PLC Use at European XFEL PLC Based Controls at ICALEPCS 2019

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The PLC installation at European XFEL

We are based on industrial components produced by Beckhoff Automation GmbH (IPCs) and PLC (61131-3 compliant) implemented with TwinCAT for all x-ray photon-system (mainly TC3.1, TC2.11 in undulator systems). These offer:

TwinCAT based software with full-fledged diagnostic tools and interface to Automation Interface

EtherCAT Fieldbus – RT, fast and truly open communication standard

Cable redundancy

EtherBridge PLC-to-PLC RT intercommunication

Wide variety of control terminals and motors available off the shelf (servos, steppers, ADCs, DACs, encoders, communication, I/O....)

Integrated EtherCAT equipment (up to now: PI, Elmo MC, Technosoft, Festo, tested Newport-Hexpod)

European XFEL

The PLC installation and use at European XFEL (cont.)

We have production installations:

~120 xC6920-0050 (TC3.1, Win 10 LTS)

~100xC6925 (TC2.11, WinXP, cell control, undulators)

3x C5210 (TC2.11, CCN, undulators)

~25 xCP6609 (TC2.11: WinCE integrated touch panel PC for movable equipment, PumpCart&BakeoutOven)

For test setups (legacy):

~10-15 x C6015 (TC3.1: WinCE specially for in-the-field level-0 tests) ~25x C6920-0030 (TC3.1: WinCE)

< 10 x CX9020 (TC3.1: WinCE)

< 5 x CX1020 (TC2.11 obsolete, to be replaced)

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The PLC code at European XFEL (not undulator system)

Automatic PLC project generation from:

Electrical documentation Eplan P8, xml exports

Interlock definition, via spreadsheet

Using Python 3 + Object Relational Mapping (ORM) + SQL database backend

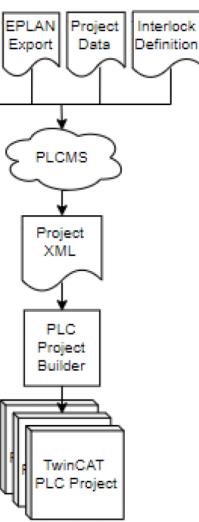
Version control under GitLab (plus Subvesion for the generated projects)

- Self-description, including names and parameteres, of all SoftDevice instances at connect time to karabo (EuXFEL SCADA)
- Issues and feature planning & tracking via Redmine
- Deployment and configuration via Puppet

Monitoring via Nagios



PLCMS
DB
\smile



Already installed equipment in photon systems (undulators not included)

Gauges and temperature sensors:	>600
Vacuum pumps:	>600
Analog signals to be digitized and processed:	>300
LED:	>100
Stepper motors:	>2200
Piezo motors:	>220
DC motors:	~3
Servo motors (standard and small servo technology):	>15x linear, ~ 6x 3-phase
Incremental encoders:	>1000
Absolute encoders:	>230