RooFit redesign

Conclusions from 27-28 June 2019 meeting @ CERN

Three parts

- Rewriting likelihood calculation in "sane" statistics/physics based structure/concepts
- Task management & parallel calculation
- Minimization

Rewrite likelihoods

- RooUnbinnedLikelihood
- RooBinnedLikelihood
- RooMultipleLikelihood
- RooConstraintLikelihood
- Common interface: evaluate_partition with components, partitions and begin + end
- everything with stride = 1 now, no more interleave (bad for vectorization & general performance)
- These are not RooAbsArgs, but there will be a wrapper class (return value of createNLL) which will
 use the Likelihoods and will again be a RAA ("calculators != RooAbsArg/Real")
 - Conceptual replacement of current RooAbsTestStatistic
 - But also different; user facing replacement, because parallelization will now be done elsewhere
- Optimization (all the stuff that's now in RooAbsOptTestStatistic):
 - Common base class for e.g. binned and unbinned (similar optimization strategy)
 - Separate RooPDFOptimizer class

- Composition instead of inheritance
- Make possible to use different "back-ends" next to the default RooFit back-end, e.g. TensorFlow, analytical derivations, etc.
- JobLikelihood, JobDerivative, Job2ndDerivative
 - These should somehow be fed to the minimizer
 - Possibilities for implementation:
 - RooMinimizer<JobL, JobD, Job2D>
 - ABClass for all three types that can be implemented per back-end

• Current situation:

- Singleton TaskManager
- Jobs defined through inheritance from Job class
 - Parallel -> Vector<Single> -> {Single, Job}
- Preferred situation:
 - Singleton TaskManager (same)
 - Jobs have RAR* likelihood (wrapper) object as member
 - Minimizer cues calculation of something, e.g. likelihood or gradient
 - Job then takes care of parallelization, i.e. talkes to TaskManager
 - Only generic part of Jobs is the partitions/components division, everything else is back-end specific

- Nomenclature of Jobs vs Tasks is confusing, can we think of better names?
 - three (/ four) concepts:
 - "Job": the concept of a parallelizable computation, like a Likelihood or a Gradient
 - [unnamed]: a single full execution of that computation
 - "task": individual computational unit of the Job; one part of the Job that can be computed in parallel from the other parts
 - "batch": used for vectorization, overlaps currently with tasks
 - How do others call these things?
 - TBB
 - Tasks: corresponds to our tasks
 - Blocks: range of tasks
 - Iteration space: full range of tasks
 - Not 100% compatible, just different units of the same basic quantity, no semantic link to the thing you're trying to parallelize
 - <u>https://en.wikipedia.org/wiki/Job_(computing)</u>
 - In computing, a **job** is a unit of work or unit of execution (that performs said work). A component of a job (as a unit of work) is called a task or a step (if sequential, as in a job stream).
 - Compatible with our current definition
 - More (creative) options instead of Job:
 - <u>http://www.namibian.org/travel/misc/collective-nouns.html</u> collective animal names
 - Problem decomposition https://en.wikipedia.org/wiki/Parallel_programming_model#Problem_decomposition
 - "Workflow"
 - Something from graph theory maybe... Tasks could perhaps be Leafs, which would also alleviate the Job/Task degeneracy

- TaskManager needs to know all tasks of all jobs at start-up time (fork)
- How do we handle tasks that themselves can be split up as a Job into new tasks?
- If the constellation of Jobs is known before fork, it's possible in current framework
- Need some form of dependency management
- We can implement switching between different sets of tasks (e.g. only partial derivatives or also split Gradient by likelihood components or...) as Job "strategies"
- This can then be handled internally in the Jobs
- The only non-Job infra that has to be added is a message to change strategies

Minimization

- For Jobs to implement effective strategies based on minimizer phase, they must be able to somehow detect "phase"
 - E.g. in line search phase, or in gradient calculation phase, or doing Hesse or using Simplex method, etc.
 - Must Minimizer interface be modified to expose this information?
 - As far as we can see: no.
 - The information is already signaled by the call the minimizer makes to the back-end
 - For Minuit, 3 possible calls:
 - FCN.evaluate()
 - GRAD.Gradient()
 - GRAD.G2ndDerivative() [Is it actually used? If not, can we do this? Does this only calculate the symmetric components (seems like it, it only has one "icoord" parameter)? @Lorenzo]