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Combination of ATLAS and Tevatron W boson mass measurements

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The ATLAS, CDF and D0 Collaborations

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This note presents a combination of the ATLAS, CDF and D0 measurements of the W -boson mass. These measurements were performed at different moments in time, using different modelling assumptions for W -boson production and decay, using fits to detector-level distributions. The correlations between these measurements are dominated by uncertainties in the PDFs, for which different choices were made. Methods are presented to evaluate the effect of PDF variations on existing measurement results in a realistic way, which allows extrapolating past measurements to any past or present PDF set and evaluate the corresponding uncertainties. Based on this method, the measurements can be corrected to set of common PDF references, and combined accounting for PDF correlations in a rigorous way. The combined value is

$$m_W = 80XYZ \pm X(\text{exp.}) \pm Y(\text{PDF}) \pm Z(\text{mod.})$$

where the central value has been obtained for **PDF set to be defined**. The quoted PDF uncertainty includes the effect of partial correlations between the experiments. Central values for alternate sets are also given.

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45 TO DO

- 46 • improve (rebin) pTZ constraint plots
- 47 • compare PDF uncertainties with showered and unshowered evgen
- 48 • add CTEQ6.1 PDF uncertainties to D0 result
- 49 • improve D0 parameterisation

1 Introduction

The present note describes a combination of the CDF [1], D0 [2] and ATLAS [3] measurements of the W -boson mass, m_W . At hadron colliders, measurements of m_W rely on the interpretation of the kinematic peaks in leptonic decays. The final-state distributions carry information about the decaying particle mass, but also reflect the W production distributions, in particular the rapidity and transverse momentum distributions, and polarization. Predictions for the latter are obtained using event generators and parton distribution functions (PDFs) that are state-of-the-art at the time the measurements are performed, and typically differ between measurements.

The Tevatron and LHC measurements discussed here were performed at distant moments in time, and used different tools for the theoretical description of W -boson production and decay. Specifically, CDF and D0 used the ResBos [4–6] event generator for the prediction of the p_T^W distribution and the CTEQ6.6 PDF set [7], and ATLAS used Powheg [8–10], Pythia [11] and CT10 [12]. Combining both sets of results thus involves three steps : first, translate both results to a common reference model, *i.e.* a common set of proton PDFs; secondly, evaluate the correlation of PDF uncertainties at the Tevatron and LHC – while both machines are hadron colliders, the different center-of-mass energies (2 and 7 TeV for the Tevatron and LHC measurements, respectively) and initial states ($p\bar{p}$ vs. pp) makes this correlation non-trivial; finally, evaluate the model dependence of the result by repeating this procedure for a relevant set of current PDF sets.

A proper evaluation of PDF uncertainties and their correlations is numerically relevant, as PDFs constitute the dominant source of uncertainty for all measurements. While significant in size, uncertainties related to the p_T^W distribution are evaluated separately in each experiment through a detailed analysis of Z -boson production *in situ*, reducing correlations across experiments. Experimental uncertainties are by nature uncorrelated.

Beyond the interest of improving the overall measurement precision, several arguments motivate this project :

- At least three private, semi-qualitative averages are being used in recent literature [13–15]. While these numbers are probably numerically close to the actual result, they do not rely on a well established methodology that can be used for future averages of this or other hadron collider parameters, and neglect the fact that the measurements were performed assuming different PDF sets;
- the techniques developed to translate published measurements to a common PDF reference can also be used to update measurements to newer, more precise PDF sets;
- PDF uncertainty correlations, discussed here for the first time in the context of electroweak precision measurements, will also matter in the joint interpretation of different parameters in electroweak or EFT fits. For example, strong PDF uncertainty correlations are expected between m_W and the effective weak mixing angle, $\sin^2 \theta_{\text{eff}}$, when the LHC ultimately dominates the measurement precision for these parameters.

A general discussion of uncertainty correlations in m_W measurements is first given in Section 2. Sections 3 and 4 describe the general analysis methodology and the event samples used for the present analysis; analysis details are described in Section 5. Section 6.1–6.3 present extrapolations of the published CDF, D0 and ATLAS measurements to different PDF sets. Section 6.4 presents the fully combined results and gives PDF uncertainty correlations across experiments; finally, conclusions are given in Section 7.

2 Correlated and uncorrelated sources of uncertainty

Experimental uncertainties are by nature uncorrelated across experiments. Modelling uncertainties can be categorized as induced by the PDFs, by the p_T^W distributions or by electroweak corrections and are discussed below.

2.1 Electroweak corrections

The dominant effect of QED radiation on the W boson mass measurement is the reduction of the measured lepton momentum due to final-state radiation. The experiments model this radiation with the PHOTOS generator that produces a shower of photons above an energy threshold. Uncertainties on the modelling of electroweak corrections include: (1) the difference between the shower model and an explicit matrix-element calculation; (2) the energy threshold for producing final-state photons; and (3) higher-order corrections from final-state e^+e^- pair production. Tables 1 and 2 list these uncertainties for each experiment in the electron and muon channels, respectively. The uncertainties are completely correlated between the channels.

Uncertainty	CDF	D0	ATLAS	CDF-ATLAS	CDF-D0	D0-ATLAS
NLO calculation	4 (4)	5 (5)	2.5 (3.3)	0%	0%	100%
Photon y cutoff	2 (2)	2 (1)	--	--	100%	--
FSR e^+e^-	1 (1)	--	0.8 (3.6)	0%	--	--
Total	4 (4)	7 (7)	2.6 (4.9)			

Table 1: QED uncertainties in MeV on the m_W measurement in the electron channel using the m_T (p_T) fit. Uncertainty correlations between each pair of experiments are shown.

Uncertainty	CDF	ATLAS
NLO calculation	4 (4)	2.5 (3.5)
Photon y cutoff	2 (2)	--
FSR e^+e^-	1 (1)	0.8 (3.6)
Total	4 (4)	2.6 (5.6)

Table 2: QED uncertainties in MeV on the m_W measurement in the muon channel using the m_T (p_T) fit. The uncertainties are uncorrelated between the experiments.

To estimate the uncertainty from the limitations of the shower model relative to the matrix-element calculation, D0 performs a direct comparison between PHOTOS and WGRAD. ATLAS estimates the uncertainty with a similar procedure but with WINHAC providing the NLO model. The uncertainties are taken to be completely correlated between these experiments. CDF uses a different strategy, applying a correction to the measurement using the HORACE generator, which matches single-photon radiation to the NLO calculation. The residual uncertainty is entirely due to MC statistics, and is uncorrelated with the D0 and ATLAS uncertainties.

The shower model includes a lower threshold on the photon energy, expressed as a ratio y with respect to the energy of the lepton from the W boson decay. CDF uses a threshold of 10^{-5} and determines the

112 uncertainty by increasing the threshold by an order of magnitude. D0 uses a similar procedure except with
 113 an increase from 2.5×10^{-4} to 2×10^{-2} in y . These uncertainties are taken to be completely correlated.

114 To account for the higher-order process of an off-shell final-state photon splitting into an e^+e^- pair, CDF
 115 applies an effective radiator approximation to the radiated photons. ATLAS does not apply a correction,
 116 instead taking the uncertainty from a PHOTOS model of this process. The uncertainties are treated as
 117 uncorrelated.

118 2.2 W -boson p_T distribution

119 The prediction of the W -boson p_T distribution is a second potential source of uncertainty correlation. In
 120 the region relevant for m_W , the p_T distribution is described by a combination of perturbative fixed-order
 121 QCD, soft-gluon resummation and non-perturbative effects. The Tevatron experiments rely on analytical
 122 resummation as implemented in ResBos, while ATLAS used the Pythia parton shower.

123 Non-perturbative effects influence the very low boson p_T^W region, typically $p_T^W < 5$ GeV and are generally
 124 assumed universal between W and Z production. In absence of precise direct measurements of the W -boson
 125 p_T distribution, all measurements rely on Z -boson data to constrain the corresponding parameters.

126 The resulting model is then used for the prediction of the W -boson p_T distribution. The associated
 127 uncertainty originates from the limited precision of the Z -boson data, and from differences between the Z
 128 and W production mechanisms, in particular related to the different initial-state partonic configurations.

129 ATLAS, CDF and D0 derive the W -boson production model from their respective Z -boson data. Un-
 130 certainties from parton-level differences between Z and W production are only considered in ATLAS.
 131 Uncertainties related to the W -boson p_T distribution can thus be considered as uncorrelated between the
 132 three experiments.

133 2.3 PDF uncertainties

134 PDF uncertainties constitute the main source of correlation between the measurements. In the case of the
 135 Tevatron-only combination [16], the very similar measurement conditions implied full correlation of the
 136 PDF uncertainty, considered as a single nuisance parameter. In contrast, the large gap in energy between
 137 the Tevatron and the LHC, as well the different initial states are expected to induce only a partial correlation
 138 of these uncertainties, and a detailed study of the PDF uncertainty components is required. Methods to
 139 estimate this correlation are described in Section 3.

140 3 General methodology

141 3.1 Overview

142 The proposed method relies on an emulation of the existing measurements. The emulation consists of
 143 simplified parameterizations of the response of the experiments, and a reproduction of the corresponding
 144 analyses (event selections, fitting procedure, etc). While this approach is obviously not adequate for an
 145 actual measurement, it is sufficient for a reliable estimation of PDF uncertainties, as shown in Section 3.2.
 146 The emulation of the ATLAS, CDF and D0 measurements is described in Sections 6.1–6.3.

147 This emulation is applied to particle-level W - and Z -event samples that include event weights allowing to
 148 reproduce the production and decay distributions expected for an ensemble of PDF sets, including those
 149 used for the published measurements and a choice of more recent sets. The initial states reproduce the
 150 measurement conditions, ie $p\bar{p}$ collisions at 2 TeV for the Tevatron, and pp collisions at 7 TeV for ATLAS.
 151 Full details are given in Section 4.

152 The Monte Carlo samples are produced using a reference value for the W -boson mass and the corresponding
 153 Standard Model prediction for Γ_W . Kinematic distributions for different values of m_W are obtained by
 154 applying the following event weight:

$$w(m, m_W, m_W^{\text{ref}}) = \frac{(m^2 - m_W^2)^2 + m^4 \Gamma_w^2 / m_W^2}{(m^2 - m_W^{\text{ref}2})^2 + m^4 \Gamma_w^2 / m_W^{\text{ref}2}} \quad (1)$$

155 which represents the ratio of the Breit–Wigner densities corresponding to m_W and m_W^{ref} , for a given value
 156 of the final state invariant mass m .

157 The shift in the measured value of m_W resulting from a change in the assumed PDF set is estimated as
 158 follows. Considering a set of template distributions obtained for different values of m_W and a given reference
 159 PDF set, and “pseudo-data” distributions obtained for $m_W = m_W^{\text{ref}}$ and an alternate set i (representing the
 160 difference between the nominal predictions of two PDF sets, or uncertainty variations with respect to
 161 a given nominal PDF set), the preferred value of m_W for this set is determined by minimizing the χ^2
 162 between the pseudo-data and the templates. The preferred value of m_W for this set is denoted m_W^i , and the
 163 corresponding shift is defined as $\delta m_W^i = m_W^i - m_W^{\text{ref}}$.

164 The shifts are used to extrapolate existing measurements to alternate PDF sets and to estimate the
 165 corresponding PDF uncertainty, as discussed in Section 3.2. The procedure is validated by comparing the
 166 obtained PDF uncertainties with the published numbers.

167 For a proper evaluation of the PDF uncertainty correlations, the latter need to be evaluated for all existing
 168 measurement channels or categories, and combined. This includes six measurements for CDF (with fits to
 169 the p_T^ℓ , m_T and E_T^{miss} distributions in the $W \rightarrow e\nu, \mu\nu$ channels); two measurements for D0 (fits to the p_T^ℓ
 170 and m_T distributions in the $W \rightarrow e\nu$ channel), and 28 measurement categories for ATLAS (with fits to
 171 the p_T^ℓ and m_T distributions in the $W \rightarrow e\nu$, and $W \rightarrow \mu\nu$ channels, with three and four pseudorapidity
 172 categories respectively, separately for W^+ and W^- events). Combinations are performed using the BLUE
 173 method [17], as was used in all published measurements. Partial combinations, *i.e* reproducing published
 174 numbers for the individual CDF, D0 and ATLAS combinations and for the Tevatron combination provides
 175 further validation. Finally, a complete combination can be performed.

176 This procedure is repeated for a representative ensemble of current PDF sets, to evaluate the model
 177 dependence of the PDF correlations. The combined values of m_W are then compared for various PDF sets,
 178 and final prescription is given to define the reference combined value.

179 3.2 Impact of PDF variations on measurements of m_W

180 Correcting existing measurements to alternate PDFs

181 Denoting $m_W^{\text{data} | \text{ref}}$ the result of a measurement performed using a reference PDF set, and $m_W^{\text{data} | \text{alt}}$ the result
 182 corrected to an alternate PDF set, the latter can be written

$$m_W^{\text{data} | \text{alt}} = m_W^{\text{data} | \text{ref}} - \delta m_W^{\text{alt}} \quad (2)$$

183 where δm_W is introduced in the previous section and defined with respect to the reference PDF set.
 184 Published values are always used for $m_W^{\text{data|ref}}$; the measurement emulation procedure is only used for
 185 δm_W^{alt} .

186 PDF uncertainties

187 For Hessian PDF sets, the uncertainty corresponding to a given set is estimated as

$$\delta m_W^+ = \left[\sum_i (\delta m_W^i)^2 \right]^{1/2} \text{ if } \delta m_W^i > 0, \quad \delta m_W^- = \left[\sum_i (\delta m_W^i)^2 \right]^{1/2} \text{ if } \delta m_W^i < 0, \quad (3)$$

188 where i runs over the uncertainty sets, and δm_W^i is the difference between the fitted value for set i and the
 189 reference PDF set. Only symmetrized uncertainties, $\delta m_W = (\delta m_W^+ + \delta m_W^-)/2$, are discussed below for
 190 simplicity.

191 The effect of each PDF eigenset is fully correlated across experiment or measurement categories, and its
 192 contribution to the covariance between any two measurements α, β is given by

$$C_{\alpha\beta}^i = \delta m_{W\alpha}^i \delta m_{W\beta}^i. \quad (4)$$

193 Accounting for all eigensets of a given set, the total PDF uncertainty covariance and the corresponding
 194 uncertainty correlation are calculated as

$$C_{\alpha\beta}^{\text{PDF}} = \sum_i C_{\alpha\beta}^i \quad (5)$$

$$\rho_{\alpha\beta} = \frac{\sum_i \delta m_{W\alpha}^i \delta m_{W\beta}^i}{\delta m_{W\alpha} \delta m_{W\beta}}. \quad (6)$$

195 In the case of NNPf, which provides PDF replica sets from fits to fluctuated data, the uncertainty is
 196 estimated from the spread of the fitted values of m_W over the N replicas:

$$\delta m_W = \left[\frac{1}{N} \sum_i (\delta m_W^i)^2 \right]^{1/2}. \quad (7)$$

197 ATLAS case : p_T^Z -constrained PDF uncertainties

198 Due to their influence on the rate of W, Z -boson production in association with jets, PDFs contribute to
 199 the uncertainty in the vector boson p_T distributions. The ATLAS measurement accounts for the precisely
 200 measured Z -boson p_T distribution at 7 TeV [18] by correcting the PDF weight returned by Powheg as
 201 follows:

$$w_{i \rightarrow j}^{\text{corr}} \equiv w_{i \rightarrow j} \times \left(\frac{1}{\sigma_Z} \frac{d\sigma_Z}{dp_T} \right)_i \bigg/ \left(\frac{1}{\sigma_Z} \frac{d\sigma_Z}{dp_T} \right)_j \quad (8)$$

202 where $w_{i \rightarrow j}$ is the Powheg PDF weight modifying the generated distributions from PDF sets i and j .
 203 This correction ensures that the Z -boson p_T distribution remains unchanged, and removes the part of
 204 the corresponding W -boson uncertainty that is correlated to the Z . This is approximately equivalent to
 205 re-tuning the Pythia parton shower to the Z data for each PDF variation, but simpler in practice. The impact
 206 of this correcting weight on the generator-level W^+ - and W^- -boson p_T distribution at 7 TeV is illustrated
 207 in Figure 1 for CT10; the effect on the transverse mass and lepton p_T distributions is shown in Figure 2.
 208 Other PDFs are illustrated in Figure 11 in Appendix A.

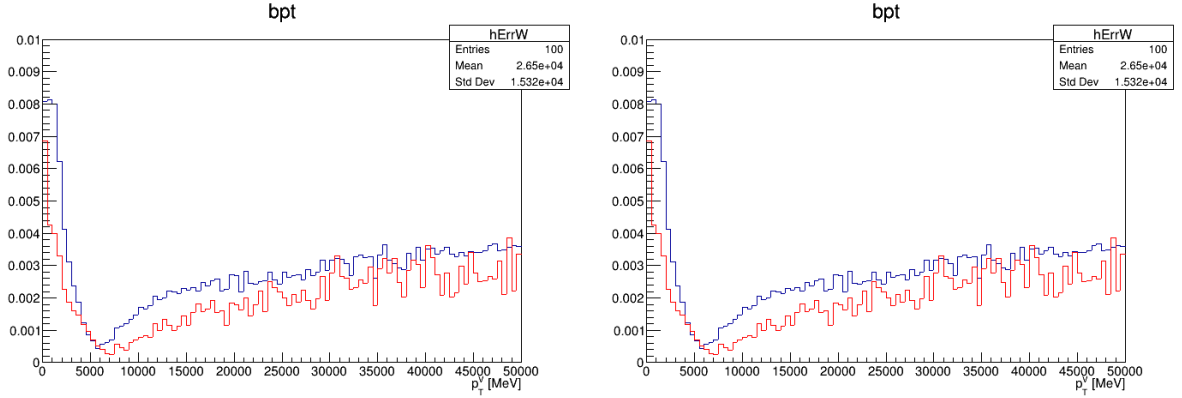


Figure 1: Effect of the $p_T Z$ constraint on the generator-level W^+ - and W^- -boson p_T distributions. The blue and red curves represent the conventional and p_T^Z -constrained PDF uncertainties, respectively.

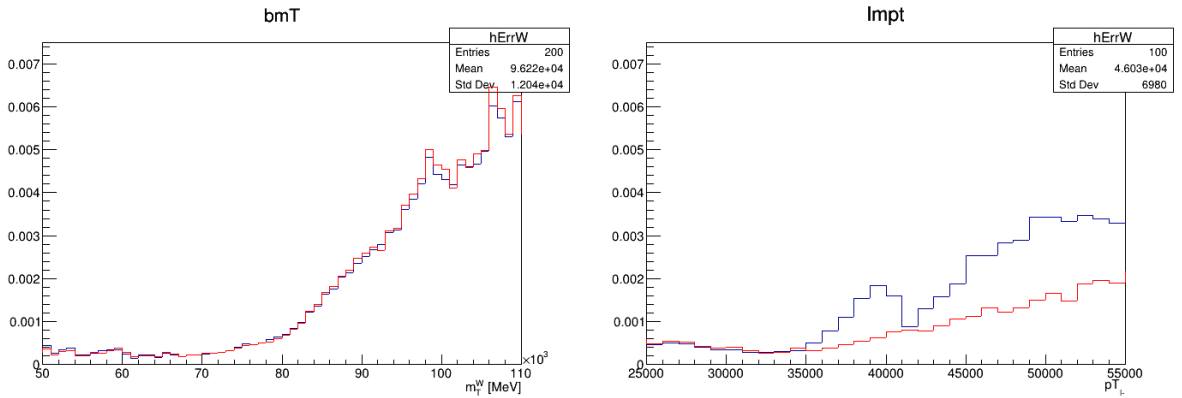


Figure 2: Effect of the $p_T Z$ constraint on the generator-level transverse mass and lepton p_T distributions. The blue and red curves represent the conventional and p_T^Z -constrained PDF uncertainties, respectively. The p_T^Z -constraint significantly reduces the uncertainty in the p_T^ℓ distribution as expected; the m_T distribution, which is by construction insensitive to p_T^W modelling uncertainties, is mostly unaffected.

209 4 Event generation

210 The generation of $W \rightarrow \ell \nu$ and $Z \rightarrow \ell \ell$ events both for pp collisions at $\sqrt{s} = 7$ TeV and $p\bar{p}$ collisions
 211 at $\sqrt{s} = 1.96$ TeV relies on the POWHEG V2 event generator [8–10]. The `W_EW_BMNNP` [19] and
 212 `Z_EW_BMNNPV` [20] processes are used without the NLO electroweak corrections. Final-state QED
 213 corrections (QED FSR) are applied using PHOTOS [21].

214 Apart from the collinear photon radiation, which can be completely absorbed by “dressing” the leptons
 215 with all QED FSR photons within a cone of $\Delta R < 0.1$ around the final state lepton, the generated electron
 216 and muon decays are identical. It is sufficient to generate just the muon decays.

217 The nominal event generation is performed with the CT10 PDF set [12]. Weights are calculated internally
 218 by POWHEG that allow the samples to be reweighted to several alternate PDF sets including their eigenvectors
 219 or replicas to estimate the effects of PDF uncertainties and their correlations: CT10 [12], CTEQ6.1 [22]¹,
 220 CTEQ6.6 [7], CT10nnlo [23], CT14nnlo [24], CT18NNLO and CT18ANNLO [25], MSTW2008nlo with
 221 both the 68% CL and 90% CL error sets [26], MMHT2014nnlo 68%CL [27], NNPDF31_nnlo_as_0118 [28],
 222 ABMP16_5_nnlo [29] and CJ15nlo [30].

223 A first set of samples was produced interfacing POWHEG to the PYTHIA 8 event generator [11] with
 224 parameters set according to the AZNLO tune [31]. This gives the best-possible modelling of the full
 225 final state, including the effects from parton showering, intrinsic k_T and underlying event. Although the
 226 computing requirements of these types of samples are still modest, it involves three steps with two large
 227 intermediate output formats to arrive at the final analysis ntuple: first EVNT files are produced from the
 228 Powheg+Pythia 8+Photos stage; EVNT files are converted to Truth DAOD format; finally TruthDAOD are
 229 processed with the MiniTree maker to ntuple format.

230 However, eventually only the four-vectors of leptons (ℓ^\pm, ν) at bare and dressed QED level are required
 231 for the analysis. A more efficient way with minimal loss of accuracy was therefore chosen to generate
 232 the samples: POWHEG LHE events are directly interfaced to PHOTOS, an empirical “shower” algorithm is
 233 applied to smear the transverse momentum while respecting the leading p_T emission already generated by
 234 POWHEG, and finally the events are directly written to disk in the form of the small analysis ntuple. This
 235 processing chain requires just a single step and no intermediate files need to be written to disk.²

236 5 Measurement emulation

237 5.1 Parameterisation of the ATLAS, CDF and D0 experimental resolutions

238 ATLAS, CDF and D0 use different notations and conventions to parameterise the recoil response and
 239 resolution. Introducing u_{\parallel} and u_{\perp} , the projections of the recoil on the axes parallel and perpendicular to
 240 the W boson line of flight, we compare the experiments in terms of a response function $R \equiv -\langle u_{\parallel} \rangle / p_T^W$,
 241 and resolution functions $\sigma_{u_{\parallel}}$ and $\sigma_{u_{\perp}}$. R represents the ratio between the reconstructed and true transverse
 242 momentum of the W boson; the resolution of u_{\parallel} , $\sigma_{u_{\parallel}}$, is expected to be slightly larger than $\sigma_{u_{\perp}}$ due to the
 243 presence of hard radiation recoiling against the W .

244 Resolution effects in lepton reconstruction are also accounted for in the procedure. With a typical relative
 245 momentum resolution of about 2% for all experiments, these effects are subleading and not discussed
 246 further.

¹ Special thanks to Andy Buckley for converting the PDF set from LHAPDF5 to LHAPDF6 version.

² If necessary, events can still be reweighted to the POWHEG+PYTHIA8 AZNLO prediction of vector boson p_T .

247 The recoil response functions for CDF are parameterised in terms of the recoil magnitude and angular
 248 resolution. For $p_T^W < p_T^{\max} = 15$ GeV:

$$R(p_T^W) = 0.645 \times \log(5.1 \times p_T^W + 8.2) / \log(5.1 \times p_T^{\max} + 8.2), \quad (9)$$

$$\sigma_{u_T}(p_T^W) = 0.82 \times \sqrt{p_T^W} \text{ GeV}, \quad (10)$$

$$\sigma_{u_\phi}(p_T^W) = 0.306 + 0.021 \times (9.4 - p_T^W) \text{ rad}; \quad (11)$$

249 while for $p_T^W > p_T^{\max}$ the angular resolution becomes

$$\sigma_{u_\phi}(p_T^W) = 0.144 + 0.0048 \times (24.5 - p_T^W) \text{ rad}. \quad (12)$$

250 A simplified parameterisation of the recoil response for D0, adequate for the purpose of this study, is³:

$$R(p_T^W) = 0.46/p_T^W - 0.55 - 0.0021 \times p_T^W, \quad (13)$$

$$\sigma_{u_\perp}(p_T^W) = 3.6 + 0.013 \times p_T^W + 0.00010 \times p_T^{W2} \text{ GeV}, \quad (14)$$

$$\sigma_{u_\parallel}(p_T^W) = 3.5 - 0.055 \times p_T^W + 0.00072 \times p_T^{W2} \text{ GeV}. \quad (15)$$

251 Both experiments achieve a typical resolution of 4–5 GeV in the p_T^W range relevant for the measurement.

252 For ATLAS, the recoil response is extracted from profiles of R , σ_{u_\parallel} and σ_{u_\perp} as a function of the W -boson
 253 transverse momentum, obtained from the simulation and corrected for calibration discrepancies. The recoil
 254 resolution is about 12–16 GeV, mostly depending on the amount of pile-up.

255 The performances of ATLAS, CDF and D0 for the recoil response are compared in Figure 3.

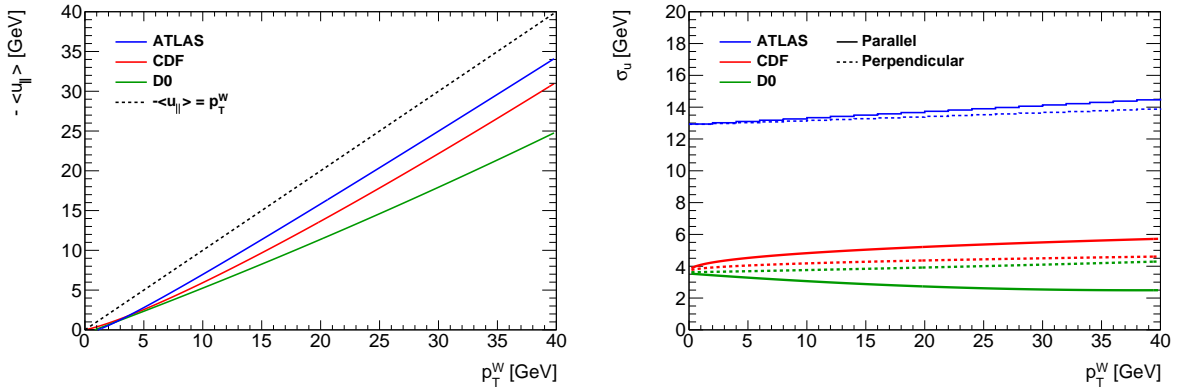


Figure 3: Comparison of the parameterised recoil response (left) and resolution (right) for ATLAS, CDF and D0.

256 5.2 Event selections, fit ranges and measurement categories

257 Event selections and fitting ranges for the three measurements are summarized in Table 3. CDF and D0
 258 use very similar analysis configurations. The looser recoil cut and wider m_T fit range in ATLAS are a
 259 consequence of the worse recoil resolution. The multijet background is enhanced in ATLAS due to the
 260 worse recoil resolution and the higher collision energy; the tighter p_T^ℓ fit range mitigates this effect.

³ R. Coelho Lopes de Sa, private communication.

Experiment	Event selections	Fit ranges
CDF	$30 < p_T^\ell < 55 \text{ GeV}, \eta_\ell < 1$ $30 < E_T^{\text{miss}} < 55 \text{ GeV}, 60 < m_T < 100 \text{ GeV}$ $u_T < 15 \text{ GeV}$	$32 < p_T^\ell < 48 \text{ GeV}$ $32 < E_T^{\text{miss}} < 48 \text{ GeV}$ $65 < m_T < 90 \text{ GeV}$
D0	$p_T^\ell > 25 \text{ GeV}, \eta_\ell < 1.05$ $E_T^{\text{miss}} > 25 \text{ GeV}, m_T > 50 \text{ GeV}$ $u_T < 15 \text{ GeV}$	$32 < p_T^\ell < 48 \text{ GeV}$ $65 < m_T < 90 \text{ GeV}$
ATLAS	$p_T^\ell > 30 \text{ GeV}, \eta_\ell < 2.4$ $E_T^{\text{miss}} > 30 \text{ GeV}, m_T > 60 \text{ GeV}$ $u_T < 30 \text{ GeV}$	$32 < p_T^\ell < 45 \text{ GeV}$ $66 < m_T < 99 \text{ GeV}$

Table 3: Event selections and fit ranges for CDF, D0 and ATLAS.

261 CDF performs measurements in the $W \rightarrow e\nu$ and $W \rightarrow \mu\nu$ channels, using template fits to the p_T^ℓ , m_T and
262 E_T^{miss} distributions, *i.e.* six measurements. D0 uses the p_T^ℓ and m_T distributions in the $W \rightarrow e\nu$ channel only.
263 These measurements are performed inclusively in pseudorapidity and summing over W^+ and W^- decays.
264 ATLAS measures W^+ and W^- events separately, as in pp collisions the final state distributions are different
265 for these processes. In addition, the analyzed pseudorapidity range is separated into three categories in the
266 electron channel, and four categories in the muon channel, yielding a total of 28 measurements.

267 The p_T^ℓ and m_T distributions simulated as above, and obtained after all event selections are compared to the
268 published distributions in Figure 4.

269 5.3 Quality of the emulated PDF-induced shifts in m_W

270 The precision of the emulated PDF-induced shifts in the fitted value of m_W is studied using the ATLAS
271 measurement. With 28 measurement categories and 25 CT10nnlo PDF eigensets, a high-statistics
272 comparison between the emulation and the full measurement procedure can be performed.

273 This comparison is performed in Figure 5, which illustrates the correlation between the published and
274 emulated shifts for CT10nnlo. The shifts are defined as in Section 3.1: $\delta m_W^i = m_W^i - m_W^{\text{ref}}$, where the
275 reference set is the CT10nnlo central set, and the variations i are the uncertainty sets.

276 Analyzing all variations separately (50 shifts for each category), a spread of 3 MeV is found between the
277 published and emulated shifts. When symmetrizing the uncertainty variations, *i.e.* considering only 25
278 symmetrized shifts, the spread reduces to 1.5 MeV. These numbers are included as a systematic uncertainty
279 associated to the emulation procedure.

280 6 Results

281 The methods described above are used to estimate the effect of PDF variations on the existing m_W results
282 by CDF, D0 and ATLAS.

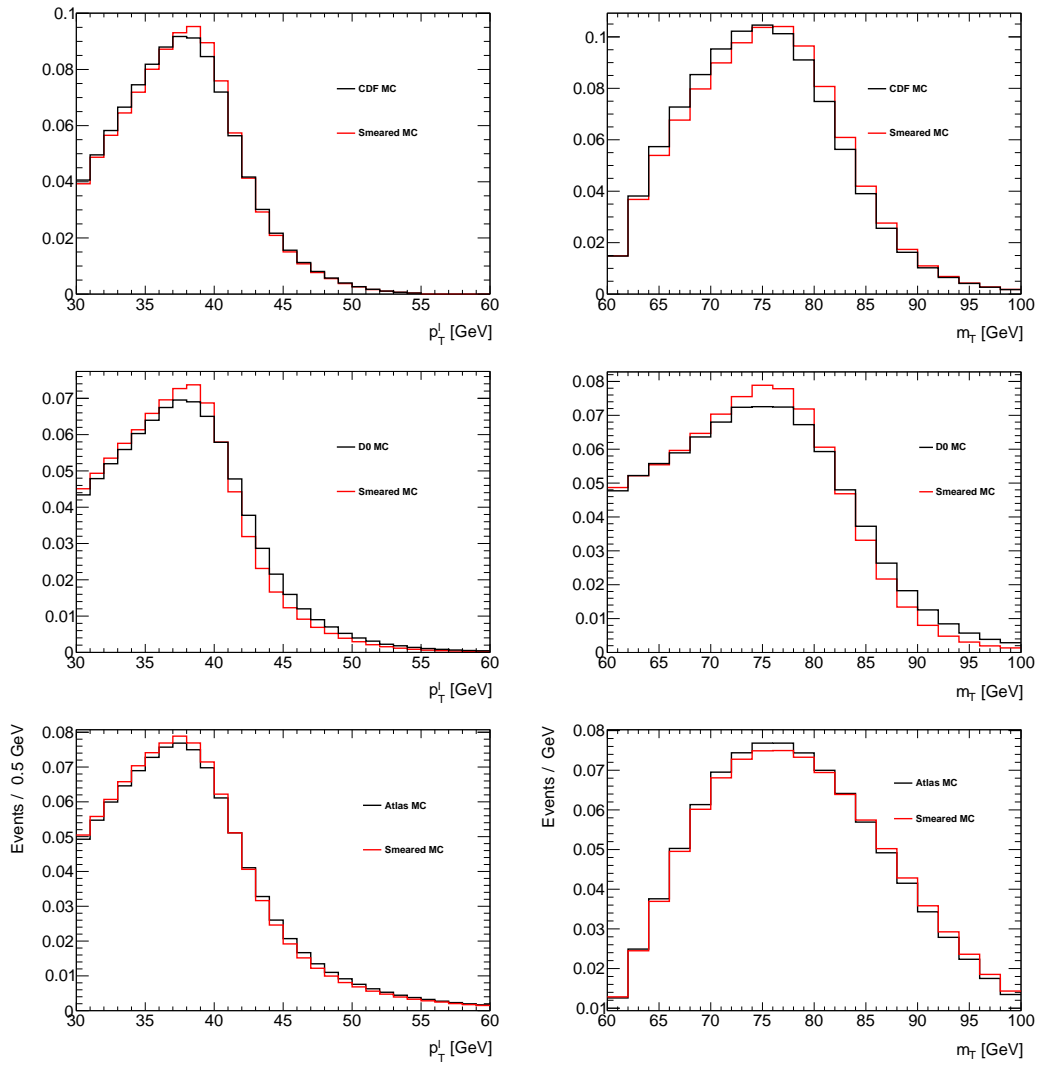


Figure 4: Comparison of the published and simulated p_T^{ℓ} (left) and m_T (right) distributions, for CDF (top), D0 (centre) and ATLAS (bottom).

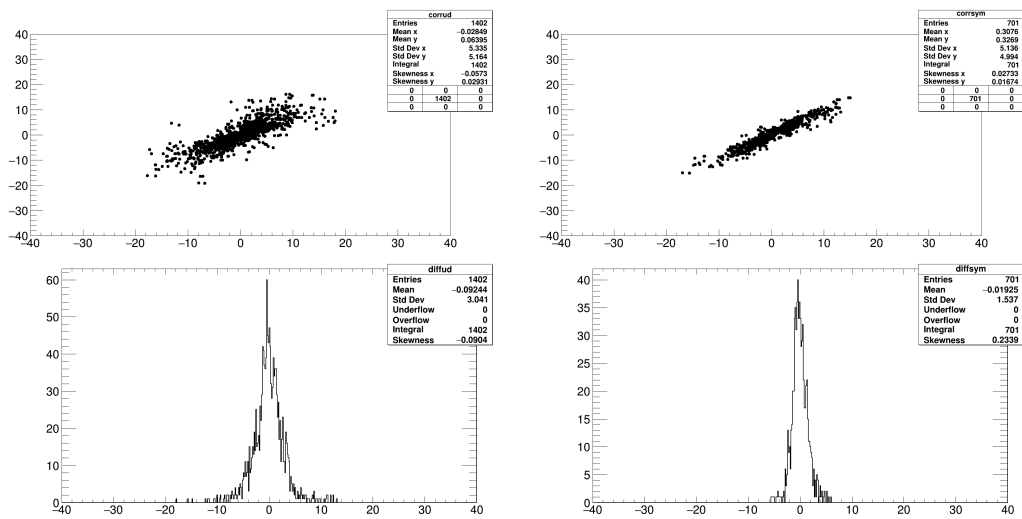


Figure 5: Top : correlation between the published and emulated CT10nnlo PDF shifts, in the MeV, for the ATLAS measurement. Bottom : distribution of the differences between published and emulated shifts. On the left, all uncertainty sets enter the distributions. On the right only symmetrized shifts are considered.

283 As a first step, the method is validated by reproducing, using the analysis emulation described above,
 284 the PDF uncertainty estimates of the corresponding publications. The same techniques are then used
 285 to extrapolate, for each experiment, the measurement result to alternate PDFs, and the corresponding
 286 uncertainties.

287 This procedure is applied separately for all measurement results, i.e. six channels for CDF, two for D0, and
 288 28 for ATLAS. The combinations are then performed separately for all experiments, accounting for PDF
 289 uncertainty correlations as explained in Section 3.2.

290 Fully combined results are then calculated for all considered PDF sets, and a final recommendation is
 291 derived.

292 6.1 Results for CDF

293 The published CDF results used CTEQ6.6 for the central value with PDF uncertainties estimated using
 294 MSTW2008 at 68% CL. The scaling factor between MSTW2008 at 90% CL and MSTW2008 at 68% CL
 295 is 2.15 and was found back in the context of this analysis. Extrapolated results for CDF are given in Table 4,
 296 and the corresponding PDF uncertainties are given in Table 5. The analysis emulation procedure with
 297 MSTW2008 accurately reproduces the published PDF uncertainty.

298 The combined result is reproduced within 2 MeV. The residual difference is due to the fact that the channel
 299 combination is performed using the full PDF uncertainty decomposition (i.e. all PDF uncertainty sets are
 300 used separately in the combination), where the CDF measurement treats the PDF uncertainty as a single,
 301 fully correlated nuisance parameter across all channels.

302 Extrapolating the measurement to different PDF sets yields shifts in the central values smaller than 5 MeV,
 303 compared to the published result, for all sets considered here. PDF uncertainties range between 16 MeV
 304 for CT10 and 8 MeV for MMHT2014.

Category	CTEQ6.6 [†]	CT10	CT10nnlo	CT14	MSTW2008	MMHT2014
$W \rightarrow e\nu$ m_T fit	80 408	80 400	80 408	80 403	80 407	80 402
$W \rightarrow e\nu$ p_T^ℓ fit	80 393	80 386	80 391	80 389	80 396	80 391
$W \rightarrow e\nu$ E_T^{miss} fit	80 431	80 423	80 431	80 426	80 429	80 425
$W \rightarrow \mu\nu$ m_T fit	80 379	80 371	80 379	80 374	80 378	80 373
$W \rightarrow \mu\nu$ p_T^ℓ fit	80 348	80 341	80 346	80 344	80 351	80 346
$W \rightarrow \mu\nu$ E_T^{miss} fit	80 406	80 398	80 406	80 401	80 404	80 400
Combined (published)	80 387	–	–	–	–	–
Combined (emulated)	80 389	80 382	80 389	80 385	80 388	80 384

Table 4: Fitted values of m_W (MeV) at CDF, for various PDF sets. The PDF set labelled [†] is used to define the central value of the published measurement result.

	Published		Emulated					
	CTEQ6.6 [†]	MSTW2008 [§]	CTEQ6.6 [†]	CT10	CT10nnlo	CT14	MSTW2008 [§]	MMHT2014
Central value	80 387	80 387	80 389	80 382	80 389	80 385	80 388	80 384
Stat.	12	12	12	12	12	12	12	12
Exp. syst.	10	10	10	10	10	10	10	10
QCD, QED	6	6	6	6	6	6	6	6
PDF	10	10	14	16	11	14	10	8
Total	19	19	22	23	20	21	19	18

Table 5: CDF combination results, for various PDF sets. The first column indicated the published uncertainty table; the next columns indicate the extrapolated central values and PDF uncertainties, calculated consistently with the given PDF set. PDF sets labelled [†] and [§] are used for the published measurement central value and for the PDF uncertainty, respectively.

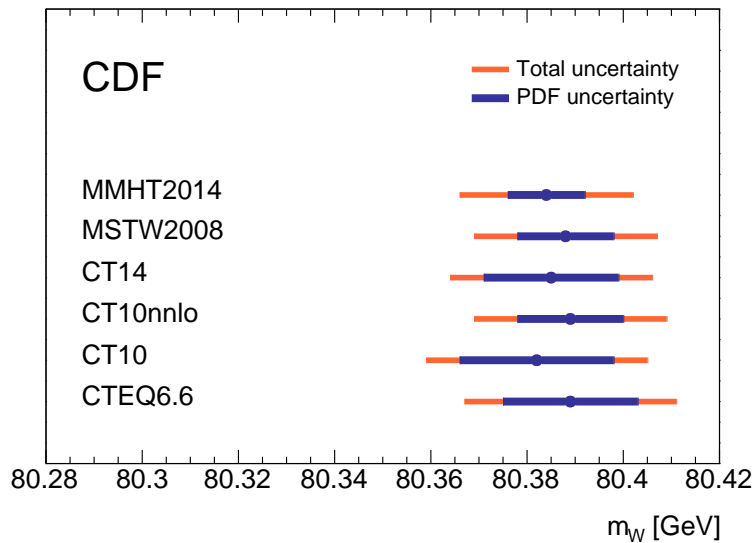


Figure 6: Measured value of m_W in CDF for different PDF sets. The reference PDF set for CDF is CTEQ6.6.

6.2 Results for D0

The published D0 results used CTEQ6.6 PDF set for the central value and CTEQ6.1 for the estimation of PDF uncertainties with a scaling of 1.645 to 68% CL. Extrapolation results for D0 are given in Table 6, and the corresponding PDF uncertainties are given in Table 7.

The analysis emulation yields a CTEQ6.1 PDF uncertainty of 15 MeV, compared to 10 MeV in the D0 publication. This difference remains to be understood. Comparing Tables 7 and 5, it can be noted that the D0 and CDF PDF uncertainties are always close, as expected from the similarity of the measurement conditions and as mentioned in Section 2. The observed difference is therefore likely due to a difference in the physics modelling assumptions rather than the limited accuracy of the parameterisation of the recoil response and resolution.

The emulated combined result differs from the publication by 3.5 MeV, which is understood as follows. The two channels of the D0 measurement are correlated to 90%; the larger PDF uncertainty found here further increases this correlation. The BLUE combination procedure determines the channel weights such that the resulting uncertainty is minimal; in the limit of full correlation, the weight of the most precise channel tends to 1 and the less precise channel is ignored, even if the difference in precision is very small. In the present case, the m_T fit is slightly more precise than the p_T^{ℓ} fit, and the combined result tends to that result when the correlation increases. When scaling the PDF uncertainty to reproduce the publication, the published combined value is recovered to better than 1 MeV.

Extrapolating the measurement to different PDF sets yields shifts in the central values smaller than 4 MeV, compared to the published result, for all sets considered here. As for CDF, PDF uncertainties range between 16 MeV for CT10 and 8 MeV for MMHT2014.

6.3 Results for ATLAS

The published ATLAS results used CT10nnlo for both the central value and the estimation of PDF uncertainties with a scaling of 1.645 to 68% CL. Measurement extrapolation results for ATLAS are given in Table 8, and the corresponding PDF uncertainties are given in Table 9. The analysis emulation procedure reproduces the published PDF uncertainty, and the combined result is reproduced within 1 MeV. As above, this residual difference is mostly due to the influence of the impact of the emulated PDF uncertainties on the channel weights.

Extrapolating the measurement to different PDF sets yields shifts in the central values up to 15 MeV compared to the published result. The larger PDF dependence can be explained an increased PDF model dependence, in a region that is less strongly constrained by the data compared to the Tevatron. PDF uncertainties range from 12 MeV for CT14, down to 5 MeV for MSTW2008.

6.4 Tevatron–LHC combination

This sections presents the complete combination results, including all available results. The procedure, and the full list of considered PDF sets is as above, and the results are shown in Table 10. Figure 9 gives a graphical representation of these results.

TO DO The choice of PDFs considered for the final result is decided following criteria:

Category	CTEQ6.6 [†]	CT10	CT10nnlo	CT14	MSTW2008	MMHT2014
$W \rightarrow e\nu$ m_T fit	80 371	80 363	80 371	80 366	80 369	80 365
$W \rightarrow e\nu$ p_T^ℓ fit	80 343	80 336	80 341	80 339	80 345	80 340
Combined (published)	80 367	–	–	–	–	–
Combined (emulated)	80 370	80 364	80 370	80 367	80 367	80 363

Table 6: Fitted values of m_W (MeV) at D0, for various PDF sets. The PDF set labelled [†] is used to define the central value of the published measurement result.

	Published		Emulated				
	CTEQ6.6 [†] , CTEQ6.1 [§]	CTEQ6.6 [†]	CT10	CT10nnlo	CT14	MSTW2008	MMHT2014
Central value	80 367	80 370	80 364	80 370	80 367	80 367	80 363
Stat.	13	13	13	13	13	13	13
Exp. syst.	18	18	18	18	18	18	18
QCD, QED	7	7	7	7	7	7	7
PDF	11	14	16	11	13	10	8
Total	26	27	28	26	27	25	25

Table 7: D0 combination results (**TODO : this is the 4 fb⁻¹ result only**). The first column indicated the published uncertainty table; the next columns indicate the extrapolated central values and PDF uncertainties, calculated consistently with the given PDF set. PDF sets labelled [†] and [§] are used for the published measurement central value and for the PDF uncertainty, respectively.

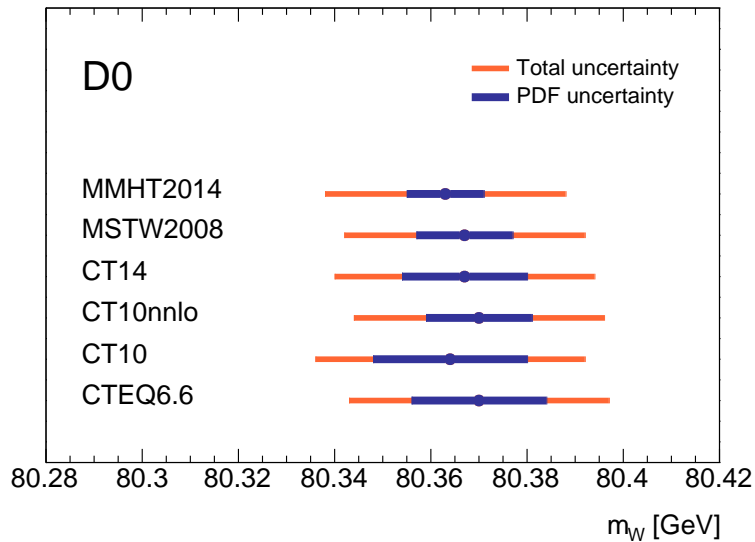


Figure 7: Measured value of m_W in D0 for different PDF sets. The reference PDF set for D0 is CTEQ6.6.

Channel	$ \eta $ range	CT10nnlo [†]	CT10	CTEQ6.6	CT14	MSTW2008	MMHT2014
<i>m_T</i> fits							
$W^- \rightarrow e\nu$	0–0.6	80 416	80 386	80 392	80 405	80 395	80 440
$W^- \rightarrow e\nu$	0.6–1.2	80 298	80 280	80 285	80 277	80 287	80 308
$W^- \rightarrow e\nu$	1.8–2.4	80 424	80 454	80 437	80 439	80 474	80 418
$W^+ \rightarrow e\nu$	0–0.6	80 353	80 321	80 324	80 326	80 318	80 365
$W^+ \rightarrow e\nu$	0.6–1.2	80 382	80 352	80 364	80 349	80 340	80 369
$W^+ \rightarrow e\nu$	1.8–2.4	80 353	80 341	80 351	80 375	80 291	80 338
$W^- \rightarrow \mu\nu$	0–0.8	80 376	80 345	80 352	80 365	80 355	80 400
$W^- \rightarrow \mu\nu$	0.8–1.4	80 418	80 400	80 405	80 397	80 407	80 428
$W^- \rightarrow \mu\nu$	1.4–2.0	80 380	80 384	80 376	80 367	80 396	80 388
$W^- \rightarrow \mu\nu$	2.0–2.4	80 335	80 365	80 347	80 349	80 384	80 328
$W^+ \rightarrow \mu\nu$	0–0.8	80 372	80 340	80 342	80 344	80 336	80 383
$W^+ \rightarrow \mu\nu$	0.8–1.4	80 355	80 324	80 337	80 321	80 312	80 342
$W^+ \rightarrow \mu\nu$	1.4–2.0	80 427	80 403	80 421	80 416	80 374	80 401
$W^+ \rightarrow \mu\nu$	2.0–2.4	80 335	80 324	80 333	80 357	80 274	80 320
<i>p_T^ℓ</i> fits							
$W^- \rightarrow e\nu$	0–0.6	80 352	80 329	80 333	80 344	80 337	80 370
$W^- \rightarrow e\nu$	0.6–1.2	80 310	80 295	80 298	80 295	80 304	80 321
$W^- \rightarrow e\nu$	1.8–2.4	80 414	80 435	80 419	80 428	80 455	80 413
$W^+ \rightarrow e\nu$	0–0.6	80 337	80 314	80 316	80 318	80 311	80 344
$W^+ \rightarrow e\nu$	0.6–1.2	80 346	80 323	80 332	80 322	80 315	80 338
$W^+ \rightarrow e\nu$	1.8–2.4	80 345	80 335	80 343	80 363	80 292	80 332
$W^- \rightarrow \mu\nu$	0–0.8	80 428	80 406	80 410	80 421	80 414	80 446
$W^- \rightarrow \mu\nu$	0.8–1.4	80 396	80 381	80 384	80 381	80 389	80 407
$W^- \rightarrow \mu\nu$	1.4–2.0	80 381	80 383	80 376	80 373	80 394	80 390
$W^- \rightarrow \mu\nu$	2.0–2.4	80 316	80 337	80 320	80 329	80 357	80 315
$W^+ \rightarrow \mu\nu$	0–0.8	80 328	80 305	80 307	80 309	80 302	80 336
$W^+ \rightarrow \mu\nu$	0.8–1.4	80 358	80 334	80 344	80 333	80 327	80 349
$W^+ \rightarrow \mu\nu$	1.4–2.0	80 447	80 428	80 441	80 439	80 406	80 429
$W^+ \rightarrow \mu\nu$	2.0–2.4	80 335	80 324	80 332	80 352	80 281	80 322
Combined (published)		80 370	–	–	–	–	–
Combined (emulated)		80 369	80 355	80 358	80 354	80 353	80 369

Table 8: Fitted values of m_W (MeV) at ATLAS, for various PDF sets. The PDF set labelled [†] is used to define the central value of the published measurement result.

	Published		Emulated				
	CT10nnlo ^{†§}	CT10nnlo ^{†§}	CT10	CTEQ6.6	CT14	MSTW2008	MMHT2014
Central value	80 370	80 369	80 355	80 358	80 354	80 353	80 369
Stat.	7	7	7	7	7	7	7
Exp. syst.	11						
QCD, QED	10						
PDF	9	9	10	8	12	5	9
Total	19	19	19	18	21	17	19

Table 9: ATLAS combination results. The first column indicated the published uncertainty table; the next columns indicate the extrapolated central values and PDF uncertainties, calculated consistently with the given PDF set. Occasional changes between the published and emulated experimental and modelling uncertainties are due to the influence of the PDF uncertainties on the weights of the categories. PDF sets labelled [†] and [§] are used for the published measurement central value and for the PDF uncertainty, respectively.

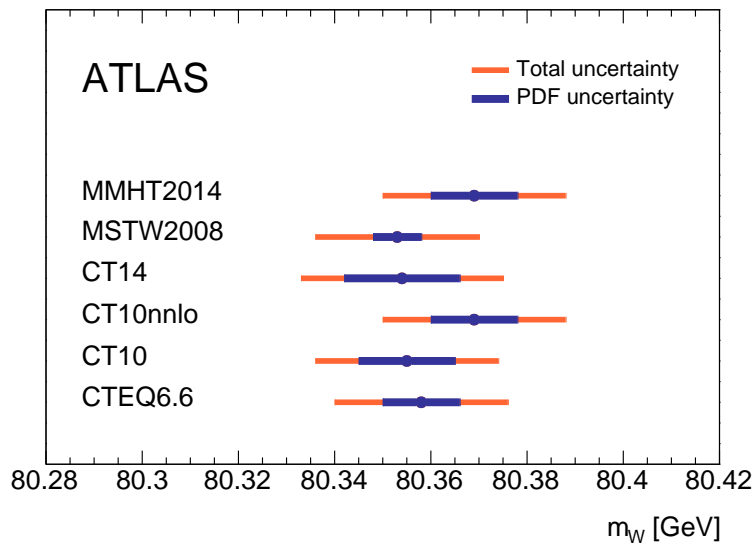


Figure 8: Measured value of m_W in ATLAS for different PDF sets. The reference PDF set for ATLAS is CT10nnlo.

- 342 • Consider only the last published set of each PDF fitting group;
- 343 • Consider only NNLO PDF fits;
- 344 • Consider only sets explicitly providing 68% C.L. uncertainties.

345 CT14, MMHT2014, NNPDF3.1, ABMP.. survive these criteria.

346 The final results are shown in Figure 10. The final world average is defined from the flat average between all
 347 considered combined results. Assuming full correlation between the different PDF uncertainty estimates,
 348 the final PDF uncertainty is defined from the average PDF uncertainty over all sets, as calculated from
 349 Table ???. An additional uncertainty is counted for for the spread of the m_W central values, defined from
 350 half the maximum difference between all fit results.

	CTEQ6.6	CT10	CT10nnlo	CT14	MSTW2008	MMHT2014
Central value	80 367	80 364	80 380	80 373	80 363	80 375
Statistical	6	6	7	7	6	6
Experimental						
Boson p_T						
PDF	9	10	8	9	5	7
Other QCD						
Higher-order EWK						
Total	14	15	14	14	12	13

Table 10: Combination summary

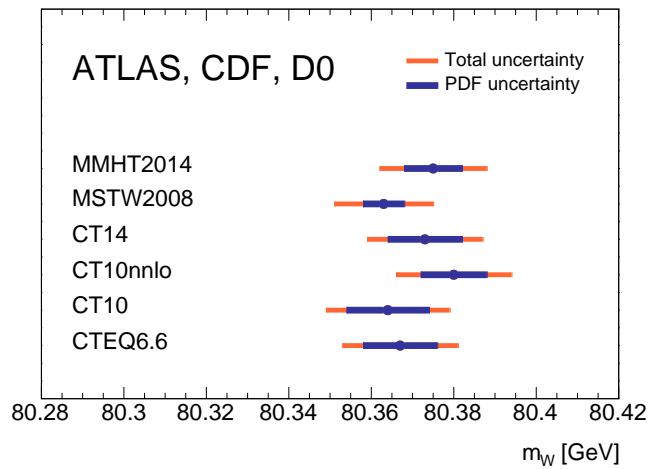


Figure 9: Combined value of m_W for different PDF sets.

351 7 Conclusion

We have presented a combination of the ATLAS, CDF and D0 measurements of the W -boson mass. These measurements were performed at different moments in time, using different modelling assumptions for W -boson production and decay, using fits to detector-level distributions. The correlations between these measurements are dominated by uncertainties in the PDFs, for which different choices were made. Methods are presented to evaluate the effect of PDF variations on existing measurement results in a realistic way, which allows extrapolating past measurements to any past or present PDF set and evaluate the corresponding uncertainties. Based on this method, the measurements can be corrected to set of common PDF references, and combined accounting for the partial PDF correlations in a quantitative way. The combined value is

$$m_W = 80XYZ \pm X(\text{exp.}) \pm Y(\text{PDF}) \pm Z(\text{mod.})$$

352 where the central value has been obtained for PDF set to be defined, conventionally chosen as reference for
 353 the combination. Central values for alternate sets are also given.

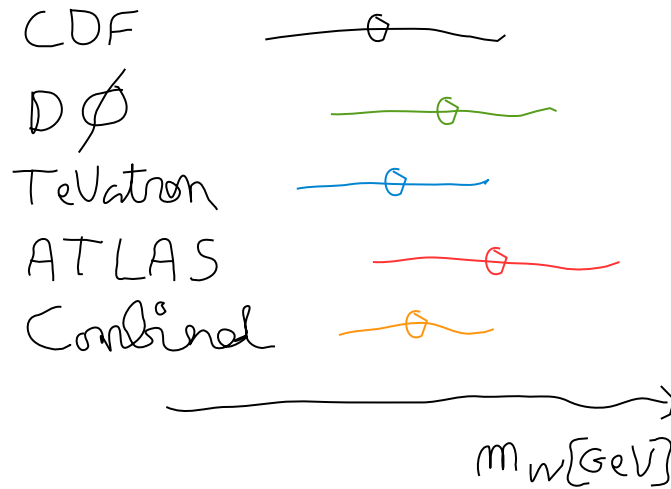


Figure 10: m_W summary plot (CDF, D0, Tevatron, ATLAS and fully combined values). Recommendation for PDF baseline and uncertainty to be decided.

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427 The supporting notes for the analysis should also contain a list of contributors. This information should
428 usually be included in `mydocument-metadata.tex`. The list should be printed either here or before the
429 Table of Contents.

430 **List of contributions**

431

432 **Appendices**

433 **A p_T^Z -constrained final state distributions for CTEQ6.6, CT14,**
434 **MMHT2014 and NNPDF3.1**

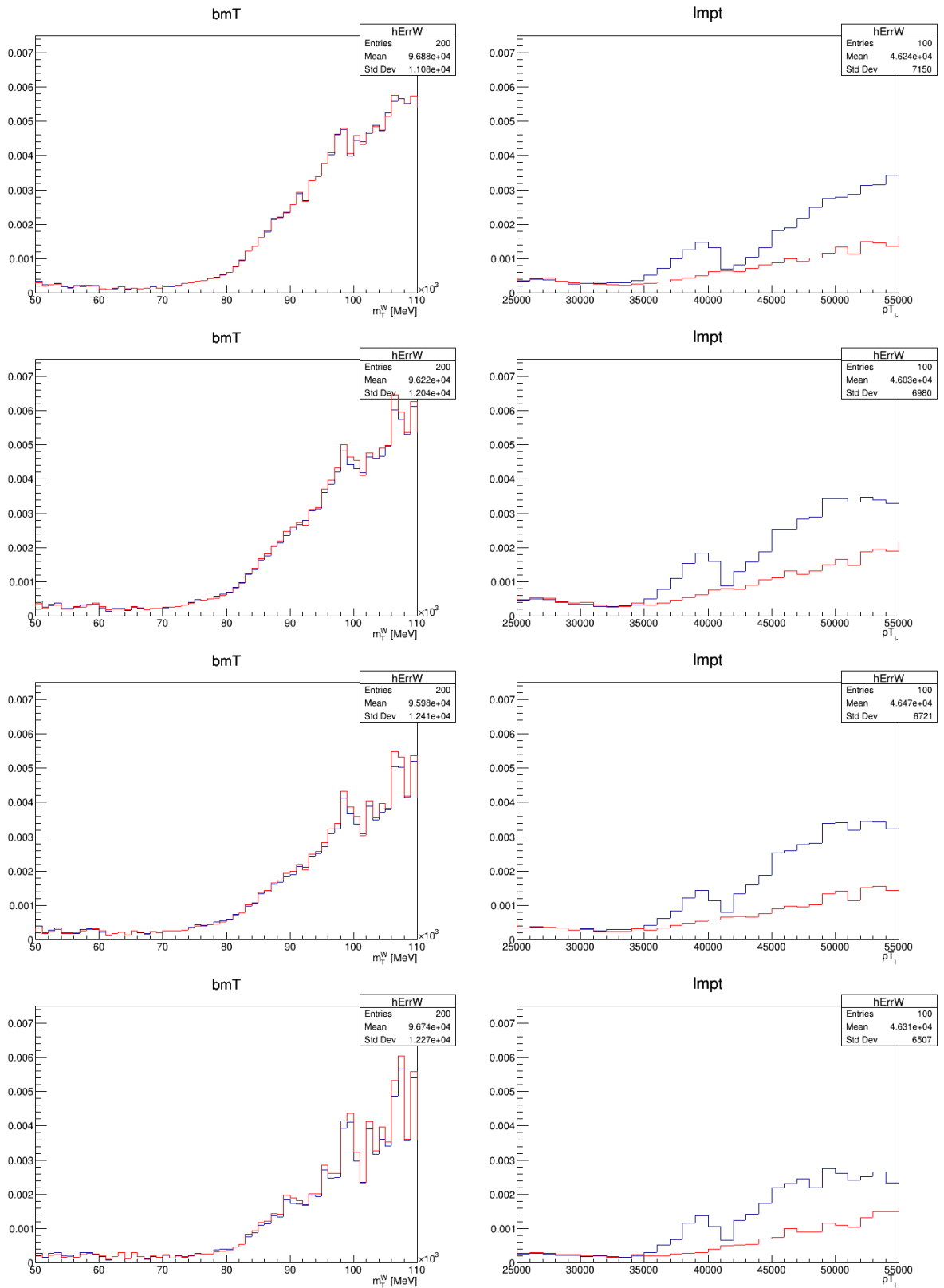


Figure 11: Effect of the p_{TZ} constraint on the generator-level transverse mass (left) and lepton p_T (right) distributions, for CTEQ6.6, CT10, CT14 and MMHT2014.