

Fully Bayesian Unfolding



Mgr. Petr Baroň
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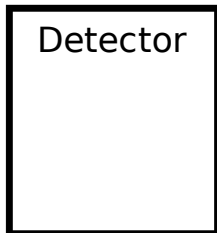
- 1.) What is unfolding
- 2.) Fully Bayesian Unfolding
- 3.) Regularization
- 4.) Conclusion



Unfolding is the process of correcting measured data to its detector efficiency, acceptance and resolution.

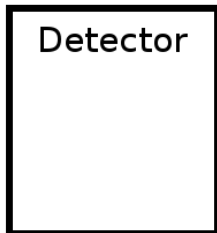


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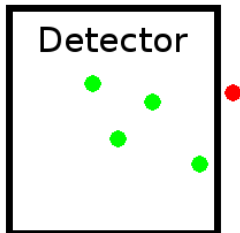
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Particle level Detector level



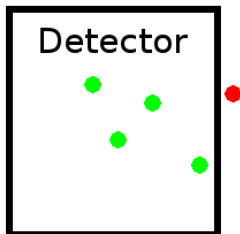
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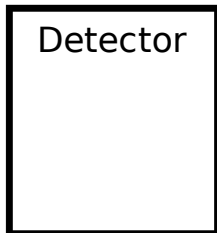


Efficiency = 80%

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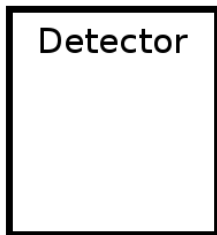


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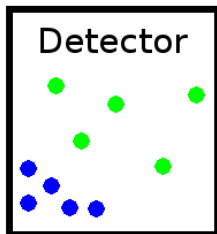
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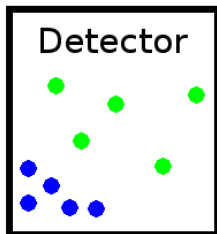
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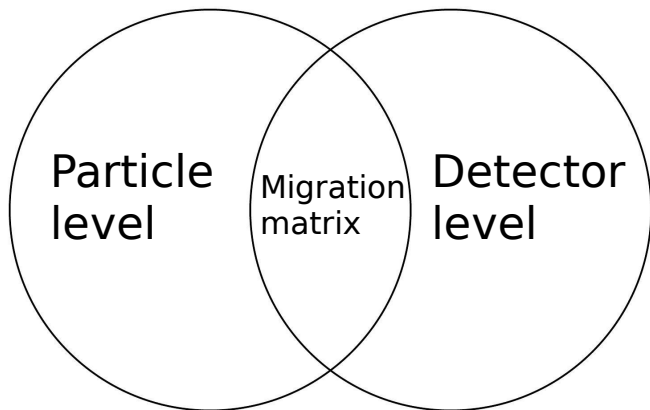


Acceptance = 50%

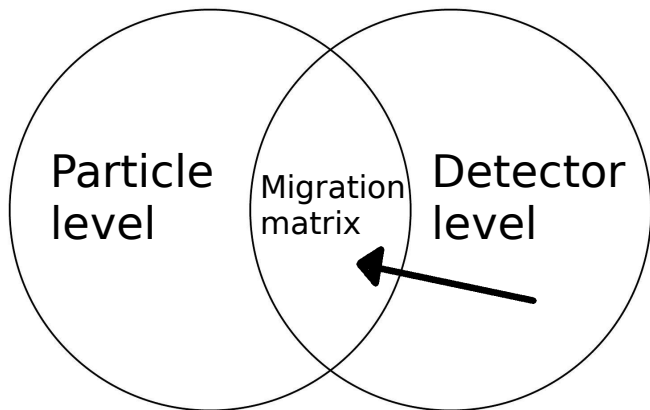
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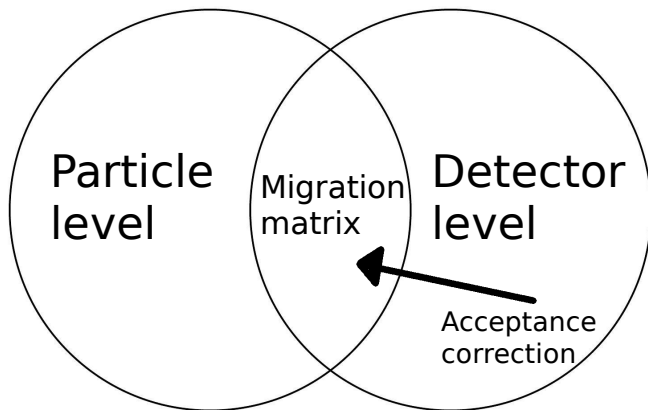
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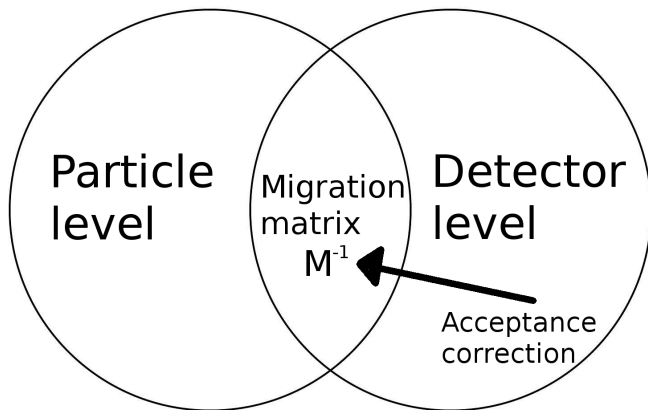
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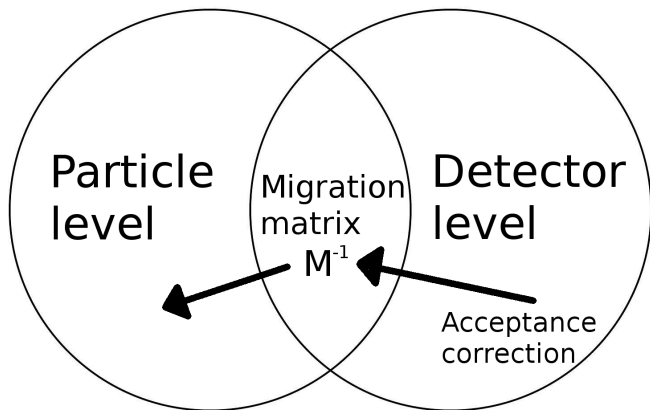
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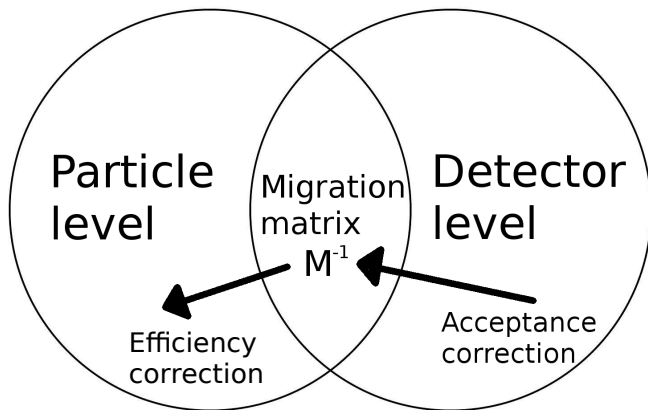
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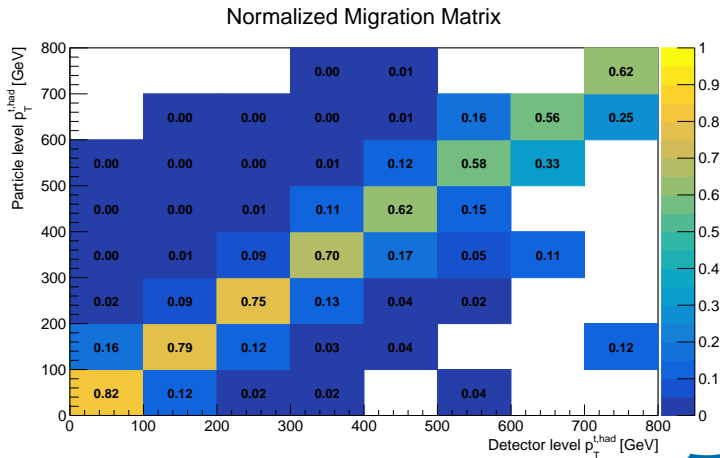
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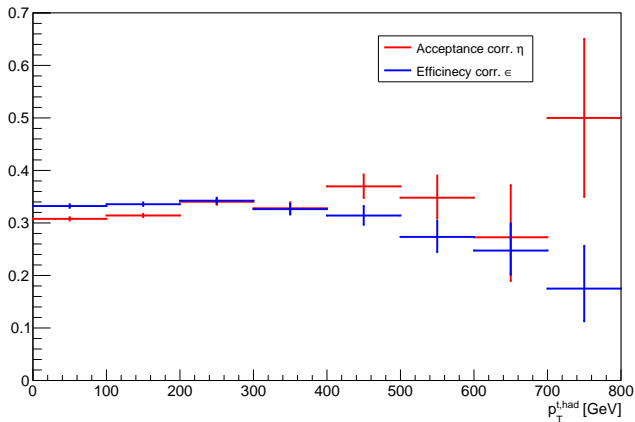
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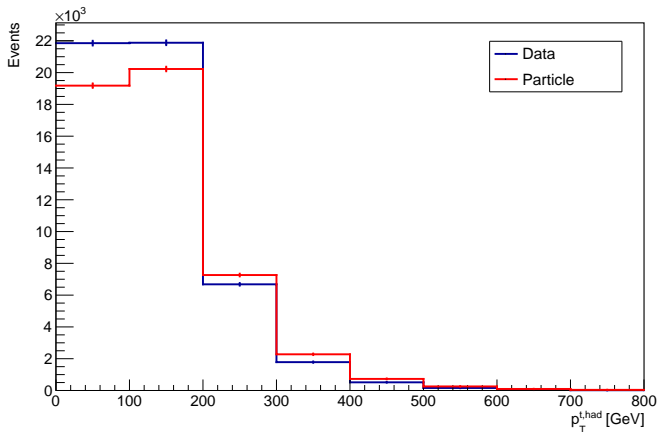
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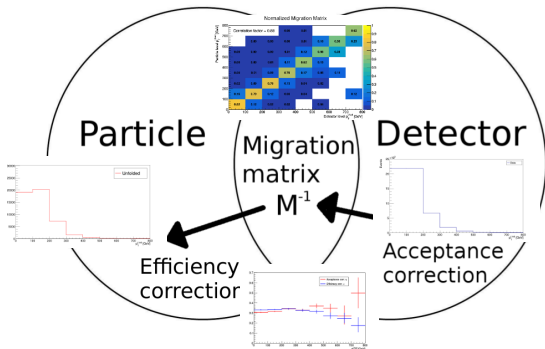


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$$p = \frac{1}{\epsilon} \cdot M^{-1} \cdot \eta \cdot (D - B) \quad (1)$$



Methods of RooUnfold package:

Invert

TUnfold

Svd

Ids

BinByBin

IterativeBayes

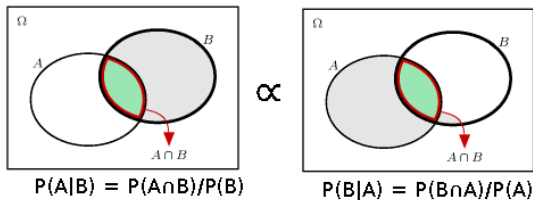
Maybe one day FBU - **Fully Bayesian** with regularization

<https://arxiv.org/abs/1201.4612>



Bayesian theorem: $P(A|B) = \frac{P(B|A) \cdot P(A)}{P(B)}$

$$p(\mathbf{T}|\mathbf{D}, \mathcal{M}) = L(\mathbf{D}|\mathbf{T}, \mathcal{M}) \cdot \frac{\pi(\mathbf{T}, \mathcal{M})}{\text{Norm. Const.}}$$



Likelihood function $L(T_1, T_2, \dots, T_N)$.

$$P(T|D) \propto L(D|T) \cdot \pi(T) =$$

$$= \frac{1}{\epsilon} \left(\prod_{i=1}^{n=\text{bins}} \frac{(\sum_{j=1}^{n=\text{bins}} M_{ij} T_j)^{[\alpha_i(D_i - B_i)]}}{[\alpha_i(D_i - B_i)]!} e^{-(\sum_{j=1}^{n=\text{bins}} M_{ij} T_j)} \right) e^{-\tau S(T)}$$



Markov chain Monte Carlo (MCMC)

- general name for sampling algorithms → each step is derived based on previous one, which creates chain.

Gibbs Sampling - Bayesian inference Using Gibbs Sampling

Random Walk Metropolis Hastings

Adaptive Metropolis Hastings

Hamiltonian Monte Carlo

No-U-Turn Sampler - NUTS

<https://arxiv.org/abs/1111.4246>

Metropolis-adjusted Langevin Algorithm (MALA)

Hessian-Hamiltonian Monte Carlo (H2MC)

Stein Variational Gradient Descent (SVGD)

Nested Sampling with RadFriends (RadFriends-NS)



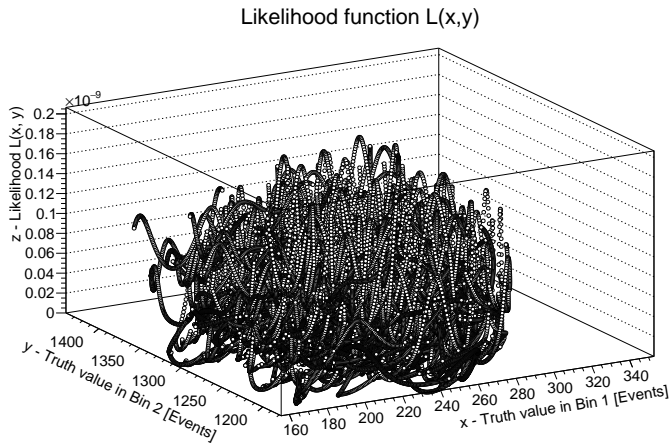
Hamiltonian Monte Carlo (HMC)

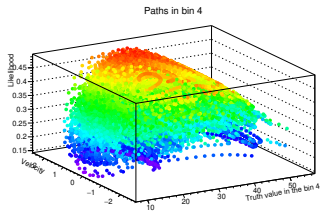
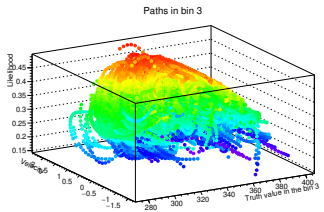
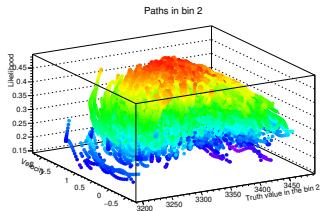
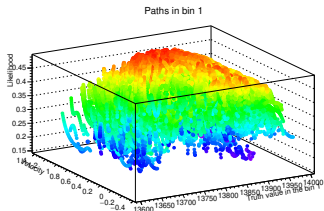
- problem of sampling likelihood function is **transformed** to the free particle (frog) motion in the potential given by likelihood function $V = L(T_1, T_2, \dots, T_N)$.

$$H = \frac{\vec{p}^2}{2m} + V(x, y, z, \dots)$$

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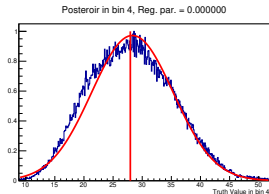
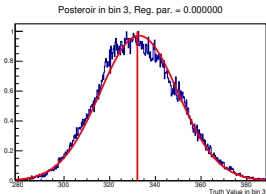
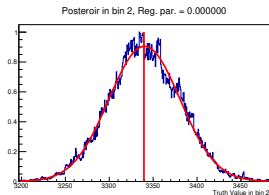
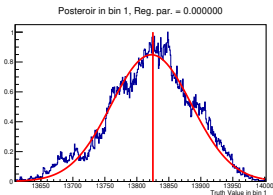






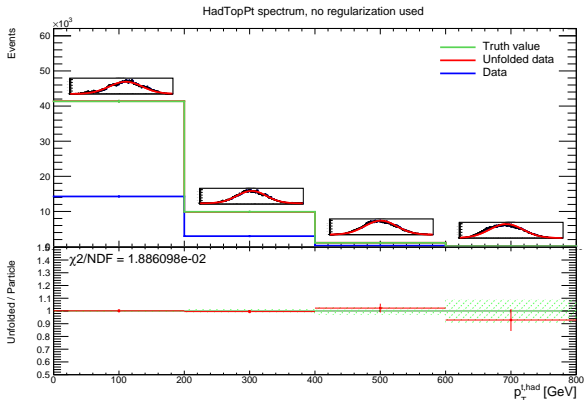
Unfolded spectrum is derived from posteriors which are calculated for each bin i as:

$$p_i(T_i|D) = \int \int P(T|D) dT_1 \dots dT_{i-1} dT_{i+1} \dots dT_N \quad (2)$$



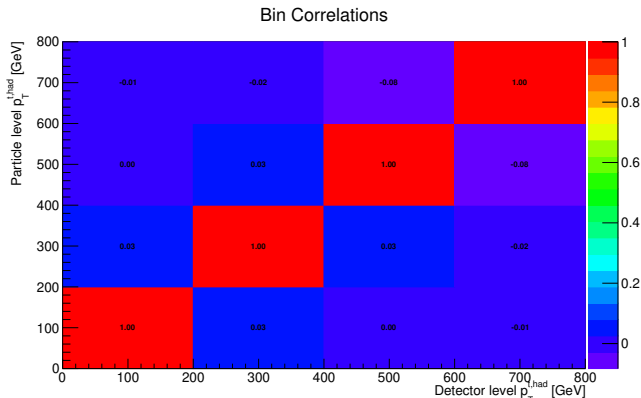
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$$P(T|D) \propto L(D|T) \cdot \pi(T) =$$
$$= \frac{1}{\epsilon} \left(\prod_{i=1}^{n=\text{bins}} \frac{(\sum_{j=1}^{n=\text{bins}} M_{ij} T_j)^{[\alpha_i(D_i - B_i)]}}{[\alpha_i(D_i - B_i)]!} e^{-(\sum_{j=1}^{n=\text{bins}} M_{ij} T_j)} \right) e^{-\tau S(T)}$$

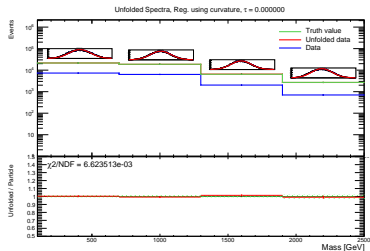
$$S(T) = \sum_{t=2}^{N-1} (\Delta_{t+1,t} - \Delta_{t,t-1})^2 \quad (5)$$

where

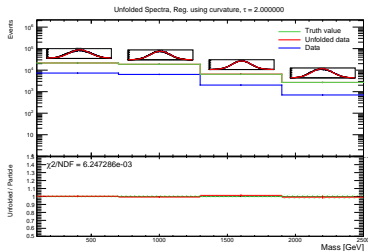
$$\Delta_{t_1,t_2} = T_{t_1} - T_{t_2} \quad (6)$$

where T' and T'' are first and second derivatives of the truth pseudo experiment.





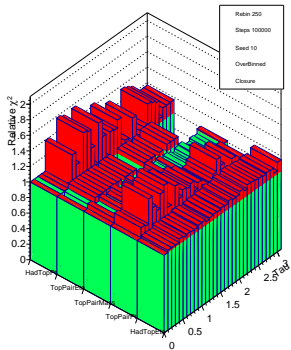
(a)



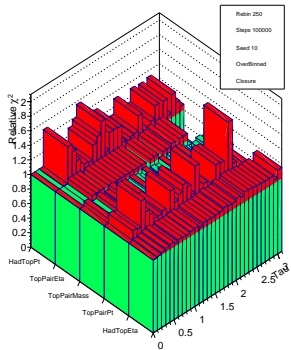
(b)

Figure: **a)** No regularization is applied. **b)** Regularization using curvature with reg. strengt $\tau = 2.0$.

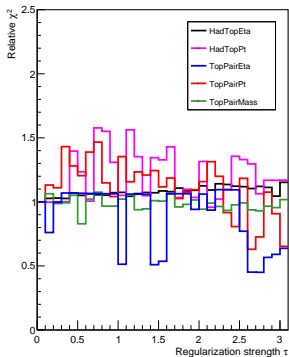
χ^2 using Curvature Regularization



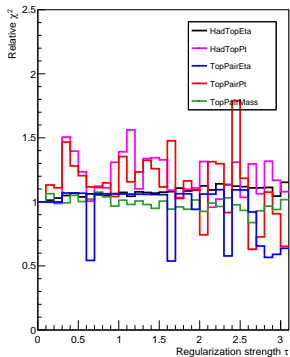
χ^2 using Entropy Regularization



χ^2 using Curvature Regularization



χ^2 using Entropy Regularization



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Thank to my supervisor Mgr. Jiří Kvita, PhD. , organisers for the opportunity to give this talk and for your attention.

Questions?

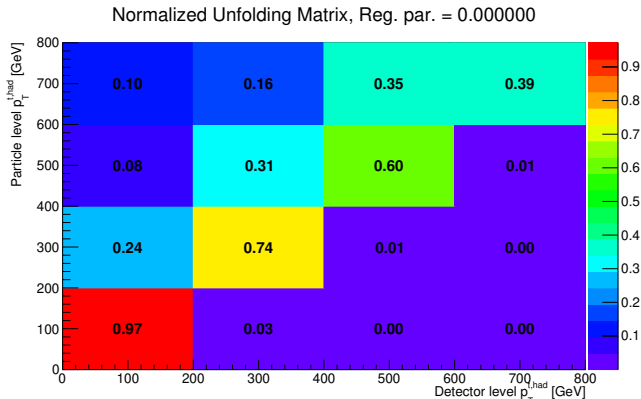


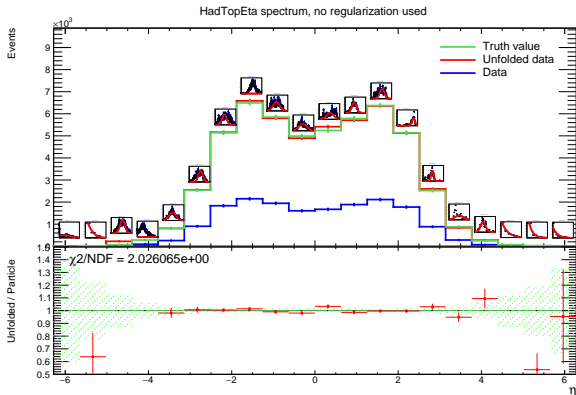
$$\epsilon = \frac{P_{\text{particle, proj. from M}}}{P_{\text{level}}}; \quad \eta = \frac{D_{\text{data, proj. from M}}}{D} \quad (7)$$



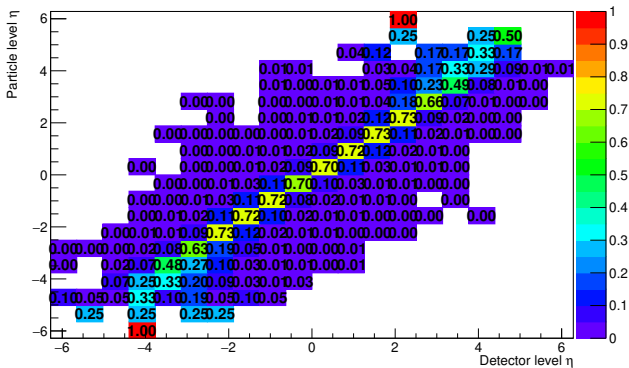
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Normalized Unfolding Matrix, Reg. par. = 0.000000



Bin Correlations

