

Integration-By-Parts-like identities in Schwinger-Feynman-Lee-Pomeransky parametrization

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Multi-Loop calculations and Reductions

- Multi-loop, higher order calculations are demanded in high energy phenomenology; the number of Feynman integrals combinatorially explodes when we aim at higher order corrections for scattering amplitude calculations.
- Among such a large number of Feynman integrals, not all integrals are linearly independent, i.e., there exists a set of non-trivial linear relations.
- A standard way of generating linear relations among families of Feynman integrals relies upon Integration-By-Parts identities ([Chetyrkin et al. 1981](#)) over, for example, momentum space.
- In this talk, we will present another approach, namely a construction of IBP-like identities over Schwinger-Feynman parameters ([Chen 2020](#); [Sameshima 2019](#)).

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Feynman Integrals

Feynman integrals are given as **d -dimensional momentum integrals**, which are direct translation of Feynman diagrams. Let us fix a generic diagram, and consider the associated Feynman integral:

$$J = \int \frac{d^d l_1}{(2\pi)^d} \cdots \int \frac{d^d l_L}{(2\pi)^d} \frac{\text{Num}(l)}{D_1 \cdots D_K},$$

where the numerator is a polynomial of loop momenta and kinematic invariants.

We consider the following **scalar integrals**, in stead, adding auxiliary denominators:

$$J(\vec{\nu}) := \left(\prod_{j=1}^L \int \frac{d^d l_j}{(2\pi)^d} \right) \prod_{a=1}^N \frac{1}{D_a^{\nu_a}}.$$

Schwinger-Feynman Parametrizations

Using Schwinger trick and an identity $1 = \int_0^\infty d\rho \delta\left(\rho - \sum_{j=1}^N x_j\right)$, we obtain the following parametrizations (for simple derivations, e.g., see (Bitoun et al. 2019)).

- Schwinger parametrization:

$$I(\vec{\nu}) = \frac{1}{(4\pi)^{\frac{dL}{2}}} \left(\prod_{a=1}^N \int_{x_a=0}^{\infty} \frac{dx_a x_a^{\nu_a-1}}{\Gamma(\nu_a)} \right) \frac{\exp\left(-\frac{\mathcal{F}}{\mathcal{U}}\right)}{\mathcal{U}^{\frac{d}{2}}}$$

- Feynman parametrization:

$$I(\vec{\nu}) = \frac{1}{(4\pi)^{\frac{dL}{2}}} \Gamma(\omega) \left(\prod_{a=1}^N \int_{x_a=0}^1 \frac{dx_a x_a^{\nu_a-1}}{\Gamma(\nu_a)} \right) \frac{\delta\left(1 - \sum_{j=1}^N x_j\right)}{\mathcal{F}^\omega \mathcal{U}^{\frac{d}{2}-\omega}}$$

- Lee-Pomeransky parametrization:

$$I(\vec{\nu}) = \frac{1}{(4\pi)^{\frac{dL}{2}}} \frac{\Gamma\left(\frac{d}{2}\right)}{\Gamma\left(\frac{d}{2} - \omega\right)} \left(\prod_{a=1}^N \int_{x_a=0}^{\infty} \frac{dx_a x_a^{\nu_a-1}}{\Gamma(\nu_a)} \right) \mathcal{G}^{-\frac{d}{2}}$$

where $\omega = \sum_{a=1}^N \nu_a - \frac{dL}{2}$, \mathcal{U} , \mathcal{F} and $\mathcal{G} := \mathcal{U} + \mathcal{F}$ are graph polynomials.

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Differentiate then Integrate

Integration-By-Parts identities (Chetyrkin et al. 1981) are the outcomes of the translational invariance of Feynman integrals in momentum space:

$$\int d^d l_1 \cdots d^d l_L \frac{\partial}{\partial l_i} \cdot \left[q_k \prod_{a=1}^N \frac{1}{D_a^{\nu_a}} \right] = \text{surface term} = 0.$$

The surface term corresponding to $\frac{\partial}{\partial l_i} \cdot q_k$ is zero. Applying partial derivative, we can build a set of linear relations among Feynman integrals.

We follow the same spirit; for a fixed graph and the associated graph polynomial \mathcal{G} , we consider:

$$\left(\prod_a \int_{x_a=0}^{\infty} dx_a \right) \partial_i \left[f \mathcal{G}^{-\frac{d}{2}+1} \right] = \text{surface term},$$

where f is a monomial of parameters $[x_1, \dots, x_N]$. In SF parametrizations, the surface term is in general **non-zero** (Roman N. Lee et al. 2013). Some early discussions on surface terms are already appeared in literature, e.g., in (Bern et al. 1994).

Non-zero Surface Terms

Let us show an example of **non-zero surface term**: $f = 1, \partial_1 = \frac{\partial}{\partial x_1}$ case.

Using the fundamental theorem of calculus, we obtain:

$$\int_{x_1=0}^{\infty} dx_1 \partial_1 \mathcal{G}^{-\frac{d}{2}+1} = \mathcal{G}^{-\frac{d}{2}+1} \Big|_{x_1=\infty} - \mathcal{G}^{-\frac{d}{2}+1} \Big|_{x_1=0} = - \mathcal{G}^{-\frac{d}{2}+1} \Big|_{x_1=0},$$

where we have used the fact that $\mathcal{G}^{-\frac{d}{2}+1} \Big|_{x_1=\infty} = 0$ in the dimension regularization scheme. Hence, we have the following **non-zero surface term**:

$$(-) \int dx_2 \cdots \int dx_N \underbrace{\mathcal{G} \Big|_{x_1=0}}_{\text{Polynomials of } x_2 \cdots x_N} \mathcal{G}^{-\frac{d}{2}} \Big|_{x_1=0}.$$

We interpret it as a linear combination of integrals of **D_1 -reduced diagrams**.

Differential Forms

As a natural generalization of the above formalism, consider a generic $(N - 1)$ -form

$$f := \sum_i \varphi_i dx_1 \wedge \cdots \wedge \widehat{dx_i} \wedge \cdots \wedge dx_N,$$

where $\varphi_i, 1 \leq i \leq N$ is an arbitrary 0-form. Then we obtain

$$\begin{aligned} \int_{\Gamma} d \left(f \mathcal{G}^{-\frac{d}{2}} \right) &= \int_{\Gamma} \sum_i \frac{\partial \left(\mathcal{G}^{-\frac{d}{2}} \varphi_i \right)}{\partial x_i} (-)^{i-1} dx_1 \wedge \cdots \wedge dx_N \\ &= \int_{\Gamma} \left(\sum_i (-)^{i-1} \frac{\partial \varphi_i}{\partial x_i} \mathcal{G}^{-\frac{d}{2}} + \left(-\frac{d}{2} \right) \sum_i (-)^{i-1} \varphi_i \frac{\partial \mathcal{G}}{\partial x_i} \mathcal{G}^{-\frac{d}{2}-1} \right) \\ &\quad \times dx_1 \wedge \cdots \wedge dx_N \end{aligned}$$

If we apply Stokes' theorem, we will obtain IBP-like linear equations with **dimension shift**.

Dimension shift and Syzygies

We can remove such **dimension shift** by adding an additional constrain: a **syzygy**. Let $(\phi_0, \phi_1, \dots, \phi_N)$ be a set of polynomial that satisfies:

$$\phi_0 \mathcal{G} + \sum_i \phi_i \partial_i \mathcal{G} = 0.$$

Constructive algorithms and implementations are known (Cox et al. 2007), hence we obtain the following equation with **no dimension shift**:

$$\int_{\Gamma} d \left(f \mathcal{G}^{-\frac{d}{2}} \right) dx_1 \cdots dx_N = \int_{\Gamma} \left[\sum_{i=1}^N \left(\frac{\partial \phi_i}{\partial x_i} \right) + \frac{d}{2} \phi_0 \right] \mathcal{G}^{-\frac{d}{2}} dx_1 \cdots dx_N$$

When we combine the left hand side with Stokes' theorem (within the dimensional regularization scheme), we have the following **IBP-like equations in SFLP**:

$$(-) \sum_{i=1}^N \int_{\partial_i \Gamma} \left[\phi_i \mathcal{G}^{-\frac{d}{2}} \right]_{x_i=0} d^{N-1} x_i = \int_{\Gamma} \left[\frac{d}{2} \phi_0 + \sum_{i=1}^N \left(\frac{\partial \phi_i}{\partial x_i} \right) \right] \mathcal{G}^{-\frac{d}{2}} dx_1 \cdots dx_N$$

Syzygies as Generators

If $(\phi_0, \phi_1, \dots, \phi_N)$ satisfies the syzygy condition: $\phi_0 \mathcal{G} + \sum_i \phi_i \partial_i \mathcal{G} = 0$, clearly, for any polynomial e in $[x_1, \dots, x_N]$ (e.g., $e := x_j$), we obtain another:

$$(e\phi_0, e\phi_1, \dots, e\phi_N)$$

I.e., we can generate another equation by multiplying polynomials to a given $(\phi_0, \phi_1, \dots, \phi_N)$:

$$(-) \sum_{i=1}^N \int_{\partial_i \Gamma} \left[e\phi_i \mathcal{G}^{-\frac{d}{2}} \right]_{x_i=0} d^{N-1}x_i = \int_{\Gamma} \left[\frac{d}{2} e\phi_0 + \sum_{i=1}^N \left(\frac{\partial e \phi_i}{\partial x_i} \right) \right] \mathcal{G}^{-\frac{d}{2}} dx_1 \cdots dx_N$$

Looping over such a polynomial e in the parameter space, we can construct a set of non-trivial equations.

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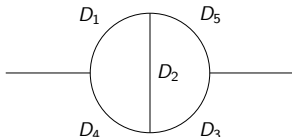
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Kite diagram

We will show a **full reduction** of the following **Kite** diagram:



The corresponding Lee-Pomeransky polynomial \mathcal{G} is:

$$\begin{aligned} & p^2 x_3 x_4 x_5 + p^2 x_2 x_4 x_5 + p^2 x_1 x_4 x_5 + x_4 x_5 + p^2 x_2 x_3 x_5 + p^2 x_1 x_3 x_5 + x_2 x_5 \\ & + x_1 x_5 + p^2 x_1 x_3 x_4 + x_3 x_4 + p^2 x_1 x_2 x_4 + x_2 x_4 + p^2 x_1 x_2 x_3 + x_2 x_3 + x_1 x_3 + x_1 x_2 \end{aligned}$$

One can obtain, running an IBP reduction automation (e.g., Kira ([Maierhöfer et al. 2018](#))), **two** Master Integrals:

$$\sim I(1, 1, 1, 0, 0)$$

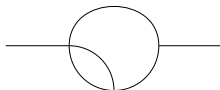
$$\sim I(1, 0, 1, 1, 1)$$

Subdiagrams

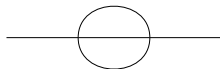
If we **contract** the central edge D_2 of the kite diagram, we obtain the following glasses diagram:



If we are to contract another edge, we will have a **massless tadpole**, a scale-less diagram. Such a scale-less diagram is zero. Similarly, we obtain four types of non-zero subdiagrams (moon diagrams):



and a non-zero sunset diagram:



Including the sunset diagram, these are the only surviving (sub-)diagrams.

“Pinching” of edge contraction

This edge contraction, or simply pinching, of a graph-theoretical procedure has appeared in the Surface Term. From the kite to the glasses:

$$\frac{1}{D_1 D_2 D_3 D_4 D_5} \rightarrow \frac{1}{D_1 D_3 D_4 D_5}$$

we eliminate the central edge D_2 and obtain a subdiagram.

When we set $\nu_2 = 0$ within LP parametrization, we will immediately face troubles:

$$\int_{\mathbb{R}_>} \frac{dx_1 x_1^{-1}}{\Gamma(0)} \left(\prod_{a \neq 2} \int_{\mathbb{R}_>} dx_a \right) \mathcal{G}^{-\frac{d}{2}}.$$

However, the “ D_2 absence” can be achieved by setting the corresponding parameter x_2 to be zero:

$$\mathcal{G} \mapsto \mathcal{G}|_{x_2=0}.$$

Cauchy’s integral formula gives us the same prescription:

$$\oint_{\mathcal{C}} \frac{dx_2}{2\pi i x_2} \mathcal{G} = \mathcal{G}|_{x_2=0}.$$

We use Singular ([Decker et al. 2018](#)) to construct the syzygies

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syzygies of kite:
[0, 0, (p^4)*x3*x5+(-p^4)*x4*x5+(-2*p^2)*x1+(p^2)*x3+(p^2)*x5, (p^4)*x3*x5+(p^4)*x4*x5+(-p^2)*x3+(p^2)*x5-2, (-p^4)*x3*
x5+(-p^4)*x4*x5+(-p^2)*x3+(-2*p^2)*x4+(-p^2)*x5, (2*p^2)*x1+(2*p^2)*x5+2],
[0, 0, (2*p^4)*x1*x5+(2*p^4)*x2*x5+(p^4)*x4*x5+(2*p^2)*x1+(p^2)*x2, (-p^4)*x4*x5+(-p^2)*x2+2, (p^4)*x4*x5+(p^2)*x2+(2*p
^2)*x4, (-2*p^4)*x1*x5+(-2*p^4)*x5^2+(-2*p^2)*x1+(-4*p^2)*x5-2],
[0, 0, (p^2)*x2*x3+(2*p^2)*x1*x4+(p^2)*x2*x4+(p^2)*x3*x4+(-p^2)*x3*x5+(p^2)*x4*x5+2*x1+x2-x3+2*x4-x5, (p^2)*x2*x3+(p^2
)*x2*x4+(p^2)*x3*x4+(-p^2)*x3*x5+(-p^2)*x4*x5+x2-x3-x5, (-p^2)*x2*x3+(-p^2)*x2*x4+(-p^2)*x3*x4+(p^2)*x3*x5+(p^2)*x4*
x5-x2+x3+x5, (-2*p^2)*x1*x4+(-2*p^2)*x4*x5-2*x1-2*x4],
[0, 0, (2*p^2)*x1*x3+(p^2)*x2*x3+(p^2)*x2*x4+(p^2)*x3*x4+(p^2)*x3*x5+(-p^2)*x4*x5+x2+x3+x5, (-p^2)*x2*x3+(-p^2)*x2*x4+
(-p^2)*x3*x4+(p^2)*x3*x5+(p^2)*x4*x5-x2+x3+x5, (p^2)*x2*x3+(p^2)*x2*x4+(p^2)*x3*x4+(-p^2)*x3*x5+(-p^2)*x4*x5+x2-x3-x
5, (-2*p^2)*x1*x3+(-2*p^2)*x3*x5-2*x3-2*x5],
[0, 0, (2*p^2)*x1^2+(2*p^2)*x1*x2+(p^2)*x1*x4+x1+x2+x4, (-p^2)*x1*x4+x1+x2-x4, (p^2)*x1*x4-x1-x2-x4, (-2*p^2)*x1^2+(-2*p
^2)*x1*x5-2*x1],
[0, 1, (p^2)*x3+(-p^2)*x4, (p^2)*x3+(p^2)*x4+1, (-p^2)*x3+(-p^2)*x4-1, -1],
[0, (p^2)*x1+(p^2)*x5+1, (p^2)*x1+(-p^2)*x5, 1, -1, (-p^2)*x1+(-p^2)*x5-1],
[2, -x1, -x1-2*x2-x4, x4, -x4, x1]

```

Figure: A set of syzygies constructed with Singular.

and a built-in linear solver of Maxima CAS ([Maxima 2017](#)) to solve a linear system of equations.

We use “bottom-up” approach; building a system of equations from lower sectors until we obtain a full reduction within each sector (Laporta algorithm (Laporta 2000)). E.g., on the sunset sector, all the surface terms fall into massless tadpoles, hence zeros, and we eventually obtain a master integral $I(1, 1, 1, 0, 0)$ in the sunset sector.

A syzygy on the sunset sector is

$$[p^2 x_3 + 2, -p^2 x_1 x_3 - x_3 - 2 x_1, p^2 x_2 x_3 + x_3, -p^2 x_3^2 - x_3].$$

When we plug this list into our IBP-like identity formula, we obtain:

$$0 = \Gamma\left(\frac{3(d-2)}{2}\right) (d-3) I(1, 1, 1, 0, 0) + \Gamma\left(\frac{3d-8}{2}\right) \frac{(d-4) p^2}{2} I(1, 1, 2, 0, 0)$$

It gives a reduction of $I(1, 1, 2, 0, 0)$ with respect to $I(1, 1, 1, 0, 0)$ of a MI.

In the sunset sector, any integral of the form $I(\nu_1, \nu_2, \nu_3, 0, 0)$ can be reduced into a linear combination of a MI, $I(1, 1, 1, 0, 0)$.

$$\begin{aligned}
 I(1, 1, 3, 0, 0) &= \frac{I([1, 1, 1, 0, 0]) (d-3) (3d-10) (3d-8)}{\dots}, I([1, 3, 1, 0, 0]) = \frac{I([1, 1, 1, 0, 0]) (d-3) (3d-10) (3d-8)}{\dots}, I([3, 1, 1, 0, 0]) = \frac{I([1, 1, 1, 0, 0]) (d-3) (3d-10) (3d-8)}{\dots} \\
 I(1, 1, 2, 2, 0, 0) &= \frac{I([1, 1, 1, 0, 0]) (d-3) (3d-10) (3d-8)}{\dots}, I([2, 1, 2, 0, 0]) = \frac{I([1, 1, 1, 0, 0]) (d-3) (3d-10) (3d-8)}{\dots}, I([2, 2, 1, 0, 0]) = \frac{I([1, 1, 1, 0, 0]) (d-3) (3d-10) (3d-8)}{\dots} \\
 I(1, 1, 4, 0, 0) &= \frac{I([1, 1, 1, 0, 0]) (d-5) (d-4) (d-3) (3d-10) (3d-8)}{\dots}, I([1, 4, 1, 0, 0]) = \frac{I([1, 1, 1, 0, 0]) (d-5) (d-4) (d-3) (3d-10) (3d-8)}{\dots} \\
 I(4, 1, 1, 0, 0) &= \frac{I([1, 1, 1, 0, 0]) (d-5) (d-4) (d-3) (3d-10) (3d-8)}{\dots}, I([1, 2, 3, 0, 0]) = \frac{I([1, 1, 1, 0, 0]) (d-5) (d-3) (3d-10) (3d-8)}{\dots} \\
 I(1, 1, 3, 2, 0, 0) &= \frac{I([1, 1, 1, 0, 0]) (d-5) (d-3) (3d-10) (3d-8)}{\dots}, I([2, 1, 3, 0, 0]) = \frac{I([1, 1, 1, 0, 0]) (d-5) (d-3) (3d-10) (3d-8)}{\dots} \\
 I(2, 3, 1, 0, 0) &= \frac{I([1, 1, 1, 0, 0]) (d-5) (d-3) (3d-10) (3d-8)}{\dots}, I([3, 1, 2, 0, 0]) = \frac{I([1, 1, 1, 0, 0]) (d-5) (d-3) (3d-10) (3d-8)}{\dots} \\
 I(3, 2, 1, 0, 0) &= \frac{I([1, 1, 1, 0, 0]) (d-5) (d-3) (3d-10) (3d-8)}{\dots}, I([2, 2, 2, 0, 0]) = \frac{I([1, 1, 1, 0, 0]) (d-5) (d-3) (3d-10) (3d-8)}{\dots} \\
 I(1, 1, 5, 0, 0) &= \frac{I([1, 1, 1, 0, 0]) (d-5) (d-4) (d-3) (3d-14) (3d-10) (3d-8)}{\dots}, I([1, 5, 1, 0, 0]) = \frac{I([1, 1, 1, 0, 0]) (d-5) (d-4) (d-3) (3d-14) (3d-10) (3d-8)}{\dots} \\
 I(5, 1, 1, 0, 0) &= \frac{I([1, 1, 1, 0, 0]) (d-5) (d-4) (d-3) (3d-14) (3d-10) (3d-8)}{\dots}, I([1, 2, 4, 0, 0]) = \frac{I([1, 1, 1, 0, 0]) (d-5) (d-3) (3d-14) (3d-10) (3d-8)}{\dots} \\
 I(1, 4, 2, 0, 0) &= \frac{I([1, 1, 1, 0, 0]) (d-5) (d-3) (3d-14) (3d-10) (3d-8)}{\dots}, I([2, 1, 4, 0, 0]) = \frac{I([1, 1, 1, 0, 0]) (d-5) (d-3) (3d-14) (3d-10) (3d-8)}{\dots} \\
 I(2, 4, 1, 0, 0) &= \frac{I([1, 1, 1, 0, 0]) (d-5) (d-3) (3d-14) (3d-10) (3d-8)}{\dots}, I([4, 1, 2, 0, 0]) = \frac{I([1, 1, 1, 0, 0]) (d-5) (d-3) (3d-14) (3d-10) (3d-8)}{\dots} \\
 I(4, 2, 1, 0, 0) &= \frac{I([1, 1, 1, 0, 0]) (d-5) (d-3) (3d-14) (3d-10) (3d-8)}{\dots}, I([1, 3, 3, 0, 0]) = \frac{I([1, 1, 1, 0, 0]) (d-5) (d-3) (3d-14) (3d-10) (3d-8)}{\dots} \\
 I(3, 1, 3, 0, 0) &= \frac{I([1, 1, 1, 0, 0]) (d-5) (d-3) (3d-14) (3d-10) (3d-8)}{\dots}, I([3, 3, 1, 0, 0]) = \frac{I([1, 1, 1, 0, 0]) (d-5) (d-3) (3d-14) (3d-10) (3d-8)}{\dots} \\
 I(2, 2, 3, 0, 0) &= \frac{I([1, 1, 1, 0, 0]) (d-5) (d-3) (3d-14) (3d-10) (3d-8)}{\dots}, I([2, 3, 2, 0, 0]) = \frac{I([1, 1, 1, 0, 0]) (d-5) (d-3) (3d-14) (3d-10) (3d-8)}{\dots}
 \end{aligned}$$

Figure: Sunset sector's reductions over Maxima CAS environment

In the moon sector, any integral of of the form $I(\nu_1, \nu_2, \nu_3, \nu_4, 0)$ can be reduced into a linear combination of a MI, $I(1, 1, 1, 0, 0)$. In particular, the scalar integral $I(1, 1, 1, 1, 0)$ is reducible:

$$I(1, 1, 1, 1, 0) = \frac{(3d-8)}{(d-4)p^2} I(1, 1, 1, 0, 0)$$

The image shows a complex mathematical derivation on a computer screen. The derivation starts with a large fraction involving multiple gamma functions and integrals. It then simplifies through several steps, using various mathematical identities and substitutions, eventually leading to the final result: $I(1, 1, 1, 1, 0) = \frac{(3d-8)}{(d-4)p^2} I(1, 1, 1, 0, 0)$. The screen shows the step-by-step algebraic manipulation of the integrals.

Combining the reduction of glasses sector with another MI, $I(1, 0, 1, 1, 1)$, we can finally build a full reduction chain for the kite; for any integral with five indices is reduced into a linear combination of two MI, e.g.,

$$I(1, 1, 1, 1, 1) = \frac{2(3d-10)(3d-8)}{(d-4)^2 p^4} I(1, 1, 1, 0, 0) + \frac{-2(d-3)}{(d-4)p^2} I(1, 0, 1, 1, 1).$$

The screenshot shows a Mathematica notebook with the following content:

```

3 I([1, 1, 1, 0, 0]) (d - 5) (d - 3) (3 d - 10) (3 d - 8)
-----, I([2, 2, 0, 2, 1]) = I([2, 2, 1, 2, 0]), I([1, 1, 0, 1,
(d - 6) (d - 4) p
3 I([1, 1, 1, 0, 0]) (d - 3) (3 d - 10) (3 d - 8)
-----, I([1, 2, 0, 1, 2]) = -
(d - 8) (d - 6) p
3 I([1, 1, 1, 0, 0]) (d - 5) (d - 3) (3 d - 10) (3 d - 8)
-----, I([2, 1, 0, 2, 2]) = I([2, 1, 2, 2, 0]), I([1, 2, 0, 2,
(d - 6) (d - 4) p
3 I([1, 1, 1, 0, 0]) (3 d - 8)
-----, I([0, 2, 1, 1, 1]) = -
(d - 4) p
3 I([1, 1, 1, 0, 0]) (d - 3) (3 d - 10) (3 d - 8)
-----, I([0, 1, 1, 2, 1]) = -
(d - 8) (d - 6) p
3 I([1, 1, 1, 0, 0]) (d - 3) (3 d - 10) (3 d - 8)
-----, I([0, 1, 1, 2, 1]) = -
(d - 6) (d - 4) p
3 I([1, 1, 1, 0, 0]) (3 d - 10) (3 d - 8)
-----, I([0, 2, 2, 1, 1]) = I([1, 2, 2, 2, 0]), I([0, 1, 1, 1, 2]) = -
(d - 6) (d - 4) p
3 I([1, 1, 1, 0, 0]) (3 d - 10) (3 d - 8)
-----, I([0, 2, 2, 1, 2]) = I([2, 2, 1, 2, 0]), I([0, 1, 1, 2, 2]) = -
(d - 4) p
3 I([1, 1, 1, 0, 0]) (d - 5) (d - 3) (3 d - 10) (3 d - 8)
-----, I([0, 2, 1, 2, 2]) = I([2, 2, 2, 2, 0]), I([0, 1, 2, 2, 2,
(d - 6) (d - 4) p
2 (2 d - 14 d + 24) p I([1, 0, 1, 1, 1]) + ((- 18 d) + 108 d - 160) I([1, 1, 1, 0, 0])
-----,
(d - 8 d + 16) p
3 2 2 3 2
(2 d - 26 d + 188 d - 144) p I([1, 0, 1, 1, 1]) + ((- 27 d) + 297 d - 1050 d + 1200) I([1, 1, 1, 0, 0])
-----,
(d - 10 d + 24) p
3 2 3 2
(2 d - 26 d + 188 d - 144) p I([1, 0, 1, 1, 1]) + ((- 27 d) + 297 d - 1050 d + 1200) I([1, 1, 1, 0, 0])
-----]
(d - 10 d + 24) p

```

Conclusion

We showed an alternative way of constructing linear equations, IBP-like equations over Schwinger-Feynman parameters.

Setting no-dimension shift as an additional constrain, we built syzygies, and constructed a set of linear equations by looping over monomials in the parameter space.

We showed that an example of full reductions; the results are cross-checked with Kira ([Maierhöfer et al. 2018](#)).

The next steps will be

- more complicated diagrams (more scales, masses, loops etc)
- automation

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Non-positive indices and CIF

The edge contraction “pinching” implies the following natural interpretation of the non-positive indices:

$$\int \frac{dx_a}{\Gamma(-n)x_a^{n+1}} \mapsto (-)^n \frac{n!}{2\pi i} \oint_{\circlearrowleft} \frac{dx_a}{x_a^{n+1}} = (-)^n \left. \frac{\partial^n}{\partial x_a^n} \right|_{x_a=0}.$$

This is nothing but Cauchy's integral formula.

For massive kite, consider $I(1, 1, 1, -1, 0)$:

$$\begin{aligned} I^d(1, 1, 1, -1, 0) &= \frac{\Gamma(\frac{d}{2})}{(4\pi)^d} \frac{1}{\Gamma(\frac{d}{2}(2+1) - (3-1))} \int dx_1 dx_2 dx_3 \int \frac{dx_4 x_4^{-1-1}}{\Gamma(-1)} \mathcal{G}^{-\frac{d}{2}} \Big|_{x_5=0} \\ &= \frac{\Gamma(\frac{d}{2})}{(4\pi)^d} \frac{1}{\Gamma(\frac{3d}{2} - 2)} \int dx_1 dx_2 dx_3 \int \frac{dx_4 x_4^{-1-1}}{\Gamma(-1)} \mathcal{G}^{-\frac{d}{2}} \Big|_{x_5=0} \end{aligned}$$

Replacing x_4 -integration by the partial derivative with respect to it, we have:

$$\begin{aligned}
 I^d(1, 1, 1, -1, 0) &= \frac{\Gamma(\frac{d}{2})}{(4\pi)^d \Gamma(\frac{3d}{2} - 2)} \int dx_1 dx_2 dx_3 \frac{d}{2} \frac{\partial \mathcal{G}}{\partial x_4} \Big|_{\substack{x_5=0 \\ x_4=0}} \mathcal{G}^{-\frac{d}{2}-1} \Big|_{\substack{x_5=0 \\ x_4=0}} \\
 &= \frac{\Gamma(\frac{d+2}{2})}{(4\pi)^d \Gamma(\frac{3(d+2)}{2} - 5)} \int dx_1 dx_2 dx_3 \frac{\partial \mathcal{G}}{\partial x_4} \Big|_{\substack{x_5=0 \\ x_4=0}} \mathcal{G}^{-\frac{d+2}{2}} \Big|_{\substack{x_5=0 \\ x_4=0}}
 \end{aligned}$$

Note that, since here we consider massive kite, a tadpole becomes a scale-full integral and indeed has a non-zero contribution.

Since $\frac{\partial \mathcal{G}}{\partial x_4} \Big|_{\substack{x_5=0 \\ x_4=0}}$ becomes

$$\begin{aligned} \frac{\partial \mathcal{G}}{\partial x_4} \Big|_{\substack{x_5=0 \\ x_4=0}} &= m^2 x_3^2 + 3m^2 x_2 x_3 + p^2 x_1 x_3 + 2m^2 x_1 x_3 + x_3 + m^2 x_2^2 + p^2 x_1 x_2 + 2m^2 x_1 x_2 + x_2 \\ &= m^2 (x_3^2 + x_2^2) + 3m^2 x_2 x_3 + (p^2 + 2m^2) (x_1 x_3 + x_1 x_2) + x_1 + x_2, \end{aligned}$$

the right hand side of the above becomes the following integrals in $(d+2)$ -dimension:

$$\begin{aligned} (4\pi)^2 &\left[m^2 \Gamma(3) \left(I^{d+2}(1, 1, 3, 0, 0) + I^{d+2}(1, 3, 1, 0, 0) \right) + 3m^2 I^{d+2}(1, 2, 2, 0, 0) \right. \\ &\quad + (p^2 + 2m^2) \left(I^{d+2}(2, 1, 2, 0, 0) + I^{d+2}(2, 2, 1, 0, 0) \right) \\ &\quad \left. + \frac{3d-5}{2} \left(I^{d+2}(2, 1, 1, 0, 0) + I^{d+2}(1, 2, 1, 0, 0) \right) \right] \end{aligned}$$

When we plug the above expression using LoweringDRR function in LiteRed (R. N. Lee 2012), we obtain the consistent reduction with Kira; LiteRed can also gives us the same reduction directory from $I^d(1, 1, 1, -1, 0)$:

$$I(1, 1, 1, -1, 0) = \frac{p^2}{3} I(1, 1, 1, 0, 0) + I(1, 1, 0, 0, 0)$$