

TIMING DETECTORS AT THE HL-LHC

Learning to Discover : Advanced Pattern Recognition

Institut Pascal, Orsay

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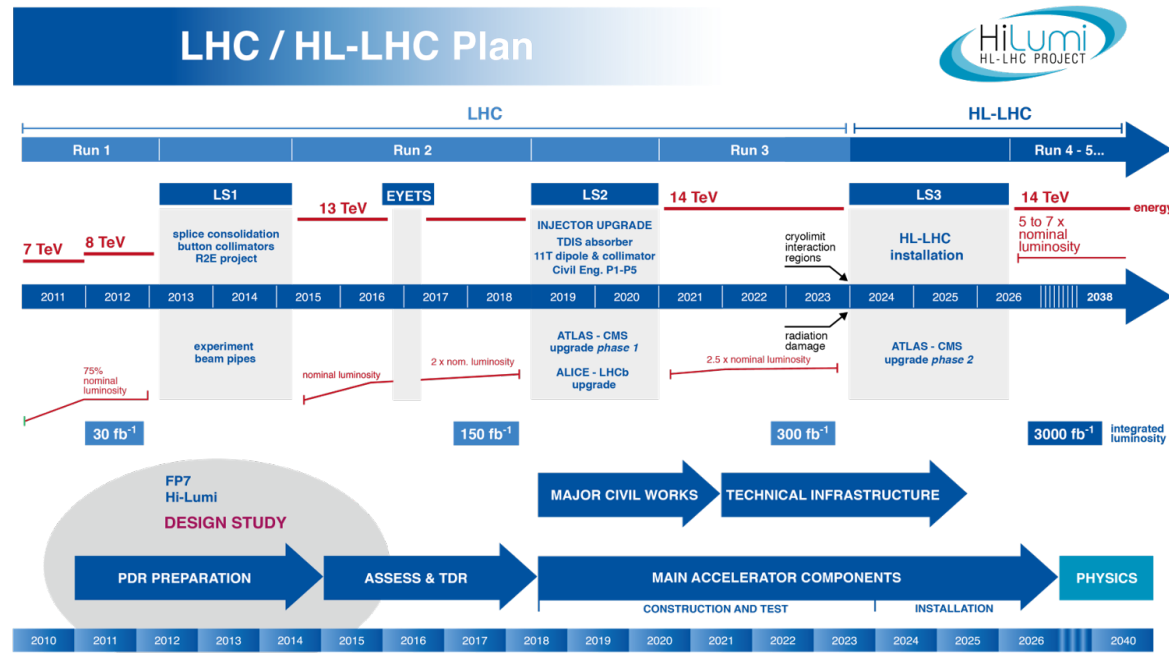
The High Luminosity LHC

- End of Run 3 (2023) : 300 fb⁻¹
- With current luminosity, 10 extra year need to halve statistical errors
- Plan to increase the instantaneous luminosity from (1-2)×10³⁴cm⁻²s⁻¹ to 7.5×10³⁴cm⁻²s⁻¹
- A total integrated luminosity of 4000 fb⁻¹ at the end of the LHC in 2037

$$\mathcal{L} = \frac{n_1 n_2 f N_b F}{4\pi\sigma_x\sigma_y}$$

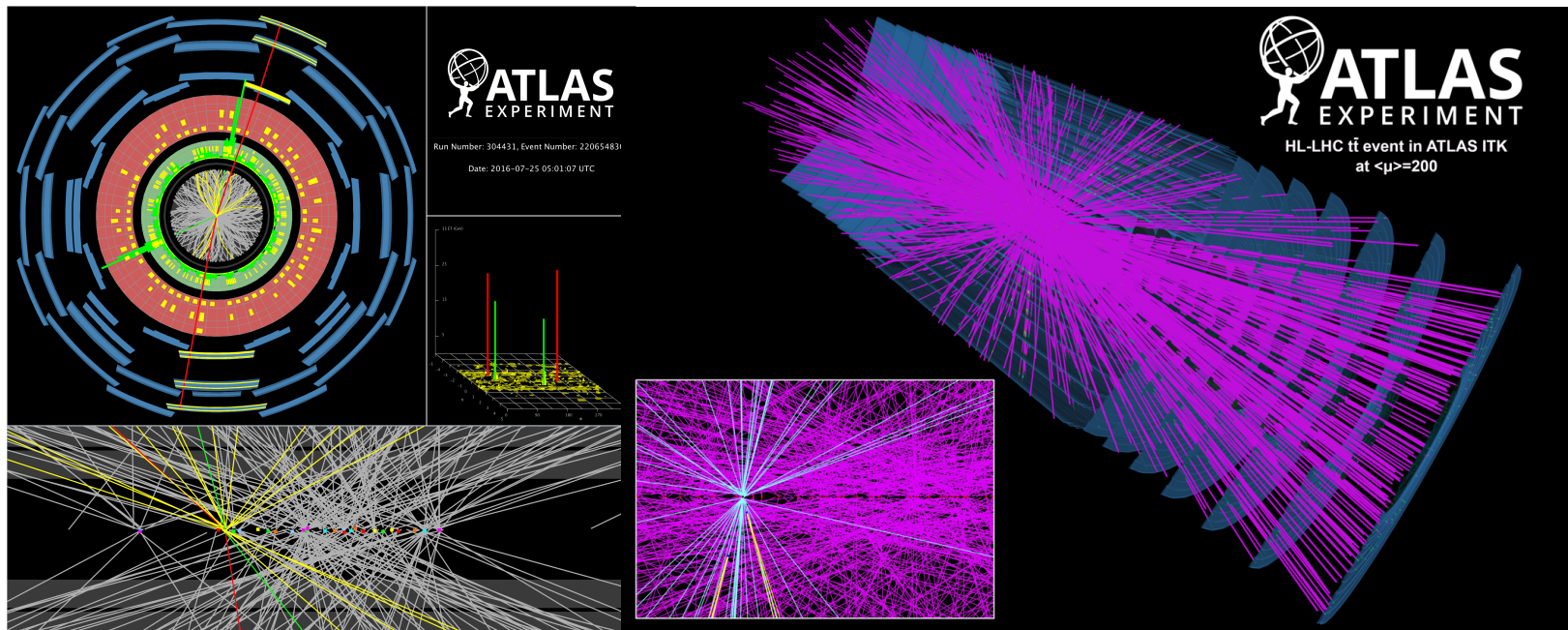
LHC Upgrades :

- Smaller bunches with more protons -> larger density of proton -> larger luminosity
- Improved insertion magnet (squeeze the bunches pre-collision)
- Crab cavities to improve geometrical factor of the collision
- Luminosity levelling



Pile-up at the HL-LHC

- Pile-up increase with the luminosity :
$$\mu = \frac{\mathcal{L} \times \sigma_{inel}}{N_{bf}}$$
- Large PU increase at the HL-LHC :
 - Harder object reconstruction
 - Large radiation dose deposited in the detector
- From $\langle\mu\rangle=25$ to $\langle\mu\rangle=200$, larger PU density

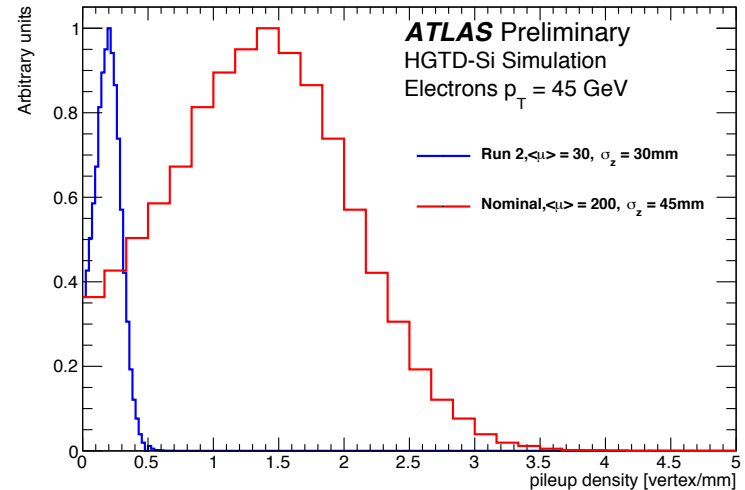


H->eeμμ, $\langle\mu\rangle=25$

Simulation $t\bar{t}$, $\langle\mu\rangle=200$

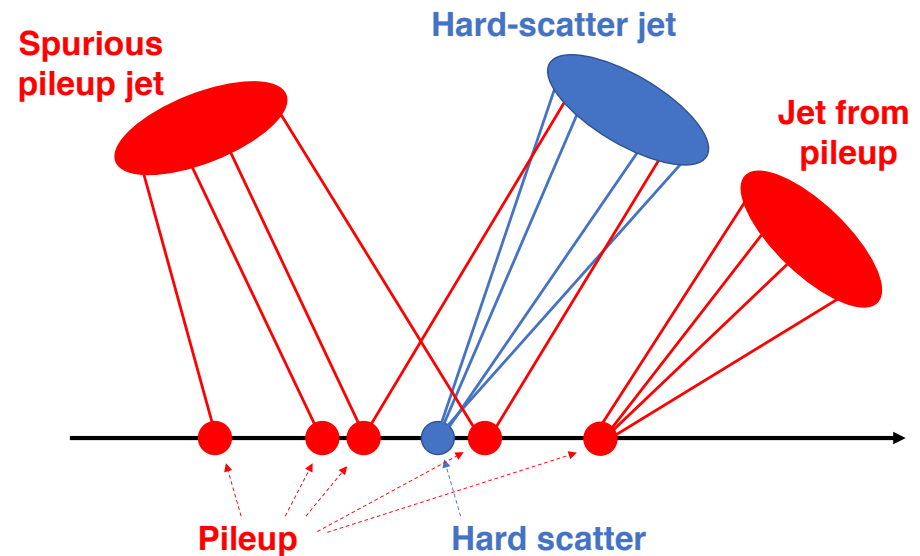
Pile-up at the HL-LHC

- The pile-up (PU) increase with luminosity
- Same size beamspot -> larger PU density
- Close by vertices might not be differentiated by the tracker -> merged vertices
- Result in additional PU jets and contamination of hard scatter (HS) objects

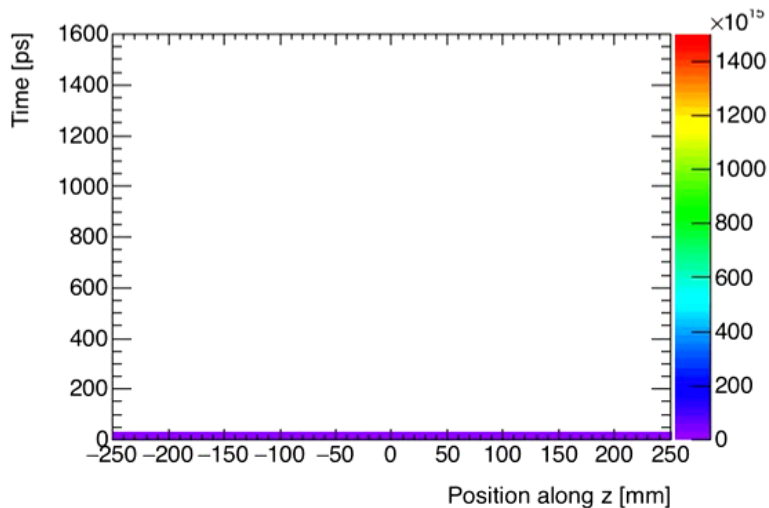
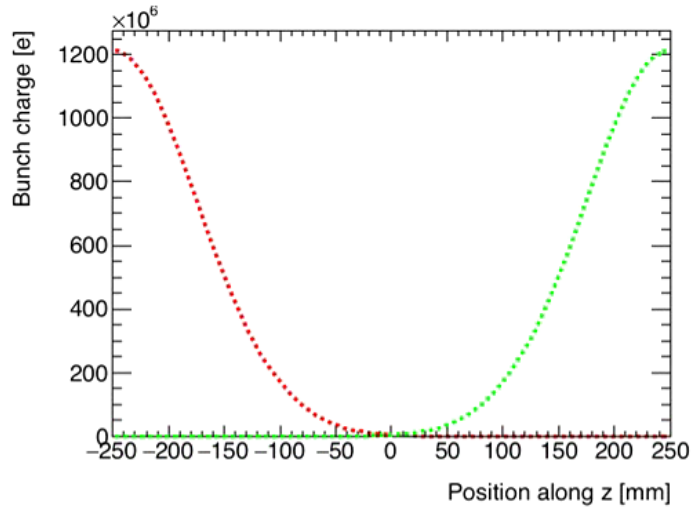


Example with jets:

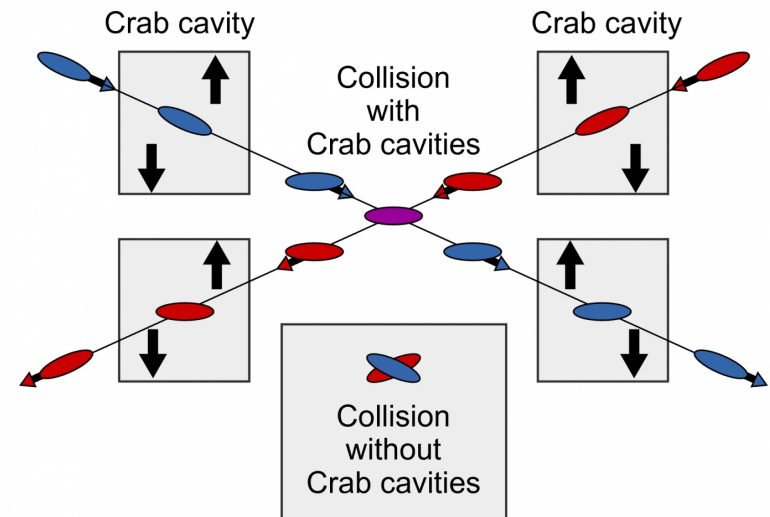
- Pile-up can contaminate HS jets
- Pile-up jet can appear to come from the HS vertex
- Pile-up particle can be combine and create jets



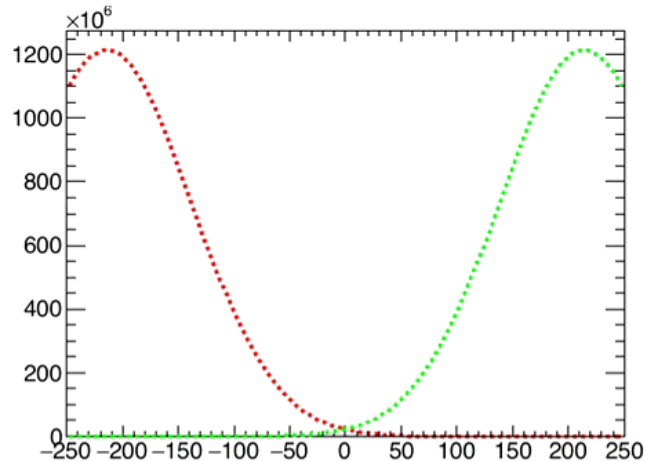
ATLAS Beamspot



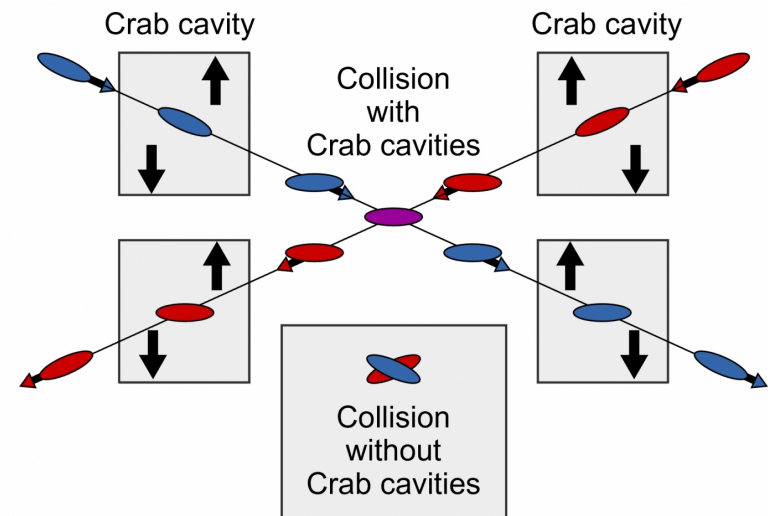
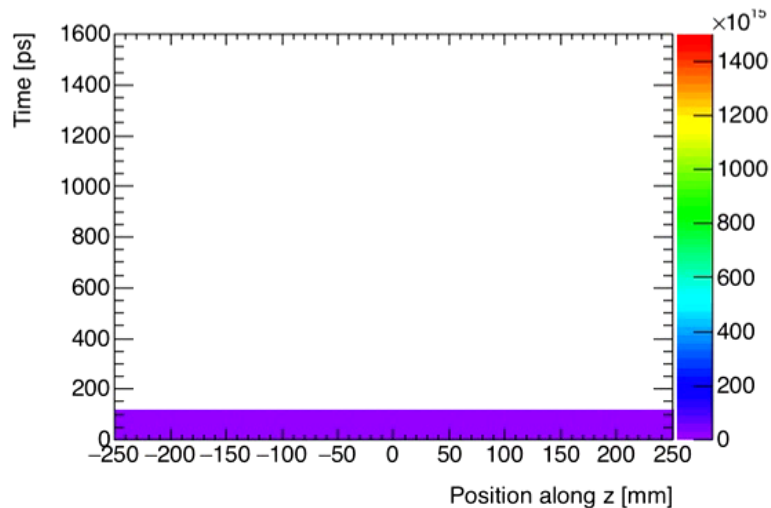
- Proton bunches \rightarrow gaussian density
- Crab cavities maximize the overlap of the bunch
- Bunch length of 90 mm
- Crossing non-instantaneous : interaction spread in time



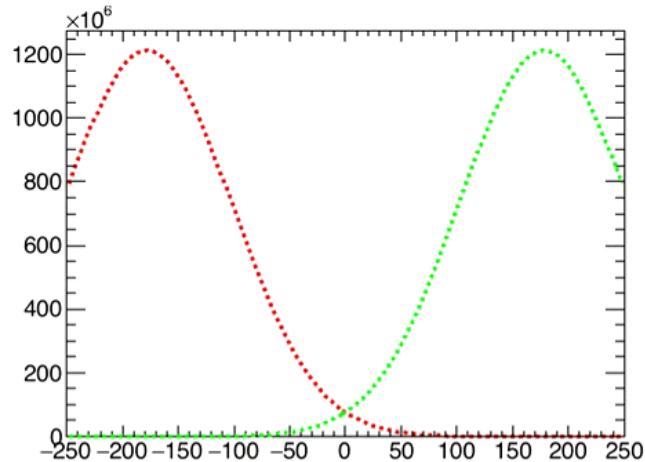
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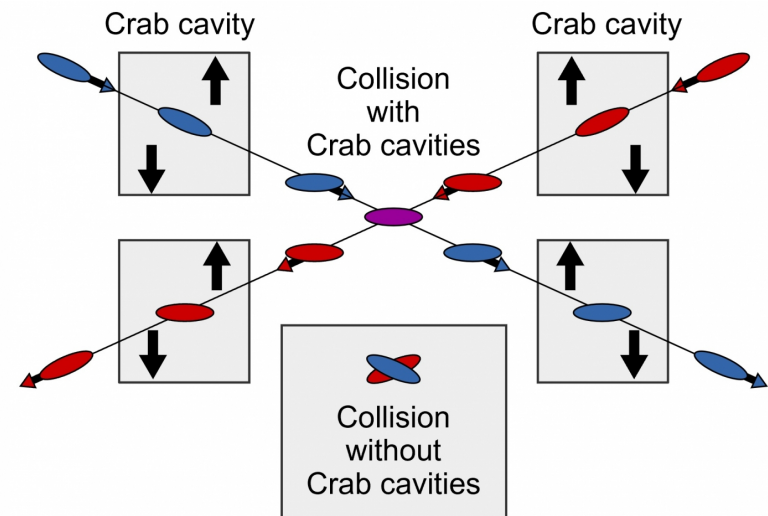
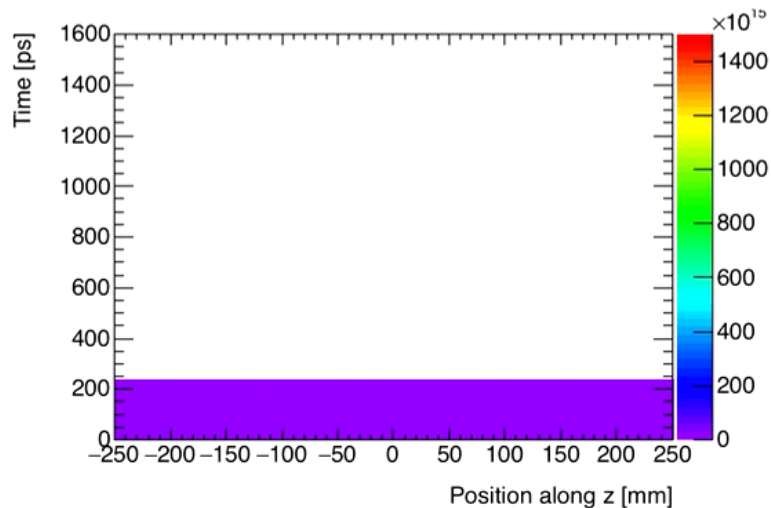
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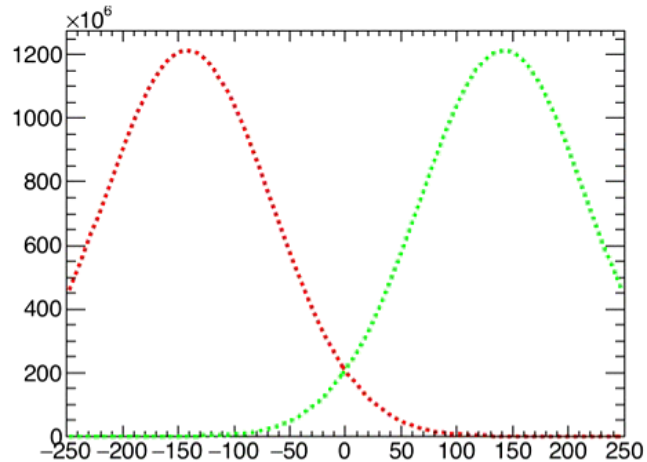
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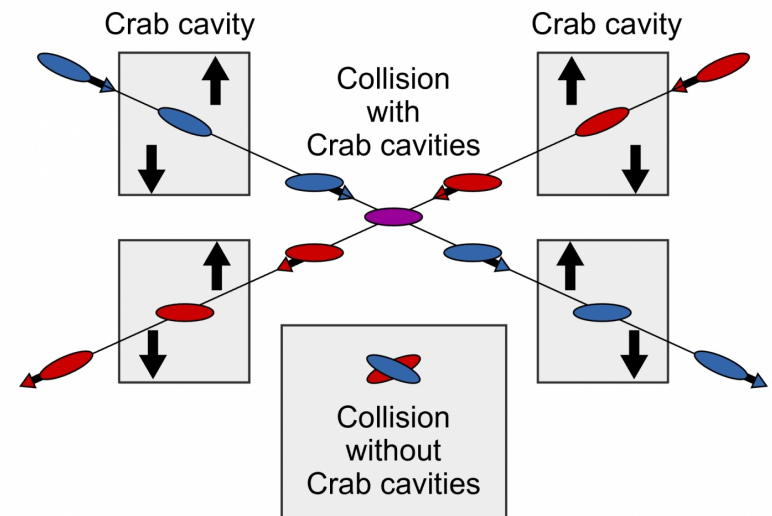
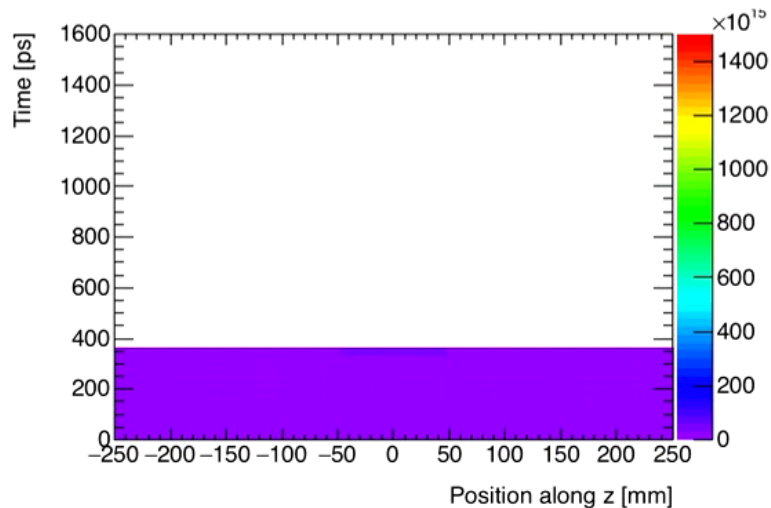
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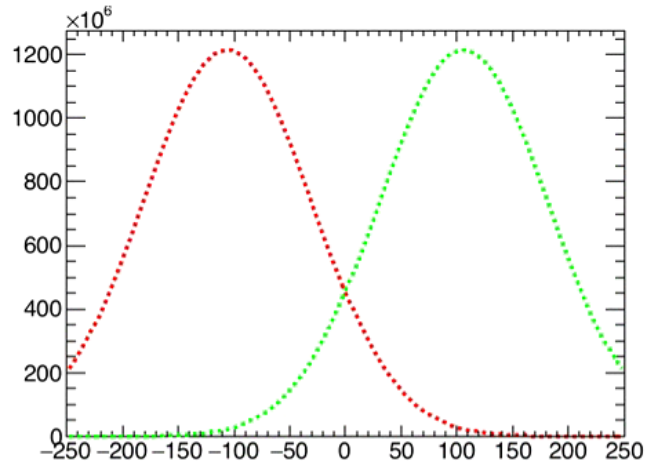
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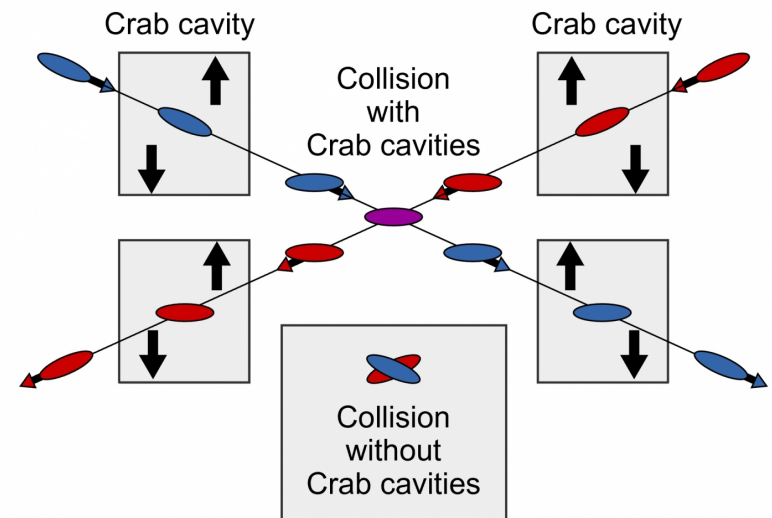
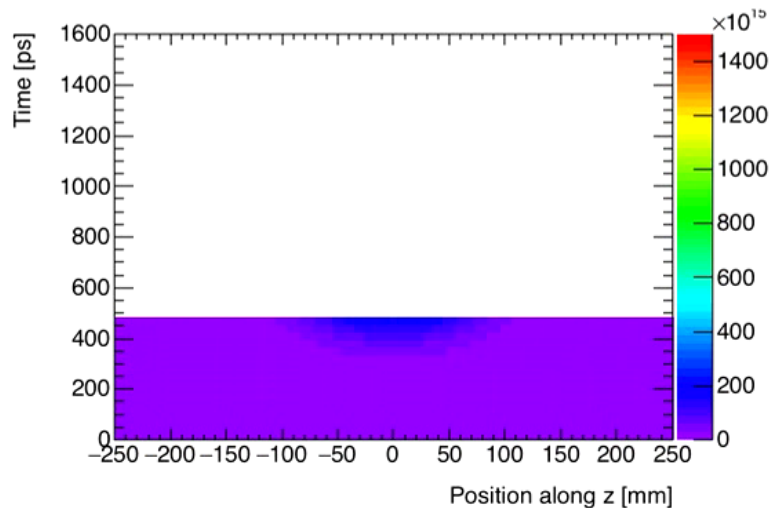
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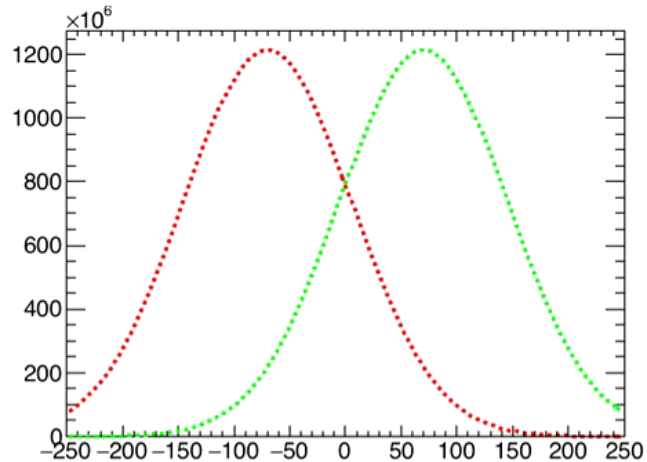
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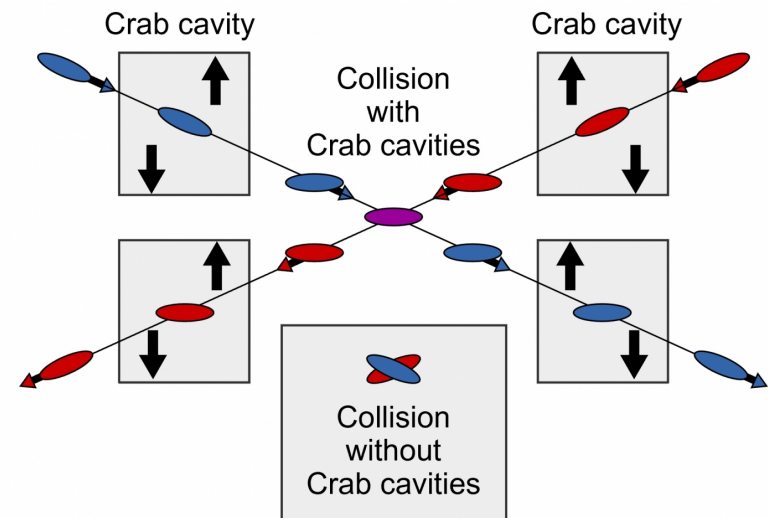
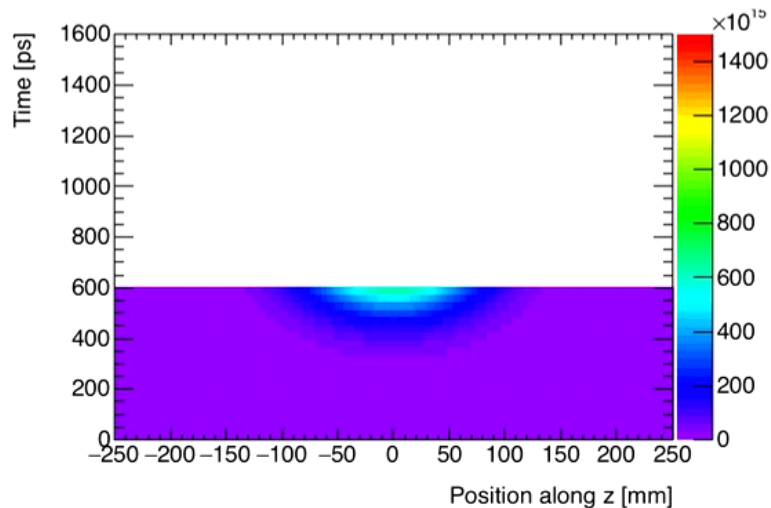
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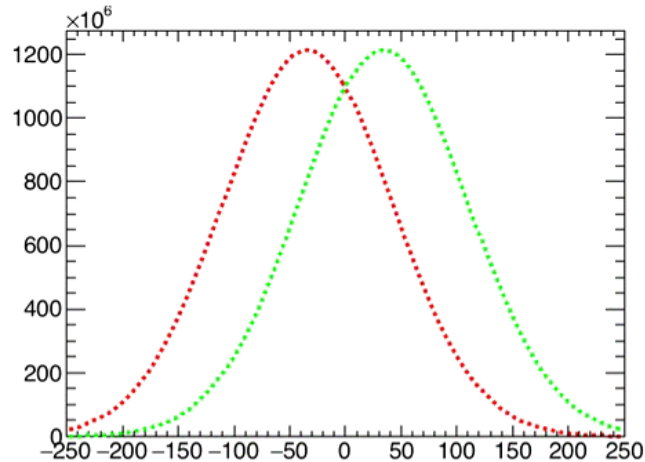
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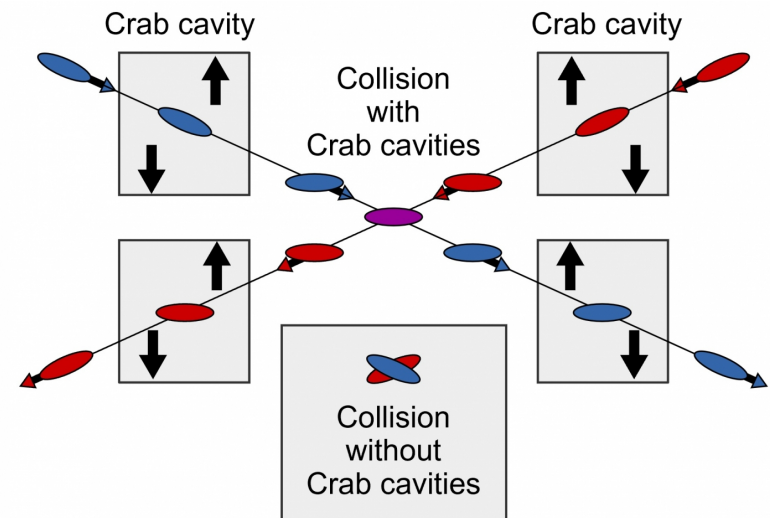
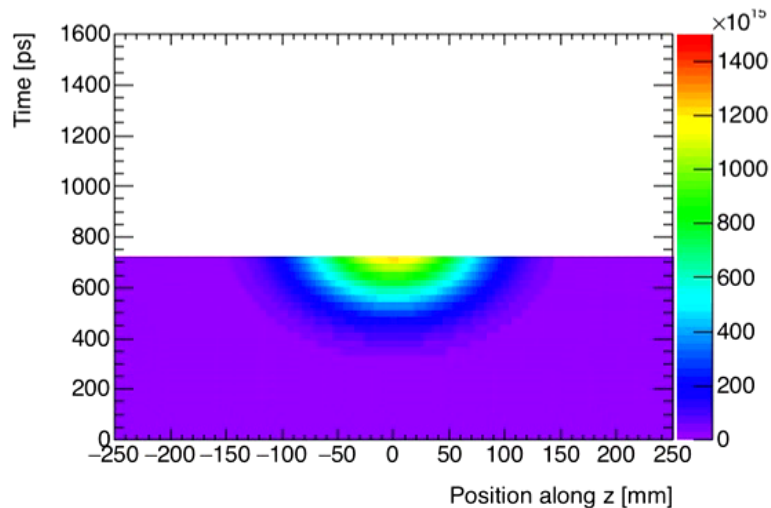
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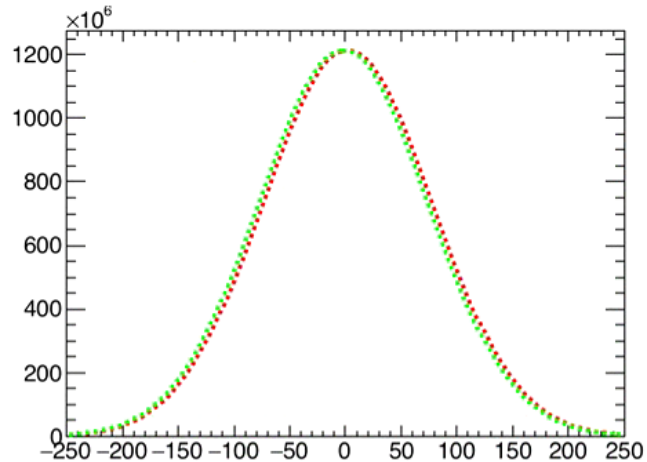
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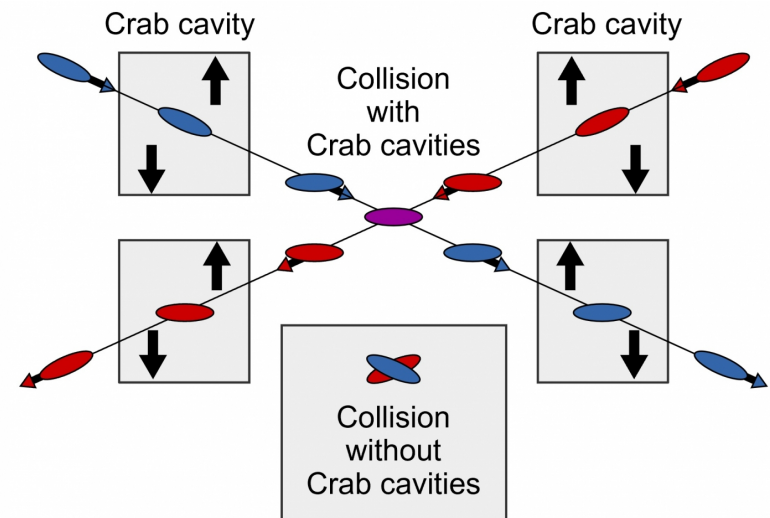
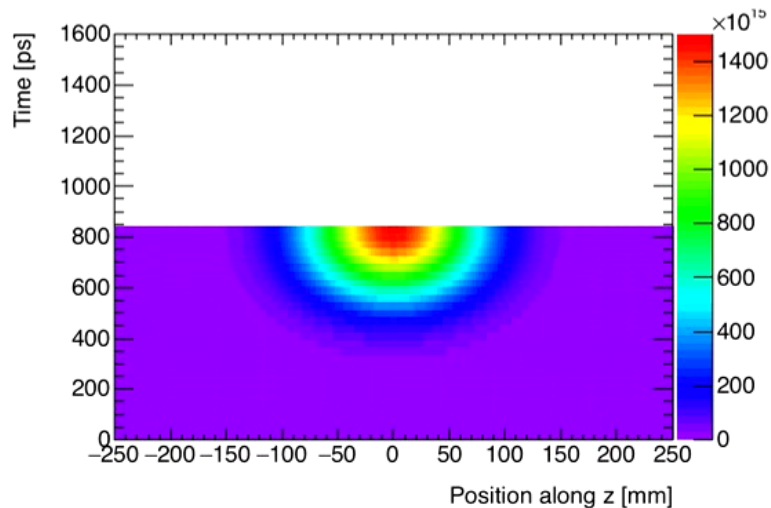
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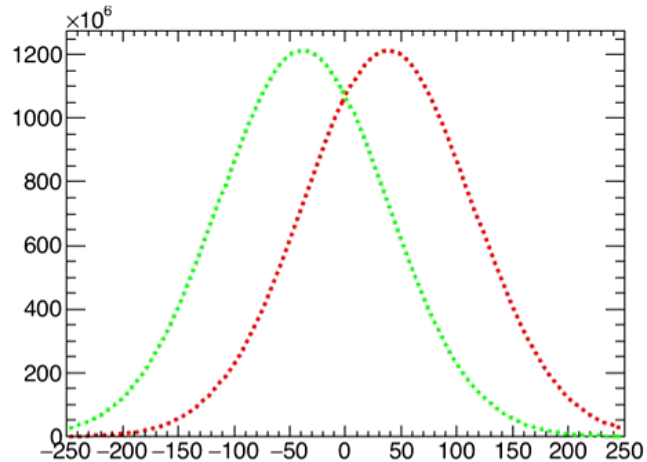
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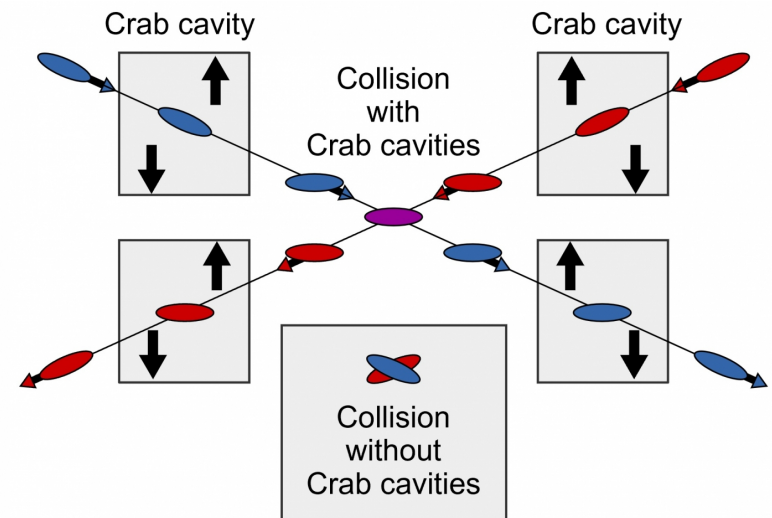
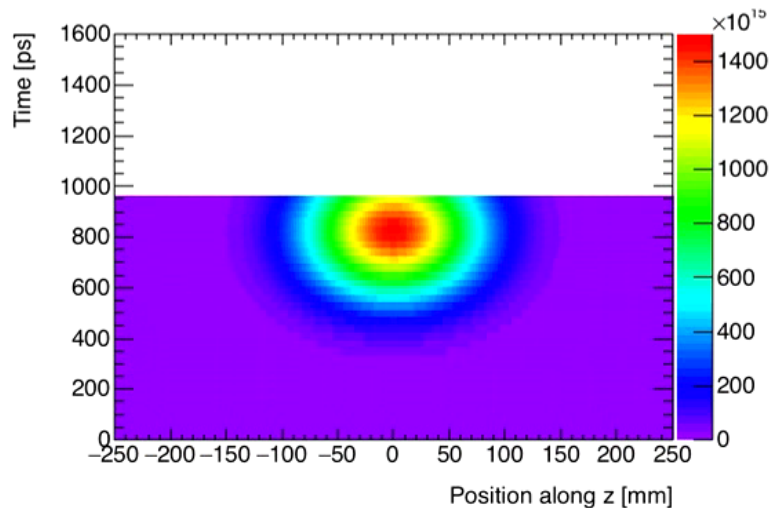
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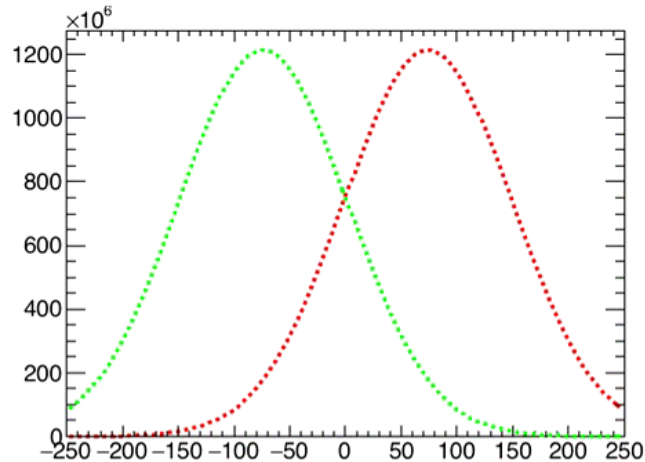
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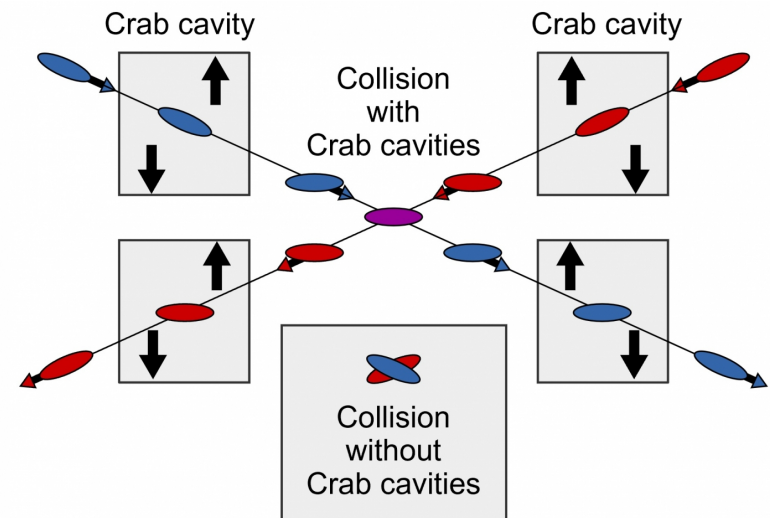
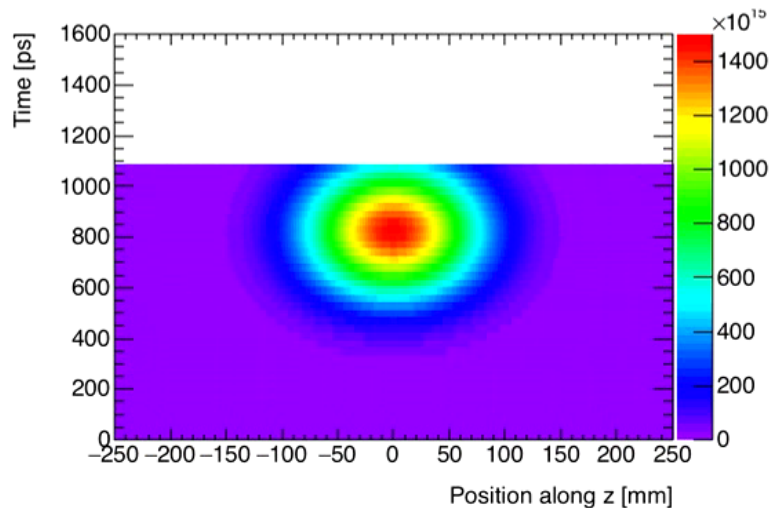
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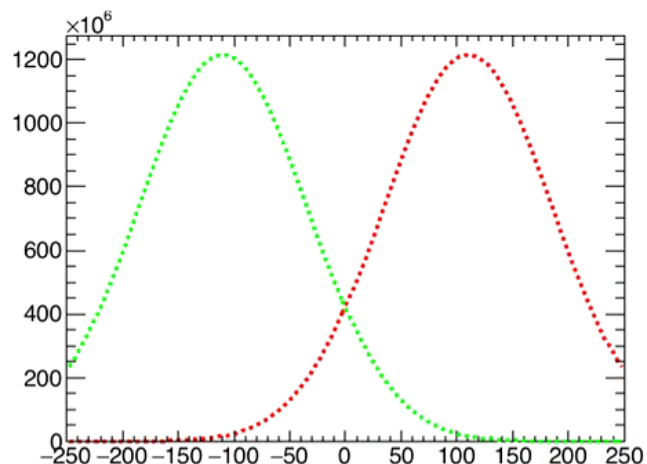
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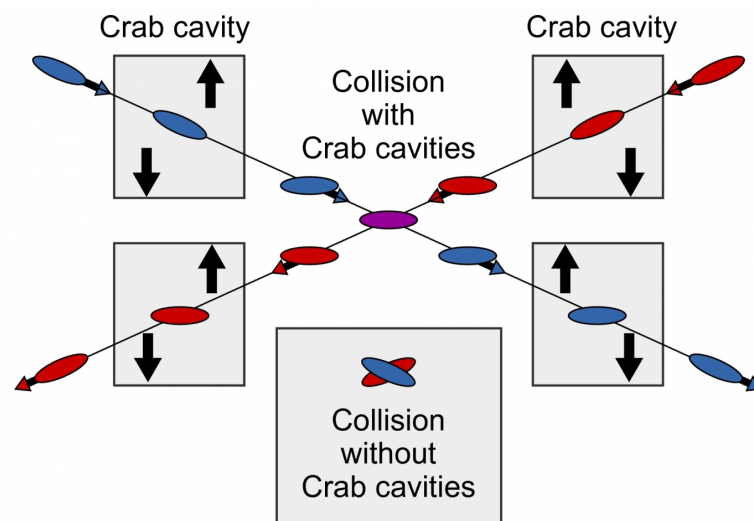
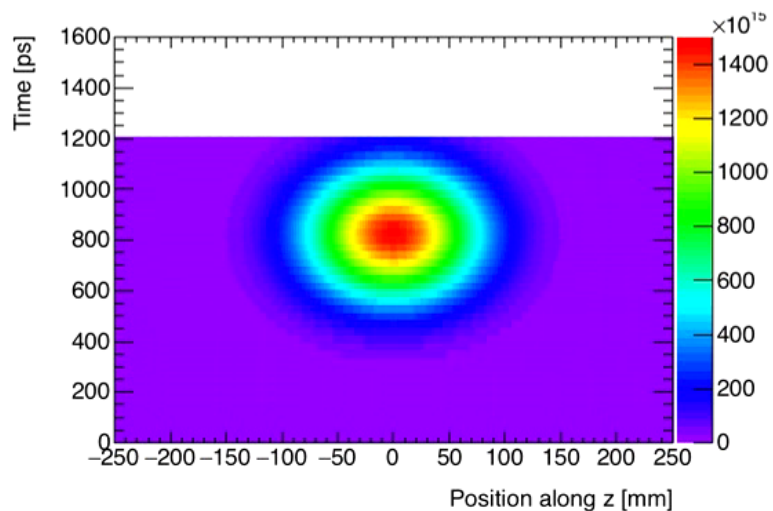
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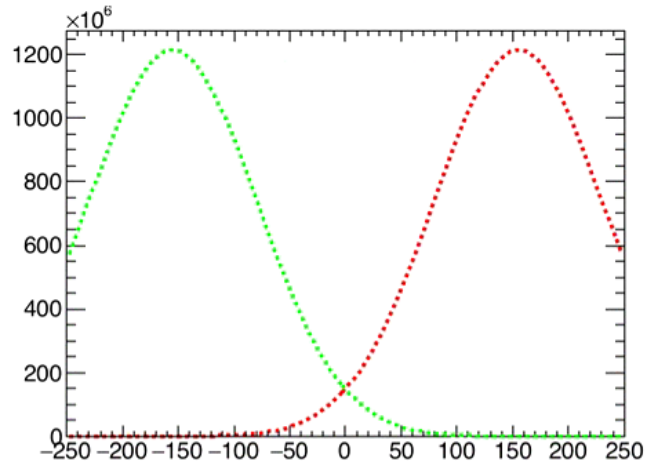
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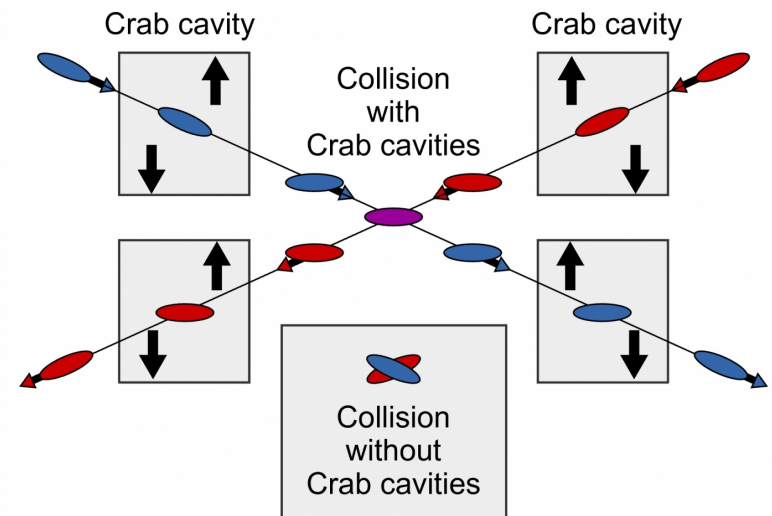
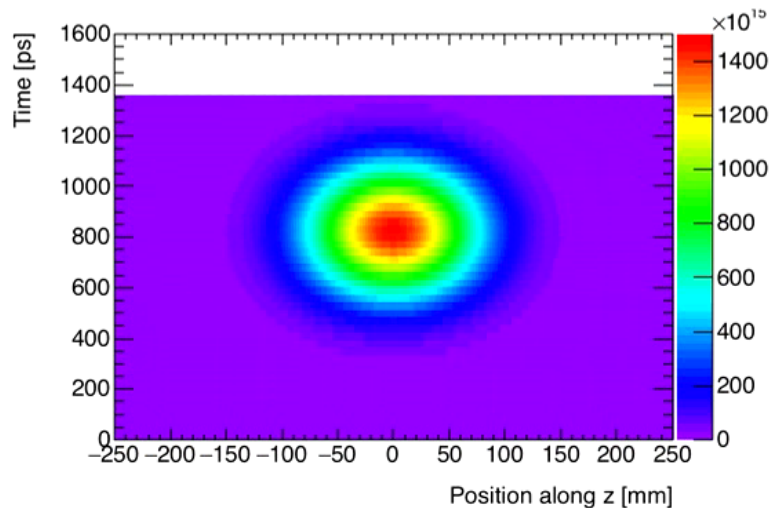
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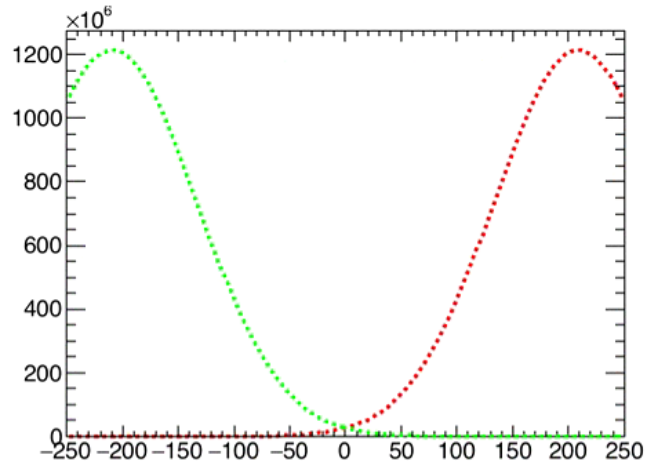
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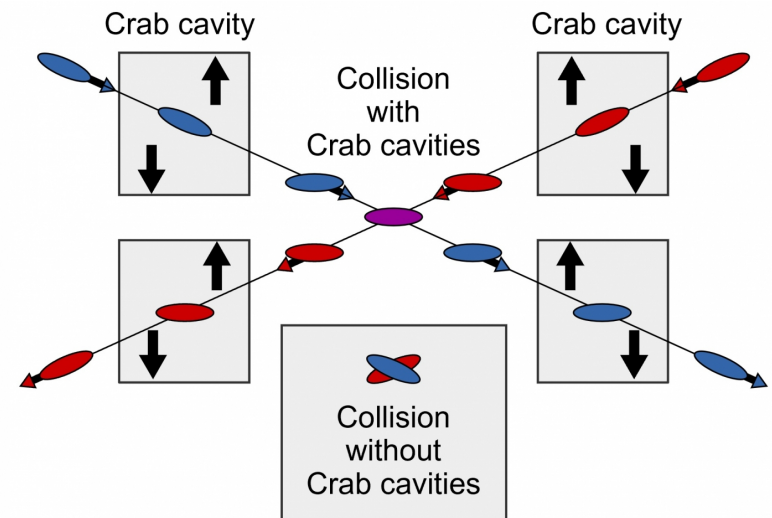
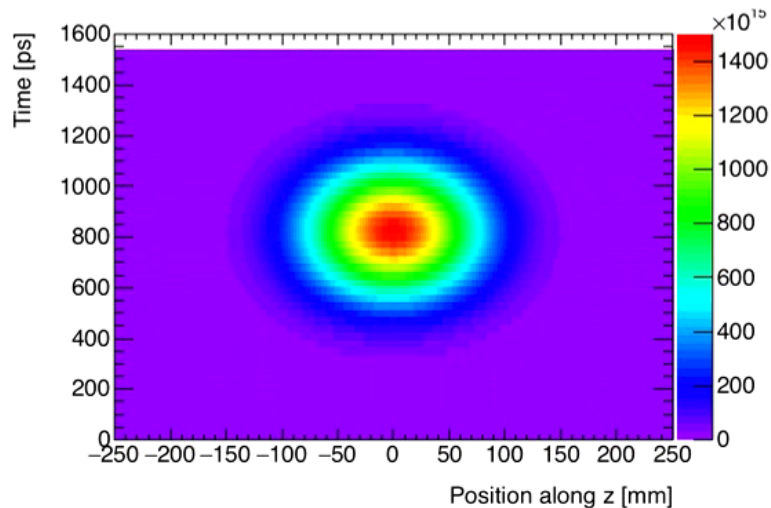
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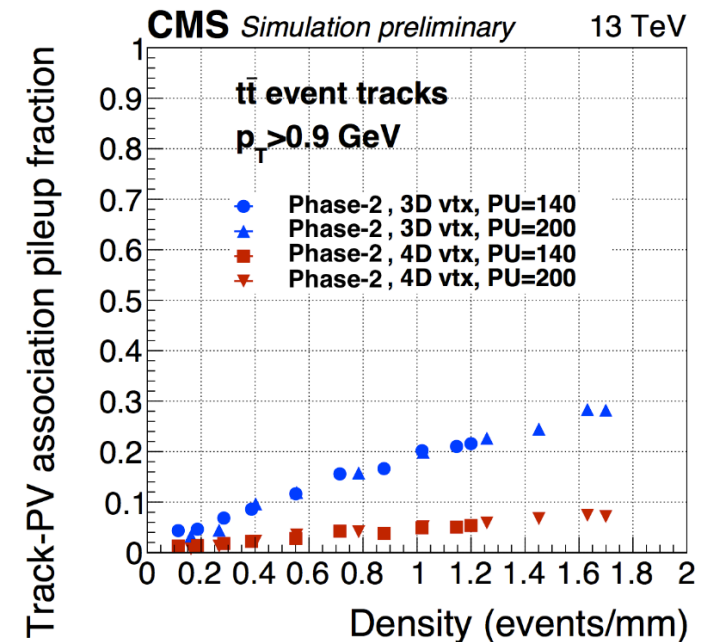
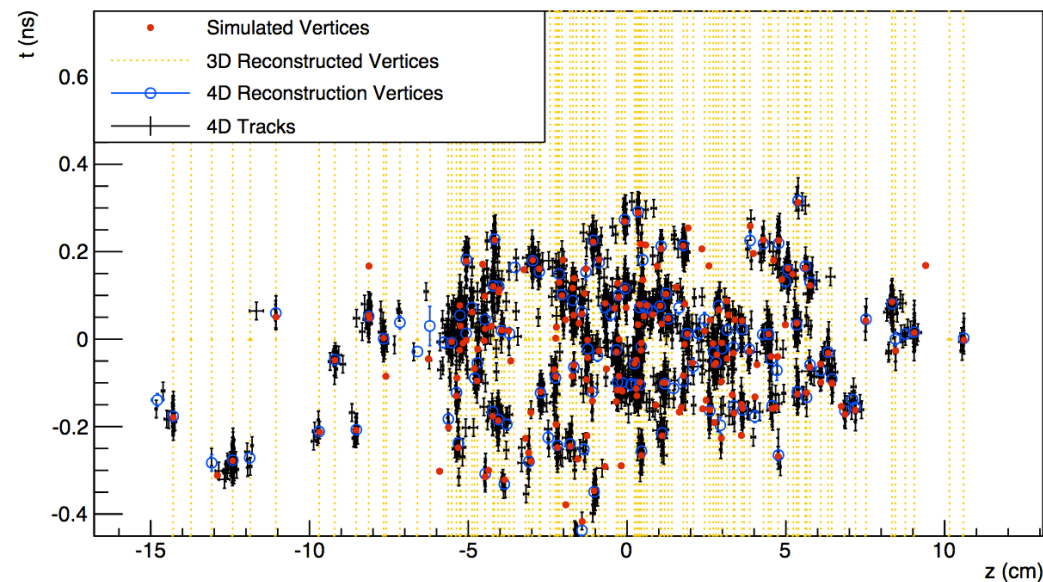


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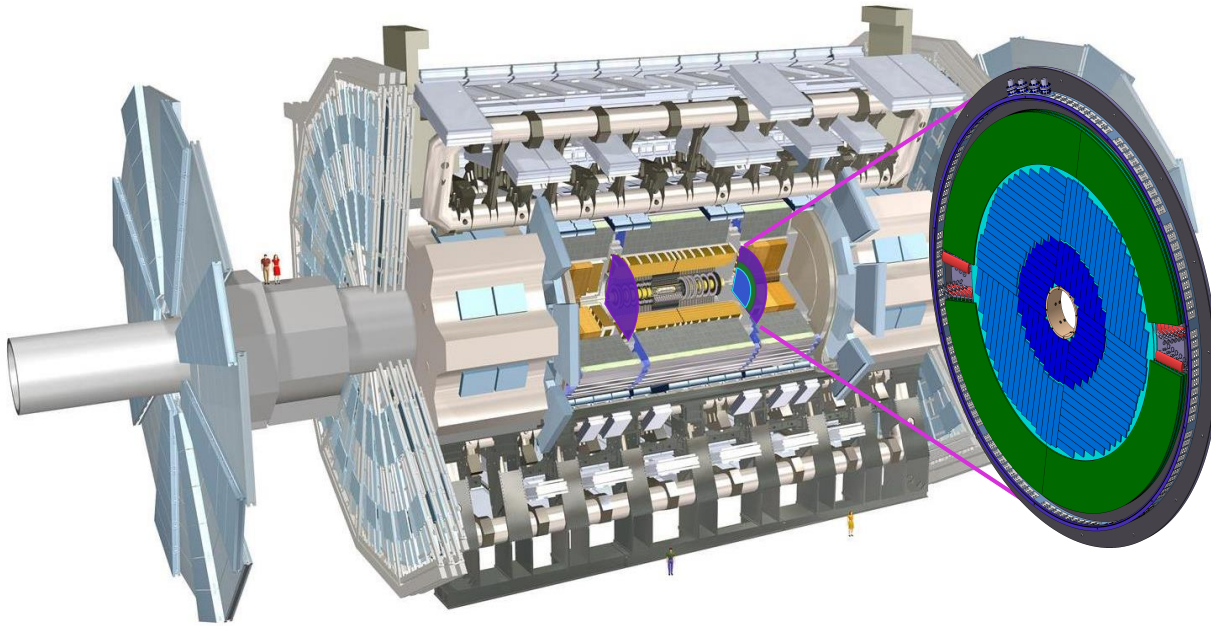


Removing Pile-up vertices

- Vertices are spread in position and time :
 - $\sigma_z = 45 \text{ mm}$ ($\approx 150 \text{ ps}$)
 - $\sigma_t = 175 \text{ ps}$
- Some pile-up interaction are merged with the hard scatter one by the tracker
- The use of timing information can be used to separate pile-up and hard scatter
- Limited by the timing resolution and the timing association capability



The High Granularity Timing Detector

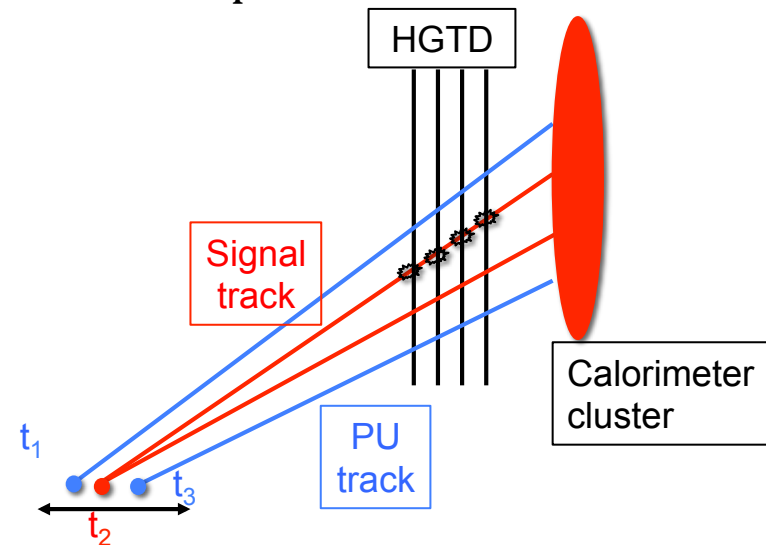


HGTD :

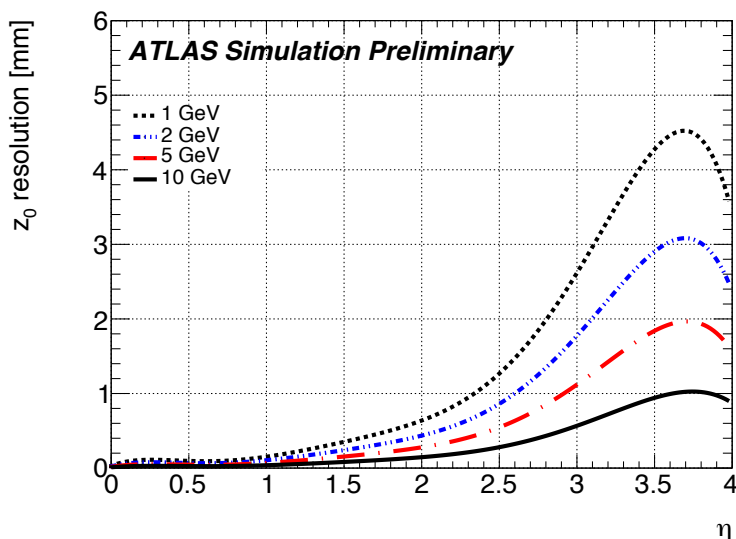
- In both endcap of ATLAS ($z = \pm 3.5$ m)
- Cover : $120 < r < 640$ mm ($2.4 < |\eta| < 4$)
- 2 double sided-layer per endcap
- 1.3×1.3 mm² LGAD sensor

Principle :

- Tracks extended to the HGTD
- Associated with Hits (time)
- The more hits the better the resolution :
$$Track_{res} = \frac{Hit_{res}}{\sqrt{N}}$$
- 30 ps resolution per track before irradiation
50 ps at the end of life



HGTD motivation



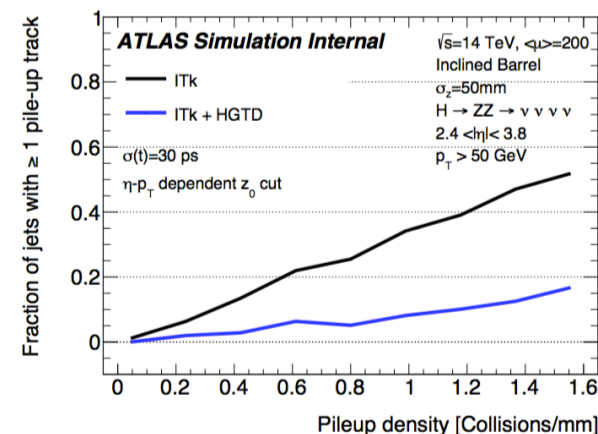
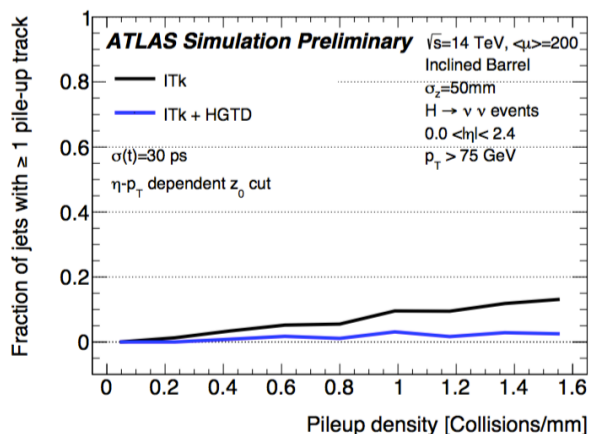
- Resolution of the tracker worst in the forward region (order of the mm)
- High PU density (1.4 vertices/mm)
- High likelihood of having a PU vertices merged with the signal vertex
- Could be complemented by time information to separate PU track from signal one
- Negligible impact in the forward region

$$\frac{z_0 - z_{vertex}}{\sigma_{z_0}} < 2$$

$$\sigma_{z_0}$$

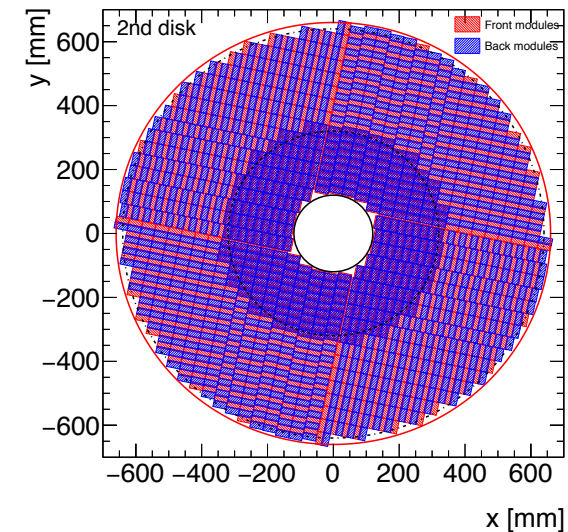
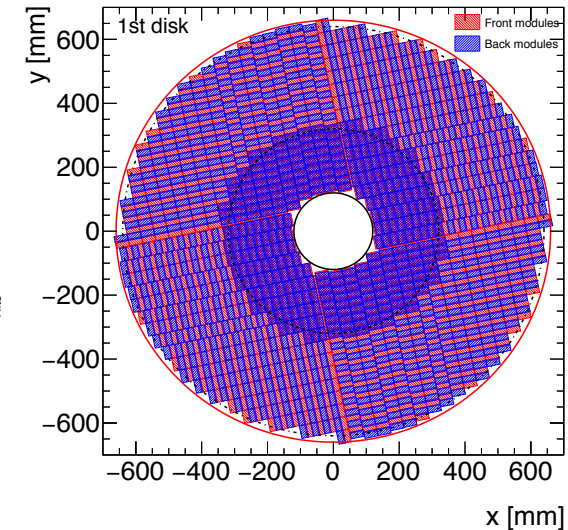
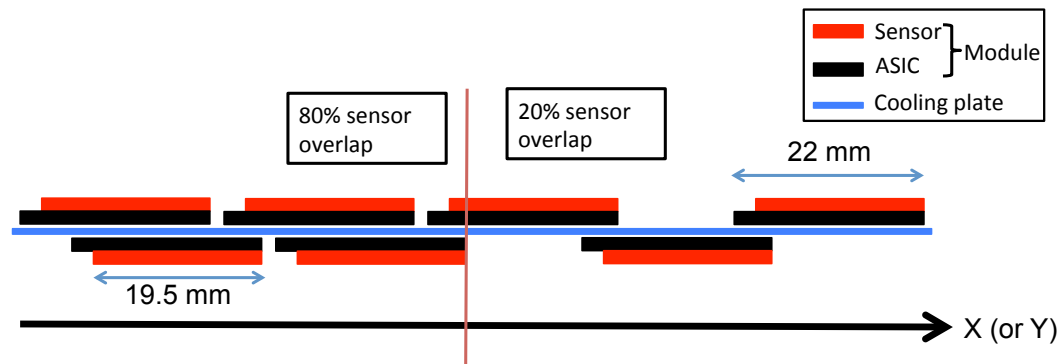
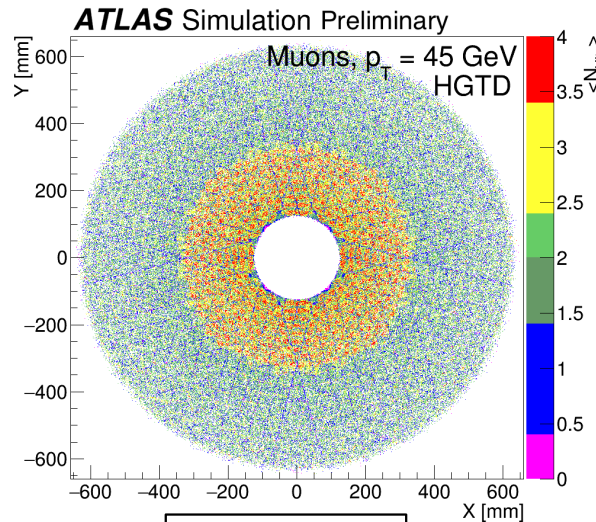
$$\frac{t - t_{vertex}}{\sigma_t} < 2$$

$$\sigma_t$$



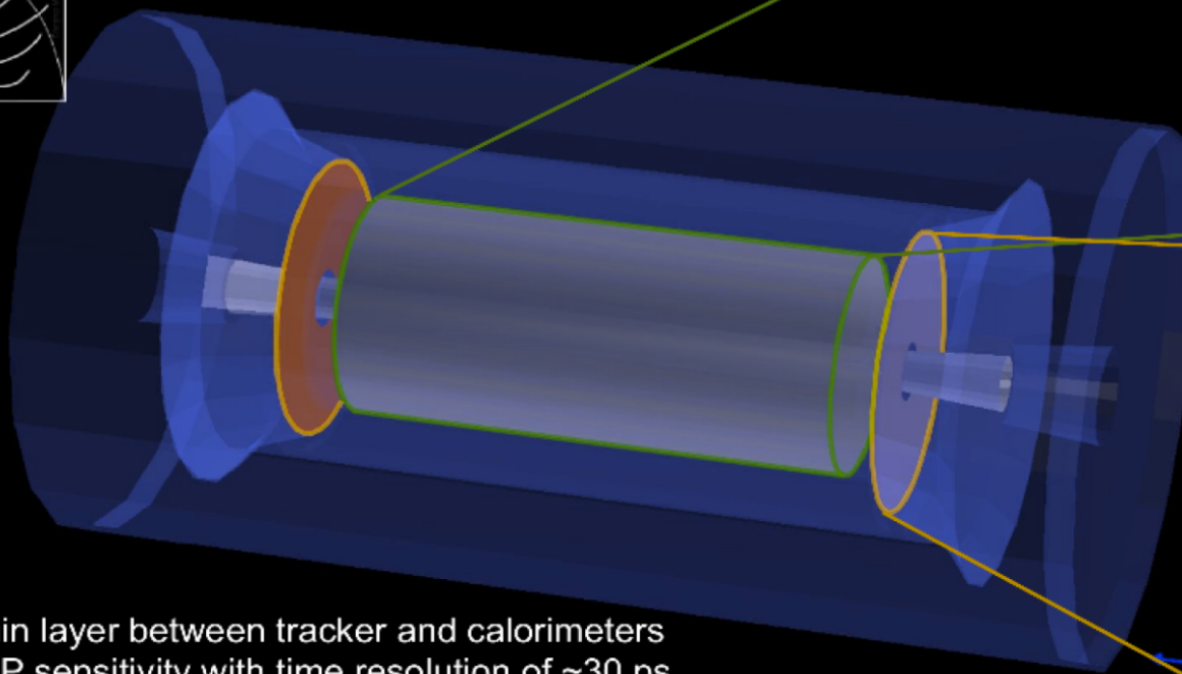
HGTD layout

- To maximise the resolution of the HGTD the number of hit associated to each track need to be maximize
- 2 double sided-layer per endcap : from 0 to 4 hit per track
- More module in the inner region to compensate the larger radiation
- Layout optimised to maximise the efficiency



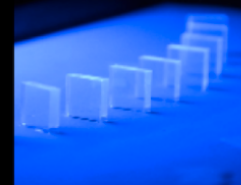
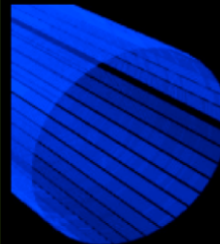
MIP Timing Detector

MTD design overview



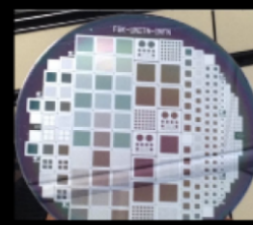
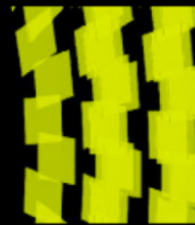
BARREL

TK/ECAL interface ~ 25 mm thick
Surface ~ 40 m²
Radiation level ~ 2×10^{14} n_{eq}/cm²
Sensors: LYSO crystals + SiPMs



ENDCAPS

On the CE nose ~ 42 mm thick
Surface ~ 12 m²
Radiation level ~ 2×10^{15} n_{eq}/cm²
Sensors: Si with internal gain (LGAD)



- Thin layer between tracker and calorimeters
- MIP sensitivity with time resolution of ~30 ps
- Hermetic coverage for $|\eta| < 3$

MIP Timing Detector

Barrel :

- LYSO crystal + SiPM (similar to calorimeter)
- Layer built at the end of the tracker
- Less radiation than the forward region

Endcap :

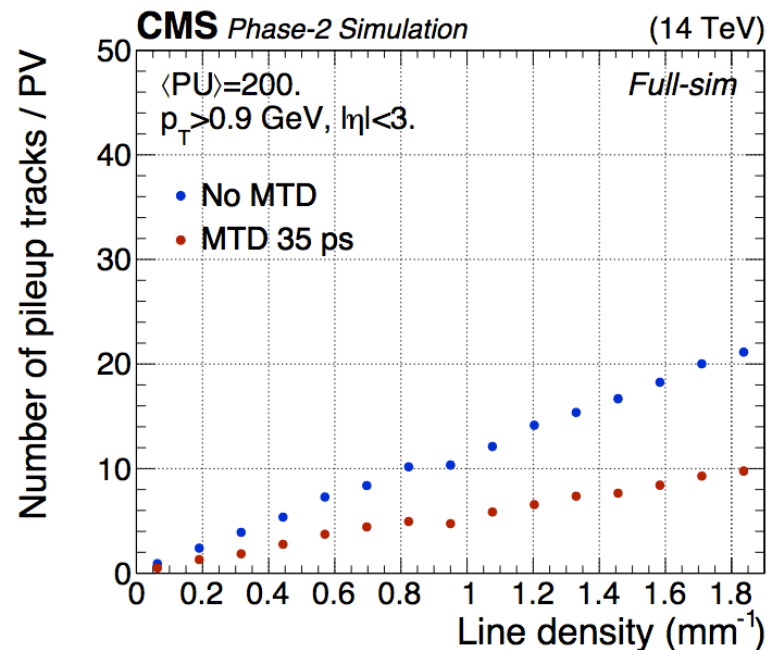
- LGAD (similar to ATLAS HGTD)
- Single layer between the tracker and calorimeter
- High radiation dose

- Fewer layers : worst timing resolution and efficiency
- Full timing coverage : Easier to reconstruct vertices times

	Barrel LYSO+SiPM	Endcap LGAD
Coverage	$ \eta < 1.5$	$1.5 < \eta < 3.0$
Surface Area	$\sim 40 \text{ m}^2$	$\sim 12 \text{ m}^2$
Power Budget	$\sim 0.5 \text{ kW/m}^2$	$\sim 1.8 \text{ kW/m}^2$
Radiation Dose	$\leq 2e14 \text{ neq/cm}^2$	$\leq 2e15 \text{ neq/cm}^2$
Installation Date	2022	2024

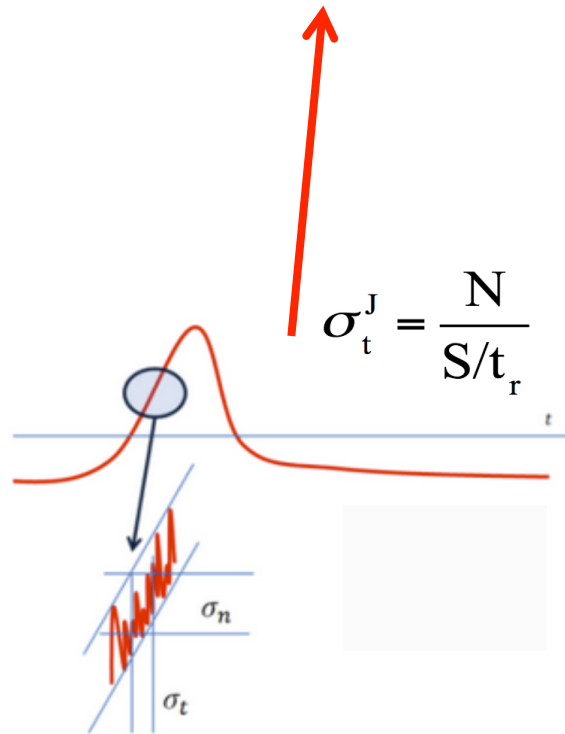
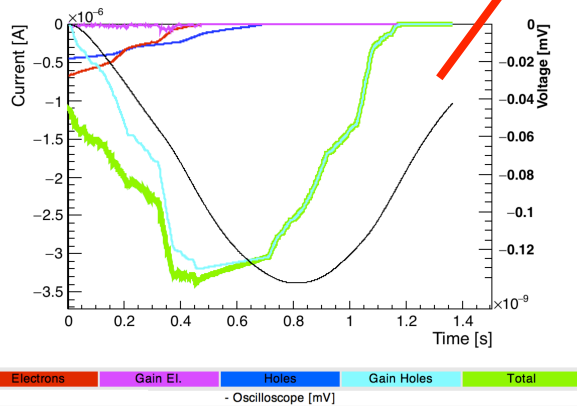
MTD motivation

- CMS rely on a Particle flow algorithm : information from the different subdetector are combined to fully reconstruct the events
- Time information significantly improve such algorithm by providing a way to determine if track are from PU or HS
- CMS calorimeter is also capable of achieving a time resolution of the order of 100-150 ps, the timing can thus help associate tracks to calorimeter cluster



Time resolution

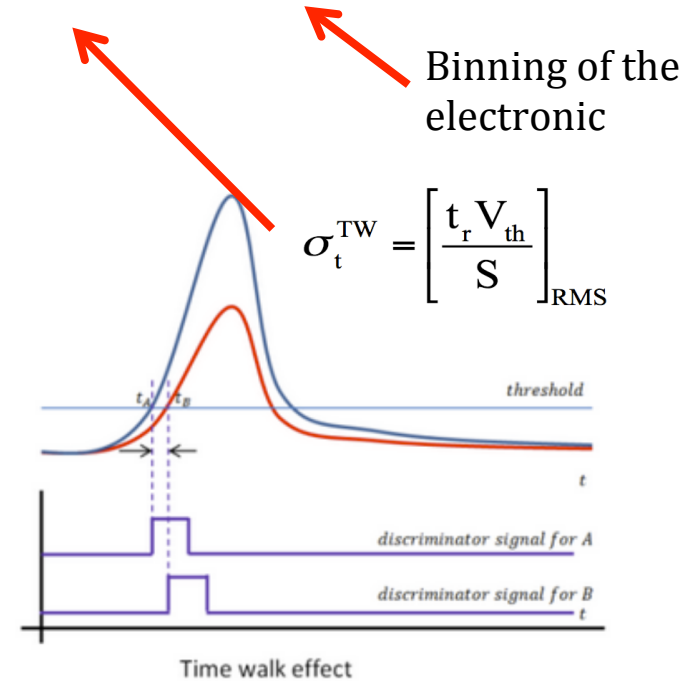
$$\sigma_{\text{det}}^2 = \sigma_{\text{Landau}}^2 + \sigma_{\text{jitter}}^2 + \sigma_{\text{TW}}^2 + \sigma_{\text{TDC}}^2$$



Jitter effect

Noise affect the reconstructed time

$$\sigma_t^J = \frac{N}{S/t_r}$$



Binning of the electronic

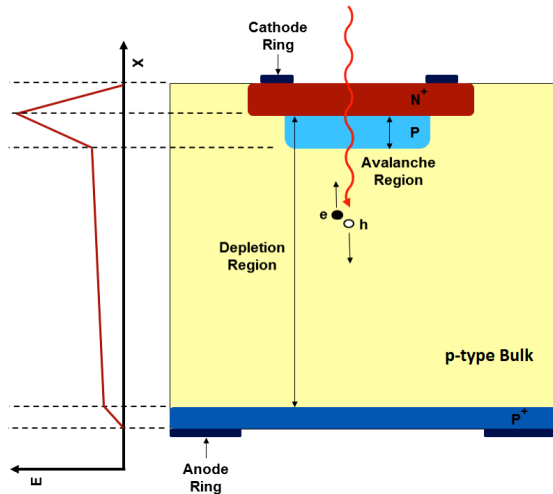
$$\sigma_t^{\text{TW}} = \left[\frac{t_r V_{\text{th}}}{S} \right]_{\text{RMS}}$$

Reconstructed time change with the amplitude of the pulses

- Energy deposit in the sensor change the pulse shape
- Uncertainty on the reconstructed time

Technology to measure time

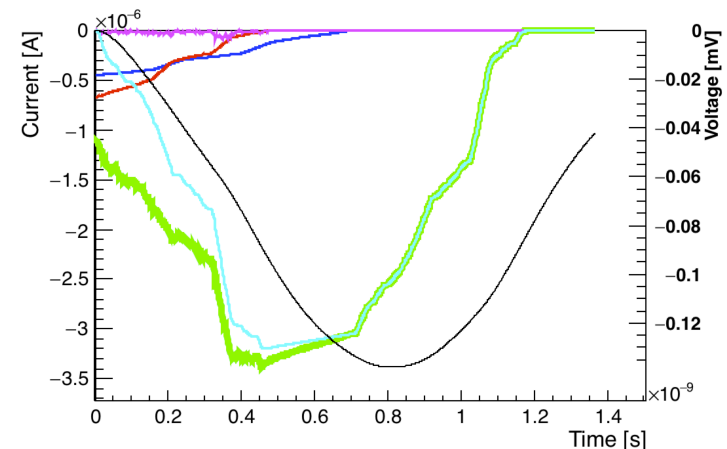
Gain -> Good timing resolution



- Relatively new technology
- Lots of R&D still on going
- Si sensors : particle create $e^- /$ hole pairs, they drift through the sensor -> signal
- LGAD sensors : Same but the e^- go through a high E field -> showering -> **gain**

LGADs : ATLAS and CMS
forward timing

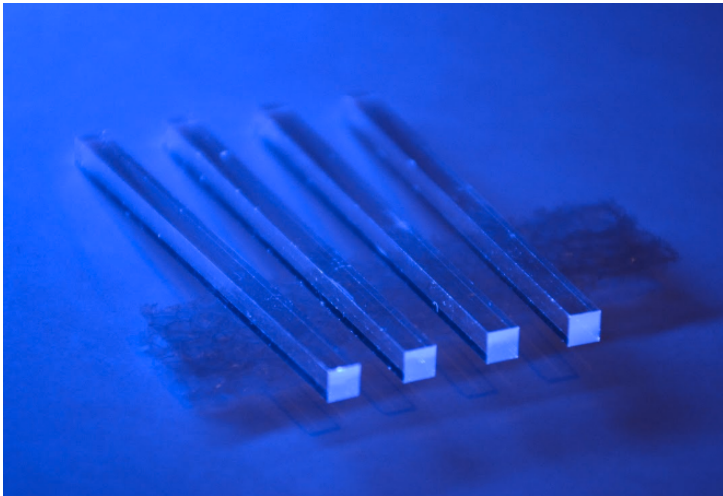
- Gain of the order of 10-15 -> time resolution of ~ 30 ps
- Good radiation resistance, loss of resolution with the dose received



Electrons Gain El. Holes Gain Holes Total
- Oscilloscope [mV]

Technology to measure time

Gain -> Good timing resolution

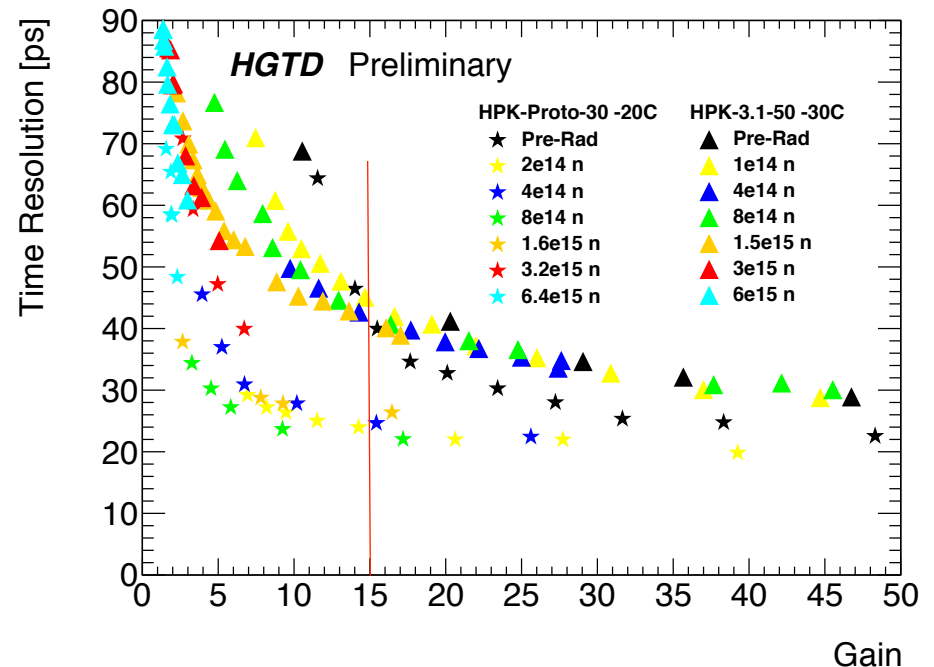
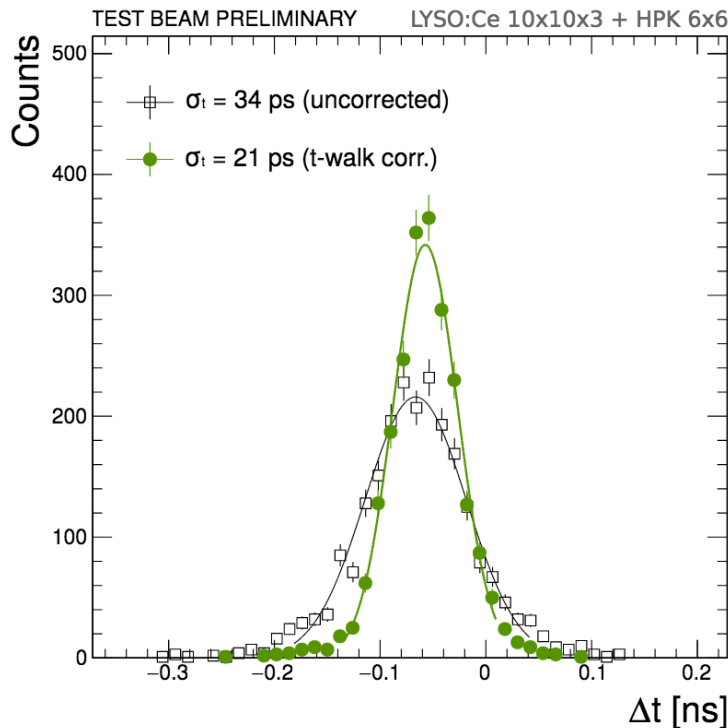


LYSO crystal + SIPM

- Crystal : produce photons when particles go through them
- SIPM : Multiply the number of photon (gain) and collect them to create a signal
- Already used in CMS calorimeters
- Can provide a resolution of ~ 40 ps
- Less radiation resistant

Resolution

- ATLAS and CMS have study extensively the resolution of their sensor in different test beam campaign
- Good resolution of 30 ps have been shown to be achievable pre-irradiation
- After irradiation the resolution worsen up to 50-60 ps

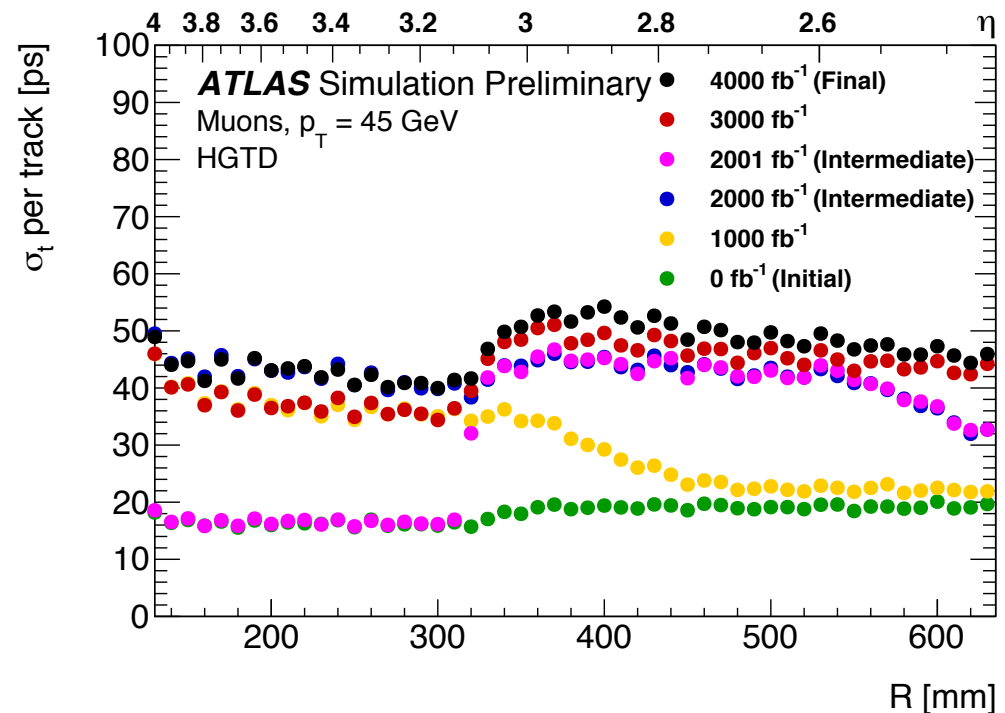


Resolution in the detector

- The more hits from the timing detector associated with the track the better the resolution of the tracks
- The reconstruction algorithm used to associate the hits to the tracks thus has a major impact on the performances

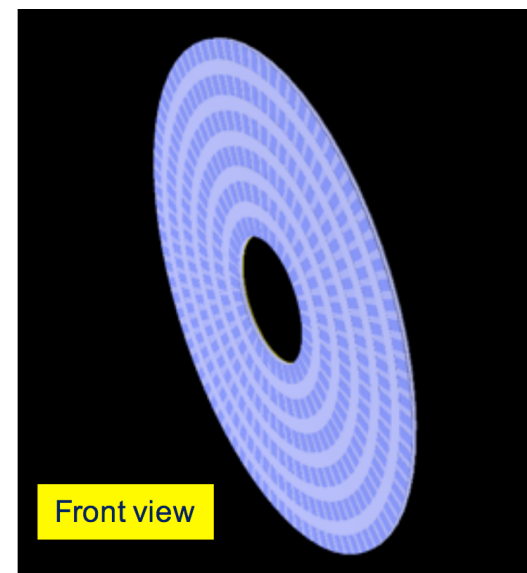
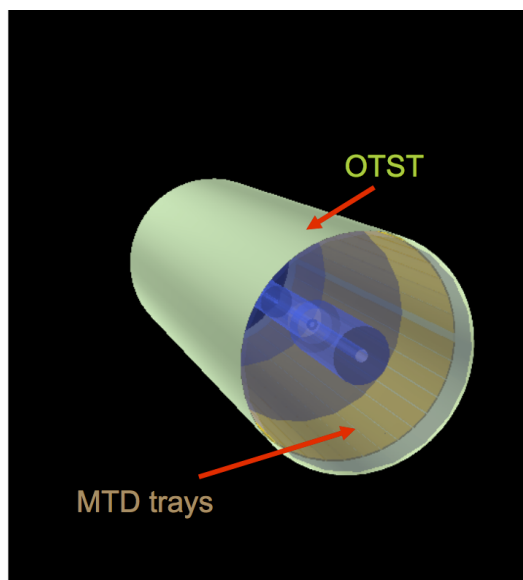
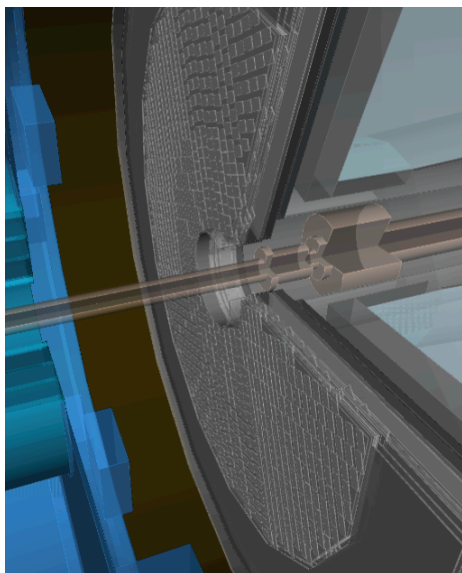
Two approaches :

- The times of the tracks can be compared with each other (track to track)
- Tracks can be used to reconstruct global t_0 time (vertex to track)



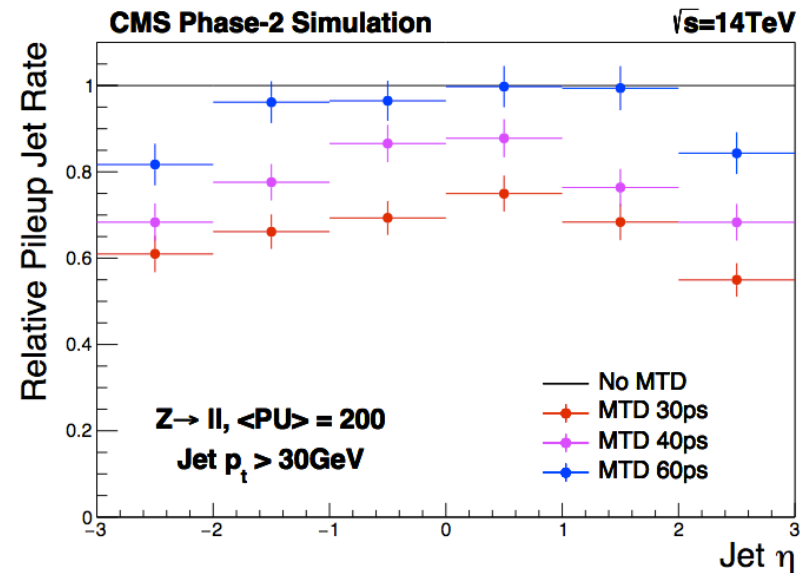
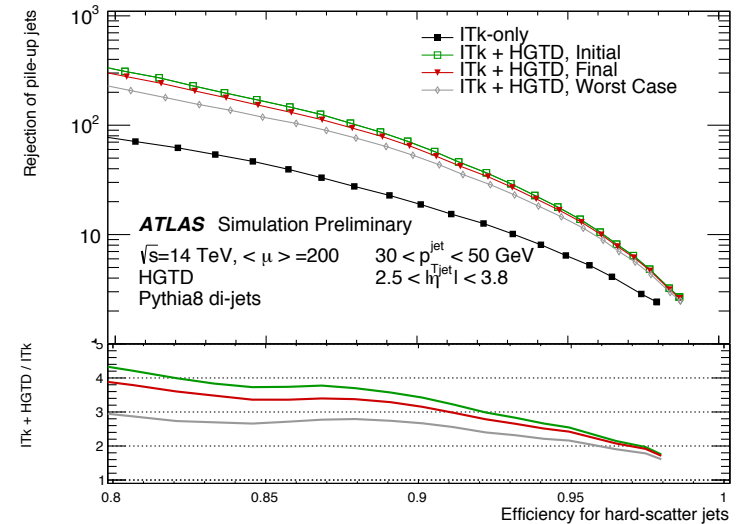
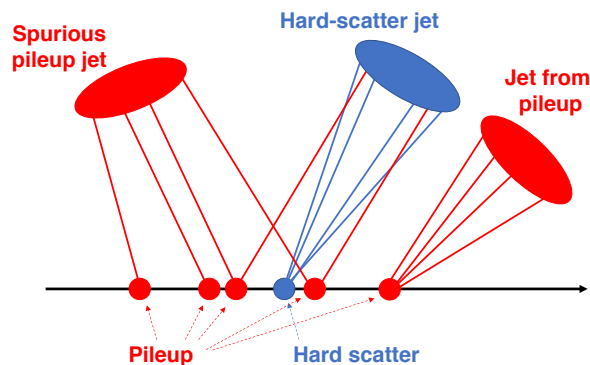
Impact of the timing detector

- Both ATLAS and CMS studied the impact on such detector on the performances using simulation
- Most reconstruction algorithms were not reoptimized for those studies better improvement could be expected with smarter algorithm

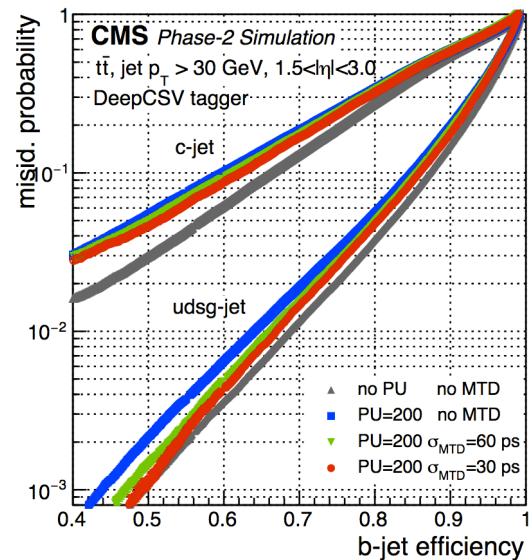
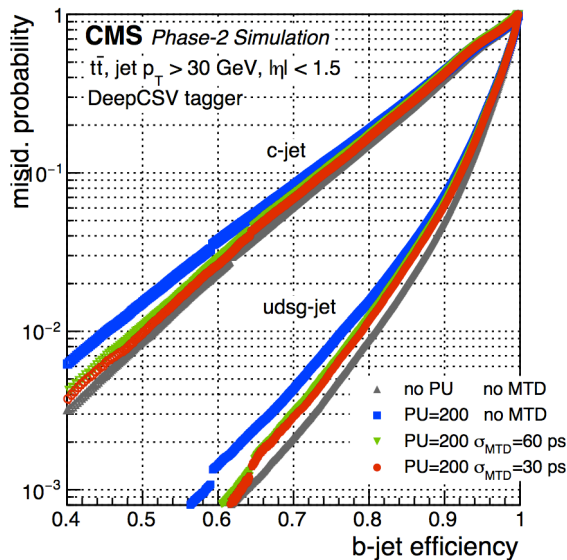
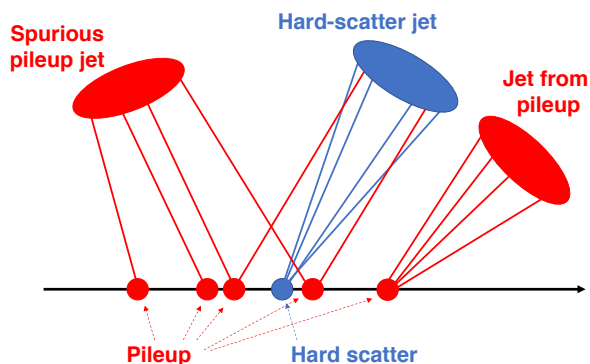


Pile-up jet rejection

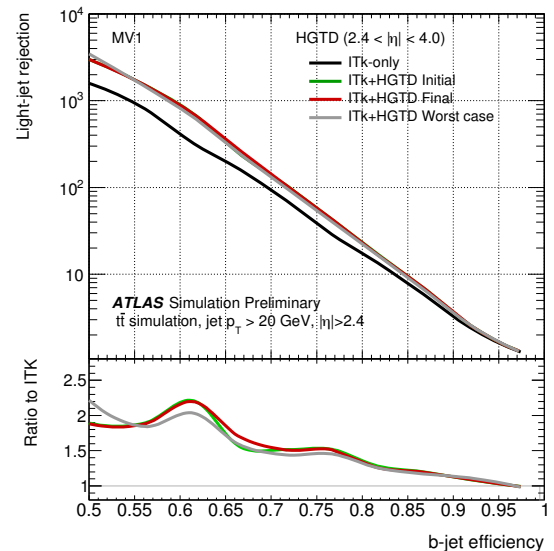
- Improved by the time information
- ATLAS : Rejection of PU jets based on ratio of p_T (tracks) and p_T (jet)
- Removing out of time tracks improve the algorithm
- In CMS track out of time are removed from the particle flow algorithm
- This also result in a reduction of the number of PU jets



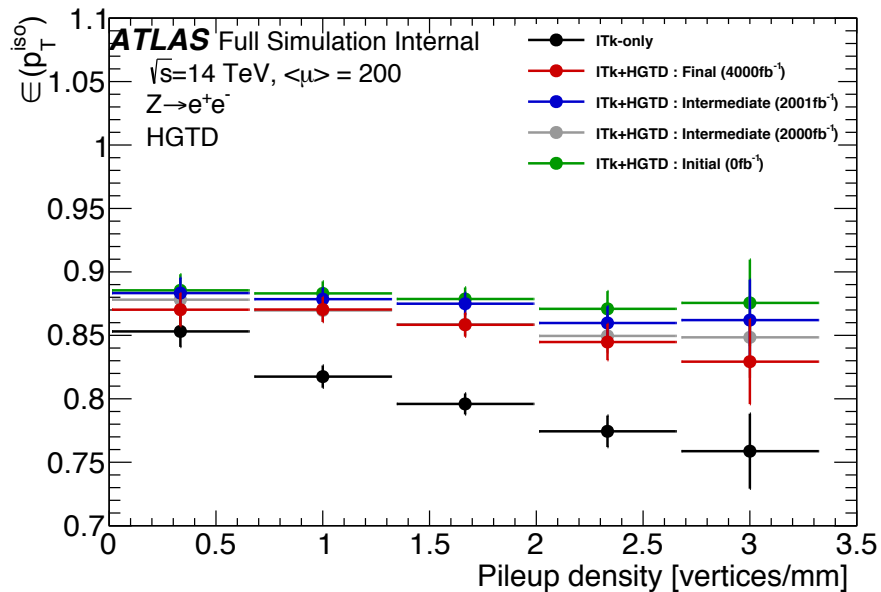
Heavy flavor tagging



- Identification of heavy flavor quarks improved by time information
- When reconstructing such jets more track are accepted due to the longer lifetime of the b hadron -
> more PU jet contamination
- Time help keep the PU contamination low and improve the reconstruction

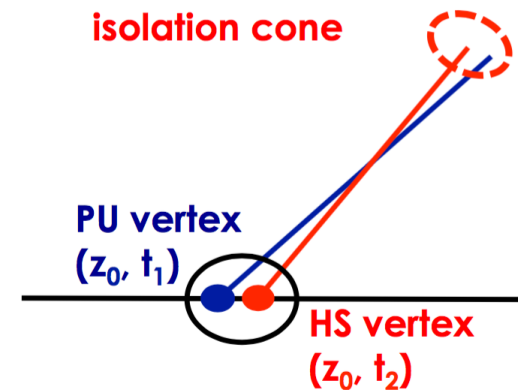


Electron Isolation



- Track isolation used in many analyses with leptons to fight QCD background
- Isolated lepton \rightarrow Lepton that come from the studied process (and not from showering)
- Isolated : with no other track with $p_T > 1$ GeV in $\Delta R < 0.2$

- PU can reduce the Isolation efficiency
- A time compatibility of the close track with the electron track can be added
- Improve the efficiency of such algorithm



Conclusion

- Time information can greatly improve the performances of the detectors in high pile up environments
- The performance of such detector greatly depend on the reconstruction algorithm
- Different experiment can use timing in different way depending on their needs
- The technology is evolving quite quickly : Smaller granularity (pixel like), better resolution (1 ps)
- Currently part of their own subdetector but will probably be in the future part of most trackers