

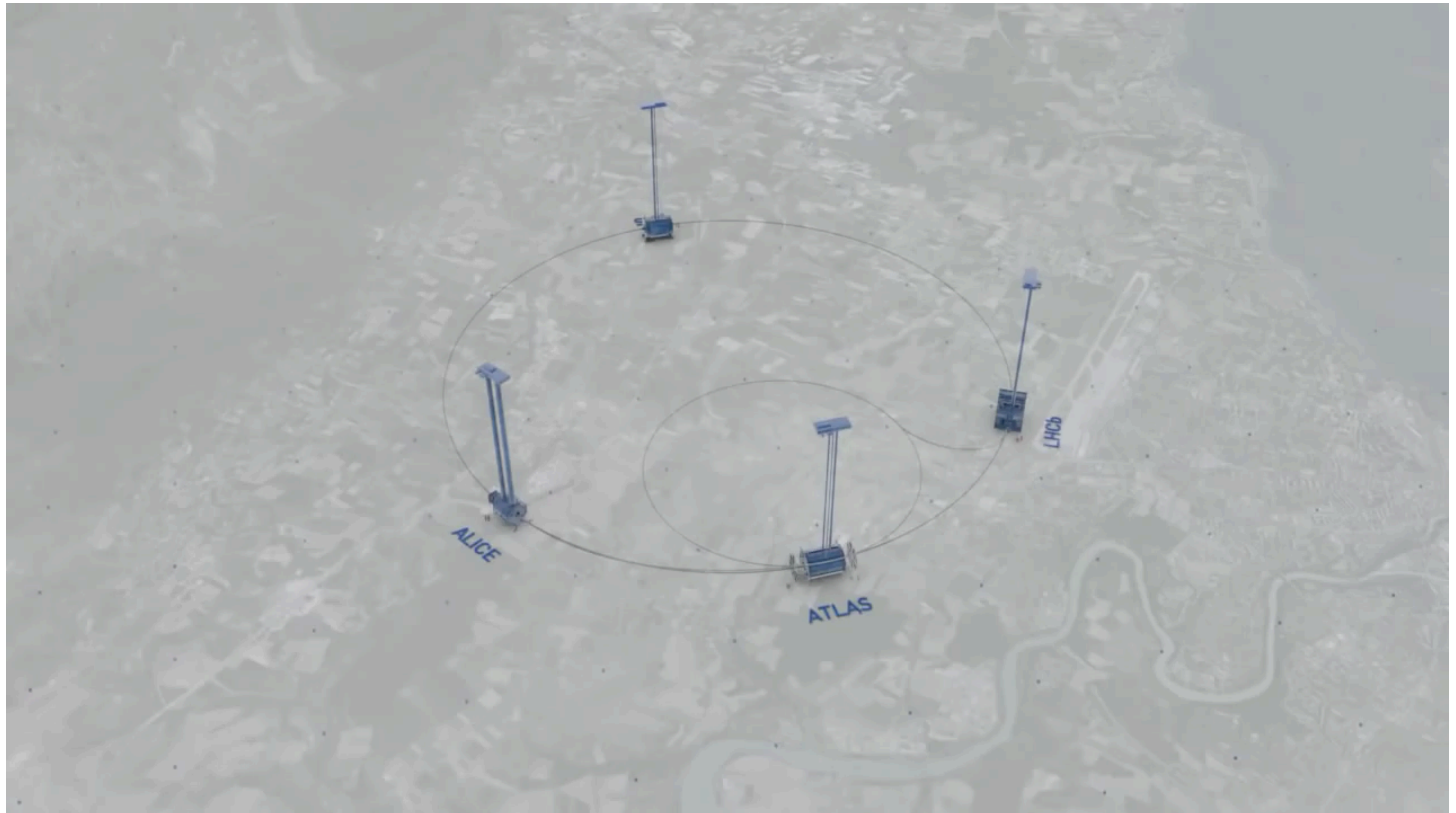
Deep Learning Applications for LHC experiments

Maurizio Pierini



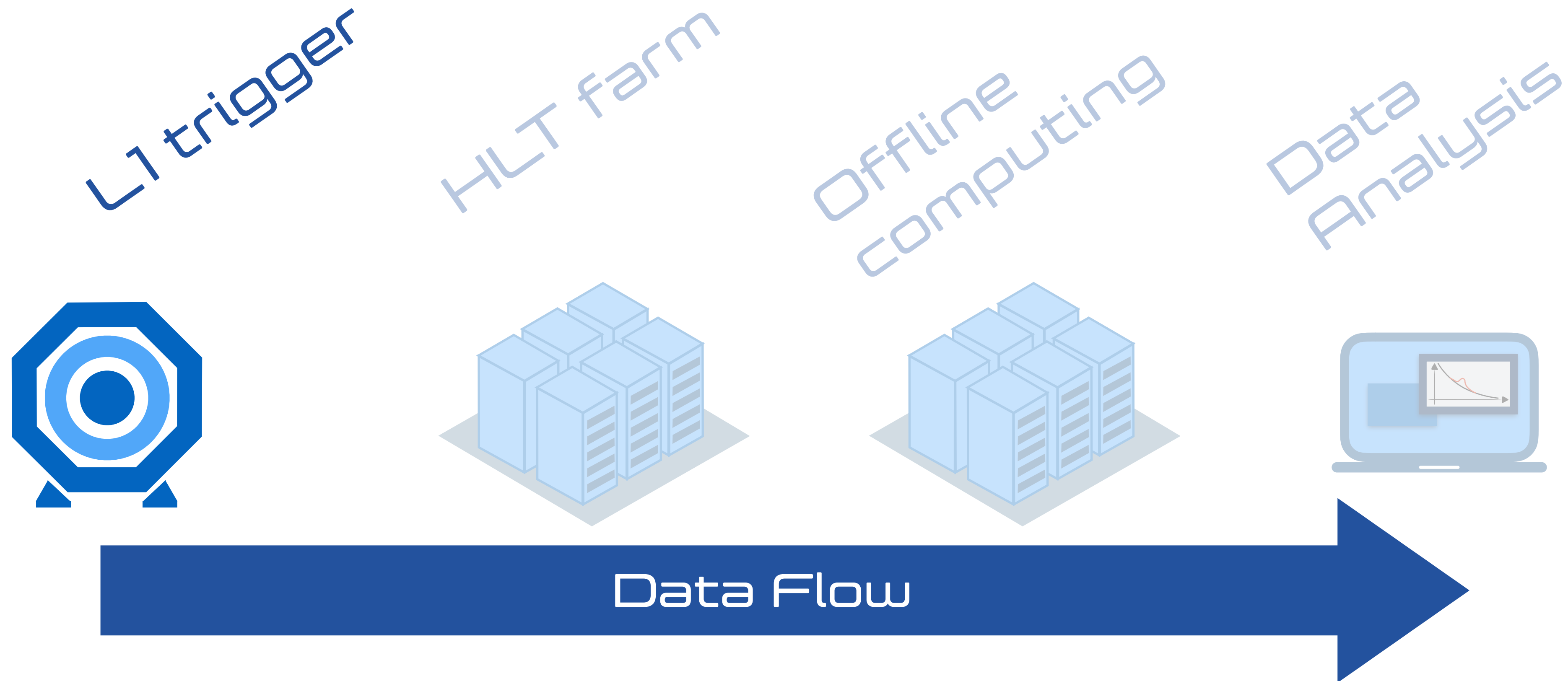
Oxford, 27/11/2018





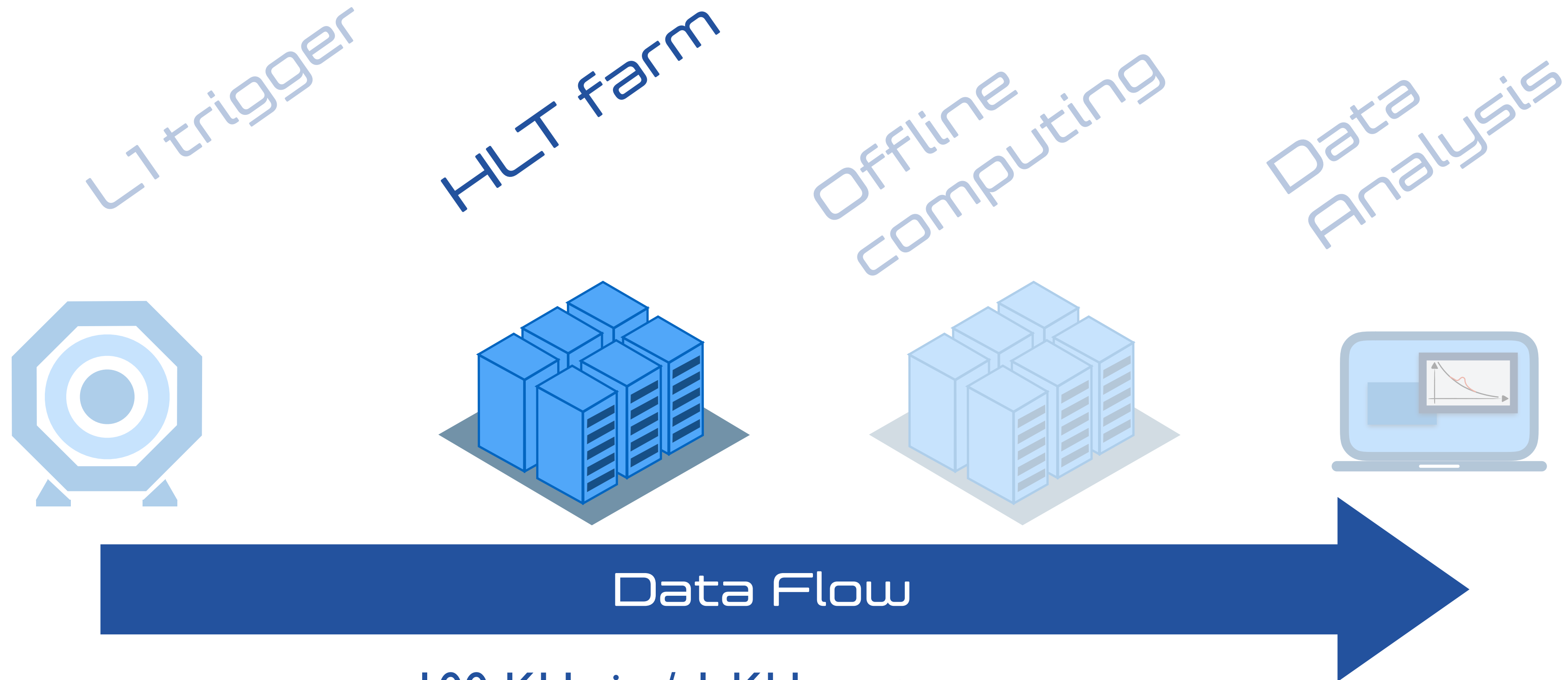
<https://www.youtube.com/watch?v=jDC3-QSiLB4>

The LHC Big Data problem



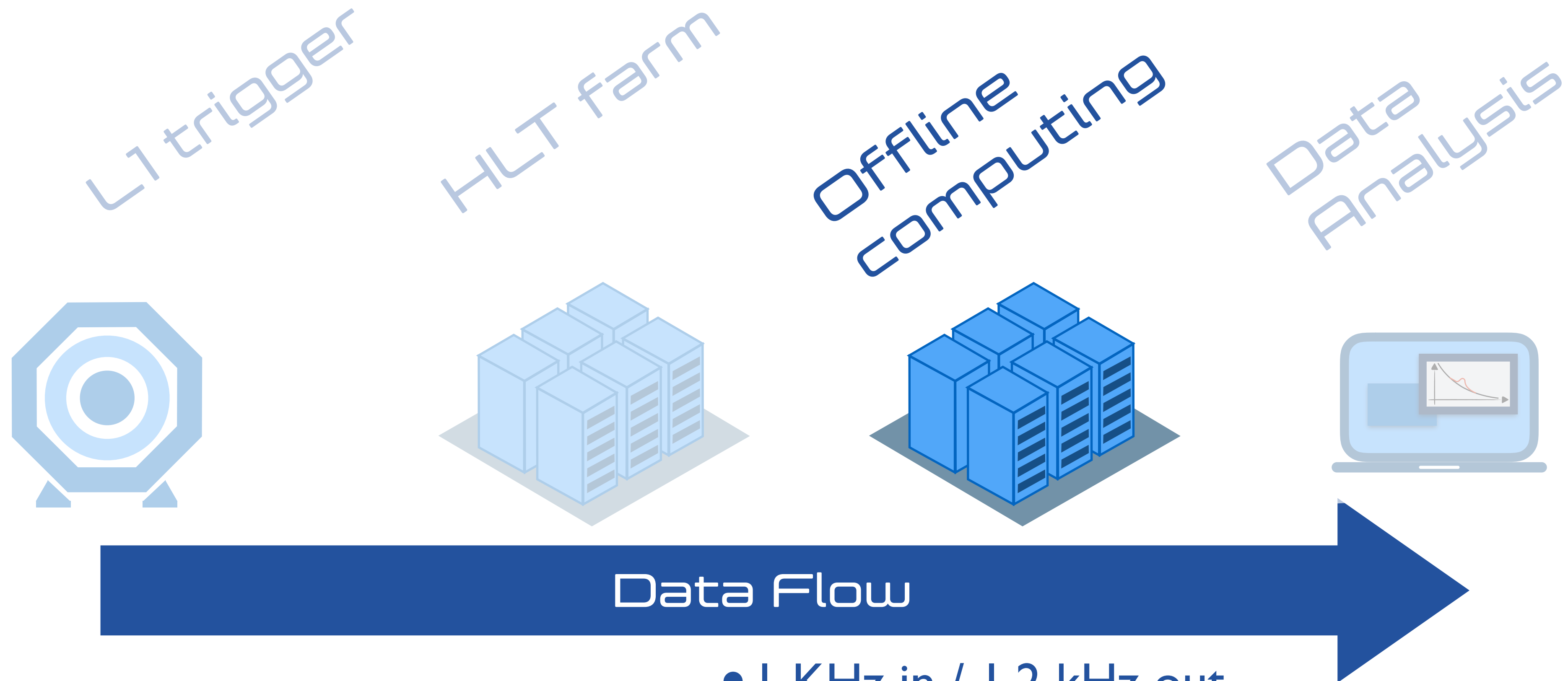
- 40 MHz in / 100 KHz out
- ~ 500 KB / event
- Processing time: ~10 μ s
- Based on coarse local reconstructions
- FPGAs / Hardware implemented

The LHC Big Data problem



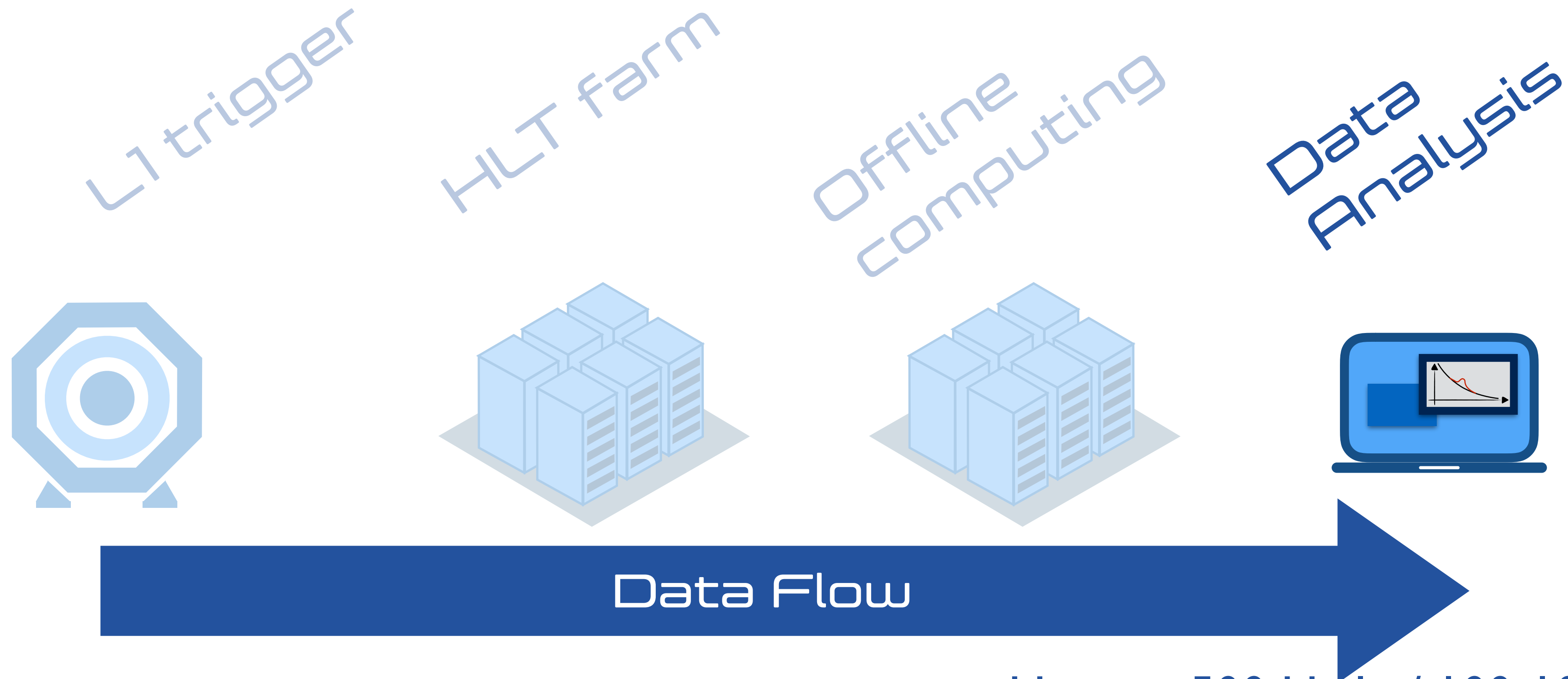
- 100 KHz in / 1 KHz out
- ~ 500 KB / event
- Processing time: ~100 ms
- Based on simplified global reconstructions
- Software implemented on CPUs

The LHC Big Data problem



- 1 KHz in / 1.2 kHz out
- ~ 1 MB / 200 kB / 30 kB per event
- Processing time: ~20 s
- Based on accurate global reconstructions
- Software implemented on CPUs

The LHC Big Data problem

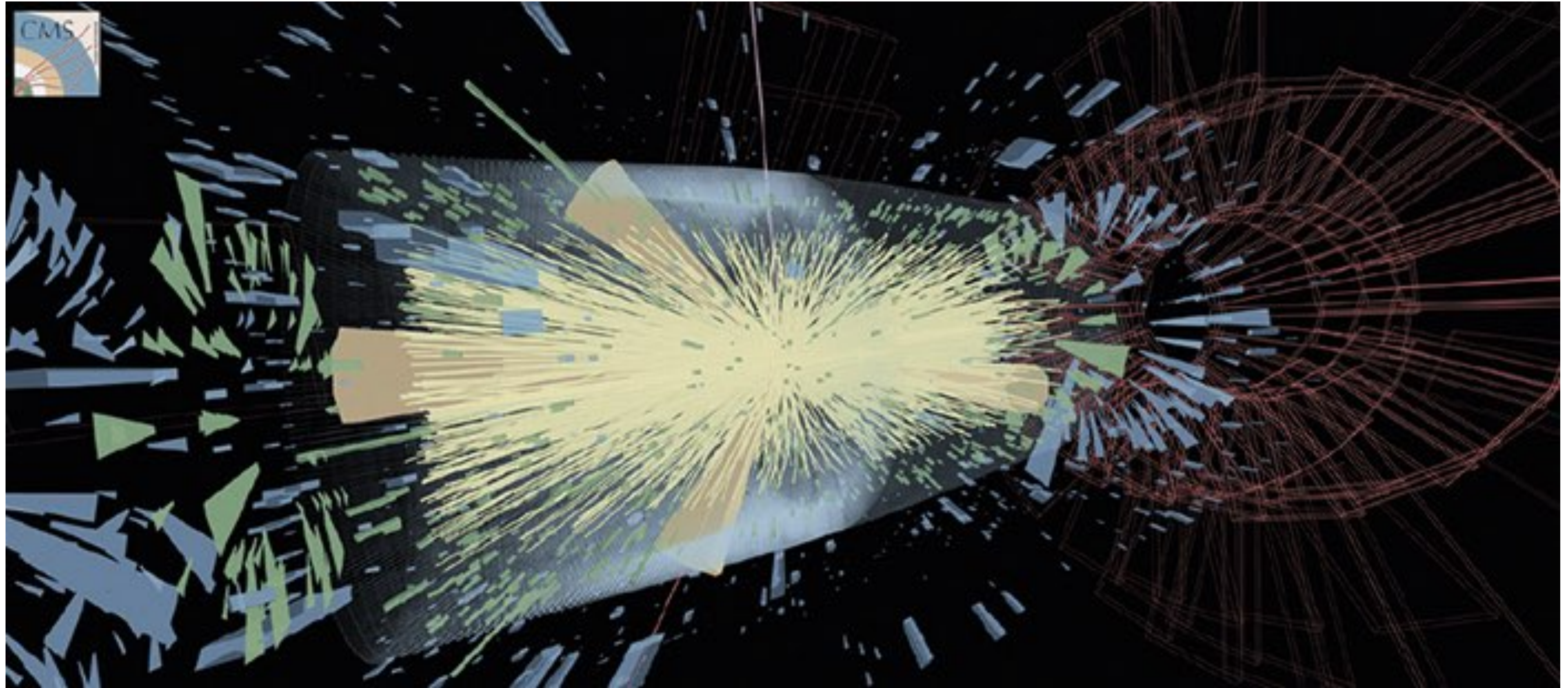


- Up to ~ 500 Hz In / 100-1000 events out

- < 30 KB per event

- Processing time irrelevant

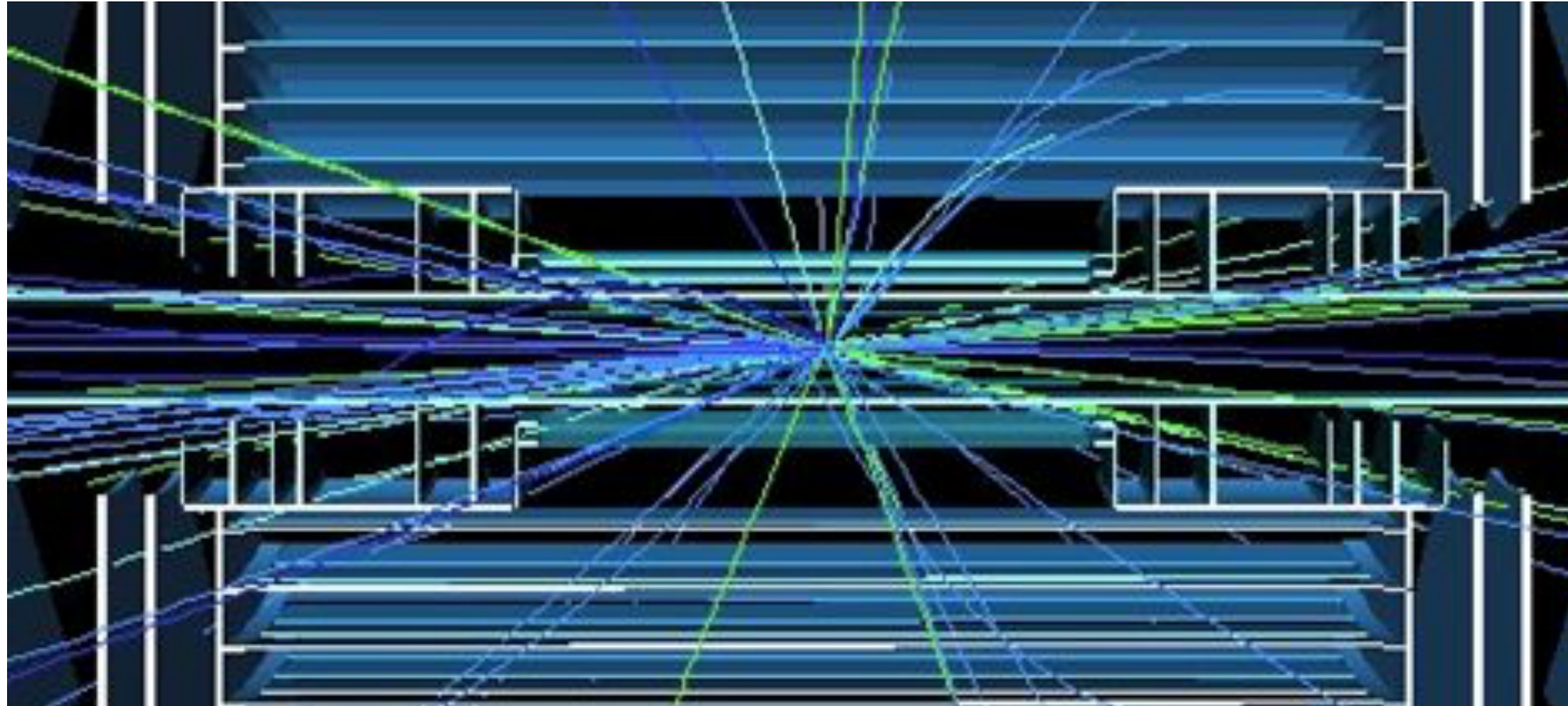
- User-written code + centrally produced selection algorithms



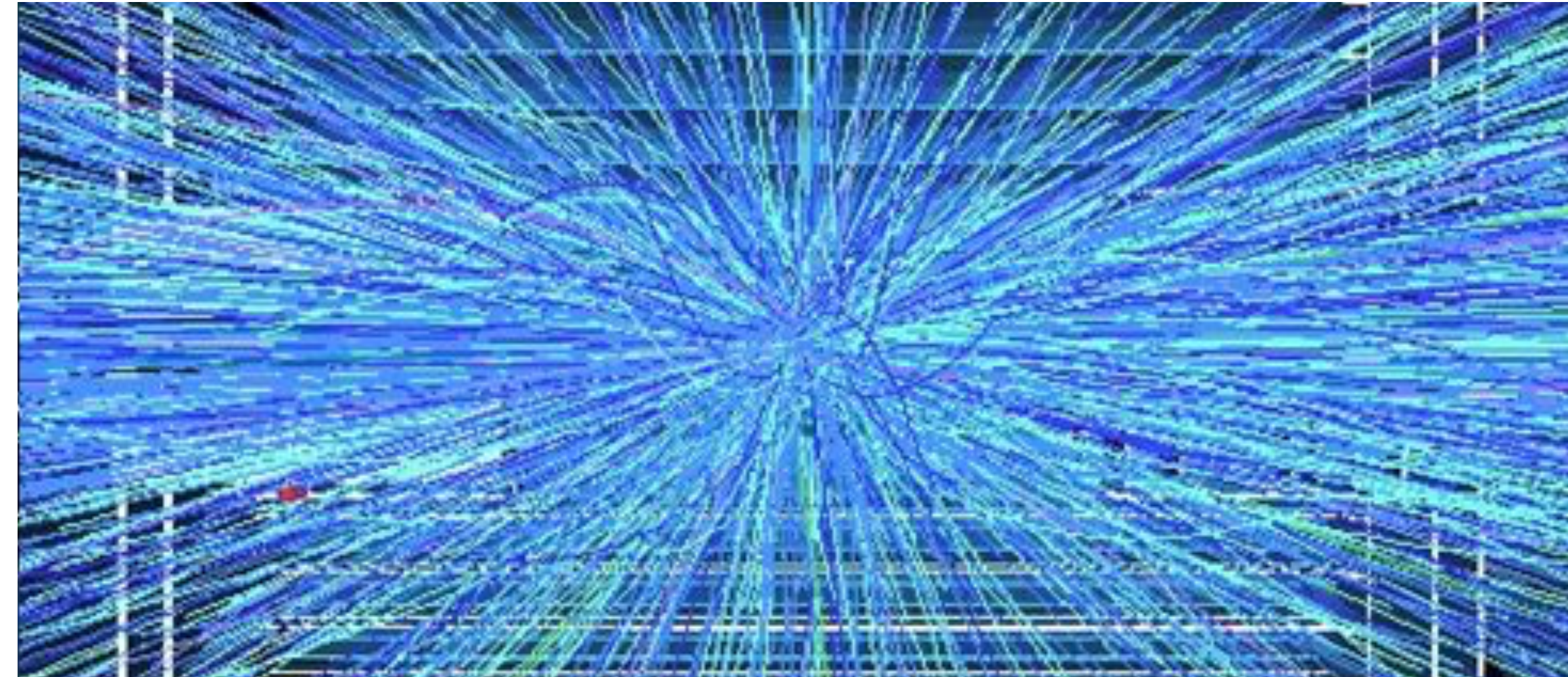
LHC future and its big challenge

HL-LHC: elephant in the room

5 interactions/beam cross



400 interactions/beam cross



This is when the R&D has to happen

LHC Today

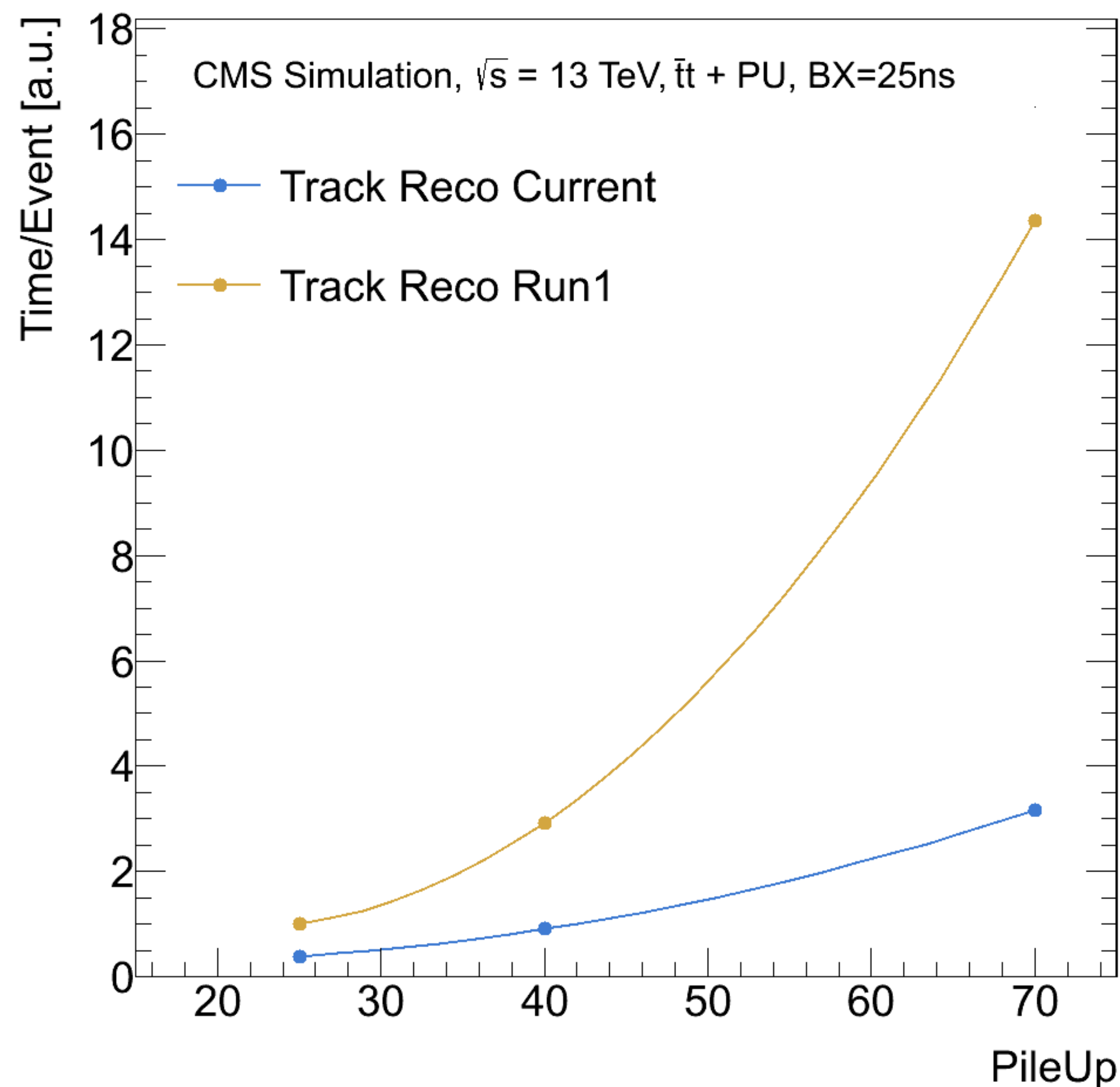
- ▶ ~40 collisions/event
- ▶ ~10 sec/event processing time
- ▶ (at best) Same computing resources as today

HL_LHC

- ▶ ~200 collisions/event
- ▶ ~minute/event processing time
- ▶ (at best) Same computing resources as today

HL-LHC: elephant in the room

- ◎ *Flat budget vs. more needs = current rule-based reconstruction algorithms will not be sustainable*
- ◎ *Adopted solution: more granular and complex detectors → more computing resources needed → more problems*
- ◎ ***Modern Machine Learning might be the way out***

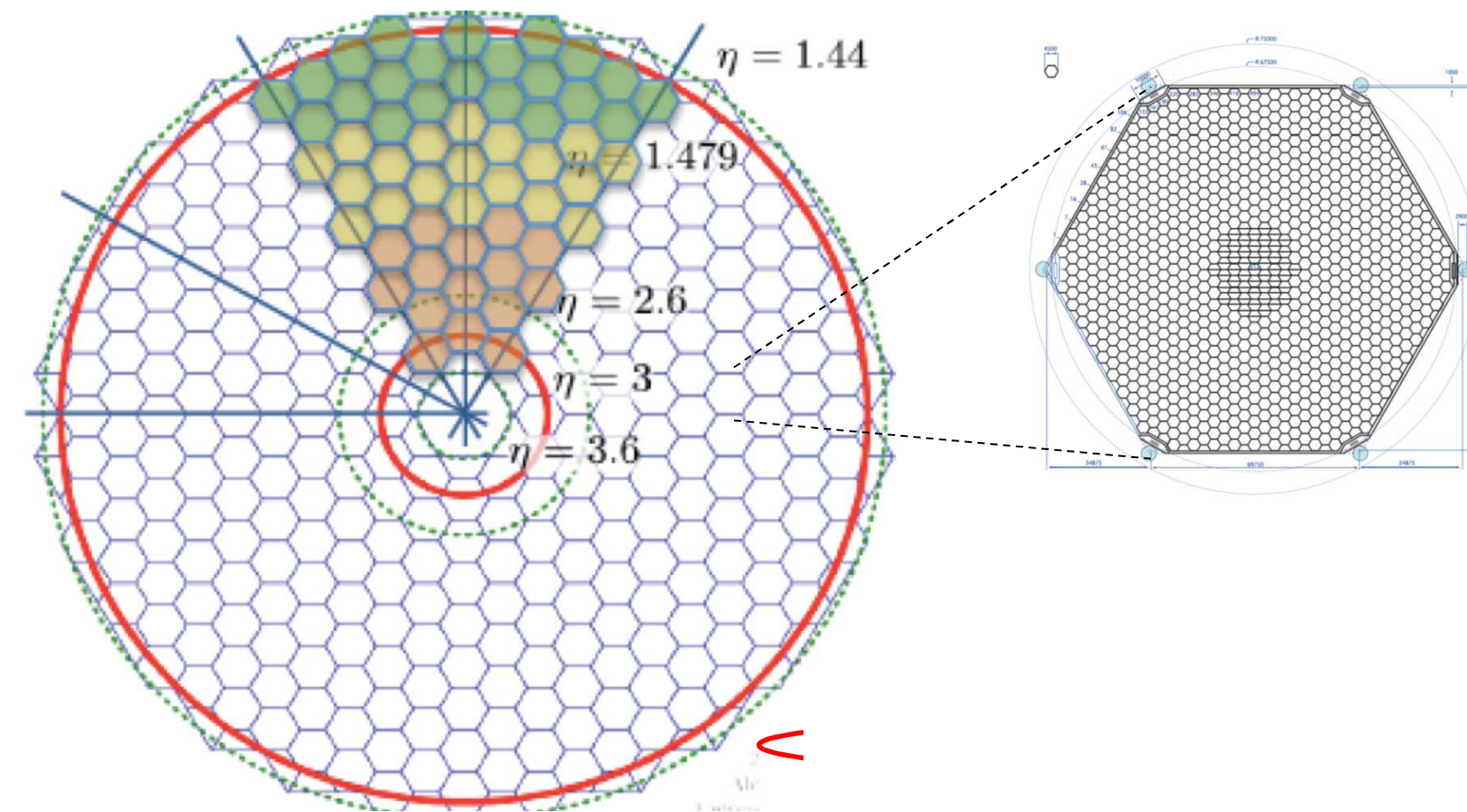


HL-LHC: elephant in the room

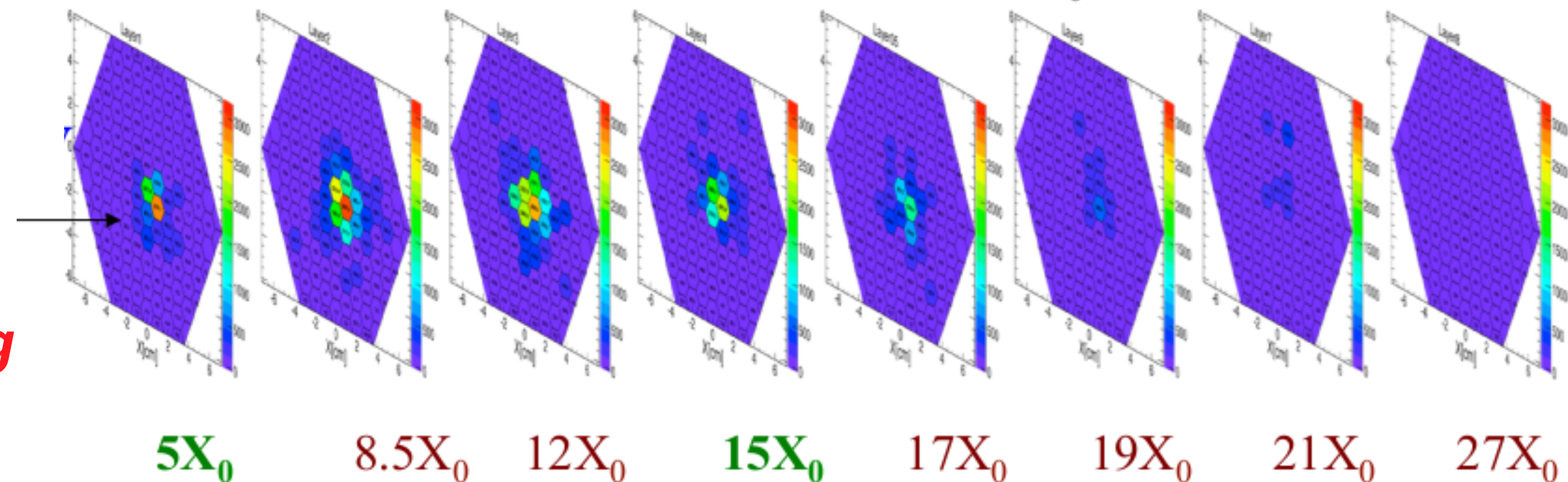
● *Flat budget vs. more needs = current rule-based reconstruction algorithms will not be sustainable*

● *Adopted solution: more granular and complex detectors → more computing resources needed → more problems*

● ***Modern Machine Learning might be the way out***

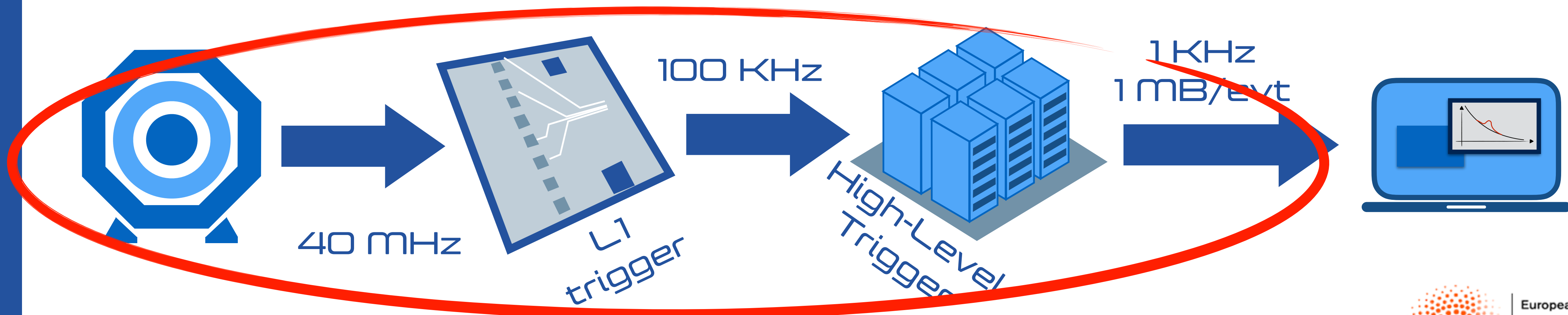


250 GeV electron passing through 8 layers ($27 X_0$)



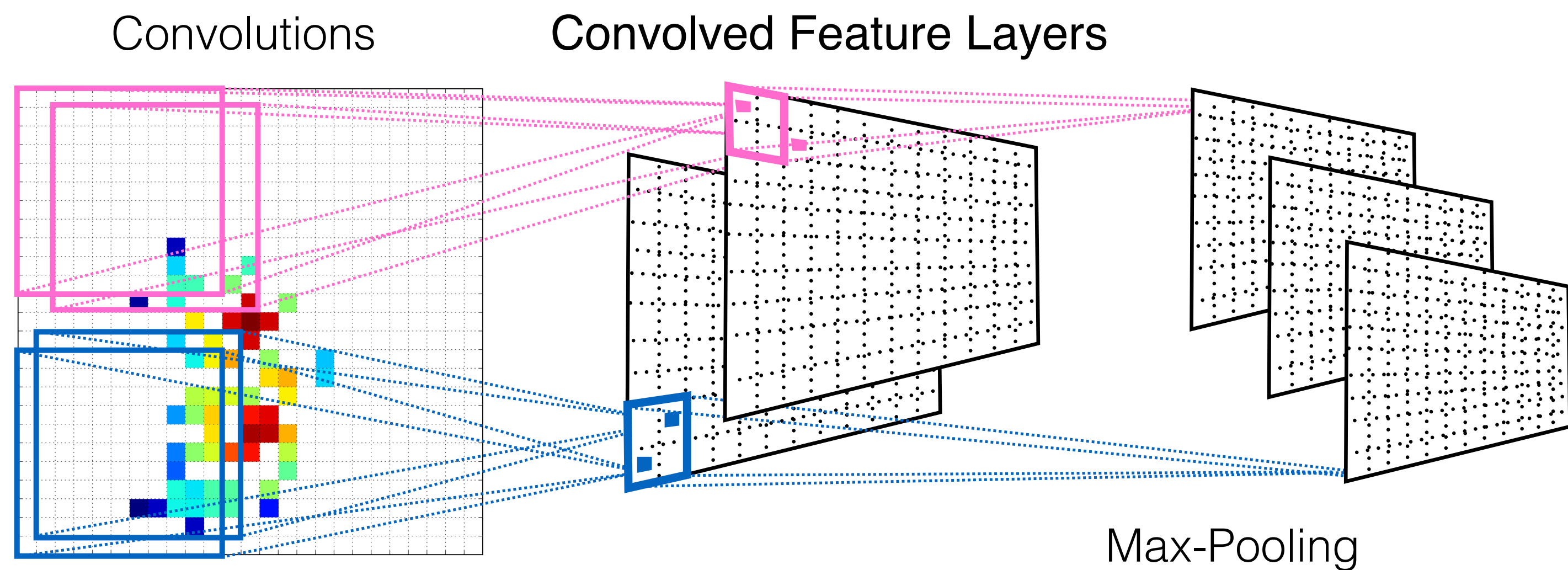
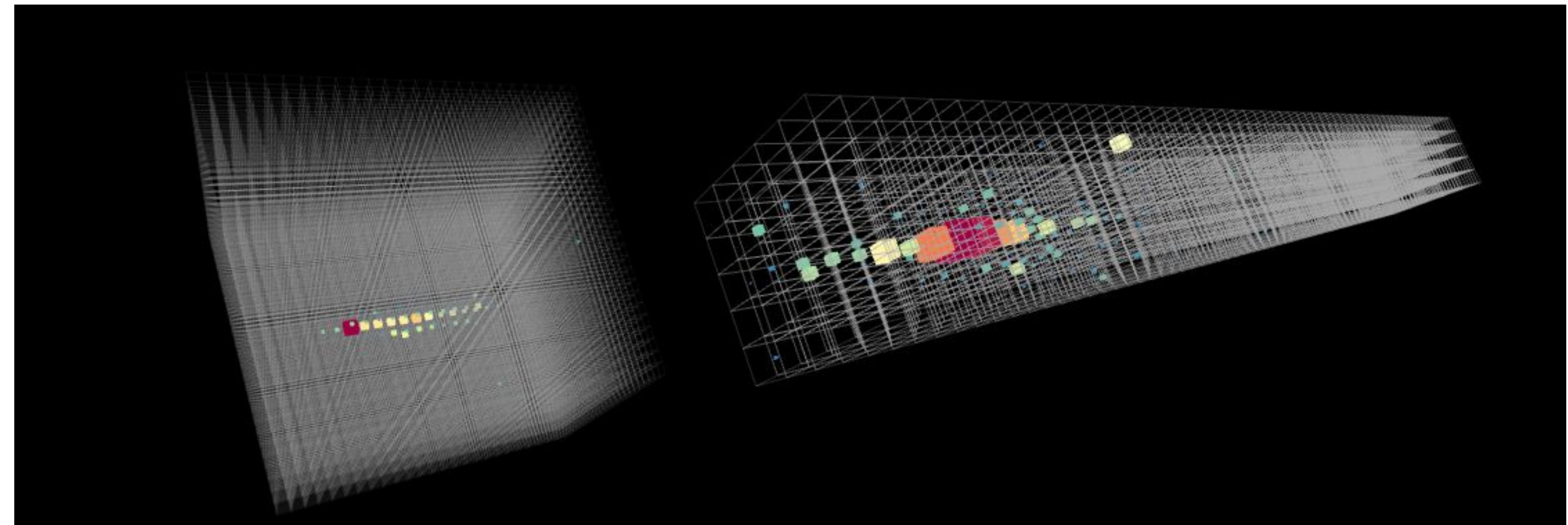
Deep Learning and LHC Big Data

- ◎ Possible solution to the HL-LHC problem: Deep Learning to be faster and better in what we do today, freeing resources for new ideas
- ◎ DL deployment needs to happen *in between collisions and data analysis* (trigger, reconstruction, ...), where freeing resources will make a difference



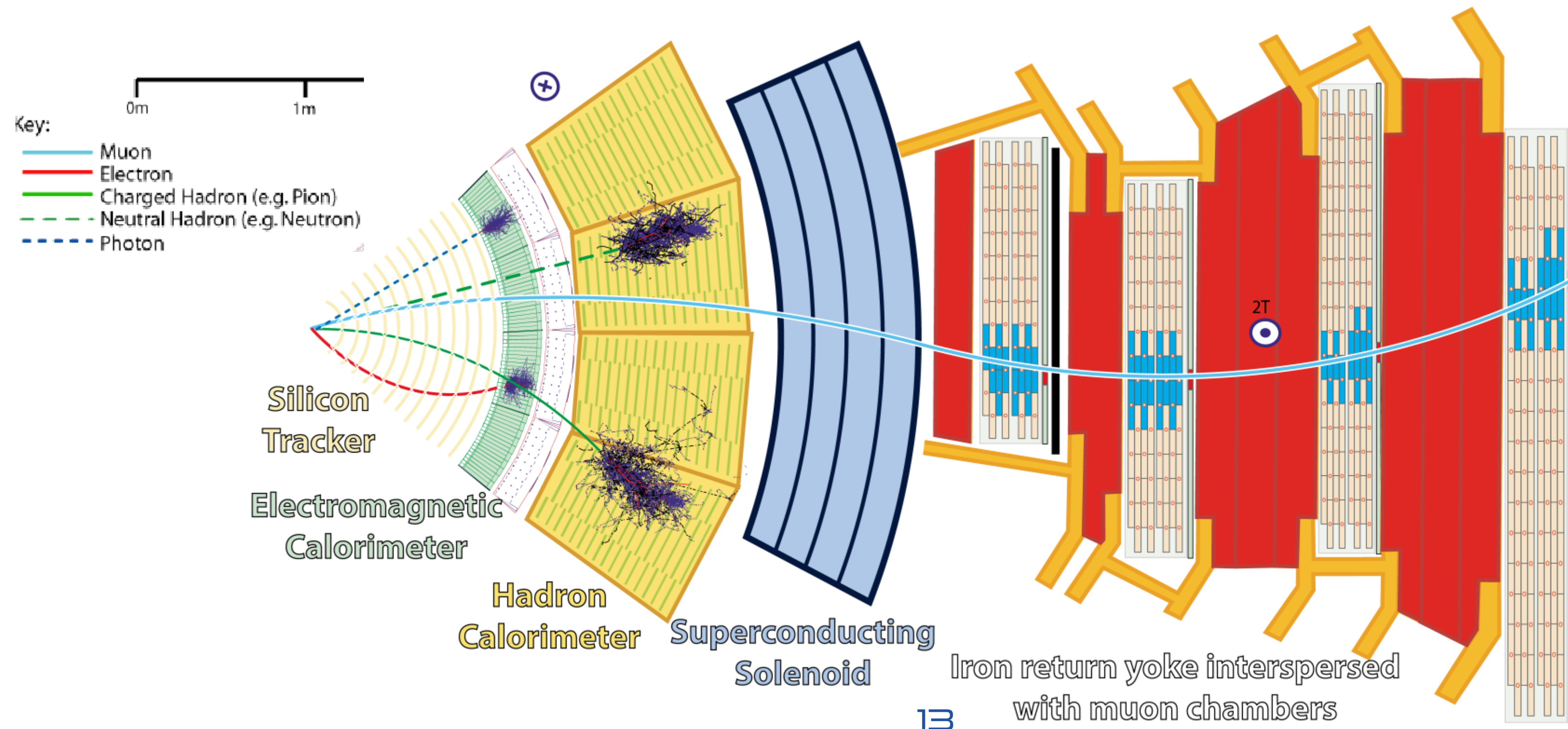
Particle reconstruction as image detection

- Future detectors will be 3D arrays of sensors with regular geometry
- Ideal configuration to apply Convolutional Neural Network
 - speed up reconstruction at similar performances
 - and possibly improve performances



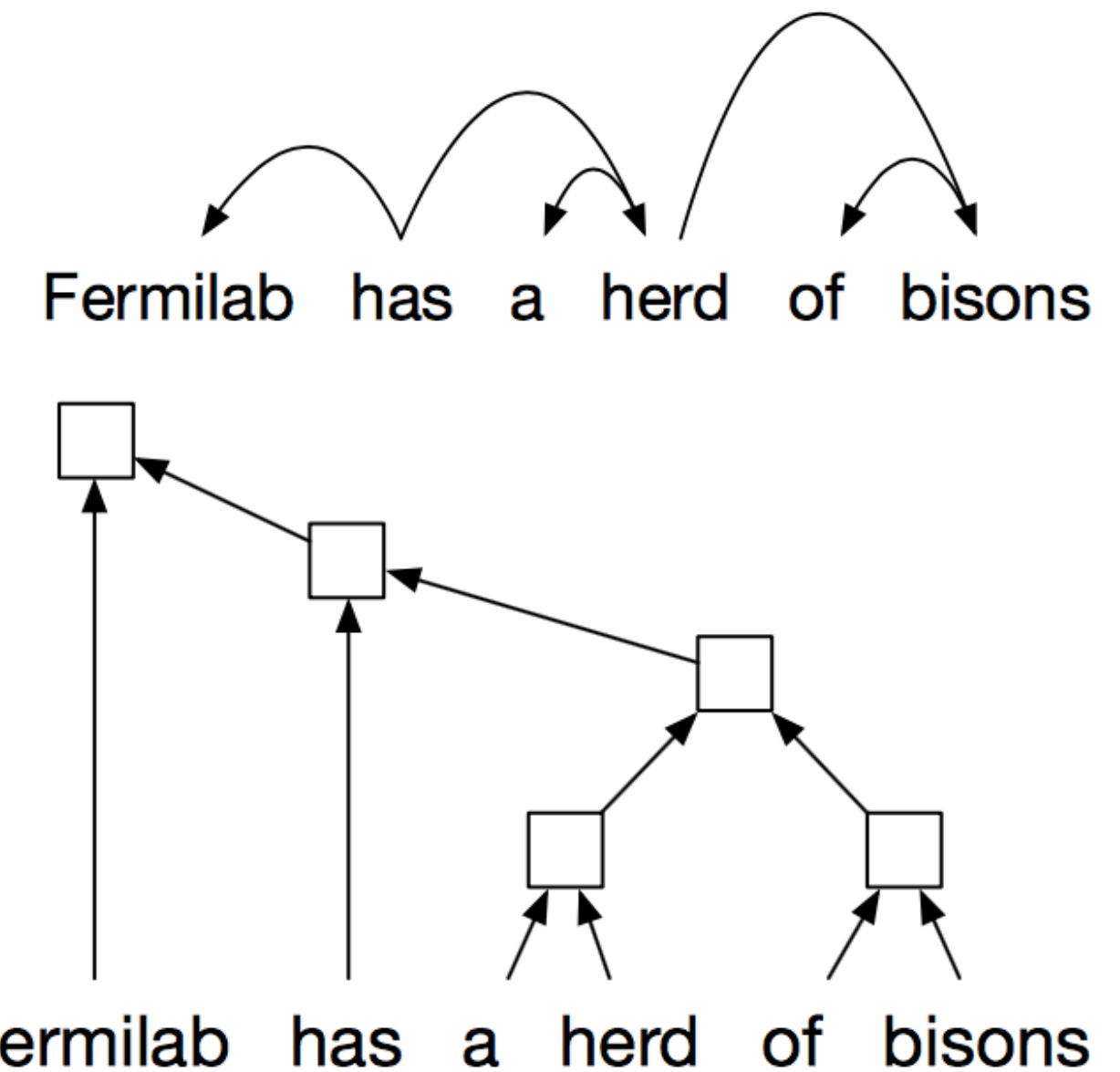
Particle Flow

- ◉ CMS uses PF to combine sub-detector information and produce a list of reconstructed particles
- ◉ Anything (jets, MET, resonances, etc) is reconstructed from these particles
- ◉ One could generalise the VAE new-physics-detection algorithm and make it PF compliant
 - ◉ integrated in the reconstruction flow @HLT
 - ◉ can abstract from model dependence inherited by any physics-motivated HLF choice



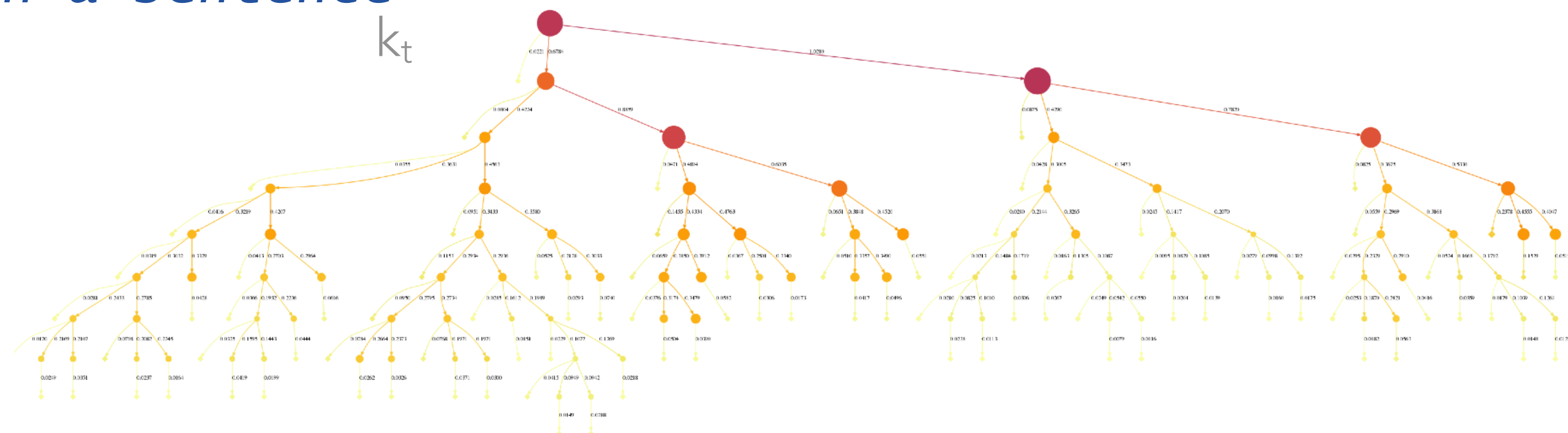
LHC events & language processing

- ⦿ *PF reco is not the best match for computing vision techniques (e.g., convolutional neural networks) don't work*
- ⦿ *one would have to convert the particles to a pixelated images, loosing resolution*
- ⦿ *Instead, list of particles can be processed by Deep Learning architectures designed for natural language processing (RNN, LSTMs, GRUs, ...)*



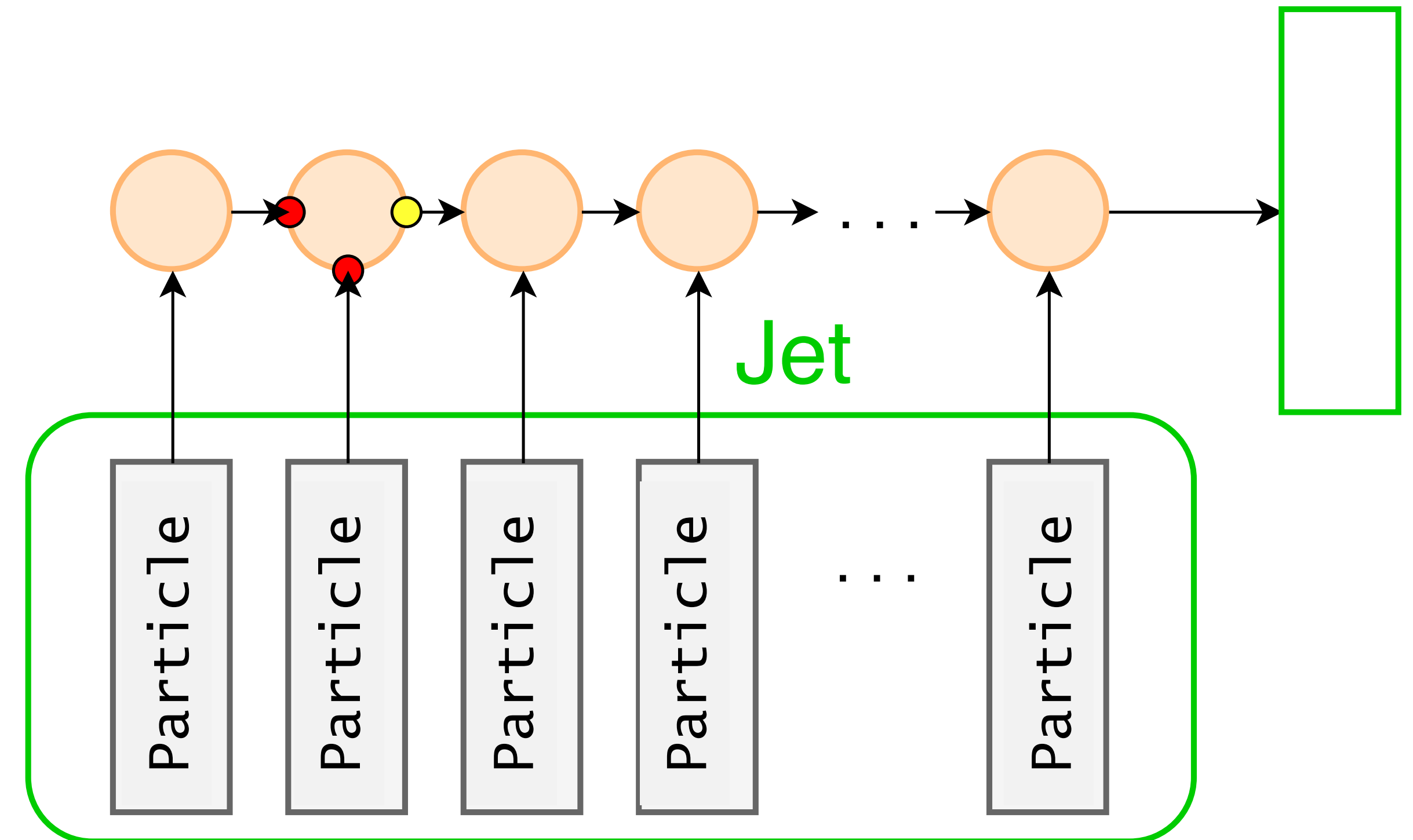
⦿ *particles as words in a sentence*

⦿ *QCD is the grammar*



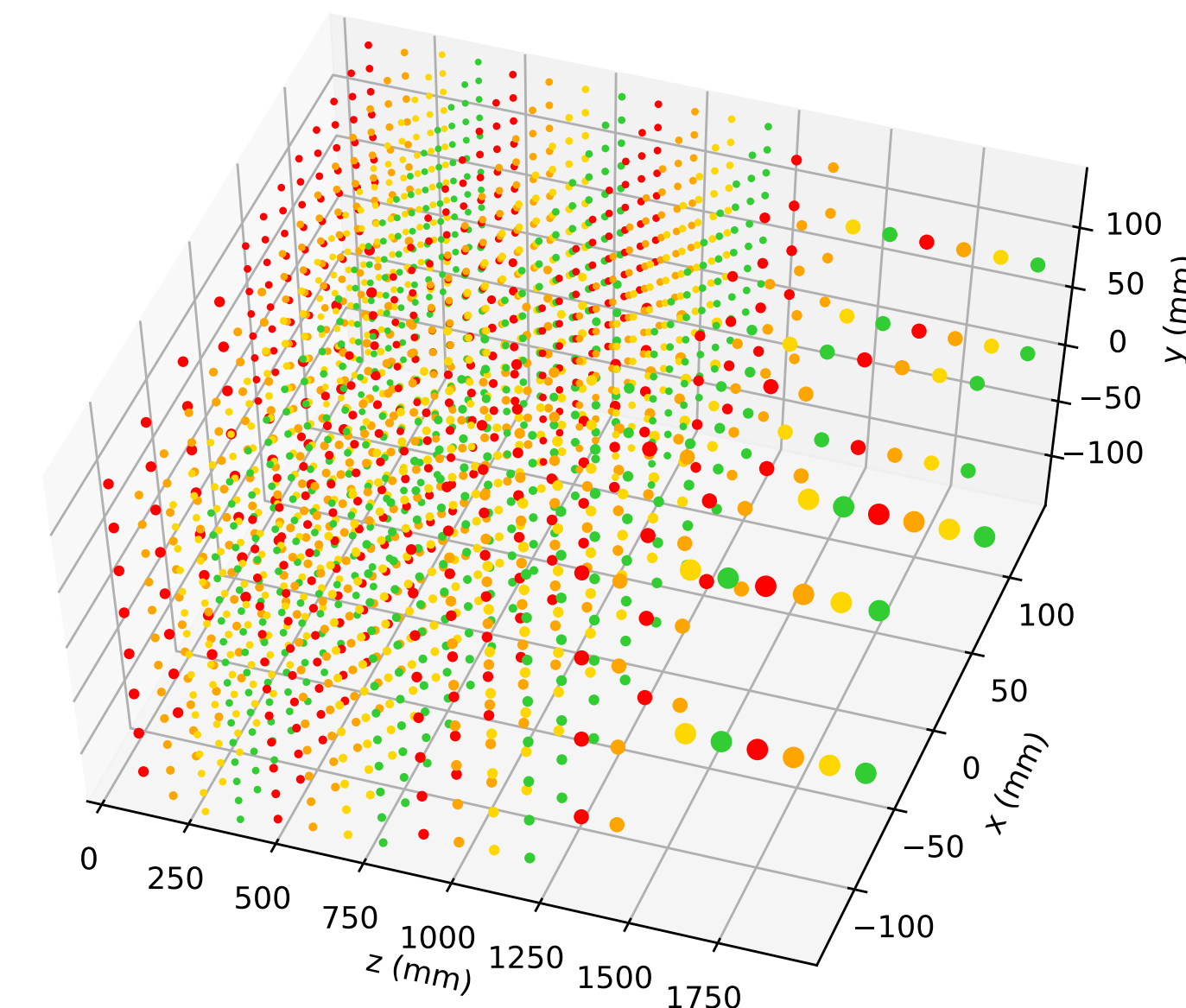
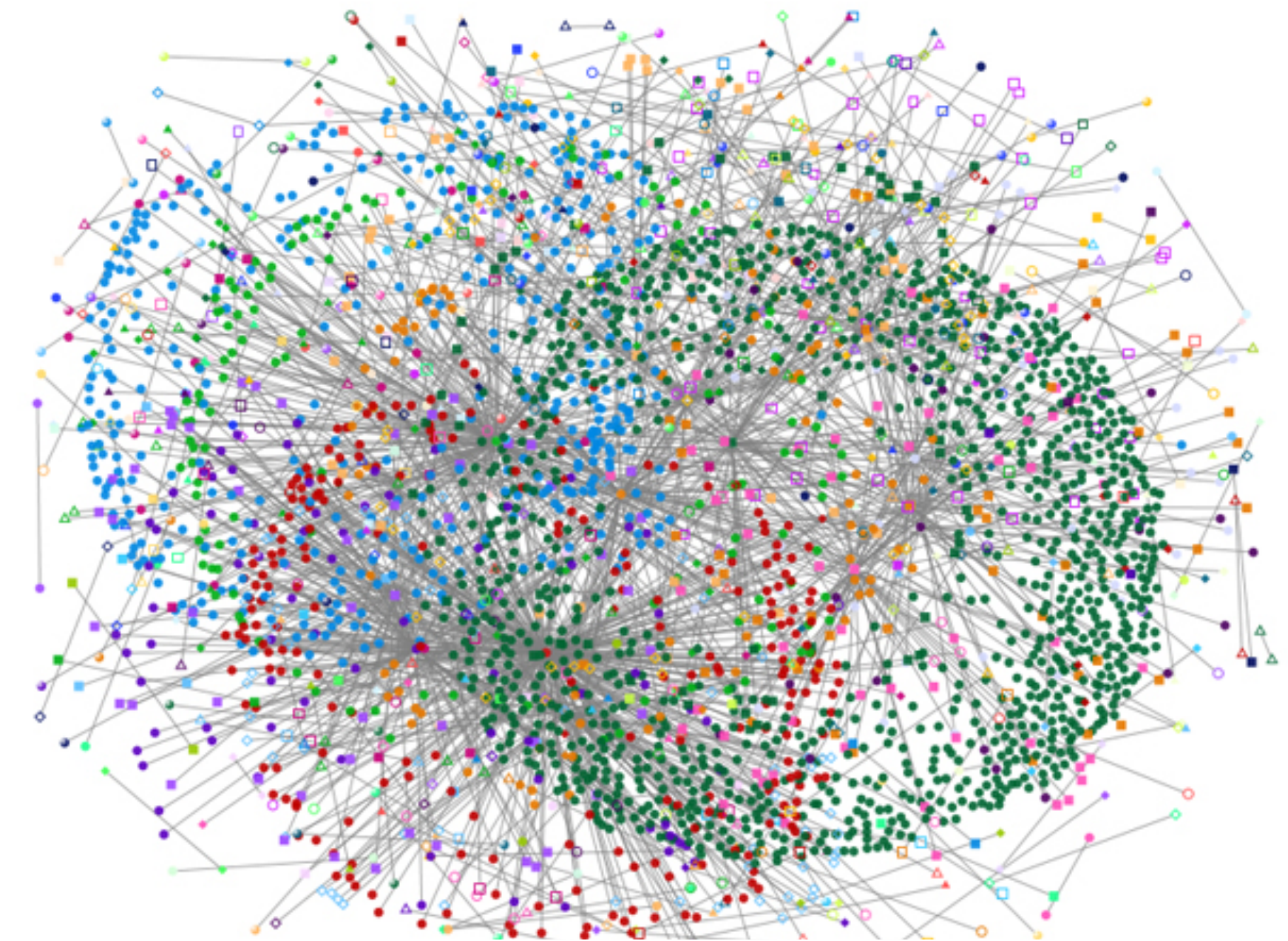
Recurrent Neural Networks

- A network architecture suitable to process an ordered sequence of inputs
- words in text processing
- a time series
- particles in a list
- Could be used for a single jet or the full event
- Next step: graph networks (active research direction)



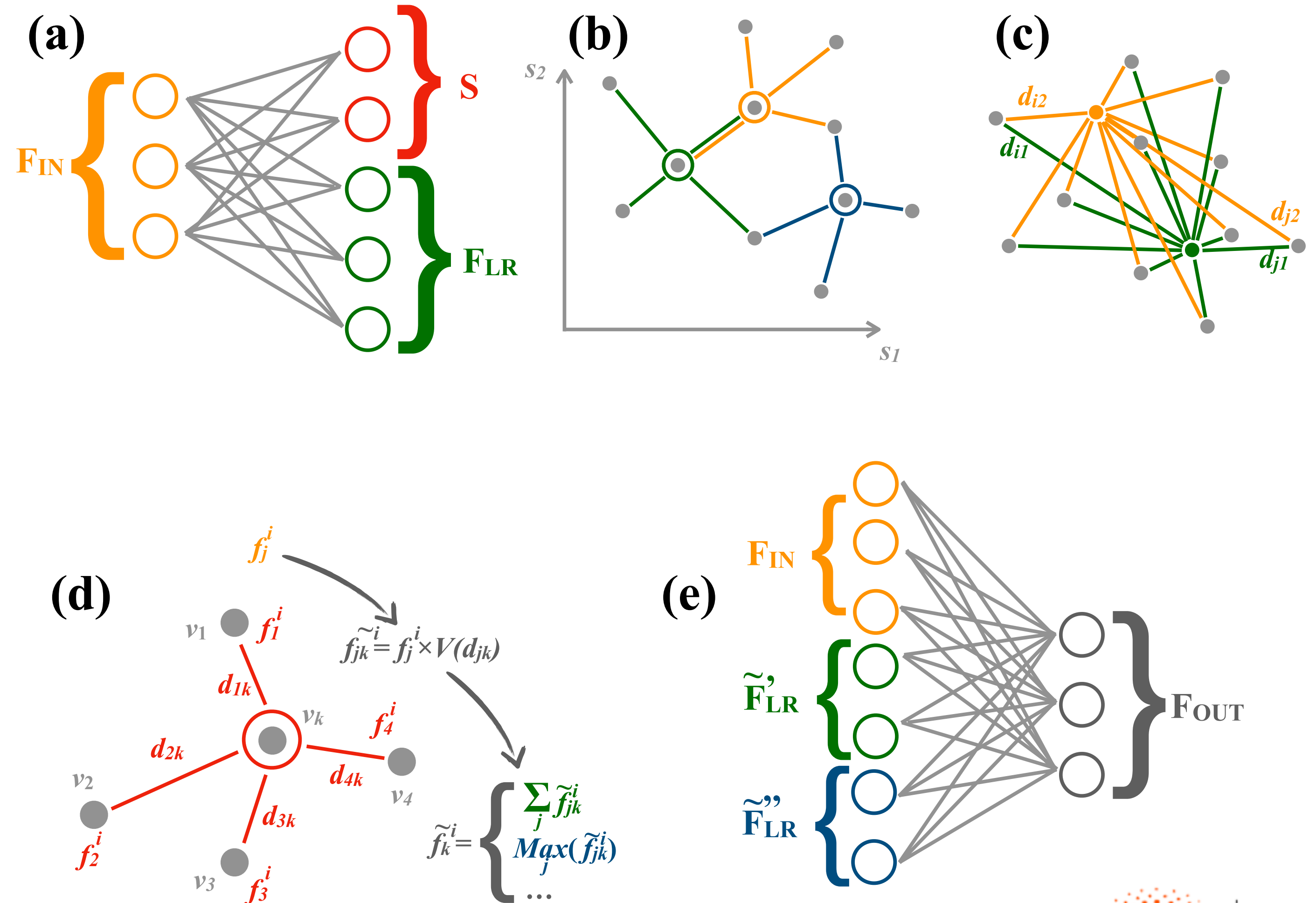
Graph Networks for real detectors

- ⦿ *CNNs assume that our detectors are regular arrays of sensors*
- ⦿ *Our detectors are not*
 - ⦿ *different components with different technologies*
 - ⦿ *some particle visible only to some part of the detector*
- ⦿ *CNNs don't really fit the sparsity of the collision data*
- ⦿ *Instead, we think graph networks can work better*



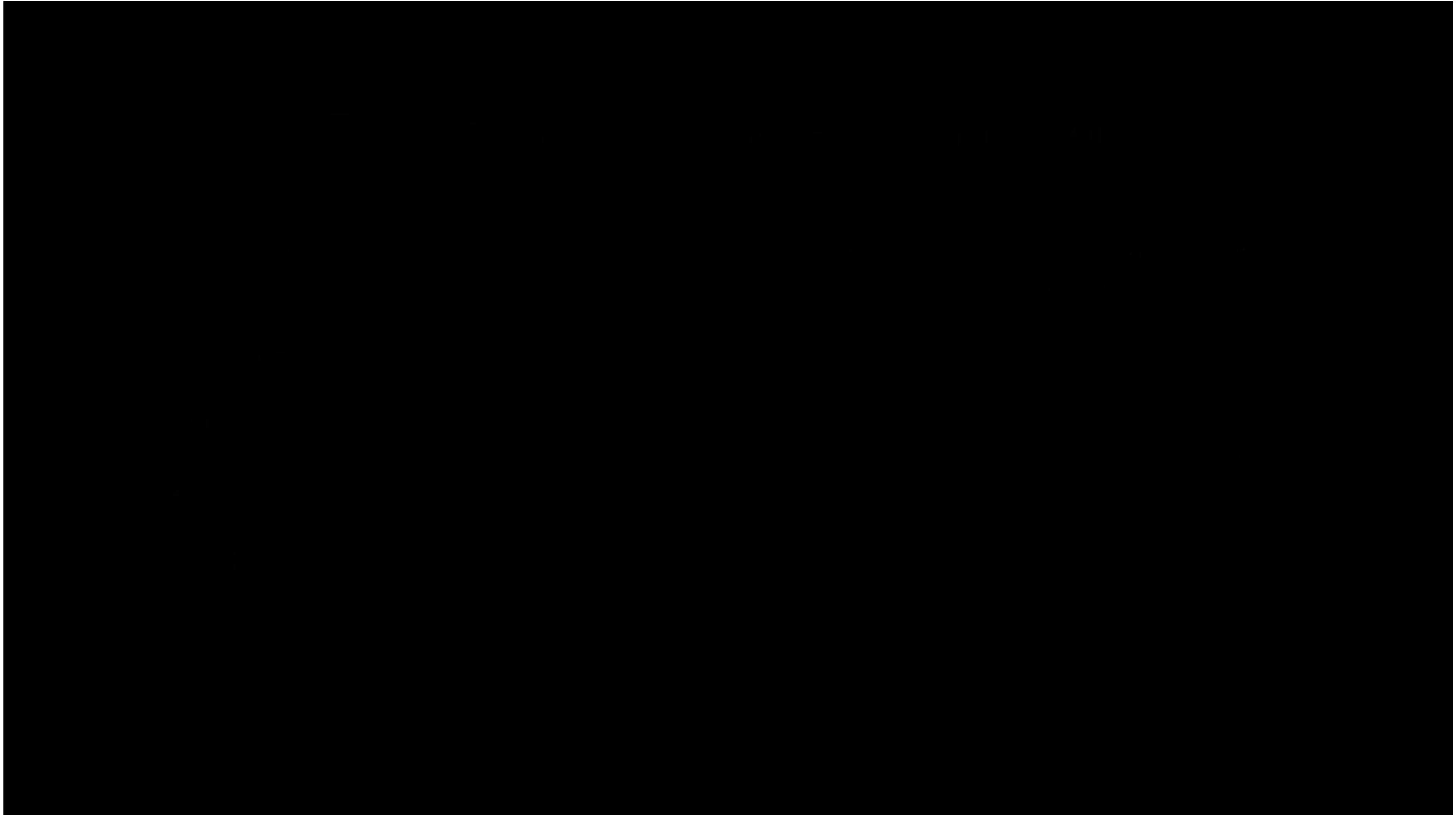
Learning representation

- What a graph network does is projecting a set of point into some other space where the concept of nearby (related to affinity) is learned
- Such a concept allows to abstract from the geometry of a detector and design experiment-independent architectures

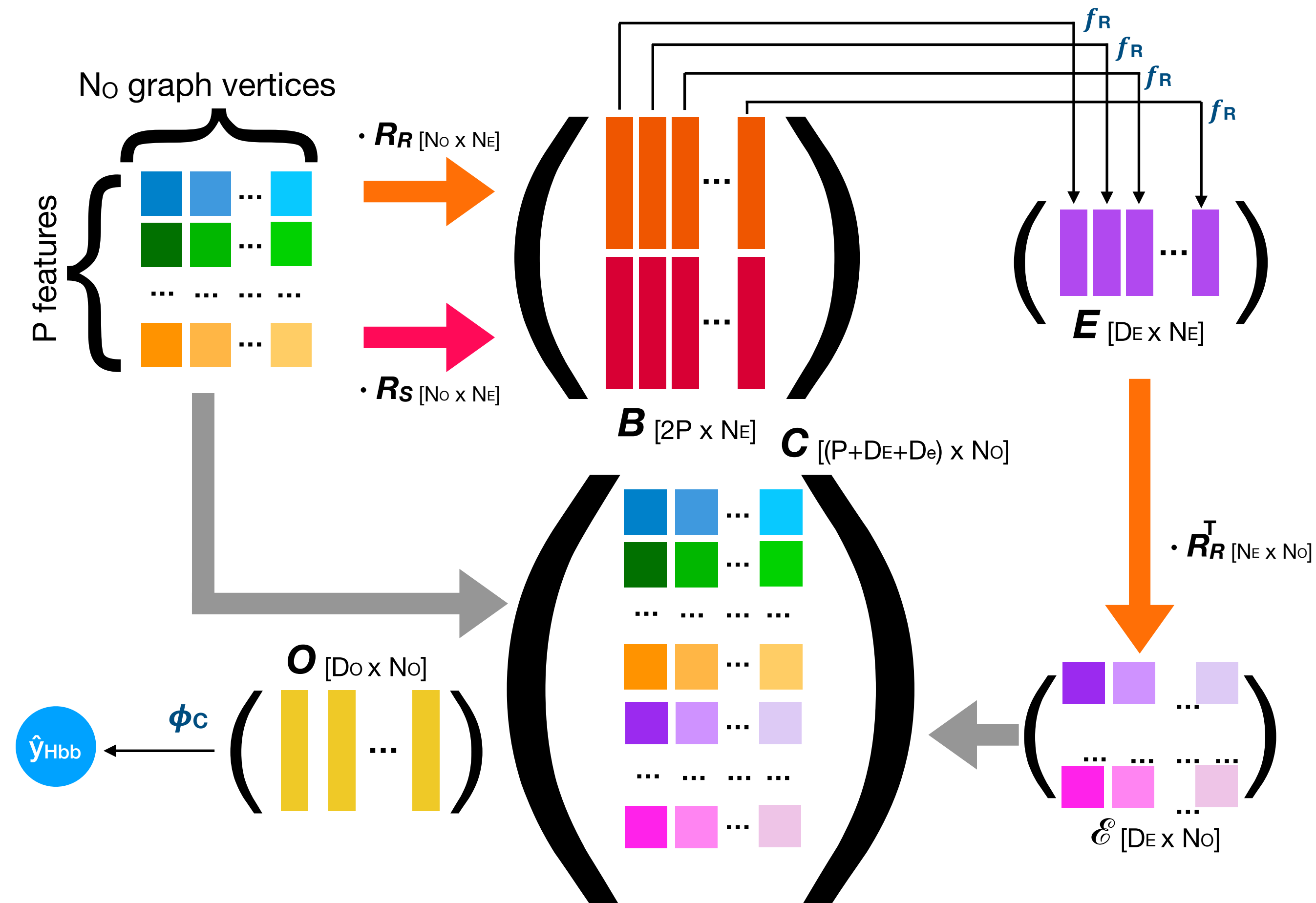


<https://arxiv.org/abs/1902.07987>

Interaction Networks



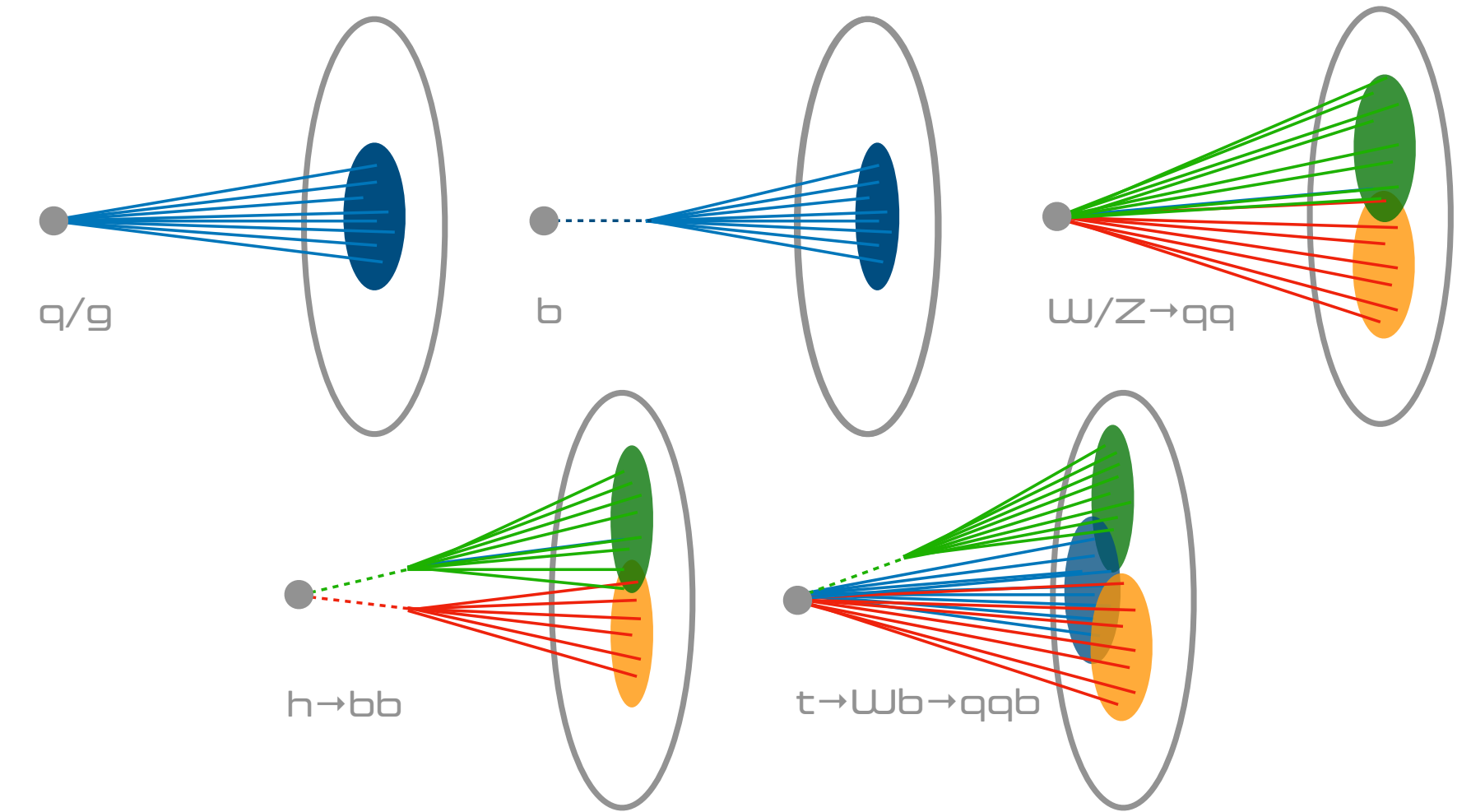
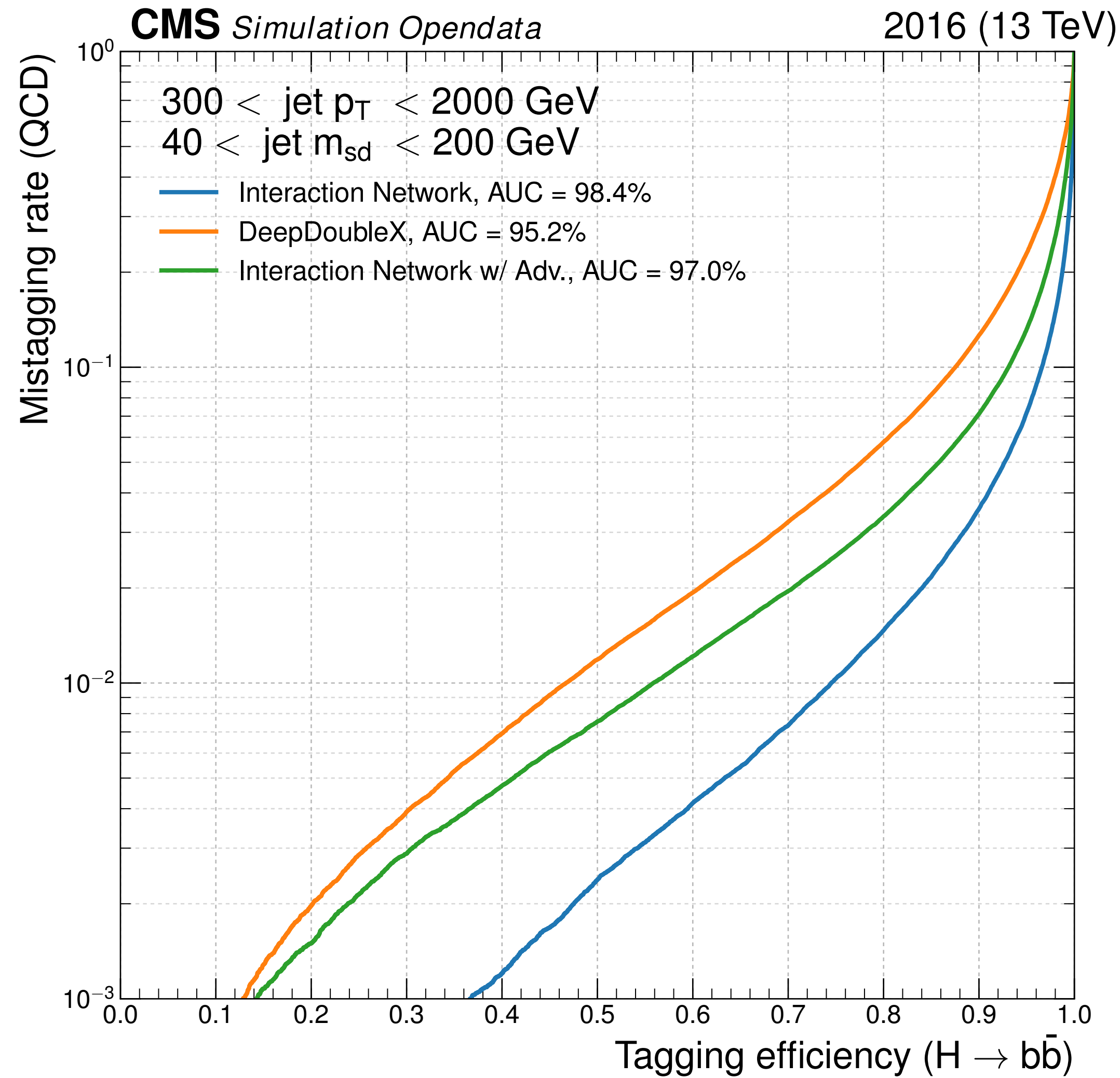
Interaction Networks



N_0 : # of constituents
 P : # of features
 $N_E = N_0(N_0-1)$: # of edges
 D_E : size of internal representations
 D_0 : size of post-interaction internal representation

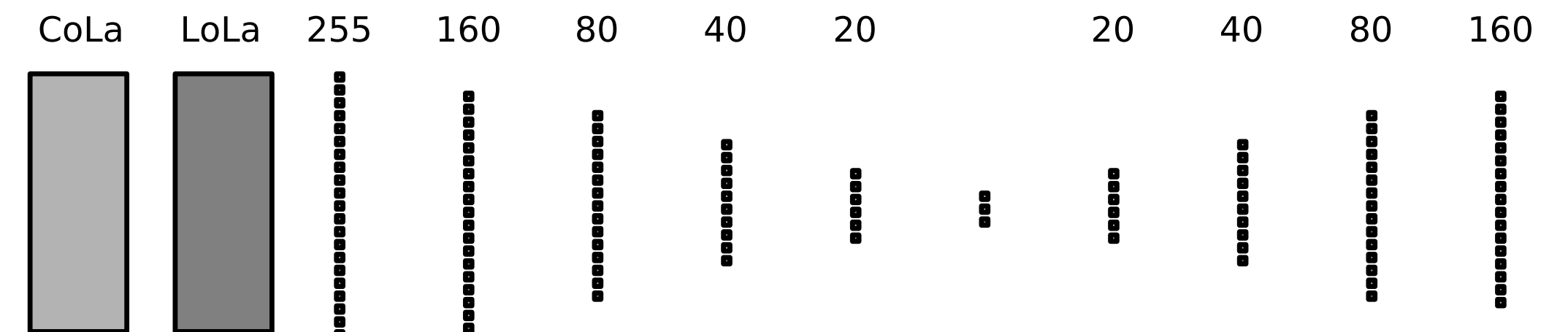
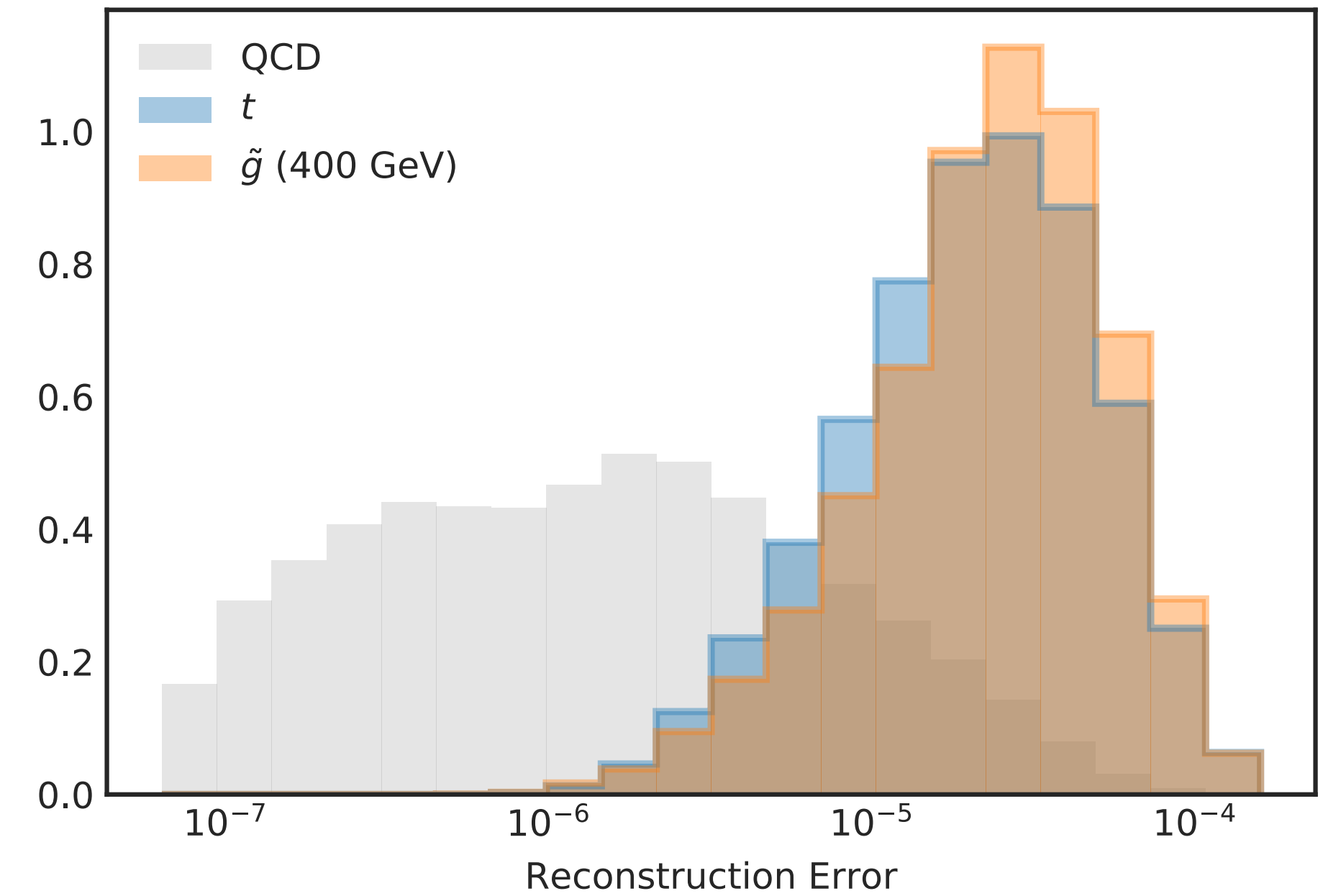
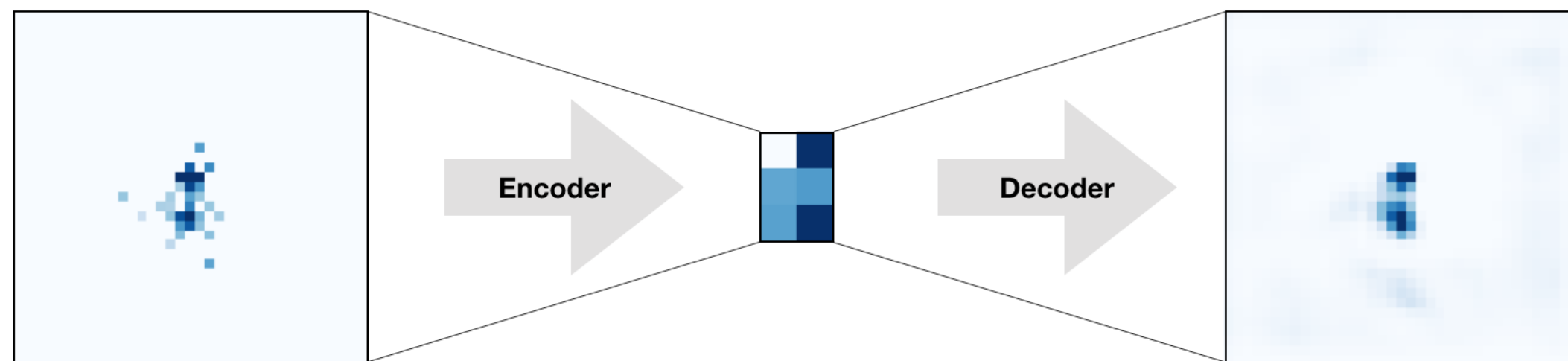
ϕ_C, f_O, f_R
 parameterized as
 neural networks

Interaction Networks



Autoencoders

- Use autoencoders to learn standard Physics
- Find new physics as “distant” events
- Based on image and physics-inspired representations of jets



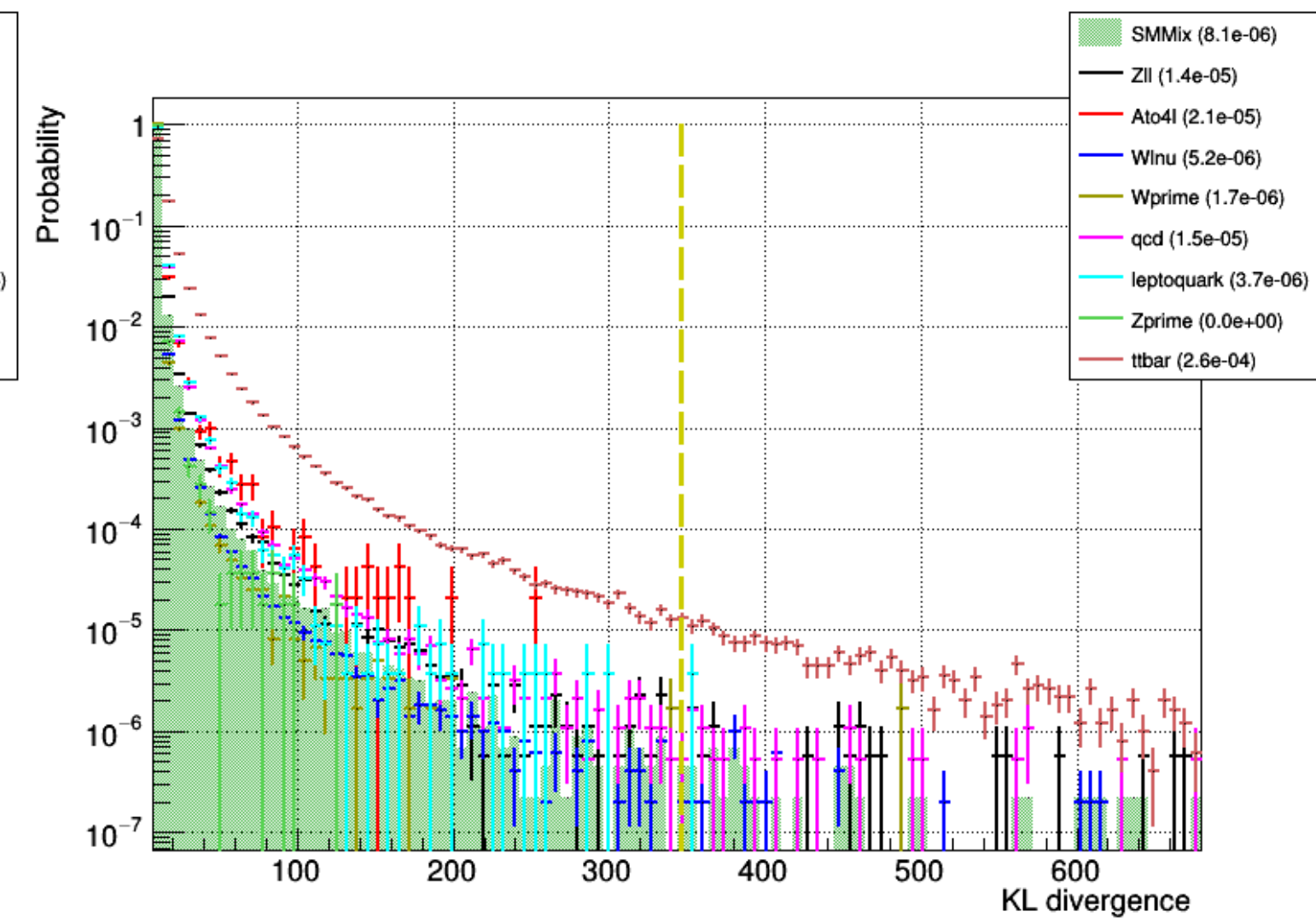
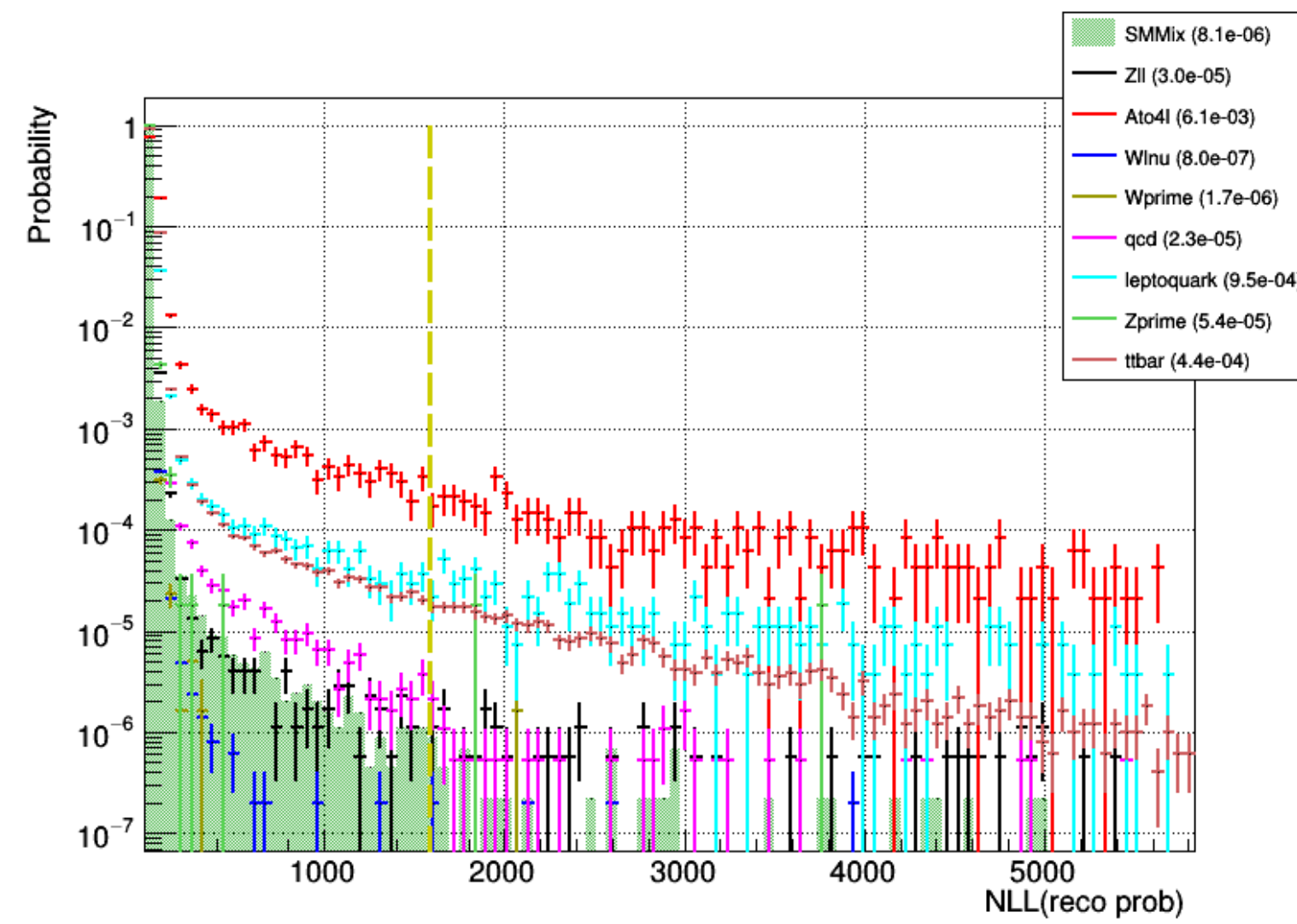
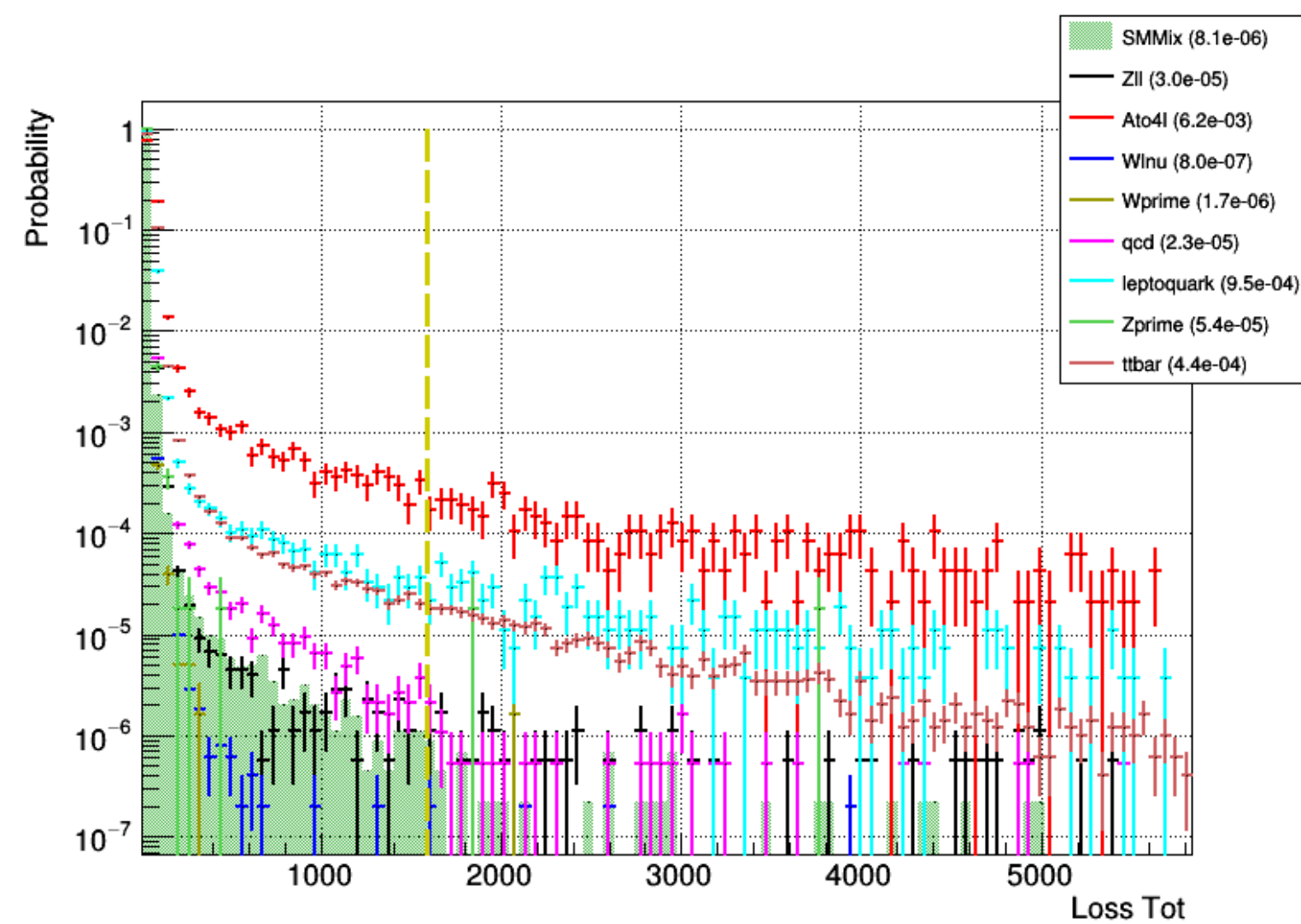
$$\tilde{k}_j = \begin{pmatrix} \tilde{k}_{0,j} \\ \tilde{k}_{1,j} \\ \tilde{k}_{2,j} \\ \tilde{k}_{3,j} \end{pmatrix} \xrightarrow{\text{LoLa}} \begin{pmatrix} \tilde{k}_{0,j} \\ \tilde{k}_{1,j} \\ \tilde{k}_{2,j} \\ \tilde{k}_{3,j} \\ \sqrt{\tilde{k}_j^2} \end{pmatrix}$$

[Farina et al., arXiv:1808.08992](#)

[Heimel et al., arXiv:1808.08979](#)

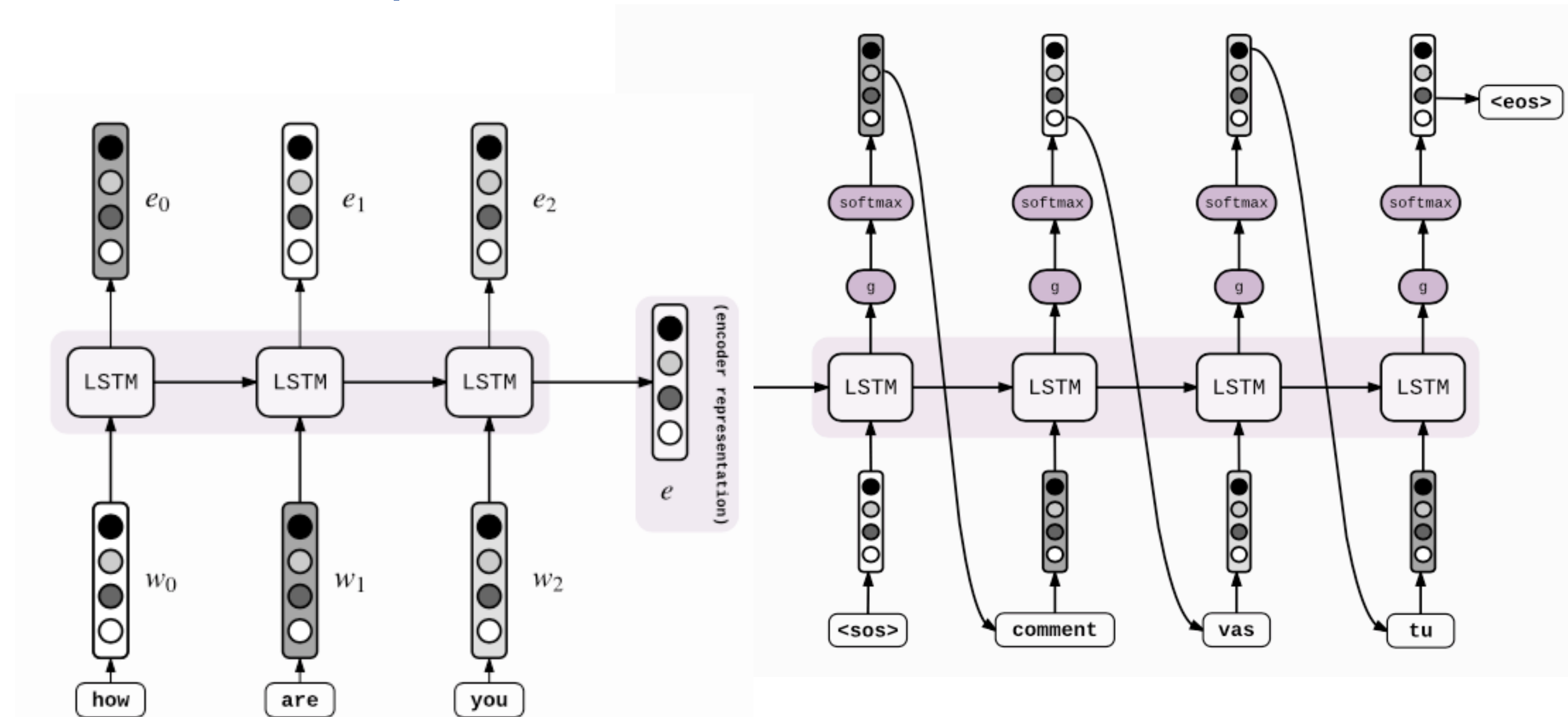
Anomaly Detection

- ⊙ Anomaly defined as a p -value threshold on a given test statistics
- ⊙ Loss function an obvious choice
- ⊙ Some part of a loss could be more sensitive than others
- ⊙ We tested different options and found the total loss to behave better



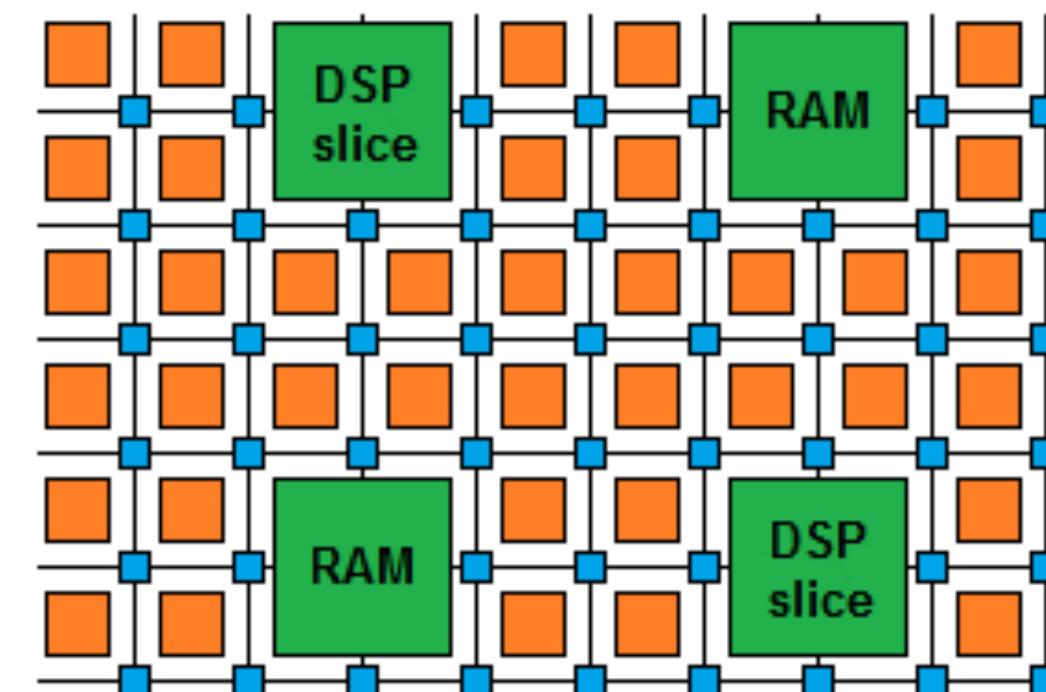
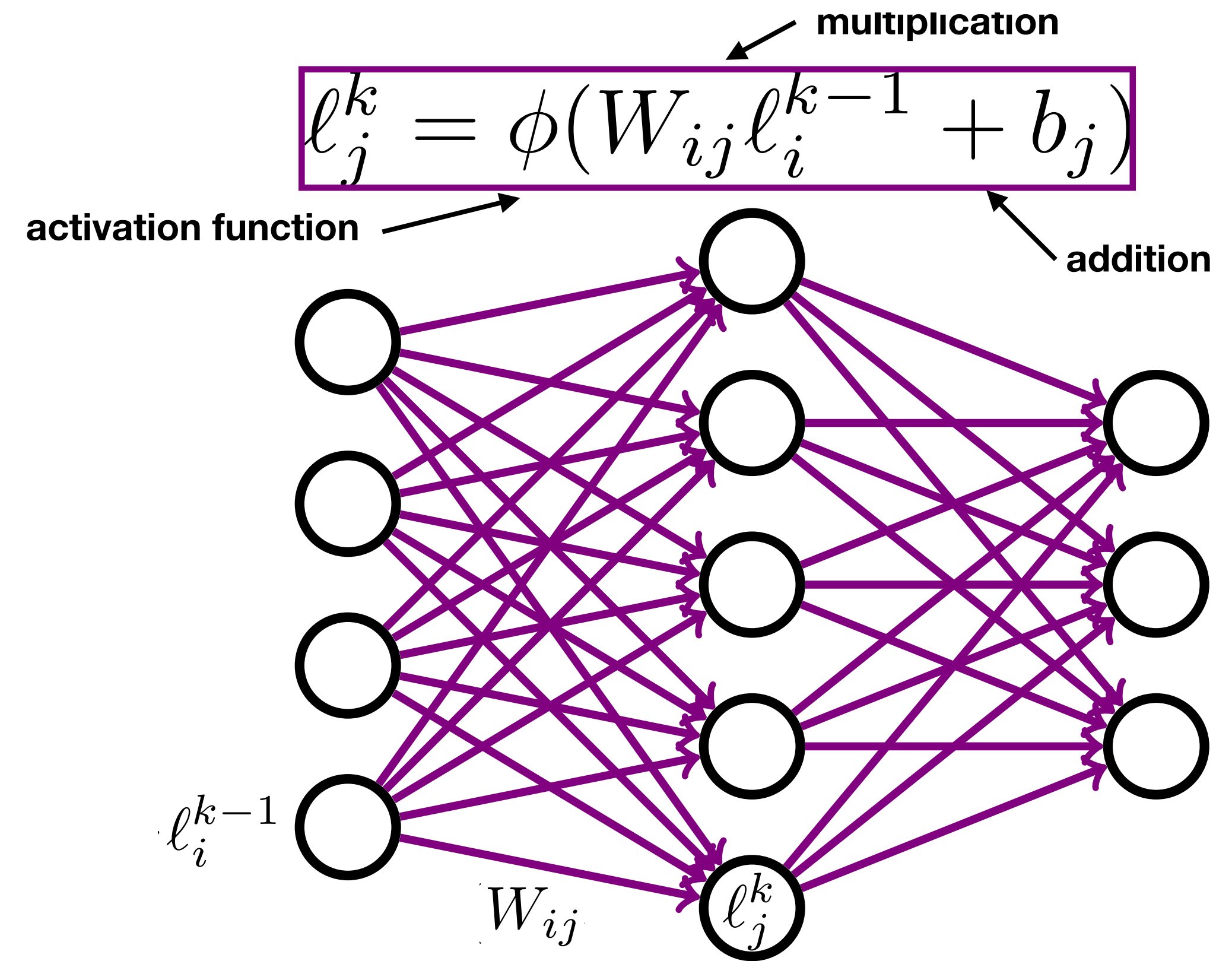
VAE with PF particles

- *Issues:*
 - *variable number of particles/event as input*
 - *need to return particles as output*
- *Networks used for translation*
 - *start from a sentence in language*
 - *code its meaning in some latent space z*
 - *translate to some other language, generating words from z*

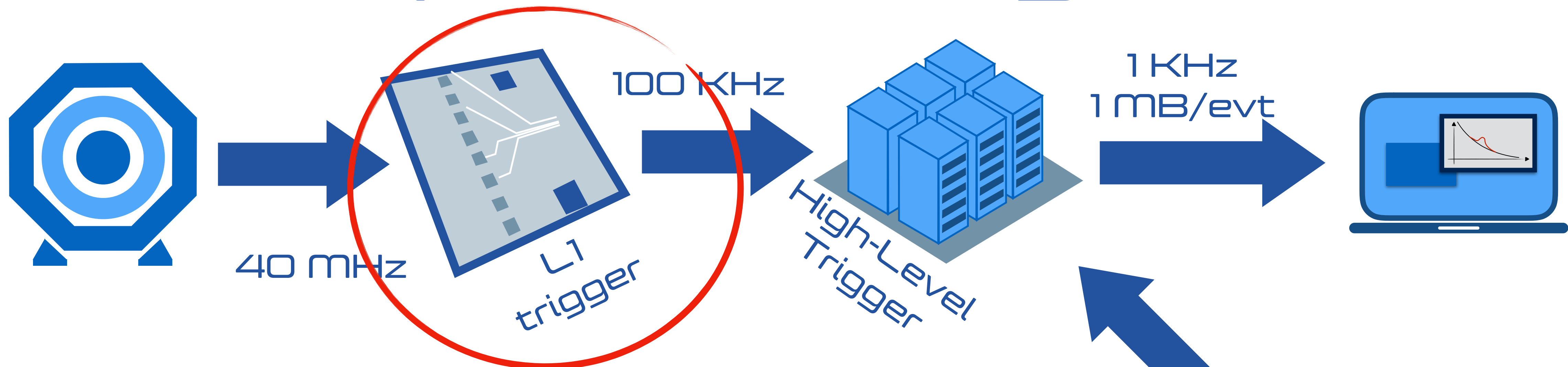


Network Operations

- A classic Dense NN manipulate the inputs in three ways
 - multiplying by weights
 - adding biases
 - applying activation functions
- All these operations map nicely into an FPGA
 - high IO, DSPs, LUTs, tunable precision



Deep Learning at L1

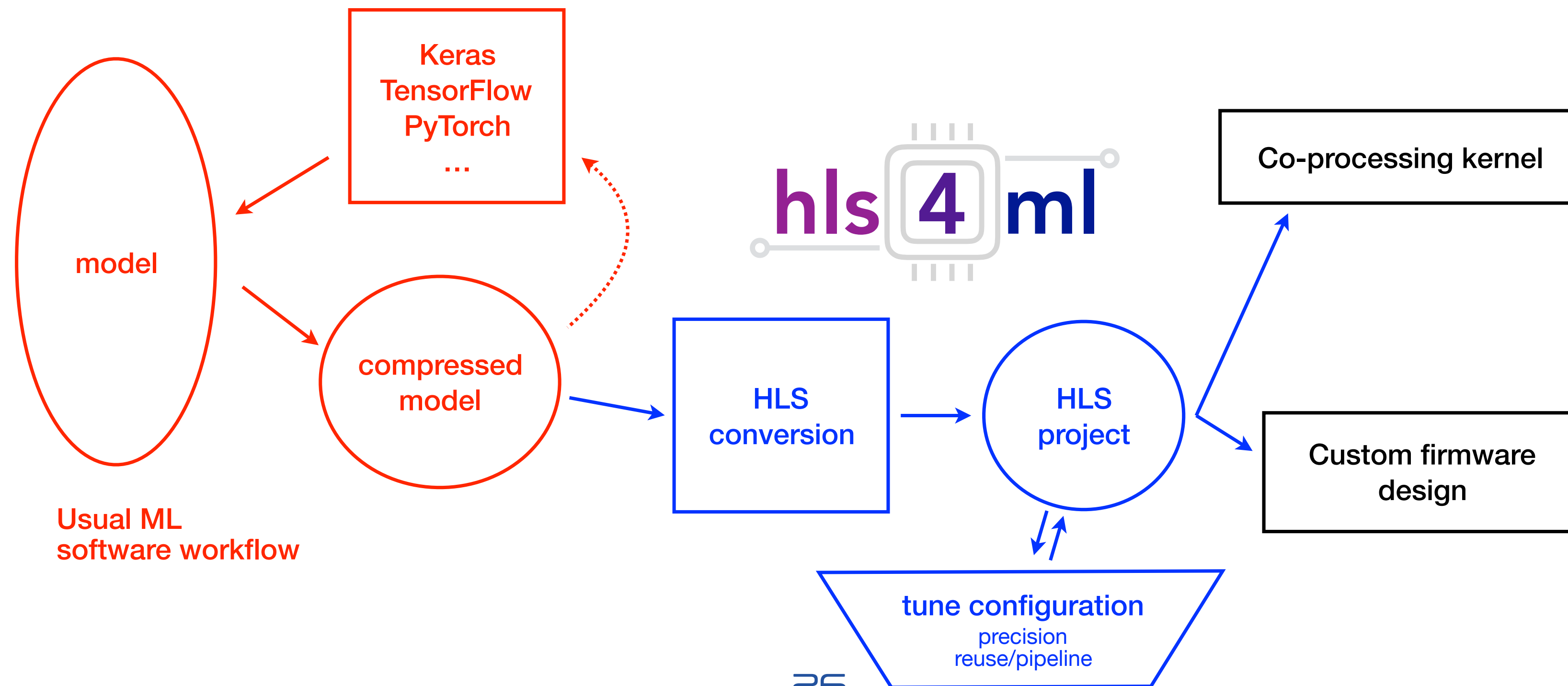


- ◉ *To gain of Deep Learning, we want to bring it at L1 trigger*
 - ◉ *Need to deal with very small latency (<10 μ sec)*
- ◉ *Custom cards connected to detector electronics by optic links*
- ◉ *Data flow in the cards one by one*
- ◉ *Networks need to be implemented in FPGA firmware*
 - ◉ *advanced design by expert engineers (not common resource in HEP)*
 - ◉ *automatic translation tools doing the job*

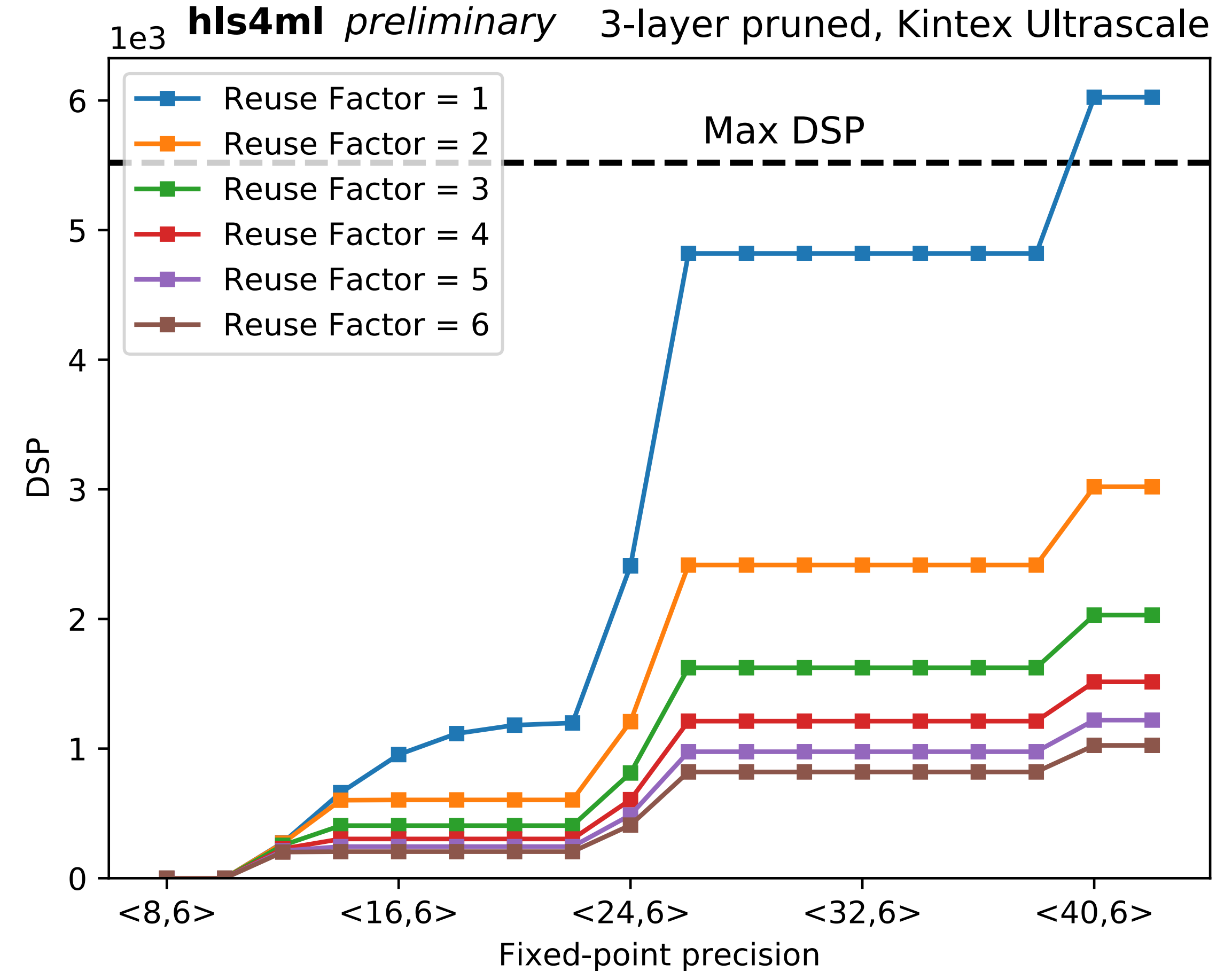
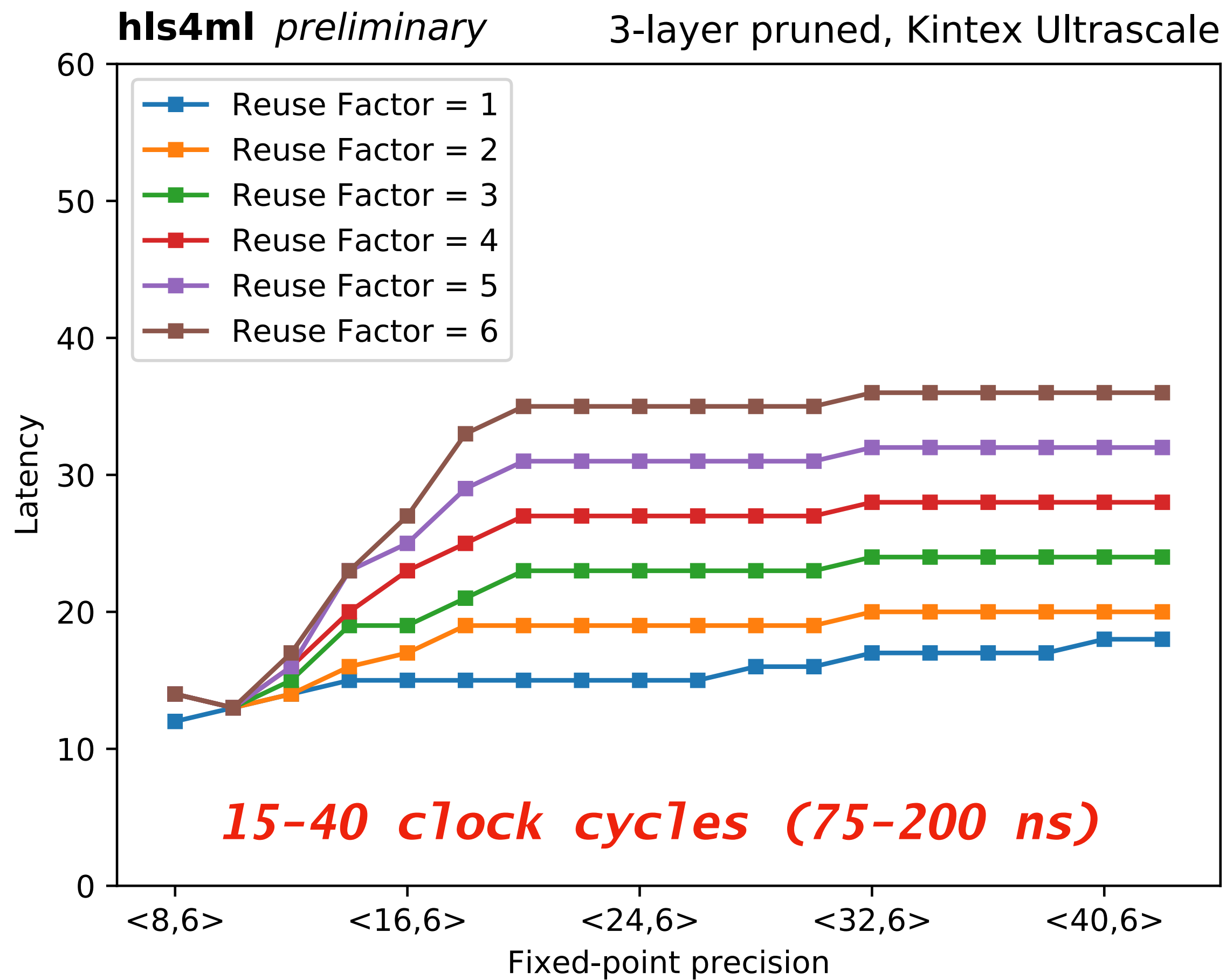


HLS4ML

- *HLS4ML aims to be this automatic tool*
 - *reads as input models trained on standard DeepLearning libraries*
 - *comes with implementation of common ingredients (layers, activation functions, etc)*
 - *Uses HLS softwares to provide a firmware implementation of a given network*
 - *Could also be used to create co-processing kernels for HLT environments*
- *It turns a neural network into an electronic circuit, emulated on the FPGA*

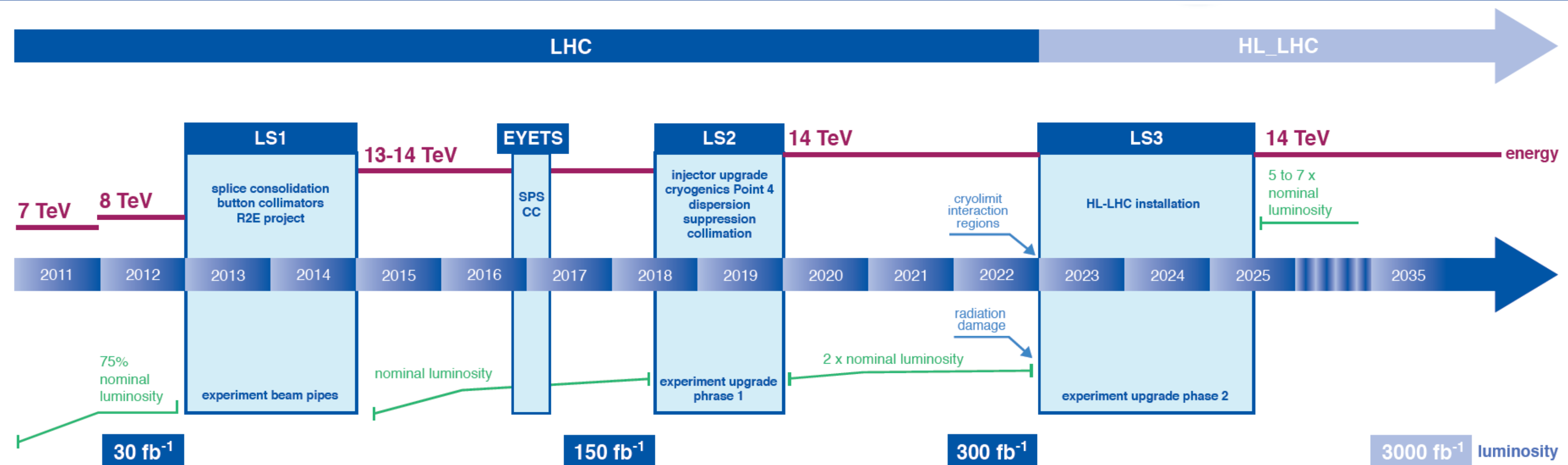


Parallelisation



*Foreseen architecture (FPGAs) will handle these networks
 Inference-optimized GPUs could break the current paradigm
 Looking forward to R&D projects with nVidia & E4 on this*

Deep Learning 4 HEP: A roadmap



- ⦿ We need to be ready by 2025 (High-Luminosity LHC)
- ⦿ LHC Run 3 (2020–2022) is the ultimate demonstration opportunity
 - ⦿ for model building, deployment and commissioning
- ⦿ Strong synergy with other research lines in HEP
 - ⦿ Dark Matter underground experiments
 - ⦿ Neutrino experiments
- ⦿ Collaboration with nVidia to find optimal (performances & speed) solutions