# Transverse Dynamics (part II) 

JAI lectures - Michaelmas Term 2019

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## General matrix formalism (linear systems)

The transformation between $x\left(s_{0}\right)$ and $x(s)$ can be expressed in a general way:

$$
\begin{equation*}
\mathbf{x}(s)=M\left(s \mid s_{0}\right) \mathbf{x}\left(s_{0}\right) \tag{1}
\end{equation*}
$$

where the application $M\left(s \mid s_{0}\right)$ can be expressed in matrix formalism:

$$
\binom{x}{x^{\prime}}=\left(\begin{array}{cc}
C\left(s \mid s_{0}\right) & S\left(s \mid s_{0}\right)  \tag{2}\\
C^{\prime}\left(s \mid s_{0}\right) & S^{\prime}\left(s \mid s_{0}\right)
\end{array}\right)\binom{x_{0}}{x_{0}^{\prime}}
$$

where $C$ and $S$ are the cosine-like and sine-like functions and its derivatives $C^{\prime}$ and $S^{\prime}$ with respecto to $s$.

## Element concatenation

The transfer matrices for different elements of the lattice can be concatenated to find the full transfer matrix between two points $s_{0}$ and $s_{n}$.

$$
\begin{equation*}
x\left(s_{n}\right)=M_{n}\left(s_{n} \mid s_{n-1}\right) \ldots M_{3}\left(s_{3} \mid s_{2}\right) M_{2}\left(s_{2} \mid s_{1}\right) M_{1}\left(s_{1} \mid s_{0}\right) x\left(s_{0}\right) \tag{3}
\end{equation*}
$$

Remember to multiply matrices in reverse order.
Lattice design lecture
We will see more of how lattices are design in practice using MADX.

## Thin lens approximation

When the focal length $f$ of the quadrupole is much bigger than the length of the magnet itself $L_{q}$ the transfer matrices can be rewriten:

$$
\begin{gather*}
M_{\mathrm{foc}}=\left(\begin{array}{cc}
1 & 0 \\
-\frac{1}{f} & 1
\end{array}\right)  \tag{4}\\
M_{\mathrm{def}}=\left(\begin{array}{cc}
1 & 0 \\
\frac{1}{f} & 1
\end{array}\right) \tag{5}
\end{gather*}
$$

Take-home exercise
Derive the limits for the thin lens approximation and find the new matrices for quadrupoles in thin lens approximation.

## Twiss parameters

$$
\begin{equation*}
u=\sqrt{2 J_{u} \beta_{u}(s)} \sin \left(\phi_{u}(s)-\phi_{u 0}\right) \tag{6}
\end{equation*}
$$

$\beta_{u}(s)$ is a periodic function given by the focusing properties of the lattice.


$$
\begin{gather*}
\phi\left(s_{0} \mid s\right)=\int_{s_{0}}^{s} \frac{d s^{\prime}}{\beta\left(s^{\prime}\right)}  \tag{7}\\
\alpha_{u}(s)=-\frac{1}{2} \beta_{u}^{\prime}(s)  \tag{8}\\
\gamma_{u}(s)=\frac{1+\alpha_{u}^{2}(s)}{\beta_{u}(s)} \tag{9}
\end{gather*}
$$

## Twiss parameters

$$
\begin{equation*}
u=\sqrt{2 J_{u} \beta_{u}(s)} \sin \left(\phi_{u}(s)-\phi_{u 0}\right) \tag{10}
\end{equation*}
$$

$\beta_{u}(s)$ is a periodic function given by the focusing properties of the lattice:


$$
\begin{gather*}
\phi\left(s_{0} \mid s\right)=\int_{s_{0}}^{s} \frac{d s^{\prime}}{\beta\left(s^{\prime}\right)}  \tag{11}\\
\alpha_{u}(s)=-\frac{1}{2} \beta_{u}^{\prime}(s)  \tag{12}\\
\gamma_{u}(s)=\frac{1+\alpha_{u}^{2}(s)}{\beta_{u}(s)} \tag{13}
\end{gather*}
$$

## Transfer matrix in terms of Twiss parameters

Express $M$ in terms of initial and final Twiss parameters (instead of magnetic properties).

Taking $s(0)=s_{0}$ and $\phi(0)=0$ we can take Eq. (??) to obtain,

$$
M=\left(\begin{array}{cc}
\sqrt{\frac{\beta_{s}}{\beta_{0}}}\left(\cos \phi_{s}+\alpha_{0} \sin \phi_{0}\right) & \sqrt{\beta_{s} \beta_{0}} \sin \phi_{s}  \tag{14}\\
\frac{\left(\alpha_{0}-\alpha_{s}\right) \cos \phi_{s}-\left(1+\alpha_{0} \alpha_{s}\right) \sin \phi_{s}}{\sqrt{\beta_{s} \beta_{0}}} & \sqrt{\frac{\beta_{0}}{\beta_{s}}}\left(\cos \phi_{s}-\alpha_{s} \sin \phi_{s}\right)
\end{array}\right)
$$

This expression is very useful when Twiss parameters are known at two different locations.

## How do we mesure $\beta$ and $\phi$ ?

## Phase $\phi$

- Harmonic analysis of orbit oscillations.


## Betatron tune $Q$

- FFT of transverse beam position over many turns.

$\beta$-function
- $\beta$ from phase.
- $\beta$ from amplitude.
- K-modulation.



## One matrix to rule them all: the one-turn matrix

If we take previous matrix (Eq. [14]) and consider the case of one full turn (i.e. $\beta_{s}=\beta_{0}, \alpha_{s}=\alpha_{0}$ ) the matrix simplifies

$$
\mathcal{M}=\left(\begin{array}{cc}
\cos \phi_{L}+\alpha_{s} \sin \phi_{L} & \beta_{s} \sin \phi_{L}  \tag{15}\\
\gamma_{s} \sin \phi_{L} & \cos \phi_{L}-\alpha_{s} \sin \phi_{L}
\end{array}\right)
$$

remember that the tune is the phase advance in units of $2 \pi$ :

$$
\begin{equation*}
Q=\frac{1}{2 \pi} \oint \frac{d s}{\beta(s)}=\frac{\phi}{2 \pi} \tag{16}
\end{equation*}
$$

then, the one turn matrix in terms of tune is,

$$
\mathcal{M}=\left(\begin{array}{cc}
\cos (2 \pi Q)+\alpha_{s} \sin (2 \pi Q) & \beta_{s} \sin (2 \pi Q)  \tag{17}\\
\gamma_{s} \sin (2 \pi Q) & \cos (2 \pi Q)-\alpha_{s} \sin (2 \pi Q)
\end{array}\right)
$$

## Properties of transfer matrices

1. Phase space area preservation:

$$
\begin{equation*}
\operatorname{det}(M)=1 \tag{18}
\end{equation*}
$$

2. Motion is stable over $N \rightarrow \infty$ turns if:

$$
\begin{equation*}
\operatorname{trace}(M) \leq 2 \tag{19}
\end{equation*}
$$

## Stability condition (derivation)

Let's consider a general transfer matrix $M$ for a periodic system:

$$
M=\left(\begin{array}{ll}
a & b \\
c & d
\end{array}\right)
$$

we want the motion to be stable after $N \rightarrow \infty$ turns:

$$
x_{N}=M^{N} x_{0}
$$

How can we compute $M^{N}$ ?

## Stability condition (derivation)

$$
x_{N}=M^{N} x_{0}
$$

- $\operatorname{det}(M)=a d-b c=1$
- trace $(M)=a+d$

If we diagonalise $M$, we can rewrite it as:

$$
M=U \cdot\left(\begin{array}{cc}
\lambda_{1} & 0 \\
& \lambda_{2}
\end{array}\right) \cdot U^{T}
$$

where $U$ is some unitary matrix and $\lambda_{1}$ and $\lambda_{2}$ are the eigenvalues.

## Stability condition (derivation)

After $N$ turns:

$$
M^{N}=U \cdot\left(\begin{array}{cc}
\lambda_{1}^{N} & 0 \\
0 & \lambda_{2}^{N}
\end{array}\right) \cdot U^{T}
$$

Given that $\operatorname{det}(M)=1$ :
Solve it:

$$
\lambda_{1} \lambda_{2}=1 \rightarrow \lambda_{1,2}=\exp ^{ \pm i x}
$$

To have stable motion $x \in \mathbb{R}$. To find the eigenvalues we use the characteristic equation:

$$
\begin{gathered}
\lambda^{2}-(a+d) \lambda+(a d-b c)=0 \\
\lambda^{2}-\operatorname{trace}(M) \lambda+1=0 \\
\operatorname{trace}(M)=\lambda+1 / \lambda=\exp ^{i x}+\exp ^{-i x}= \\
=2 \cos (x)
\end{gathered}
$$

$$
\operatorname{det}(M-\lambda \mathbb{I})=\operatorname{det}\left(\begin{array}{cc}
a-\lambda & b \\
c & d-\lambda
\end{array}\right)=0
$$

Since $x \in \mathbb{R}$ :

$$
|\operatorname{trace}(M)| \leq 2
$$

## Twiss transport matrix and Twiss parameters evolution

Instead of transporting coordinates $x$ and $x^{\prime}$ we can transport Twiss parameters ( $\beta, \alpha, \gamma$ ).

$$
\left(\begin{array}{l}
\beta  \tag{20}\\
\alpha \\
\gamma
\end{array}\right)_{s}=\left(\begin{array}{ccc}
C^{2} & -2 C S & S^{2} \\
-C C^{\prime} & C S^{\prime}+S^{\prime} C & -S S^{\prime} \\
C^{\prime 2} & -2 C^{\prime} S^{\prime} & S^{\prime 2}
\end{array}\right)\left(\begin{array}{l}
\beta \\
\alpha \\
\gamma
\end{array}\right)_{s_{0}}
$$

- Given the twiss parameters at any point in the lattice we can transform them and compute their values at any other point in the ring.
- the transfer matrix is given by the focusing properties of the lattice elements, the same matrix elements to compute single particle trajectories.


## Phase Space properties

Phase space ellipse.


$$
\begin{equation*}
J=\gamma_{x}(s) x(s)^{2}+2 \alpha_{x}(s) x(s) x^{\prime}(s)+\beta(s) x^{\prime}(s)^{2} \tag{21}
\end{equation*}
$$

## Phase Space properties



## Normalized phase space

Can we use another reference frame so it is simpler to describe the system?

$$
\mathcal{M}=\left(\begin{array}{cc}
\cos \phi & \sin \phi  \tag{22}\\
-\cos \phi & \sin \phi
\end{array}\right)
$$



For linear systems is fine but it gets much more complex when non-linearities are included (we will see more details in the tutorial).

## Beam emittance: single particle definition.

The geometric emittance is a constant of motion only if the beam energy is preserved (conservative system). This quantity is related to the action $J$ that appeared in the solution of the Hill's equation.

Normalized emittance takes into account beam energy. It is a constant of motion even if energy is not constant:

$$
\begin{equation*}
\epsilon_{n} \equiv \beta_{\mathrm{rel}} \gamma_{\mathrm{rel}} \epsilon \tag{23}
\end{equation*}
$$

The beam size at any location of the lattice is given by,

$$
\begin{equation*}
\sigma=\sqrt{\epsilon \beta} \tag{24}
\end{equation*}
$$



## Beam emittance: statistical definition

The beam is composed of particles distributed in phase space.


Emittance is defined by

$$
\begin{equation*}
\epsilon_{\mathrm{rms}}=\sqrt{\sigma_{u}^{2} \sigma_{u^{\prime}}^{2}-\sigma_{u u^{\prime}}^{2}} \tag{25}
\end{equation*}
$$

The rms emittance of a ring in phase space, i.e. particles uniformly distributed in phase $\phi$ coordinate at a fixed action J , is

$$
\epsilon_{\mathrm{rms}}=J
$$

If the accelerator is composed of linear elements and no dissipative forces act $\epsilon_{\text {rms }}$ is invariant.

## Beam emittance: phenomenology

What determines beam emittance?

- Amount of particles.
- Injectors manipulations.
- Beam transfer efficiency.

Sources of emittance growth

- Intrabeam scattering.
- Optics mismatch.
- Beam-gas scattering.
- Beam-beam interaction.
- Betatron resonances.
- Ground motion and PS ripples.

(a) machine phase space

(b) unmatched beam injected

(c) filamenting beam

(d) fully filamented beam


## Liouville's theorem and symplectic condition

The Liouville equation describes the time evolution of the phase space distribution function, $\rho$.

Liouville's theorem

$$
\begin{equation*}
\frac{d \rho}{d t}=\frac{\partial \rho}{\partial t}+\sum_{i=1}^{N}\left(\frac{\partial \rho}{\partial q_{i}} \dot{q}_{i}+\frac{\partial \rho}{\partial p_{i}} \dot{p}_{i}\right)=0 \tag{26}
\end{equation*}
$$

where $\left(q_{i}, p_{i}\right)$ are the canonical coordinates and the system is Hamiltonian.

## Symplectic condition

Lioville's theorem $\Rightarrow$ invariant volume in phase space.

$$
\begin{equation*}
M^{T} J M=J \tag{27}
\end{equation*}
$$

where $J$ is the 6 D symplectic matrix

$$
J=\left(\begin{array}{cccccc}
0 & 1 & 0 & 0 & 0 & 0  \tag{28}\\
-1 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 1 & 0 & 0 \\
0 & 0 & -1 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 1 \\
0 & 0 & 0 & 0 & -1 & 0
\end{array}\right)
$$

Take home exercice
Prove that Eq. (27) holds for the matrices described above.

## FODO lattice

The FODO lattice is a sequence of a Focusing magnet (F), a Drift space (O), a Defocusing magnet (D) and a second drift space (0).


$$
M_{\mathrm{FODO}}=M_{0} M_{\mathrm{def}} M_{0} M_{\mathrm{foc}}=\left(\begin{array}{cc}
1+\frac{L}{2 f} & L+\frac{L^{2}}{4 f}  \tag{29}\\
-\frac{L}{2 f^{2}} & 1-\frac{L}{2 f}-\frac{L^{2}}{4 f^{2}}
\end{array}\right)
$$

## FODO lattice

Take-home exercise:
Prove that the stability condition for a FODO lattice is given by:

$$
\begin{equation*}
f>\frac{L}{4} \tag{30}
\end{equation*}
$$

## What if...

We take the FODO lattice and replace drifts by bending magnets?
You will see this in next lectures...

## The end of the ideal world...

So far, we have considered ideal linear systems.

- Dispersion.
- Chromaticity.
- Misalignments.
- Magnetic errors.

Some of these topics will be covered in next lectures.

## Dispersion

What if particles within a bunch have different momenta?
Remember beam rigidity:

$$
\begin{equation*}
B \rho=\frac{P}{q} \tag{31}
\end{equation*}
$$

Orbit:

$$
\begin{equation*}
x(s)=D(s) \frac{\Delta P}{P_{0}} \tag{32}
\end{equation*}
$$

where $D(s)$ is the dispersion function, an intrinsic propertie of the dipole magnets.


## Dispersion

Inhomogeneus Hill's equation:

$$
\begin{equation*}
u^{\prime \prime}+\left(\frac{1}{\rho^{2}}+k\right) u=\frac{1}{\rho} \frac{\Delta P}{P_{0}} \tag{33}
\end{equation*}
$$

Particle trajectory:

$$
\begin{align*}
u(s) & =u_{\beta}(s)+u_{D}(s)=  \tag{34}\\
& =u_{\beta}(s)+D(s) \frac{\Delta P}{P} \tag{35}
\end{align*}
$$

where $D(s)$ is the solution of:

$$
\begin{equation*}
D^{\prime \prime}(s)+K(s) D(s)=\frac{1}{\rho} \tag{36}
\end{equation*}
$$



## Dispersion

## Dipole transfer matrix:

Solution:

$$
u(s)=C(s) u_{0}+S(s) u_{0}^{\prime}+D(s) \frac{\Delta P}{P_{0}}
$$

so this can be added to the transfer matrix representation:

$$
M=\left(\begin{array}{ccc}
C & S & D \\
C^{\prime} & S^{\prime} & D^{\prime} \\
0 & 0 & 1
\end{array}\right)
$$

$$
\left(\begin{array}{ccc}
\cos \left(\frac{L}{\rho}\right) & \rho \sin \left(\frac{L}{\rho}\right) & \rho\left(1-\cos \left(\frac{L}{\rho}\right)\right)  \tag{39}\\
-\frac{1}{\rho} \sin \left(\frac{L}{\rho}\right) & \cos \left(\frac{L}{\rho}\right) & \sin \left(\frac{L}{\rho}\right) \\
0 & 0 & 1
\end{array}\right)
$$

Quadrupole;

$$
\left(\begin{array}{ccc}
\cos (\sqrt{K} L) & \frac{1}{\sqrt{K}} \sin (\sqrt{K} L) & 0  \tag{40}\\
-\sqrt{K} \sin (\sqrt{K} L) & \cos (\sqrt{K} L) & 0 \\
0 & 0 & 1
\end{array}\right)
$$

## Chromaticity

All particles do not have exactly the same energy. Therefore, according to Eq. (??) they focalize at different points.


This defines
chromaticity:

$$
\begin{equation*}
\xi=-\frac{1}{4 \pi} \oint \beta(s) k(s) d s \tag{41}
\end{equation*}
$$

## How to correct chromaticity

Sextuples, through a non-linear magnetic field, corrects the effect of energy spread and focuses particles at a single location.

- Located in dispersive regions
- Usually in arcs.
- Sextupole families.



## Now is when the party starts...

- Sexupoles introduce non-linear fields...
- ... i.e. they induce non-linear motion.
- resonances, tune shifts, chaotic motion...


## Chromaticity correction

- Chromatic aberrations must be compensated in both planes.

$$
\begin{align*}
& \xi_{x}=-\frac{1}{4 \pi} \oint \beta_{x}(s)\left[k(s)-S_{F} D_{x}(s)+S_{D} D_{x}(s)\right] d s  \tag{42}\\
& \xi_{y}=-\frac{1}{4 \pi} \oint \beta_{y}(s)\left[-k(s)+S_{F} D_{x}(s)-S_{D} D_{x}(s)\right] d s \tag{43}
\end{align*}
$$

- To minimise sextupole strength they must be located near quadrupoles where $\beta D$ are large.
- For optimal independent correction $S_{F}$ should be located where $\beta_{x} / \beta_{y}$ is large and $S_{D}$ where $\beta_{y} / \beta_{x}$ is large.


## Recap.

- Optics functions and Twiss parameters.
- Phase space and emittance.
- Example: FODO lattice.
- Dispersion and chromaticity.


## What do we do with all this?

- We have covered the basic aspects of linear transverse dynamics.
- I skipped almost all derivations. You can follow references.
- Are you familiar with Jupyter environtment?
- Lattice design and tutorials in a couple of weeks will give a more complete picture.
- Now you are ready to take next lectures to become an accelerator phyisics experts.


## Thank you very much!

