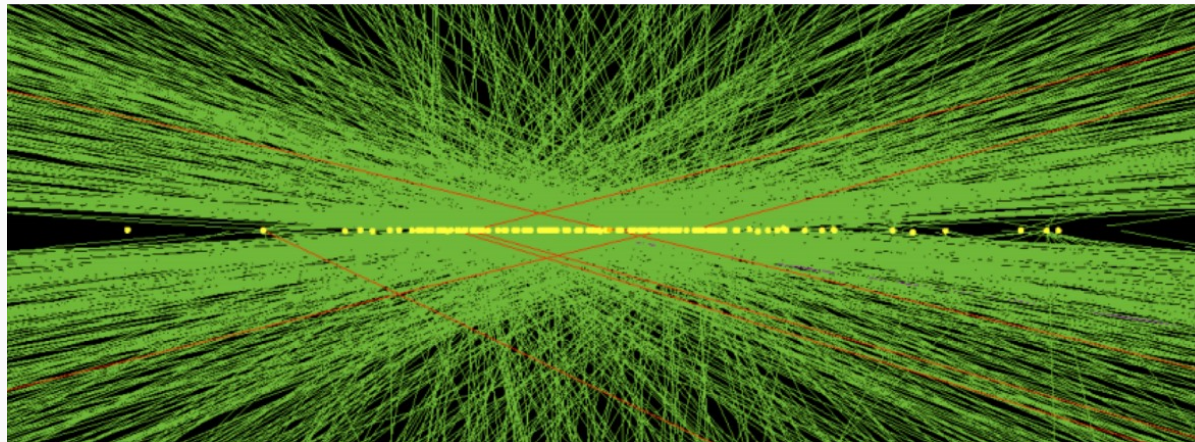


Level-1 Track Finding at CMS for the HL-LHC

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Rutgers, The State University of New Jersey

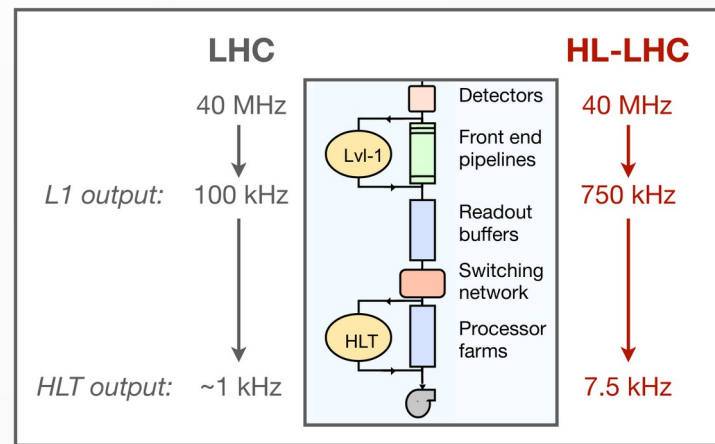
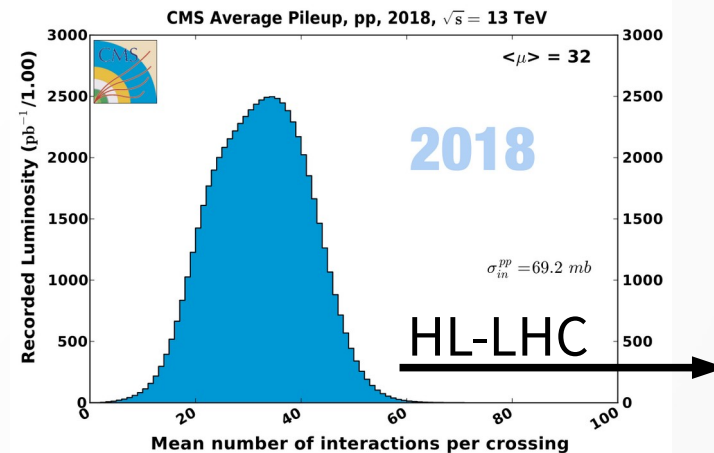
The High-Luminosity LHC

- The High-Luminosity LHC (HL-LHC) upgrade in 2025-2027 is expected to achieve luminosities up to $7.5 \times 10^{34} \text{ cm}^{-2} \text{ s}^{-1}$:
 - Great opportunities for physics
 - Very challenging at every stage, from triggering to data analysis
- How do we ensure that we get the most out of this data?
 - A key component of the strategy for CMS is to introduce tracking in the Level-1 (L1) trigger
 - Here we show the latest results from the L1 tracking system currently being developed

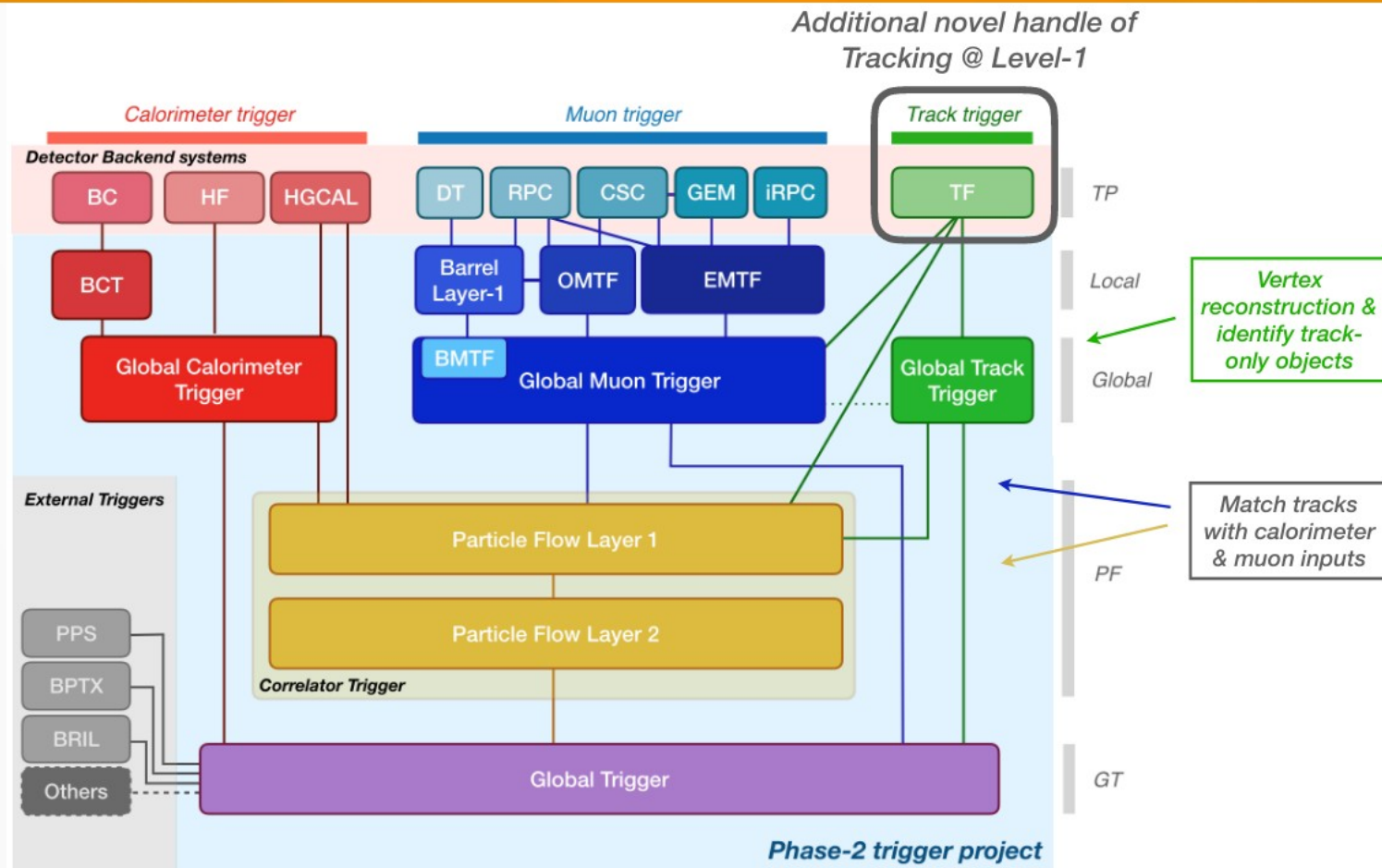


Triggering with 200 pileup

- Many exciting possibilities with $\sim 4000 \text{ fb}^{-1}$ datasets expected from the HL-LHC:
 - Precision measurements of the Higgs boson and its interactions, including the self-coupling
 - Extended discovery reach for beyond-the-standard model (BSM) physics
 - Observe rare standard model processes that could be sensitive to BSM physics
- The cost of these physics possibilities is huge amounts of pileup:
 - Expect an average of 200 overlapping pp collisions per bunch crossing
- Trigger system has to reduce the 40 MHz input rate to $\sim 7.5 \text{ kHz}$:
 - Tracking at L1 is central to accomplishing this
 - Without tracking, L1 output would be $\sim 4000 \text{ kHz}$ at 200 PU

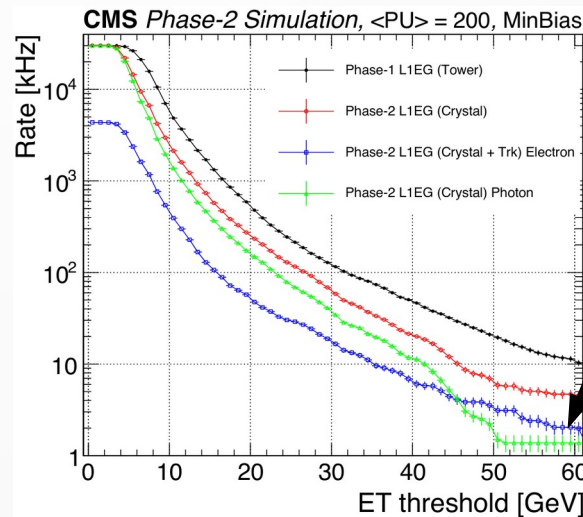
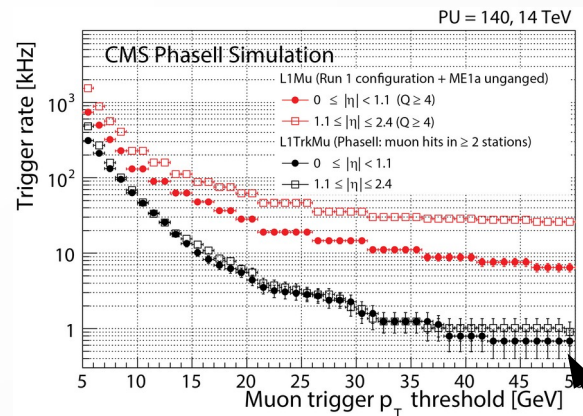


L1 trigger for HL-LHC



Tracking at L1

- Usually, in order to reduce trigger rates, we increase momentum/energy thresholds:
 - This can obviously hurt physics potential
 - Also insufficient by itself at HL-LHC rates
- L1 tracking provides a powerful alternative:
 - Improved muon p_T resolution
 - Better $e/\gamma/\tau$ identification
 - Ability to associate tracks with vertices



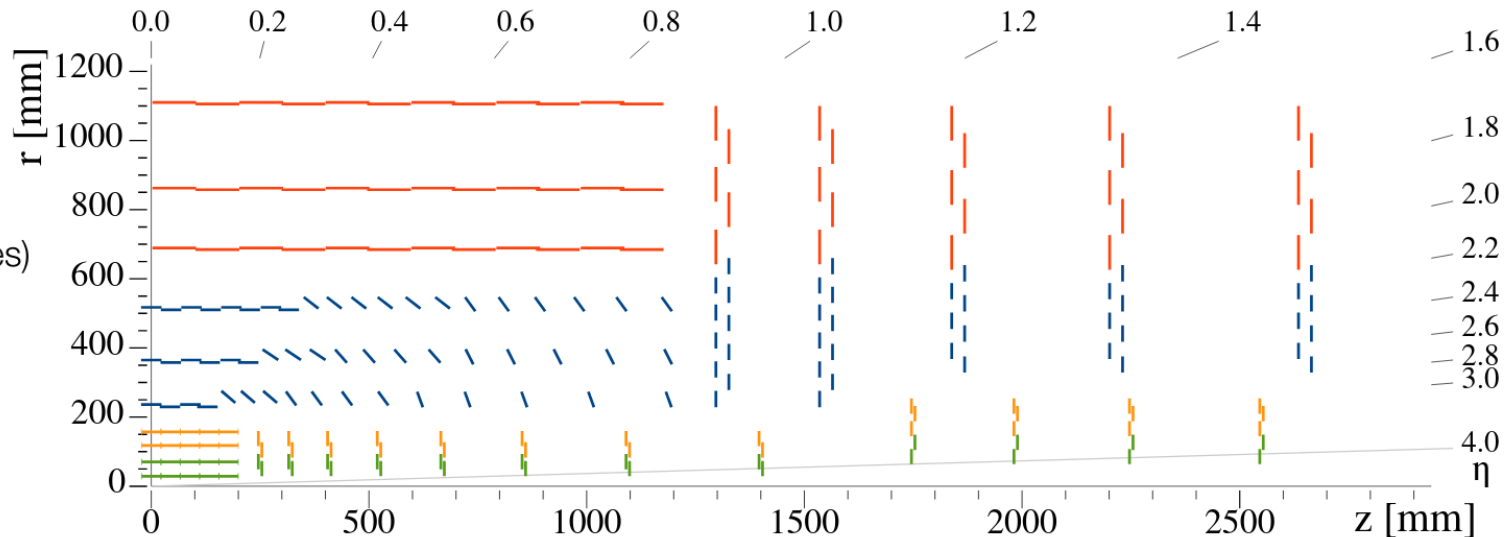
L1 tracking
reduces rates

CMS tracker for HL-LHC

- New pixel and outer tracker:
 - All silicon as with the current CMS tracker
 - Increased granularity in order to handle increased occupancies

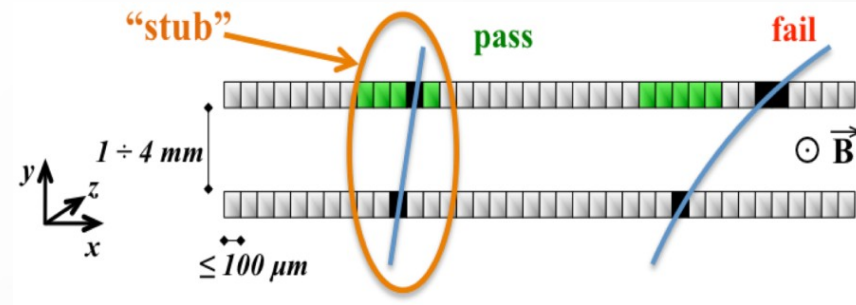
Outer Tracker
(PS vs 2S modules)
=> used at L1

Inner Pixel
(1x2 vs 2x2 chip modules)
=> not used in L1



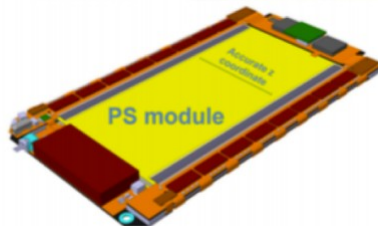
p_T modules

- Two-sided modules in outer tracker enable front-end p_T discrimination:
 - Pairs of clusters inconsistent with a $p_T > 2$ GeV track rejected
 - Data reduction of 10-20
- Stubs formed from correlated pairs of clusters consistent with a $p_T > 2$ GeV track:
 - These are the inputs to the L1 tracking algorithm



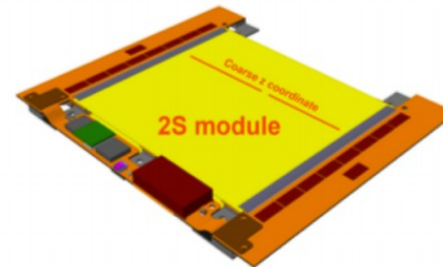
Pixel-strip (PS) modules

- Top sensor: 2×960 strips, 2.4 cm long, $100 \mu\text{m}$ pitch
- Bottom sensor: 32×960 pixels, $1.5 \text{ mm} \times 100 \mu\text{m}$



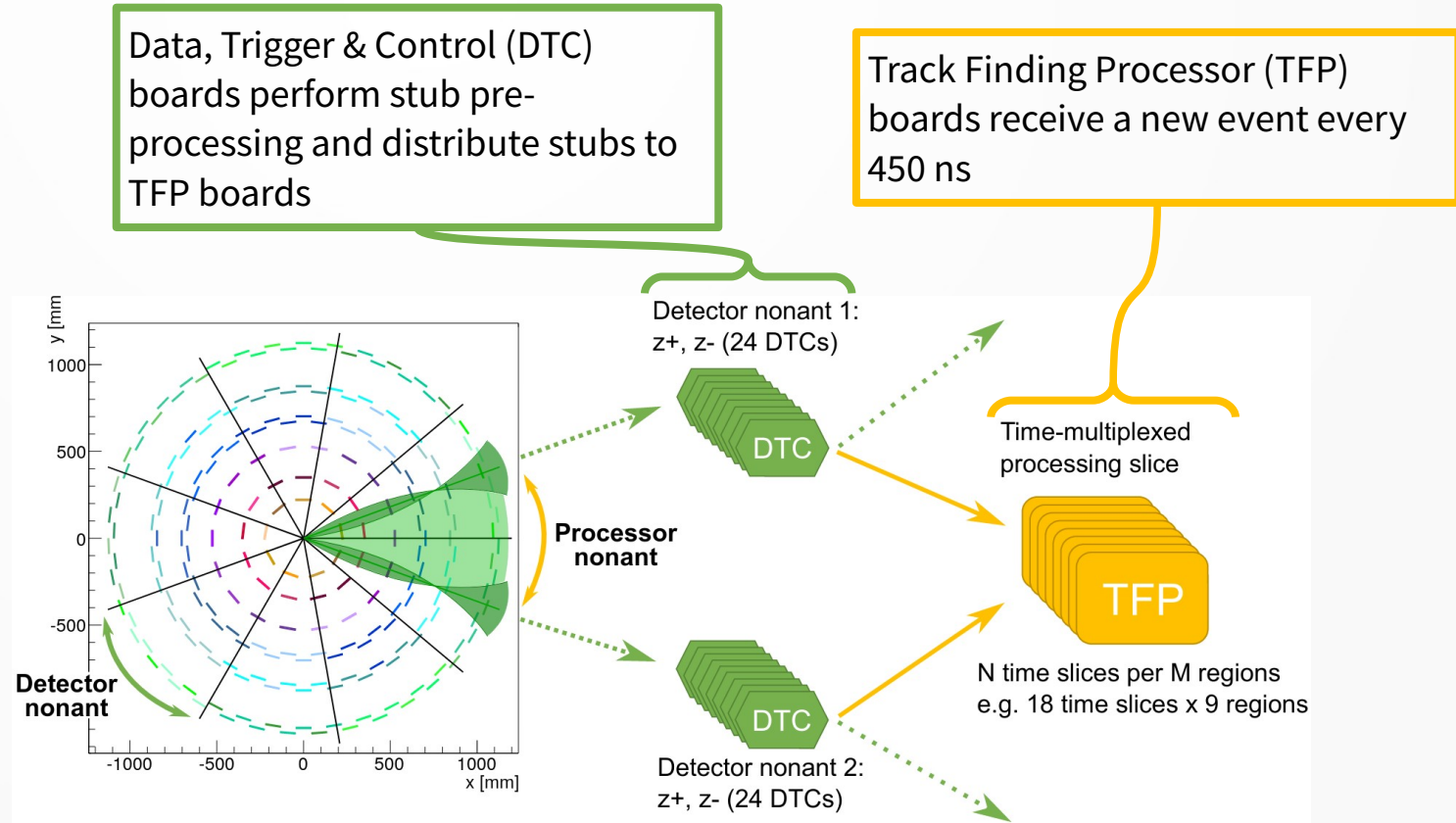
Strip-strip (2S) modules

- Both sensors are strips
- 2×1016 strips, 5 cm long, $90 \mu\text{m}$ pitch



Track finder architecture

- Parallelized in time and space:
 - Time multiplexing factor of 18
 - Detector divided into nine ϕ sectors; stubs shared between sectors, but not tracks

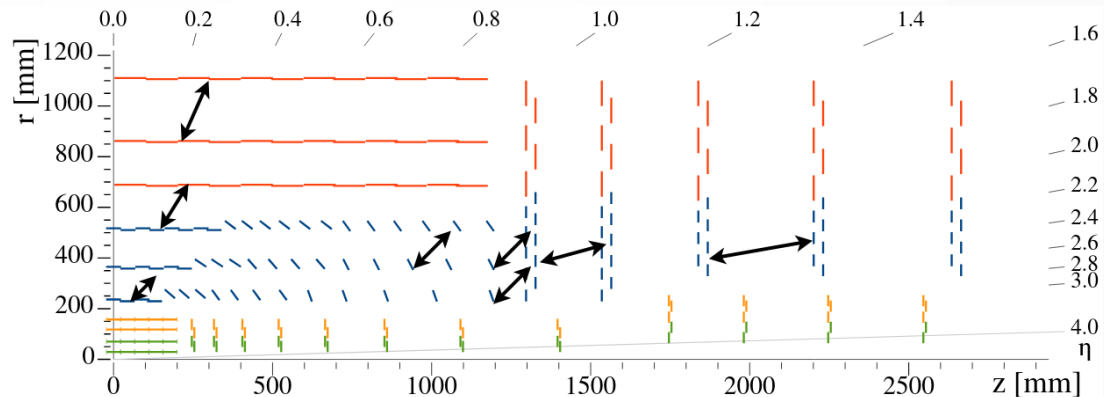
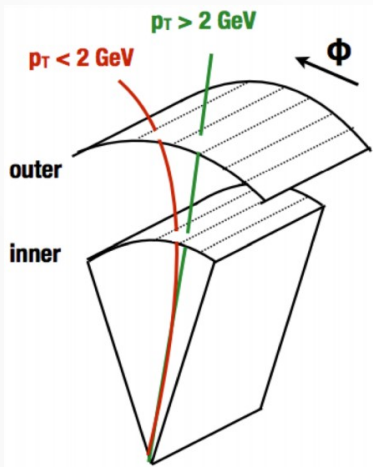


Track seeds

Central η :
L1+L2, L3+L4, L5+L6

Barrel-disk overlap:
L1+D1, L2+D1, L1+L2

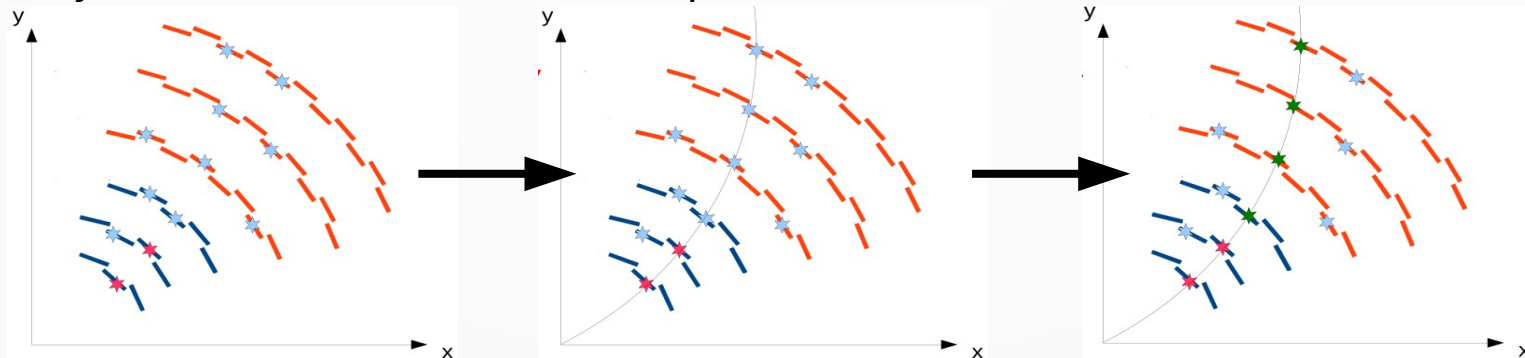
Disks:
D1+D2, D3+D4



- Tracks seeded by stub pairs in certain layer/disk combinations
- Only stub pairs consistent with $p_T > 2 \text{ GeV}$ are kept:
 - Tracker layers coarsely segmented into virtual modules (VM)
 - Only VM pairs consistent with p_T threshold are even connected in the firmware to reduce the combinatorics

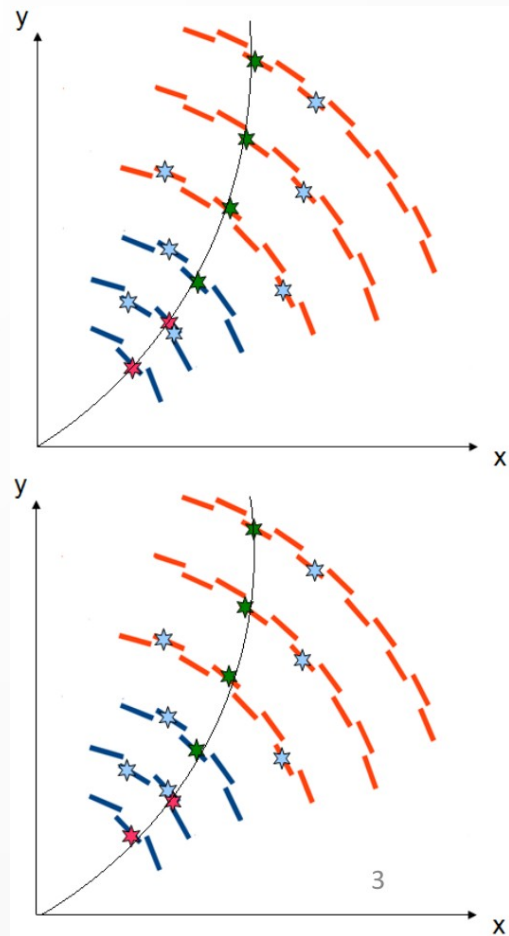
Matches in other layers/disks

- From these seeds, helix parameters and projections to other layers/disks are calculated:
 - Assume tracks originate from beamline
- The projections are used to calculate residuals and match stubs in additional layers/disks:
 - This yields full tracks that are the inputs to the final track fit



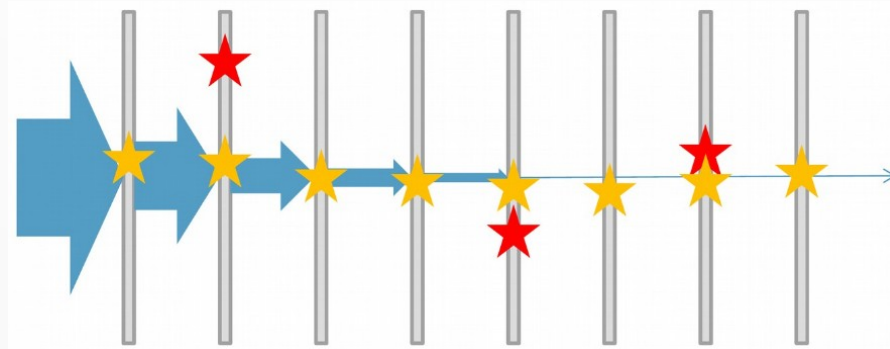
Duplicate removal

- The pattern recognition naturally produces duplicate tracks for a given charged particle:
 - Most come from redundancies in the seeds:
 - e.g., a central charged particle will usually be seeded three times: L1L2, L3L4, L5L6
 - Some come from nearby stubs in a given layer yielding very similar tracks
- These have to be removed before track fitting:
 - Currently merge any tracks that share ≥ 3 stubs



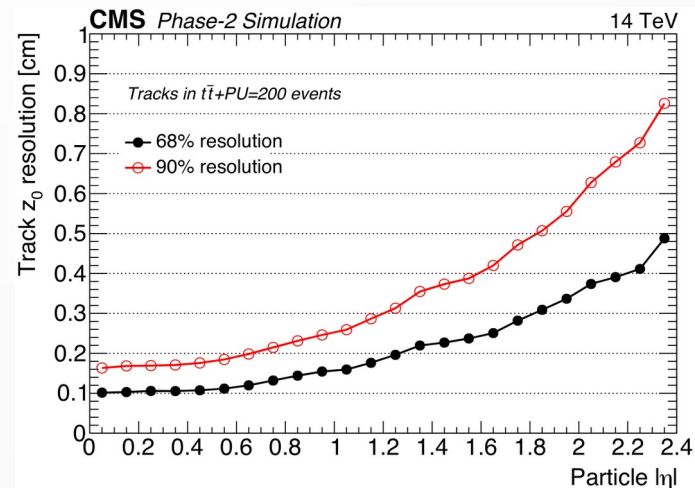
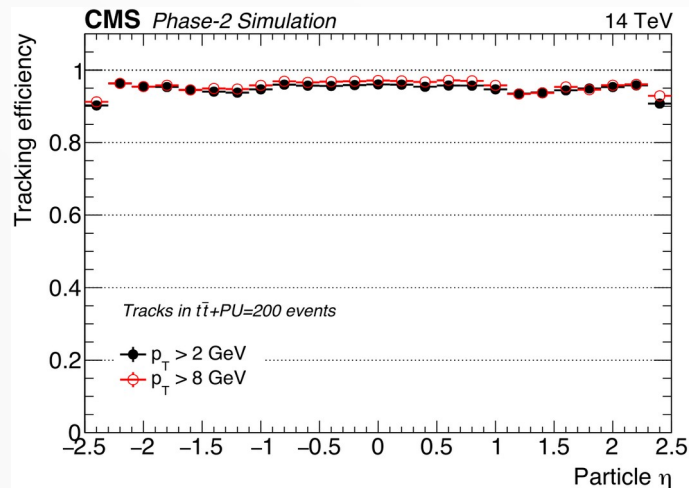
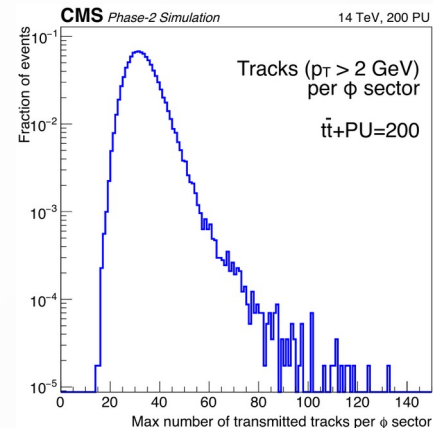
Kalman filter fit

- The final fit of the tracks is done with a Kalman filter:
 - Roughly similar to what is done in the offline tracking of CMS
 - Starts with coarse helix parameters from the seed
 - Adds stubs one by one, updating the helix parameters with greater and greater precision
- By default, there is a beamline constraint and four track parameters are fit:
 - Can easily remove this constraint and also fit for transverse impact parameter (d_0)



L1 tracking performance

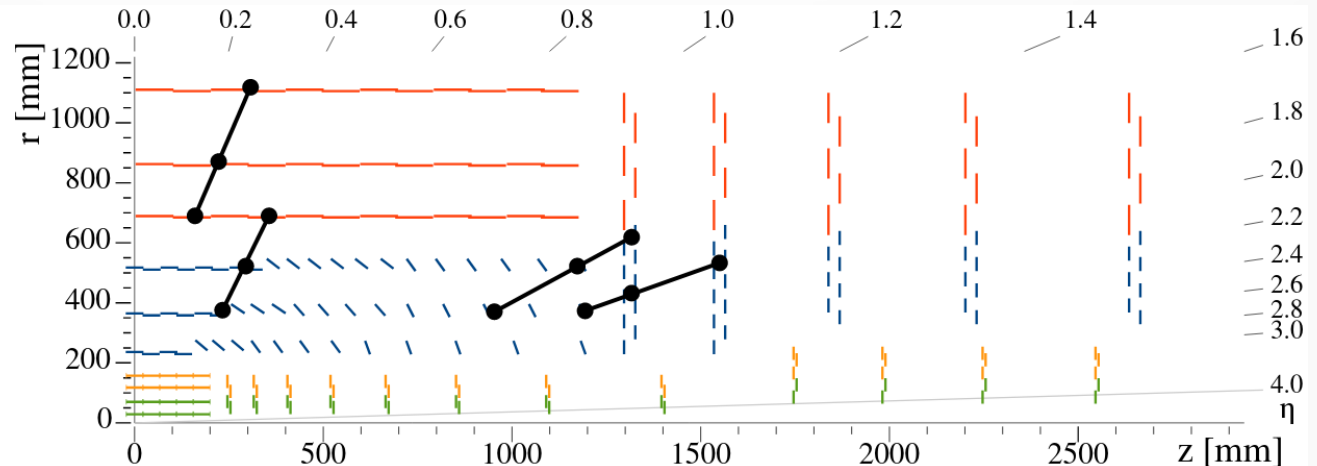
- Expected performance of L1 tracking:
 - High efficiency across the entire tracker
 - Good z_0 resolution:
 - Critical for vertex association and PU mitigation



Displaced tracking

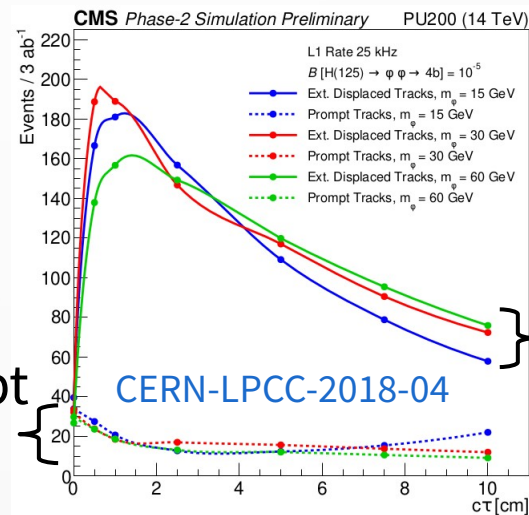
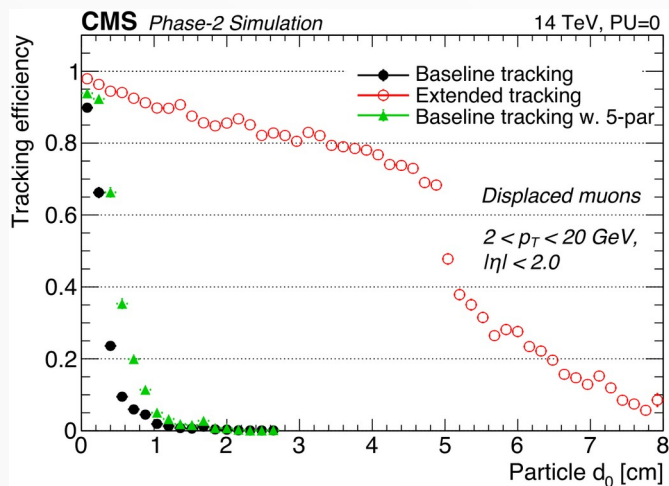
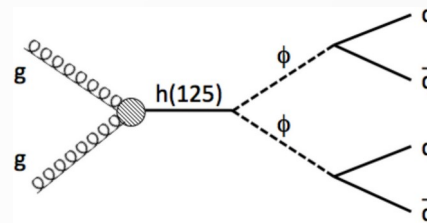
- Displaced tracks at L1 is an exciting extension to the baseline algorithm currently under active development
- Achieved via two additions/modifications:
 - Seeds: three triplet seeds added; projected to additional layers without a beamline constraint
 - Fit: transverse impact parameter added to fit; 5-parameter Kalman filter fit

Triplet seeds:
L4L5L6, L2L3L4,
L2L3D1, L2D1D2



Displaced tracking

- Initial results promising:
 - Displaced tracks reconstructed with good efficiency up to $|d_0| \sim 5$ cm
 - Overall track rate increases by $\sim 40\%$ (conservative estimate)
- Greatly increases sensitivity of Higgs boson decays to exotic long-lived particles:
 - $H \rightarrow \phi\phi \rightarrow 4$ jets, where ϕ is a new long-lived scalar
 - Challenging without displaced L1 tracking because of the low H_T of the signal



Only prompt tracks

With displaced tracks

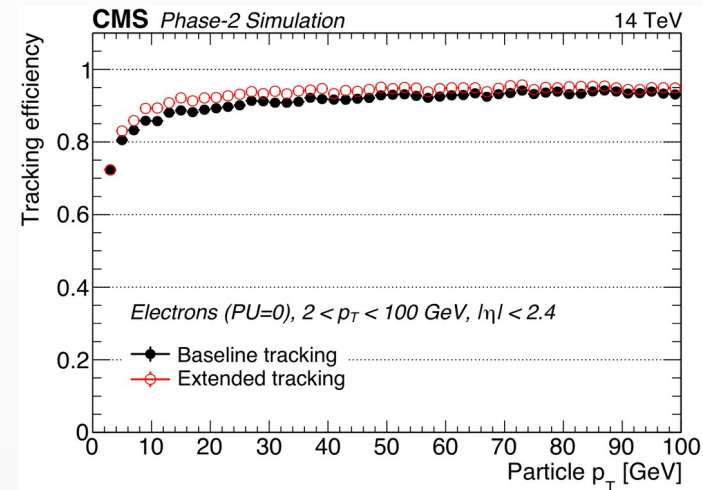
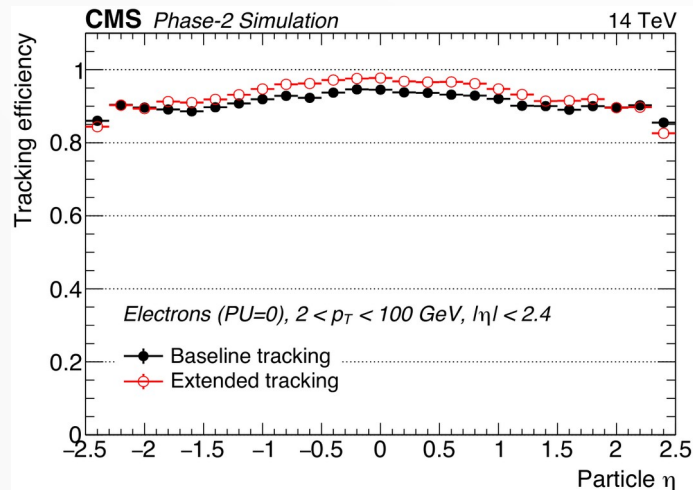
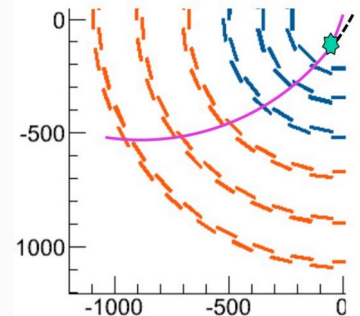
CERN-LPCC-2018-04

Electron performance

- Electron tracking challenging due to large bremsstrahlung:
 - Mitigated in offline software with a Gaussian sum filter, which is not employed in the L1 trigger
- Electrons can appear as displaced tracks if most of the bremsstrahlung occurs before the outer tracker:
 - Displaced tracking can recover some of these tracks

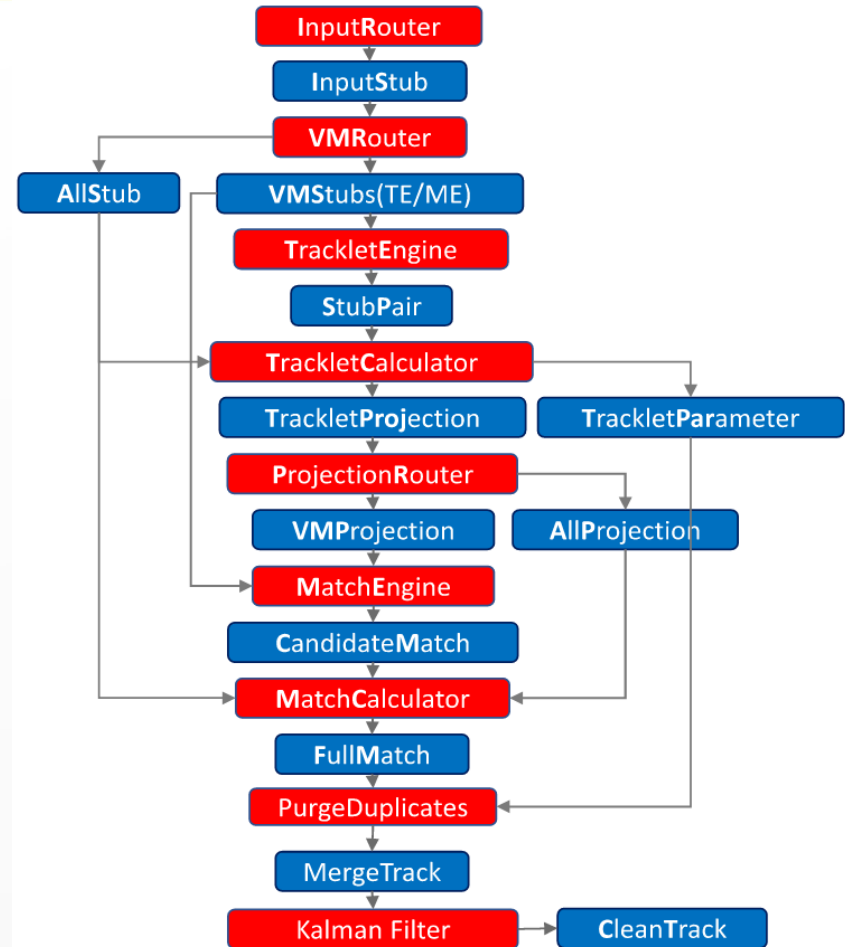
Brem in the inner tracker:

- With PV constraint: no track at all
- Displaced long track with OK χ^2



Firmware implementation

- Track finding algorithm implemented as an FPGA design
- Firmware organized as a series of **processing modules** with **memory modules** between each step:
 - Most processing modules implemented in Xilinx Vivado HLS (C++)
 - Kalman filter largely implemented in VHDL
 - Individual processing and memory modules connected together in a top-level VHDL module

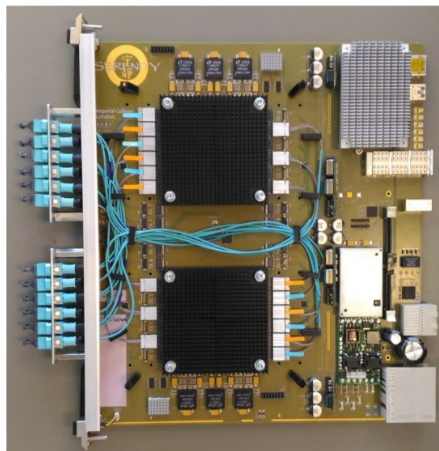


Hardware demonstration

- Track-finding hardware based on ATCA platform, the CMS standard for HL-LHC upgrades
- Multiple subchains of processing modules have been tested successfully already

Serenity: DTC processing

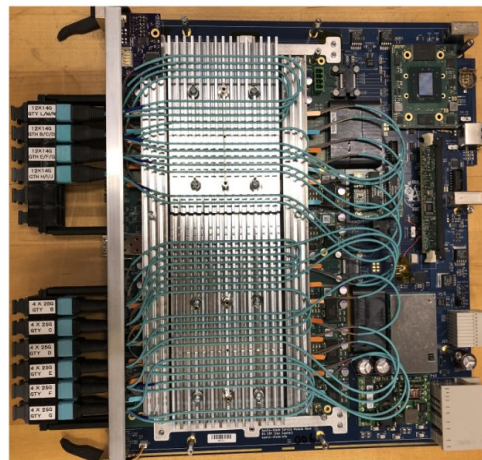
- Carrier card provides services
- Daughter cards host FPGAs for data processing



[cds:2646388](#)

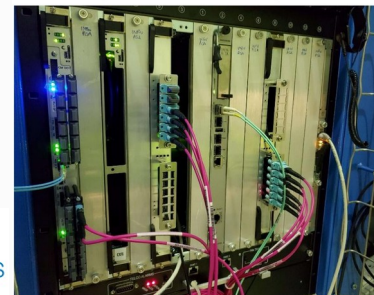
Apollo: track finding processing boards

- Service Module provides infrastructure components
- Command Module contains two large FPGAs, optical fiber interfaces & memories



[arXiv:1911.06452](#)

Test stand @ CERN
with Apollo & Serenity blades



Conclusion

- L1 tracking is a key part of the strategy in CMS for making the most of the challenging data that will be delivered by the HL-LHC
- The algorithm combines a road search for pattern recognition with a Kalman filter fit:
 - Simulations shows that the algorithm performs very well
 - Implemented as an FPGA design with processing modules written in Xilinx Vivado HLS and VHDL
 - Multiple subchains of processing modules have been successfully demonstrated in actual hardware
- The focus now is on finalizing the system specifications, and demonstrating more extensive chains of modules in hardware