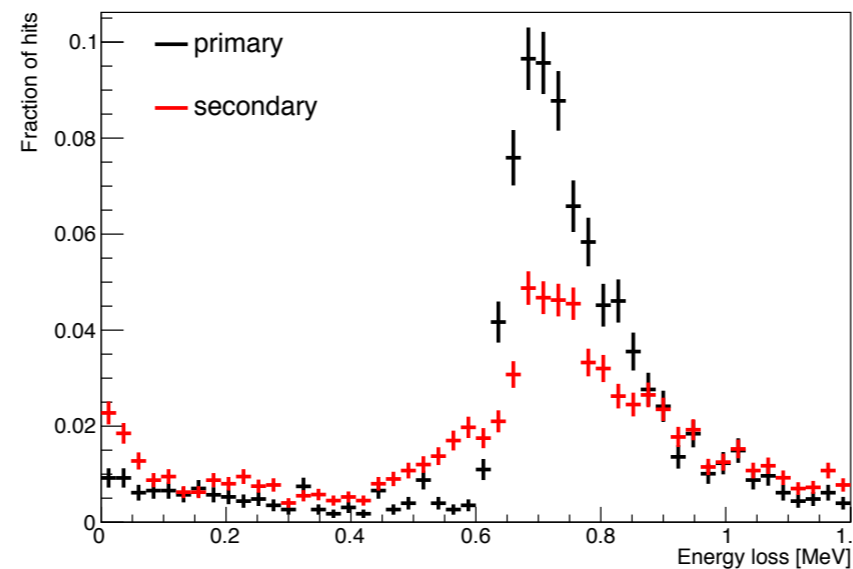
Energy loss photons



BCM hits, origin vertices profile

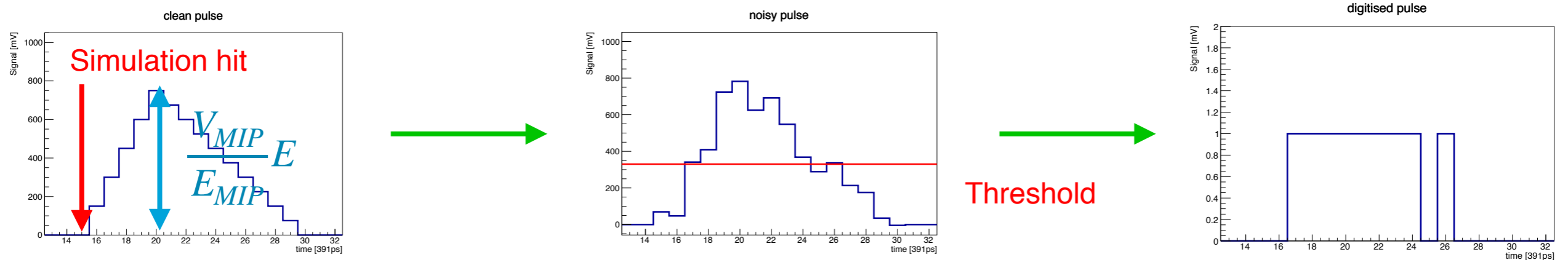


Energy loss of pions



# BCM digitisation

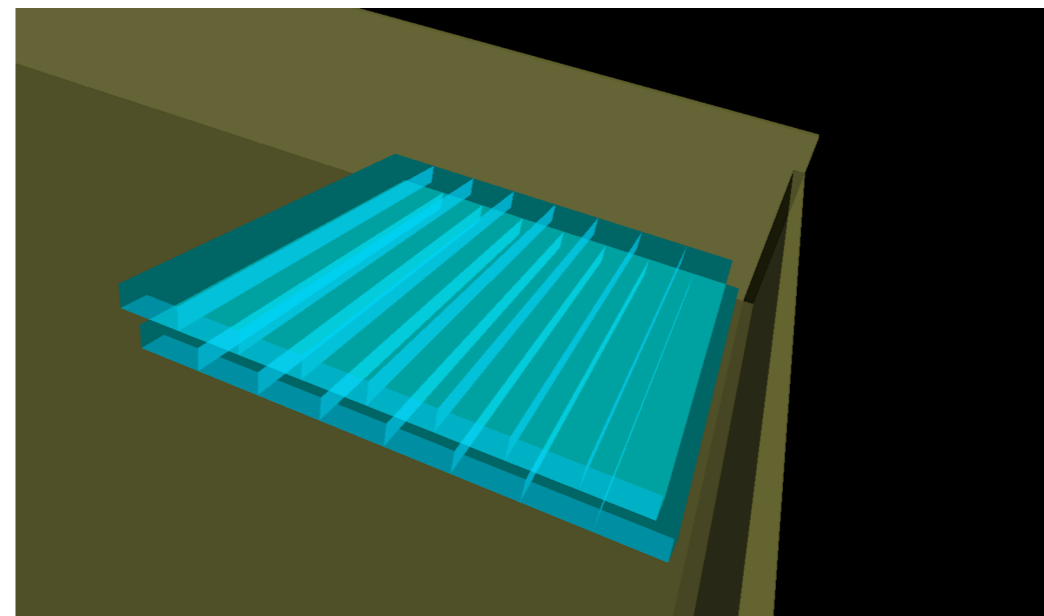
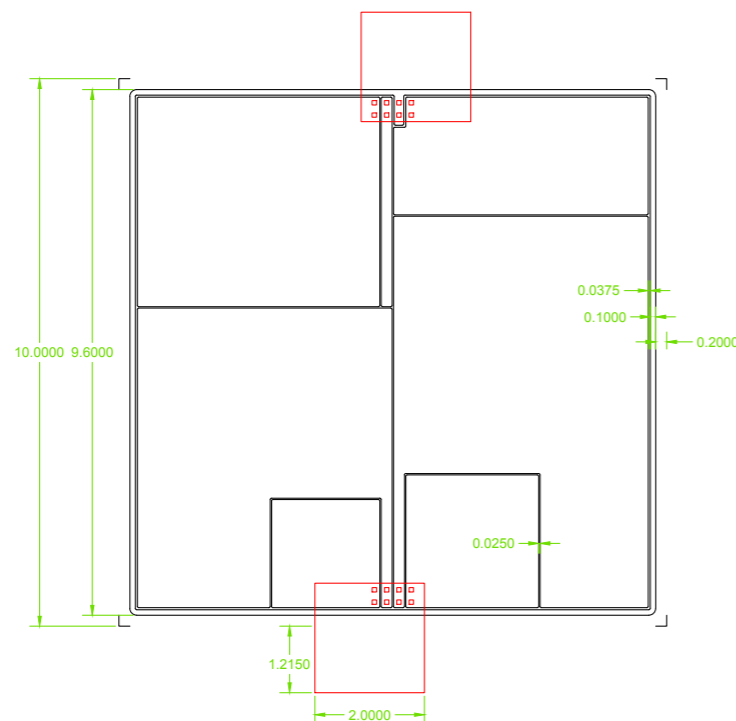
- ATLAS detector response is modelled in two steps: simulation and digitisation: in digitisation truth energy deposits from sensitive detector volumes are transformed into signal (charge collection efficiencies applied, time response, noise, detector resolution)
- In BCM signal is proportional to the energy deposition
- Pulses have triangular shape, with fixed rise and falling time
- Gaussian noise added on top of the pulse
- Splitting of the signal to luminosity and abort
- Digitisation of the pulse: thresholds applied in each of the 64 time windows for both signals





# BCM for high luminosity runs

- In Run 4 luminosity is expected to be order of magnitude higher
- BCM will need to cover wider dynamical range in terms of hits per time unit
- For different particle flux, different sensitive area is optimal:
  - sensitive area is too large → two subsequent pulses can merge
  - sensitive area is too small → larger statistical fluctuation
- BCM sensors are going to be composed of several pads, with different curvatures
  - Difficulty: How is the charge, deposited on a boundary, going to be shared among different pads?



# Conclusions

- BCM monitors beam confinement and measures luminosity
- Collision and non-collision events are discriminated, based on time measurement
- BCM for high luminosity needs to cover broader dynamical range
- Splitting the sensor into pads with different shapes
- Simulation is very important tool study of the performance of BCM'
- Sharing of the charge needs to be understood and thus accurately modelled in BCM simulation