

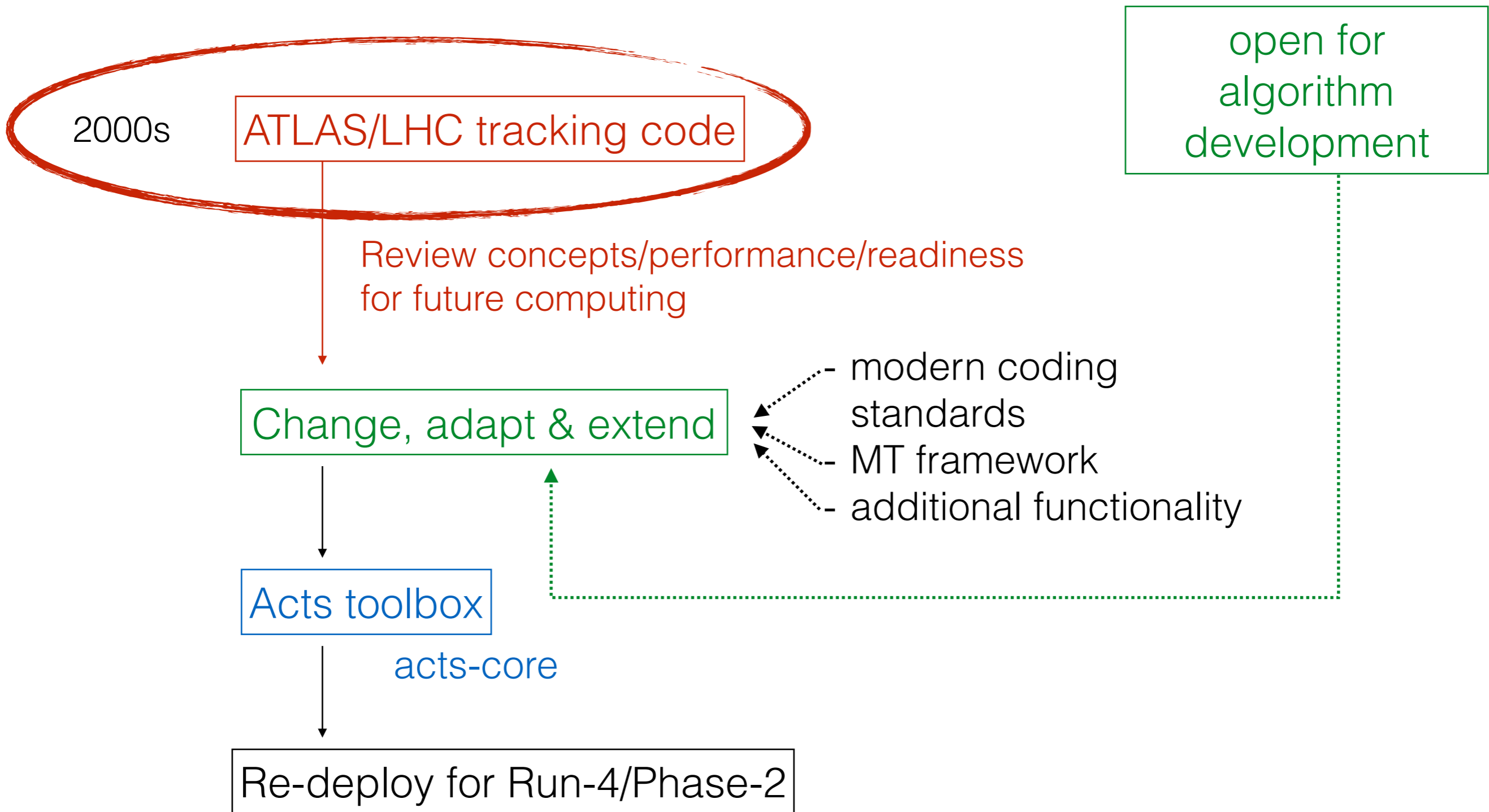
# Acts Concept, Status & Plans

<https://cern.ch/acts>

A. Salzburger (CERN)



# Mission statement



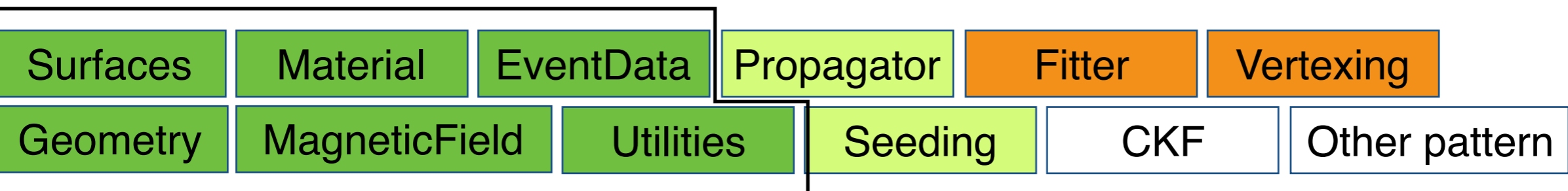
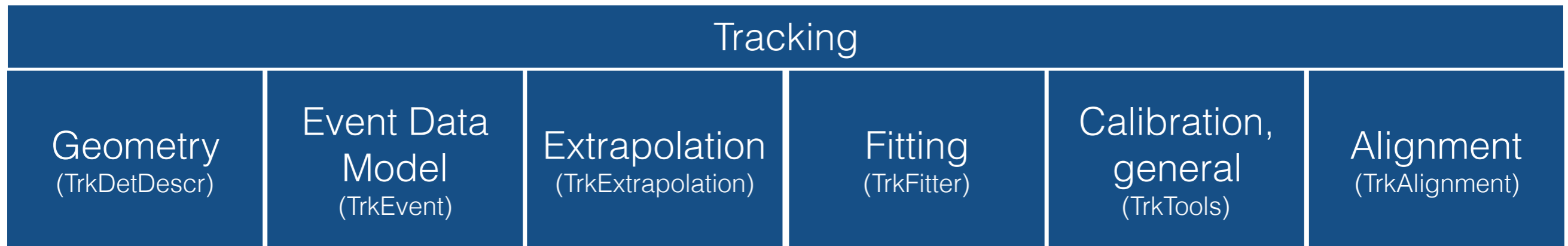
ATLAS: atlas/athena/Tracking/Acts

# Status Tracking code porting

2000s

ATLAS/LHC tracking code

Review concepts/performance/readiness for future computing



API practically frozen

# Mission statement

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open for  
algorithm  
development

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- modern coding standards
- MT framework
- additional functionality

Acts toolbox

acts-core

Re-deploy for Run-4/Phase-2

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# Feature completing

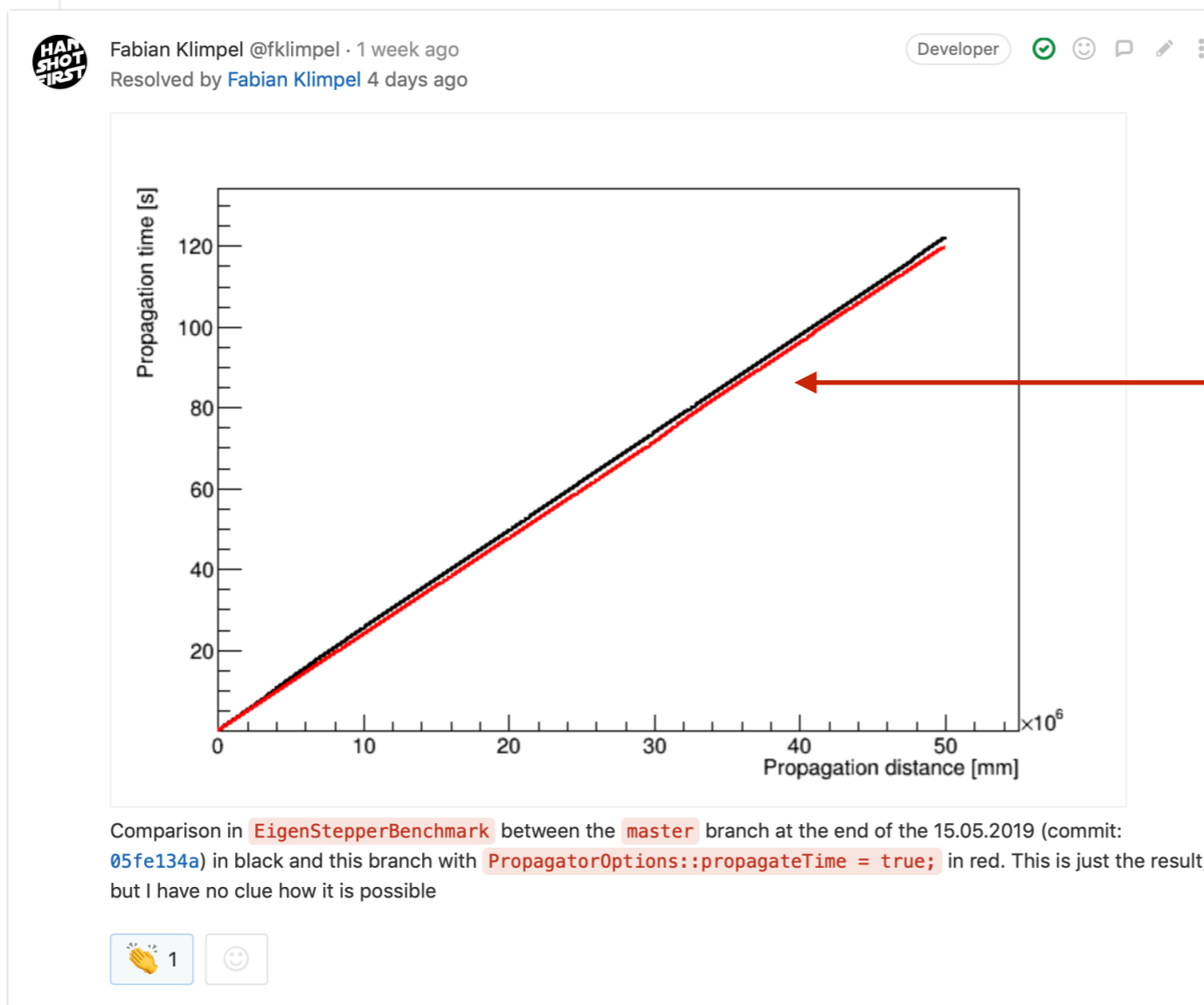
E.g., included time-component into full tracking stack

- Most of LHC code it is (whenever needed) post-fitted

Internal representation expanded from **7x7** description to **8x8**

- full time covariance transport developed (and numerically tested)
- positive impact on execution speed

$$\mathbf{q} = (l_1, l_2, \phi, \theta, q/p, t)$$



- could be better vectorisation, not confirmed yet

# Getting fully MT ready the extra mile

Based on ATLAS needs developed a full contextual tracking setup

- Lumiblock based alignment for ATLAS due to IBL bowing

*Not the most standard workflow, however, needs a clean solution*

*In a real **MULTI**-threaded environment, several alignment or conditions might have to be in memory*

*(e.g. high selective trigger stream)*

Merged Opened 1 month ago by Andreas Salzburger Edit

## Introduce Context object into acts-core

Closes [ACTS-568](#)

Introduce a `Context` object to deal with payload, conditions, alignment in the most flexible (and fast) manner.

There are now three `Context` objects included, two are already tested, the third, i.e. the `CalibrationContext` object needs a `KalmanFilter`, which will come soon.

`clang` build still fails due to `libcxx` inconsistency.

Edited 2 weeks ago by Andreas Salzburger

239 changed files  
4054 additions 3826 deletions

large scale update  
for MT capability

Request to merge [ACTS-568\\_PayloadObj...](#) into `master`

Pipeline #767312 passed with warnings for [c1434d86](#) on [ACTS-568\\_PayloadObj...](#)  
Coverage 67.00%

Merge request approved  
Approved by

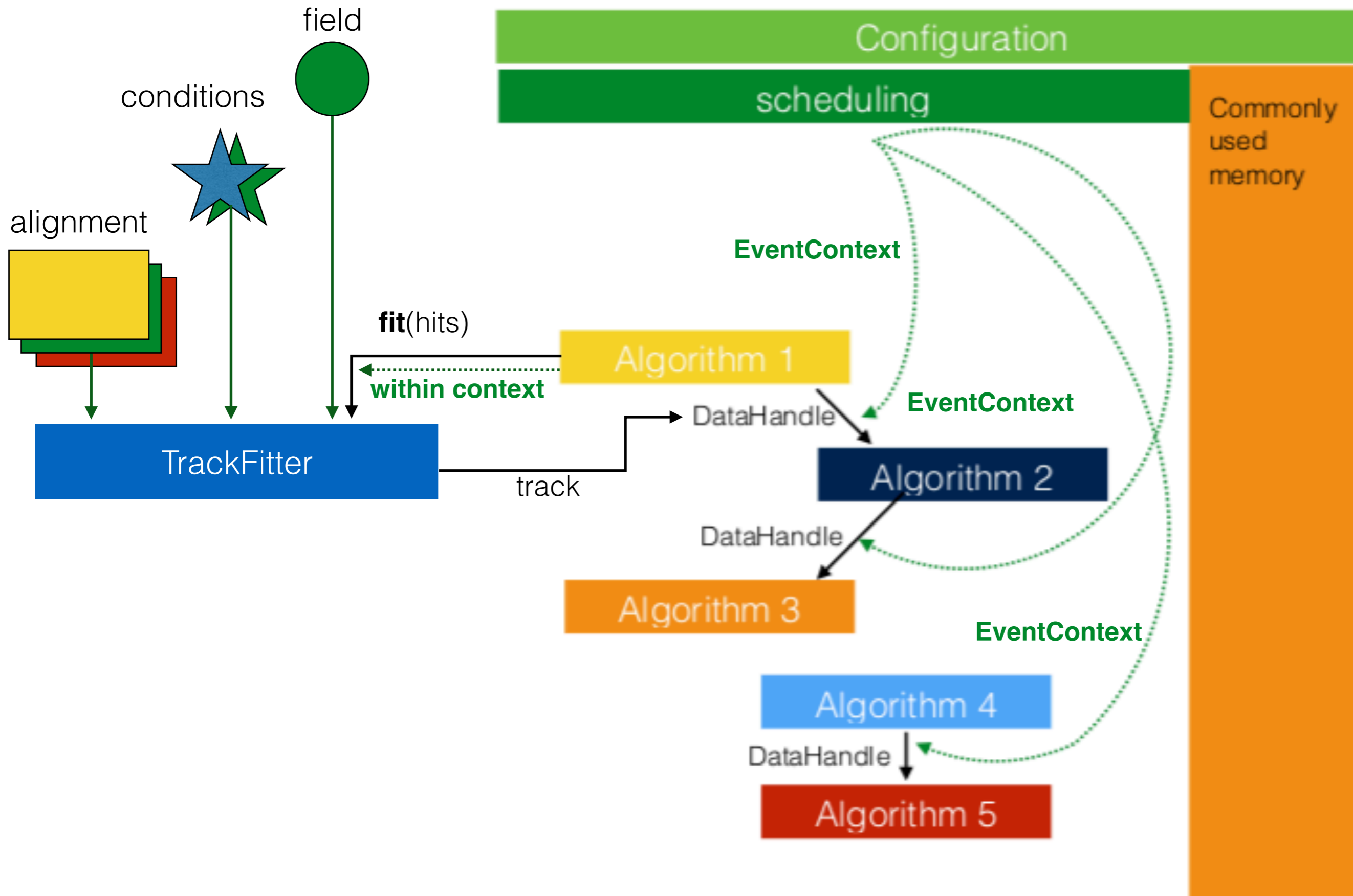
Merged by Andreas Salzburger 2 days ago Revert Cherry-pick

The changes were merged into `master` with [13d76c1a](#)

You can remove source branch now Remove Source Branch

Closed [ACTS-568](#)

# Contextual Tracking The "clean" solution



# ACTS with Context

Introduced context objects in **acts-core** & testes in **acts-framework**

- nomen est omen

```
/// Aggregated information to run one algorithm over one event.
struct AlgorithmContext
{
    size_t          algorithmNumber;    ///< Unique algorithm identifier
    size_t          eventNumber;       ///< Unique event identifier
    WhiteBoard&     eventStore;        ///< Per-event data store
    Acts::GeometryContext geoContext;  ///< Per-event geometry context
    Acts::MagneticFieldContext magFieldContext; ///< Per-event magnetic Field context
    Acts::CalibrationContext calibContext; ///< Per-event calibration context
};
```

While they are untouched in **acts-core** and simply defined as

```
#pragma once

/// Set the identifier PLUGIN
#ifdef ACTS_CORE_GEOMETRYCONTEXT_PLUGIN ← can even be
#include ACTS_CORE_GEOMETRYCONTEXT_PLUGIN overloaded
#else
#include <any>

namespace Acts {

using GeometryContext          = std::any;
using DefaultGeometryContext = GeometryContext;

} // namespace Acts

#endif
```



# Parallelism testbed

Test with different alignment every single event

```
salzburg$ export ACTSFW_NUM_THREADS=1
salzburg$ ./ACTFWAlignablePropagationExample -n10 --prop-ntests 1000 --bf-values 0 0 2 --output-root 1
12:49:10 Sequencer INFO Added context decorator GeometryRotationDecorator
12:49:10 Sequencer INFO Added service RandomNumbersSvc
12:49:10 Sequencer INFO Appended algorithm PropagationAlgorithm
12:49:11 Sequencer INFO Added writer RootPropagationStepsWriter
12:49:11 Sequencer INFO Starting event loop for
12:49:11 Sequencer INFO 1 services
12:49:11 Sequencer INFO 0 readers
12:49:11 Sequencer INFO 1 writers
12:49:11 Sequencer INFO 1 algorithms
12:49:11 Sequencer INFO Run the event loop
12:49:11 Sequencer INFO start event 0
12:49:12 Sequencer INFO event 0 done
12:49:12 Sequencer INFO start event 1
12:49:13 Sequencer INFO event 1 done
12:49:13 Sequencer INFO start event 2
12:49:14 Sequencer INFO event 2 done
12:49:14 Sequencer INFO start event 3
12:49:15 Sequencer INFO event 3 done
12:49:15 Sequencer INFO start event 4
12:49:16 Sequencer INFO event 4 done
12:49:16 Sequencer INFO start event 5
12:49:17 Sequencer INFO event 5 done
12:49:17 Sequencer INFO start event 6
12:49:19 Sequencer INFO event 6 done
12:49:19 Sequencer INFO start event 7
12:49:19 Sequencer INFO event 7 done
12:49:19 Sequencer INFO start event 8
12:49:20 Sequencer INFO event 8 done
12:49:20 Sequencer INFO start event 9
12:49:22 Sequencer INFO event 9 done
12:49:22 Sequencer INFO Running end-of-run hooks of writers and services

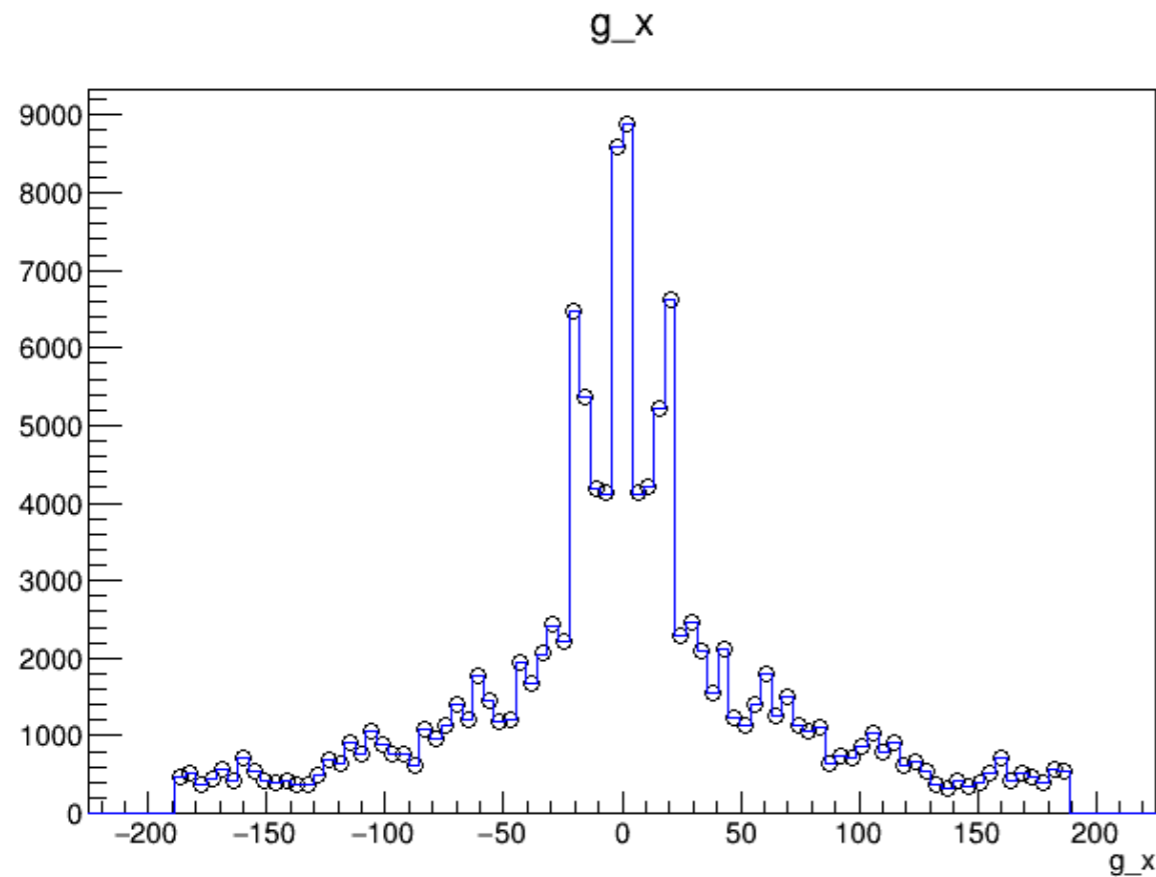
salzburg$ export ACTSFW_NUM_THREADS=4
12:51:19 Sequencer INFO start event 0
12:51:19 Sequencer INFO start event 5
12:51:19 Sequencer INFO start event 8
12:51:19 Sequencer INFO start event 7
12:51:20 Sequencer INFO event 7 done
12:51:20 Sequencer INFO start event 2
12:51:21 Sequencer INFO event 8 done
12:51:21 Sequencer INFO start event 9
12:51:21 Sequencer INFO event 5 done
12:51:21 Sequencer INFO start event 6
12:51:21 Sequencer INFO event 0 done
12:51:21 Sequencer INFO start event 1
12:51:22 Sequencer INFO event 2 done
12:51:22 Sequencer INFO start event 3
12:51:23 Sequencer INFO event 9 done
12:51:23 Sequencer INFO start event 4
12:51:23 Sequencer INFO event 6 done
12:51:23 Sequencer INFO event 1 done
12:51:23 Sequencer INFO event 3 done
12:51:24 Sequencer INFO event 4 done
```

12 seconds

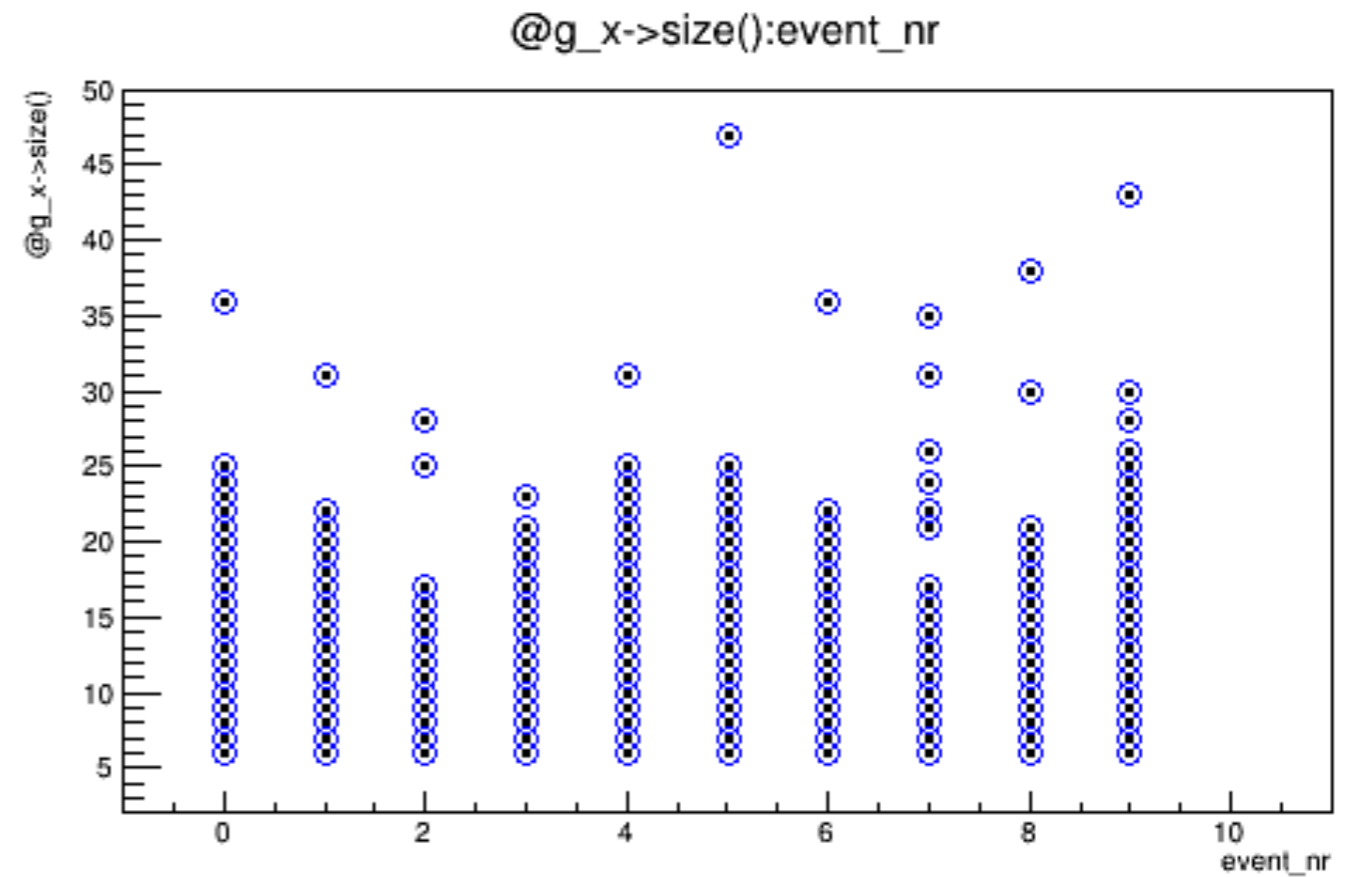
5 seconds

# GeometryContext Comparing the two

Total comparison:



Per event comparison:



```
salzburg$ export ACTSFW_NUM_THREADS=1
```

```
salzburg$ export ACTSFW_NUM_THREADS=4
```

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Re-deploy for Run-4/Phase-2

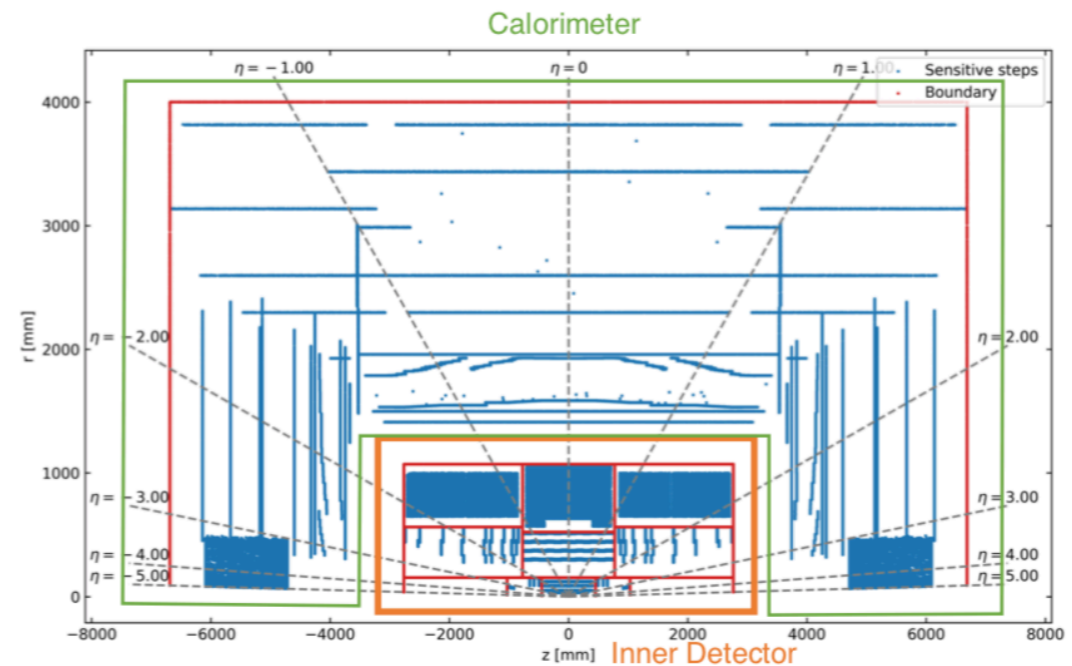
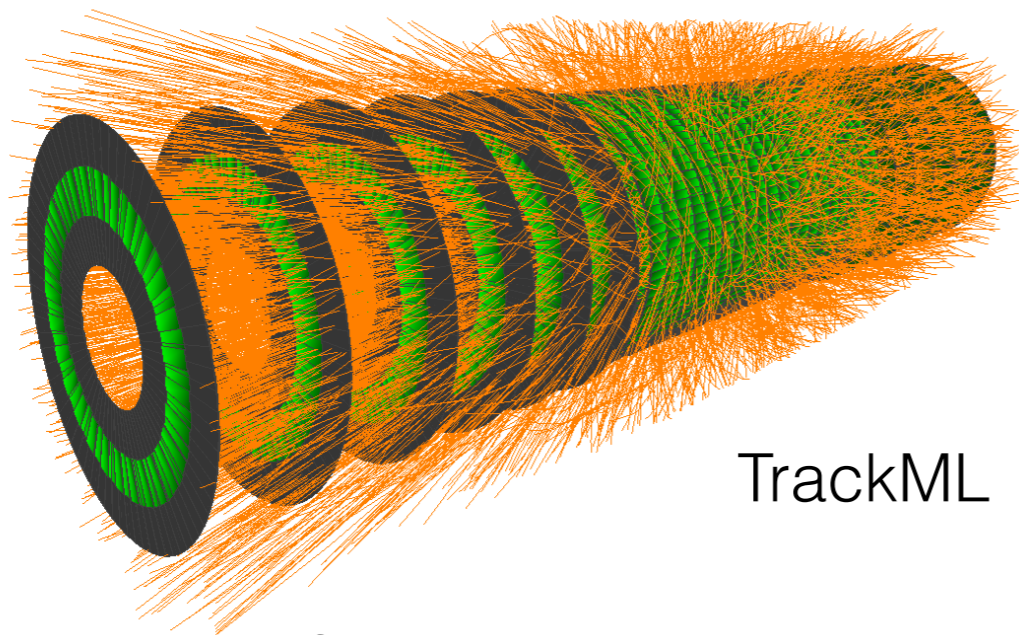
open for  
algorithm  
development

ATLAS: atlas/athena/Tracking/Acts

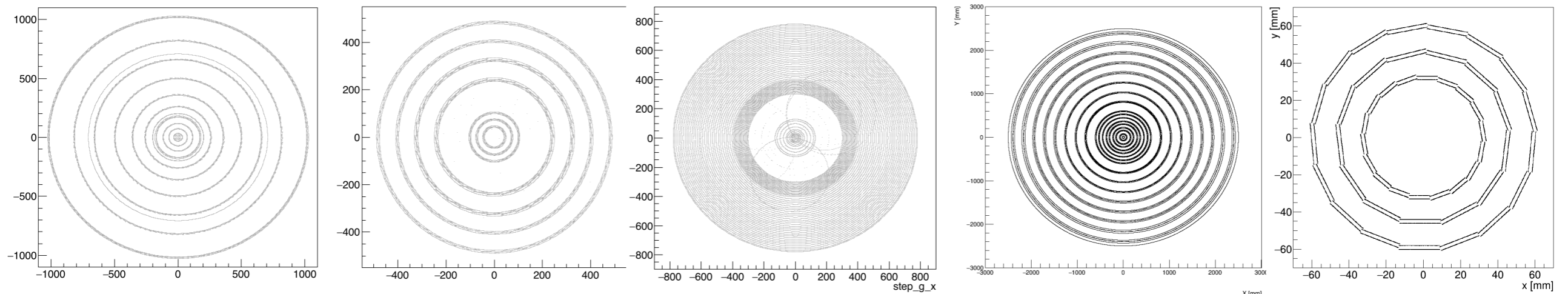
# TrackML Aftermath

Started to port first TrackML algorithms into **acts-framework**

- Idea is to create a testbed for algorithm development and templating
- provide several detectors to test on



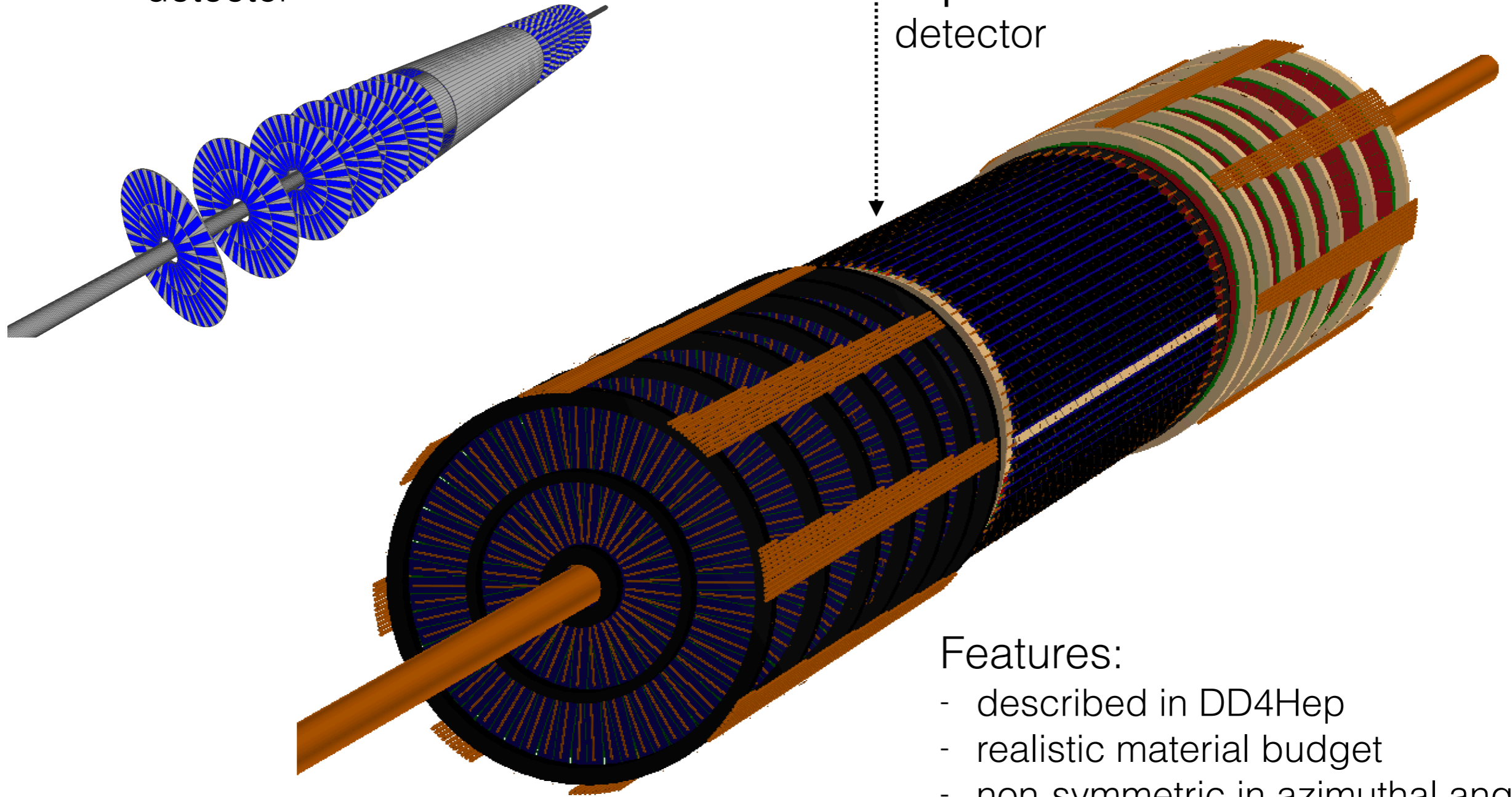
A bunch of other detectors:



# OpenData Detector

TrackML Pixel  
detector

OpenData Pixel  
detector



## Features:

- described in DD4Hep
- realistic material budget
- non-symmetric in azimuthal angle
- full (G4) and fast (ACTS) simulation
- misalignment possibility

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ATLAS: atlas/athena/Tracking/Acts

# acts-core repository

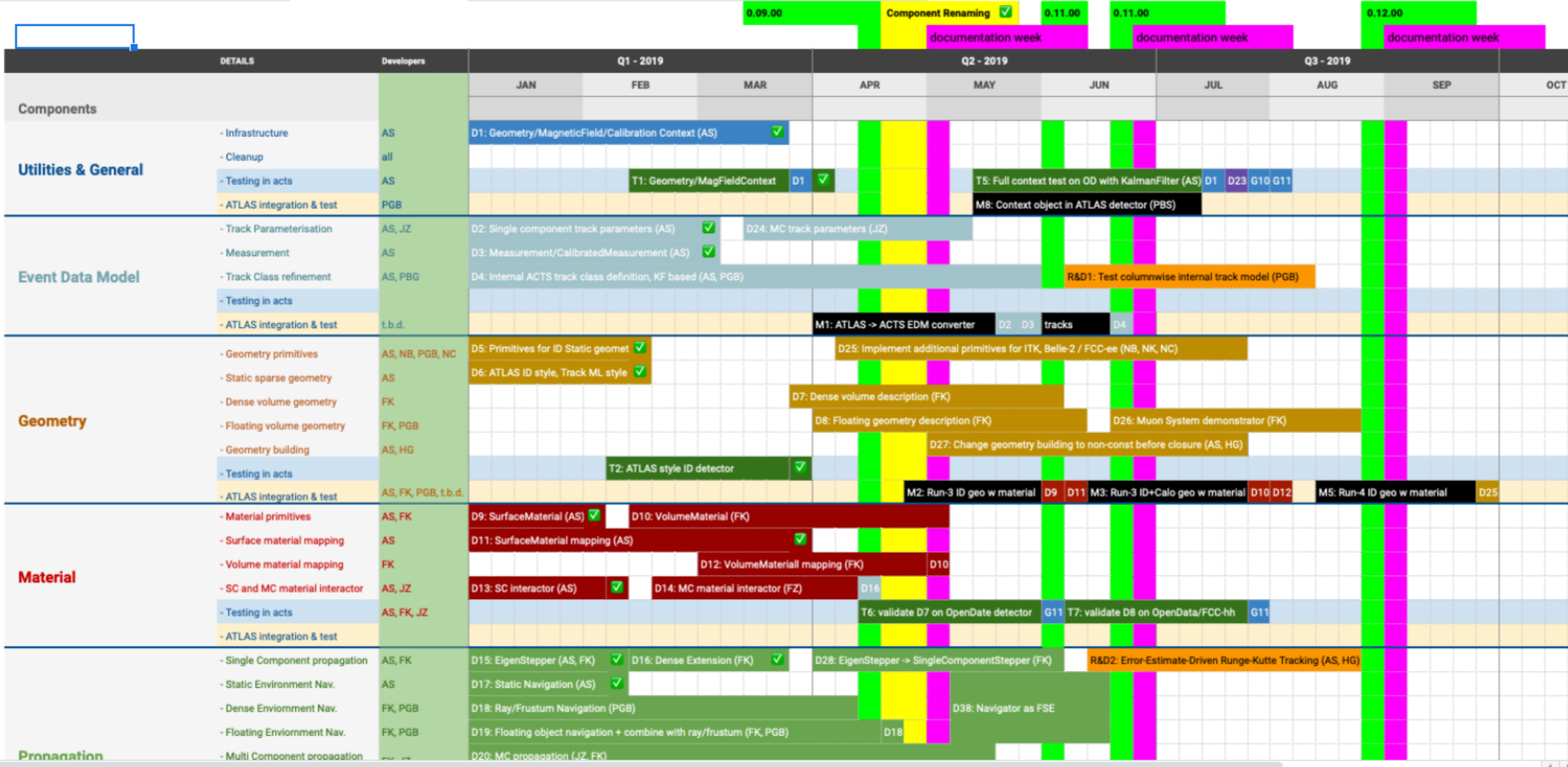
freeze geometry & EDM API

freeze propagation API

## ACTS PROJECT TIMELINE

PROJECT TITLE: acts  
 PROJECT MANAGER: AS

COMPANY NAME: CERN  
 DATE: 17/03/2019



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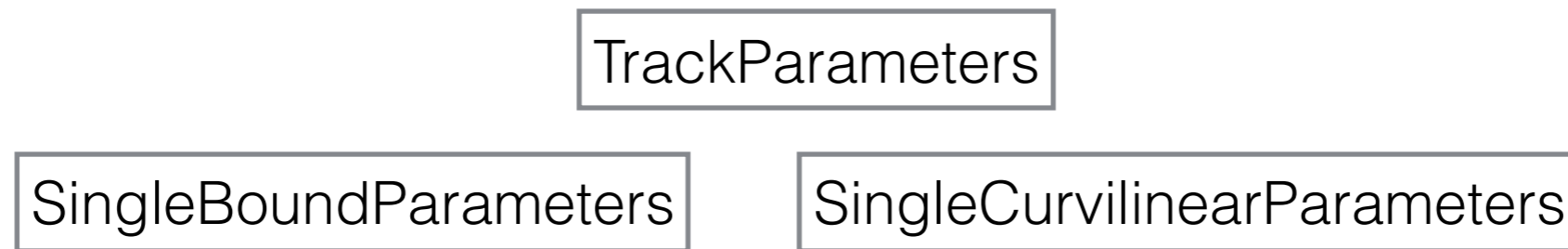
ATLAS: atlas/athena/Tracking/Acts

started geometry  
building & extrapolation



# Backup

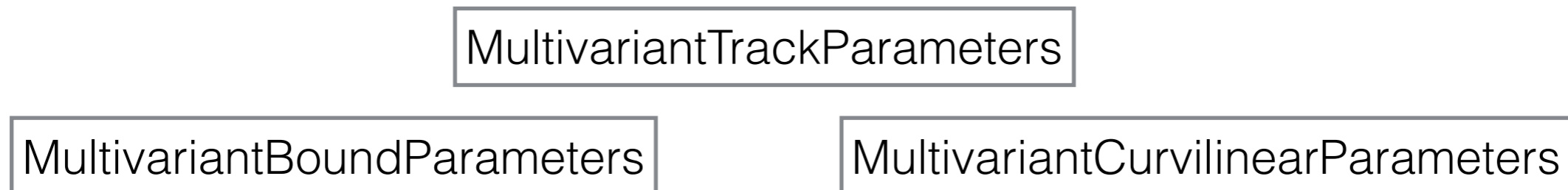
# Event Data Model Track Parameters



## Extension for Multi Component representation

- avoid copying of Extrapolator (as done in ATLAS) and Fitter infrastructure for multi-variant fitters (MultiTrackFitter, GSF)

*act as single track parameters in navigation, but will be propagated as multiple components in between*

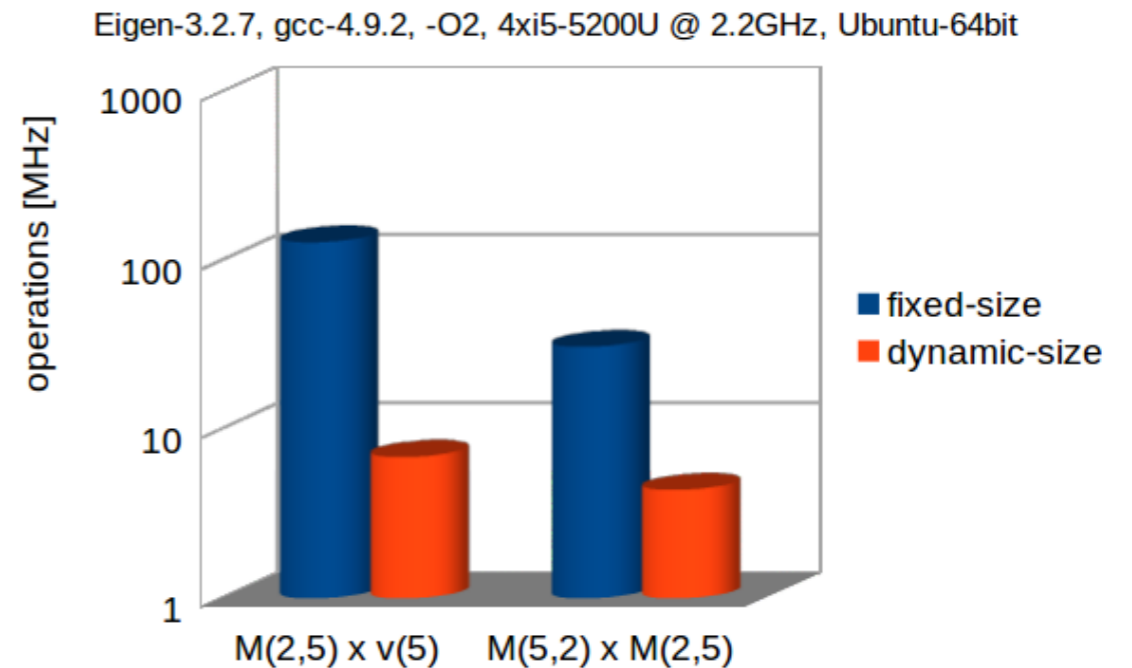


# Event Data Model Measurements

Fixed size matrix operations are evidently faster

- Acts EDM uses fixed-size
- needs container for heterogenous measurements:

*e.g. PixelCluster (2D), StripCluster (1D), Segment (4D), how to combine them in a track class or containers ?*



currently using `std::variant<>`

Investigating a more xAOD type storage in the background  
(MR open for testing)

# **Status** Binding to detector software & framework

Acts designed to have minimal overhead when being integrated in detector software

Algebra library is Eigen but dependencies are minimal

- may change to a template implementation (if beneficial)

No dependency on Identifier

- Detector calibration is resolved in detector geometry

Screen logging can be replaced by Id pre-loading

- needs a simple struct on the detector framework side that provides a `logger()` method.
- **tested with different loggers:**
  - Acts logger in acts-framework
  - Gaudi logger within FCCSW

# Status Binding to framework configuration

ACTS tools have a nested configuration struct:

```
namespace Acts {  
  /// doxygen documentation  
  class WorkHorse {  
    /// @struct Config for To  
    struct Config {  
      float coatColor; ///  
      float maxPath;    ///  
    };  
  };  
}
```

These structs are then configured by the detector framework,  
e.g. through Gaudi/Athena

```
/// feed from Framework into ACTS configuration  
declareProperty("CoatColor", m_cfg.coatColor);  
declareProperty("MaxPath",    m_cfg.maxPath);
```

tested with Gaudi for FCCSW & AthenaMT

# Configuration Strategy

Nested configuration struct by convention

```
namespace Acts {  
    /// doxygen documentation  
    class SomeComponent {  
        /// @struct Config for this Component  
        struct Config {  
            bool run_faster = false; ///  
        };  
        /// Constructor with config object  
        SomeComponent(Config& cfg);  
    };  
}
```

Inside the framework Wrapper

```
#include "ACTS/Package/SomeComponent.hpp"  
  
...  
    /// create the config struct  
    Acts::SomeComponent::Config scConfig;  
  
    /// bind to your framework configuration  
    declareProperty("RunFastVersion", scConfig.run_faster);  
    Acts::SomeComponent sc(scConfig);
```

# Concurrency Strategy

const-correctness

- ❑ Remove every use of "mutable" in ACTS  
!265 · opened 3 days ago by Hadrien Grasland

✔️ 👍 1 🗨️ 1 💬 9  
updated 3 days ago

statelessness engines

- cache visitor pattern for calls that need to run concurrently

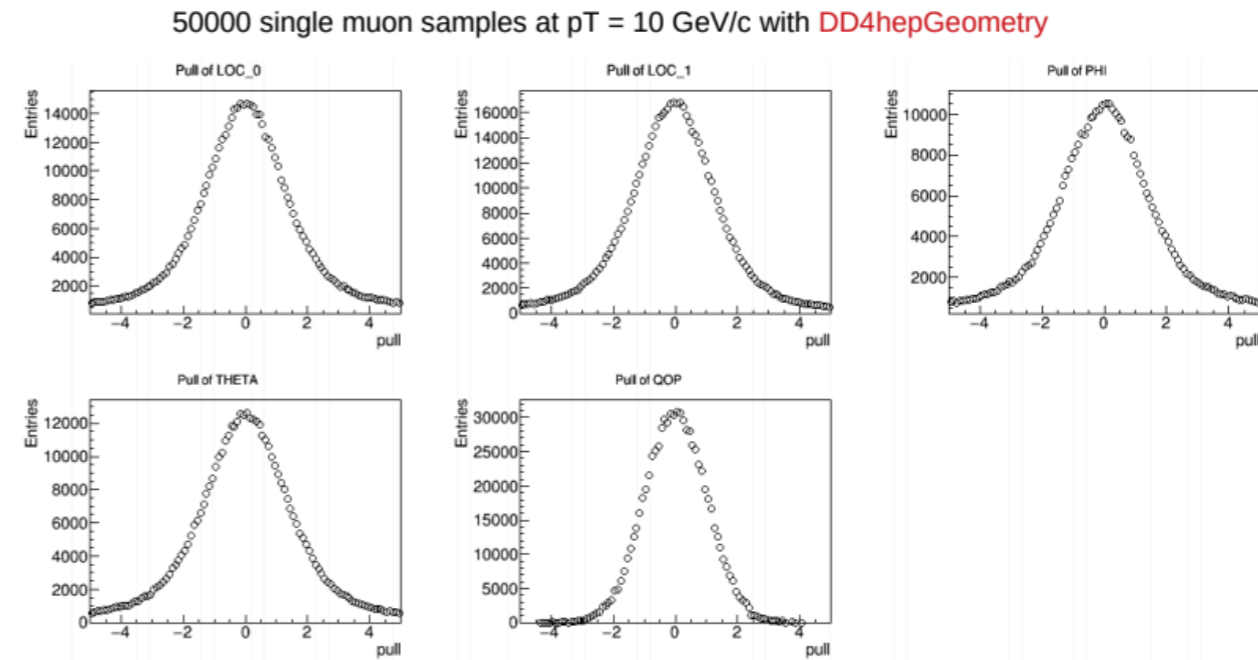
```
namespace Acts {  
    /// doxygen documentation  
    class WorkHorse {  
        /// @struct Cache for the WorkHorse  
        struct State {  
            float accumulatedPath = 0.; ///< the passed path so far  
        };  
        /// method to make the horse run  
        /// @param hState - cache tracker for this horse  
        /// @param coords - place where the horse should run to  
        /// @return a result, horse may drop dead if max path is reached  
        const RunResult run(State& hState, const Vector3D& coords) const;  
    };  
}
```

# Fitter Development & Validation

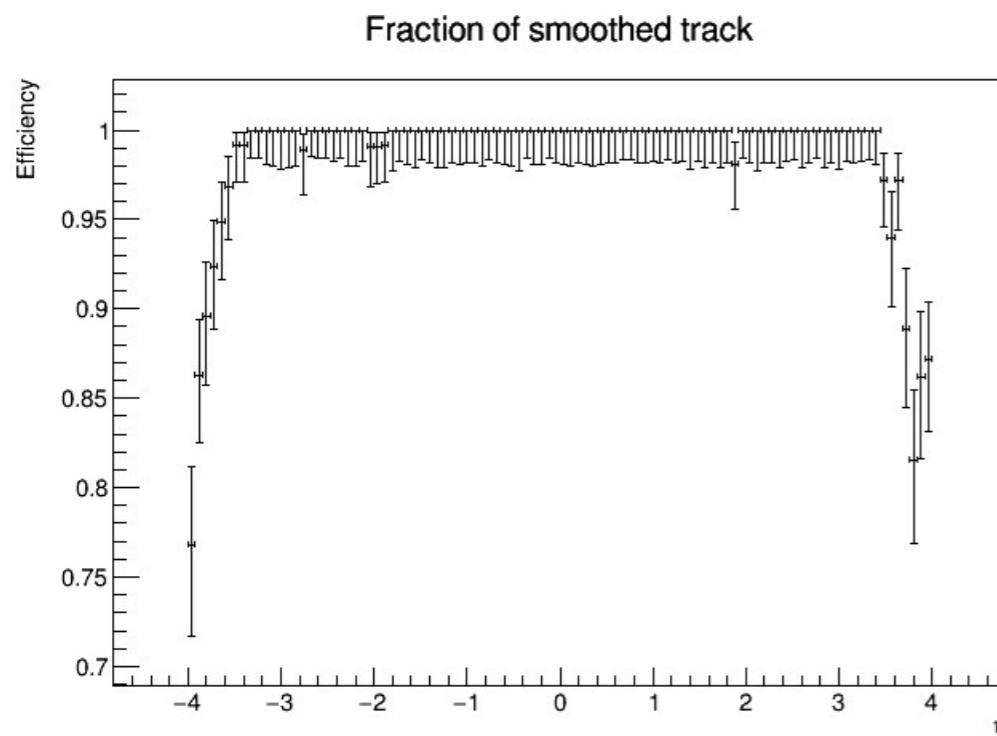
KalmanFitter prototype in validation currently

- multi-step validation program
  - *maths*
  - *material effects*
  - *transport*
  - *hole search*
- should exercise the full contextual chain including calibration

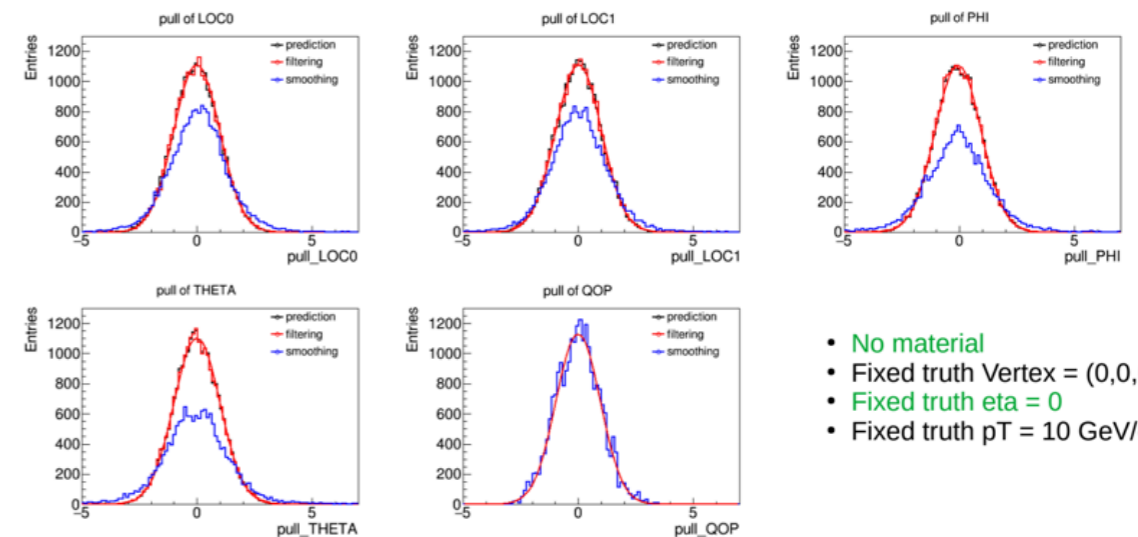
## Pull distribution



## Pull of track parameter



Pulls have Gaussian(0,1) distributions when track is almost perpendicular to plane surface



- No material
- Fixed truth Vertex = (0,0,0)
- Fixed truth eta = 0
- Fixed truth  $p_T = 10$  GeV/c