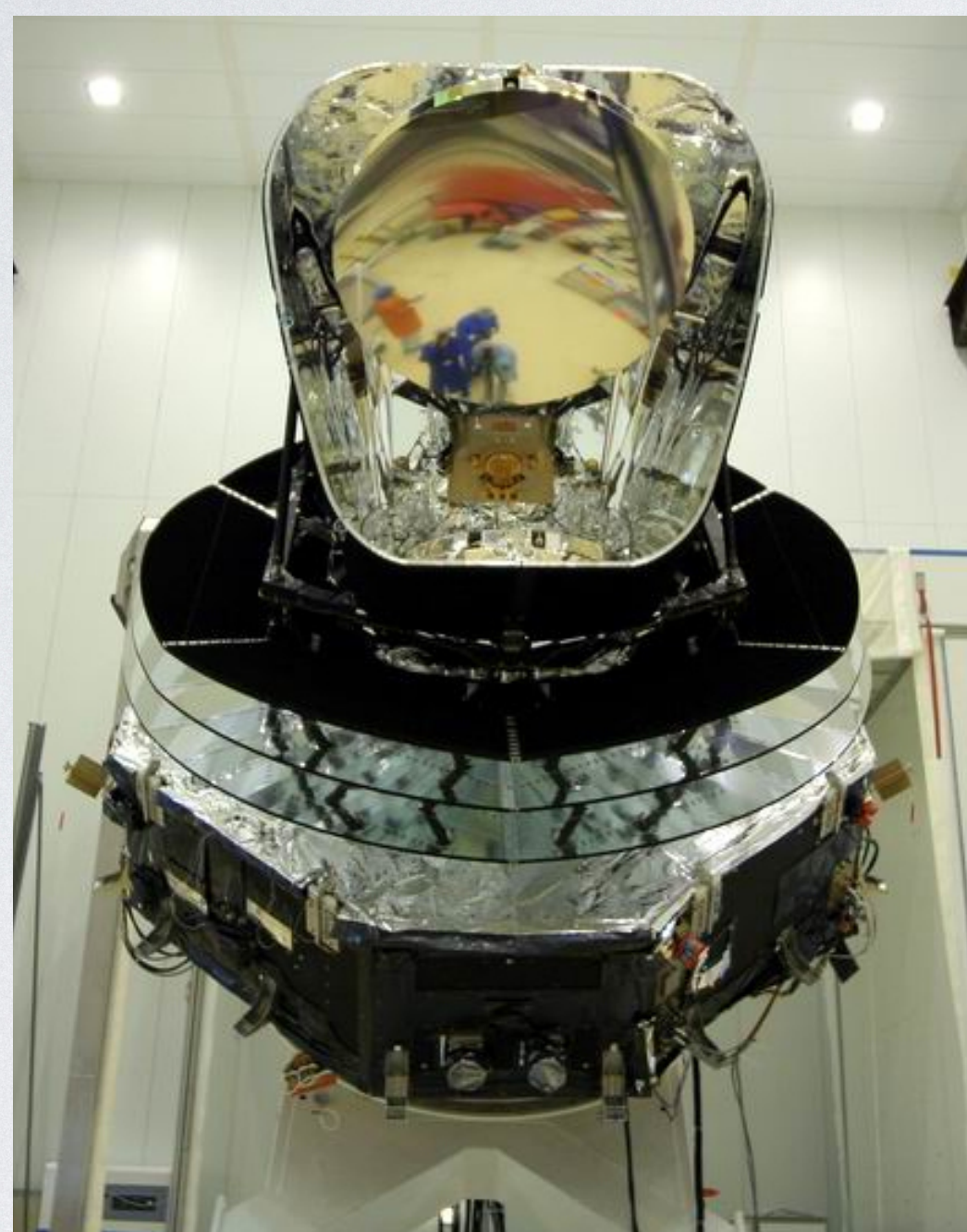


# LARGE-SCALE B-MODE POLARIZED FOREGROUNDS

Andrei Frolov, SFU  
[frolov@sfu.ca](mailto:frolov@sfu.ca)

COSMOLOGY 2023 in Miramare, 29 August 2023

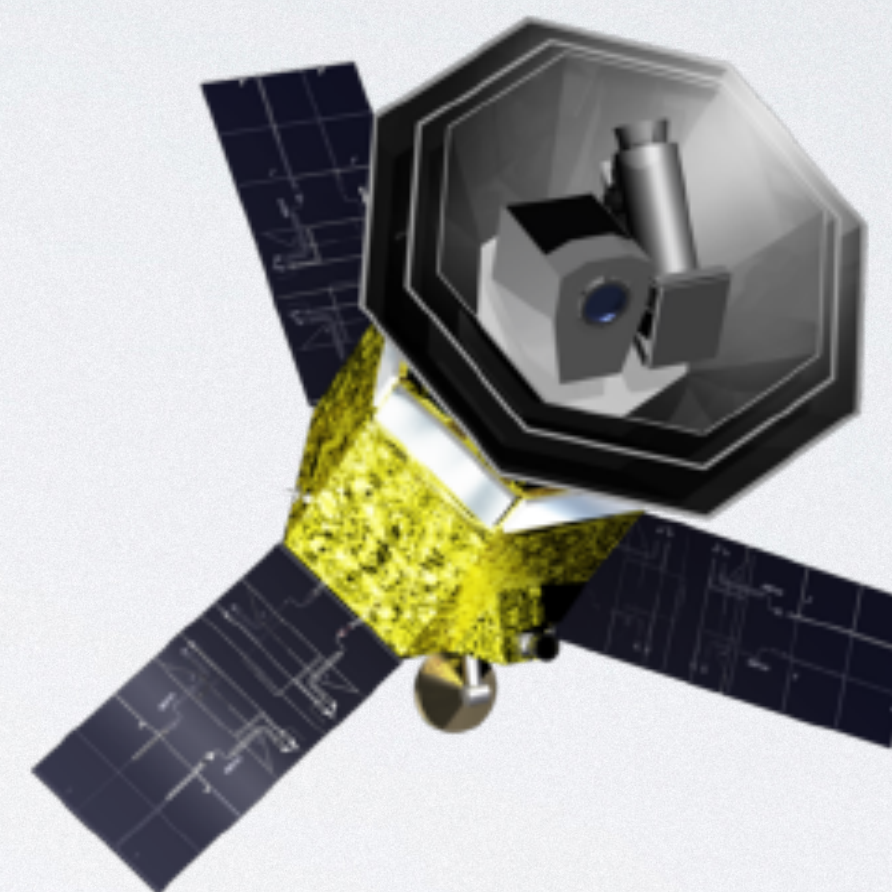
# PAST AND FUTURE CMB EXPERIMENTS



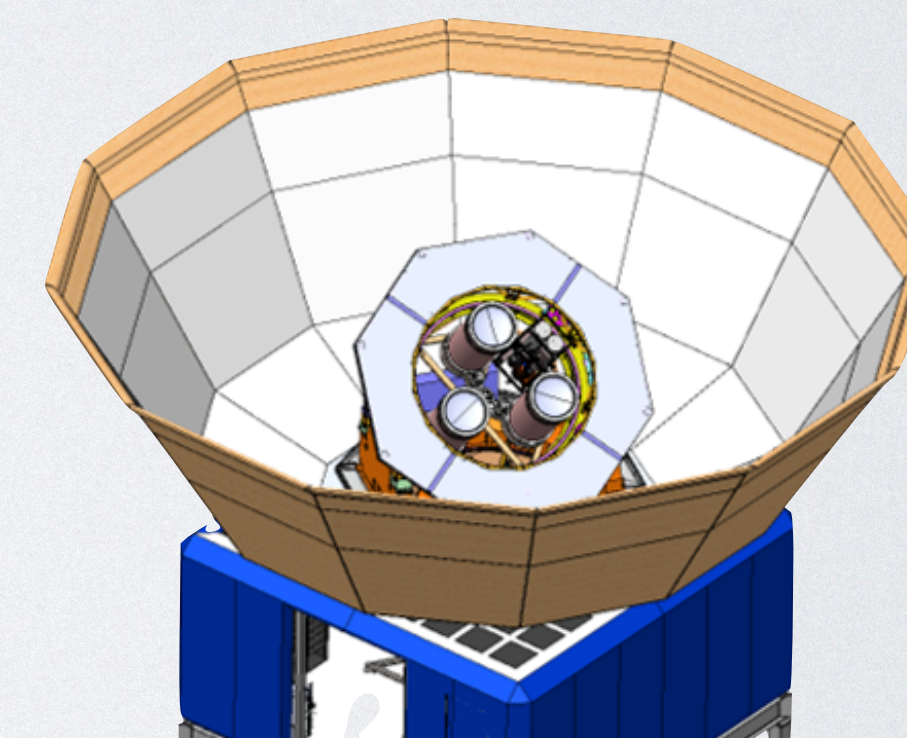
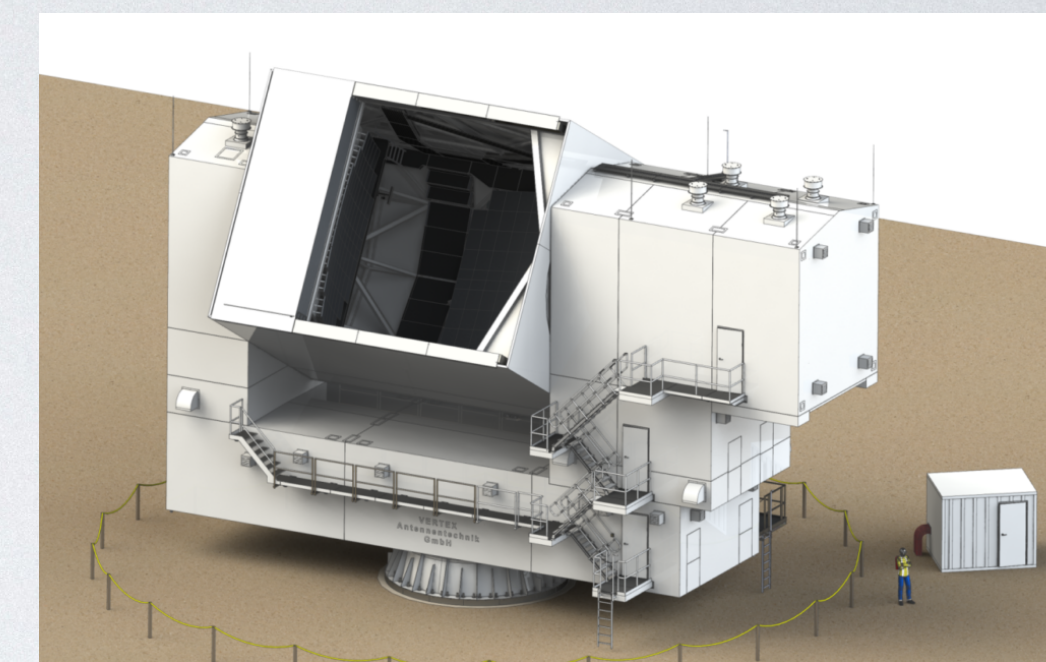
Planck (done!)



Simons Observatory  
(happening now)

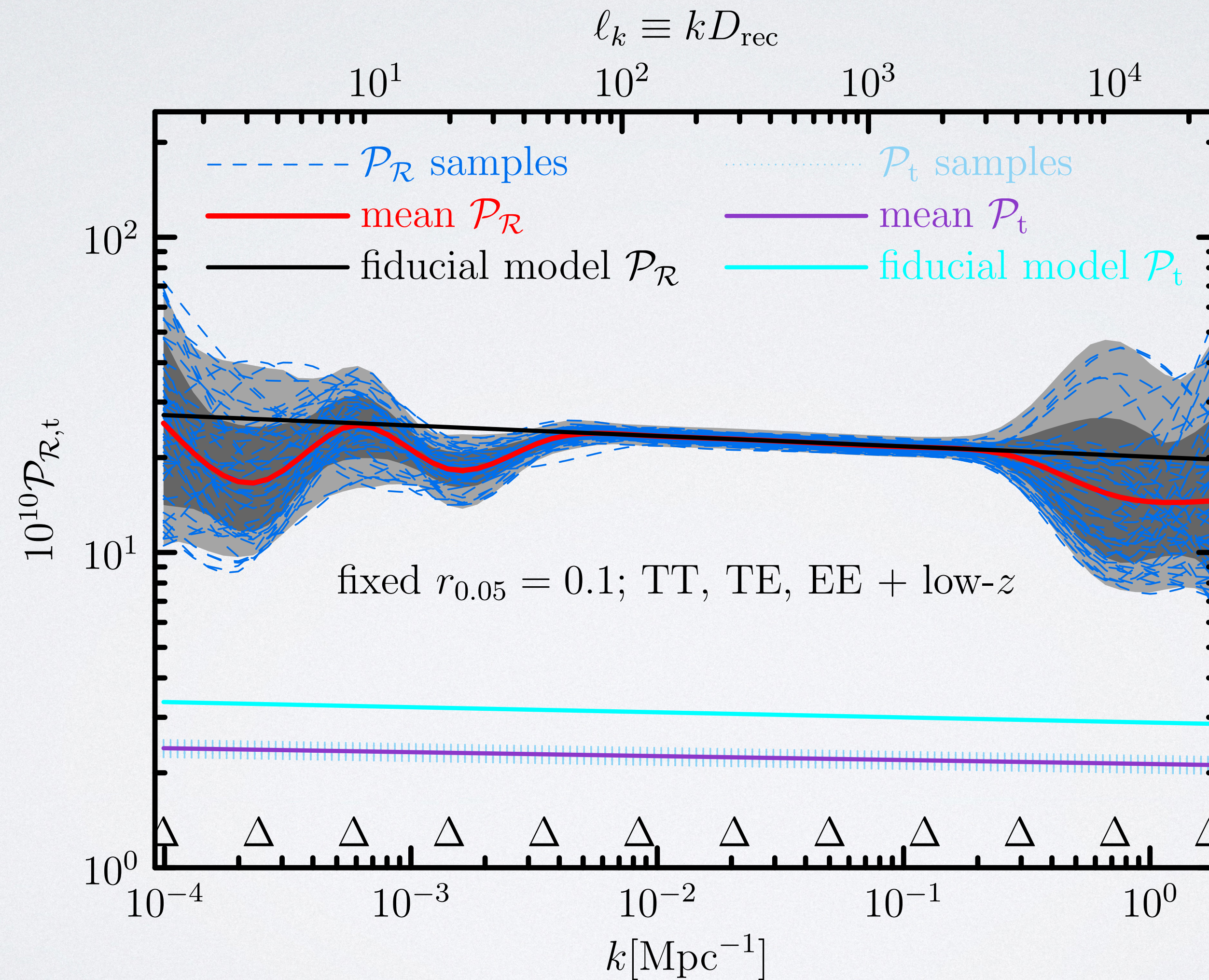


LiteBIRD  
(space based)



CMB-S4

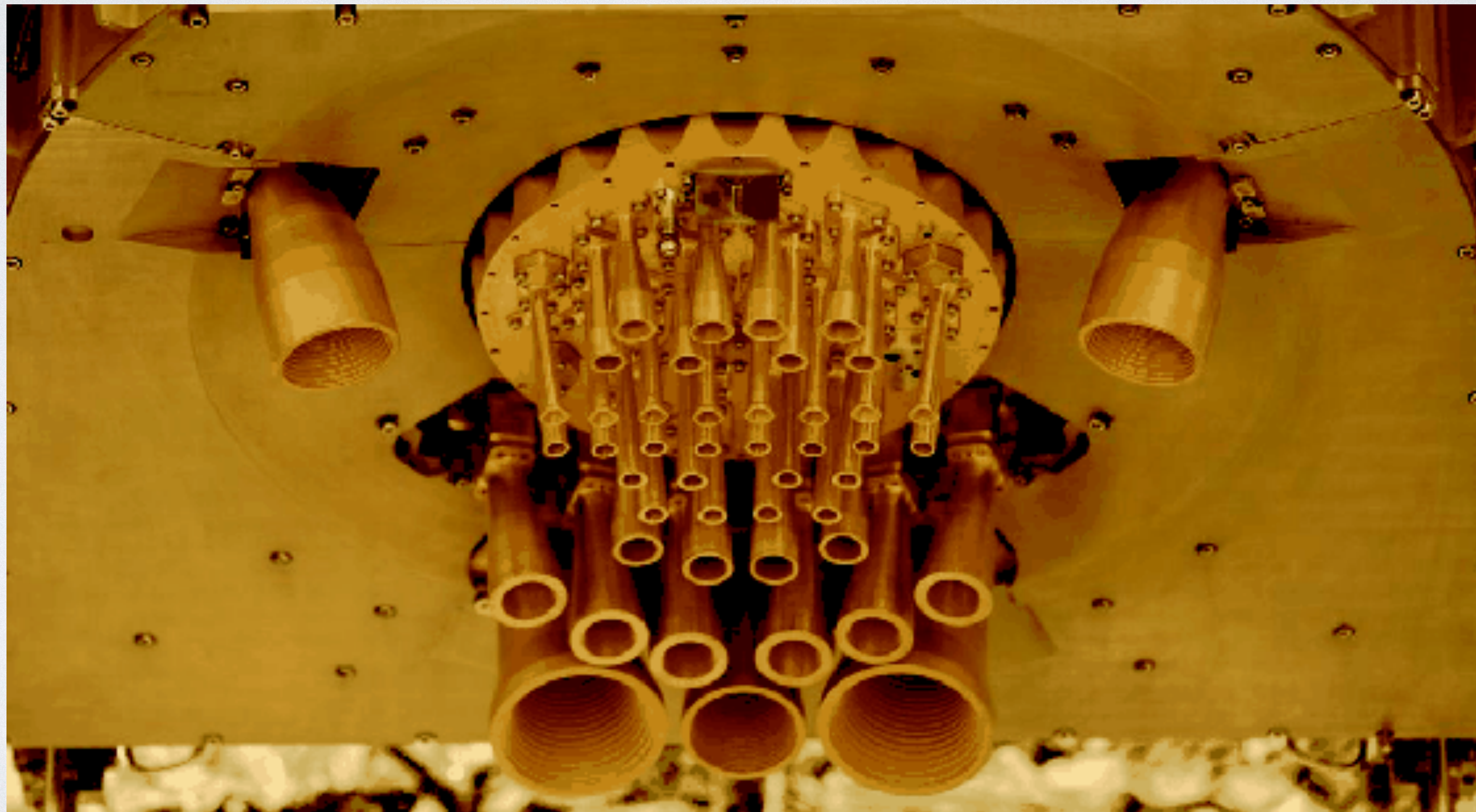
# T AND E MODES ARE NOW NAILED!



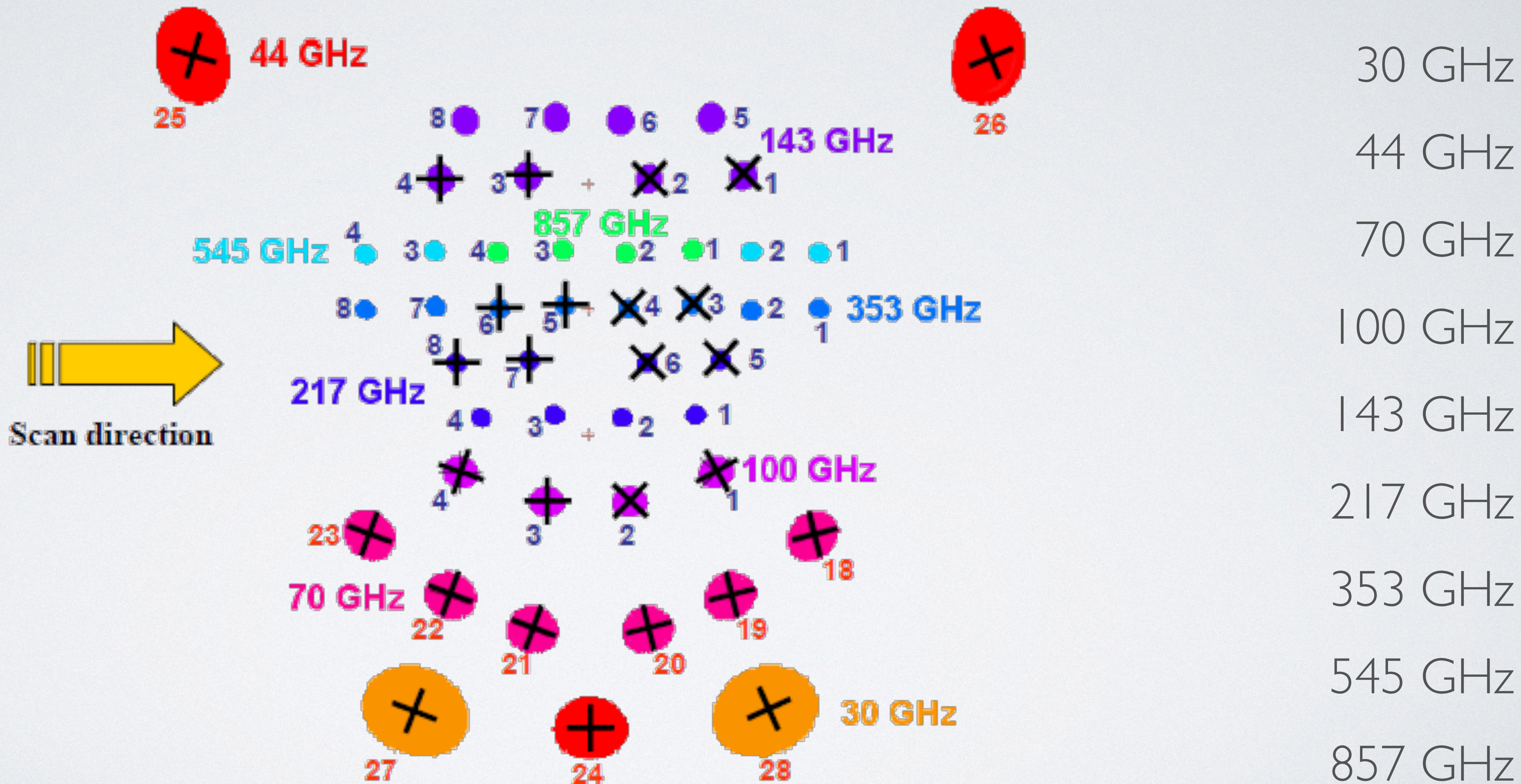
# NEXT TARGET: B-MODES

primordial gravitational waves, large scale lensing...

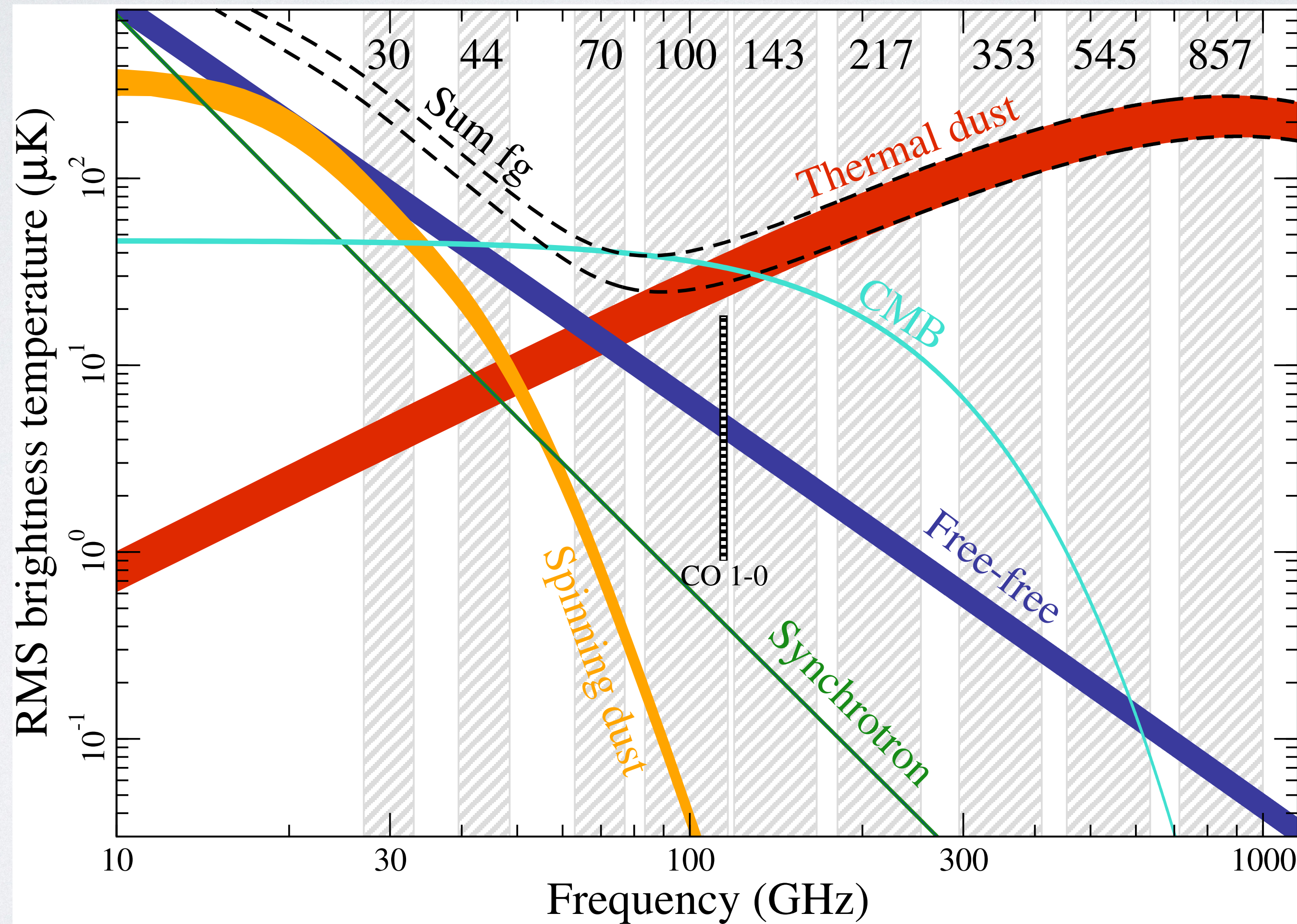
# PLANCK FOCAL PLANE



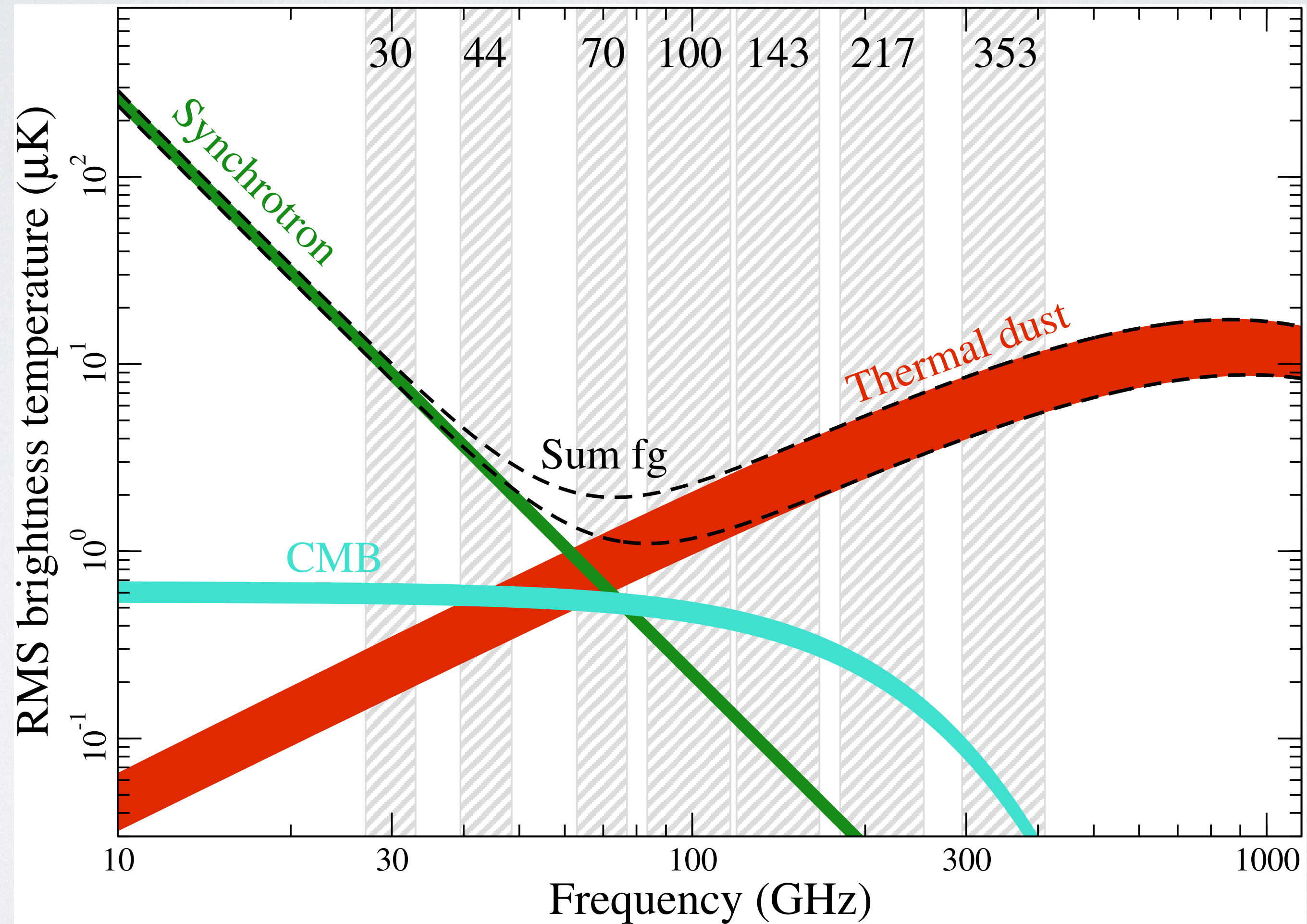
# PLANCK FOCAL PLANE



# INTENSITY FOREGROUNDS



# POLARIZED FOREGROUNDS

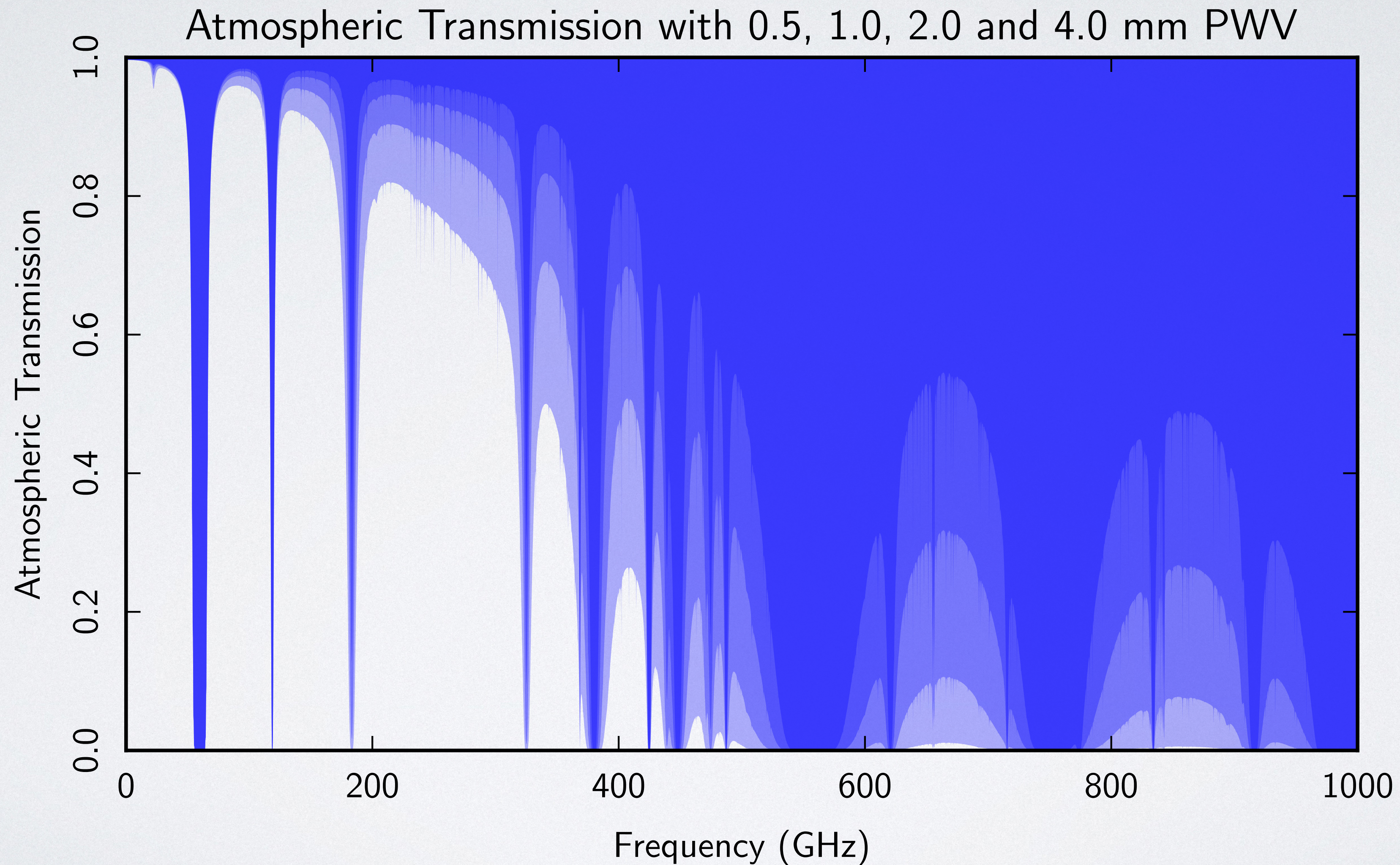




# POLARIZED FOREGROUNDS

- two main foregrounds - synchrotron and thermal dust
- both are *strongly* polarized, with abundant B-mode content
- synchrotron is power law, dominant at *low frequency*
- thermal dust is modified black body, dominant at *high frequency*
- primordial B-modes are *sub-dominant* at all frequencies

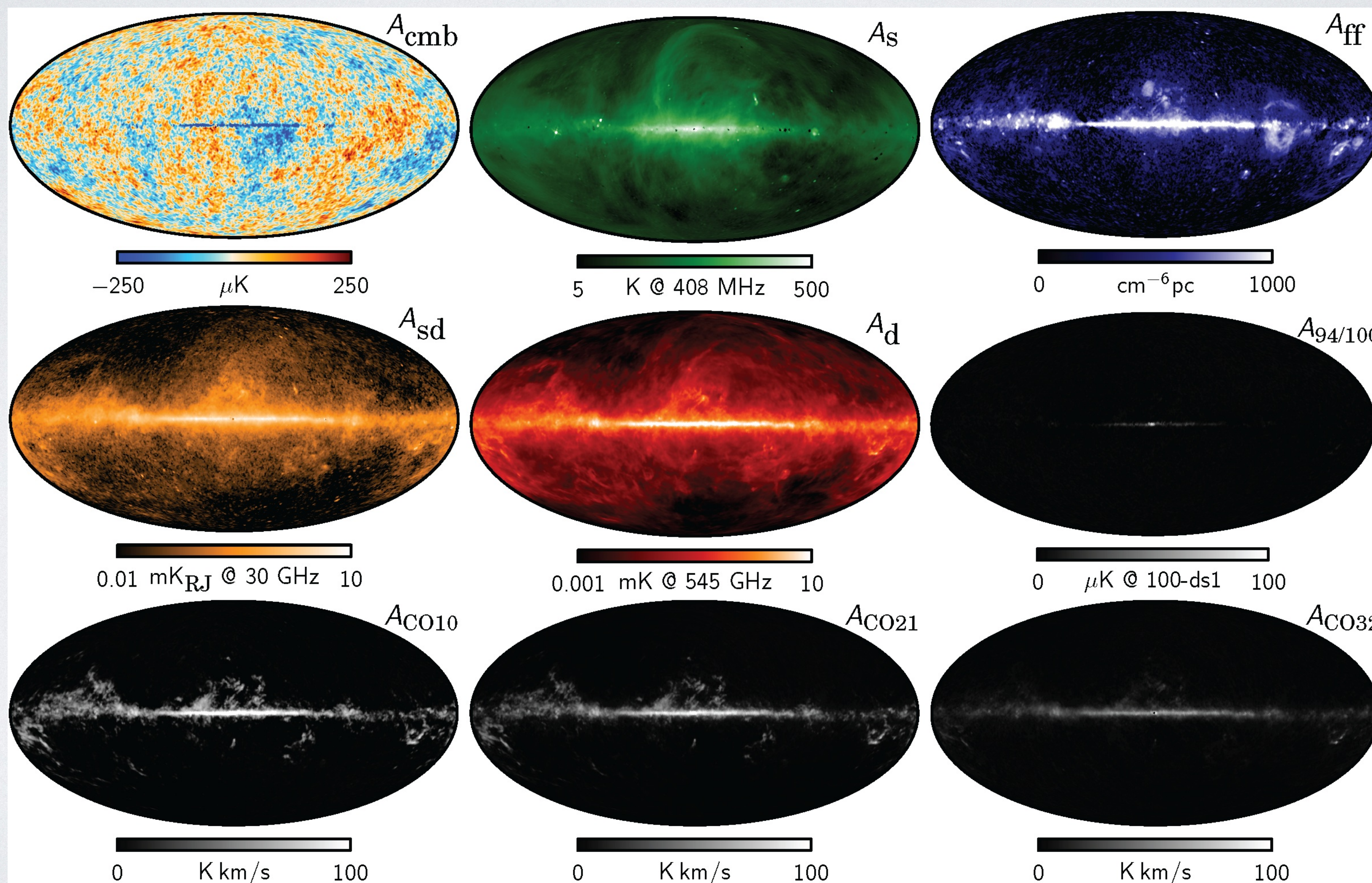
# ADDITIONAL COMPLICATION - WATER!



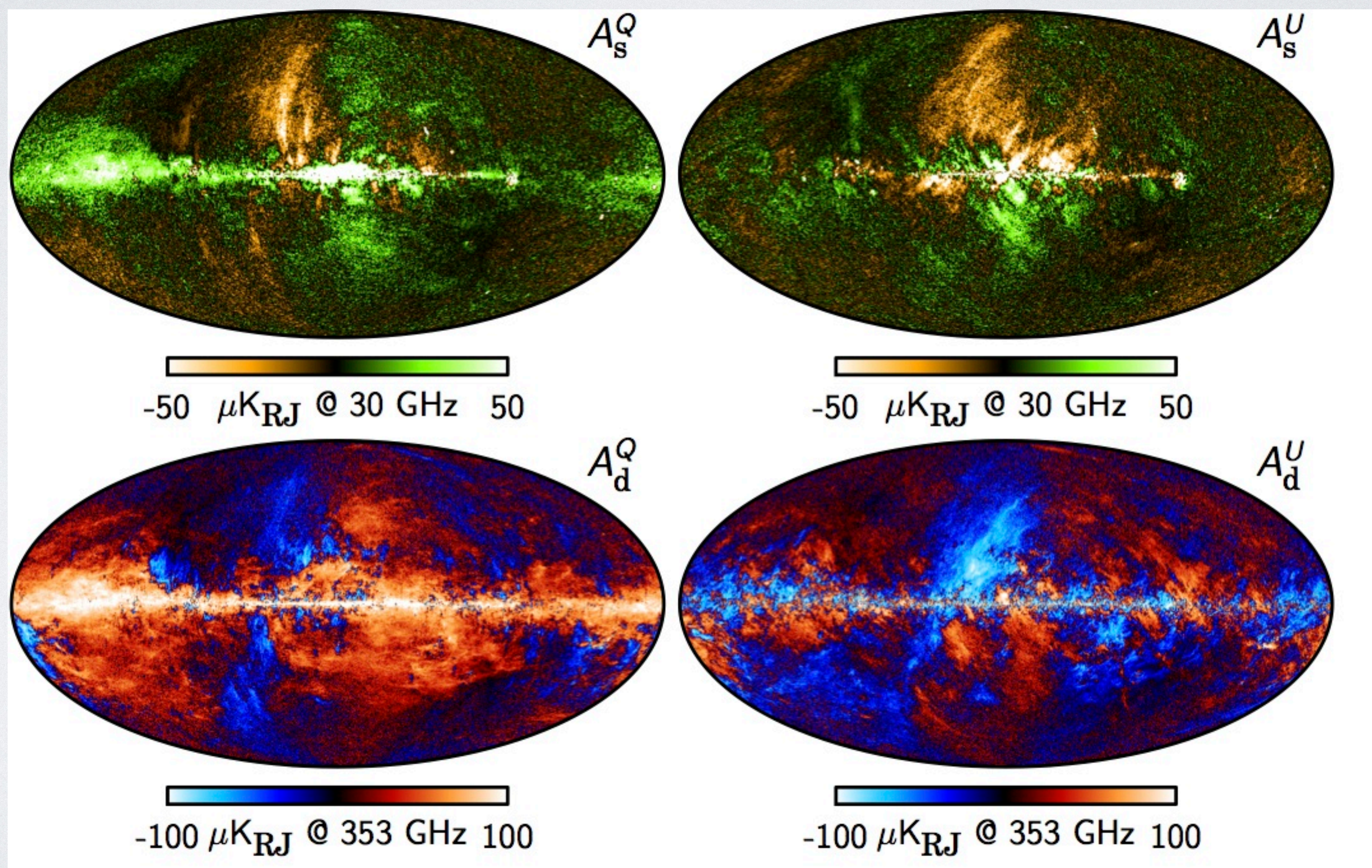
# COMPONENT SEPARATION

- different components have different frequency dependence!
- two basic strategies: fit component spectra (Gibbs samplers), or construct minimal variance linear combination (ILC, BLUE, etc.)
- Planck used 4 pipelines (Commander, NILC, SEVEM, SMICA)
- spatial and morphological information not fully exploited yet...

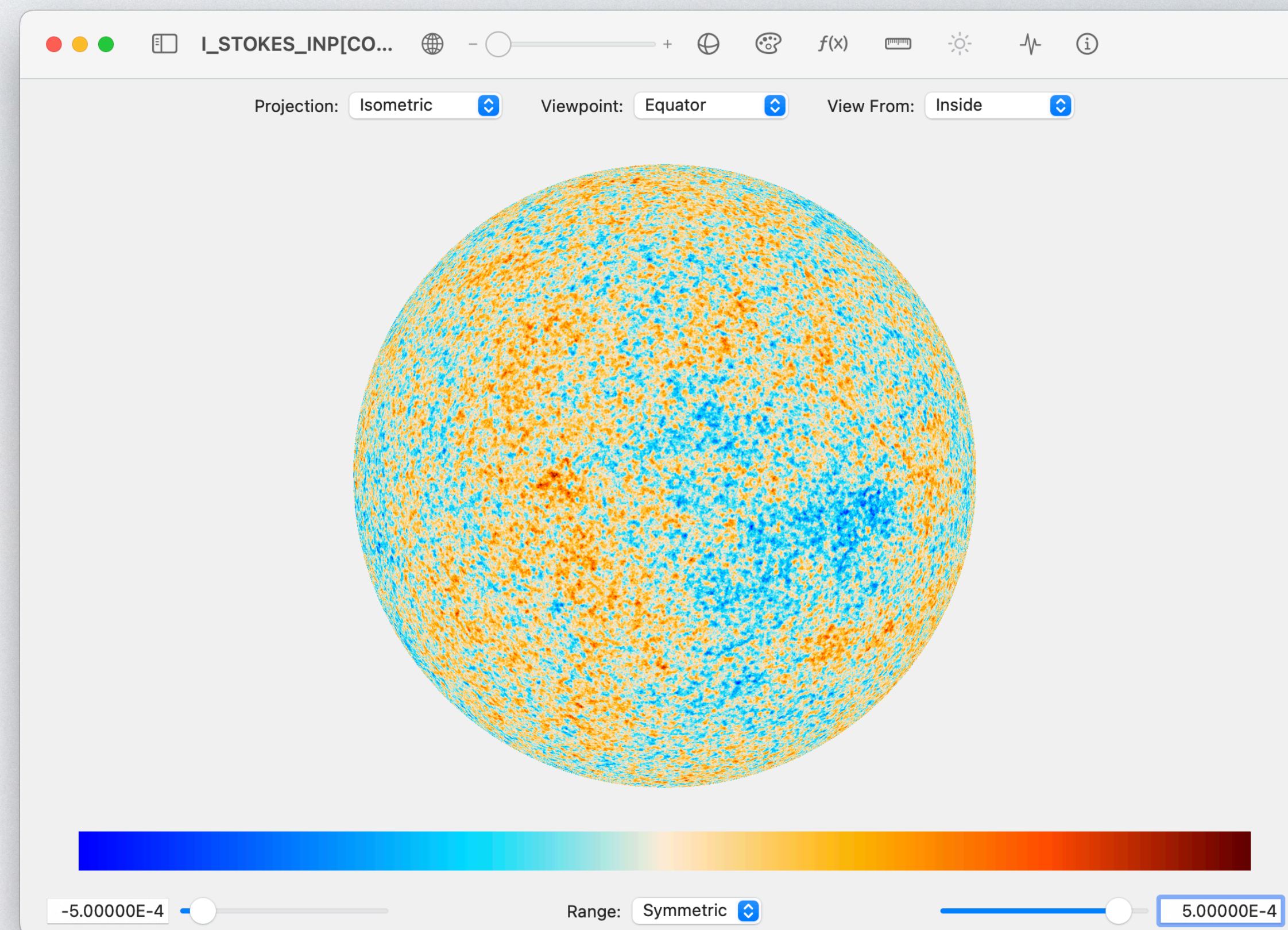
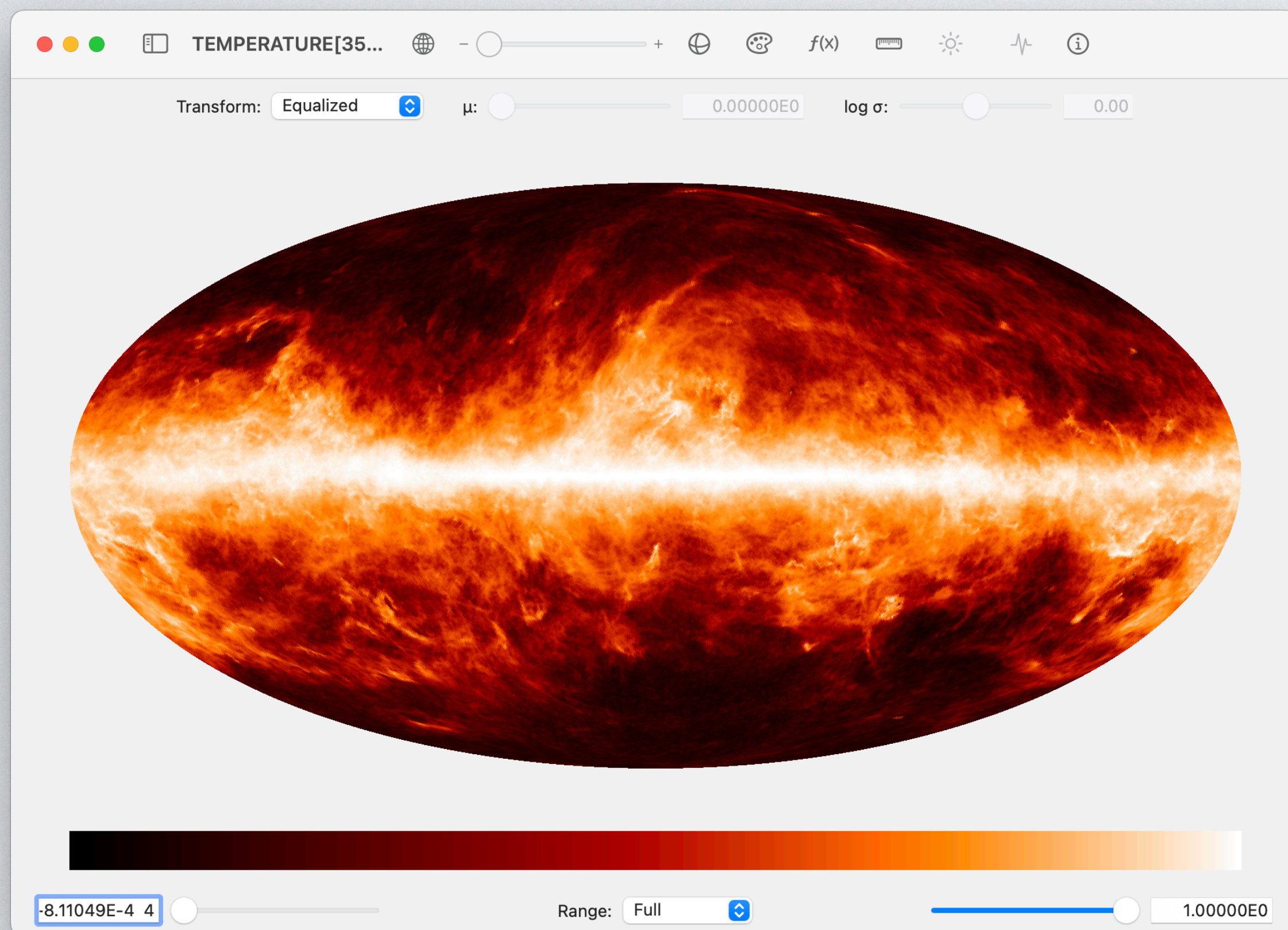
# INTENSITY COMPONENTS



# POLARIZED COMPONENTS



# QUICK ASIDE - HEALPIX VIEWER



<https://github.com/andrei-v-frolov/healpix-viewer>

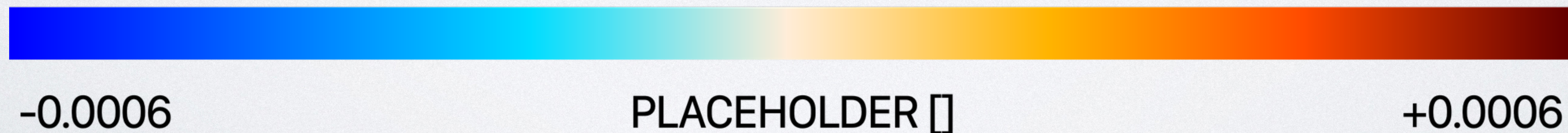
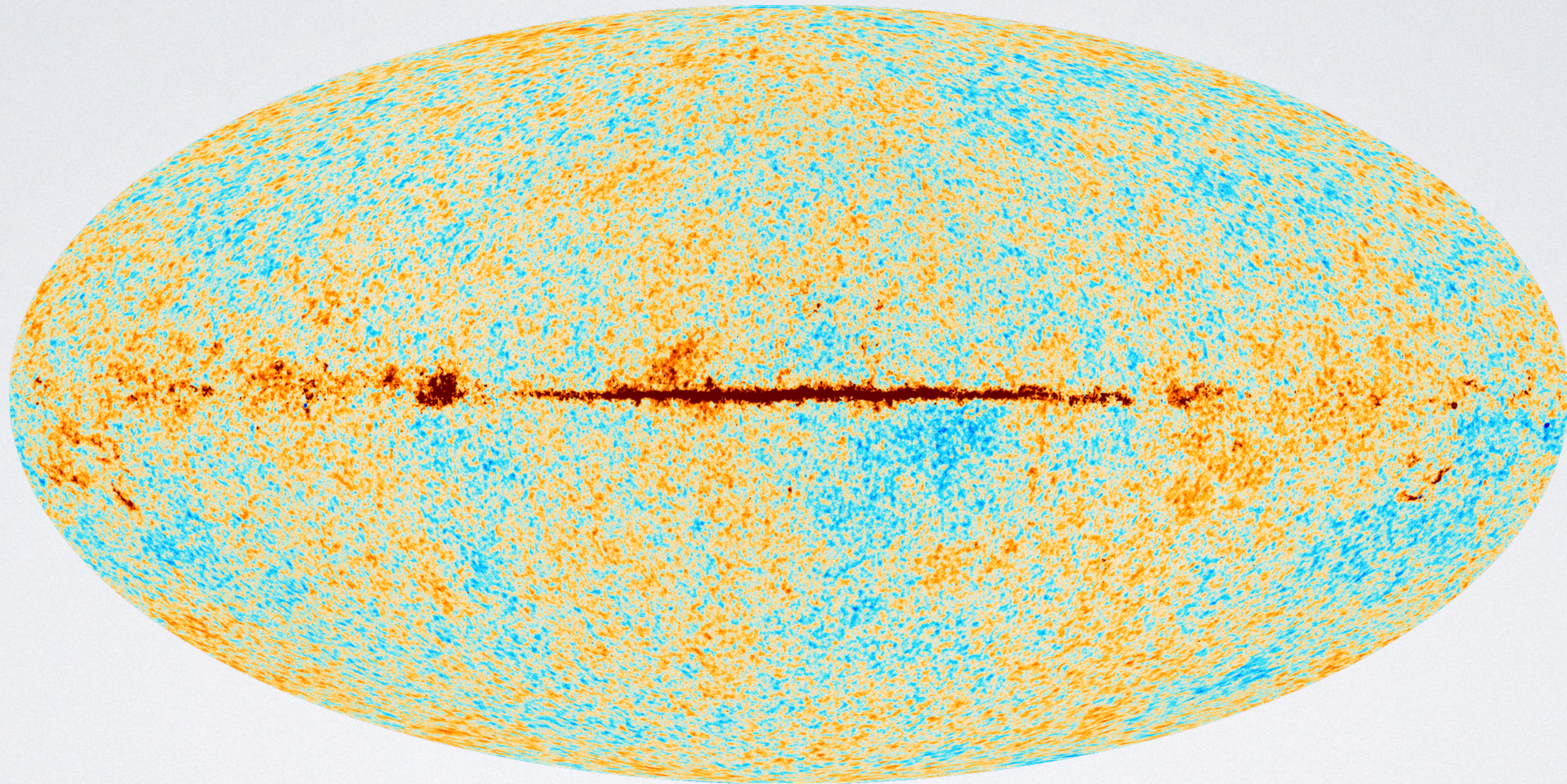


Download on the  
**Mac App Store**

# COMPONENT SEPARATION ON GPU

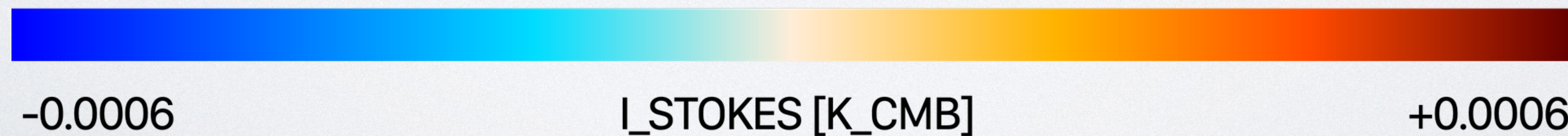
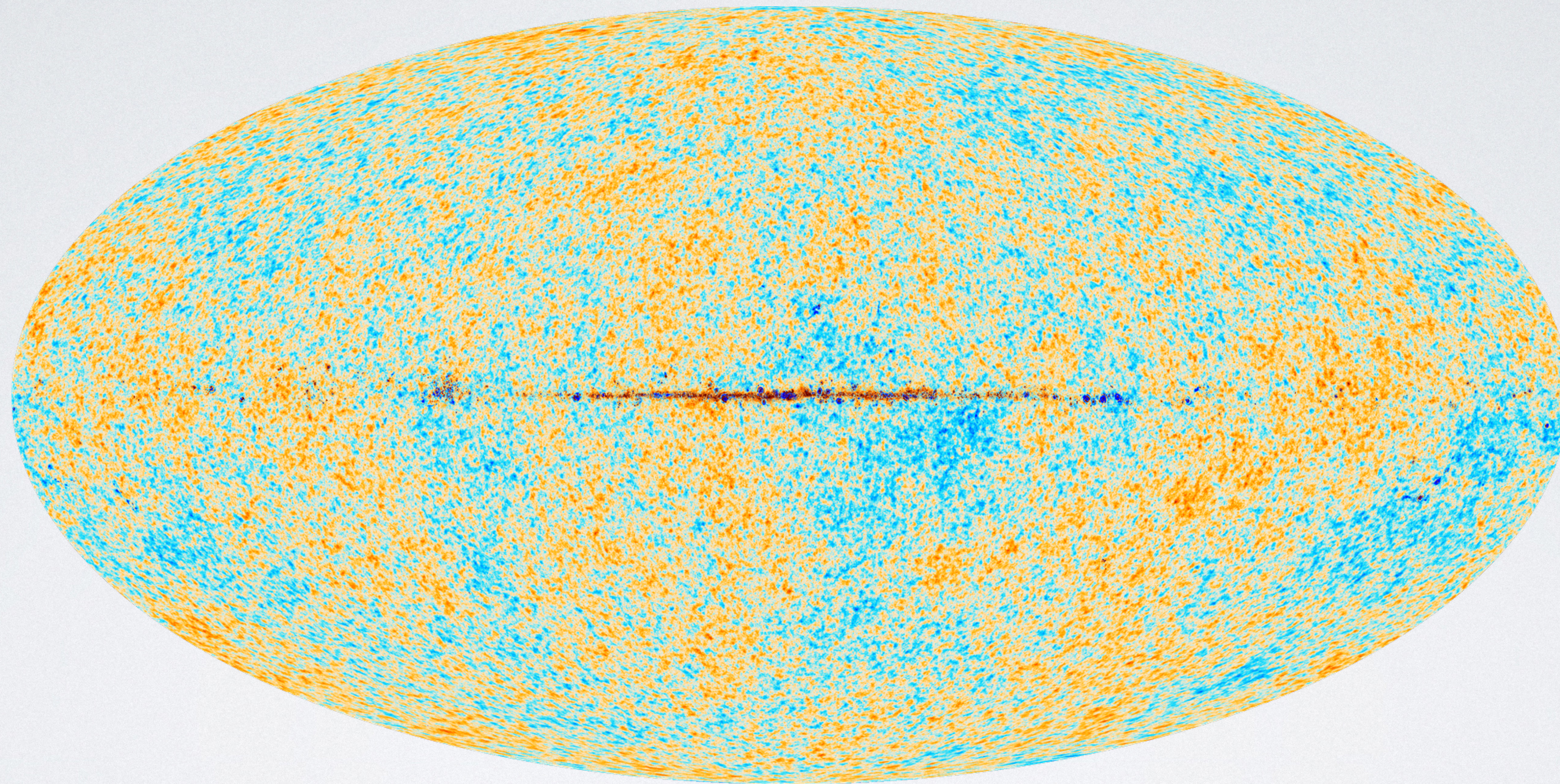
- Gibbs samplers are massively parallel - perfect fit for GPU...
- I coded up simplified (3 component, no beams) Commander model
- uses Barzilai-Borwein optimizer, can be extended with spatial priors
- takes 30ms to separate three  $n_{\text{side}}=2048$  maps on M1 laptop...
- this means you can do component separation in *real time* now!

# QUICK AND DIRTY (REAL TIME)



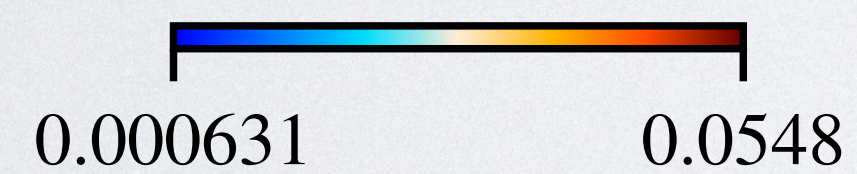
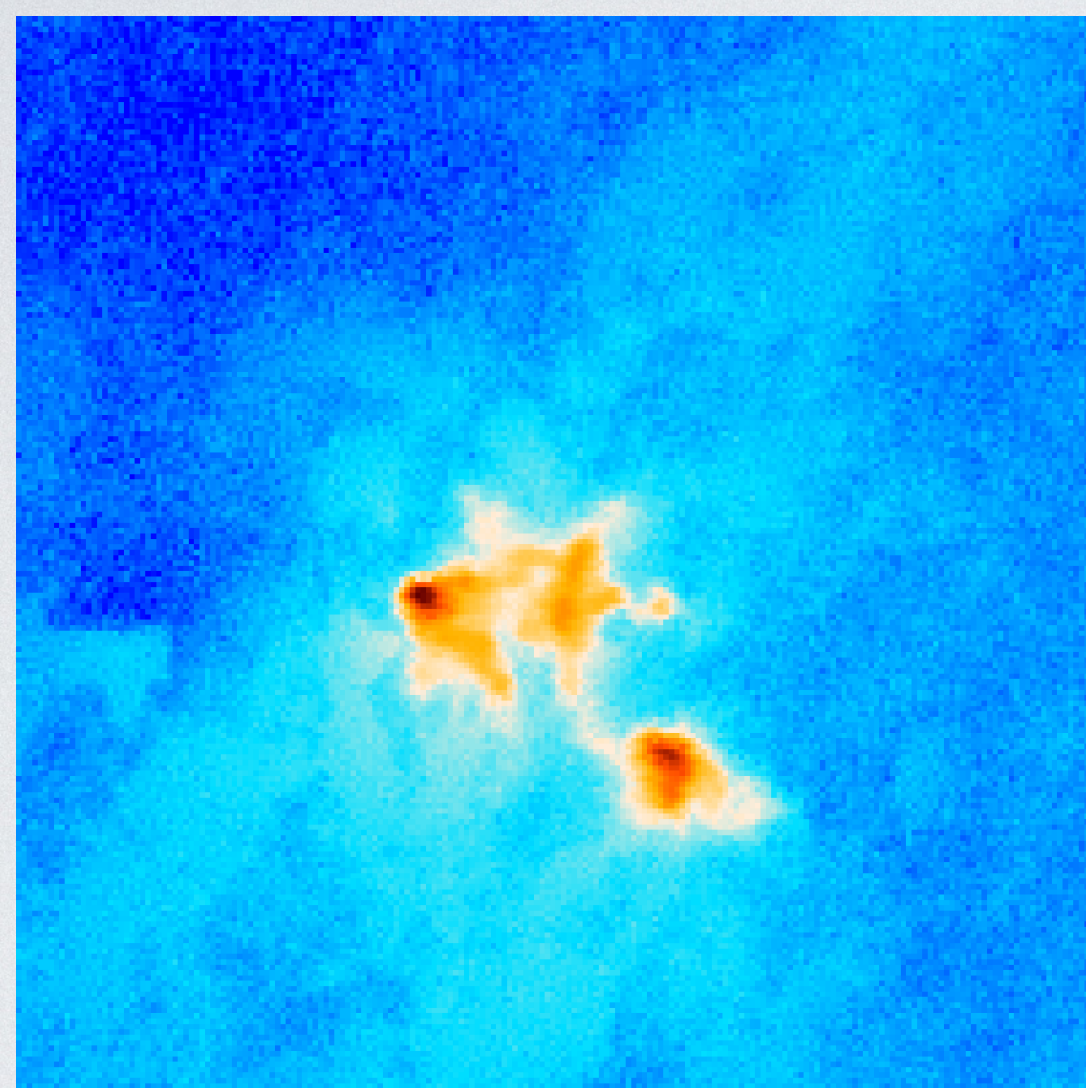


# COMMANDER 2018 (HOURS)

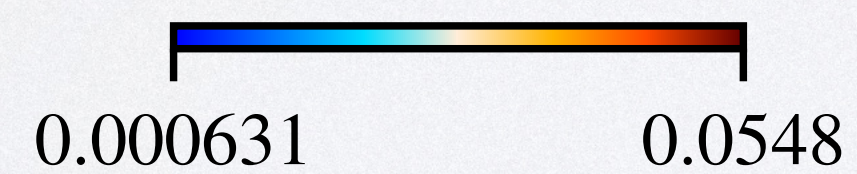
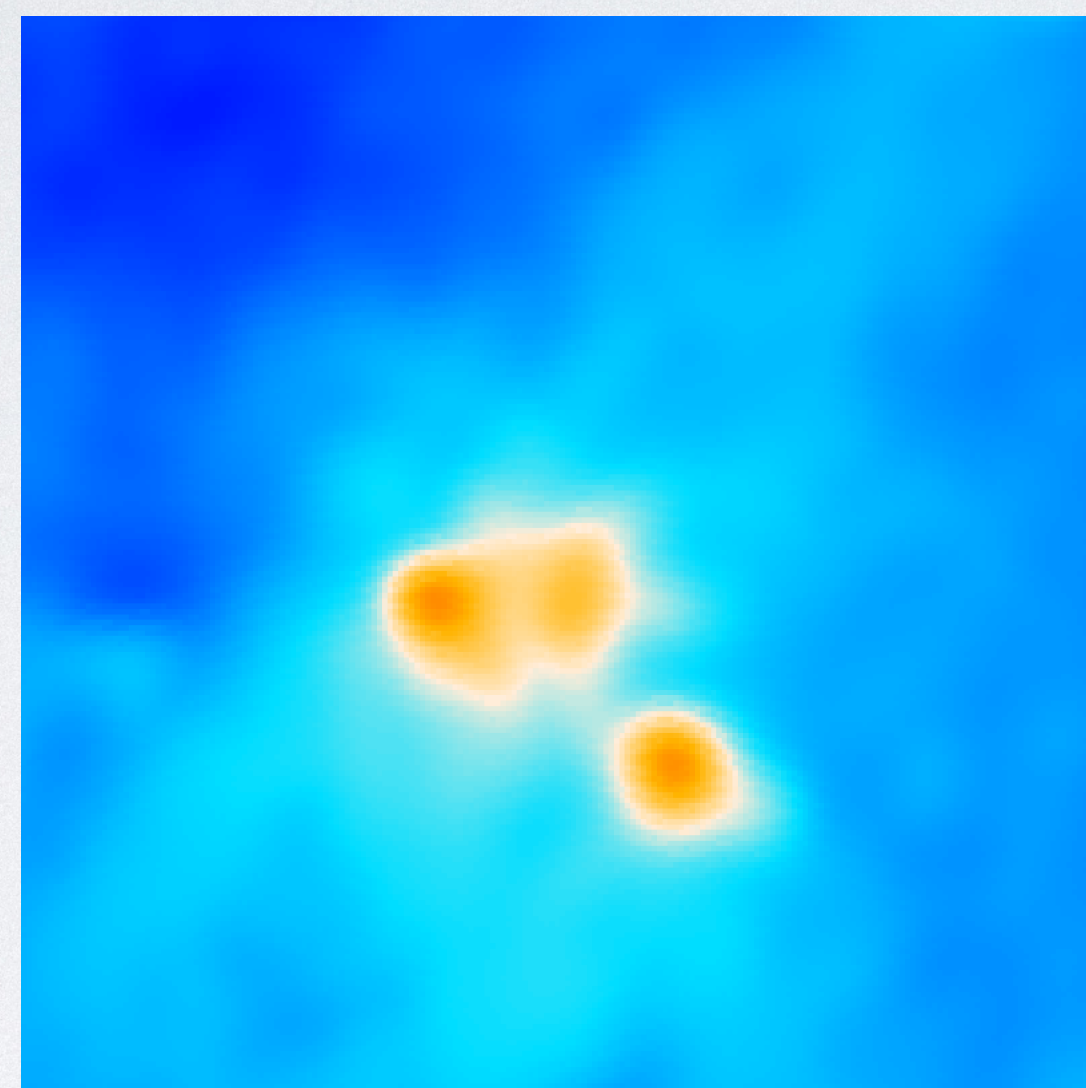


# QUICK ASIDE II - NON-LOCAL MEANS

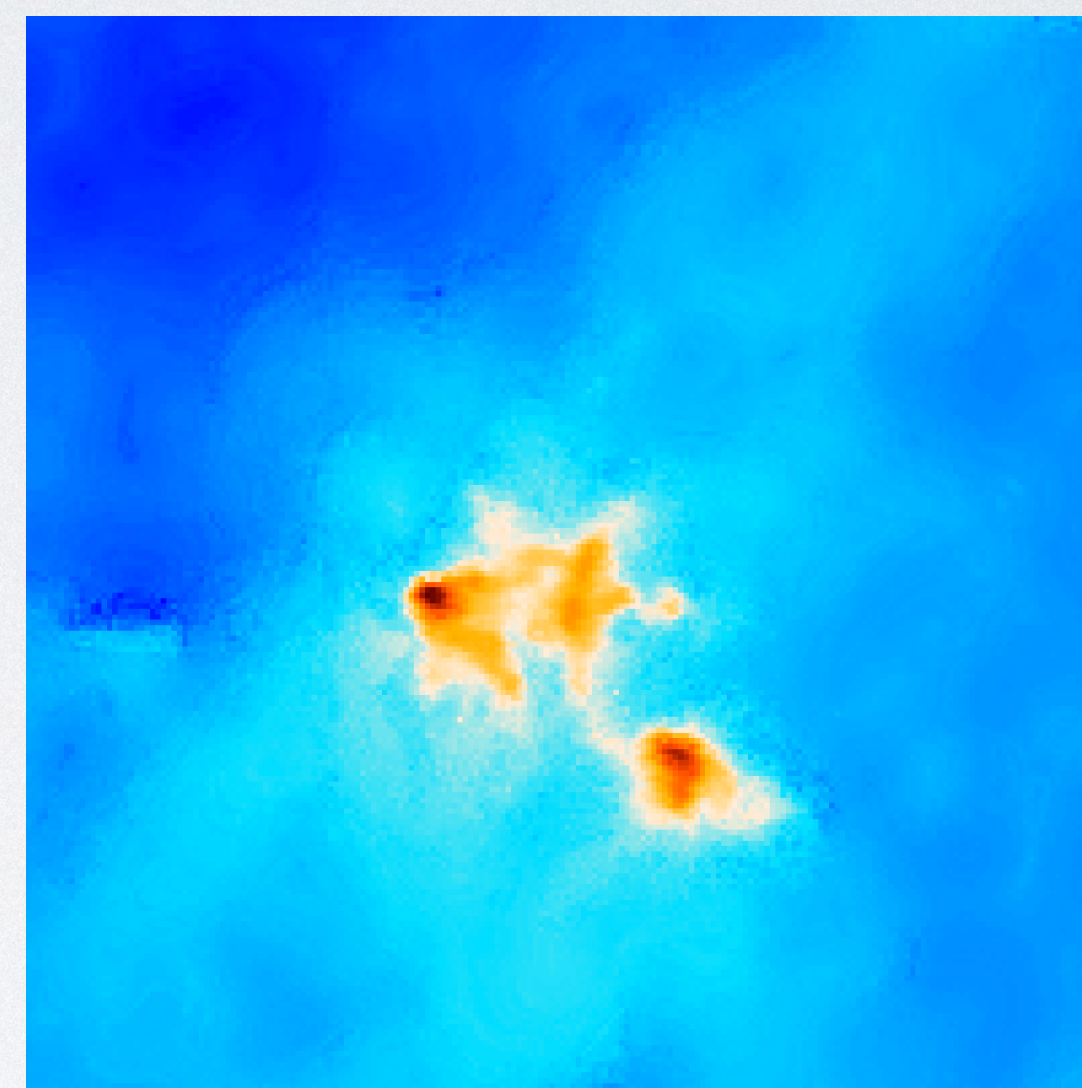
Input map



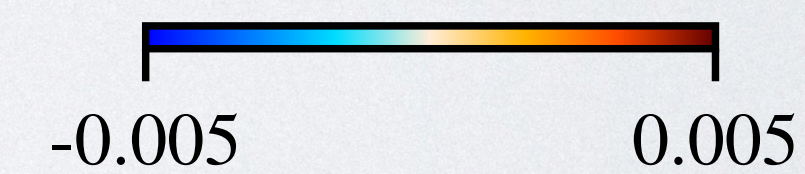
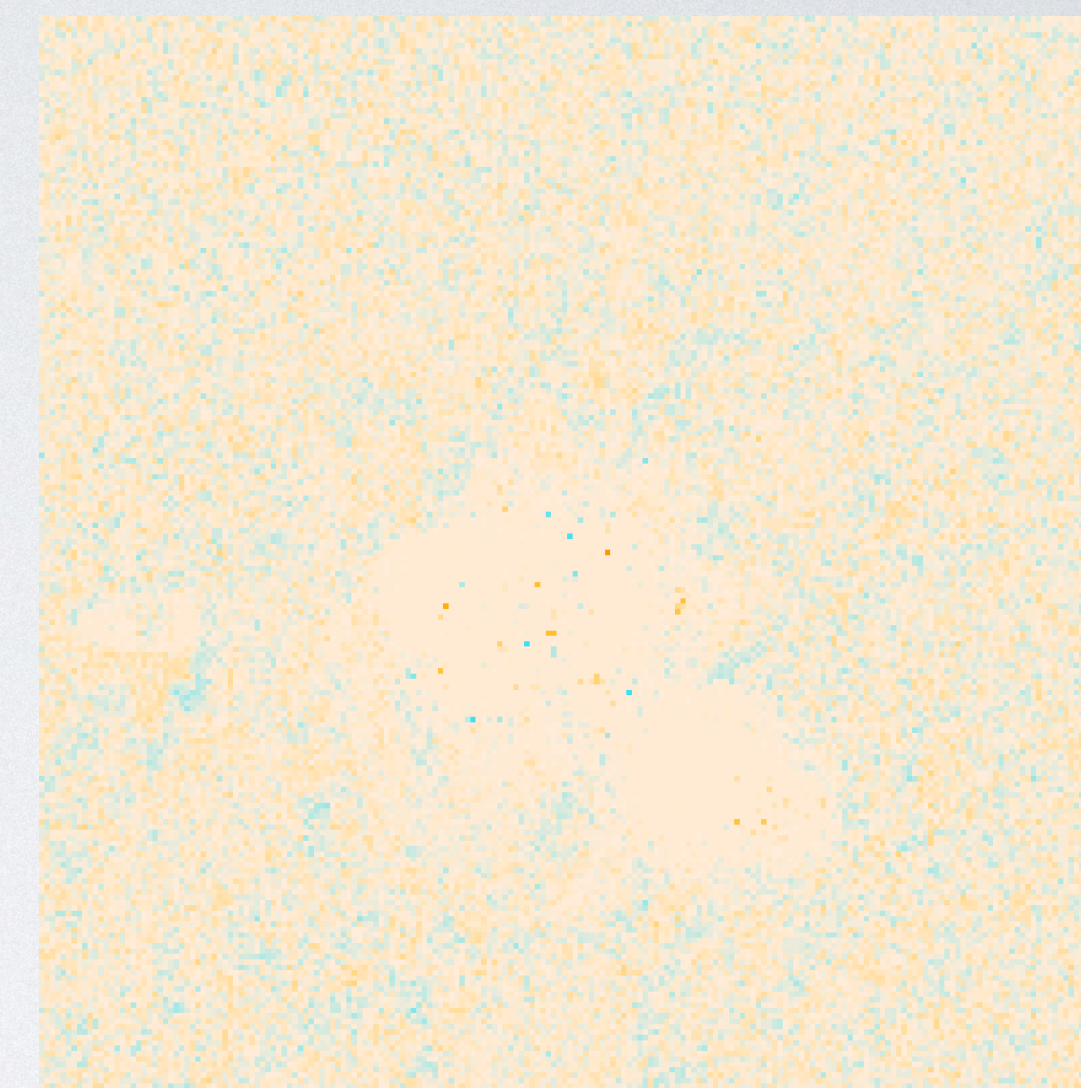
Gaussian-smoothing



Non-local means



Residual



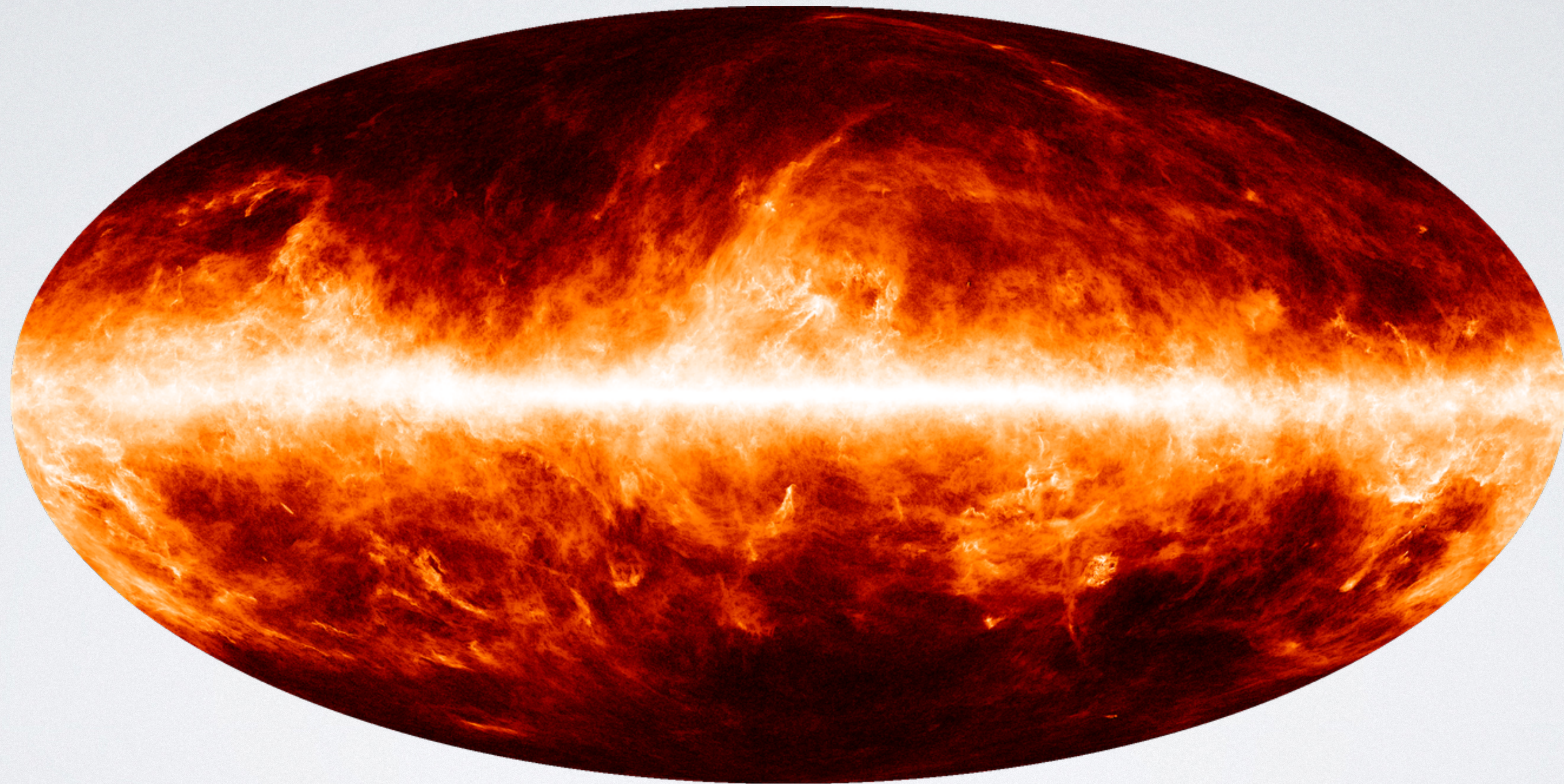
average smarter, not harder: average *similar* pixels, not *nearby* ones!

[arXiv:2306.00211](https://arxiv.org/abs/2306.00211)

# BACK TO FOREGROUNDS...

modelling large-scale polarized emission

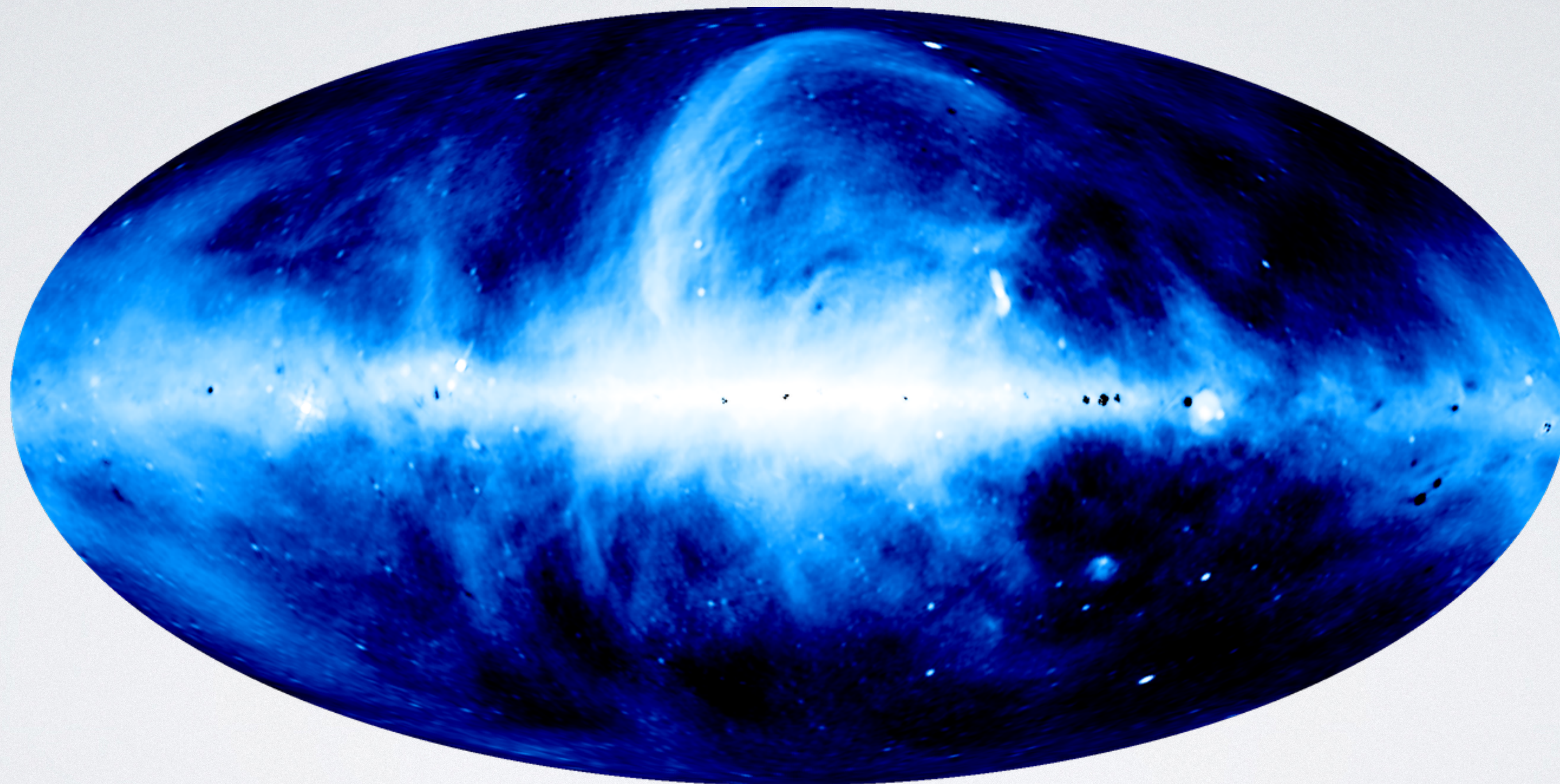
# THERMAL DUST EMISSION



+0

+1

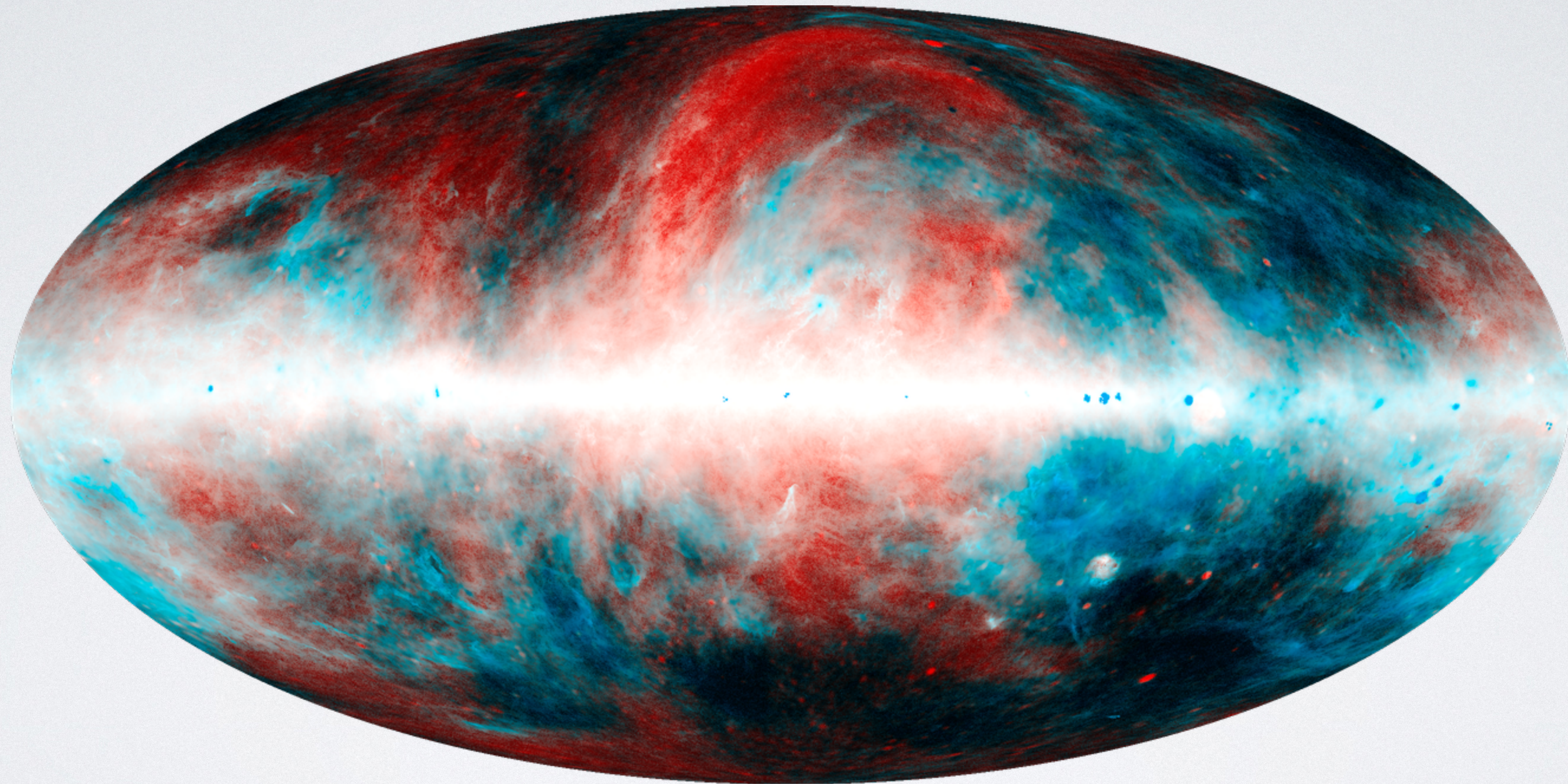
# SYNCHROTRON EMISSION



+0

+1

# DUST AND SYNCHROTRON



the intensity of two polarized foregrounds is not quite correlated!

# SHORT SUMMARY

- thermal dust is  $\sim 20\text{K}$  black body, modified by  $\sim 2.6$  power law
- intensity traces dust distribution (complicated, but optically thin),  
polarization fraction traces magnetic field configuration (simple)
- synchrotron is  $-3.1$  power law, extremely polarized
- intensity traces electron distribution (complicated, optically thick),  
polarization fraction traces magnetic field (averaged, not so simple)

# POLARIZED DUST EMISSION

- polarization is caused by grain alignment due to magnetic field:

$$I = \int S_\nu e^{-\tau_\nu} d\tau_\nu \left[ 1 - p_0 \left( \cos^2 \gamma - \frac{2}{3} \right) \right]$$

$$\begin{pmatrix} Q \\ U \end{pmatrix} = \int S_\nu e^{-\tau_\nu} d\tau_\nu \begin{pmatrix} \cos 2\psi \\ \sin 2\psi \end{pmatrix} p_0 \cos^2 \gamma$$

$p_0$  is intrinsic polarization fraction  $\sim 0.2$ ,  $\gamma$  and  $\psi$  are angles of magnetic field



# POLARIZED DUST EMISSION

- geometric factors in emission integral from magnetic field orientation:

$$\mathfrak{p} \equiv \frac{B_{\phi}^2 + B_{\theta}^2}{B^2} = \cos^2 \gamma$$

$$\mathfrak{q} \equiv \frac{B_{\phi}^2 - B_{\theta}^2}{B^2} = \cos^2 \gamma \cos 2\psi$$

$$\mathfrak{u} \equiv -\frac{2B_{\phi}B_{\theta}}{B^2} = \cos^2 \gamma \sin 2\psi$$

# MAGNETIC FIELD MODEL

- split magnetic field into large-scale and random components:

$$\mathbf{B} = \bar{\mathbf{B}} + \delta\mathbf{B}$$

- dust samples magnetic field, giving *average* geometric factors

$$\langle X \rangle = \frac{1}{s_\nu} \int S_\nu e^{-\tau_\nu} d\tau_\nu X, \quad s_\nu = \int S_\nu e^{-\tau_\nu} d\tau_\nu$$

- all complexity is in dust column density distribution, fit large-scale  $\bar{\mathbf{B}}$ !

# EXPANDING TO LINEAR ORDER...

- intensity and polarization split into large-scale and random parts:

$$I = s_\nu \left( 1 + \frac{2}{3} p_0 \right) - s_\nu p_0 \left[ \mathbf{p}[\bar{\mathbf{B}}] + \frac{\partial \mathbf{p}}{\partial \mathbf{B}} \Big|_{\bar{\mathbf{B}}} \langle \delta \mathbf{B} \rangle + \dots \right]$$

$$Q = s_\nu p_0 \left[ \mathbf{q}[\bar{\mathbf{B}}] + \frac{\partial \mathbf{q}}{\partial \mathbf{B}} \Big|_{\bar{\mathbf{B}}} \langle \delta \mathbf{B} \rangle + \dots \right]$$

$$U = s_\nu p_0 \left[ \mathbf{u}[\bar{\mathbf{B}}] + \frac{\partial \mathbf{u}}{\partial \mathbf{B}} \Big|_{\bar{\mathbf{B}}} \langle \delta \mathbf{B} \rangle + \dots \right]$$

# ESTIMATORS OF MAGNETIC FIELD

- estimator of dust column depth:  $I + P = s_\nu \left( 1 + \frac{2}{3} p_0 \right) + O(\delta B^2)$
- estimators of magnetic field geometry:

$$\tilde{q} \equiv \frac{Q}{I + P} = \frac{3p_0}{3 + 2p_0} \left[ \mathbf{q}[\bar{\mathbf{B}}] + \frac{\partial \mathbf{q}}{\partial \mathbf{B}} \Big|_{\bar{\mathbf{B}}} \langle \delta \mathbf{B} \rangle + \dots \right]$$

$$\tilde{u} \equiv \frac{Q}{I + P} = \frac{3p_0}{3 + 2p_0} \left[ \mathbf{u}[\bar{\mathbf{B}}] + \frac{\partial \mathbf{u}}{\partial \mathbf{B}} \Big|_{\bar{\mathbf{B}}} \langle \delta \mathbf{B} \rangle + \dots \right]$$

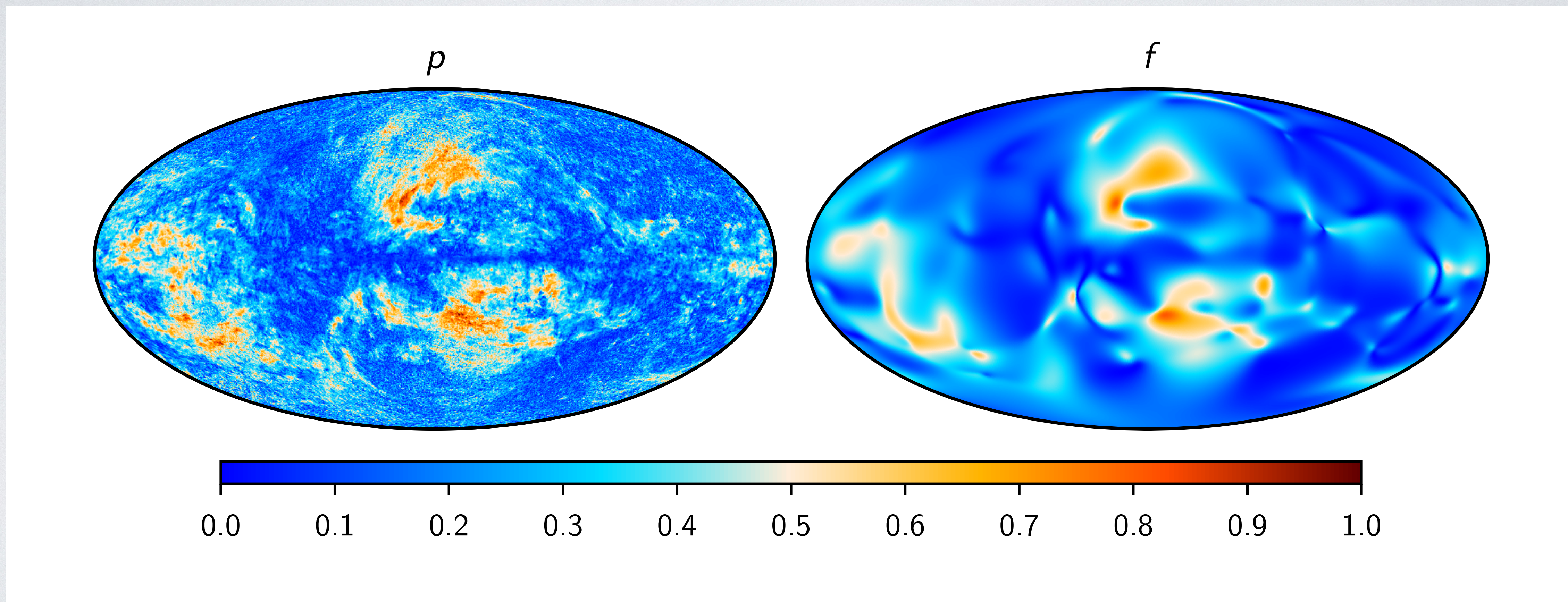
# MAGNETIC FIELD RECONSTRUCTION

- one can fit large-scale (smooth) magnetic field optimizing

$$\chi_{\bar{\mathbf{B}}}^2 = \left( \tilde{q} - \varepsilon \mathbf{q}[\bar{\mathbf{B}}] \right)^2 + \left( \tilde{u} - \varepsilon \mathbf{u}[\bar{\mathbf{B}}] \right)^2, \quad \varepsilon = \frac{3p_0}{3 + 2p_0}$$

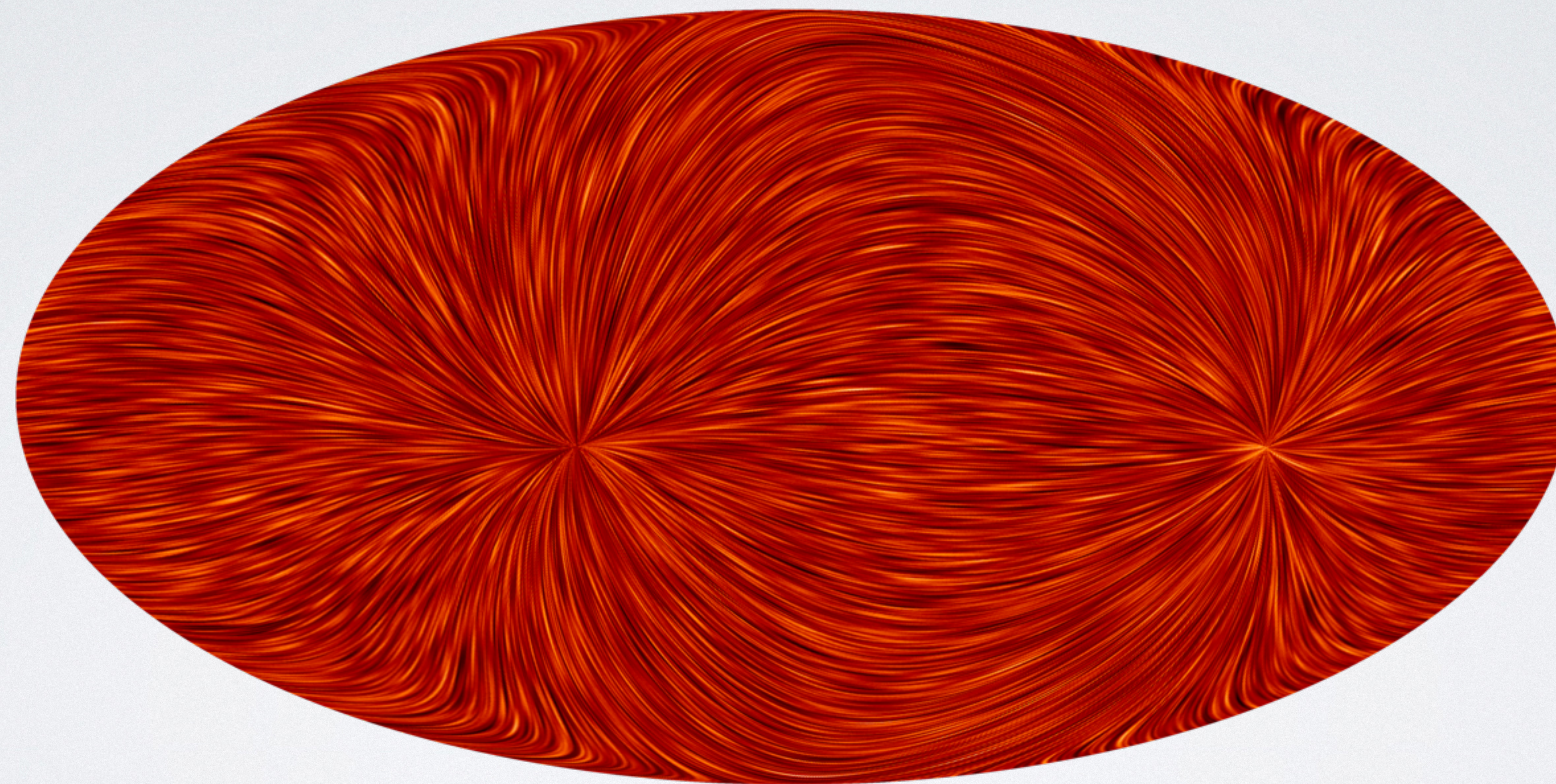
- optimization problem is large, use L-BFGS-B optimizer and wait...
- this seems a bit simple-minded, but it works! but why?...
- looks like dust does not have too much averaging along line of sight, samples magnetic field mostly from a single layer...

# MAGNETIC FIELD RECONSTRUCTION



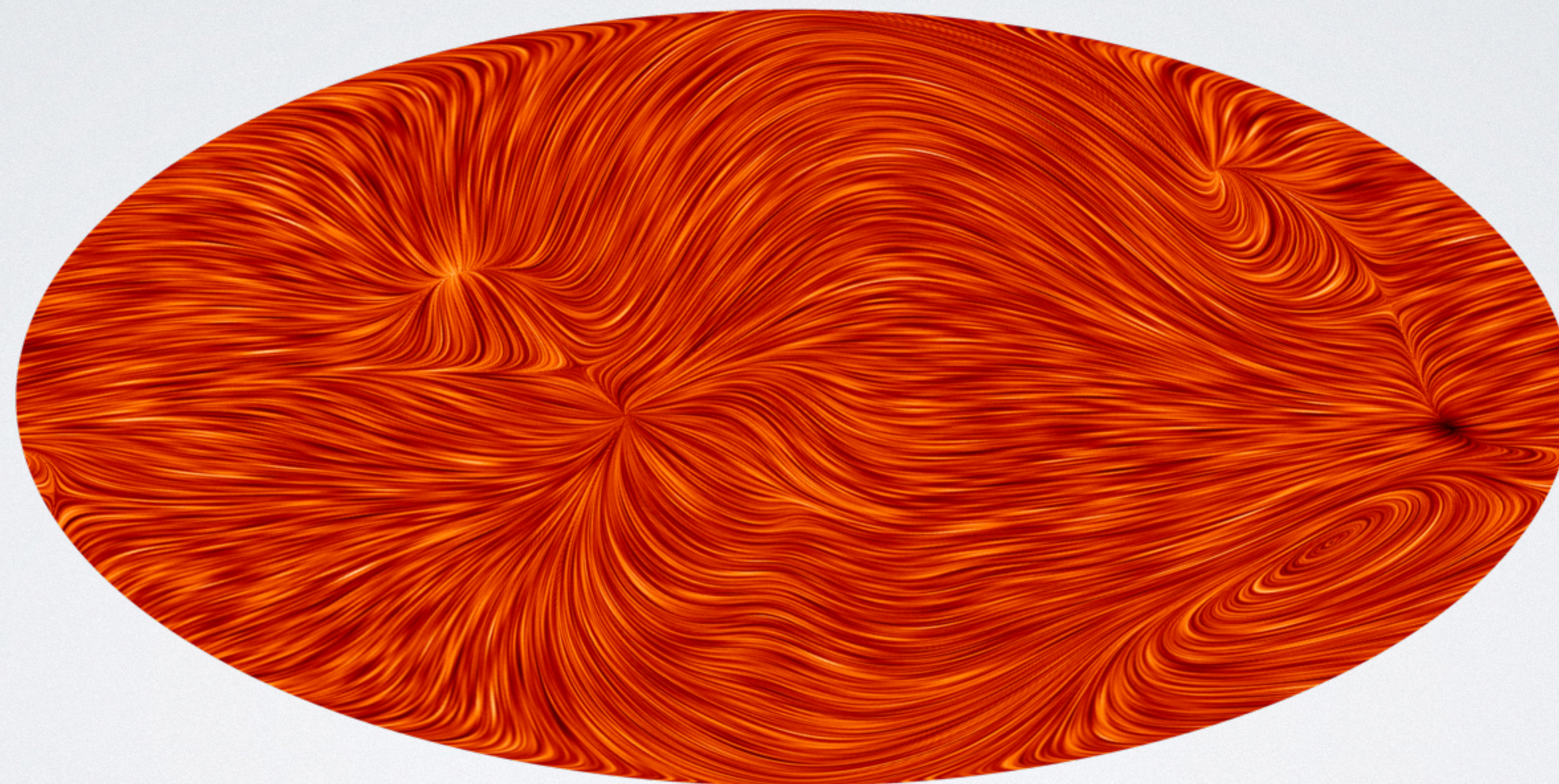
polarization fraction in 353 GHz dust map versus reconstruction with  $\ell_{\max} = 15$

# MAGNETIC FIELD LINES



$$\ell_{\max} = 1$$

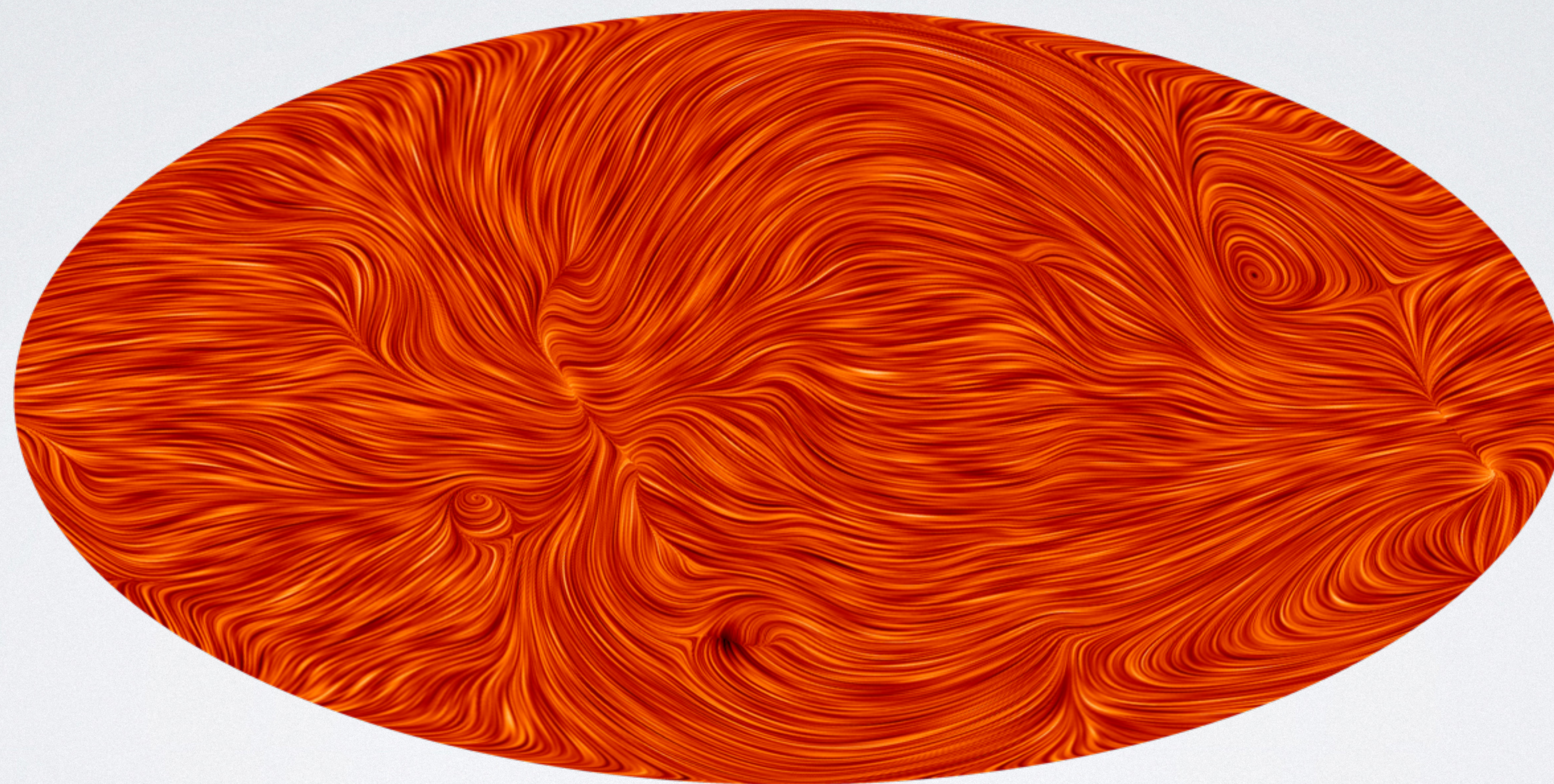
# MAGNETIC FIELD LINES



$$\ell_{\max} = 5$$

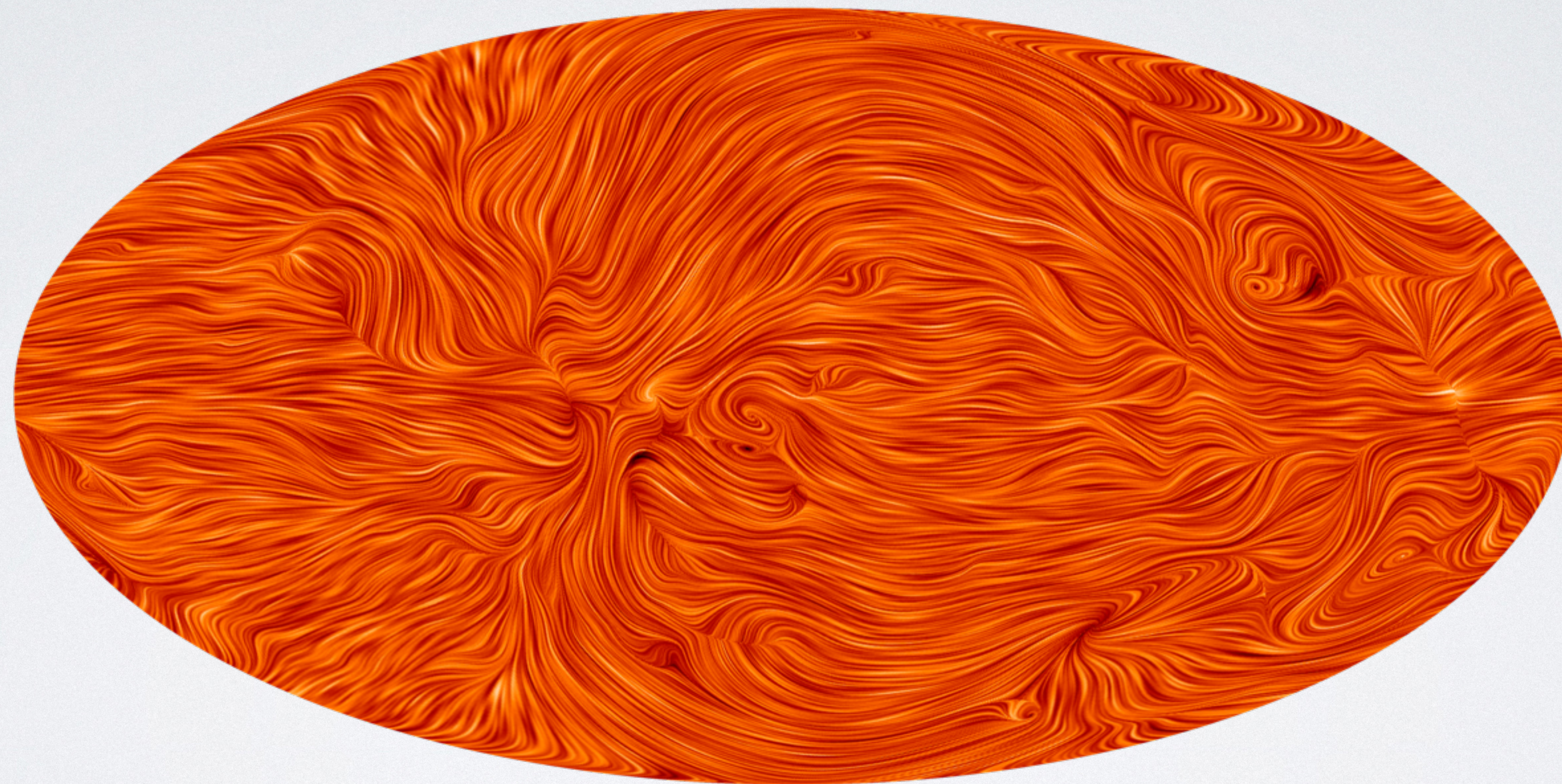


# MAGNETIC FIELD LINES



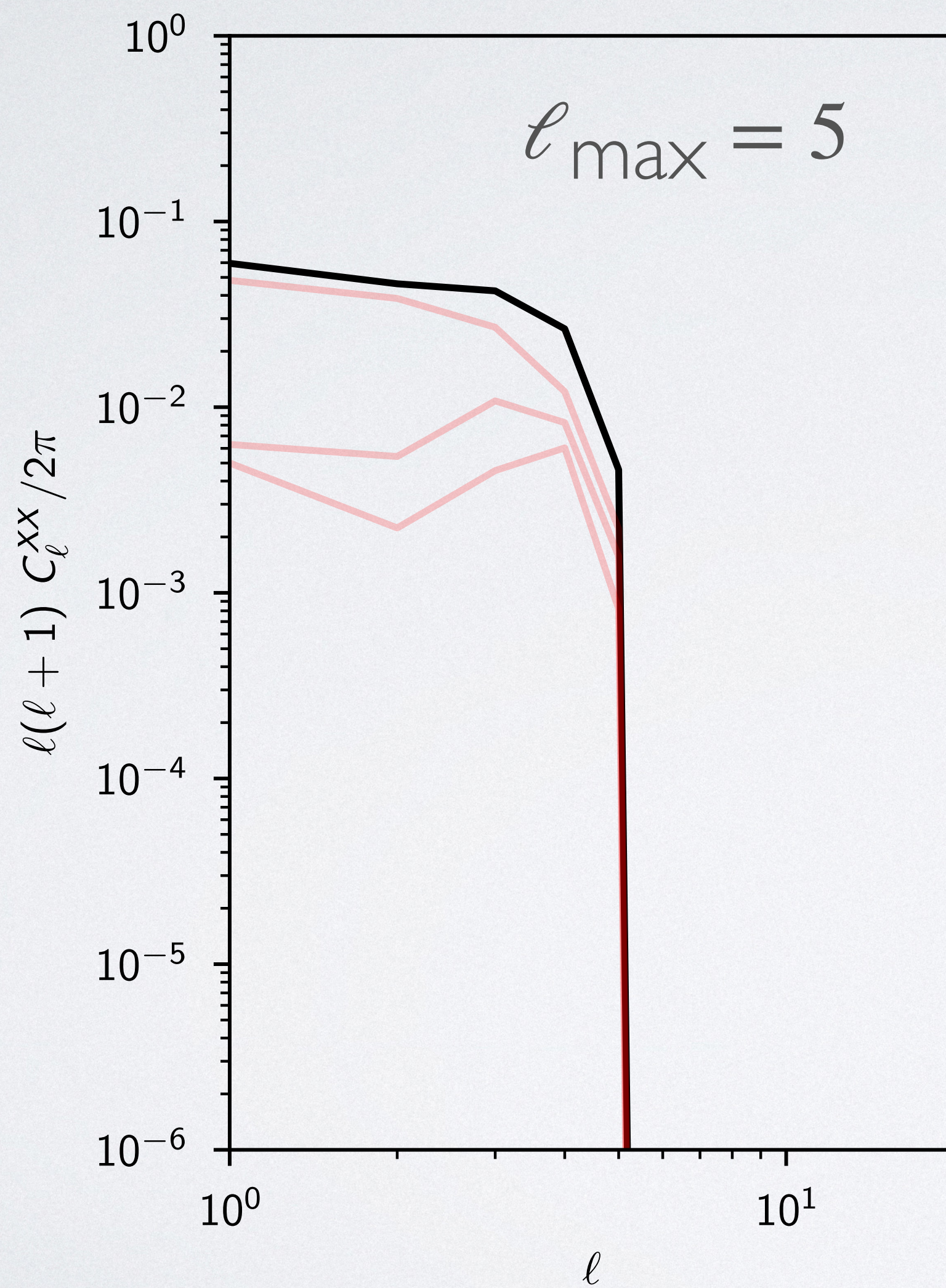
$$\ell_{\max} = 10$$

# MAGNETIC FIELD LINES

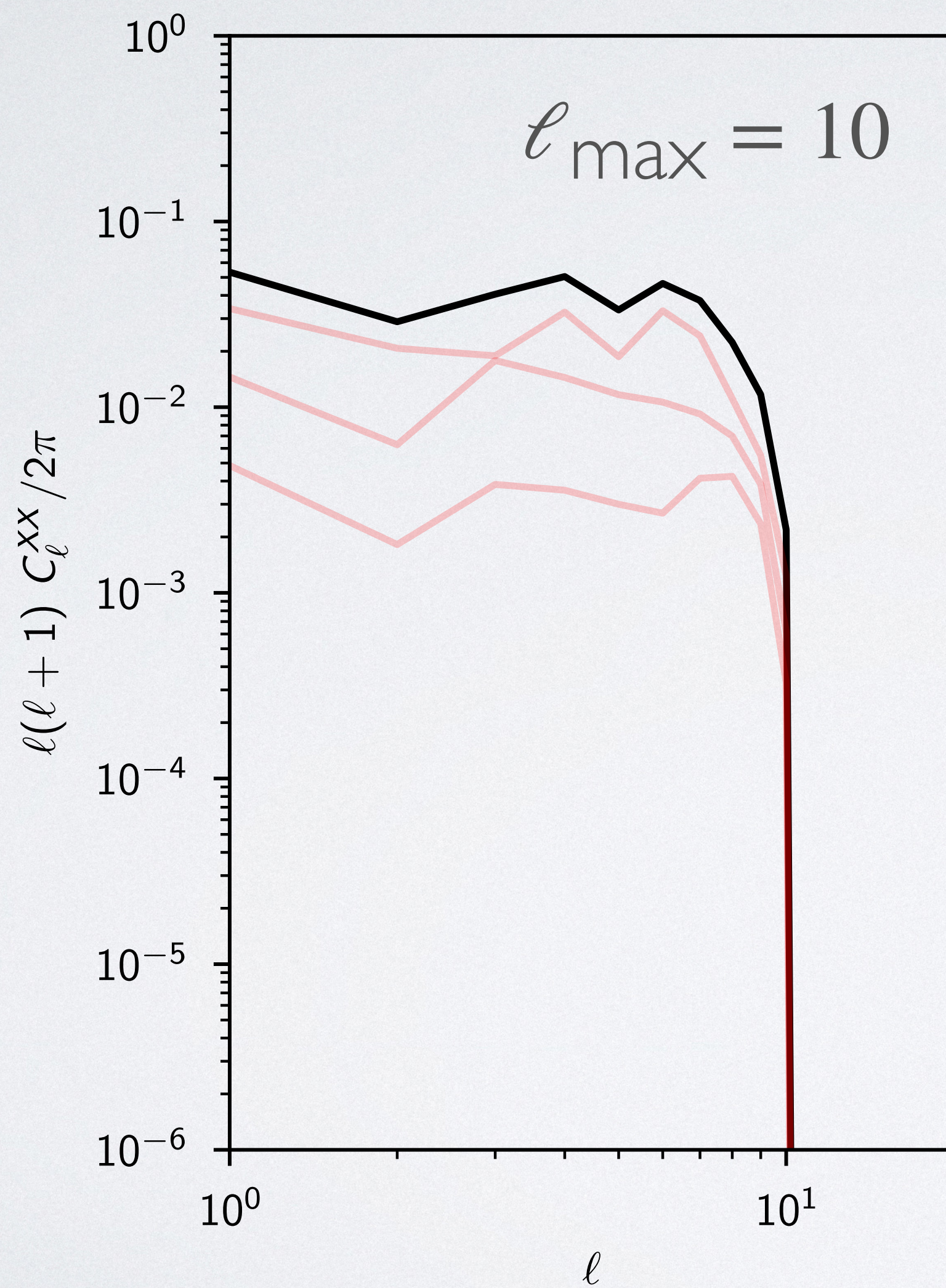


$$\ell_{\max} = 20$$

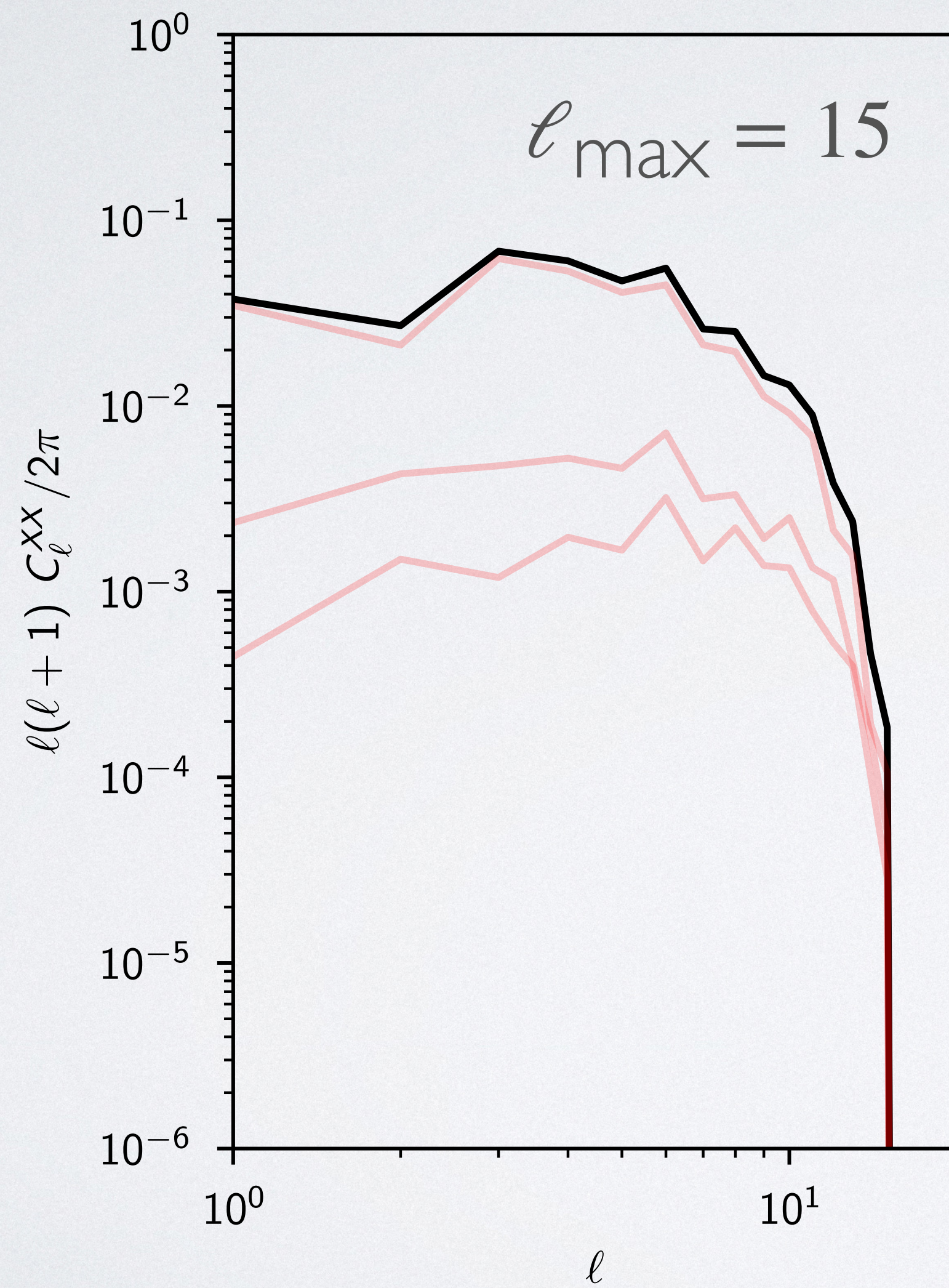
# RECONSTRUCTED SPECTRUM



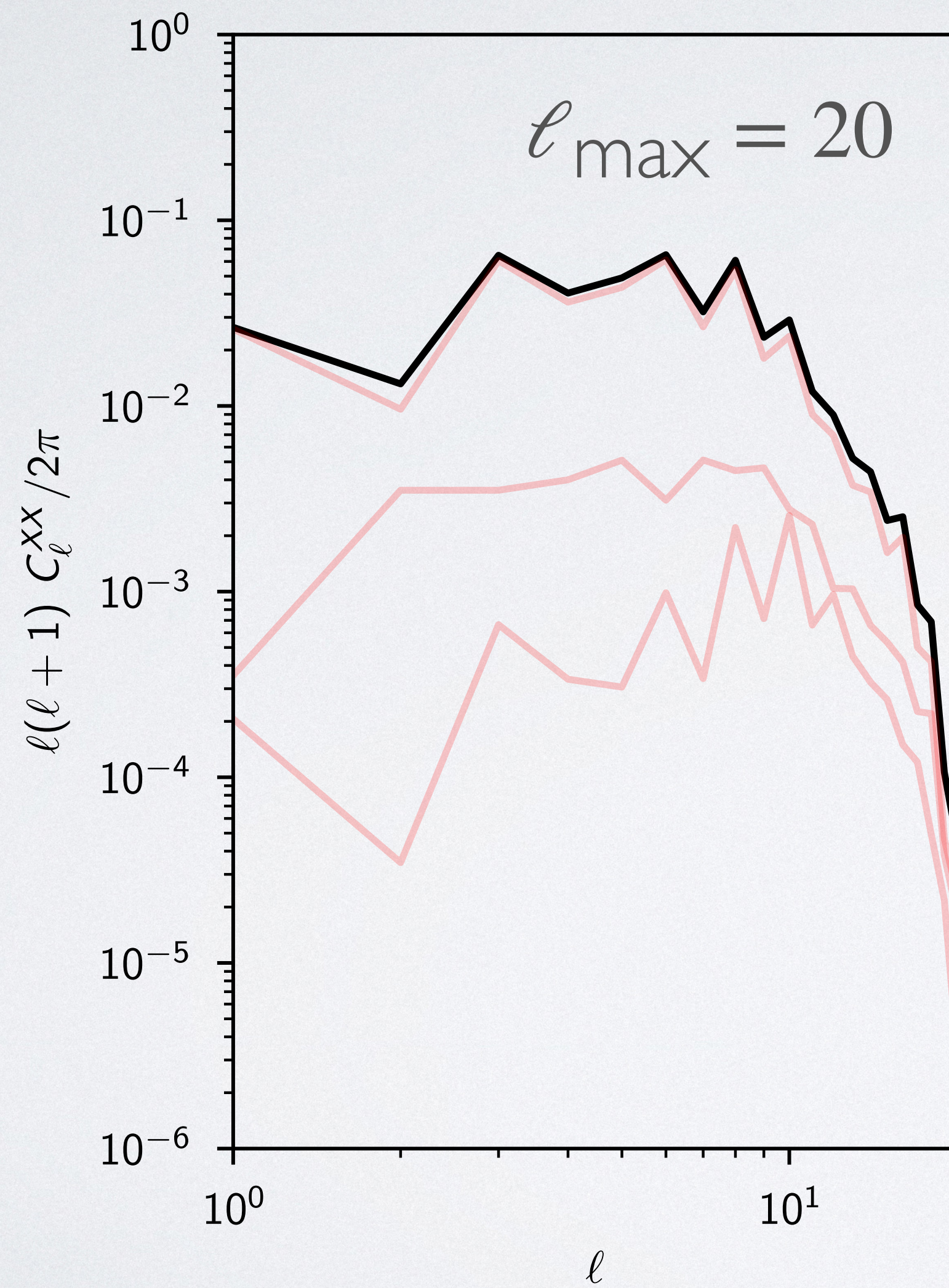
# RECONSTRUCTED SPECTRUM



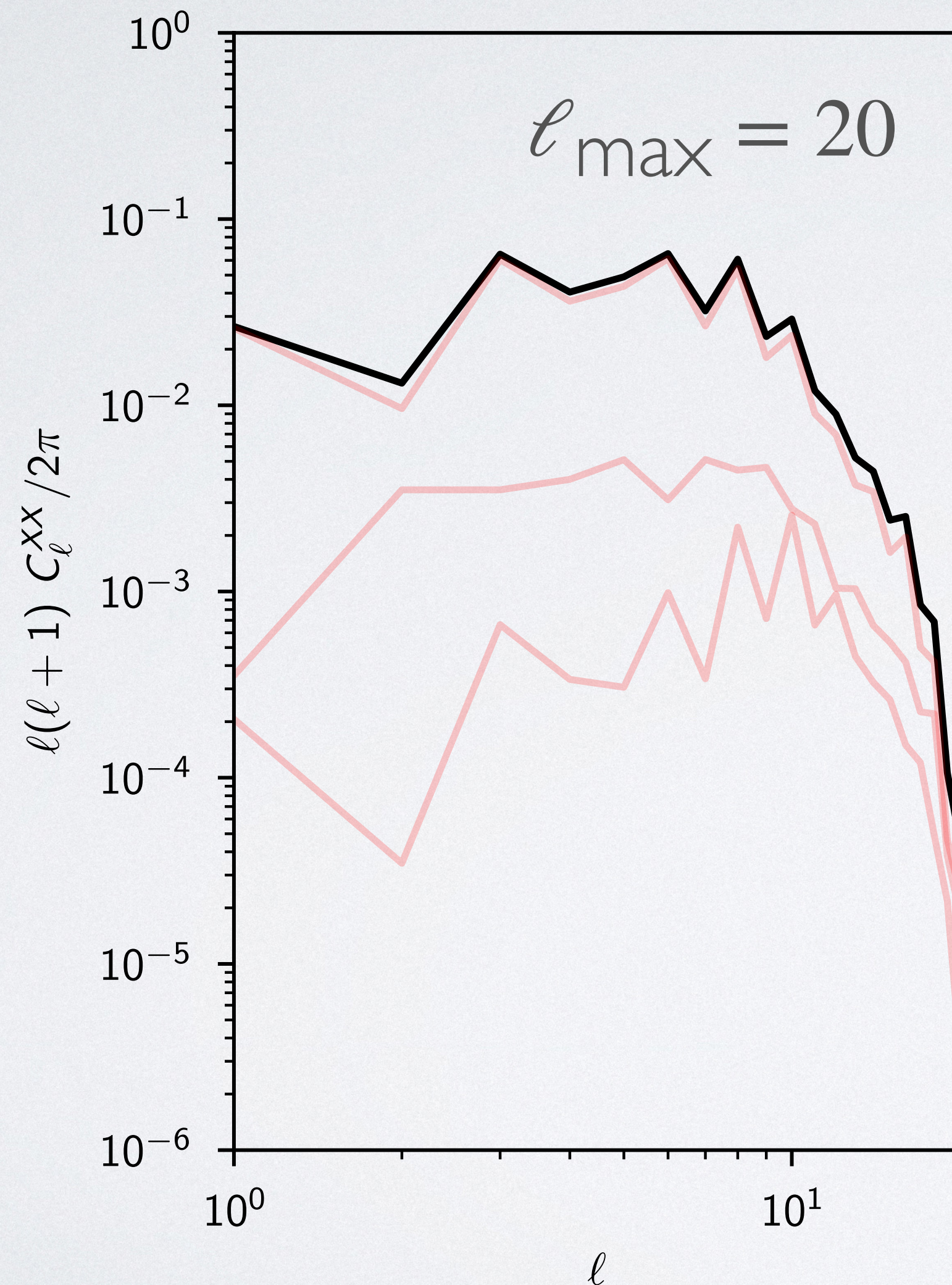
# RECONSTRUCTED SPECTRUM



# RECONSTRUCTED SPECTRUM



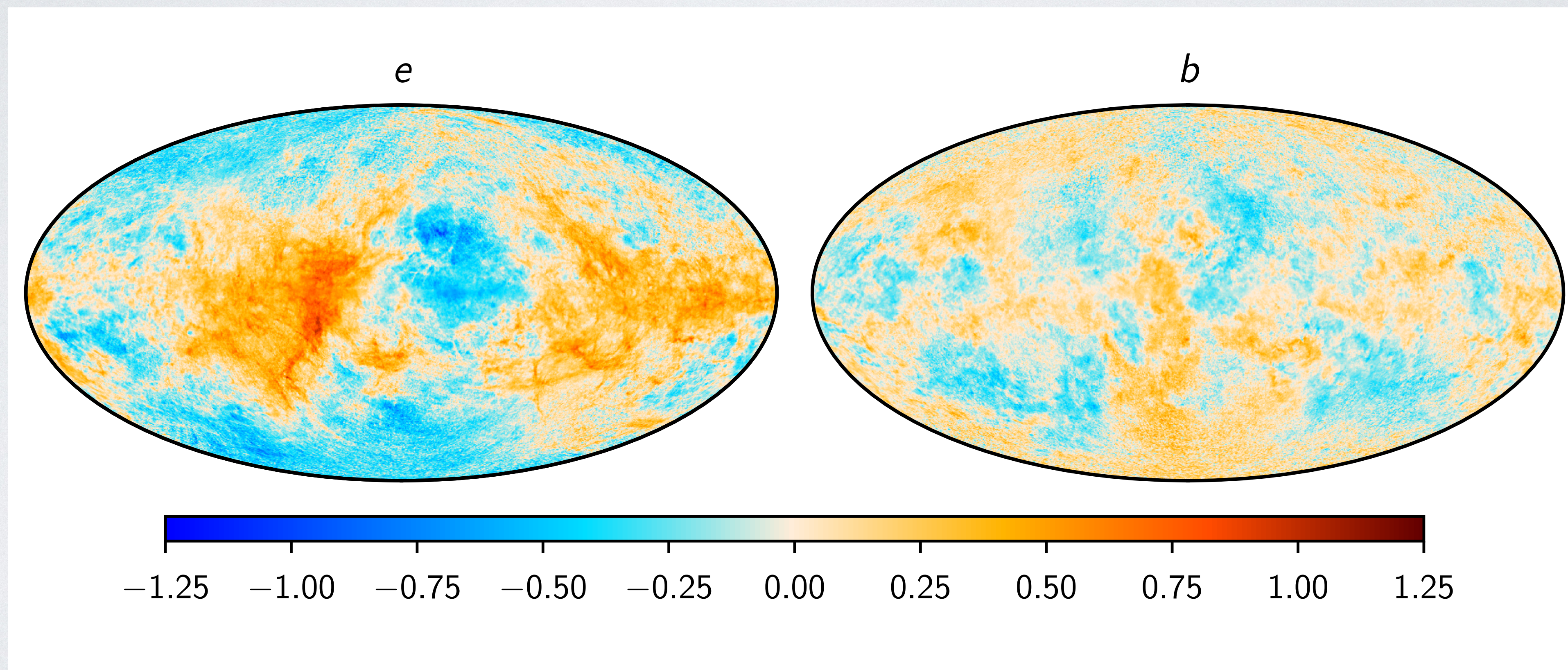
# RECONSTRUCTED SPECTRUM



there seems to be  
a break at  $\ell \sim 10!$

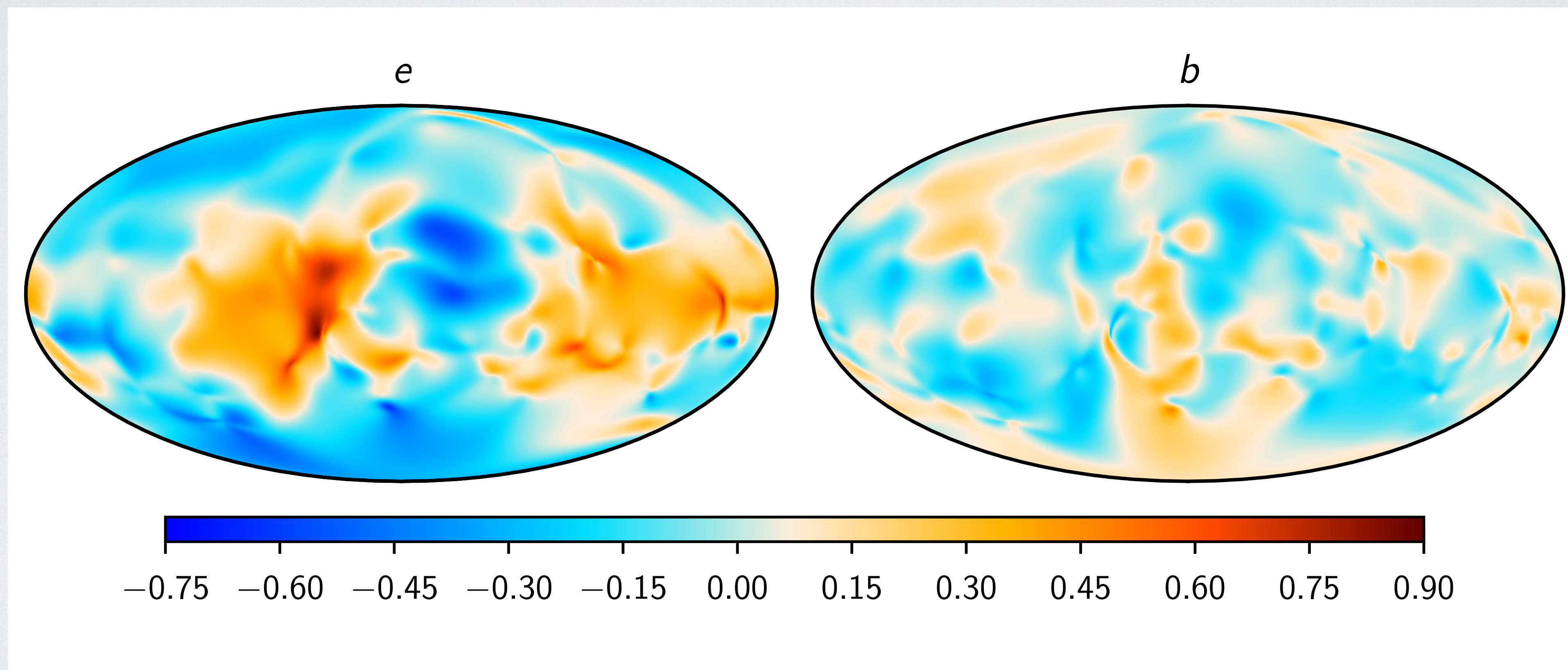
large scale (local)  
and turbulent  
components?

# DUST POLARIZATION FRACTION

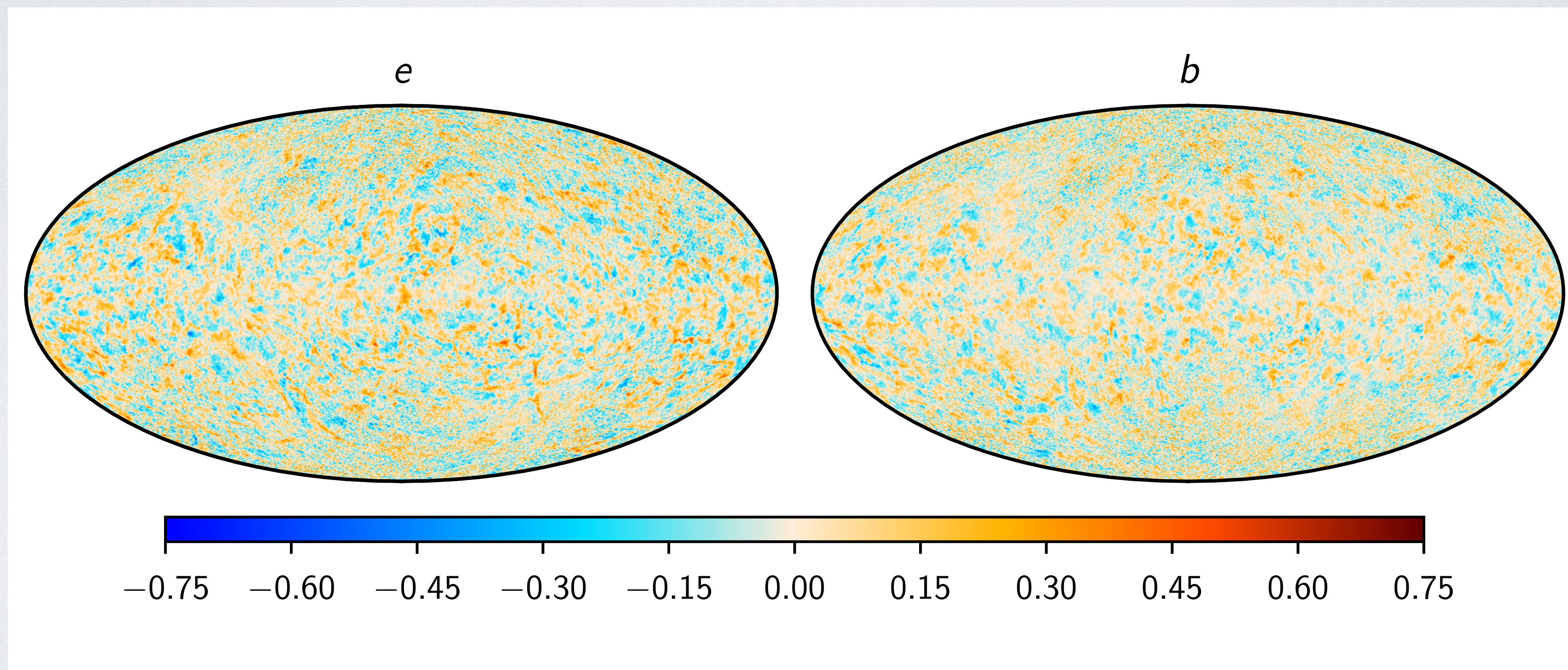




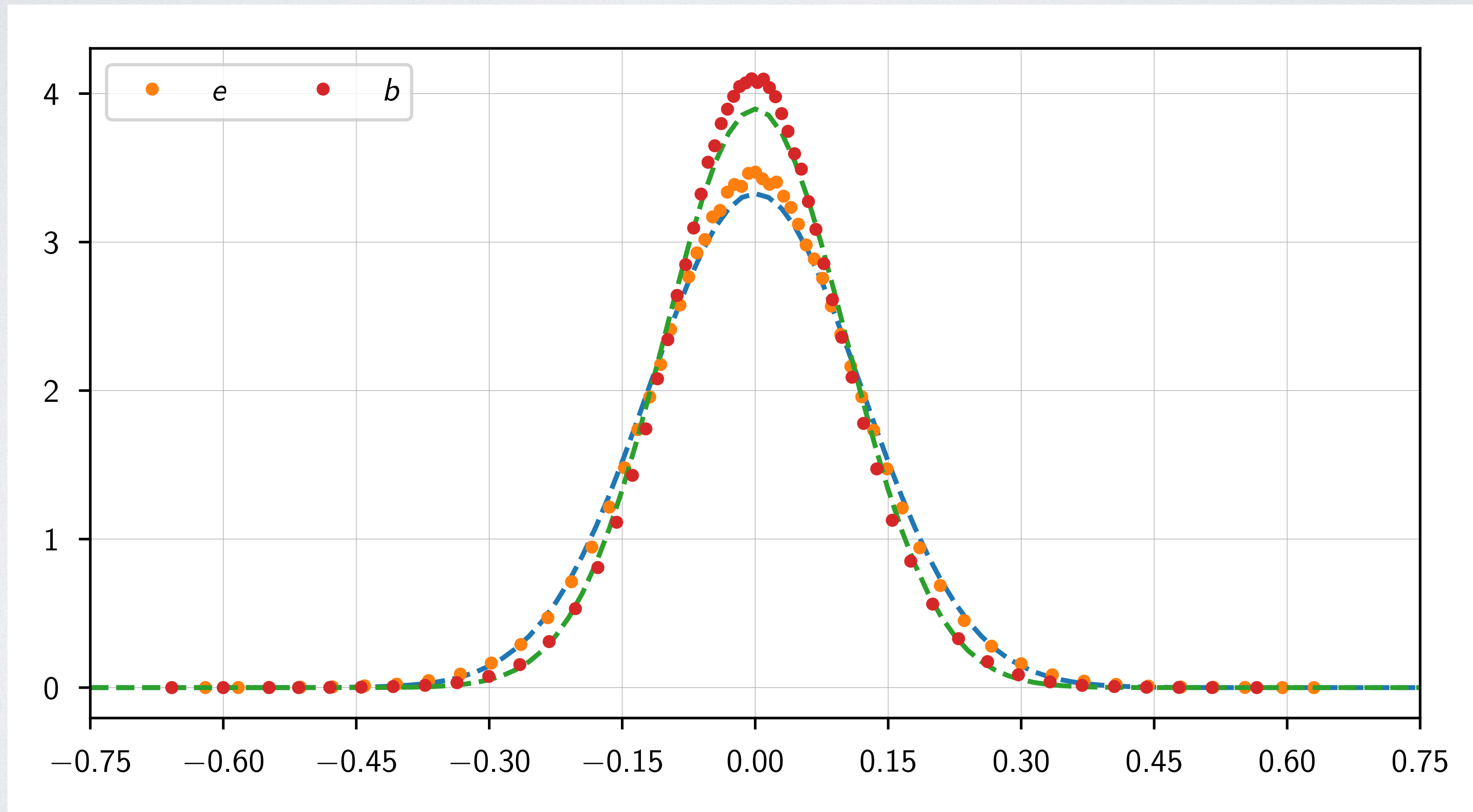
# LARGE SCALE COMPONENT



# TURBULENT COMPONENT



# RANDOM PART IS QUITE GAUSSIAN!



# DUST POLARIZATION IS SIMPLE!

large-scale spatial template common to all frequency channels,  
can be extracted (and reliably subtracted), residual is Gaussian!

# SYNCHROTRON IS NOT SO SIMPLE...

- synchrotron polarization also depends on magnetic field, but sampled by electron density, and it does depend on field magnitude...
- polarization fraction is reduced by averaging along the line of sight, getting explicit reconstruction is more complicated...
- logarithmic variables are still the best to describe map statistics

# POLARIZATION FRACTION TENSOR

- transform polarization tensor into polarization fraction tensor:

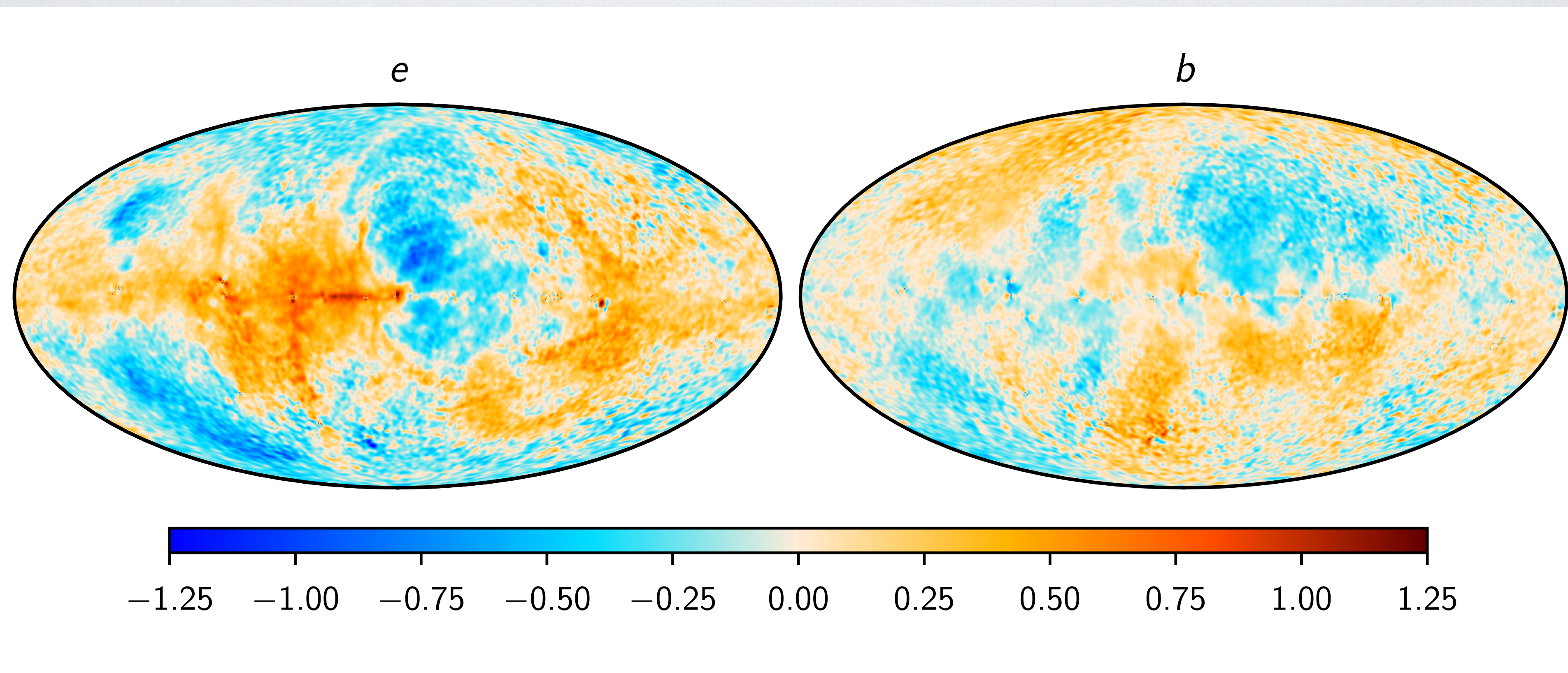
$$\begin{bmatrix} i + q & u \\ u & i - q \end{bmatrix} = \ln \begin{bmatrix} I + Q & U \\ U & I - Q \end{bmatrix}$$

- this is an invertible transformation on IQU maps:

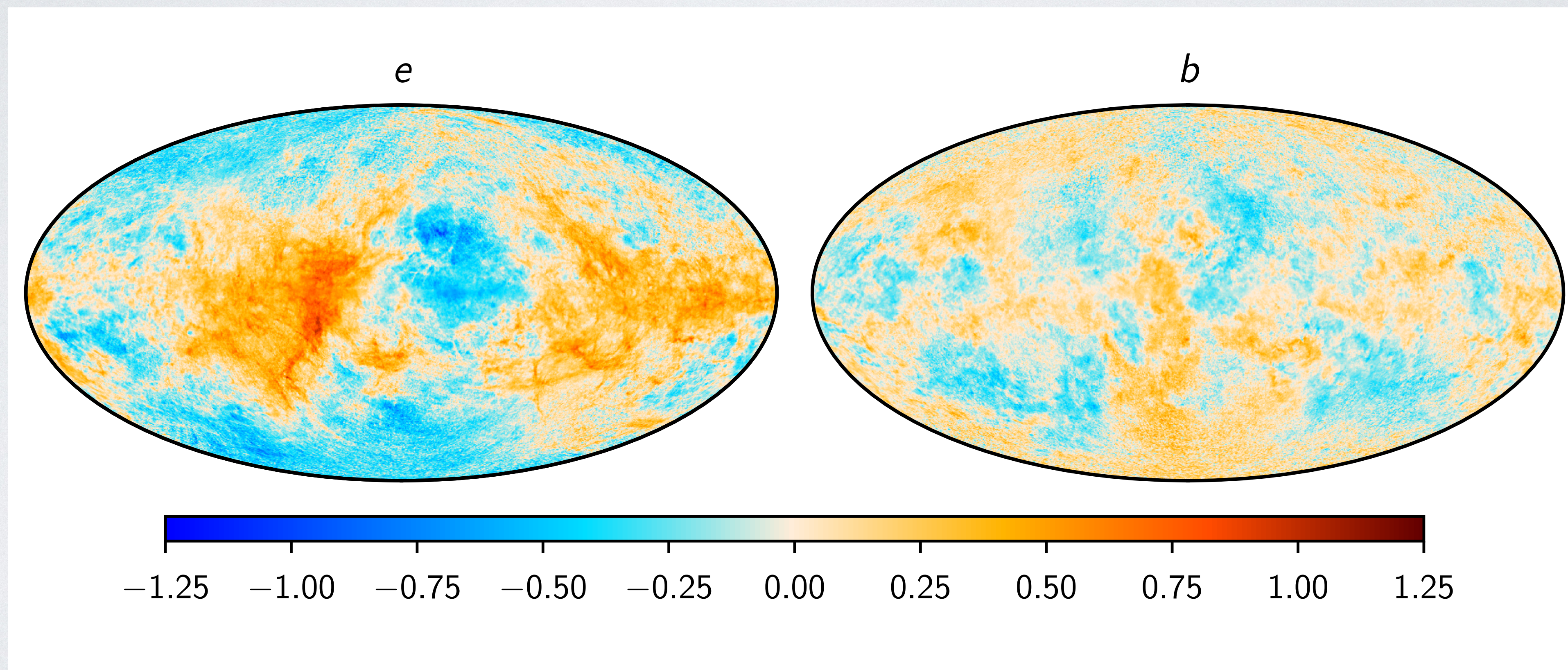
$$i = \frac{1}{2} \ln (I^2 - P^2), \quad q = \frac{1}{2} \frac{Q}{P} \ln \frac{I + P}{I - P}, \quad u = \frac{1}{2} \frac{U}{P} \ln \frac{I + P}{I - P}$$

- useful for defining likelihoods and priors, also reconstruction...

# SYNC POLARIZATION FRACTION



# DUST POLARIZATION FRACTION





# SHORT SUMMARY

- dust polarization is actually fairly simple on large scales!
- synchrotron is more complicated, not entirely correlated to dust
- additional data could be rolled in (Faraday rotation in particular)
- I am working on GPU algorithms for visualization, data clean-up, and component separation... still in progress, but it's fun!

THANKS!