

Bridging the Machine Detector Interface



ROYAL
HOLLOWAY
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OF LONDON



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ICHEP Virtual Conference

The Machine Detector Interface

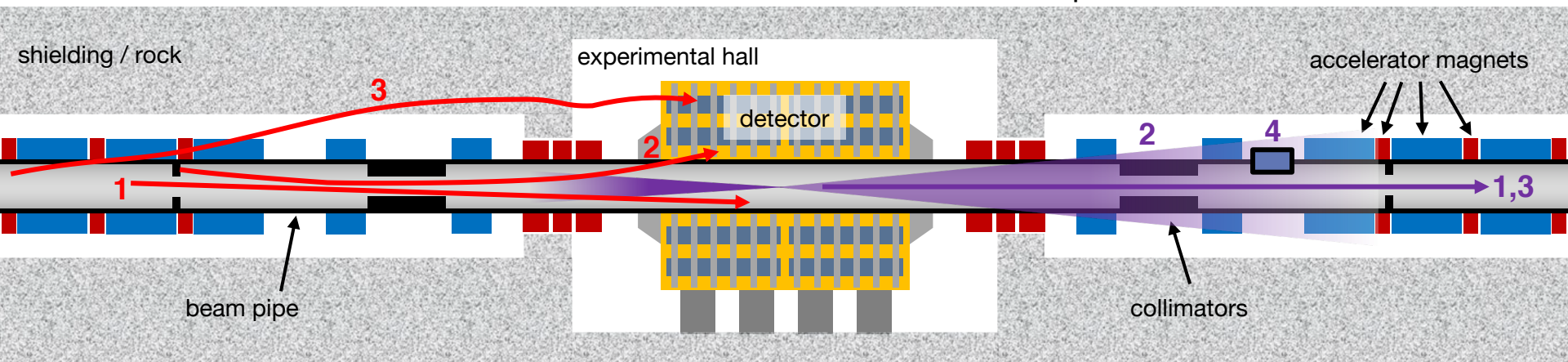
- Radiation / particles in both directions - both are interesting

Incoming:

1. products from residual gas interaction
2. leakage from collimation system
3. secondaries from beam loss

Outgoing:

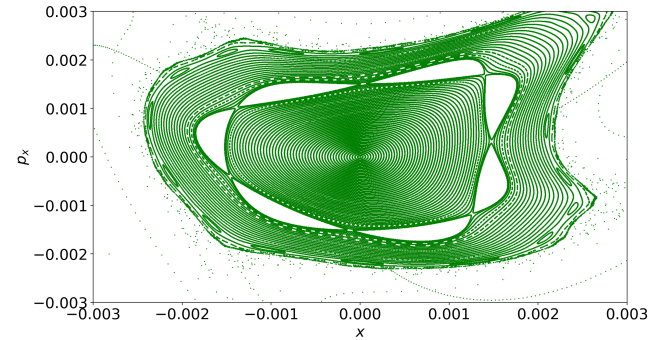
1. lightly scattered primaries
2. physics debris
3. forward physics
4. forward experiments



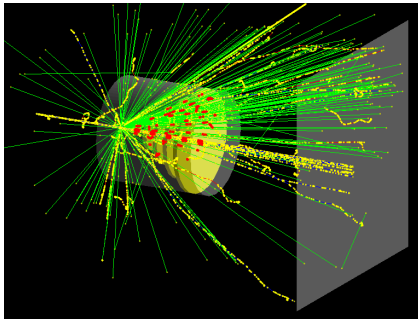
Goal: Simulate far reaching particles *in* and *out* of experiment and understand them
Need: accurate magnetic particle tracking + interaction with matter

Simulating the Machine Detector Interface

- Accurate tracking required for many (>100 s) magnets
 - numerical integration (like 4th order Runge Kutta) is not accurate enough
- Specialised codes exist for accelerator tracking
 - MADX, SAD, PTC, Elegant, COSY Infinity, SixTrack, OPAL, Zgoubi, Merlin
 - these often exploit specific maps for pure fields
 - **no** interaction with material or only limited in select places (e.g. collimators)
 - typically **no** secondaries tracked or their production considered
- Typically 'losses' are when coordinates exceed aperture
 - high energy particles don't just stop! (although correlation works in some cases)

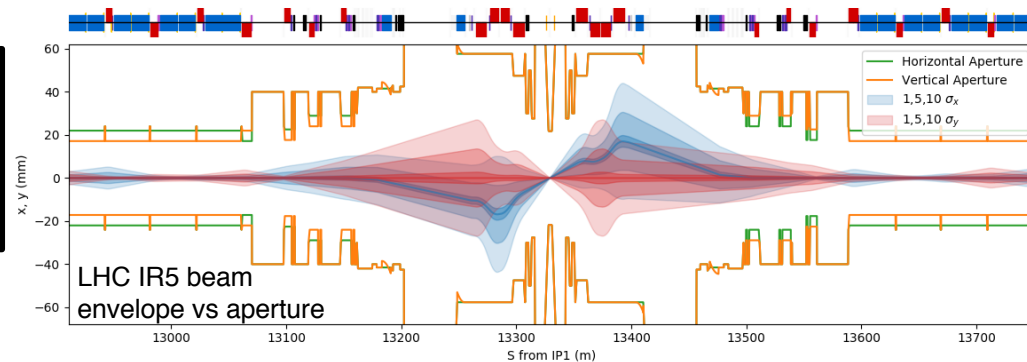


Example Poincaré map through nonlinear fields



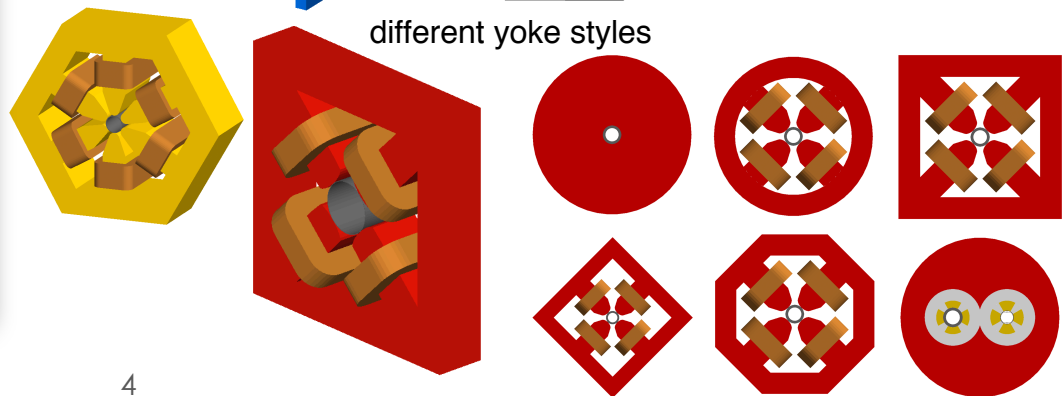
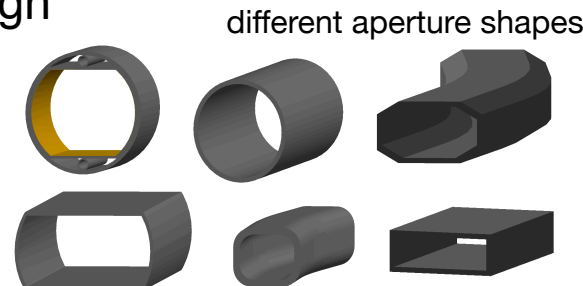
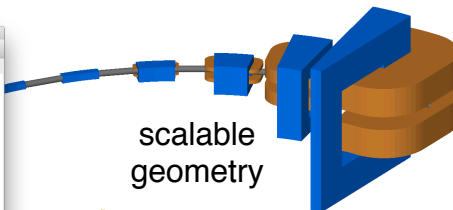
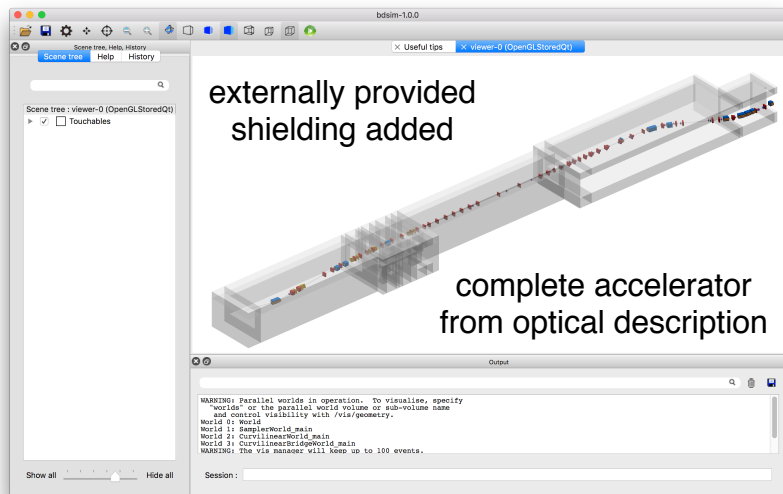
simple example Geant4 detector model

3D detector radiation transport models are often **complex** and highly specialised



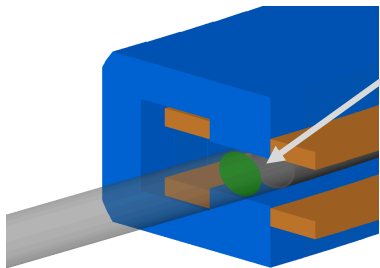
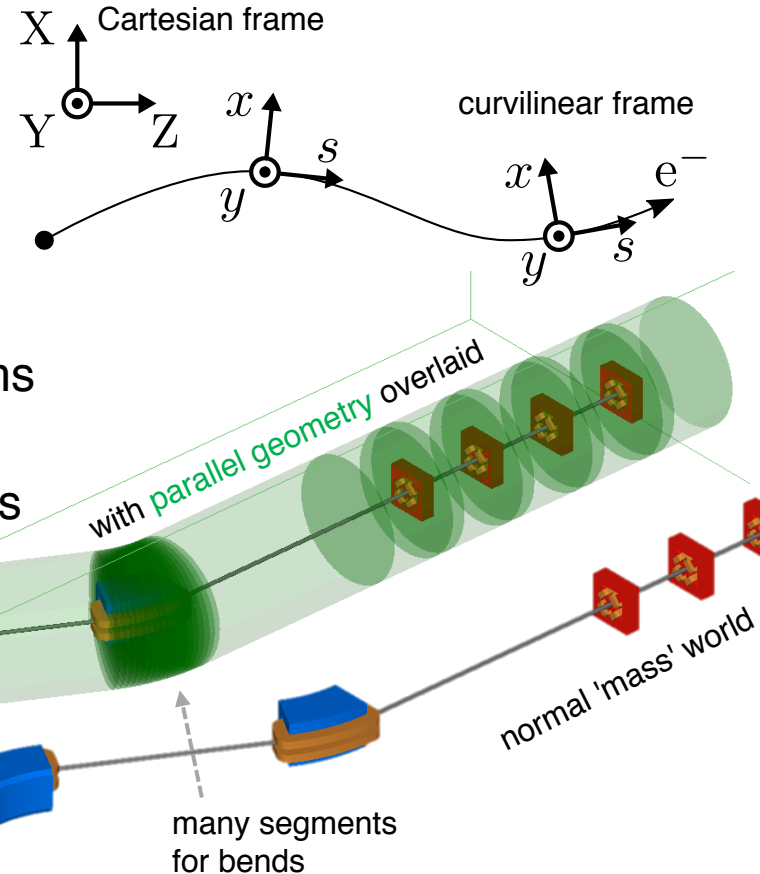
A Solution: Accelerator Tracking + Geant4

- Geant4 is a widely used open source C++ library for modelling detectors
 - regularly updated and developed based on latest results by community
- Use this and add accelerator tracking
- Accelerators are typically repetitive and similar in design
 - add library of typical accelerator components with adjustable proportions



Coordinate Systems & "Thin" Elements

- Accelerator tracking is done in a **curvilinear** coordinate system following the beam line
 - increased precision and only relative motion
 - beam of particles typically moves together in one direction
- Radiation transport models use **Cartesian** coordinates - no preferred direction
- Use **parallel geometry** for coordinate transforms
- Tracking uses 'thin' elements for instantaneous kicks - for magnet fringe fields and imperfections
 - include as very short elements with 1 tracking step

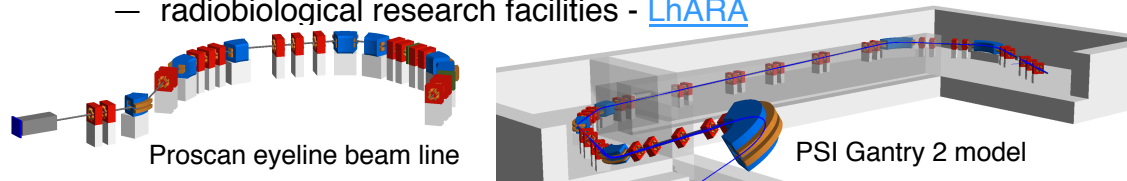


thin element for
dipole fringe fields

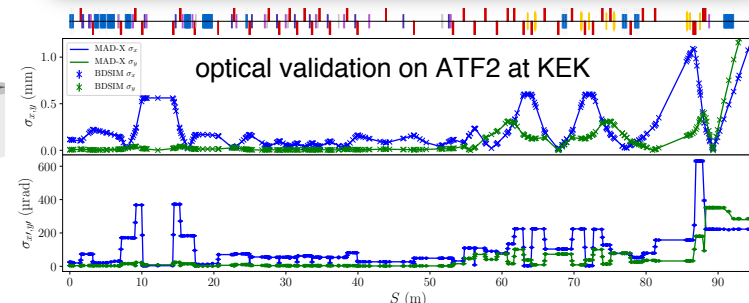
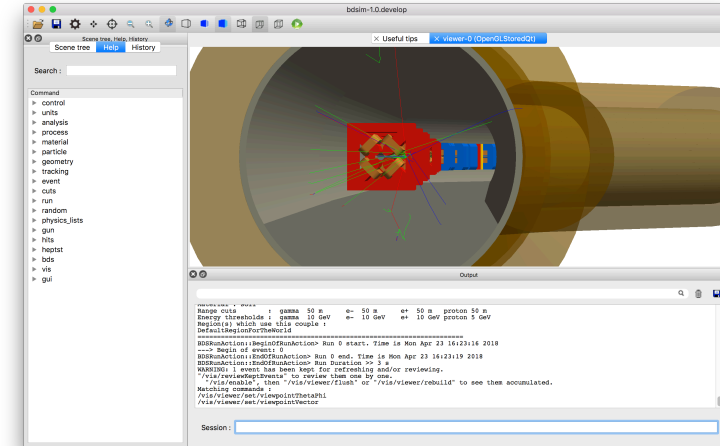
Beam Delivery Simulation (BDSIM) History



- Beam Delivery Simulation (BDSIM) application started in 2004 by G. Blair at Royal Holloway for Linear Collider backgrounds
 - open source C++ - see references at end for links
- Automatic Geant4 models of accelerators
 - start from scratch with text input or convert from optical format
 - actively developed and modernised since 2013
- Applied to many experiments and machines
 - *ILC / CLIC, AWAKE, XFEL undulators, LHC collimation, Laserwires, FASER, ATLAS non-collision backgrounds, MAGIX at MESA*
- Also for **medical** applications
 - proton therapy gantries with ULB & IBA
 - radiobiological research facilities - [LhARA](#)



[Computer Physics Communications \(252\), July 2020, 107200](#)

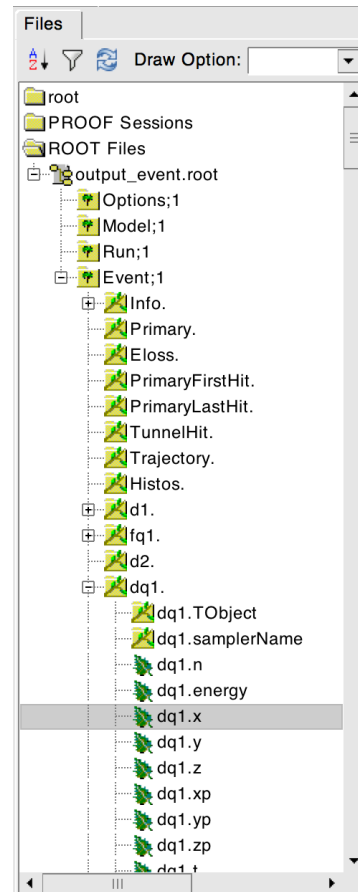
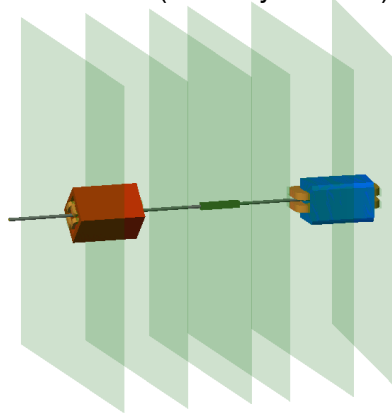


*don't forget the 'i' when googling it

- Modern CMake build system
 - uses Geant4, ROOT & CLHEP
- Can be used as a class inside another application
- Data is stored in ROOT format with per-event structure
 - accelerator tracking simulations are typically 1 particle in, 1 particle with much simpler data format
 - radiation transport model requires more advanced format and analysis tools
 - *trajectory filtering* and linking back to primary
- Data format and included analysis tools key to understanding the origin of energy deposition
 - easy filtering / selection in analysis and skimming
- Strong reproducibility from output data
 - recreate single or multiple events afterwards
- Invisible "sampler" planes to record distributions after an object

example data tree
structure

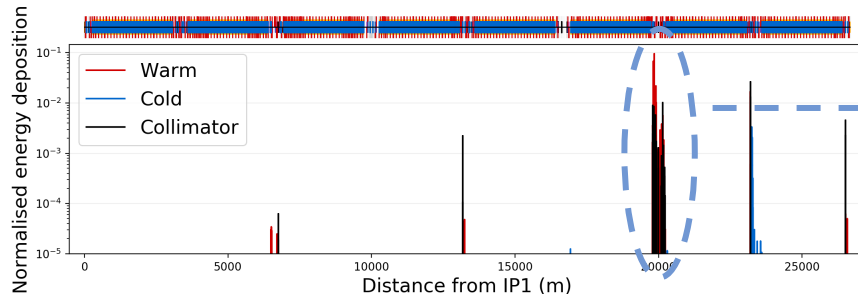
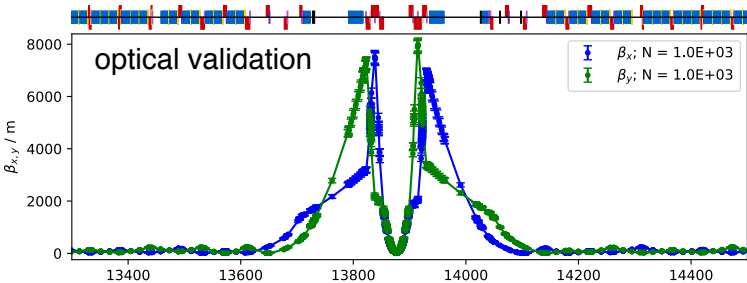
sampling planes after each
element (normally invisible)



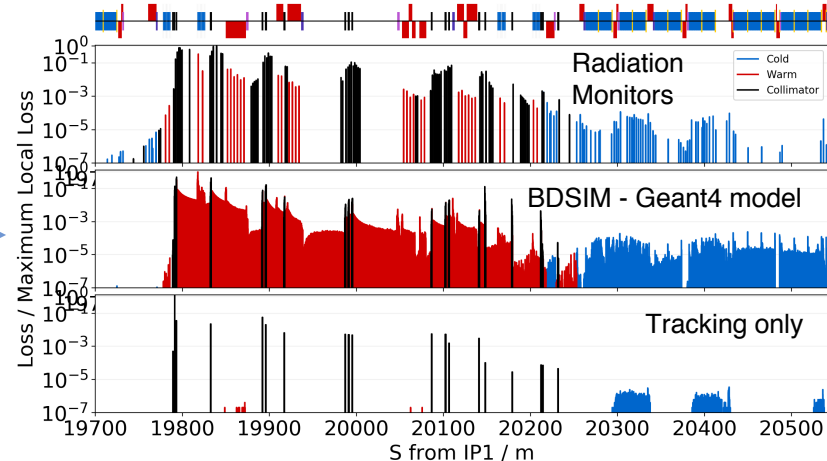
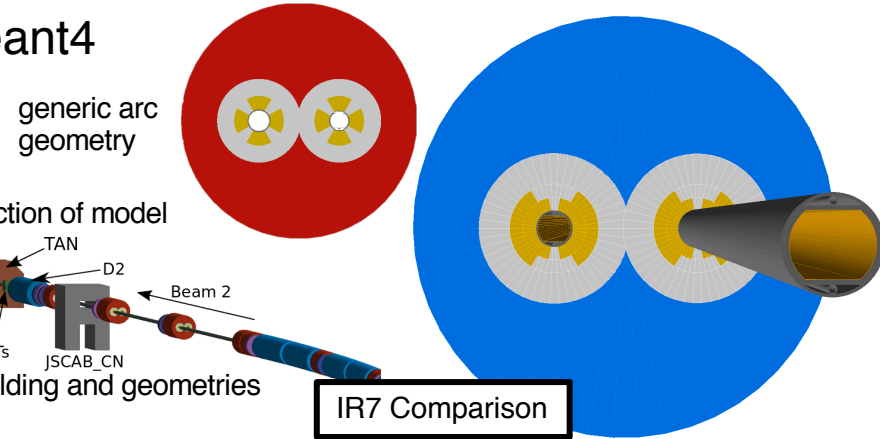
Model of the Full LHC Accelerator

- Full LHC ring model created in BDSIM / Geant4

- for studying collimation and detector backgrounds
- ~15k beam line elements with ~300k volumes
- supports multi-turn tracking
- mostly based on simplified geometry



proton loss map
for collimation

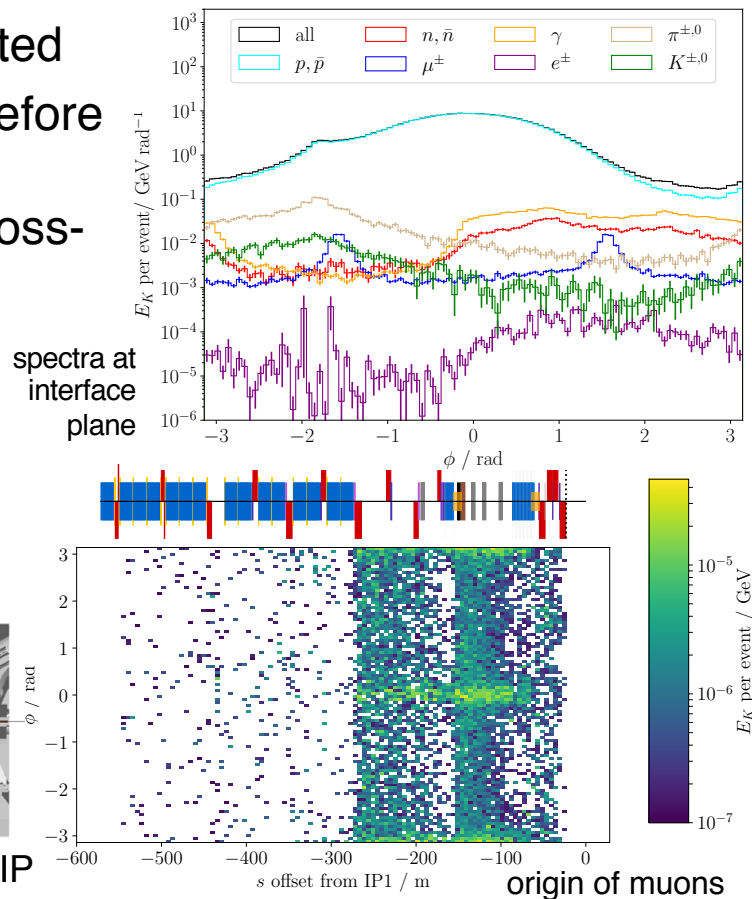
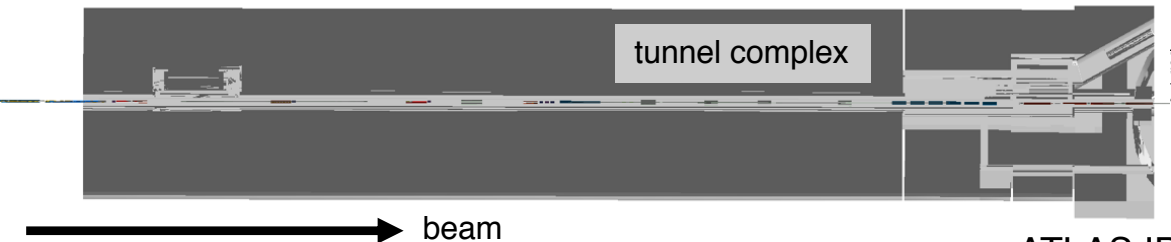


ATLAS Non-Collision Backgrounds

- Detailed model of IR1 leading up to ATLAS created
- Beam simulated up to "interface plane" 22.6m before
 - hand off to dedicated ATLAS simulation
- Simulate experimental pressure bumps using cross-section biasing in select regions
- Simulations allow understanding of origin and transport of penetrating background
- Good agreement with experimental data found

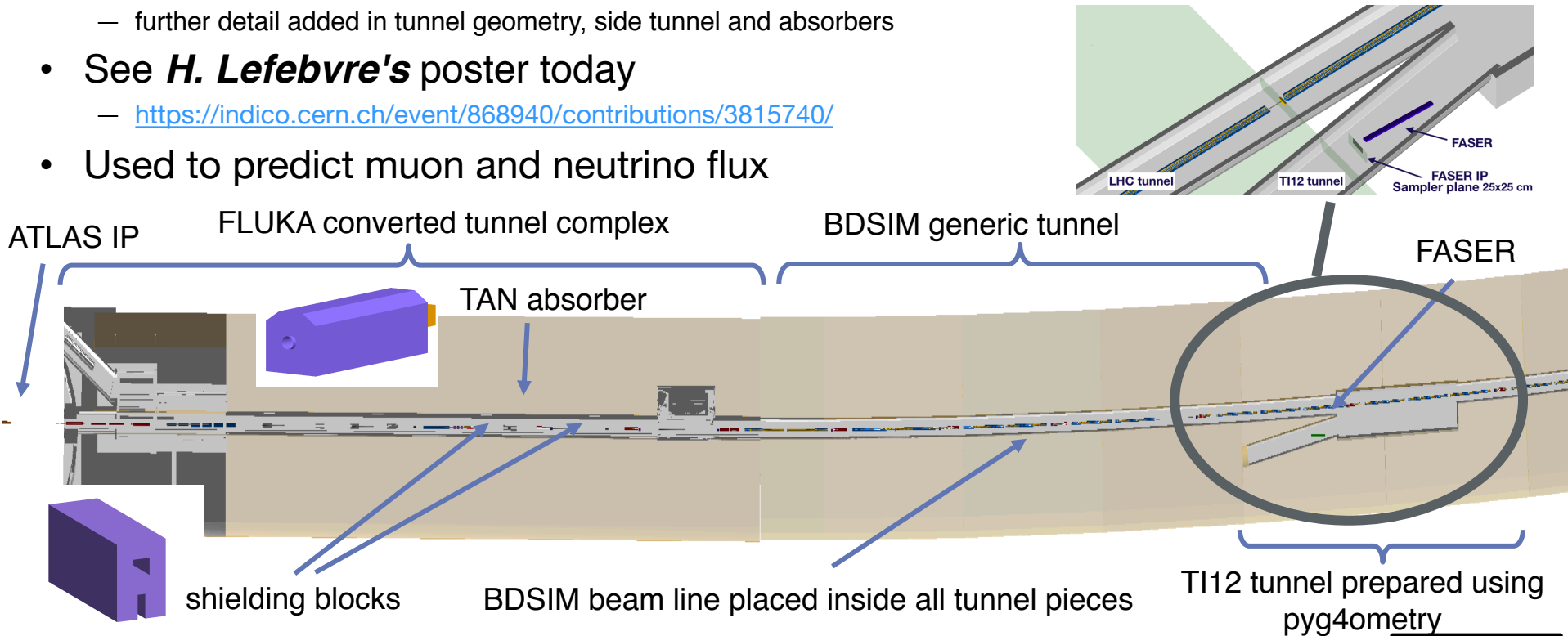
S.D. Walker thesis 2020

~300m before ATLAS

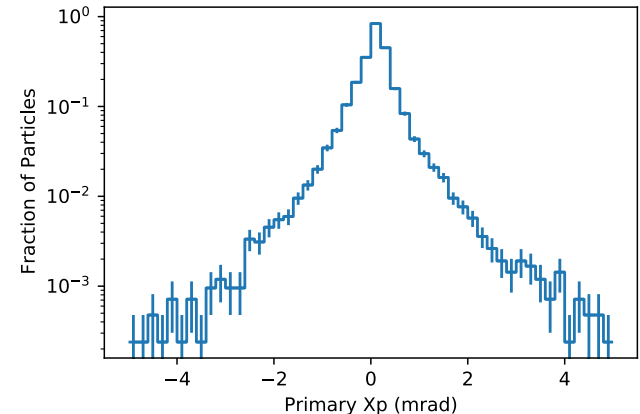
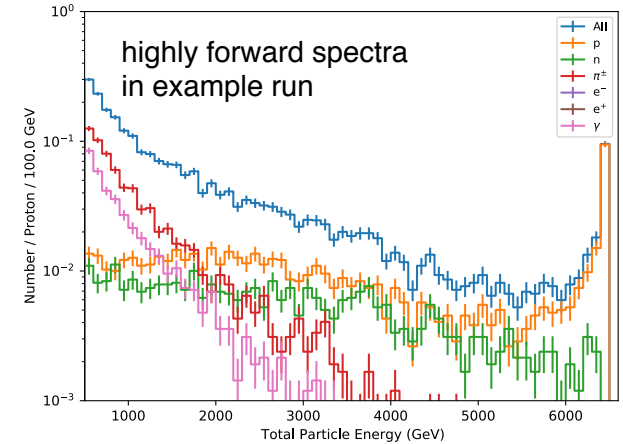


Forward Experiment Simulations

- Exploiting the same model but outgoing for forward experiment FASER
 - further detail added in tunnel geometry, side tunnel and absorbers
- See **H. Lefebvre's** poster today
 - <https://indico.cern.ch/event/868940/contributions/3815740/>
- Used to predict muon and neutrino flux

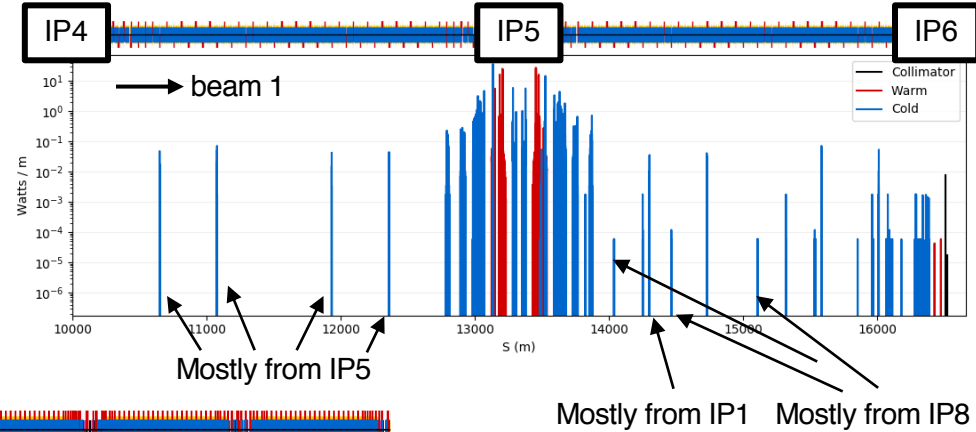


- A very interesting application is physics debris
- Elastically and inelastically scattered protons and *secondaries* can reach far from the experiments into the accelerator
- Certain beam loss monitors are highly correlated with luminosity and not with the stored beam intensity
- This isn't a problem for the machine but it is measurable
- We can use this to measure the luminosity or, assuming the luminosity: the total cross-section
 - with down-selection to beam loss monitors that only represent luminous beam losses
- *Potential for forward physics simulations!*



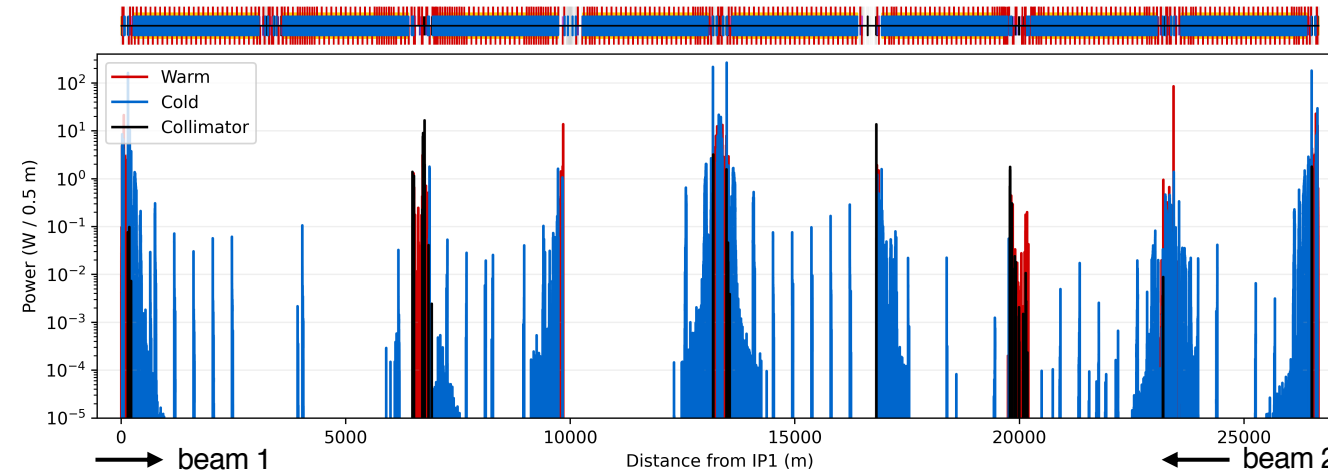
LHC Physics Debris Simulations

- Simulate head-on p-p collision with event generator at IPs 1,5 and 8
 - CRMC using SIBYLL 2.3 model
 - add on beam collision angle to primaries and propagate from each IP
- Record energy deposition throughout
 - individual peaks in arcs agree well with known BLMs to be correlated with luminosity



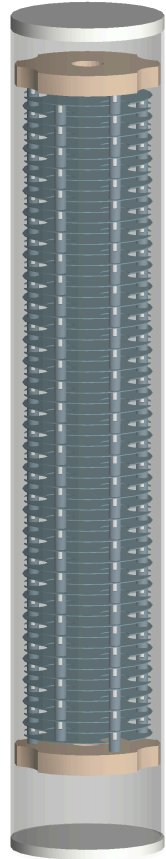
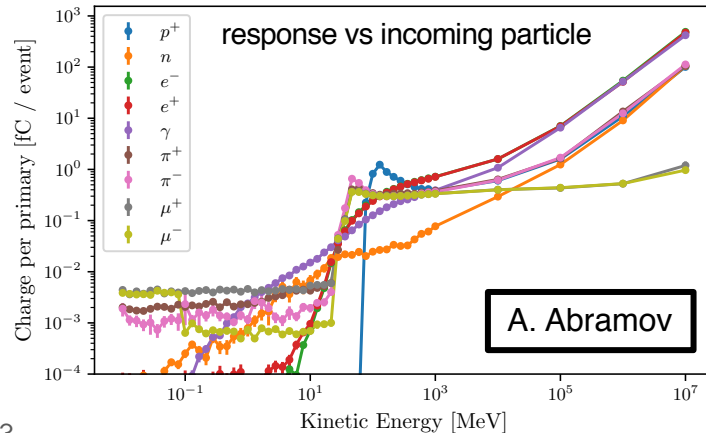
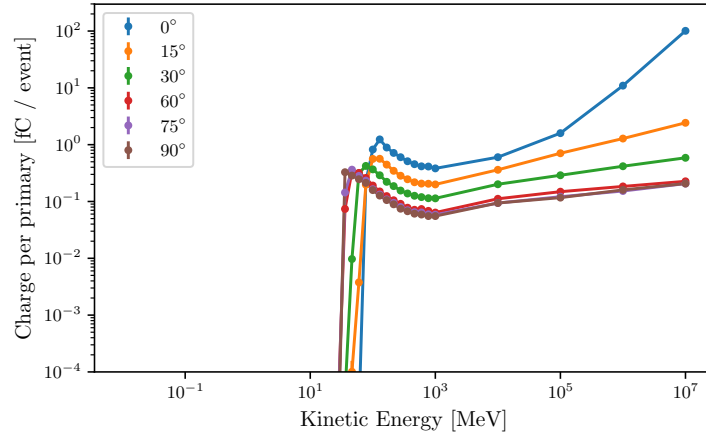
Weighted combination of each study according to luminosity

IP	Luminosity
1	1.5×10^{34}
5	1.5×10^{34}
8	0.05×10^{34}



Beam Loss Monitor Modelling

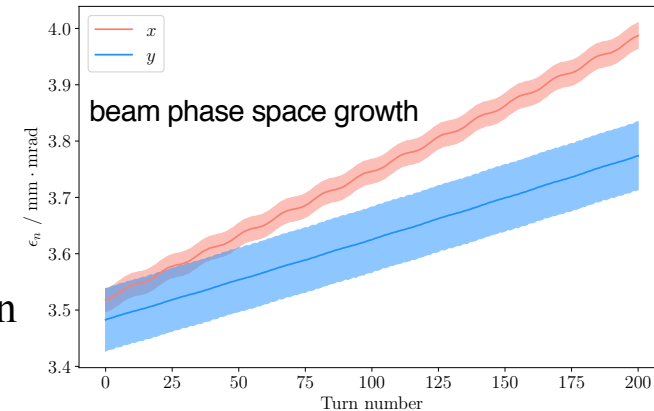
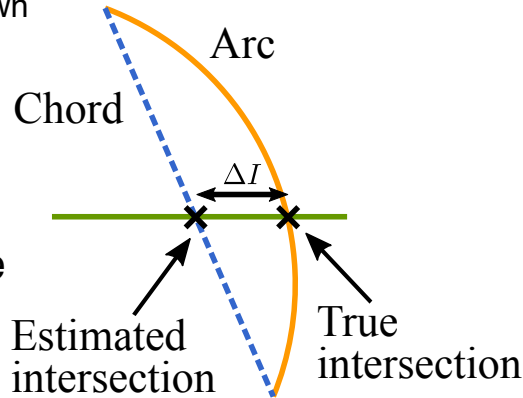
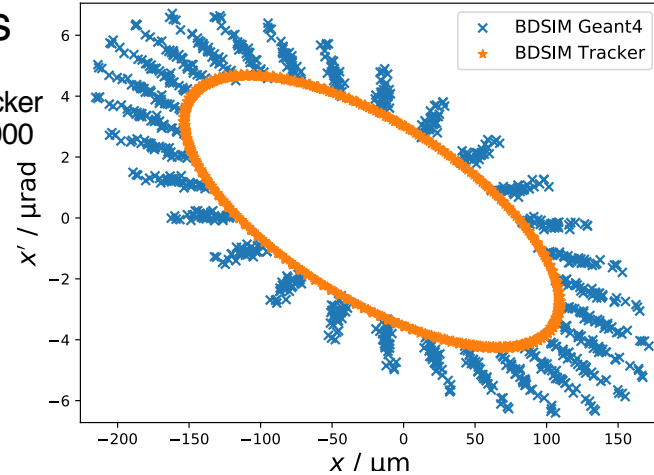
- LHC is instrumented with ~ 3600 beam loss monitors for machine protection
 - mostly gas ionisation chambers
 - too high losses and beam dumped to protect machine
- Geometry modelled in GDML using *pyg4ometry* package
 - see backup slides for rapid geometry package
- Calibration simulations as separate model recording charge deposited
 - agrees very well with published literature
- Use as parameterised model for simple geometry in complete LHC model
 - parameterise signal also on the collimator hits as high kinetic energy cuts can lead to lack of particles intercepting BLMs
 - place all ~ 3600 in BDSIM / Geant4 model of the LHC



Limitations & Symplecticity

- For longer term ring tracking we start to see limitations
 - "longer term" here is 100s to 1000s of turns of the LHC
 - for single pass models the tracking is very accurate
- Small numerical errors can build up
- '*Symplectic*' tracking conserves phase space
- Here, errors build up due to the convergence of the intersection with each boundary
 - each step of an algorithm is fine on its own
 - there is always a geometrical tolerance
 - leads to inaccurate result eventually
 - loss of precision with large models
 - a particle tracker has no such problem
- Tracker applies one map at a time
 - no ambiguity along direction of travel
- Need to retain accuracy

comparison of tracker
with Geant4 for 1000
turns of LHC



Combined Simulation Strategy

- Several possible strategies for combined tracker and physics model

- apart from already described BDSIM full Geant4 model

1. Pass over once from tracker to 3D model

- if particle is expected to go with beam first then be 'lost'
- after initial scatter assume won't complete multiple turns

2. Discrete regions for physics processes

- particle tracked in tracker
- for select elements propagate in 3D model
- works well for collimation - but no physics in tracker

3. Truly integrated tracking

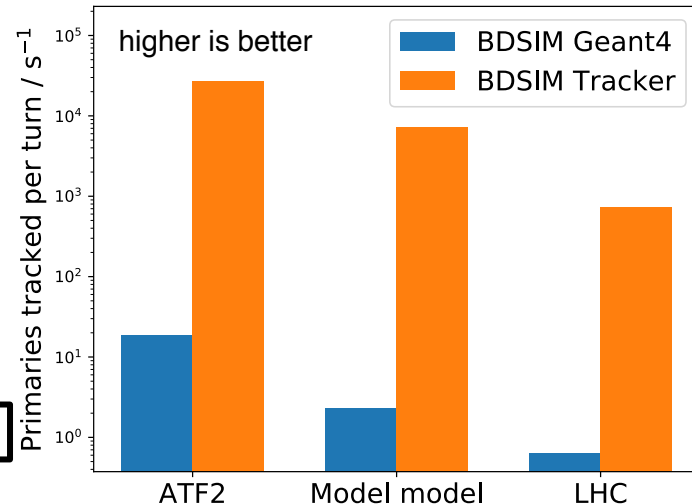
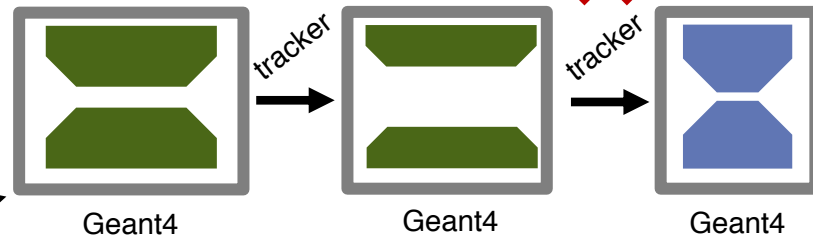


choose this option

- override transportation process in Geant4
- maintain concurrent curvilinear and Cartesian coordinates
- transform from curvilinear to Cartesian to push particle in 3D world
- no stringent intersection to maintain tracking accuracy (faster)
- tracking library written

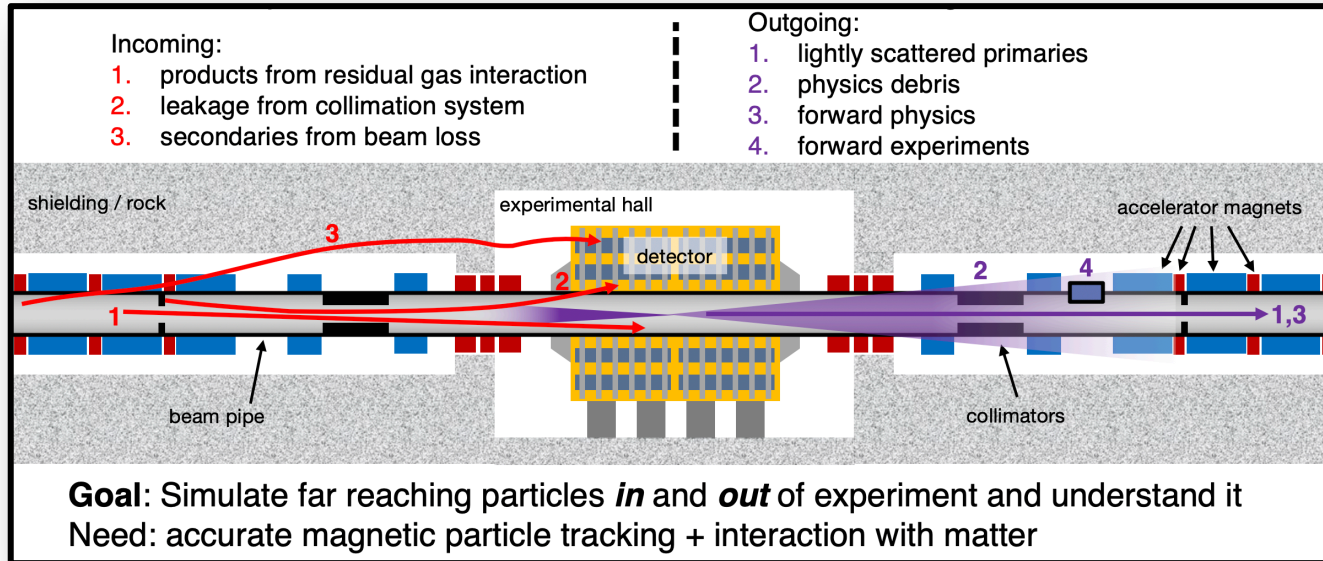
- *integration underway*

tracker alone is $\sim 10^3$ times faster



Conclusions - Bridging The Machine Detector Interface

- Ability to create Geant4 detector-like models of accelerators exists
 - permits understanding and analysis of origins of many background sources as well as signal propagation
 - include matter interaction and secondary particles
- Shown how to track *all* particles including ions and partially stripped ions



- Complete multi-turn *Geant4 model of the LHC* accelerator
- Future work to use model with all ~ 3600 beam loss monitors to disentangle *luminous* and *non-luminous* losses
 - potentially make independent luminosity measurement
- Upcoming *fully symplectic* particle tracker with in-flight Geant4 physics
- Many exciting extensions being added
 - laser-Compton scattering for laserwires
 - photo-detachment; excitation; spontaneous emission for in-flight partially stripped ions (see Gamma Factory)
 - Geant4 crystal channelling model for crystal collimation and beam extraction
 - halo generation throughout from residual gas interaction
- Please contact if interested in collaboration!
 - potential for joint PhD projects also

Thank you

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BDSIM - [website](#) - [manual](#) - [paper](#)

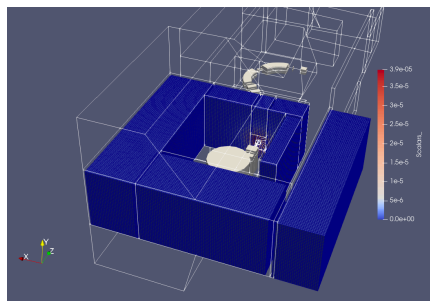
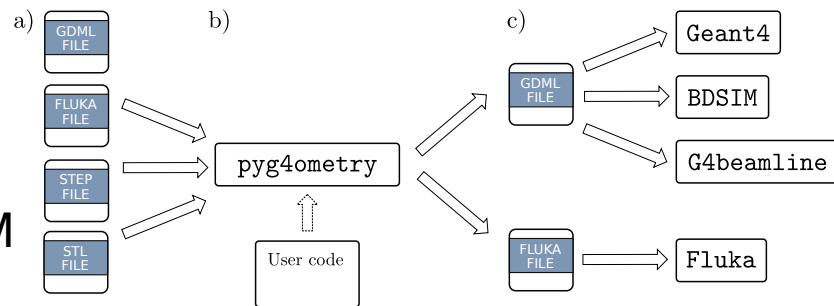
[1] Title slide image credit; CERN + BDSIM model



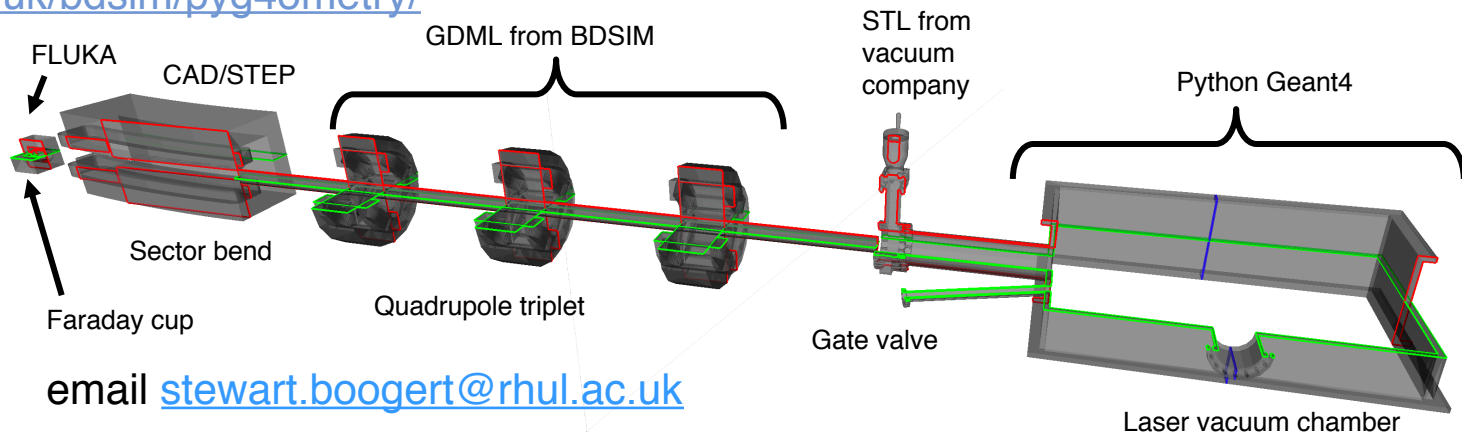
- python package to rapidly prepare and convert geometry for Geant4 & FLUKA
 - create / convert / composite geometry
 - validate and ensure safe for tracking (no overlaps etc)
- Place custom components in Geant4 / BDSIM
- Have parity with models in Geant4 & FLUKA

<https://bitbucket.org/jairhul/pyg4ometry/src/develop/>

<http://www.pp.rhul.ac.uk/bdsim/pyg4ometry/>



Shielding and beam line



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