

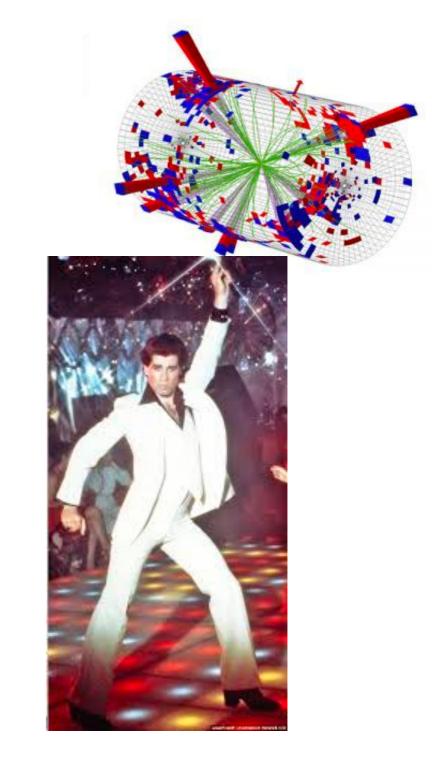


### DisCo Decorrelation:

Robustifying classifiers and automating the ABCD method

David Shih

4th IML Workshop October 23, 2020



## Work done in collaboration with







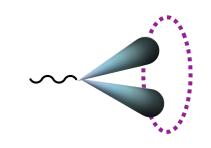
## Motivation: beyond classification

There has been enormous progress in the past ~5 years in improving jet classifiers with deep learning.

Now there is increasing interest in applications of deep learning to other issues necessary for realistic applications, beyond raw classification performance.

One important issue is the need for **robust classifiers** which are stable against variations in an auxiliary feature.

- data vs. simulation validation
- data-driven background estimation
- reducing systematic uncertainties

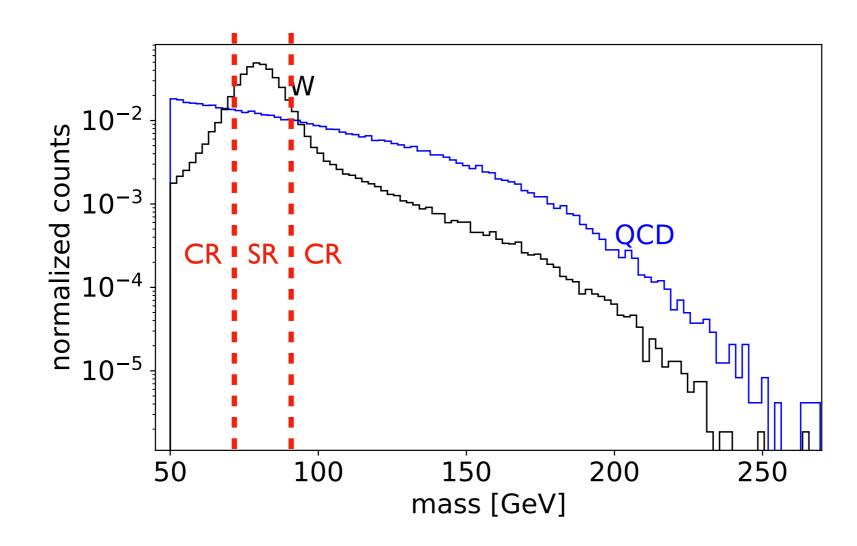


## Motivation: beyond classification

#### VS.

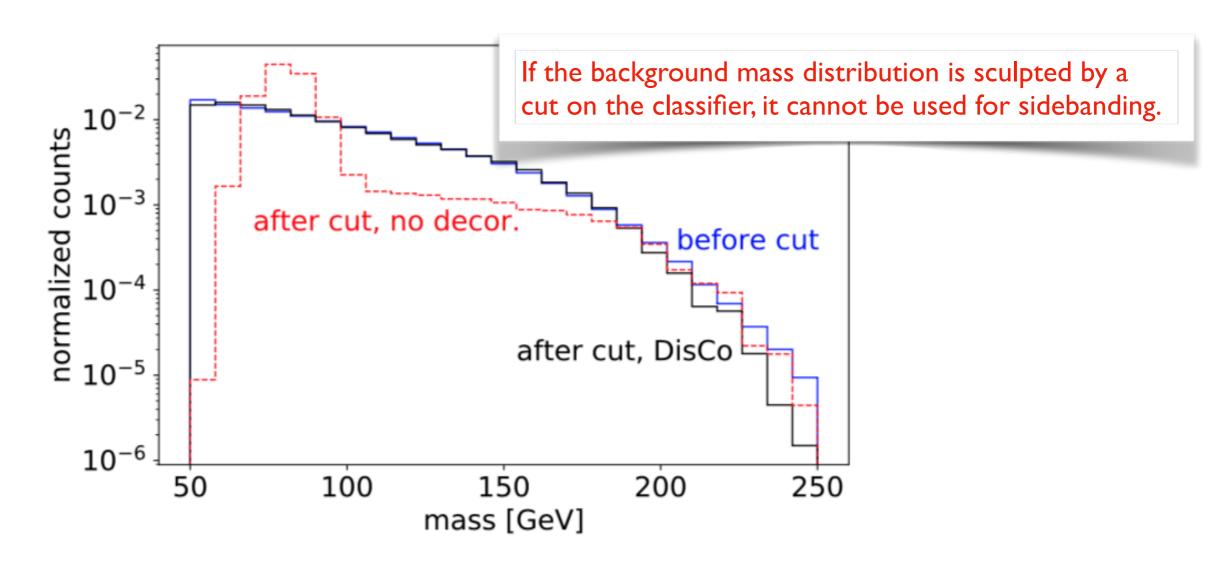
#### Example: boosted hadronic W tagging





Typically use jet mass to define signal and control regions in data, for validation and/or background estimation.

## Motivation: beyond classification



Would like a classifier that doesn't "learn" the jet mass, i.e. is statistically independent from it.

Challenging, because many of the input features to the classifier are highly correlated with mass.

State of the art in mass decorrelation methods was studied by ATLAS for boosted W-tagging in ATL-PHYS-PUB-2018-014

			Cut-base
Variable	Type	Reference	Cut-bas
$C_2, D_2$	Energy correlation ratios	[38]	
$ au_{21}$	<i>N</i> -subjettiness	[41]	or
$R_2^{ m FW}$	Fox-Wolfram moment	[42]	
$ ilde{\mathcal{P}}$	Planar flow	[43]	DDT
$a_3$	Angularity	[44]	BDT
A	Aplanarity	[45]	
$Z_{\mathrm{cut}}, \sqrt{d_{12}}$	Splitting scales	[46, 47]	or
KtDR	$k_t$ -subjet $\Delta R$	[48]	

#### **Performance metrics:**

**R50**: I/[background efficiency (false positive rate) at 50% signal efficiency]

**JSD50**: Jensen-Shannon Divergence between bg mass histogram (all) and bg mass histogram (passing sig=50% cut)

## Dense NN (DNN)

Andreas Søgaard / University of Edinburgh

#### **ATLAS** Simulation Preliminary Mass-decorrelation, 1 / JSD @ $\epsilon_{sig}^{rel} = 50\%$ $\sqrt{s} = 13 \text{ TeV}$ MVA: Analytical: 10<sup>5</sup> W jet tagging • Z<sub>NN</sub> • τ<sub>21</sub> $p_{_T}\!\in[200,500]\,\text{GeV}$ $^{\circ}$ $Z_{\mathsf{ANN}}$ D<sub>2</sub> Z<sub>Adaboost</sub> 10<sup>4</sup> $\circ$ $\mathsf{D}_2^{k-\mathsf{NN}}$ Statistical limit ○ Z<sub>uBoost</sub> D<sub>2</sub> Less sculpting o D<sub>2</sub>CSS 10<sup>3</sup> 10<sup>2</sup> $\alpha$ =0.3 10 Greater separation → Maximal sculpting 10<sup>2</sup> 10 Background rejection, 1 / $\epsilon_{bkq}^{rel}$ @ $\epsilon_{siq}^{rel}$ = 50%

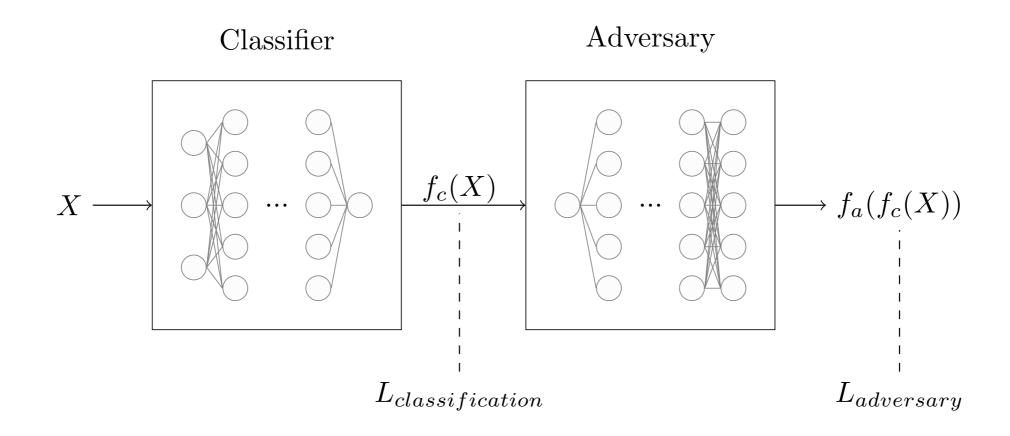
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Background rejection, 1 /  $\epsilon_{bkg}^{rel}$  @  $\epsilon_{sig}^{rel}$  = 50%

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#### Adversarial decorrelation

Louppe et al 1611.01046, Shimmin et al 1703.03507

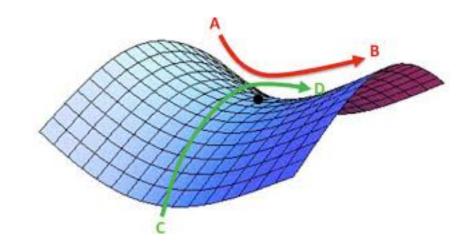


$$L_{\text{tagger}} = L_{\text{classification}} - \lambda L_{\text{adversary}}$$

Idea: train a second neural network (the "adversary") that attempts to predict the mass from the classifier output.

If classifier and mass are independent, adversary will fail.

#### Alternatives to adversaries



Adversaries are notoriously tricky to train — saddle point optimization

$$\min_{\theta_{\text{clf}}} \max_{\theta_{\text{adv}}} L_{\text{clf}}(y(\theta_{\text{clf}})) - \lambda L_{\text{adv}}(y(\theta_{\text{clf}}), m; \theta_{\text{adv}})$$

Would be great if we could achieve the same performance but with a convex regularizer term

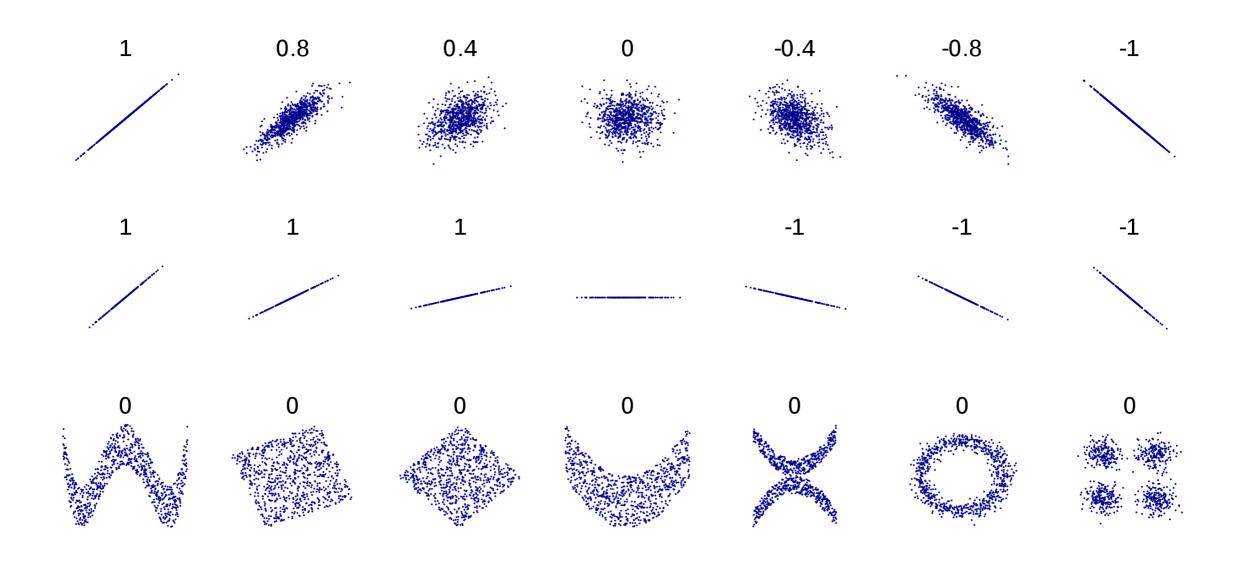
$$\min_{\theta_{\text{clf}}} L_{\text{clf}}(y(\theta_{\text{clf}})) + \lambda C_{\text{reg}}(y(\theta_{\text{clf}}), m)$$

First idea: can we just use Pearson correlation coefficient?

$$C_{\text{reg}} = R(y, m) \propto \sum_{i} y_{i} m_{i}$$

Problem: this only measures linear correlations

### Pearson correlation



y and m can be highly correlated yet R=0

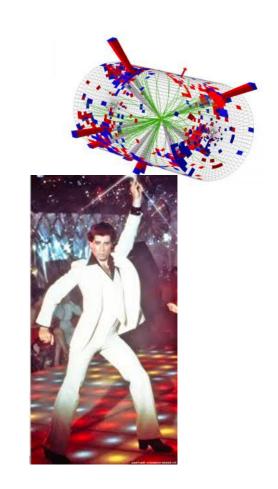
## Distance correlation ("DisCo")

$$dCov^{2}(X,Y) = \langle |X - X'||Y - Y'|\rangle$$

$$+ \langle |X - X'|\rangle\langle |Y - Y'|\rangle$$

$$- 2\langle |X - X'||Y - Y''|\rangle$$

(Szekely, Rizzo, Bakirov 2007; Szekely & Rizzo 2009)

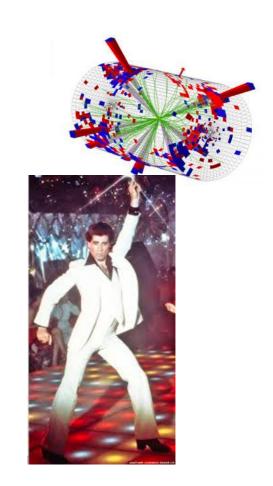


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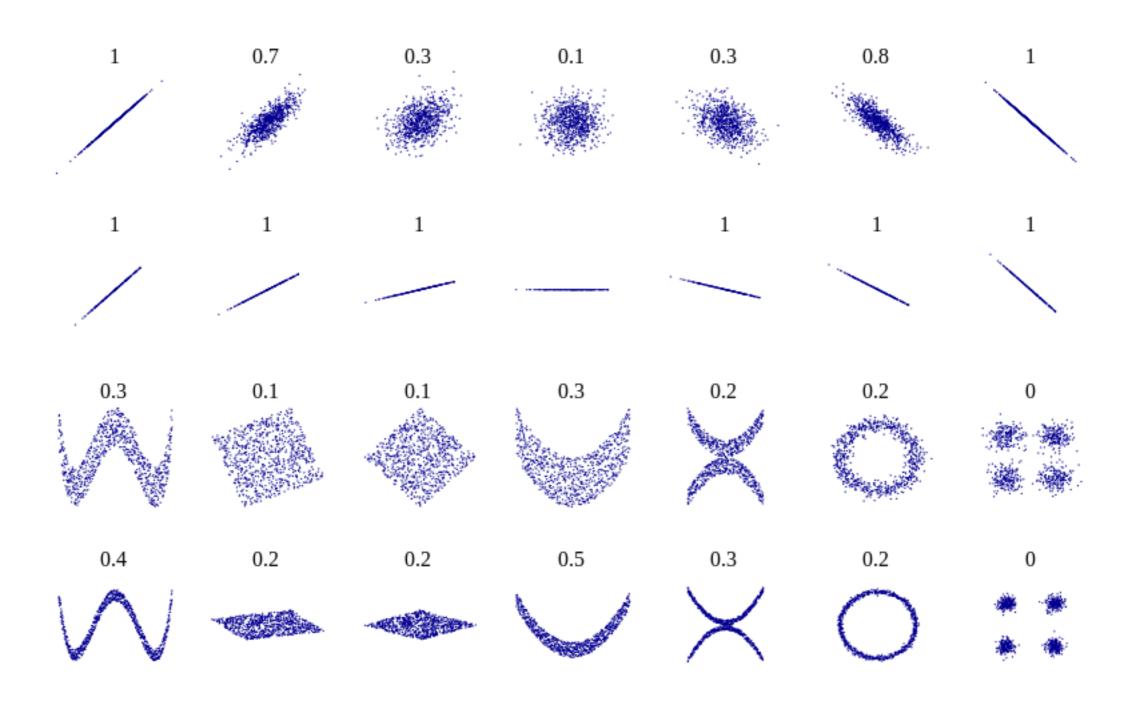
(Szekely, Rizzo, Bakirov 2007; Szekely & Rizzo 2009)

- Zero iff X,Y are statistically independent; positive otherwise
- Tractable, can be estimated from finite samples
- Idea: Add DisCo to loss function during classifier training

$$L = L_{classifier}(\vec{y}, \vec{y}_{true}) + \lambda \, dCorr_{y_{true}=0}^{2}(\vec{m}, \vec{y})$$

Gregor Kasieczka & DS, PRL 125 (2020), 2001.05310

## Distance correlation ("DisCo")



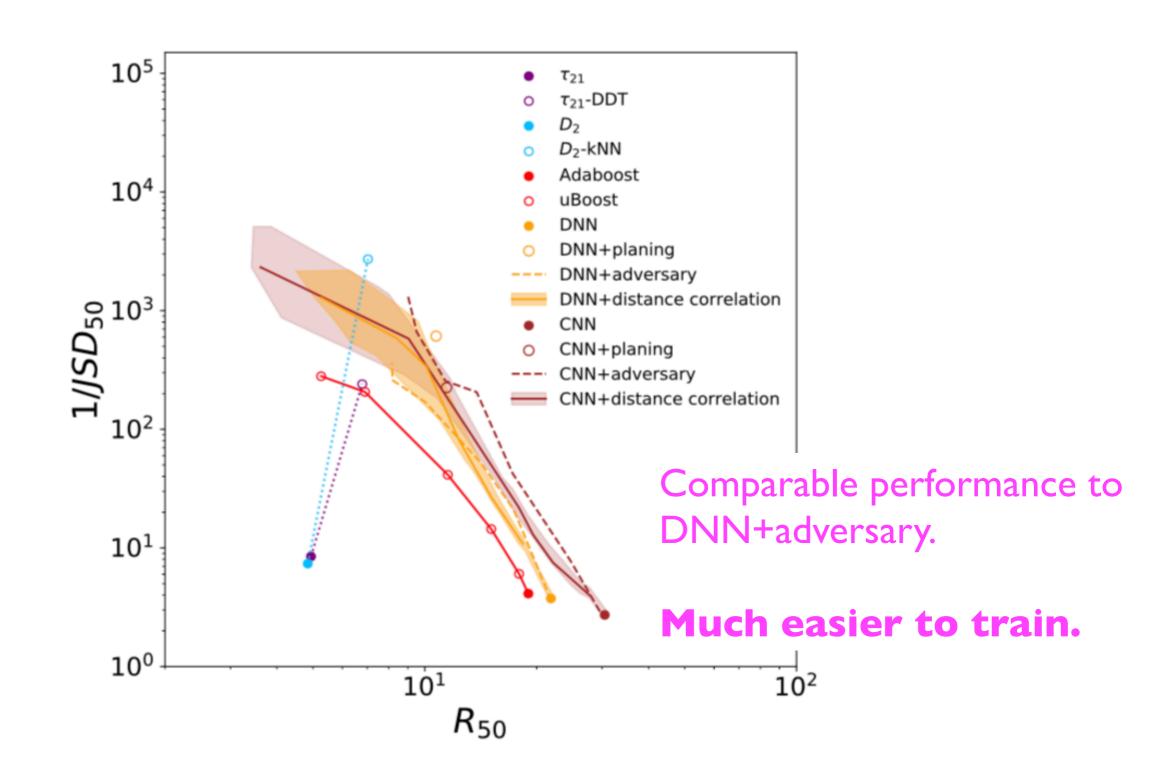
Disco is sensitive to nonlinear correlations!

#### DisCo Decorrelation

Gregor Kasieczka & DS, PRL 125 (2020), 2001.05310

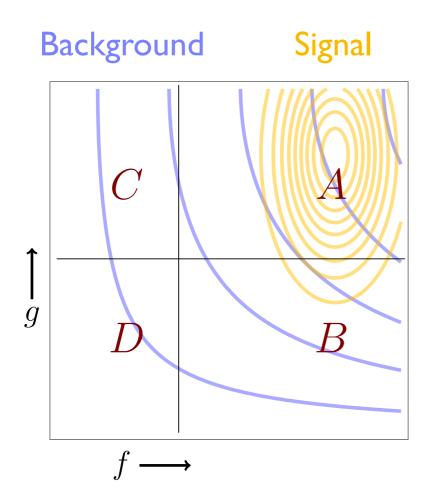
Our recast of the ATLAS study using Pythia8 + Delphes + FastJet plugins

Samples available on **Zenodo** 



#### **ABCD Method**

Another place where statistically independent features are required is the widely used "ABCD method" for data-driven background estimation



If f and g are statistically independent for the background, then:

$$N_{A,bg} = \frac{N_{B,bg} N_{C,bg}}{N_{D,bg}}$$

Usually features f and g are simple kinematic quantities chosen "by-hand"...

#### **ABCDisCo**

Kasieczka, Nachman, Schwartz & DS 2007.14400



# Idea: could construction of f and/or g be automated using NNs+DisCo?

Single ABCDisCo: decorrelate NN classifier against fixed feature (eg mass)

$$\mathcal{L}[f(X)] = \mathcal{L}_{\text{classifier}}[f(X), y] + \lambda \, d\text{Corr}_{y=0}^{2}[f(X), X_{0}]$$

Double ABCDisCo: decorrelate two NN classifiers against each other

$$\mathcal{L}[f,g] = \mathcal{L}_{\text{classifier}}[f(X),y] + \mathcal{L}_{\text{classifier}}[g(X),y] + \lambda \, d\text{Corr}_{y=0}^{2}[f(X),g(X)]$$

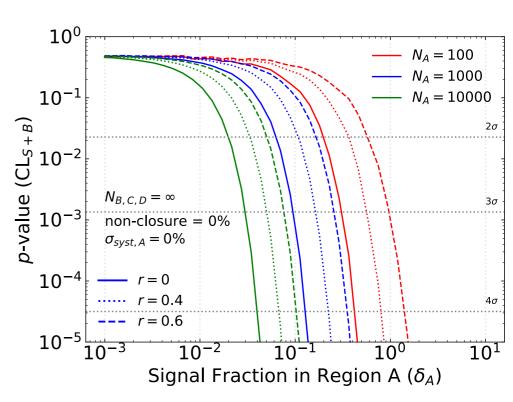
### Role of signal contamination

$$N_{A,bg} = \frac{N_{B,bg} N_{C,bg}}{N_{D,bg}} \qquad N_{A,bg} \approx \frac{N_B N_C}{N_D}$$

Key point (neglected in previous analyses?): can only estimate background in A using data in B,C,D provided that the signal contamination in B,C,D is negligible relative to the signal fraction in A.

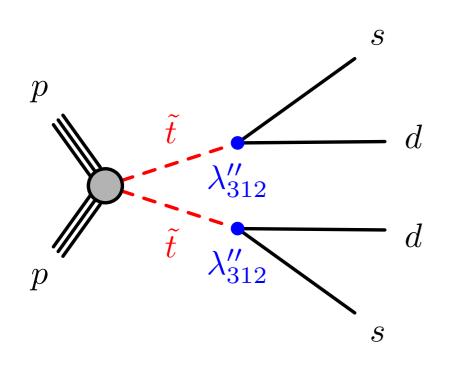
$$r = \left(rac{N_{A,s}}{N_{A,b}}
ight)^{-1} \left(rac{N_{B,s}}{N_{B,b}} + rac{N_{C,s}}{N_{C,b}} - rac{N_{D,s}}{N_{D,b}}
ight)$$

otherwise p-values are biased



### ATLAS paired dijet resonance search

1710.07171, 13 TeV, 36/fb [see also CMS version 1808.03124]



Counting experiment in bins of

$$m_{\text{avg}} = \frac{1}{2} (m_{\text{dijet 1}} + m_{\text{dijet 2}})$$

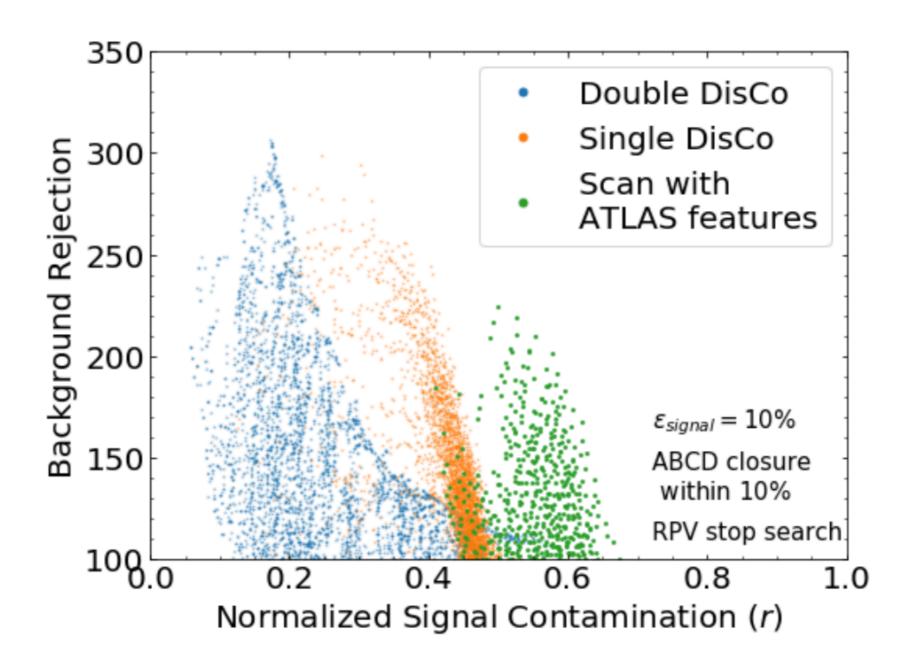
Uses ABCD method for background estimation with features

$$A_{\text{mass}} = \frac{1}{m_{\text{avg}}} | m_{\text{dijet 1}} - m_{\text{dijet 2}} |$$

$$|\cos heta^*| = ext{angle of squark with}$$
 beamline in squark-squark rest frame

#### **ABCDisCo**

Kasieczka, Nachman, Schwartz & DS 2007.14400



Can significantly reduce signal contamination and boost background rejection!

#### Conclusions

Decorrelating NNs against auxiliary features is a fascinating topic with many important applications to the LHC and beyond.

Adding a simple regularizer term based on Distance Correlation to the loss function achieves state-of-the-art performance for W-tagging.

DisCo can also be used to effectively automate feature construction for the ABCD method, simultaneously boosting background rejection and reducing signal contamination.

Stay tuned, more applications to come!

Applications to real-world issues such as Al bias and algorithmic fairness?

# Thanks for your attention!

# Backup

## Previous approaches

• Data "planing" [old idea, named and studied in 1709.10106, 1908.08959]

$$w_{i,C}|_{x_i \text{ in bin } j} = A_C \frac{1}{n_i}$$

- reweight training data to flatten mass distribution
- very simple and potentially powerful, but cannot guarantee full statistical independence
- Designed decorrelated taggers DDT [1603.00027]

$$\tau_{21}^{DDT} = \tau_{21} - a \times \log \frac{m^2}{p_T \mu}$$

- Removes most of the dependence of  $\tau_{21}$  on mass

## Previous approaches

Nonlinear subtraction via kNN regression

$$D_2^{k-\text{NN}} = D_2 - D_2^{(16\%)}$$

- Use kNN regression to remove dependence on mass and pT for a single cut efficiency
- Convolved SubStructure CSS [1710.06859]

$$\frac{1}{\sigma} \frac{d\sigma}{dx} \mapsto \frac{1}{\sigma} \frac{d\sigma}{dx_{\text{CSS}}} = \frac{1}{\sigma} \frac{d\sigma}{dx} \otimes F_{\text{CSS}}(x|\alpha, \Omega_D),$$

- Generalization of DDT
- Convolve variable with shape function
- uBoost [1305.7248]
  - Modified BDT, adaptive boosting for classification performance and uniformity at fixed selection efficiency