## LONGITUDINAL BEAM DYNAMICS

## Elias Métral (CERN BE Department)

This course started with the one of Frank Tecker (CERN-BE) in 2010 (I took over from him in 2011), who inherited it from Roberto Corsini (CERN-BE), who gave this course in the previous years, based on the transparencies written by Louis Rinolfi (CERN-BE) who held the course at JUAS from 1994 to 2002 (see CERN/PS 2000-008 (LP)):

Material from Joel LeDuff's Course at the CERN Accelerator School held at Jyvaskyla, Finland the 7-18 September 1992 (CERN 94-01) has been used as well:
http:/ / cdsweb.cern.ch/record/235242/files/p253.pdf
http://cdsweb.cern.ch/record/235242/files/p289.pdf
I attended the course given by Louis Rinolfi in 1996 and was his assistant in 2000 and 2001 (and the assistant of Michel Martini for his course on transverse beam dynamics)

This course and related exercises / exams (as well as other courses) can be found in my web page: http://emetral.web.cern.ch/emetral/

Assistant: Benoit Salvant (CERN BE Department)

## PURPOSE OF THIS COURSE

Discuss the oscillations of the particles in the longitudinal plane of synchrotrons, called SYNCHROTRON OSCILLATIONS (similarly to the betatron oscillations in the transverse planes), and derive the basic equations


Example of the LHC $p$ beam in the injector chain

$1 \mathrm{eV}=1.6 \times 10^{-19} \mathrm{~J}$ (energy gain by an e-accelerated by a potential difference of 1 Volt )

## PURPOSE OF THIS COURSE



## PURPOSE OF THIS COURSE

## IN REAL SPACE



IN PHASE SPACE
(a)


Longitudinal,
bunched beam, below transition

Longitudinal,
unbunched beam, below transition

$\delta=\frac{\Delta p}{p}$
(e)

Longitudinal, bunched beam, above transition


## PURPOSE OF THIS COURSE

Some movies (in phase space) to have a better idea of what we will work on during this course and what you will be able to understand and do after this course...
"MATCHED" AND "MISMATCHED" BUNCH



## MISMATCHED BUNCH





## MISMATCHED BUNCH





## SOME "RF GYMNASTICS"



## BUNCH ROTATION

(to shorten bunches before extraction)





juas...
JUAS - TIMETABLE 2020 - WEEK 4


+ Examination on TH 13/02/2020 (09:00 to 10:30)



## Units of physical quantities

| Quantity | unit | SI unit | SI derived unit |
| :--- | :--- | :--- | :--- |
| Capacitance | F (farad) | $\mathrm{m}^{-2} \mathrm{~kg}^{-1} \mathrm{~s}^{4} \mathrm{~A}^{2}$ | $\mathrm{C} / \mathrm{V}$ |
| Electric charge | C (coulomb) | As |  |
| Electric potential | V (volt) | $\mathrm{m}^{2} \mathrm{~kg} \mathrm{~s}^{-3} \mathrm{~A}^{-1}$ | $\mathrm{~W} / \mathrm{A}$ |
| Energy | J (joule) | $\mathrm{m}^{2} \mathrm{~kg} \mathrm{~s}^{-2}$ | Nm |
| Force | N (newton) | $\mathrm{m} \mathrm{kg} \mathrm{s}^{-2}$ | N |
| Frequency | Hz (hertz) | $\mathrm{s}^{-1}$ |  |
| Inductance | H (henry) | $\mathrm{m}^{2} \mathrm{~kg} \mathrm{~s}^{-2} \mathrm{~A}^{-2}$ | $\mathrm{~Wb} / \mathrm{A}$ |
| Magnetic flux | Wb (weber) | $\mathrm{m}^{2} \mathrm{~kg} \mathrm{~s}^{-2} \mathrm{~A}^{-1}$ | Vs |
| Magnetic flux density | T (tesla) | $\mathrm{kg} \mathrm{s}^{-2} \mathrm{~A}^{-1}$ | $\mathrm{~Wb} / \mathrm{m}^{2}$ |
| Power | W (watt) | $\mathrm{m}^{2} \mathrm{~kg} \mathrm{~s}^{-3}$ | $\mathrm{~J} / \mathrm{s}$ |
| Pressure | Pa (pascal) | $\mathrm{m}^{-1} \mathrm{~kg} \mathrm{~s}^{-2}$ | $\mathrm{~N} / \mathrm{m}^{2}$ |
| Resistance | $\Omega$ (ohm) | $\mathrm{m}^{2} \mathrm{~kg} \mathrm{~s}^{-3} \mathrm{~A}^{-2}$ | $\mathrm{~V} / \mathrm{A}$ |

Fundamental physical constants

| Physical constant | symbol | value | unit |
| :--- | :--- | ---: | :--- |
| Avogadro's number | $N_{\mathrm{A}}$ | $6.0221367 \times 10^{23}$ | $/ \mathrm{mol}$ |
| atomic mass unit $\left(\frac{1}{12} m\left(\mathrm{C}^{12}\right)\right)$ | $m_{u}$ or $u$ | $1.6605402 \times 10^{-27}$ | kg |
| Boltzmann's constant | $k$ | $1.380658 \times 10^{-23}$ | $\mathrm{~J} / \mathrm{K}$ |
| Bohr magneton | $\mu_{\mathrm{B}}=e \hbar / 2 m_{\mathrm{e}}$ | $9.2740154 \times 10^{-24}$ | $\mathrm{~J} / \mathrm{T}$ |
| Bohr radius | $a_{0}=4 \pi \epsilon_{0} \hbar^{2} / m_{\mathrm{e}} c^{2}$ | $0.529177249 \times 10^{-10}$ | m |
| classical radius of electron | $r_{\mathrm{e}}=e^{2} / 4 \pi \epsilon_{0} m_{\mathrm{e}} c^{2}$ | $2.81794092 \times 10^{-15}$ | m |
| classical radius of proton | $r_{\mathrm{p}}=e^{2} / 4 \pi \epsilon_{0} m_{\mathrm{p}} c^{2}$ | $1.5346986 \times 10^{-18}$ | m |
| elementary charge | $e$ | $1.60217733 \times 10^{-19}$ | C |
| fine structure constant | $\alpha=e^{2} / 2 \epsilon_{0} h c$ | $1 / 137.0359895$ |  |
| $m_{u} c^{2}$ |  | 931.49432 | MeV |
| mass of electron | $m_{\mathrm{e}}$ | $9.1093897 \times 10^{-31}$ | kg |
| $m_{\mathrm{e}} c^{2}$ | 0.51099906 | MeV |  |
| mass of proton |  | $1.6726231 \times 10^{-27}$ | kg |
| $m_{\mathrm{p}} c^{2}$ | 938.27231 | MeV |  |
| mass of neutron | $m_{\mathrm{p}}$ | $1.6749286 \times 10^{-27}$ | kg |
| $m_{\mathrm{p}} c^{2}$ | $m_{\mathrm{n}}$ | 939.56563 | MeV |
| molar gas constant | $R=N_{\mathrm{A}} k$ | 8.314510 | $\mathrm{~J} / \mathrm{mol} \mathrm{K}$ |
| neutron magnetic moment | $\mu_{\mathrm{n}}$ | $-0.96623707 \times 10^{-26}$ | $\mathrm{~J} / \mathrm{T}$ |
| nuclear magneton | $\mu_{\mathrm{p}}=e \hbar / 2 m_{u}$ | $5.0507866 \times 10^{-27}$ | $\mathrm{~J} / \mathrm{T}$ |
| Planck's constant | $h$ | $6.626075 \times 10^{-34}$ | J s |
| permeability of vacuum | $\mu_{0}$ | $4 \pi \times 10^{-7}$ | $\mathrm{~N} / \mathrm{A}^{2}$ |
| permittivity of vacuum | $\epsilon_{0}$ | $8.854187817 \times 10^{-12}$ | $\mathrm{~F} / \mathrm{m}$ |
| proton magnetic moment | $\mu_{\mathrm{p}}$ | $1.41060761 \times 10^{-26}$ | $\mathrm{~J} / \mathrm{T}$ |
| proton $g$ factor | 2.792847386 |  |  |
| speed of light (exact) | $g_{\mathrm{p}}=\mu_{\mathrm{p}} / \mu_{\mathrm{N}}$ | 299792458 | $\mathrm{~m} / \mathrm{s}$ |
| vacuum impedance | $c$ | 376.7303 | $\Omega$ |

## LESSON I

Fields \& forces

Acceleration by time-varying electric field

Relativistic equations

Equation of motion for a particle of charge $q$

$$
\vec{F}=\frac{\mathrm{d} \vec{p}}{\mathrm{dt}}=q(\vec{E}+\vec{v} \times \vec{B})
$$

$\vec{p}=m \vec{v}$
$\vec{v}$
$\vec{E}$
$\vec{B}$

Momentum
Velocity
Electric field
Magnetic field

## Constant electric field



$$
\frac{\mathrm{d} \vec{p}}{\mathrm{dt}}=-e \vec{E}
$$

1. Direction of the force always parallel to the field
2. Trajectory can be modified, velocity also $\Rightarrow$ momentum and energy can be modified

This force can be used to accelerate and decelerate particles

## Constant magnetic field

$$
e v B=\frac{m v^{2}}{\rho}
$$

$$
\frac{\mathrm{d} \vec{p}}{\mathrm{dt}}=\vec{F}=-e(\vec{v} \times \vec{B})
$$

1. Direction always perpendicular to the velocity
2. Trajectory can be modified, but not the velocity

This force cannot modify the energy
magnetic rigidity: $\quad B \rho=\frac{p}{e} \quad$ angular frequency: $\quad \omega=2 \pi f=\frac{e}{m} B$

Important relationship:

$$
B \rho=\frac{p}{e} \Rightarrow \rho=\frac{p}{e B}
$$

## Practical units:

$$
B \rho[\mathrm{Tm}] \approx \frac{p[\mathrm{GeV} / \mathrm{c}]}{0.3}
$$

## Application: spectrometer



## Comparison of magnetic and electric forces

$$
\begin{aligned}
& |\vec{B}|=1 \mathrm{~T} \\
& |\vec{E}|=10 \mathrm{MV} / \mathrm{m}
\end{aligned}
$$

$$
\frac{F_{M A G N}}{F_{E L E C}}=\frac{e v B}{e E}=\beta c \frac{B}{E} \cong 3 \cdot 10^{8} \frac{1}{10^{7}} \beta=30 \beta
$$

## Acceleration by time-varying electric field



- Let $V_{R F}$ be the amplitude of the RF voltage across the gap $g$
- The particle crosses the gap at a distance $r$
- The energy gain is:


In the cavity gap, the electric field is supposed to be:

$$
E(s, r, t)=E_{1}(s, r) \cdot E_{2}(t)
$$

In general, $E_{2}(t)$ is a sinusoidal time variation with angular frequency $\omega_{R F}$

$$
E_{2}(t)=E_{\circ} \sin \Phi(t) \quad \text { where } \quad \Phi(t)=\int_{t_{0}}^{t} \omega_{R F} \mathrm{~d} t+\Phi_{0}
$$

1. For circular accelerators, the origin of time is taken at the zero crossing of the RF voltage with positive slope
2. For linear accelerators, the origin of time is taken at the positive crest of the RF voltage

Time $t=0$ chosen such that:


$$
E_{2}(t)=E_{\circ} \sin \left(\omega_{R F} t\right)
$$



$$
E_{2}(t)=E_{\circ} \cos \left(\omega_{R F} t\right)
$$

## Relativistic Equations

$$
E=m c^{2}
$$

$$
\begin{aligned}
& \text { normalized velocity } \\
& \beta=\frac{v}{c}=\sqrt{1-\frac{1}{\gamma^{2}}} \\
& \begin{array}{c}
E=E_{\text {kin }}+E_{0} \\
\text { total } \\
\text { kinetic }
\end{array} \\
& \begin{array}{c}
E=E_{\text {kin }}+E_{0} \\
\text { total } \\
\text { kinetic }
\end{array} \\
& \text { energy } \\
& \frac{\text { total energy }}{\text { rest energy }} \\
& \text { momentum } \\
& \gamma=\frac{E}{E_{0}}=\frac{m}{m_{0}}=\frac{1}{\sqrt{1-v^{2} / c^{2}}}=\frac{1}{\sqrt{1-\beta^{2}}} \\
& p=m v=\beta \frac{E}{c}=\beta \gamma m_{0} c \\
& p^{2} c^{2}=E^{2}-E_{0}{ }^{2} \quad \gamma=1+\frac{E_{\text {kin }}}{E_{0}} \\
& p[\mathrm{GeV} / \mathrm{c}] \cong 0.3 B[\mathrm{~T}] \rho[\mathrm{m}]
\end{aligned}
$$

normalized velocity

$$
\beta=\frac{v}{c}=\sqrt{1-\frac{1}{\gamma^{2}}}
$$



> total energy
> rest energy

$$
\gamma=\frac{E}{E_{0}}=\frac{m}{m_{0}}=\frac{1}{\sqrt{1-v^{2} / c^{2}}}=\frac{1}{\sqrt{1-\beta^{2}}}
$$



First derivatives

$$
\begin{aligned}
& \mathrm{d} \beta=\beta^{-1} \gamma^{-3} \mathrm{~d} \gamma \\
& \mathrm{~d}(c p)=E_{0} \gamma^{3} \mathrm{~d} \beta \\
& \mathrm{~d} \gamma=\beta\left(1-\beta^{2}\right)^{-3 / 2} \mathrm{~d} \beta
\end{aligned}
$$

Logarithmic derivatives

$$
\begin{aligned}
& \frac{\mathrm{d} \beta}{\beta}=(\beta \gamma)^{-2} \frac{\mathrm{~d} \gamma}{\gamma} \\
& \frac{\mathrm{~d} p}{p}=\frac{\gamma^{2}}{\gamma^{2}-1} \frac{\mathrm{~d} E}{E}=\frac{\gamma}{\gamma+1} \frac{\mathrm{~d} E_{\text {kin }}}{E_{\text {kin }}} \\
& \frac{\mathrm{d} \gamma}{\gamma}=\left(\gamma^{2}-1\right) \frac{\mathrm{d} \beta}{\beta}
\end{aligned}
$$

## LESSON II

# Particle acceleration => Synchrotrons 

Transit time factor

Main RF parameters

Momentum compaction

Transition energy

## Synchrotron



## Synchronism condition


$h$ integer, harmonic number

1. $\quad \omega_{\mathrm{RF}}$ and $\omega$ increase with energy
2. To keep particles on the closed orbit, B should increase with time


## Synchrotron

- In reality, the orbit in a synchrotron is not a circle, straight sections are added for RF cavities, injection and extraction, etc..
- Usually the beam is pre-accelerated in a linac (or a smaller synchrotron) before injection
- The bending radius $\rho$ does not coincide to the machine radius $R=L / 2 \pi$

Examples of different proton and electron synchrotrons at CERN


## Parameters for circular accelerators

The basic principles, for the common circular accelerators, are based on the two relations:

1. The Lorentz equation: the orbit radius can be espressed as:

$$
R=\frac{\gamma v m_{0}}{e B}
$$

2. The synchronicity condition: The revolution frequency can be expressed as:

$$
f=\frac{e B}{2 \pi \gamma m_{0}}
$$

According to the parameter we want to keep constant or let vary, one has different acceleration principles. They are summarized in the table below:

| Machine | Energy ( $\gamma$ ) | Velocity | Field | Orbit | Frequency |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Cyclotron | $\sim 1$ | var. | const. | $\sim v$ | const. |
| Synchrocyclotron | var. | var. | $B(r)$ | $\sim p$ | $B(r) / \gamma(t)$ |
| Proton/Ion synchrotron | var. | var. | $\sim p$ | $R$ | $\sim v$ |
| Electron synchrotron | var. | const. | $\sim p$ | $R$ | const. |

## Transit time factor

RF acceleration in a gap $g$
$E(s, r, t)=E_{1}(s, r) \cdot E_{2}(t)$

Simplified model $\square$

$$
\begin{aligned}
& E_{1}(s, r)=\frac{V_{R F}}{g}=\text { const. } \\
& E_{2}(t)=\sin \left(\omega_{R F} t+\phi_{0}\right)
\end{aligned}
$$

At $t=0, s=0$ and $v \neq 0$, parallel to the electric field
Energy gain:

$$
\Delta E=e \int_{-g / 2}^{g / 2} E(s, r, t) \mathrm{d} s
$$

$$
\Delta E=e V_{R F} T_{a} \sin \phi_{0}
$$

where

$$
T_{a}=\frac{\sin \frac{\omega_{R F} g}{2 v}}{\frac{\omega_{R F} g}{2 v}}
$$

$T_{a}$ is called transit time factor

$$
\cdot T_{a}<1
$$

$$
\text { - } T_{a} \rightarrow 1 \text { if } g \rightarrow 0
$$

## Transit time factor II

In the general case, the transit time factor is given by:

$$
T_{a}=\frac{\int_{-\infty}^{+\infty} E_{1}(s, r) \cos \left(\omega_{R F} \frac{s}{v}\right) \mathrm{d} s}{\int_{-\infty}^{+\infty} E_{1}(s, r) \mathrm{d} s}
$$

It is the ratio of the peak energy gained by a particle with velocity $v$ to the peak energy gained by a particle with infinite velocity.
I. Voltage, phase, frequency

## Main RF parameters

In order to accelerate particles, longitudinal fields must be generated in the direction of the desired acceleration

$$
\begin{array}{ll}
E(s, t)=E_{1}(s) \cdot E_{2}(t) & E_{2}(t)=E_{0} \sin \left[\int_{t_{0}}^{t} \omega_{R F} \mathrm{~d} t+\phi_{0}\right] \\
\omega_{R F}=2 \pi f_{R F} & \Delta E=e V_{R F} T_{a} \sin \phi_{0}
\end{array}
$$

Such electric fields are generated in RF cavities characterized by the voltage amplitude, the frequency and the phase
II. Harmonic number

$$
T_{\text {rev }}=h T_{R F} \Rightarrow f_{R F}=h f_{\text {rev }}
$$

$f_{\text {rev }}=$ revolution frequency
$f_{R F}=$ frequency of the RF
$h=$ harmonic number
harmonic number in different machines:

| $A A$ | EPA | PS | SPS |
| :---: | :---: | :---: | :---: |
| 1 | 8 | 20 | 4620 |

## Dispersion




## Momentum compaction factor in a transport system

In a particle transport system, a nominal trajectory is defined for the nominal momentum $p$.
For a particle with a momentum $p+\Delta p$ the trajectory length can be different from the length L of the nominal trajectory.

The momentum compaction factor is defined by the ratio:

$$
\alpha_{p}=\frac{d L / L}{d p / p}
$$

Therefore, for small momentum deviation, to first order it is:

$$
\frac{\Delta L}{L}=\alpha_{p} \frac{\Delta p}{p}
$$

## Example: constant magnetic field



To first order, only the bending magnets contribute to a change of the trajectory length ( $r=\infty$ in the straight sections)

## Momentum compaction in a ring

In a circular accelerator, a nominal closed orbit is defined for the nominal momentum $p$.
For a particle with a momentum deviation $\Delta p$ produces an orbit length variation $\Delta C$ with:


The momentum compaction factor is defined by the ratio:

$$
\alpha_{p}=\frac{d C / C}{d p / p}=\frac{d R / R}{d p / p} \quad \text { and } \quad \alpha_{p}=\frac{1}{C} \int_{C} \frac{D_{x}(s)}{\rho(s)} \mathrm{d} s
$$

N.B.: in most circular machines, $\alpha_{p}$ is positive $\Rightarrow$ higher momentum means longer circumference

Momentum compaction as a function of energy

$$
E=\frac{p c}{\beta} \quad \Rightarrow \quad \frac{\mathrm{~d} E}{E}=\beta^{2} \frac{d p}{p}
$$

$$
\alpha_{p}=\beta^{2} \frac{E}{R} \frac{\mathrm{~d} R}{\mathrm{~d} E}
$$

## Momentum compaction as a function of magnetic field

Definition of average magnetic field

$$
\begin{array}{ll}
<B>=\frac{1}{2 \pi R} \int_{C} B_{f} \mathrm{~d} s=\frac{1}{2 \pi R}\left(\int_{\text {straights }} B_{f} \mathrm{~d} s+\int_{\text {magnets }} B_{f} \mathrm{~d} s\right) \\
<B>=\frac{B_{f} \rho}{n} & =0
\end{array}
$$

$$
B_{f} \rho=\frac{p}{\rho} \quad \square \frac{\mathrm{~d}\langle B\rangle}{\langle B\rangle}=\frac{\mathrm{d} B_{f}}{B_{f}}+\frac{\mathrm{d} \rho}{\rho}-\frac{\mathrm{d} R}{R}
$$

$$
<B>R=\frac{p}{e} \quad \Rightarrow \quad \frac{\mathrm{~d}<B>}{<B>}+\frac{\mathrm{d} R}{R}=\frac{\mathrm{d} p}{p}
$$

For $B_{f}=$ const.

$$
\alpha_{p}=1-\frac{\mathrm{d}<B\rangle}{\langle B>} / \frac{\mathrm{d} p}{p}
$$

Proton (ion) circular machine with $\alpha_{p}$ positive

1. Momentum larger than the nominal $(p+\Delta p) \Rightarrow$ longer orbit $(C+\Delta C)$
2. Momentum larger than the nominal $(p+\Delta p) \Rightarrow$ higher velocity $(v+\Delta v)$

$$
\text { What happens to the revolution frequency } f=v / C \text { ? }
$$

- At low energy, $v$ increases faster than $C$ with momentum
- At high energy $v \cong c$ and remains almost constant

There is an energy for which the velocity variation is compensated by the trajectory variation $\Rightarrow$ transition energy

Below transition: higher energy $\Rightarrow$ higher revolution frequency Above transition: higher energy $\Rightarrow$ lower revolution frequency

## Transition energy - quantitative approach

We define a parameter $\eta$ (revolution frequency spread per unit of momentum spread), called slip or slippage factor:

$$
\begin{aligned}
& \quad \eta=\frac{\mathrm{d} f / f}{\mathrm{~d} p / p}=\frac{\mathrm{d} \omega / \omega}{\mathrm{d} p / p} \\
& f=\frac{v}{C} \quad \longrightarrow \quad \frac{\mathrm{~d} f}{f}=\frac{\mathrm{d} \beta}{\beta}-\frac{\mathrm{d} C}{C}
\end{aligned}
$$

from $p=\frac{m_{0} c \beta}{\sqrt{1-\beta^{2}}} \Rightarrow \frac{\mathrm{~d} \beta}{\beta}=\frac{1}{\gamma^{2}} \frac{\mathrm{~d} p}{p} \quad \begin{aligned} & \text { definition of momentum } \\ & \text { compaction factor: }\end{aligned} \quad \frac{\mathrm{d} C}{C}=\alpha_{p} \frac{\mathrm{~d} p}{p}$

$$
\frac{\mathrm{d} f}{f}=\left(\frac{1}{\gamma^{2}}-\alpha_{p}\right) \frac{\mathrm{d} p}{p}
$$

## Transition energy - quantitative approach

$$
\eta=\frac{1}{\gamma^{2}}-\alpha_{p}
$$

The transition energy is the energy that corresponds to $\eta=0$ ( $\alpha_{p}$ is fixed, and $\gamma$ variable)

$$
\gamma_{t r}=\sqrt{\frac{1}{\alpha_{p}}}
$$

The parameter $\eta$ can also be written as

$$
\eta=\frac{1}{\gamma^{2}}-\frac{1}{\gamma_{t r}^{2}}
$$

- At low energy $\quad \eta>0$
- At high energy $\eta<0$
N.B.: for electrons, $\gamma \gg \gamma_{t r} \Rightarrow \eta<0$ for linacs $\alpha_{p}=0 \Rightarrow \eta>0$

LESSON III

Equations related to synchrotrons

Synchronous particle

Synchrotron oscillations

Principle of phase stability

## Equations related to synchrotrons

$$
\begin{aligned}
& \frac{\mathrm{d} p}{p}=\gamma_{t r}^{2} \frac{\mathrm{~d} R}{R}+\frac{\mathrm{d} B}{B} \\
& \frac{\mathrm{~d} p}{p}=\gamma^{2} \frac{\mathrm{~d} f}{f}+\gamma^{2} \frac{\mathrm{~d} R}{R} \\
& \frac{\mathrm{~d} B}{B}=\gamma_{t r}^{2} \frac{\mathrm{~d} f}{f}+\left[1-\left(\frac{\gamma_{t r}}{\gamma}\right)^{2}\right] \frac{\mathrm{d} p}{p} \\
& \frac{\mathrm{~d} B}{B}=\gamma^{2} \frac{\mathrm{~d} f}{f}+\left(\gamma^{2}-\gamma_{t r}^{2}\right) \frac{\mathrm{d} R}{R}
\end{aligned}
$$

$p[\mathrm{MeV} / \mathrm{c}]$ momentum
$R[\mathrm{~m}] \quad$ orbit radius
$B[\mathrm{~T}] \quad$ magnetic field
$f[\mathrm{~Hz}] \quad$ rev. frequency
$\gamma_{t r}$
transition energy

## I-Constant radius

## $\mathrm{d} R=0$

Beam maintained on the same orbit when energy varies

$$
\begin{aligned}
& \frac{\mathrm{d} p}{p}=\frac{\mathrm{d} B}{B} \\
& \frac{\mathrm{~d} p}{p}=\gamma^{2} \frac{\mathrm{~d} f}{f}
\end{aligned}
$$

If $p$ increases
B increases
$f$ increases

## II - Constant energy

$$
\mathrm{d} p=0
$$

$$
V_{R F}=0 \quad \text { Beam debunches }
$$

$$
\begin{aligned}
& \frac{\mathrm{d} p}{p}=0=\gamma_{t r}{ }^{2} \frac{\mathrm{~d} R}{R}+\frac{\mathrm{d} B}{B} \\
& \frac{\mathrm{~d} p}{p}=0=\gamma^{2} \frac{\mathrm{~d} f}{f}+\gamma^{2} \frac{\mathrm{~d} R}{R}
\end{aligned}
$$

If $B$ increases
$R$ decreases
$f$ increases

## III - Magnetic flat-top <br> $$
\mathrm{d} B=0
$$

Beam bunched with constant magnetic field

$$
\begin{aligned}
\frac{\mathrm{d} p}{p}=\gamma_{t r}^{2} \frac{\mathrm{~d} R}{R} \quad \frac{\mathrm{~d} B}{B} & =0
\end{aligned}=\gamma_{t r}^{2} \frac{\mathrm{~d} f}{f}+\left[1-\left(\frac{\gamma_{t r}}{\gamma}\right)^{2}\right] \frac{\mathrm{d} p}{p}, ~\left(\frac{\mathrm{~d} B}{B}=0=\gamma^{2} \frac{\mathrm{~d} f}{f}+\left(\gamma^{2}-\gamma_{t r}^{2}\right) \frac{\mathrm{d} R}{R}\right.
$$

If $p$ increases
$R$ increases
$f$ increase $\quad \gamma<\gamma_{t r}$ decreases $\gamma>\gamma_{t r}$

## IV - Constant frequency <br> $$
\mathrm{d} f=0
$$

Beam driven by an external oscillator

$$
\begin{aligned}
\frac{\mathrm{d} p}{p}=\gamma^{2} \frac{\mathrm{~d} R}{R} \quad \frac{\mathrm{~d} B}{B} & =\left[1-\left(\frac{\gamma_{t r}}{\gamma}\right)^{2}\right] \frac{\mathrm{d} p}{p} \\
\frac{\mathrm{~d} B}{B} & =\left(\gamma^{2}-\gamma_{t r}^{2}\right) \frac{\mathrm{d} R}{R}
\end{aligned}
$$

If $p$ increases
R increases
$\begin{array}{ll}\mathrm{B} \text { decreases } & \gamma<\gamma_{t r} \\ \text { increase } & \gamma>\gamma_{t r}\end{array}$

## Four conditions - resume

| Beam | Parameter | Variations |  | momentum |
| :---: | :---: | :---: | :---: | :---: |
| Debunched | $\Delta p=0$ | $B \Uparrow, R \Downarrow, f \Uparrow$ |  |  |
| Fixed orbit | $\Delta R=0$ | $B \Uparrow, p \Uparrow, f \Uparrow$ |  | orbit radius |
| Magnetic flat-top | $\Delta B=0$ | $\begin{array}{r} p \Uparrow, R \Uparrow, f \Uparrow(\eta>0) \\ f \Downarrow(\eta<0) \end{array}$ | $B$ | magnetic field |
| External oscillator | $\Delta f=0$ | $\begin{array}{r} B \Uparrow, p \Downarrow, R \Downarrow(\eta>0) \\ p \Uparrow, R \Uparrow(\eta<0) \end{array}$ | $f$ | frequency |

Simple case (no accel.): $B=$ const. $\quad \gamma<\gamma_{t r}$

## Synchronous particle

Synchronous particle: particle that sees always the same phase (at each turn) in the RF cavity



In order to keep the resonant condition, the particle must keep a constant energy
The phase of the synchronous particle must therefore be $\phi_{0}=0$ (circular machines convention)
Let's see what happens for a particle with the same energy and a different phase (e.g., $\phi_{1}$ )

## Synchrotron oscillations

$\phi_{1} \quad$ - The particle is accelerated

- Below transition, an increase in energy means an increase in revolution frequency
- The particle arrives earlier - tends toward $\phi_{0}$

- The particle is decelerated
- decrease in energy - decrease in revolution frequency
- The particle arrives later - tends toward $\phi_{0}$




## Longitudinal phase space



The particle trajectory in the phase space ( $\phi, \Delta p / p$, ) describes its longitudinal motion


Emittance: phase space area including all the particles

NB: if the emittance contour correspond to a possible orbit in phase space, its shape does not change with time (matched beam)

Case with acceleration B increasing $\quad \gamma<\gamma_{t r}$

## Synchronous particle



$$
\Delta E=e \hat{V}_{R F} \sin \phi
$$

The phase of the synchronous particle is now $\phi_{s}>0$ (circular machines convention)
The synchronous particle accelerates, and the magnetic field is increased accordingly to keep the constant radius $R$

$$
R=\frac{\gamma v m_{0}}{e B}
$$

The RF frequency is increased as well in order to keep the resonant condition

$$
\omega=\frac{e B}{\gamma m_{0}}=\frac{\omega_{R F}}{h}
$$

Phase stability


The symmetry of the case with $\mathrm{B}=$ const. is lost


## Phase stability

$\phi_{s}<\phi<\pi-\phi_{s}$

## LESSON IV

## RF acceleration for synchronous particle

RF acceleration for non-synchronous particle
Small amplitude oscillations
Large amplitude oscillations - the RF bucket
Synchrotron frequency and tune
Tracking
Nonadiabatic theory needed "close" to transition
Double RF systems

Let's assume a synchronous particle with a given $\phi_{s}>0$
We want to calculate its rate of acceleration, and the related rate of increase of $B, f$.

$$
\begin{aligned}
& p=e B \rho \\
& \text { Want to keep } \rho=\text { cons } \dagger \\
& \frac{\mathrm{d} p}{\mathrm{~d} t}=e \rho \frac{\mathrm{~d} B}{\mathrm{~d} t}=e \rho \dot{B} \\
& \text { Over one turn: } \quad(\Delta p)_{t u r n}=e \rho \dot{B} T_{r e v}=e \rho \dot{B} \frac{2 \pi R}{\beta c} \\
& \text { We know that (relativistic equations) : } \Delta p=\frac{\Delta E}{\beta c}
\end{aligned}
$$

$$
(\Delta E)_{\text {turn }}=e \rho \dot{B} 2 \pi R
$$

## RF acceleration for synchronous particle - phase

$(\Delta E)_{u u r n}=e \rho \dot{B} 2 \pi R$
On the other hand, for the synchronous particle:
$(\Delta E)_{u u n}=e \hat{V}_{R F} \sin \phi_{s}$

$$
e \rho \dot{B} 2 \pi R=e \hat{V}_{R F} \sin \phi_{s}
$$

Therefore: 1. Knowing $\phi_{s}$, one can calculate the increase rate of the magnetic field needed for a given RF voltage:

$$
\dot{B}=\frac{\hat{V}_{R F}}{2 \pi \rho R} \sin \phi_{s}
$$

2. Knowing the magnetic field variation and the RF voltage, one can calculate the value of the synchronous phase:

$$
\sin \phi_{s}=2 \pi \rho R \frac{\dot{B}}{\hat{V}_{R F}} \Rightarrow \phi_{s}=\arcsin \left(2 \pi \rho R \frac{\dot{B}}{\hat{V}_{R F}}\right)
$$

## RF acceleration for synchronous particle - frequency

$$
\begin{aligned}
& \omega_{R F}=h \omega_{s}=h \frac{e}{m}<B>\quad\left(v=\frac{e}{m} B \rho\right) \\
& \omega_{R F}=h \frac{e}{m} \frac{\rho}{R} B
\end{aligned}
$$

From relativistic equations:

$$
\omega_{R F}=\frac{h c}{R} \sqrt{\frac{B^{2}}{B^{2}+\left(E_{0} / e c \rho\right)^{2}}}
$$

Let

$$
B_{0} \equiv \frac{E_{0}}{e c \rho} \quad \Rightarrow \quad f_{R F}=\frac{h c}{2 \pi R}\left(\frac{B}{B_{0}}\right) \frac{1}{\sqrt{1+\left(B / B_{0}\right)^{2}}}
$$

Example: PS

At the CERN Proton Synchrotron machine, one has:

$$
\begin{aligned}
& R=100 \mathrm{~m} \\
& \dot{B}=2.4 \mathrm{~T} / \mathrm{s}
\end{aligned}
$$

100 dipoles with $l_{\text {eff }}=4.398 \mathrm{~m}$. The harmonic number is 20

Calculate:

1. The energy gain per turn
2. The minimum RF voltage needed
3. The RF frequency when $B=1.23 \mathrm{~T}$ (at extraction)

## RF acceleration for non synchronous particle

Parameter definition (subscript "s" stands for synchronous particle):

$$
\begin{array}{ll}
f=f_{s}+\Delta f & \text { revolution frequency } \\
\phi=\phi_{s}+\Delta \phi & \text { RF phase } \\
p=p_{s}+\Delta p & \text { Momentum } \\
E=E_{s}+\Delta E & \text { Energy } \\
\theta=\theta_{s}+\Delta \theta & \text { Azimuth angle }
\end{array}
$$

$$
\begin{aligned}
& \mathrm{d} s=R \mathrm{~d} \theta \\
& \theta(t)=\int_{t_{0}}^{t} \omega(\tau) \mathrm{d} \tau
\end{aligned}
$$



Since $\quad f_{R F}=h f_{\text {rev }}$
$\Delta \phi=-h \Delta \theta$
Over one turn $\theta$ varies by $2 \pi$ $\phi$ varies by $2 \pi h$

1. Angular frequency

$$
\begin{aligned}
\theta(t)=\int_{t_{0}}^{t} \omega(\tau) \mathrm{d} \tau \quad \Delta \omega & =\frac{\mathrm{d}}{\mathrm{~d} t}(\Delta \theta) \\
& =-\frac{1}{h} \frac{\mathrm{~d}}{\mathrm{~d} t}(\Delta \phi) \\
& =-\frac{1}{h} \frac{\mathrm{~d}}{\mathrm{~d} t}\left(\phi-\phi_{s}\right) \quad \frac{\mathrm{d} \phi_{s}}{\mathrm{~d} t}=0 \text { by definition } \\
& =-\frac{1}{h} \frac{\mathrm{~d} \phi}{\mathrm{~d} t}
\end{aligned}
$$

## Parameters versus $\dot{\phi}$

2. Momentum

$$
\eta=\frac{\mathrm{d} \omega / \omega}{\mathrm{d} p / p}=\frac{\Delta \omega / \omega}{\Delta p / p}
$$

$$
\Delta p=\frac{p_{s}}{\omega_{s}} \frac{\Delta \omega}{\eta}=\frac{p_{s}}{\omega_{s} \eta}\left(-\frac{1}{h} \frac{\mathrm{~d} \phi}{\mathrm{~d} t}\right)
$$

$$
\Delta p=\frac{-p_{s}}{\omega_{s} \eta h} \frac{\mathrm{~d} \phi}{\mathrm{~d} t}
$$

3. Energy

$$
\frac{\mathrm{d} E}{\mathrm{~d} p}=v
$$

$$
\frac{\Delta E}{\Delta p}=v=\omega R
$$

$$
\Delta E=-\frac{R p_{s}}{\eta h} \frac{\mathrm{~d} \phi}{\mathrm{~d} t}
$$

## Derivation of equations of motion

Energy gain after the RF cavity

$$
\begin{aligned}
& (\Delta E)_{t u r n}=e \hat{V}_{R F} \sin \phi \\
& (\Delta p)_{t u r n}=\frac{e}{\omega R} \hat{V}_{R F} \sin \phi
\end{aligned}
$$

Average increase per time unit

$$
\frac{(\Delta p)_{\text {turn }}}{T_{\text {rev }}}=\frac{e}{2 \pi R} \hat{V}_{R F} \sin \phi \quad 2 \pi R \dot{p}=e \hat{V}_{R F} \sin \phi \quad \text { valid for any particle! }
$$

$$
2 \pi\left(R \dot{p}-R_{s} \dot{p}_{s}\right)=e \hat{V}_{R F}\left(\sin \phi-\sin \phi_{s}\right)
$$

## Derivation of equations of motion

$$
\begin{aligned}
R \dot{p}-R_{s} \dot{p}_{s} & =\left(R_{s}+\Delta R\right)\left(\dot{p}_{s}+\Delta \dot{p}\right)-R_{s} \dot{p}_{s} \\
& \approx R_{s} \Delta \dot{p}+\dot{p}_{s} \Delta R \\
& \approx R_{s} \Delta \dot{p}+\dot{p}_{s}\left(\frac{d R}{d p}\right)_{s} \Delta p \\
& =R_{s} \Delta \dot{p}+\frac{d p_{s}}{d t} \frac{d R_{s}}{d p_{s}} \Delta p \\
& =R_{s} \Delta \dot{p}+\dot{R}_{s} \Delta p \\
& =\frac{d}{d t}\left(R_{s} \Delta_{p}\right) \\
& =\frac{d}{d t}\left(\frac{\Delta E}{\omega_{s}}\right)
\end{aligned}
$$

## Derivation of equations of motion

$$
2 \pi \frac{d}{d t}\left(\frac{\Delta E}{\omega_{s}}\right)=e \hat{V}_{R F}\left(\sin \phi-\sin \phi_{s}\right)
$$

An approximated version of the above is

$$
\frac{\mathrm{d}(\Delta p)}{\mathrm{d} t}=\frac{e \hat{V}_{R F}}{2 \pi R_{s}}\left(\sin \phi-\sin \phi_{s}\right)
$$

Which, together with the previously found equation

$$
\frac{\mathrm{d} \phi}{\mathrm{~d} t}=-\frac{\omega_{s} \eta h}{p_{s}} \Delta p
$$

Describes the motion of the non-synchronous particle in the longitudinal phase space ( $\Delta p, \phi$ )

## Equations of motion I

$$
\left\{\begin{array}{l}
\frac{\mathrm{d}(\Delta p)}{\mathrm{d} t}=A\left(\sin \phi-\sin \phi_{s}\right) \\
\frac{\mathrm{d} \phi}{\mathrm{~d} t}=B \Delta p
\end{array} \quad \text { with } \quad A=\frac{e \hat{V}_{R F}}{2 \pi R_{s}}\right.
$$

## $B$ is not the magnetic field (induction) here! <br> $$
B=-\frac{\eta h}{p_{s}} \frac{\beta_{s} c}{R_{s}}
$$

## Equations of motion II

1. First approximation - combining the two equations:

$$
\frac{\mathrm{d}}{\mathrm{~d} t}\left(\frac{1}{B} \frac{\mathrm{~d} \phi}{\mathrm{~d} t}\right)-A\left(\sin \phi-\sin \phi_{s}\right)=0
$$

We assume that $A$ and $B$ change very slowly compared to the variable $\Delta \phi=\phi-\phi_{s}$

$$
\Rightarrow \frac{\mathrm{d}^{2} \phi}{\mathrm{~d} t^{2}}+\frac{\Omega_{s y n c}^{2}}{\cos \phi_{s}}\left(\sin \phi-\sin \phi_{s}\right)=0
$$

with $\frac{\Omega_{s y m c}^{2}}{\cos \phi_{s}}=-A B \quad$ We can also define: $\quad \Omega_{0}^{2}=\frac{\Omega_{s y m c}^{2}}{\cos \phi_{s}}=\frac{e \hat{V}_{R F} \eta h c^{2}}{2 \pi R_{s}^{2} E_{s}}$
2. Second approximation

$$
\begin{aligned}
\sin \phi & =\sin \left(\phi_{s}+\Delta \phi\right) \\
& =\sin \phi_{s} \cos \Delta \phi+\cos \phi_{s} \sin \Delta \phi
\end{aligned}
$$

$\Delta \phi$ small $\Rightarrow \sin \phi \cong \sin \phi_{s}+\cos \phi_{s} \Delta \phi$

$$
\frac{\mathrm{d} \phi_{s}}{\mathrm{~d} t}=0 \quad \Rightarrow \quad \frac{\mathrm{~d}^{2} \phi}{\mathrm{~d} t^{2}}=\frac{\mathrm{d}^{2}}{\mathrm{~d} t^{2}}\left(\phi_{s}+\Delta \phi\right)=\frac{\mathrm{d}^{2} \Delta \phi}{\mathrm{~d} t^{2}}
$$

by definition

$$
\Rightarrow \frac{\mathrm{d}^{2} \Delta \phi}{\mathrm{~d} t^{2}}+\Omega_{\text {sync }}^{2} \Delta \phi=0
$$

Harmonic oscillator!

## Stability condition for $\phi_{s}$

Stability is obtained when the angular frequency of the oscillator, $\Omega_{s y n c}^{2}$ is real positive:

$$
\Omega_{s y n c}^{2}=\frac{e \hat{V}_{R F} \eta h c^{2}}{2 \pi R_{s}^{2} E_{s}} \cos \phi_{s} \Rightarrow \Omega_{s y n c}^{2}>0 \quad \Leftrightarrow \quad \eta \cos \phi_{s}>0
$$



## Small amplitude oscillations - orbits

For $\eta \cos \phi_{s}>0$ the motion around the synchronous particle is a stable oscillation:

$$
\left\{\begin{array}{l}
\Delta \phi=\Delta \phi_{\max } \sin \left(\Omega_{\text {sync }} t+\phi_{0}\right) \\
\Delta p=\Delta p_{\max } \cos \left(\Omega_{\text {sync }} t+\phi_{0}\right)
\end{array}\right.
$$

$$
\text { with } \quad \Delta p_{\max }=\frac{\Omega_{s y n c}}{B} \Delta \phi_{\max }
$$

## Synchrotron (angular) frequency and synchrotron tune

 (for small amplitudes)$$
\Omega_{s y n c}=\omega_{s} \sqrt{\frac{e \hat{V}_{R F} h}{2 \pi \beta^{2} E_{s}} \eta \cos \phi_{s}} \quad \begin{aligned}
\Omega_{s y n c} & =2 \pi f_{s y y c} \\
\omega_{s} & =2 \pi f_{s}
\end{aligned}
$$

Number of synchrotron oscillations per turn:

$$
Q_{s y n c}=\frac{\Omega_{s y n c}}{\omega_{s}}=\sqrt{\frac{e \hat{V}_{R F} h}{2 \pi \beta^{2} E_{s}} \eta \cos \phi_{s}} \quad \text { "synchrotron tune" }
$$

## Large amplitude oscillations

$$
\ddot{\phi}+\frac{\Omega_{s}^{2}}{\cos \phi_{s}}\left(\sin \phi-\sin \phi_{S}\right)=0
$$ - $\begin{aligned} & \text { Multiplying by } \dot{\phi} \\ & \text { and integrating }\end{aligned}$

$$
\frac{\dot{\phi}^{2}}{2}-\frac{\Omega_{s}^{2}}{\cos \phi_{s}}\left(\cos \phi+\phi \sin \phi_{\mathrm{s}}\right)=c t e
$$

Constant of motion

$$
\text { here } \begin{aligned}
\dot{\phi} & =0 \\
\qquad \phi & =\pi-\phi_{s}
\end{aligned}
$$

Equation of the separatrix

## $\Omega_{\text {sync }}$ will now be noted $\Omega$

$$
\frac{\dot{\phi}^{2}}{2}-\frac{\Omega_{s}^{2}}{\cos \phi_{s}}\left(\cos \phi+\phi \sin \phi_{s}\right)=-\frac{\Omega_{s}^{2}}{\cos \phi_{s}}\left[\cos \left(\pi-\phi_{s}\right)+\left(\pi-\phi_{s}\right) \sin \phi_{s}\right]
$$

## Phase space separatrix and particle trajectories

- Equation of the bucket separatrix

$$
\frac{\dot{\phi}}{\Omega_{s}}= \pm \sqrt{\frac{2}{\cos \phi_{s}}\left[\cos \phi+\phi \sin \phi_{s}-\cos \left(\pi-\phi_{s}\right)-\left(\pi-\phi_{s}\right) \sin \phi_{s}\right]}
$$

- Equation of a particle trajectory

$$
\frac{\dot{\phi}}{\Omega_{s}}= \pm \sqrt{\frac{2}{\cos \phi_{s}}\left[\cos \phi+\phi \sin \phi_{s}\right]+C t e}
$$

## Phase space separatrix and particle trajectories

- (Bucket) separatrices: Below transition
- Above transition



| $\phi_{s}=0^{\circ}$ | $\phi_{s}=30^{\circ}$ |
| :--- | :--- |
| $\phi_{s}=60^{\circ}$ | $\phi_{s}=85^{\circ}$ |

$$
\begin{array}{ll}
\phi_{s} \Rightarrow \pi-\phi_{s} & \phi_{s}=180^{\circ} \\
\phi_{s}=120^{\circ} & \phi_{s}=150^{\circ} \\
\phi_{s}=95^{\circ}
\end{array}
$$

## Phase space separatrix and particle trajectories

- Particle trajectories: Below transition

$$
\phi_{s}=0^{\circ}
$$

$$
\phi_{s}=30^{\circ}
$$




- Change of variables if one wants to use $(\Phi, \Delta E)$ or $(\Delta t, \Delta E)$ instead of $(\Phi, d \Phi / d t)$

$$
\begin{aligned}
& \Delta \phi=\phi-\phi_{s} \\
= & \omega_{R F} \Delta t \\
= & h \omega_{s} \Delta t
\end{aligned}
$$

$$
\Delta p=\frac{\Delta E}{\beta_{s} c} \quad \dot{\phi}=-\frac{\eta h c}{\beta_{s} E_{s} R_{s}} \Delta E
$$

=> System of 2 equations to be solved

$$
\begin{gathered}
\frac{d}{d t}(\Delta E)=\frac{e \hat{V}_{R F} \omega_{s}}{2 \pi}\left[\sin \left(\phi_{s}+h \omega_{s} \Delta t\right)-\sin \phi_{s}\right] \\
\frac{d}{d t}(\Delta t)=-\frac{\eta}{\beta_{s}^{2} E_{s}} \Delta E
\end{gathered}
$$

- 2 questions

- $\Phi_{\text {min }}$ is obtained from the equation of the separatrix when $\dot{\phi}=0$

$$
\Rightarrow \cos \phi+\phi \sin \phi_{s}-\cos \left(\pi-\phi_{s}\right)-\left(\pi-\phi_{s}\right) \sin \phi_{s}=0
$$



- $\Delta E_{\max }^{\text {sep }}$ is obtained from the equation of the separatrix when $\phi=\phi_{s}$

$$
\Delta E_{\max }^{\operatorname{sep}}\left(\phi_{s}\right)=\sqrt{\frac{2 \beta_{s}^{2} E_{s} e \hat{V}_{R F}}{\pi h|\eta|}} G\left(\phi_{s}\right) \quad \text { with } \quad G\left(\phi_{s}\right)=\frac{\sqrt{\left|2 \cos \phi_{s}-\left(\pi-2 \phi_{s}\right) \sin \phi_{s}\right|}}{\sqrt{2}}
$$




$$
\phi_{s}=0^{\circ} \phi_{s}=30^{\circ} \quad \phi_{s}=60^{\circ} \quad \phi_{s}=85^{\circ}
$$

- nTOF bunch in the CERN PS (near transition)

| Average machine radius: $R[\mathrm{~m}]$ | 100 |
| :---: | :---: |
| Bending dipole radius: $\rho[\mathrm{m}]$ | 70 |
| $\dot{B}[\mathrm{~T} / \mathrm{s}]$ | 2.2 |
| $\hat{V}_{R F}[\mathrm{kV}]$ | 200 |
| $h$ | 8 |
| $\alpha_{p}$ | 0.027 |
| 20 kV at |  |
| injection |  |
| Longitudinal (total) emittance: $\varepsilon_{L}[\mathrm{eVs}]$ | 2 |
| Number of protons/bunch: $N_{b}[1 \mathrm{E} 10 \mathrm{p} / \mathrm{b}]$ | 800 |
| Norm. rms. transverse emittance: $\varepsilon_{x, y}^{*}[\mu \mathrm{~m}]$ | 5 |
| Trans. average betatron function: $\beta_{x, y}[\mathrm{~m}]$ | 16 |
| Beam pipe $[\mathrm{cm} \times \mathrm{cm}]$ | $3.5 \times 7$ |
| Trans. tunes: $Q_{x, y}$ | 6.25 |

Tracking

- The motion of the particles can be tracked turn by turn using the recurrence relation (between turn $n$ and turn $n+1$ )

$$
\begin{aligned}
& \Delta E_{n+1}=\Delta E_{n}+e \hat{V}_{R F}\left[\sin \phi_{n}-\sin \phi_{s}\right] \\
& \phi_{n+1}=\phi_{n}-\frac{2 \pi h \eta}{\beta_{s}^{2} E_{s}} \Delta E_{n+1}
\end{aligned}
$$

Tracking applied to the nTOF bunch at PS injection

## $\phi_{s}=0 \mathrm{deg}$



One can show (but the detailed computation is beyond the scope of this course) that
$\frac{Q_{s}(\phi)}{Q_{s}(0)}=\frac{\pi}{2 K_{c e i 1}\left[\sin ^{2}(\phi / 2)\right]}$
$K_{c e i 1}(x)=\int_{0}^{\pi / 2} \frac{d y}{\sqrt{1-x \sin ^{2} y}}$
 of the first kind


Tracking applied to the nTOF bunch at PS injection
$\phi_{s}=20 \mathrm{deg}$

$$
n_{\max }=782=1 / Q_{s}
$$



## Bucket height near transition (with "adiabatic" theory)

- Case of a stationary bucket in the PS with the nTOF bunch from injection (~ 2.4 GeV total energy) till top energy ( $\sim 20 \mathrm{GeV}$ total energy) assuming a constant RF voltage ( 200 kV )



## Nonadiabatic theory needed "close" to transition

- Reminder: the (general, nonlinear) equations, which have to be solved, using the variables $(\Delta \Phi, \Delta E)$, are

$$
\begin{aligned}
\frac{d \Delta \phi}{d t} & =-\frac{h \eta \omega_{s}}{\beta_{s}^{2} E_{s}} \Delta E \\
\frac{d \Delta E}{d t} & =\frac{e \hat{V}_{R F} \omega_{s}}{2 \pi}\left[\sin \left(\phi_{s}+\Delta \phi\right)-\sin \phi_{s}\right]
\end{aligned}
$$

- Assuming here only small amplitude particles

$$
\frac{d \Delta E}{d t}=\frac{e \hat{V}_{R F} \omega_{s}}{2 \pi}\left[\sin \left(\phi_{s}+\Delta \phi\right)-\sin \phi_{s}\right] \approx \frac{e \hat{V}_{R F} \omega_{s}}{2 \pi} \cos \phi_{s} \Delta \phi
$$

## Nonadiabatic theory needed "close" to transition

$\Rightarrow \quad \frac{d}{d t}\left(\frac{\beta_{s}^{2} E_{s}}{h \eta \omega_{s}} \frac{d \Delta \phi}{d t}\right)-\frac{e \hat{V}_{R F} \omega_{s}}{2 \pi} \cos \phi_{s} \Delta \phi=0$
where in general $\beta_{s}, E_{s}, \eta$ and $\omega_{s}$ depend on time

- Until now we assumed that these parameters were slowly moving => Adiabatic theory
- However, close to transition the particle will not be able to catch up with the rapid modification of the bucket shape and a nonadiabatic theory is needed


## Nonadiabatic theory needed "close" to transition

- Neglecting the slow time variations of all the parameters except $\frac{\eta}{E_{s}}$,
one has to solve

$$
\frac{d}{d t}\left(\frac{E_{s}}{\eta} \frac{d \Delta \phi}{d t}\right)-\frac{h e \hat{V}_{R F} \omega_{s}^{2} \cos \phi_{s}}{2 \pi \beta_{s}^{2}} \Delta \phi=0
$$

Assuming then that $\gamma=\gamma_{t}+\dot{\gamma} t$, with $t=0$ at transition,

$$
\begin{gathered}
-\eta=\frac{1}{\gamma_{t}^{2}}-\frac{1}{\gamma^{2}} \approx \frac{2 \dot{\gamma} t}{\gamma_{t}^{3}} \quad E_{s}=\gamma E_{0} \approx \gamma_{t} E_{0} \\
\frac{\eta}{E_{s}} \approx-\frac{2 \dot{\gamma} t}{\gamma_{t}^{4} E_{0}}
\end{gathered}
$$

## Nonadiabatic theory needed "close" to transition

- The (small amplitude) equation which needs to be solved close to transition is

$$
\frac{d}{d t}\left(\frac{T_{c}^{3}}{|t|} \frac{d \Delta \phi}{d t}\right)+\Delta \phi=0
$$

with $T_{c}$ a nonadiabatic time defined by (with $E_{0}$ in eV )

$$
T_{c}=\left(\frac{\beta_{s}^{2} E_{0} \gamma_{t}^{4}}{4 \pi f_{s}^{2} \dot{\gamma} h \hat{V}_{R F}\left|\cos \phi_{s}\right|}\right)^{1 / 3}
$$



## Nonadiabatic theory needed "close" to transition

- This equation can be solved but the detailed computation is beyond the scope of this course => See for instance (for those interested)
- K.Y. Ng, "Physics of Intensity Dependent Beam Instabilities", World Scientific (2006), p. 691
- E. Métral, USPAS 2009 course, Albuquerque, USA:

Nonadiabatic theory needed "close" to transition

- Numerical (analytical) result for the case of the nTOF bunch in the CERN PS





## Double RF systems

- Show that the motion of the particles can be tracked turn by turn using the recurrence relation (between turn $n$ and turn $n+1$ )

$\qquad$ Double RF systems $\quad \frac{h_{2}}{h}=2 \quad \phi_{s}=\phi_{s 2}=0$




LESSON V

Measurement of the longitudinal bunch profile and Tomography

The pyHEADTAIL simulation code (by Benoit Salvant)

## Measurement of the longitudinal bunch profile

=> WALL CURRENT MONITOR = Device used to measure the instantaneous value of the beam current

J. Belleman

A Wall Current Monitor

## Tomography

TOMOSCOPE (developed by S. Hancock, CERN/BE/RF)

The aim of TOMOGRAPHY is to estimate an unknown distribution (here the 2D longitudinal distribution) using only the information in the


## See Tutorial by Benoit Salvant

