



New Techniques for Operational Control and Performance Optimization @ BESSY II

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At the **synchrotron radiation source BESSY II** (Helmholtz-Zentrum Berlin, HZB) both the **beamline** and the **machine groups** have started working towards setting up the infrastructure to introduce **modern analysis, optimization and automation** in order to improve the performance and the experimental setups.

In this talk we introduce some of these first tools - based among others on **ML techniques** - concerning data acquisition, simulation, machine measurement prediction and parameter tuning. More detailed results on ML- experiments will be presented at talk TUCPL01.



- ▶ The **Helmholtz Association** (the largest scientific organisation in Germany) has initiated the implementation of the **Data Management and Analysis** concept across its centers.
- ▶ Further HZB collaborations:
 - ▶ Accelerating Machine Learning for physics (AMaLea) (DESY, KIT, HZDR and HZB) - *more about this at talk TUCPL06.*
 - ▶ Advanced Computational Tools (ACT) (TU Darmstadt, HZB).
 - ▶ Findable, Accessible, Inter-operable and Re-usable Data Infrastructure for material research (FAIRmat/FAIRDI) (IRIS Berlin, HU Berlin, Max Planck Institute and HZB).



Advanced data taking and processing

ML tools @ BESSY II

- Measurement prediction framework

- RLControl - Parameter tuning with Deep RL

- Building the digital twin

- Understanding beamline performance

Next steps

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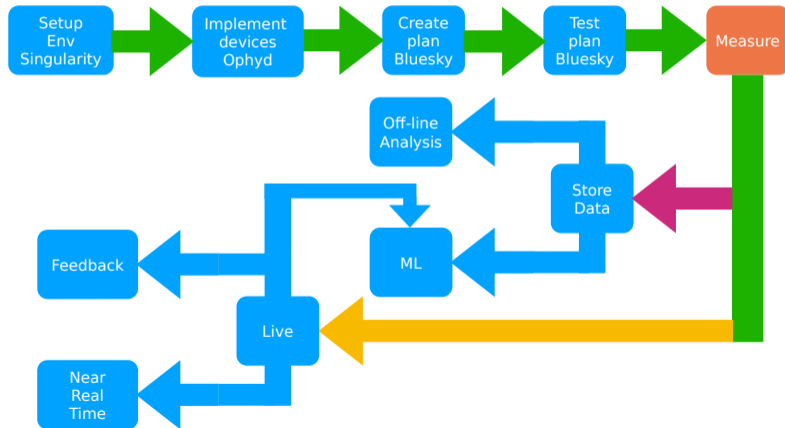
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Advanced tools for data taking and preprocessing are currently being incorporated: Singularity, Ophyd, Bluesky, ElasticSearch...



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Device	Injector Ring accelerator	Undulator	Beamline	Experiment
Data	<ul style="list-style-type: none"> • Archive, Diagnostic • Simulations • Online optimization 	<ul style="list-style-type: none"> • Diagnostic • Raytracing • Scans/online data 	<ul style="list-style-type: none"> • Demands • Simulations • Beamtimes 	
Methods	<ul style="list-style-type: none"> • SVR-RFF • DNN • Deep-RL-Control • RNN, LSTM 	<ul style="list-style-type: none"> • Autoencoder • CNN, MLP, GBoost • Dataloader • Tensor product • kNN, auto-diff. 	<ul style="list-style-type: none"> • Reasonable random generator 	
Agent	Operator	Beamline scientist		(Random-) User

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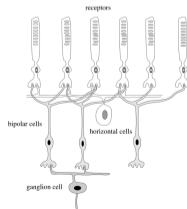
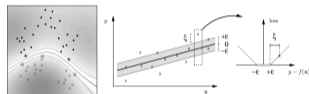
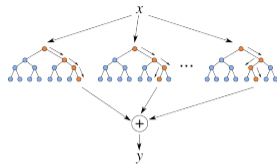
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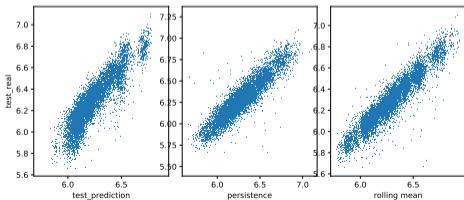
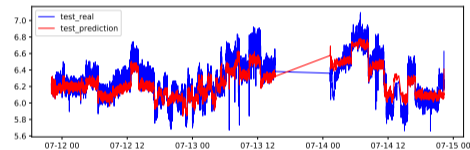
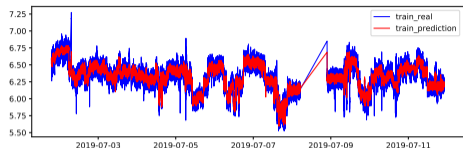
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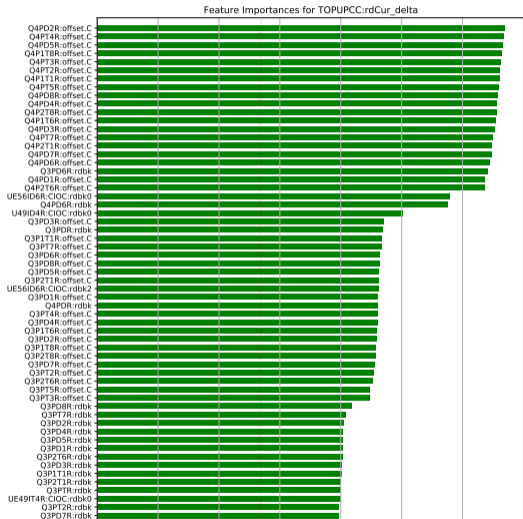
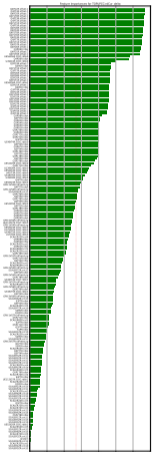
- ▶ **Ensemble methods:** Random Forests, Extremely Randomized Trees... ([Bre01], [GEW06]). For regression, **MSE** as loss \rightarrow variance as impurity measure. **Self-explaining:** allow individual analysis of each variable's behavior.
- ▶ **Support Vector Regression** [Smo98] with **Random Fourier Features** ([RR08]). SVR extends traditional SVM (for classification) via Vapnik's ϵ -insensitive loss function ([Vap95]).
- ▶ **Neural Networks** (e.g. see [Roj96]). Feed-forward NNs for regression (i.e. MSE as loss function).



Figs. from <https://dsc-spidal.github.io/harp/docs/examples/rf/>, [SS03], [Roj96].



- ▶ Prediction model w.r.t. 185 machine readbacks:
 - ▶ Gap and shift of insertion devices
 - ▶ Quadrupoles power supplies and offsets,
 - ▶ Local beam loss fractions
 - ▶ ...
- ▶ We **omit** previous lifetime observations to avoid an excessive reliance on them, force the model to identify further patterns and reuse the gained information.
- ▶ E.g. SVR with Random Fourier Features forecasts the trends in **ca. 3 days of completely unseen data** ($R^2 = 0.724506 \pm 0.015291$).



- ▶ Analysis with RandomForest.
- ▶ Evenly distributed feature importances - **quadrupoles** (offsets) and **insertion devices** stand out.

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- ▶ **Deep Deterministic Policy Gradient** ([LHP⁺16]): Actor-critic Reinforcement Learning algorithm for continuous environments.
- ▶ Off-policy data and the Bellman equation used to learn the Q -function.
- ▶ Q -function used to learn the policy.
- ▶ *Approximated* with NNs.

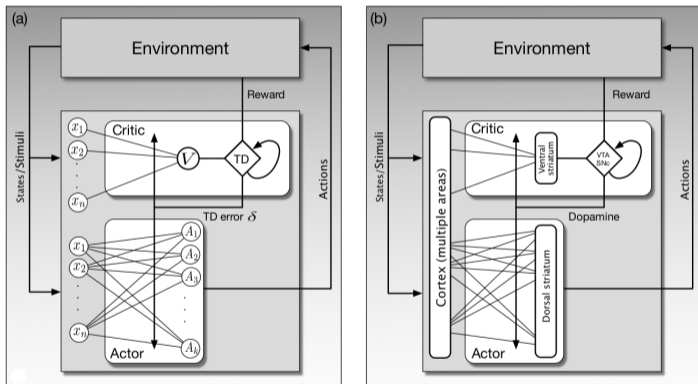
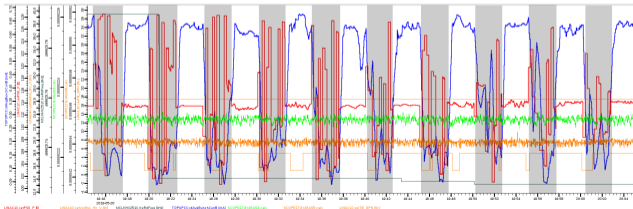
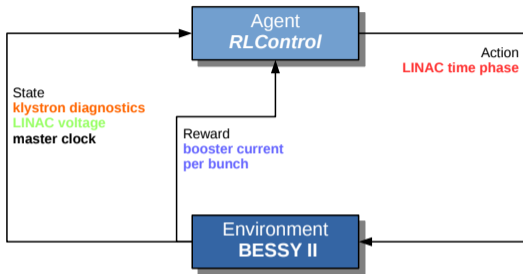
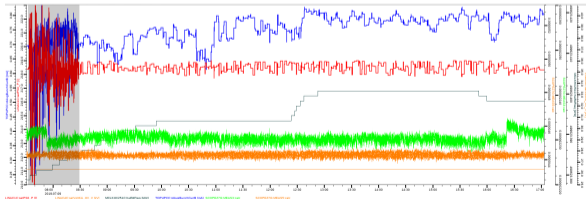
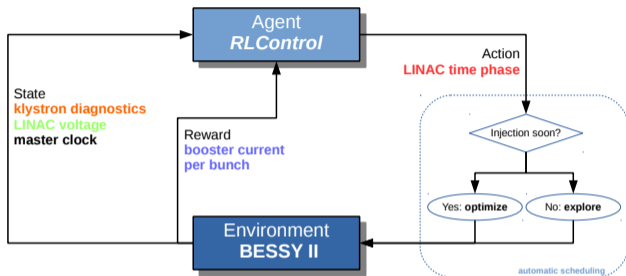


Figure: From [SB18]



- ▶ First use case: **booster current optimization**.
- ▶ Nowadays manual parameter tuning is required - low booster current after long interruptions.
- ▶ Test with periods of **pure exploration** (shaded) and optimization **learning with no exploration**. Some issues:
 - ▶ Non-optimal exploration → Parameter Space Noise ([PHD⁺17])
 - ▶ Long training time and normalization problems → pretraining with historical data (inspired by [ZM18]).



- ▶ **Automatic scheduling:**
 - ▶ Pure exploration is scheduled in the meantime between injections to avoid disturbing user activity.
 - ▶ Optimization activated shortly before each injection.
- ▶ Successful 8.5 hours long test **during user operation.**
- ▶ More detailed results and further use cases (**injection efficiency optimization**) will be presented during this conference - talk TUCPL01.

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The *accelerator/source* side: OCELOT surrogate models for RL ([AGTZ14]). Some tests with toy-examples (emittance, orbit-correction...) in small lattices already carried out. Challenge: *export* a RL-agent trained with the virtual lattice to the real accelerator.

The *beamline/x-ray* side: general initiative to take advantage of ML methods also for the **retrieval of scientific data** from the measurements. Close coordination of activities developing toolsets for the accelerator and the beamlines ([M⁺19]). Focus on improving the prerequisites for common ML methodologies.



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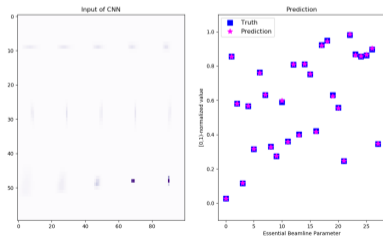
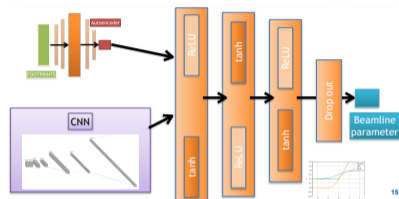
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- ▶ Today's beamlines have **couple of hundred parameters** - impossible to map with traditional simulation tools.
- ▶ Approach: **ML methods** to learn raytracing as well as beamline parameter prediction from photon diagnostics.
- ▶ Test - **inversion** of beamline raytracing:
 - ▶ Diagnostic: **photon footprint screens** at three different positions in the beamline (intermediate focus, exit slit and experimental focus).
 - ▶ These are used from a neural network to **predict 28 essential beamline parameters** (100 parameters varied in the training).

Current development by Dr. Gregor Hartmann - further info: talk MOCPL02 ([M⁺19]).



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- ▶ Measurement prediction:
 - ▶ Build models for further target variables: purity...
 - ▶ Classification approach.
 - ▶ Surrogate models.
- ▶ *RLControl*:
 - ▶ Further tests, investigation and use cases (injection efficiency with more state and action variables, orbit correction with OCELOT pretraining...).
 - ▶ Integration of advanced data collection tools such as Bluesky.
 - ▶ User interfaces.
- ▶ Beamline raytracing:
 - ▶ Benchmark and optimize beamline designs.
 - ▶ Determine the current state of a beamline.
 - ▶ Include more "building blocks" (e-beam, undulator, experiment, spectrometers).
 - ▶ Determine at which position photon detection screens are best placed.

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- ▶ **Ensemble methods:** Random Forests, Extremely Randomized Trees... ([Bre01], [GEW06])
- ▶ Based on different randomization techniques:
 - ▶ Bootstrapping
 - ▶ Random variable subsets per node
 - ▶ Random threshold selection per node
- ▶ For regression, MSE as loss \rightarrow variance as impurity measure.
- ▶ Self-explaining: allow individual analysis of each variable's behaviour.
- ▶ Can be used for several tasks (outlier detection, feature selection...).

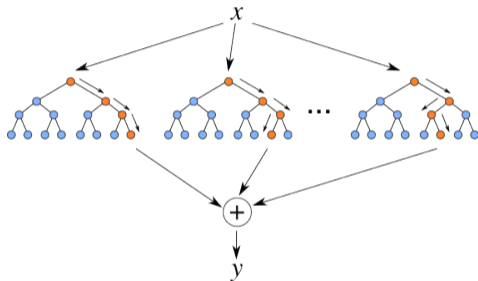


Figure: From <https://dsc-spidal.github.io/harp/docs/examples/rf/>

- ▶ **Support Vector Regression:** Linear and RBF Kernel, Random Fourier Features... ([Smo98], [RR08])
- ▶ SVR extends traditional SVM (conceived for classification) via Vapnik's ϵ -insensitive loss function ([Vap95])

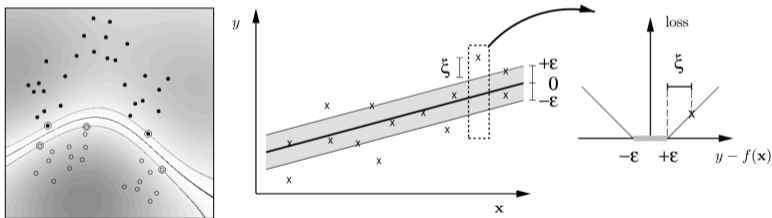


Figure: From [SS03]

- ▶ **Neural Networks** (e.g. introduction in [Roj96])
- ▶ (Deep) Feed-forward NNs for regression (i.e. MSE as loss function).
- ▶ Flexible and powerful, but with a huge meta-parameter space, including network architecture.
- ▶ Some recent works investigate this problematic from a theoretical point of view (e.g. [RT17], [IF18]) - specially interesting for our regression scenario.

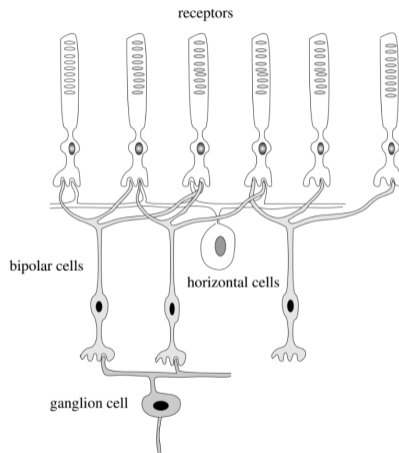


Figure: From [Roj96]

- ▶ **Isolation forest** ([LTZ08])
- ▶ Classification with an unsupervised method.
- ▶ Builds an ensemble of random trees for a given data set where each point gets a single leaf.
- ▶ Anomalies are those instances which have *short* average path lengths on the trees.

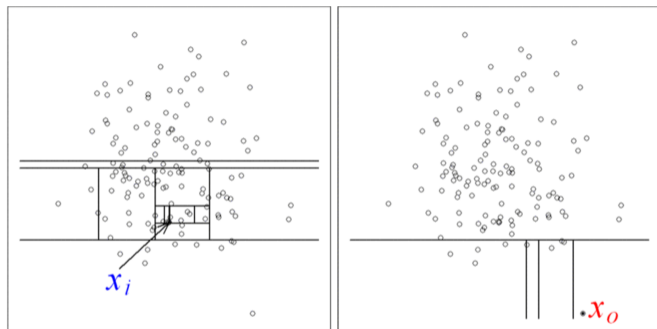
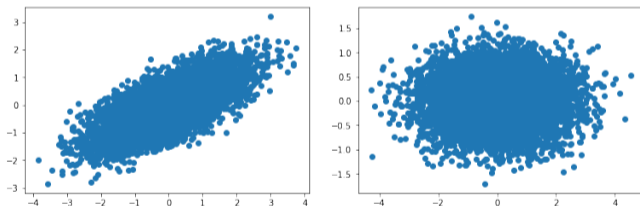


Figure: [LTZ08]

- ▶ Traditional **PCA** ([Pea01] (!!)): orthogonal transformation that creates linearly uncorrelated variables (principal components):

$$T = WX \text{ with } w_k := \arg \max_{|w|=1} \sum_i \langle [x_i - \sum_{c=1}^{k-1} \langle x_i, w_c \rangle], w \rangle^2$$



- ▶ The distribution of the transformation coefficients $\{w_i\}$ reveals the inner variable structure of the data.

- ▶ Filtering via **feature importance** with randomized forests ([LWSG13]) - based on internal impurity decrease per feature:

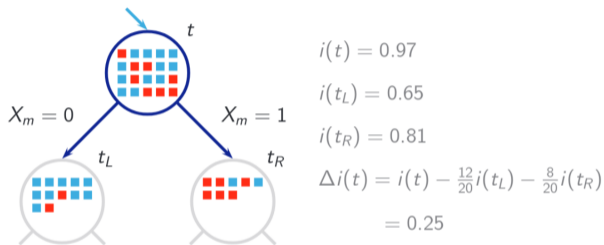


Figure: From [LWSG13] (poster)

- ▶ Theoretically conceived for totally randomized forests, can be approximated with RandomForest and/or ExtraTrees restricting the number of admitted features per node.

- ▶ **Bellman equation** with a deterministic target policy μ_θ :

$$Q^\mu(s_t, a_t) = \mathbb{E}_{s_{t+1} \sim E} [r(s_t, a_t) + \gamma Q^\mu(s_{t+1}, \mu(s_t))]$$

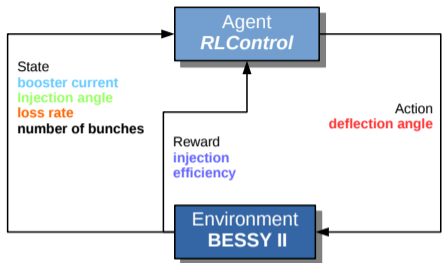
- ▶ **Critic update** (parametrized approximation Q_ϕ) through SGD with loss:

$$L(\phi) = \mathbb{E}_{s_t \sim \rho^\beta, a_t, r_t, s_{t+1} \sim E} \left[\left(Q_\phi(s_t, a_t) - (r_t + \gamma Q_{\tilde{\phi}}(s_{t+1}, \mu_{\tilde{\theta}}(s_t))) \right)^2 \right]$$

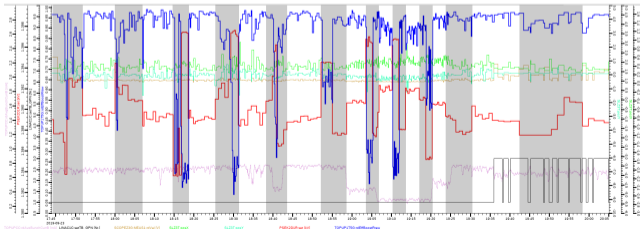
- ▶ **Actor update** - (off-policy) Deterministic Policy Gradient Theorem ([SLH⁺14]): for a performance objective $J_\beta(\mu_\theta) = \mathbb{E}_{s \sim \rho^\beta} [Q^{\mu_\theta}(s, \mu_\theta(s))]$,

$$\nabla_\theta J_\beta(\mu_\theta) \approx \mathbb{E}_{s \sim \rho^\beta} [\nabla_\theta \mu_\theta(s) \nabla_a Q^{\mu_\theta}(s, a) |_{a=\mu_\theta(s)}]$$

- ▶ Implementation tricks: delayed target networks ($Q_{\tilde{\phi}}, \mu_{\tilde{\theta}}$), replay buffer.



- ▶ Further experiments with *RLControl*: **injection efficiency optimization** (work in progress).



Backup: Beamline - Training data via simulation

- ▶ Beamline raytracing is a powerful tool to understand X-ray-beam propagation and for optimizing beam properties for the experimental requirements.
- ▶ The amount of parameters is impossible to map with traditional simulation tools.

