

Machine Learning for LHC Theory

ACAT 2021

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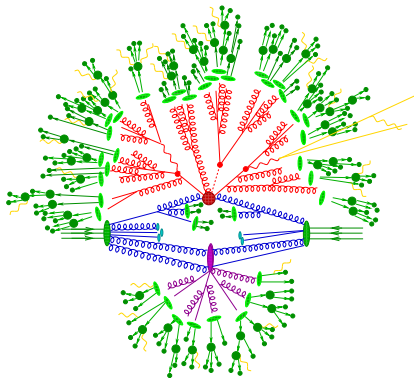
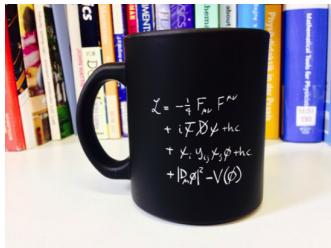
AI Decoded: Towards Sustainable, Diverse,
Performant and Effective Scientific Computing

Anja Butter

ITP, Universität Heidelberg

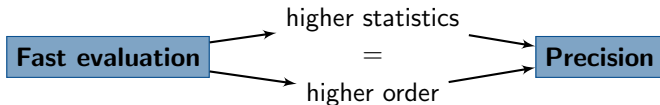
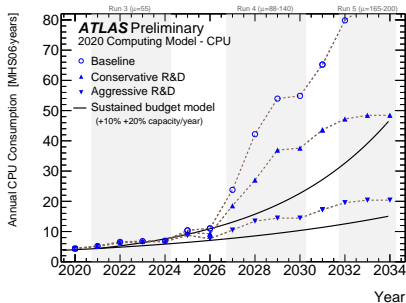
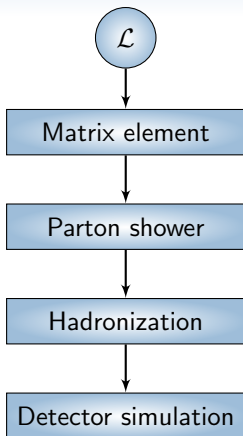


First principle based precision simulations



Unique advantage of our field!

Precision simulations with limited resources



Boosting standard event generation...

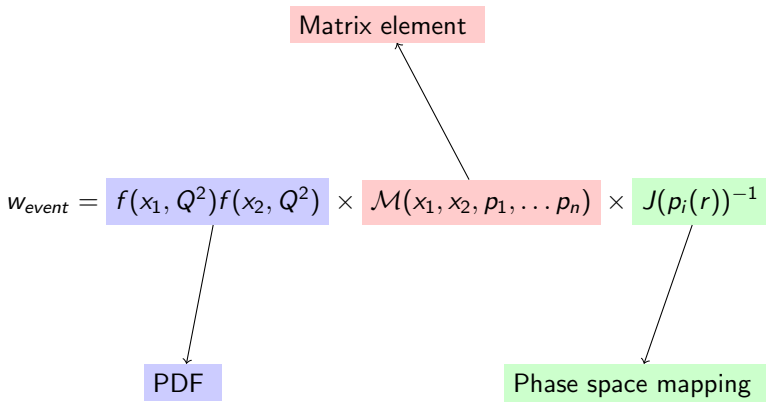
1. Generate phase space points

2. Calculate event weight

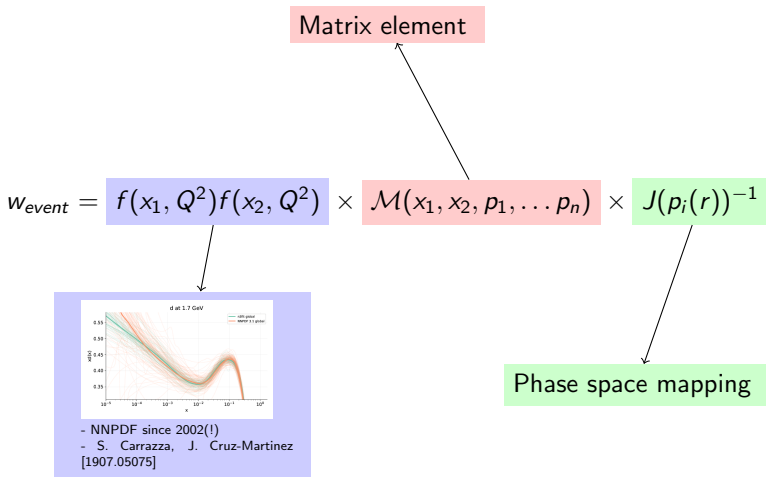
$$w_{event} = f(x_1, Q^2)f(x_2, Q^2) \times \mathcal{M}(x_1, x_2, p_1, \dots, p_n) \times J(p_i(r))^{-1}$$

3. Unweighting via $r > w/w_{max}$
→ optimal for $w \approx 1$

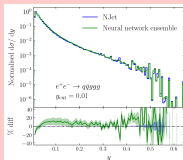
Boosting standard event generation...



Boosting standard event generation...

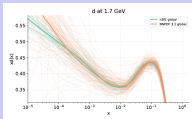


Boosting standard event generation...



- Amplitude estimation
- S. Badger, J. Bullock [2002.07516]
- J. Bendavid [1707.00028]

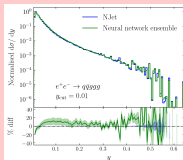
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- NNPDF since 2002(!)
- S. Carrazza, J. Cruz-Martinez [1907.05075]

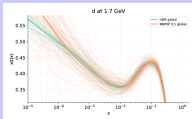
Phase space mapping

Boosting standard event generation...

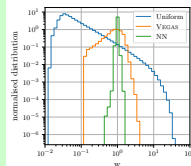


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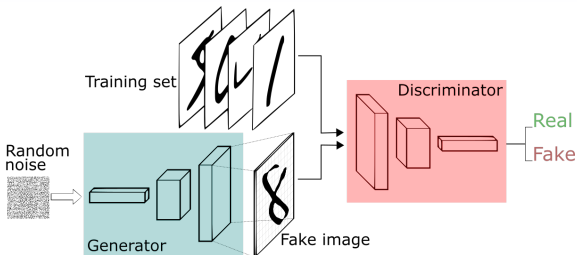


- Learn phase space distribution

Event simulation with generative models

1. Generative models for phase space sampling
 - **Control** over phase space density
2. Generative models for event generation
 - **Amplification** beyond training data?
 - Achieve high **precision**
 - Estimate **uncertainties**

Generative Adversarial Networks



Discriminator $[D(x_r) \rightarrow 1, D(x_c) \rightarrow 0]$

$$L_D = \langle -\log D(x) \rangle_{x \sim P_{Truth}} + \langle -\log(1 - D(x)) \rangle_{x \sim P_{Gen}} \rightarrow -2 \log 0.5$$

Generator $[D(x_c) \rightarrow 1]$

$$L_G = \langle -\log D(x) \rangle_{x \sim P_{Gen}}$$

⇒ **New statistically independent samples**

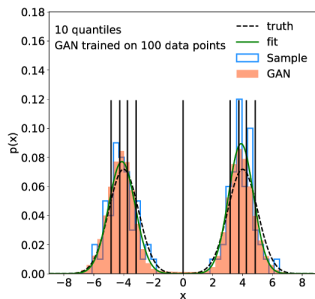
What is the statistical value of GANned events?

A.B., S. Diefenbacher, G. Kasieczka, B. Nachmann, T. Plehn, R. Winterhalder [2008.06545]

- Camel function
- Sample vs. GAN vs. 5 param.-fit

Evaluation on quantiles:

$$\text{MSE}^* = \sum_{j=1}^{N_{\text{quant}}} \left(p_j - \frac{1}{N_{\text{quant}}} \right)^2$$



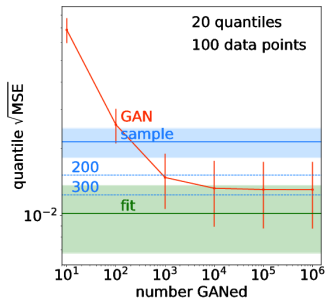
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Evaluation on quantiles:

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→ Amplification factor 2.5

Sparser data → bigger amplification

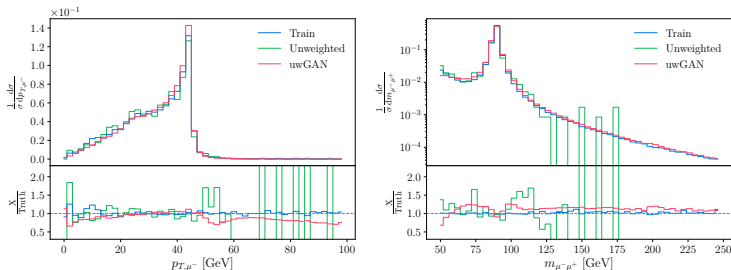
Training on weighted events

M. Backes, AB, T. Plehn, R. Winterhalder [2012.07873]

Low unweighting efficiencies \rightarrow bottleneck before training

\rightarrow Train on weighted events

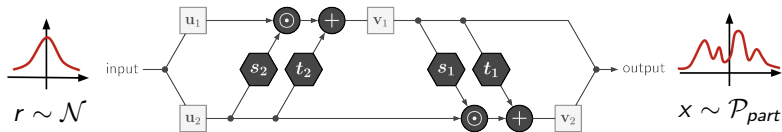
$$\rightarrow L_D = \langle -w \log D(x) \rangle_{x \sim P_{\text{Truth}}} + \langle -\log(1 - D(x)) \rangle_{x \sim P_{\text{Gen}}}$$



Populates high energy tails

Large amplification wrt. unweighted data!

Better control with invertible networks

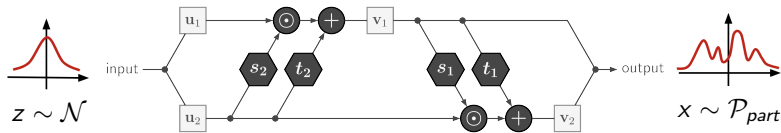


- + Tractable Jacobian
- + Enable correction for perfect precision
- + Fast evaluation in both directions

$$\begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} u_1 \cdot s_2(u_2) + t_2(u_2) \\ u_2 \end{pmatrix}$$

Training on density

Sherpa [2001.05478, 2001.10028]

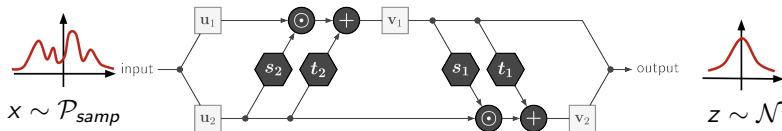


- $z \sim \mathcal{N} \rightarrow \text{NN} \rightarrow x \sim p_x$
- $p_x(x) = p_z(z) \cdot J_{\text{NN}}$
- Given target density $t(x)$
- Train NN to minimize $\log(p_z(z) \cdot J_{\text{NN}}/t(x))$

- Problem: Calculate $f(x)$ each time

Training on samples

A.B., T. Heime1, S. Hummerich, T. Krebs, T. Plehn, A. Rousselot, S. Vent [arXiv:2110.13632]



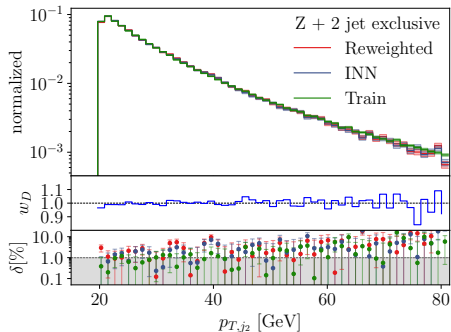
- $x \sim p_{\text{samples}} \rightarrow \text{NN} \rightarrow z$
- Train NN to ensure $z \sim \mathcal{N}$
- Loss: Maximize posterior over network weights:

$$\begin{aligned} -\log(p(\theta|x)) &= -\log(p(x|\theta)) - \log(p(\theta)) + \text{const.} \\ &= -\log(p(z|\theta)) - \log(J) - \log(p(\theta)) + \text{const.} \end{aligned}$$

Naive INN results

Inclusive Z+jets production

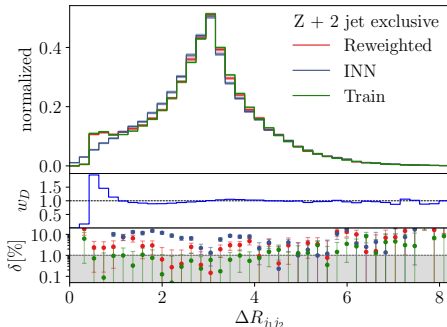
- INN easy to train
- Powerful baseline



Naive INN results

Inclusive Z+jets production

- INN easy to train
- Powerful baseline
- Challenges:
 - Topological holes
 - Sharp phase space features



How to deal with deviations?

I. Corrections through reweighting

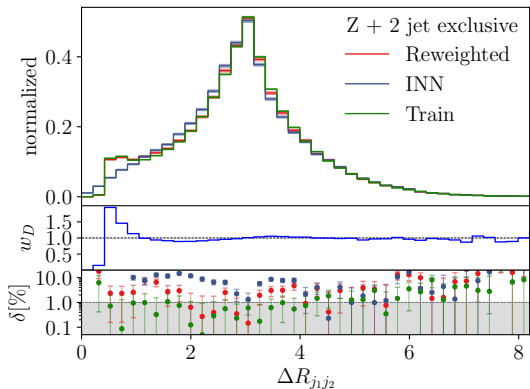
Discriminator

$$\begin{aligned}\mathcal{L} &= - \sum_{x \sim p_{data}} \log(D(x)) - \sum_{x \sim p_{INN}} \log(1 - D(x)) \\ &= - \int dx p_{data}(x) \log(D(x)) + p_{inn}(x) \log(1 - D(x))\end{aligned}$$

From variation we obtain

$$\begin{aligned}0 &= \frac{p_{data}(x)}{D(x)} - \frac{p_{inn}(x)}{1 - D(x)} \\ \Rightarrow \frac{p_{data}(x)}{p_{inn}(x)} &= \frac{D(x)}{1 - D(x)}\end{aligned}$$

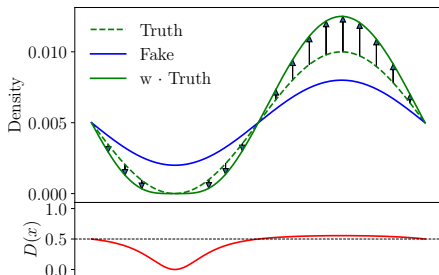
Reweighting the generated distributions



- + Close to perfect distribution after reweighting
- Yields weighted events

II. Discriminator improved training

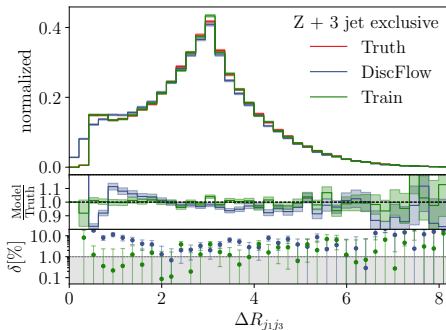
- Include discriminator information to improve training
- Discflow



$$\begin{aligned}\mathcal{L}_{\text{DiscFlow}} &= \sum_{i=1}^B w_D(x_i)^\alpha \left(\frac{\psi(x_i; c_i)^2}{2} - \log J(x_i) \right) \\ &\approx \int dx \underbrace{w_D(x)^\alpha P(x)}_{\text{reweighted truth}} \left(\frac{\psi(x; c)^2}{2} - \log J(x) \right)\end{aligned}$$

II. Discriminator improved training

- Include discriminator information to improve training
- Discflow

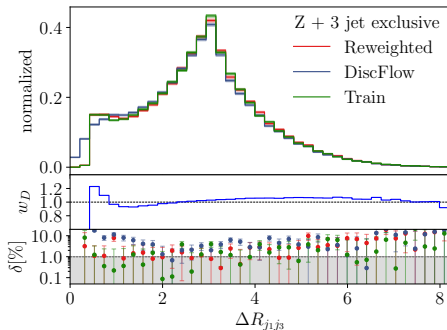


$$\mathcal{L}_{\text{DiscFlow}} = \sum_{i=1}^B w_D(x_i)^\alpha \left(\frac{\psi(x_i; c_i)^2}{2} - \log J(x_i) \right)$$

$$\approx \int dx \underbrace{w_D(x)^\alpha P(x)}_{\text{reweighted truth}} \left(\frac{\psi(x; c)^2}{2} - \log J(x) \right)$$

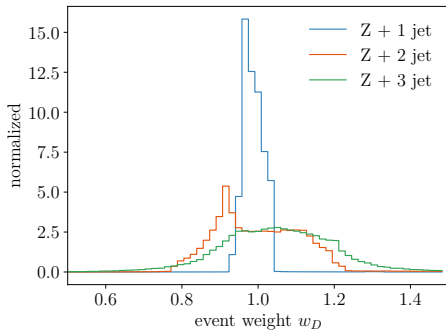
II. Discriminator improved training

- Include discriminator information to improve training
- Discflow + Reweighting

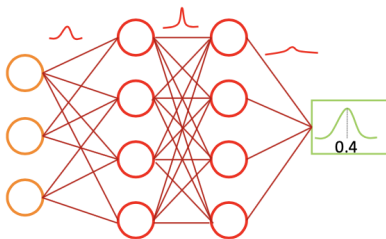
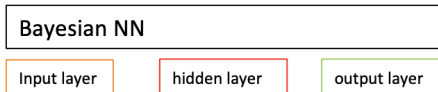


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Weight distribution after DiscFlow+Reweighting

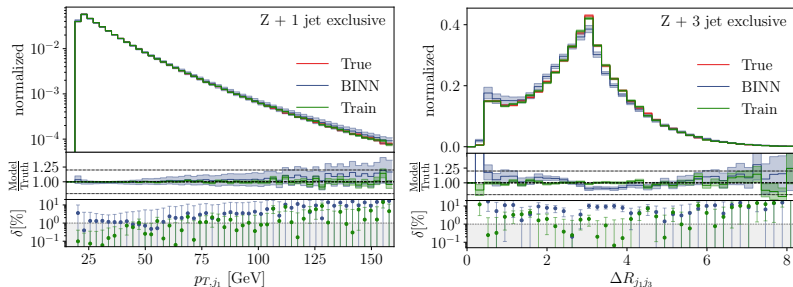


III. Addressing uncertainties



$$\mathcal{L} = \mathcal{L}_{INN} + KL_{prior}$$

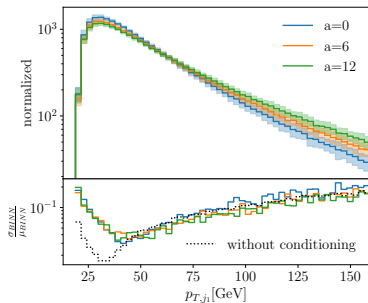
BINN results



- \Rightarrow BINN uncertainty captures convergence of the network \checkmark
- \Rightarrow BINN uncertainty does NOT capture where network fails

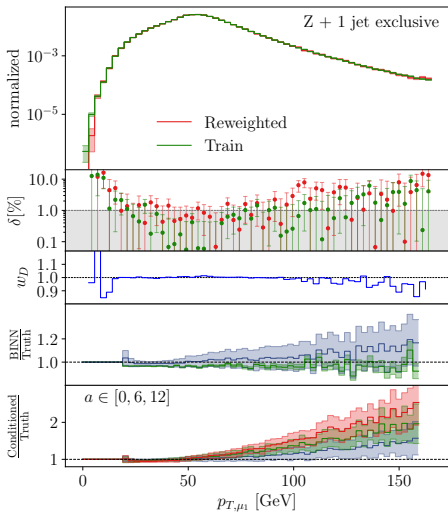
IV. Including external uncertainties through conditioning

$$w = 1 + a \left(\frac{p_{T,j_1} - 15 \text{ GeV}}{100 \text{ GeV}} \right)^2$$

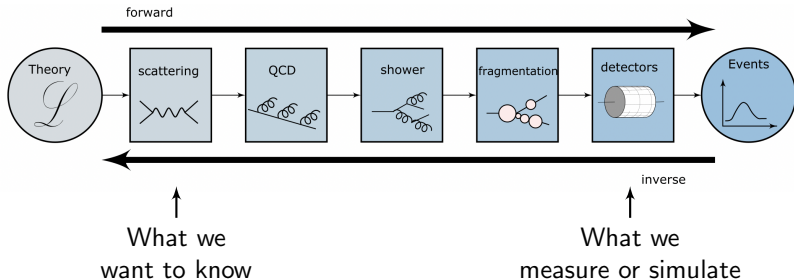


→ Include prior over α in BINN sampling

Overview on uncertainties

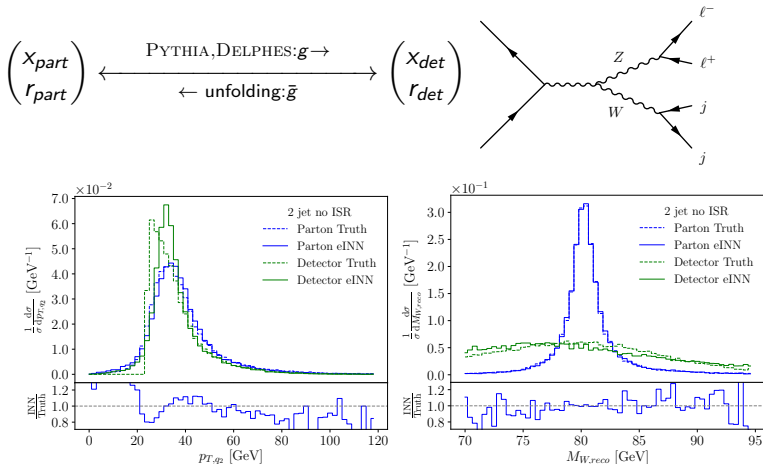


Can we invert the simulation chain?



- wish list:
- multi-dimensional
 - bin independent
 - statistically well defined

Inverting detector effects



multi-dimensional ✓ bin independent ✓ statistically well defined ?

Asking the right question

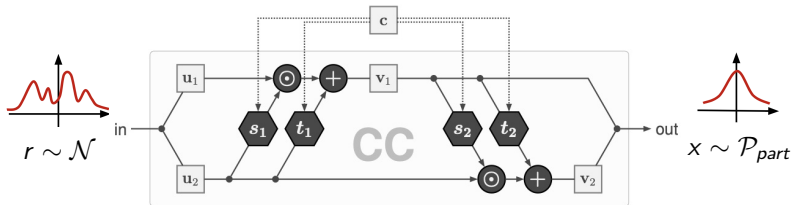
Given an event x_d , what is the probability distribution at parton level?
 → event generation conditioned on x_d

$$x_p \xleftarrow{g(x_p, f(x_d)) \rightarrow} r$$

← unfolding: $\bar{g}(r, f(x_d))$

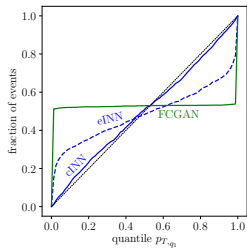
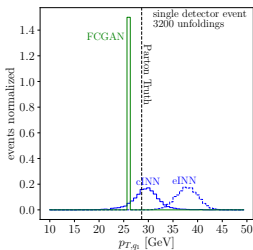
Minimizing the posterior

$$L = \langle 0.5 \|\bar{g}(x_p, f(x_d))\|_2^2 - \log |J| \rangle_{x_p \sim P_p, x_d \sim P_d} - \log p(\theta)$$



Condition INN on detector data [2006.06685]

$$\begin{array}{c}
 \xrightarrow{g(x_p, f(x_d))} \\
 x_p \longleftarrow r \\
 \longleftarrow \text{unfolding: } \bar{g}(r, f(x_d))
 \end{array}$$

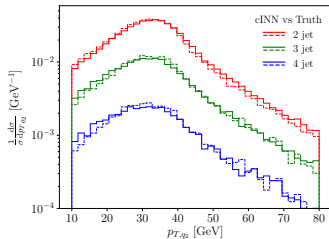
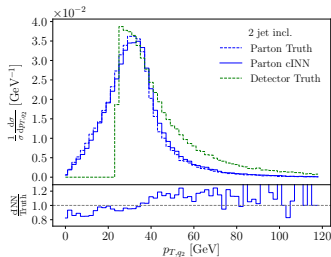


Inverting the full event

$pp > WZ > q\bar{q}l^+l^- + \text{ISR}$
 $\rightarrow 2/3/4 \text{ jet events}$

Train on inclusive dataset

Evaluate
exclusive 2/3/4 jet channels



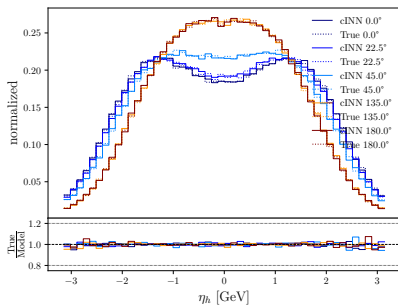
multi-dimensional ✓ bin independent ✓ statistically well defined ✓

Application to MEM

current work in progress with T. Martini, T. Heimes, S. Peitzsch, T. Plehn

- Single top production in association with Higgs
- Measure CP-phase in the top Yukawa coupling

$$\mathcal{L}(\alpha) = \prod_{i=1}^N \frac{1}{\sigma_{\text{fid}}(\alpha)} \int d^m z \frac{d^m \sigma(\alpha)}{dz_1 \dots dz_m} T(\vec{y}^{(i)}, \vec{z}) .$$



We can use ML ...

... to improve precision simulations in forward direction

... to **amplify** underlying statistics

... to achieve **precision** with discriminators

... to estimate the corresponding **uncertainties**

... to **invert** the simulation chain statistically