Metrics from Machine Learning

Moduli-dependent Calabi-Yau and SU(3)-structure metrics from machine learning

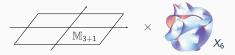
Anderson, Gerdes, Gray, Krippendorf, Raghuram, Ruehle; arXiv:2012.04656

Mathis Gerdes 27 August 2021 SUSY 2021

Why Calabi-Yau manifolds?

(Compact, complex space with $c_1(X) = 0 \leftrightarrow \text{Ricci-flat Kähler metric}$)

- String theory vacuum configuration $M_{10} = \mathbb{M}_{3+1} imes X_6$
- Compactification with CY manifold gives 4D N = 1 SUSY, hope to reproduce low energy physics (Candelas, Horowitz, Strominger, Witten 1985)



Why do we want the metric?

- Know CY metric exists but no analytic expression (Yau 1978)
- Many quantities without explicit metric using algebraic geometry
- E.g. massive spectrum, D3-brane inflation do need metric
 - \longrightarrow existing numerical & new ML approaches

Calabi-Yau Metric

Numerical Approaches

Machine Learning

Machine Learning of the Metric

Metrics from Machine Learning (Anderson, Gerdes, Gray, Krippendorf, Raghuram, Ruehle [2012.04656])

Calabi-Yau Metric

We consider a one-parameter family of hypersurfaces in \mathbb{P}^4 :

$$p_{\psi}(z) = \sum_{i=0}^{4} (z^{i})^{5} + \psi \prod_{i=0}^{4} z^{i} = 0$$



Know CY metric exists, now seek numerical approximations.

- Kähler: Kähler form $J = i g_{i\bar{j}} dz^i \wedge d\bar{z}^{\bar{j}}$ is closed: $dJ = 0 \leftrightarrow$ locally have Kähler function K s.t. $g_{i\bar{j}} = \partial_i \overline{\partial}_{\bar{j}} K$
- Overlaps: If defined on patches, must match on overlaps
- Ricci-flat: The Ricci curvature vanishes,

$$R_{i\overline{\jmath}} = -\partial_i \overline{\partial}_{\overline{\jmath}} \log \det g \stackrel{!}{=} 0$$

Fourth order PDE in terms of the Kähler potential!

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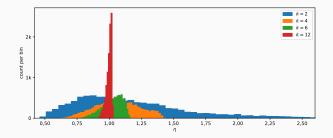
CY Accuracy Measure

Two constructions for top (volume) form:

- Holomorphic (3,0) form Ω : $vol_{\Omega} = \Omega \land \overline{\Omega}$
- Kähler form J for metric g: $vol_g = J \land J \land J \propto \det g$
- For Ricci-flat CY metric, must be proportional: $J \wedge J \wedge J = \kappa \ \Omega \wedge \overline{\Omega}$

Accuracy measure
$$\sigma = \frac{1}{\operatorname{vol}(X)} \int_X \left| 1 - \frac{\eta}{\kappa} \right|$$
 with $\eta = \frac{\operatorname{vol}_g}{\operatorname{vol}_\Omega} \stackrel{\scriptscriptstyle \mathrm{CY}}{=} \kappa = \operatorname{const}$

Integral is convex in J! (Headrick, Nassar [0908.2635])



Numerical Approaches

Local vs Spectral Methods

Finite Differences on K3 twofold (Headrick, Wiseman [hep-th/0506129])

- Using J = ∂∂K in J³ = κΩ ∧ Ω gives a Monge-Ampère equation (PDE linear in determinant of Hessian of K)
- Applying relaxation method to grid approximation of K
- Curse of dimensionality for higher dimensions & need explicit patches!

Spectral method based on Donaldson's work [math/0512625]

- Algebraic expression for K parametrized by a Hermitian matrix H_k
- Parameter k is the cut-off of a spectral expansion
- Donaldson's algorithm obtains the balanced metric which satisfies

$$H_k = T(H_k)^{-1}$$

- Obtain balanced metrics through iteration of T for fixed degree k
- Balanced metrics $\xrightarrow{k \to \infty}$ CY metric

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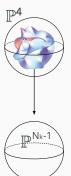
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Algebraic Kähler Potential

- Have Fubini-Study metric from \mathbb{P}^4 : $K_{FS} = \log \sum_i |z^i|^2$
- Generalize by replacing zⁱ with basis of homogeneous polynomials s^α(z) of degree k and inserting a Hermitian matrix H:

$${\cal K}_h = \log \sum_{lpha areta} s^lpha(z) \, {\cal H}_{lpha areta} \, ar s^{areta}(ar z)$$

- Geometric interpretation: H parametrizes embedding of X into \mathbb{P}^{N_k-1}
- Ansatz is the pullback of the FS metric from \mathbb{P}^{N_k-1}
- The s^α must form basis of sections of O_X(k); reduction from polynomial basis on P⁴ given p_ψ(z) = 0 not unique
- Algebraic construction always satisfies overlap and Kählerity constraints!



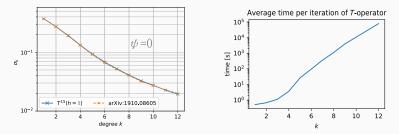
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Donaldson's Algorithm

• Donaldson's algorithm iteratively applies T-operator

$$H_{\alphaar{eta}} \quad \mapsto \quad T(H)^{lphaar{eta}} = rac{N_k}{\operatorname{vol}(X)} \int_X rac{s^lpha ar{s}^eta}{s^\gamma \, H_{\gammaar{ar{b}}} ar{s}^ar{b}} \, d\mathrm{vol}$$

- Balanced metrics converge to CY metric like $O(k^{-2})$
- If we optimize σ accuracy, expect in general exponential convergence (Headrick, Nassar [0908.2635])
- Computational cost of algorithm grows like $O(k^{16})$
- Must evaluate for each new set of moduli



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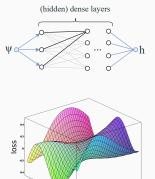
(Anderson, Gerdes, Gray, Krippendorf, Raghuram, Ruehle [2012.04656])

Machine Learning

Deep Learning

• Parametrized *network*: $(\theta, x) \mapsto \hat{y}$

- Often *deep* chain of linear combinations and non-linear *activation functions*
- Learn parameters θ by following gradient of some loss (energy) function, e.g.
 L(θ, x) = |y(x) − ŷ(θ, x)|²
- Automatic differentiation: For any f(α, β), can programatically get ∂_αf
- We need to work with complex variables, holomorphic derivatives
- Our loss contains $\eta \propto \det \partial \bar{\partial} K$
- We used PyTorch, Tensorflow and JAX

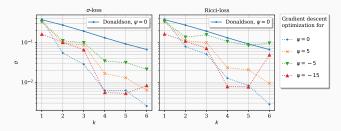


 θ_1

Machine Learning of the Metric

Existing ML Approaches

 Balanced metrics converge slowly: minimize σ for algebraic ansatz (H) at fixed moduli (Headrick, Nassar [0908.2635])



- Donaldson's algorithm is expensive: Extrapolate results to larger k (Ashmore, He, Ovrut [1910.08605])
- Reduce # parameters & faster numerics: Replace polynomial in algebraic ansatz $K_h = \log \sum_{\alpha \bar{\beta}} s^{\alpha} H_{\alpha \bar{\beta}} \bar{s}^{\bar{\beta}}$ with a network (Douglas, Lakshminarasimhan, Qi [2012.04797])

$$(z, \bar{z}) \stackrel{\mathsf{net}}{\longmapsto} s^{\alpha}(z) H_{\alpha \bar{\beta}} \, \bar{s}^{\bar{\beta}}(\bar{z})$$

Metrics from Machine Learning

(Anderson, Gerdes, Gray, Krippendorf, Raghuram, Ruehle [2012.04656])

New Approaches

Moduli-dependent approximation of algebraic metrics

- Interpolate parameters H from Donaldson's algorithm between values of ψ (at a fixed degree k)
- Optimize networks $\psi\mapsto H$ without training data from Donaldson's algorithm

Networks to predict the metric directly

- Optimize networks for CY metric: $(\psi,z)\mapsto g_\psi(z)$
- No longer automatically Kähler & satisfy overlap condition
- Advantage: also works for metrics with SU(3)-structure ($dJ \neq 0$)

$$\begin{array}{c} \psi \longrightarrow & \begin{array}{c} \text{Model} \\ \text{learnable parameters } \theta \end{array} \xrightarrow{} & \begin{array}{c} H \longrightarrow & K \\ \hline z & \downarrow \\ g_{a\bar{b}} \end{array} & \begin{array}{c} \psi \\ \hline z \end{array} \xrightarrow{} & \begin{array}{c} \text{Model} \\ \text{karnable parameters } \theta \end{array} \xrightarrow{} & \begin{array}{c} g_{a\bar{b}} \end{array} \end{array}$$

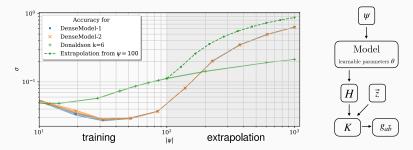
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Moduli Dependent Algebraic Metric

• In all approaches used the Monge Ampère loss which is the Monte Carlo approximation of the σ accuracy:

$$\mathcal{L}_{MA} = \frac{1}{N} \sum_{n=1}^{N} \left| \frac{\eta(z_n)}{\kappa} - 1 \right|^2 w(z_n)$$

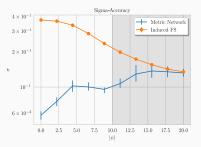
- Weights w(z_n) known if we sample points z as intersections of X with a random line in P⁴ [hep-th/0612075]
- \bullet Instead of $|\dots|^2$ could use any convex function

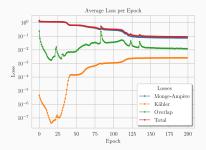


Network for Metric Directly

$$\begin{array}{c} \psi \\ \vec{z} \end{array} \longrightarrow \begin{array}{c} \text{Model} \\ \text{\tiny learnable parameters } \theta \end{array} \longrightarrow \begin{array}{c} g_{a\bar{b}} \end{array}$$

- Similar accuracy as Donaldson's balanced metric at same degree but lower numerical cost
- Need to include all losses: $\mathcal{L} = \lambda_1 \mathcal{L}_{MA} + \lambda_2 \mathcal{L}_{dJ} + \lambda_3 \mathcal{L}_{overlap}$
- Use perturbation around FS metric as ansatz: $g = g_{FS} (1 + g_{NN})$
- Weighing of different losses not obvious, application dependent
- Very general approach: non-Kähler, better parametrizations possible





Summary and Future Work

- Moduli-dependent networks which approximate the metric simultaneously for a range of values
 - Order of minutes where Donaldson's algorithm would take tens of hours (for same σ accuracy)
 - Standalone, does not need existing results for training
- · Networks which predict the metric directly
 - General approach, can apply to SU(3)-structure
- NN and ML frameworks well suited for problem
- Never explicitly exploited symmetry, but application to more moduli work for the future
- Find better basis of sections (basis for *H_k*), or replace with networks for polynomial
- Apply to physics questions

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Thank You