

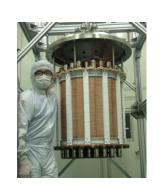
Journey of the data in PandaX dark matter experiments

Dan Zhang¹, Pengwei Xie², Xun Chen² University of Maryland, College Park¹ Shanghai Jiaotong Universtity² On the behalf of PandaX Collaboration

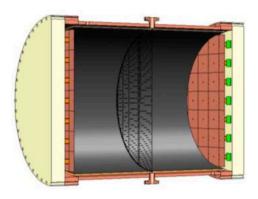
PandaX Experiment

PandaX = Particle and Astrophysical Xenon Experiments









PandaX-I: 120 kg DM experiment 2009-2014

PandaX-II: 580 kg DM experiment 2014-2019

PandaX-4T: multi-ton DM experiment 2019PandaX-III: 200kg-1ton Gaseous Xenon detector (future)

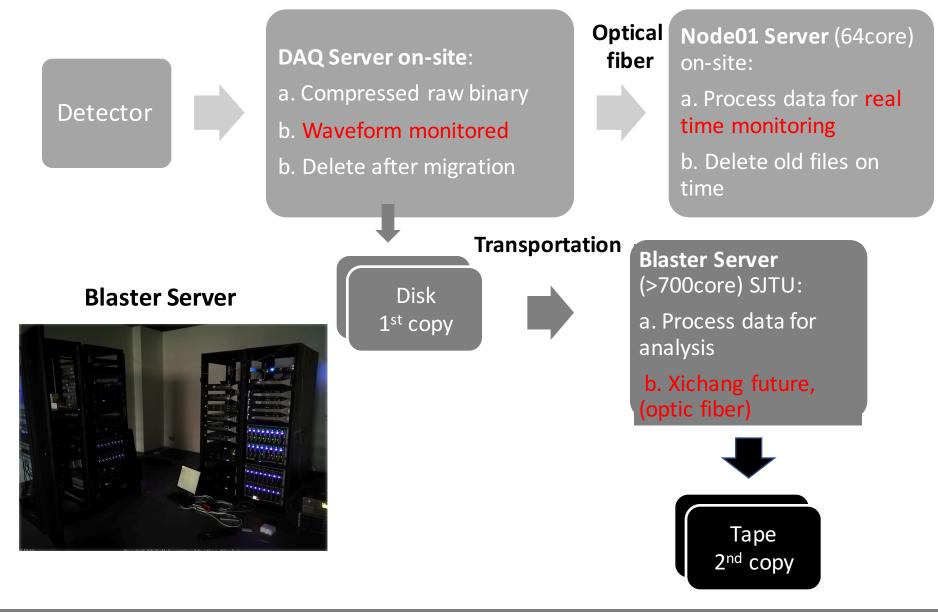
Outline

- 1. Data load
- 2. Journey of the data
 - 1. Storage and Transportation in PandaX-II and future
 - Processing chain in PandaX-II and preparation for PandaX-4T
- 3. Software accessories

1. Data load

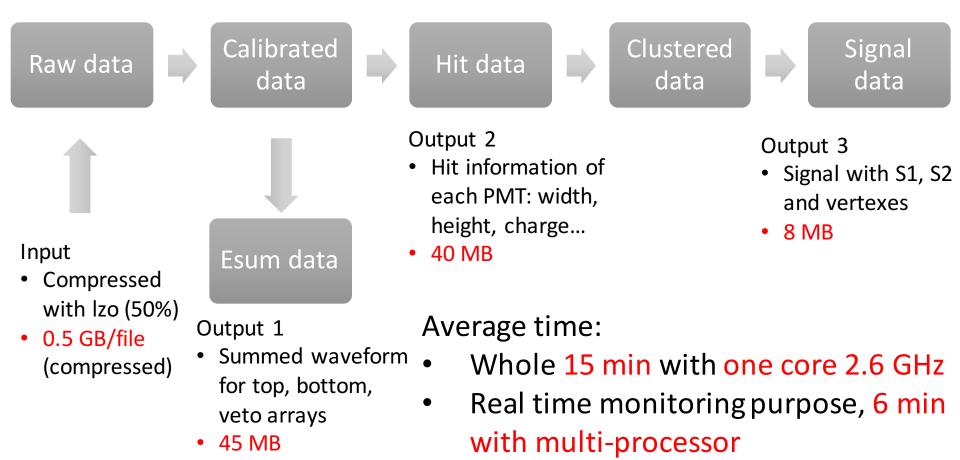
- PandaX-II (800 TB raw data)
 - 1.2 MB/s, ~ 2.2Hz (dark matter run)
 - 42 MB/s, ~ 100Hz (random trigger ²²⁰Rn calibration)
- PandaX-4T
 - Estimation: 300 MB/s (100 Hz in calibration)
 - DAQ design limitation: 800 MB/s
- PandaX future experiments (30T, 100T)
 - ~GB/s

2. Journey of the data in PandaX-II and future

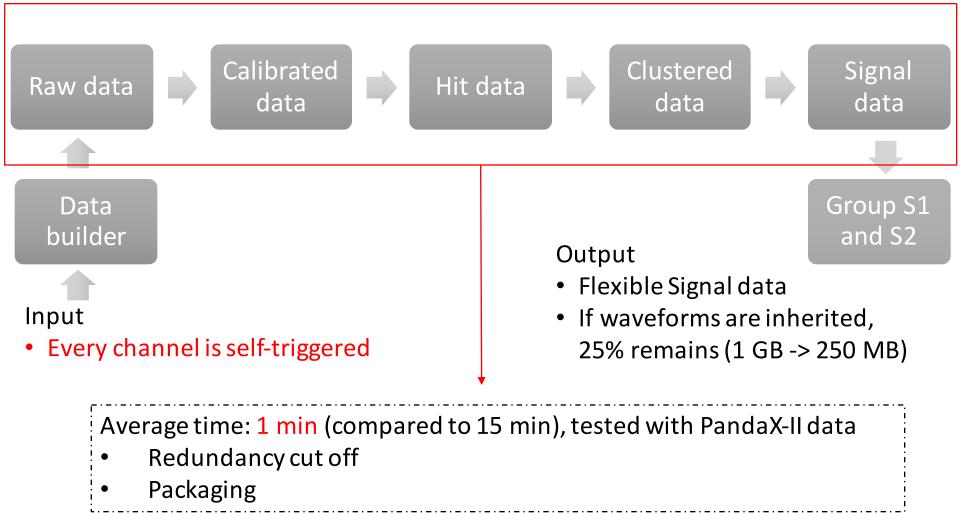


Data processing chain in PandaX-II

C++98, ROOT5



Data processing chain prepared for PandaX-4T C++14, ROOT6



3. Software accessories

- Improvement in persistent layer
- Online real-time monitor
- GitLab software management

• Machine learning/deep learning applications

Improvement in persistent layer

- Bamboo-shoot2 (PandaX-I, PandaX-II)
 - Based on ROOT TTree, ROOT serves as the persistency layer
 - Mapping Customized TObject to the Branch
- Problem
 - Compatibility (root 5.34/20)

- Bamboo-shoot3 (PandaX-4T)
- No dependency on ROOT
 - Object serialization library
 - File I/O library
 - Other utilities
- Data format
 - Bamboo-shoot data (bsd)
 - ZSTD compressed file (support lzo and no compression)

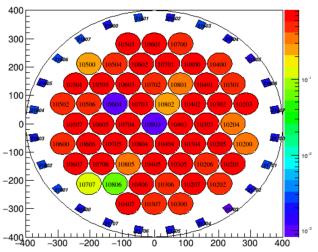
https://github.com/revive/bamboo-shoot3

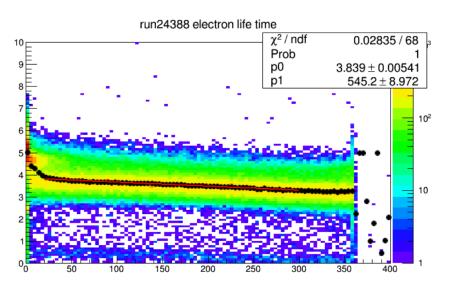
Online real-time monitor

- Waveform display (DAQ server)
 - Pipe stream, not stored but plotted when the webpage is visited
- Data quality page (64core server, 6 min right after getting the data)
 - Not deleted in the database
 - Detector and photomultiplier condition for each run and file

Run Nr. 24388	Started	Duration	Rate	Туре	Description
24388	Sep 11 21:10	10h 31m	8.47	PHYSICS_KR_ZEO	Zeolite Kr83 injection, 52+5SLPM

run24388 bottom dark rate pattern



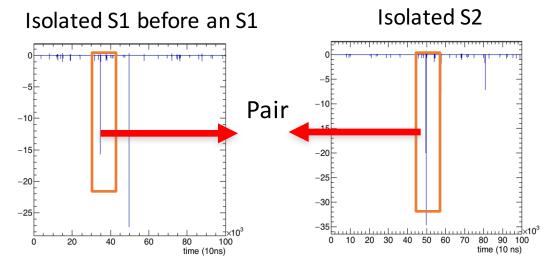


GitLab – software management

🔶 GitLat	D Projects 🗸 Groups 🗸 Activity Milestones Snippets 🖿 🎾	🕈 🗸 Search or jump to Q 🚺	n c o ~ 💽 ~
Proje	ects		New project
Your p	rojects 38 Starred projects 1 Explore projects	Filter by name	Last updated v
All F	Personal		
Ρ	PandaX / p4_tools	★O ŸO ♫O D O	Updated 2 days ago
Ν	PandaX / nest-lite Developer pandax version of nest	★1 ¥0 ♫0 D≀0	Updated 1 week ago
Ρ	PandaX / p4sc Developer slow control related code for pandax-xt	★O ŸO NO DO	Updated 2 weeks ago
В	software / BambooMC @ Developer BambooMC is a modularized simulation program based on Geant4.	★3 ¥3 ħ0 D0	Updated 1 month ago

Machine learning /deep learning applications

- Accidental background rejection in dark matter experiment
 - A multivariate approach (Boost decision tree)

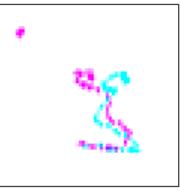


- Signal identifying in neutrinoless double beta decay (NLDBD) experiment
 - Conventional neuron network
 - Qiao Hao et. al., Signalbackground discrimination in PandaX-III

PandaX-III MC Simulation analysis



²¹⁴Bi decay gamma



Challenges for discussion

Discussion 1: self-trigger

Group S1 and S2

Black box for PandaX!

Every channel is self-triggered after passing the threshold.

No event number is recorded at the first place.

Discussion 2: decompression

- Trade-off between compressing ratio and speed
- ZSTD is used in Bamboo-shoot3, mainly selected for compressing ratio, 1GB<->0.5GB

Discussion 3: algorithms

- Position reconstruction: bad PMTs (horizontal), low drifting electric field (vertical)
- A better energy resolution.

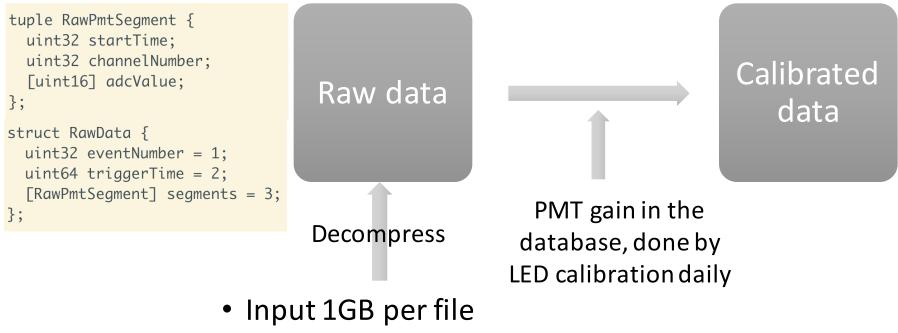


Thank you!

Backup

```
auto res = pu::map(
    [&](const RawData &raw) {
        auto cd = cal(raw);
        auto hd = hit_finder(cd);
        auto sd = hit_clustering(hd);
        auto ssd = sig_builder(sd);
        auto tsd = sig_tagging(ssd);
        auto psd = sig_pos_rec(tsd);
        return std::make_tuple(std::move(hd), std::move(psd));
    },
    raw_data);
```

New data reconstruction with Bamboo-shoot3 Test with PandaX-II data

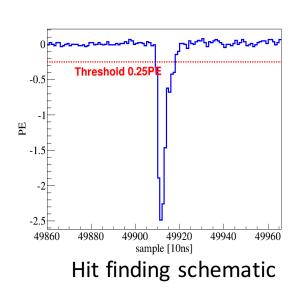


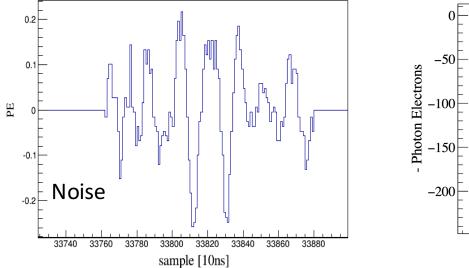
- PandaX-II
 - 1.2 MB/s, ~ 2.2Hz (dark matter run)
 - 42 MB/s, ~ 100Hz (random trigger ²²⁰Rn calibration)
- PandaX-4T
 - Estimation: 300 MB/s (100 Hz in 4T sensitive volume)

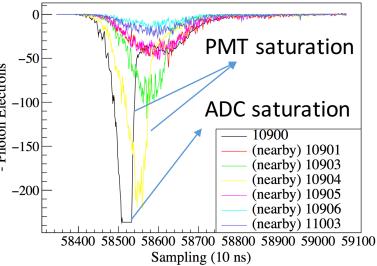




- Hit finding with a threshold (0.25 PE in PandaX-II)
- Hit tagging (noise, saturated, normal)
- Hit properties (area, peak, width, etc.)

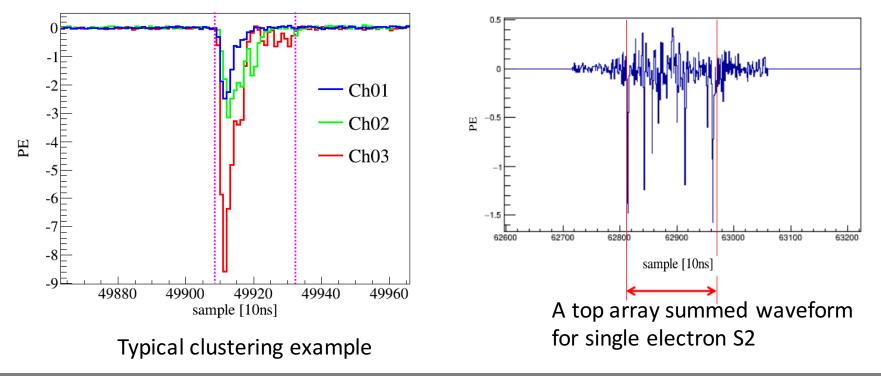








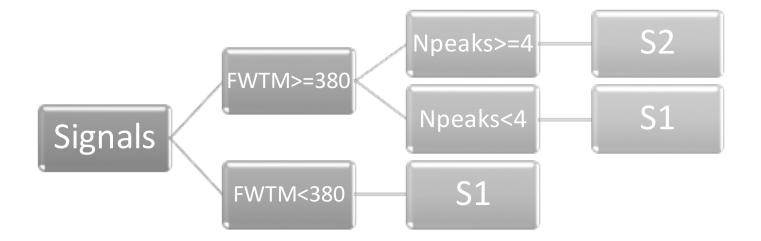
- Criterion: hits overlap in time will form a signal
- Special treatment: Small S2 (time seperation of hits less than 500ns)





Signal data

- S1 and S2 discrimination
- Horizontal position reconstruction



Horizontal position reconstruction

- Center of gravity (calculated for S1 or S2, top or bottom separately)
- Photon acception function (PAF) + statistic inference (maximum likelihood)

^{83m}Kr events comparison

Turned off 4 out of 55 top PMTs

Details will be Published soon.

