

Preliminary hardware design of the Wire BBLRC for HL-LHC

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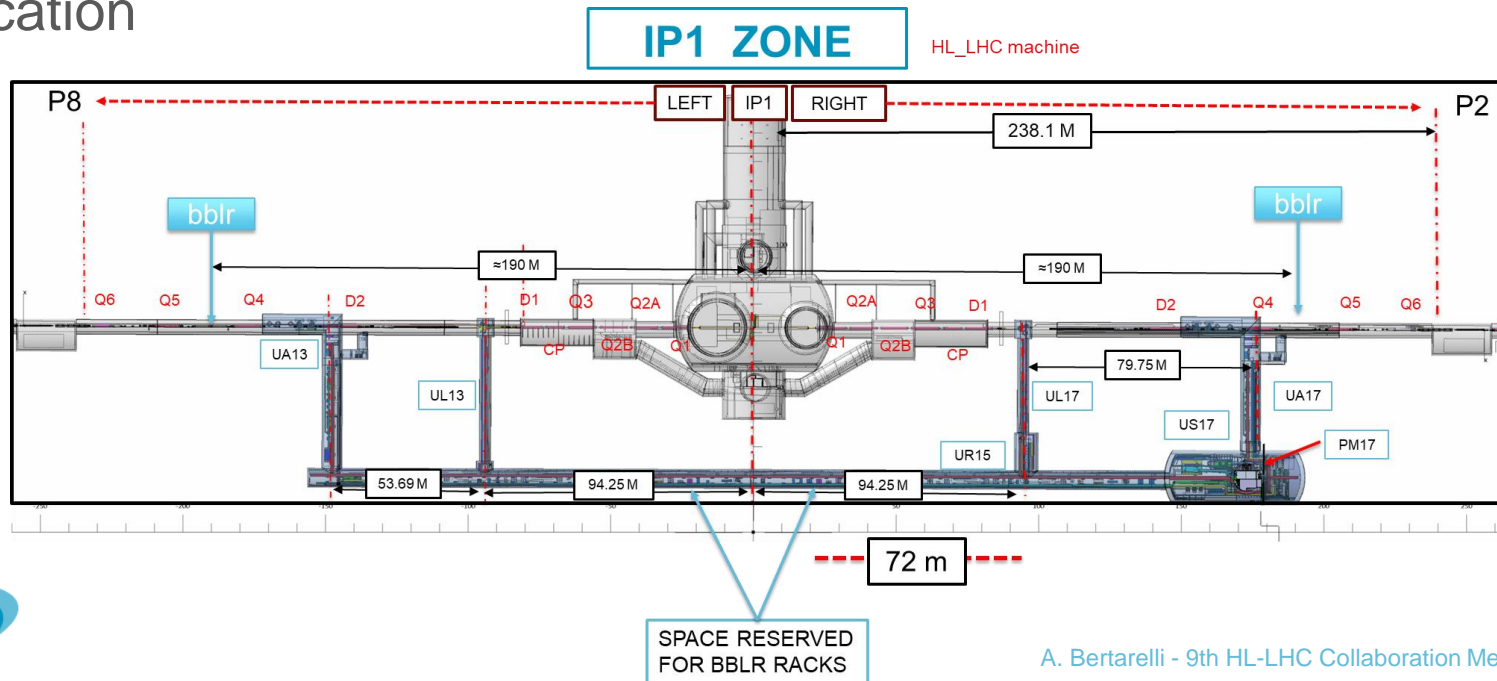
with contributions from F. Carra, M. Garlaschè, F. Motschmann

CERN

9th HL-LHC Collaboration Meeting
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Context

- Beam-Beam Long-Range Compensators with physical wires are considered a valuable options for HL-LHC to **increase dynamic aperture at small crossing angles**
 - either in conjunction with Crab Cavities (HL-LHC round optics)
 - or as back-up solution (without Crab Cavities)
- A space reservation of 4.5 m on both beams was made on either sides of IP 1 and IP5, allowing 1 unit per beam per location



Initial Design Assumptions

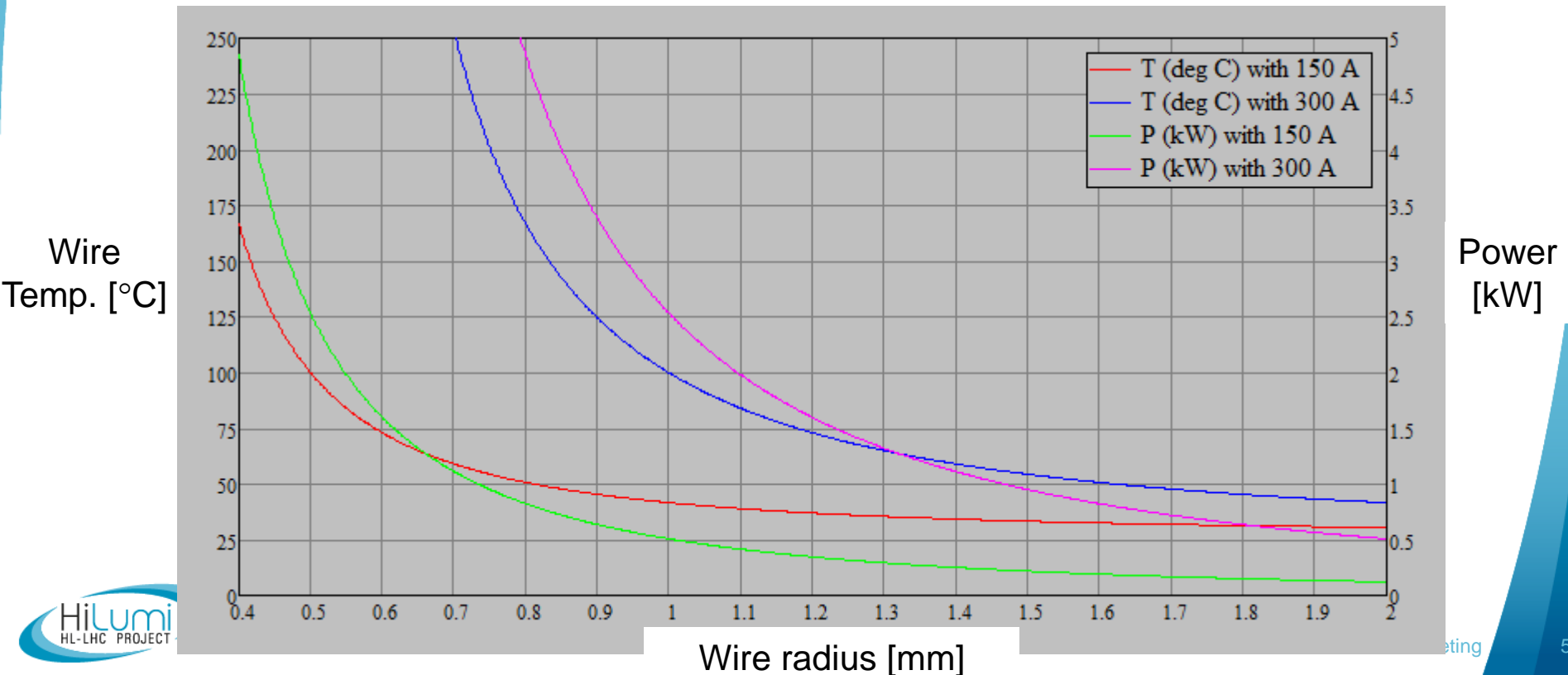
- These assumptions are a preliminary set of requirements defined for mechanical design purposes which may evolve or be scaled
 - **1 wire per beam** per side of IP1 and IP5 → **8 wires**
 - **Single wire** positioned in a vacuum chamber per beam
 - **Round wire** cross-section
 - Wire total active length **3 m**
 - **450 Am DC** per wire, i.e. **150 Am/m**
 - Wire entirely positioned in the shadow of Tertiary collimators ($> 10.4 \sigma$)
 - **Beam losses considered negligible**
 - **RF effects yet to be studied ...**

The Idea

- Use a slim, light design with a **thin, bare, metal** wire, allowing to move as close as necessary to the beam, while minimizing interactions with beam particles.
- Bond the metal wire onto a support being both an **electrical insulator** and a **thermal conductor (ceramic)**.
- To keep design simple and affordable, use a **mobile vacuum chamber**, integral with wire, which can be shifted horizontally and/or vertically. The cross-section should allow to host **two parallel chambers**, side by side on Beam 1 and 2
- To ease fabrication, assembling and installation, split the active length (3 m) in several **independent modules**, tentatively 3, **each 1 m long**
- Each module to be mounted and aligned on a **single support** structure, which can be integrally actuated.
- Exploit experience and know-how with collimators and TCTW, particularly for actuation system ...

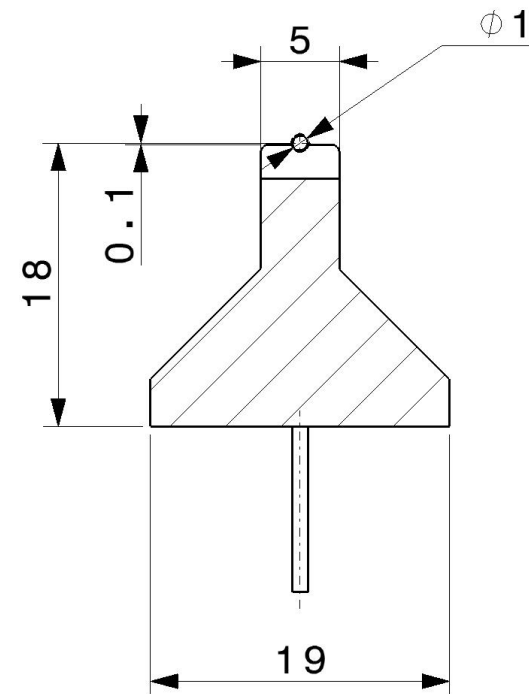
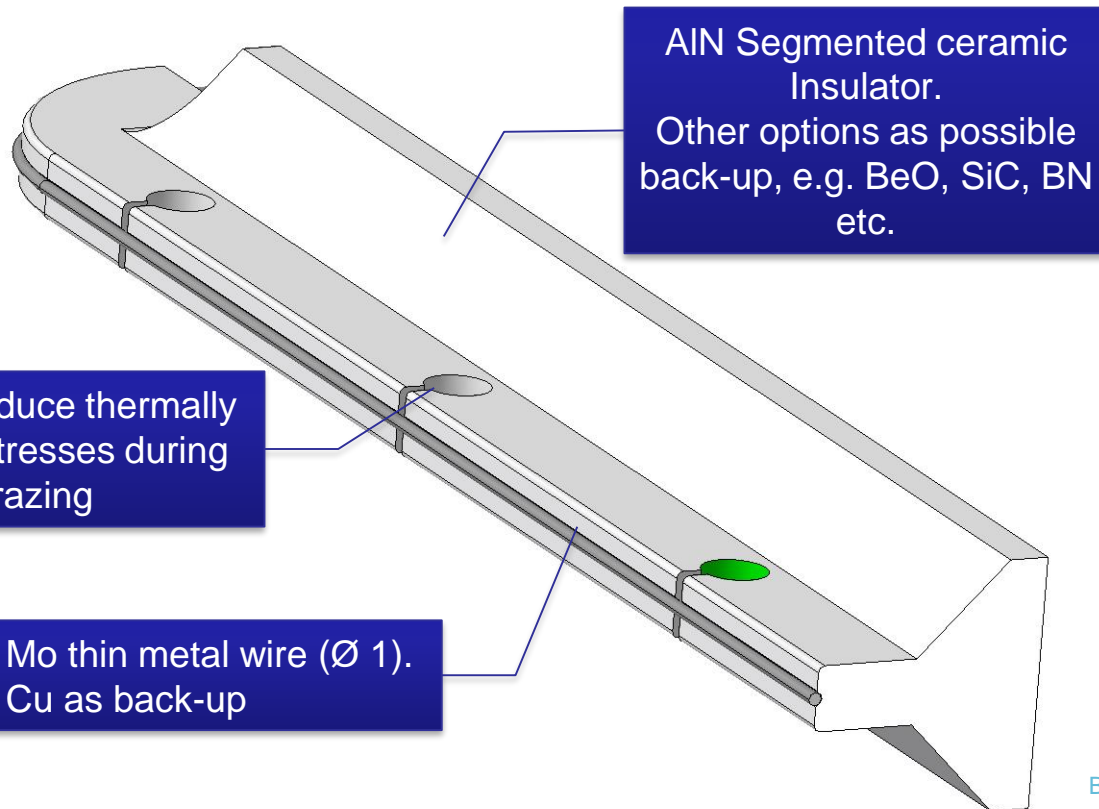
The Idea

- How much current can the wire carry? It depends on its cross section ...
 - A linear relationship exists between Current and Power (or max temperature) allowing a simple scaling of the design, if needed.
 - Mo wire used in the example below ...



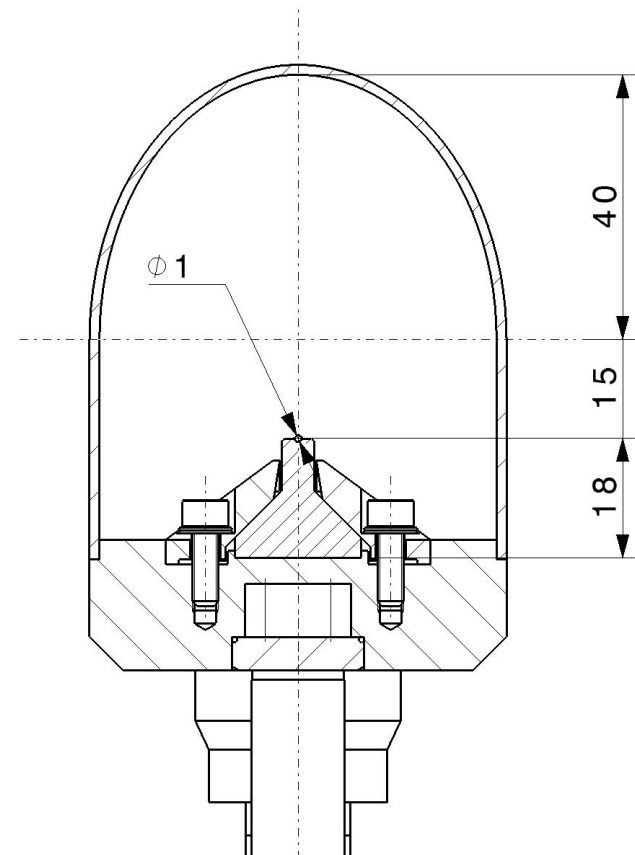
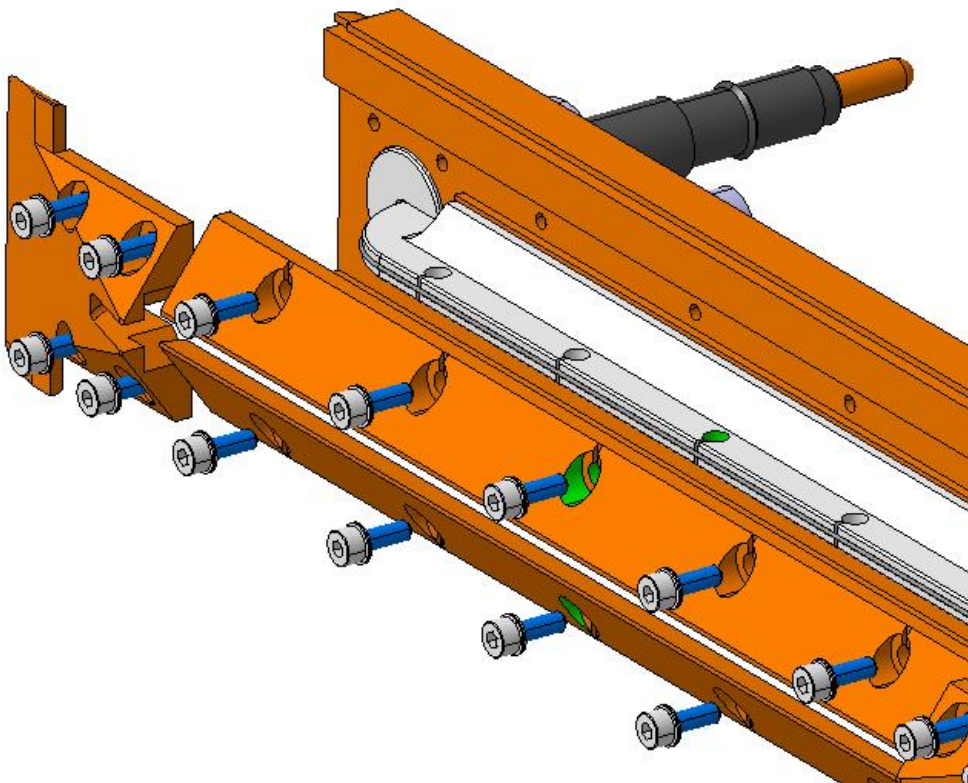
Main Design Features: Wire and Insulator

- To start, we assume a $\text{Ø}1$ mm 1 m-long Mo wire with 150 A current
 - Vacuum brazed solution
 - **Mo wire** has higher electrical resistivity compared to **Cu** (back-up), but is **better matching** ceramic **CTE** and is refractory (higher robustness)
 - Diameter can hardly be smaller than 1 mm for technological reasons (regardless of electric current)



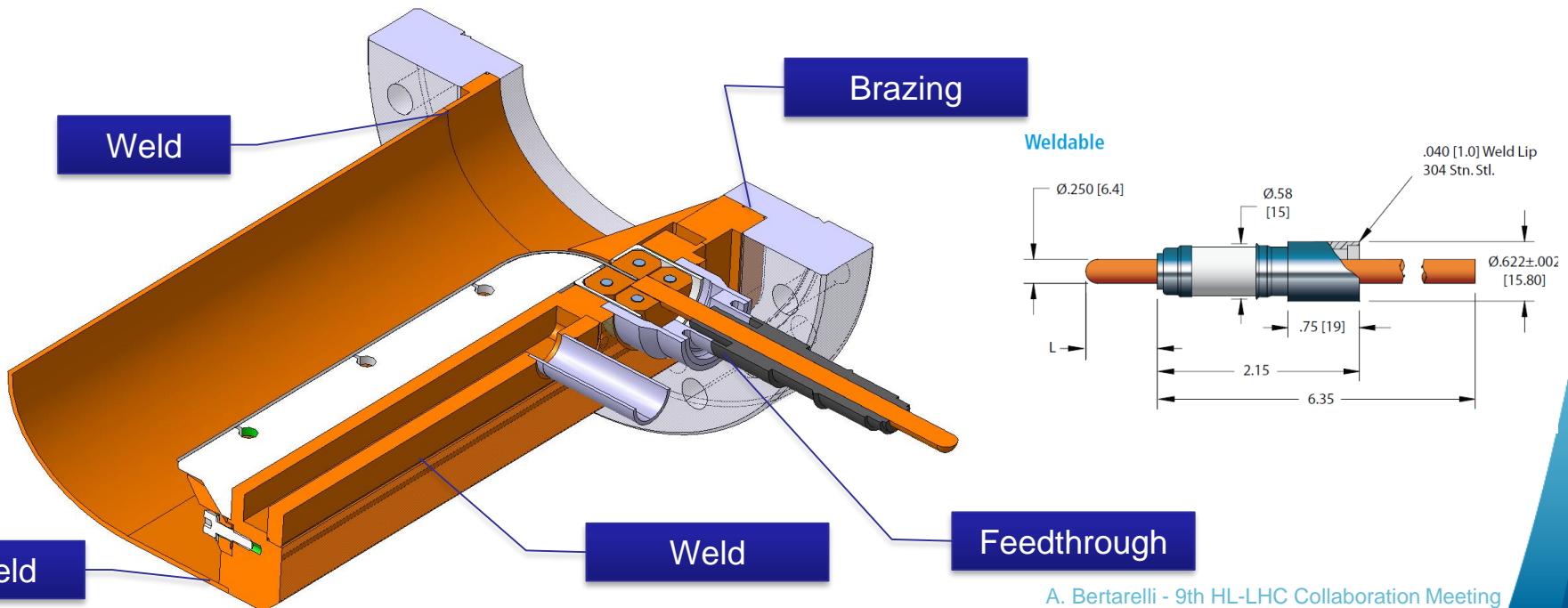
Main Design Features: Housing

- Insulator with wire is mechanically clamped to a Cu-based housing, via controlled-torque screws
- Cu clamps to be designed to minimize RF impedance
- Wire active length 1 m; several insulator modules to be assembled (250 ÷ 300 mm long)



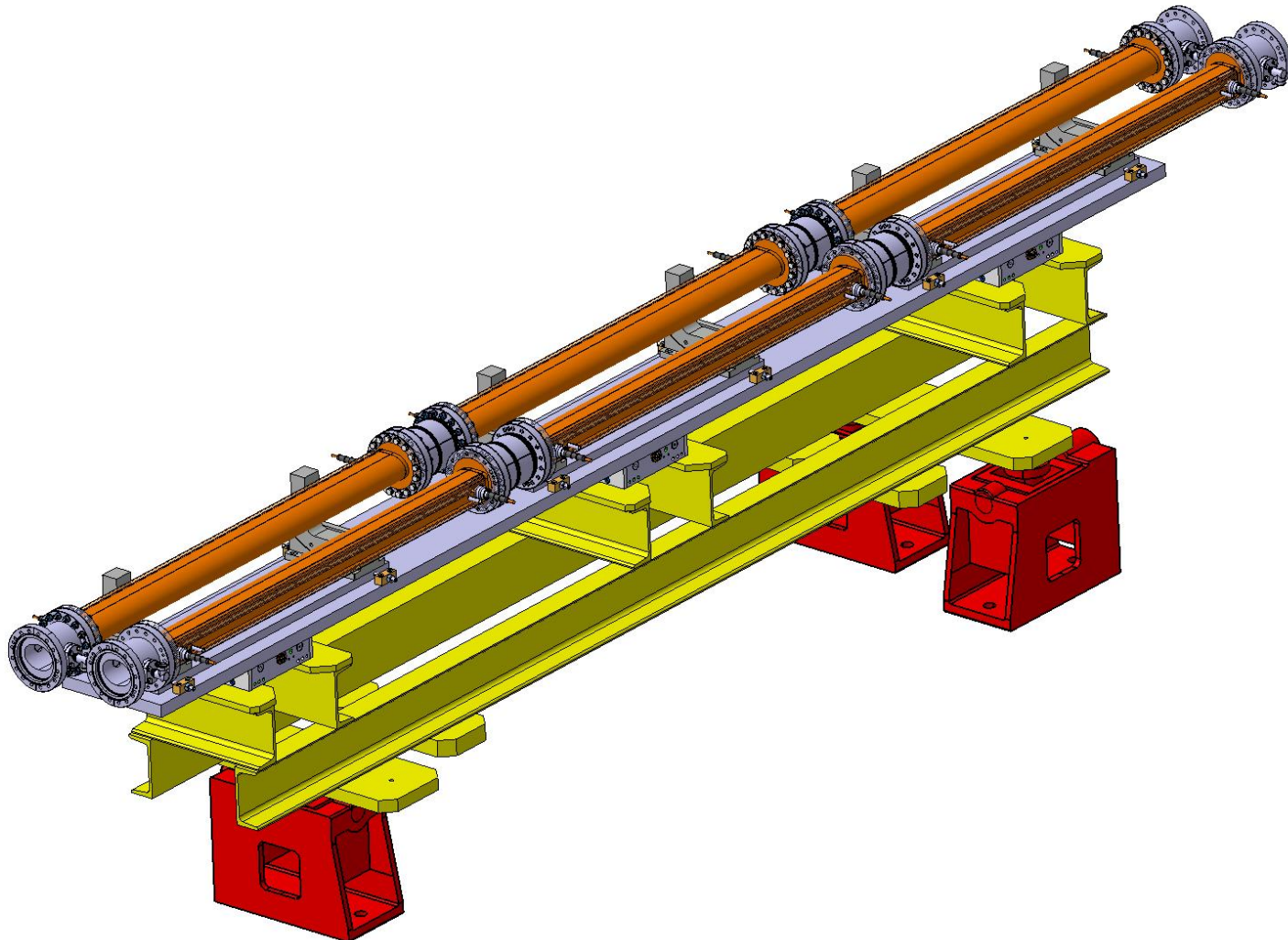
Main Design Features: Vacuum Chamber

- Water cooling channel obtained by housing machining and cover welding.
- **Commercial feedthrough** connection carrying up to 185 A. If more current is needed, liquid-cooled feedthroughs should be adopted
- Cu half-shell welded to the housing
- Stainless steel flange brazed to copper and then welded to vacuum chamber.



Possible Assembly Layout

- Conceptual layout with two parallel assemblies. For discussion only, many details missing, e.g. actuation system ...



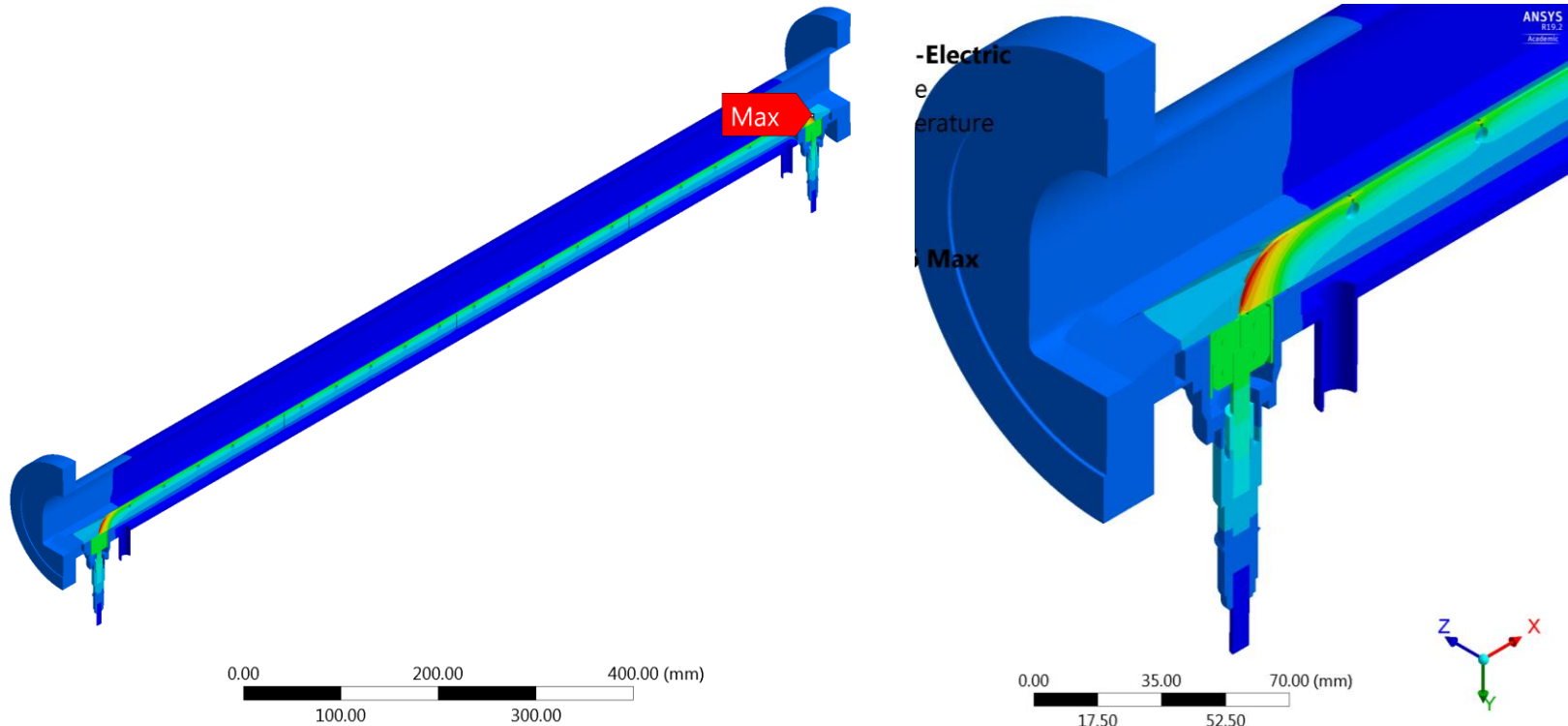
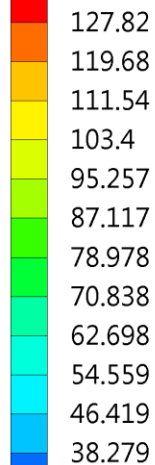
Numerical Simulations

- With a \varnothing 1 mm **Mo** wire and **150 A per module**, Joule-effect power to be dissipated is **~ 2.1 kW** corresponding to **~ 14 V** (**~ 90 m Ω**)
- Maximum temperature **~ 90 °C** in straight wire (up to **~ 140 °C** in the end transitions)
- Water coolant circulating at **~ 1.5 m/s**, **~ 12 L/min**

D: Thermal-Electric

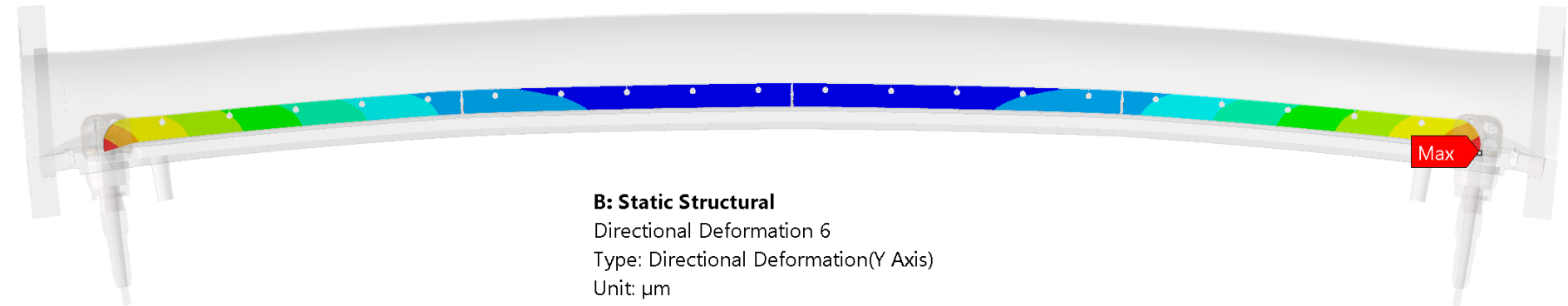
Temperature
Type: Temperature
Unit: °C
Time: 1

135.96 Max



Numerical simulations

- Estimated deflection of the vacuum chamber in operating conditions is $\sim 30 \mu\text{m}$



B: Static Structural

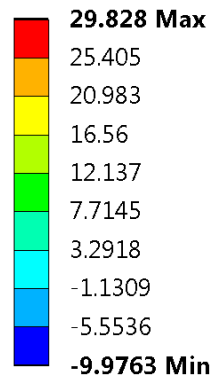
Directional Deformation 6

Type: Directional Deformation(Y Axis)

Unit: μm

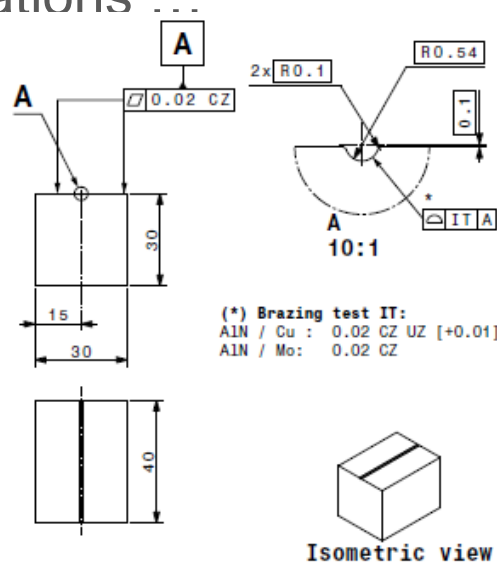
Global Coordinate System

Time: 1



Proof of Concept

- Vacuum Brazing is the most critical step in the process (a few mm gap between wire and cooler may induce a thermal runaway of hundreds degrees ...) → proof of concept proposed
- AlN + Mo (and Cu as back-up) wire specimens ordered, to be brazed to verify feasibility and optimize brazing parameters. Specimens to be delivered in 6 weeks
- If results are ok a short demonstrator (290 mm long) will be built, brazed and assembles early 2020, to validate the process and check residual deformations



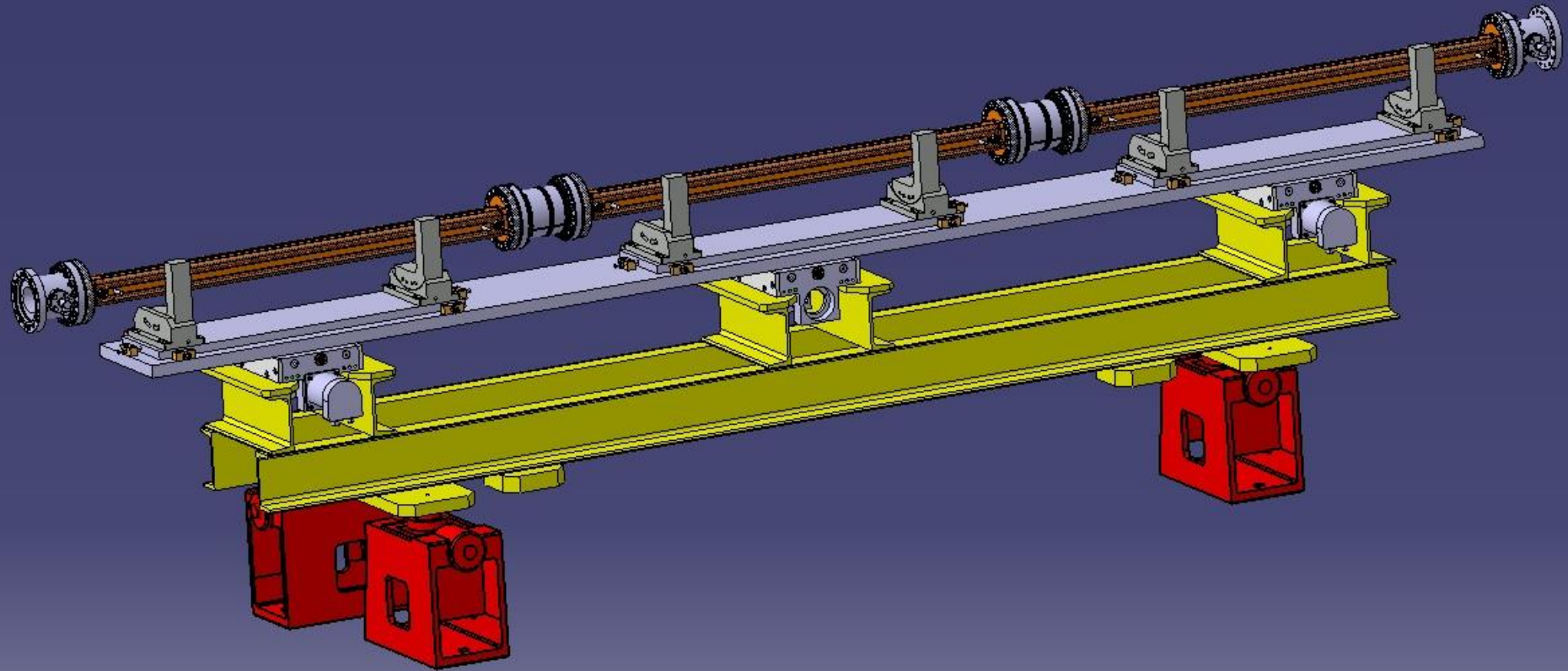
Outlook

- A simple, low-cost, modular design is being explored, allowing a certain scalability as to number of modules, current and dimensions
- No showstoppers identified (yet?) for thin Mo naked wire ($\varnothing \geq 1$ mm) brazed onto a ceramic insulator
- However, preliminary investigations ignored several key physical and technological aspects (e.g. beam and RF losses, mechanical feasibility, fabrication tolerances, UHV aspects etc.) which should be the object of a proper design study
- The manufacturing of a demonstrator is a fundamental step to validate the concept. A simplified demo is foreseen by early 2020
- A full-fledged design (number of modules, length, interfaces, motorization, integration ...) should be launched after demonstrator proves this concept is viable



Thanks for your attention

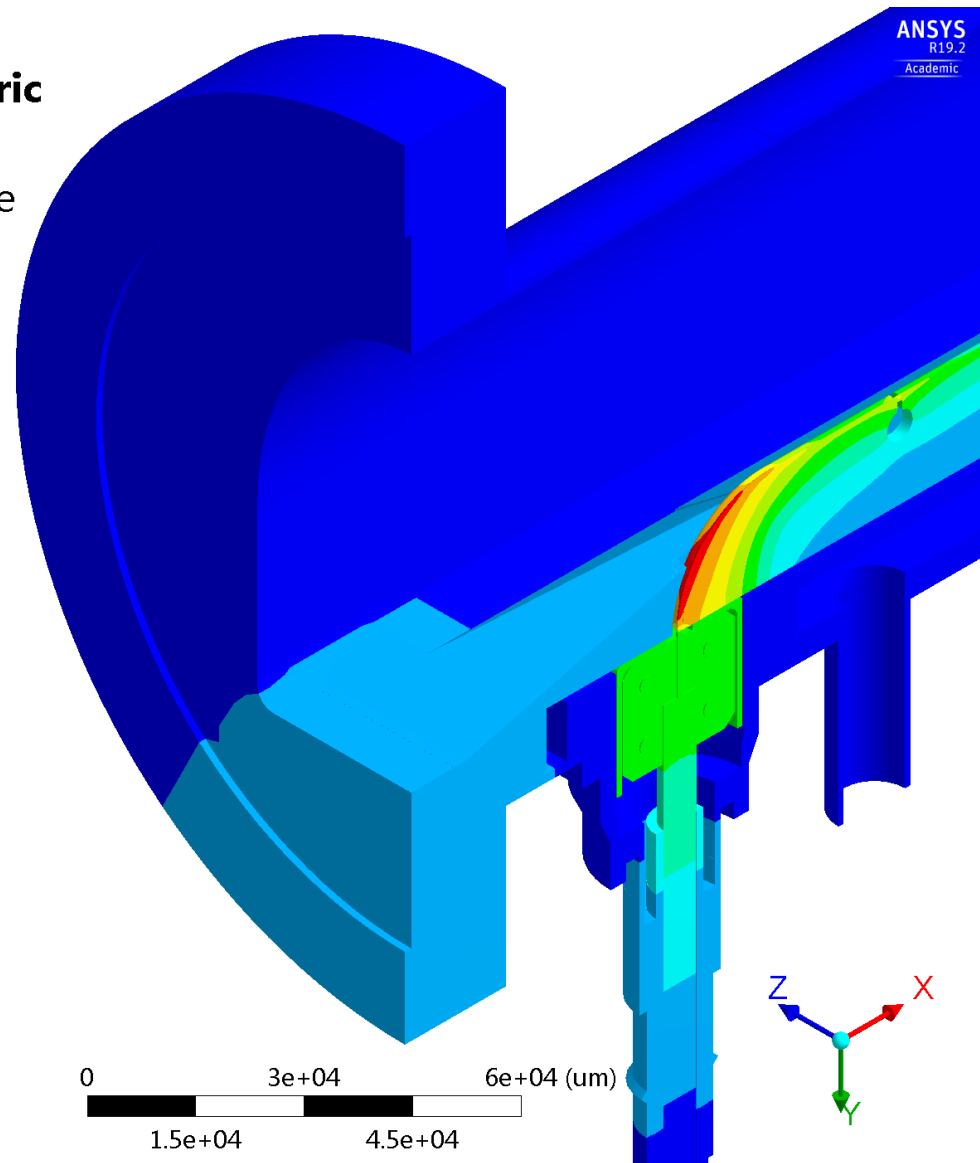
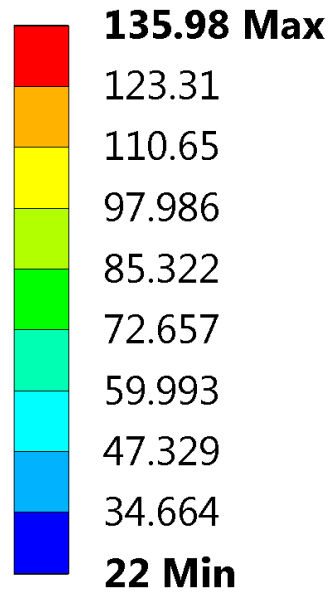
Possible Layout



Numerical Simulations

A: Thermal-Electric

Temperature
Type: Temperature
Unit: °C
Time: 1



Numerical Simulations

ANSYS
v19.2
Academic

B: Static Structural

Equivalent (von-Mises) Stress - wire_Mo - 1. s

Type: Equivalent (von-Mises) Stress

Unit: MPa

Time: 1

