#### ebg *Med* Austron



# Main Timing System Overview

Joze Dedic (joze.dedic@cosylab.com)

... on behalf of CSL MA team

<mark>ٱ</mark>

#### Outline

#### ...CWO-1

- overview & role; timing system
- operational view (run, cycles, events)
- main timing generator, MTG
- transport layer / MRF
- main timing receiver, MTR (EVR link to EUC)

• CWO-2...

## Timing activities in CWO-1

- studied & refined requirements (simplified<sup>©</sup>)
- moved reqs. to EA model (traceability)
- made high-level architecture design
- did a step further to allow better architectural decisions (CWO-2)
  MRF internal FPGA development (..NDA)
  - MRF integration to LV RT



### Overview & role;



#### **Operational view**



## Main timing generator, MTG



## Transport layer / MRF



## Main timing receiver, MTR



- trigger equipment via univ. IO module (electrical or optical signal)
- trigger application via IRQ
- trigger neighboring cards via the 8 bit PXI real-time bus
- provide time stamp functionality
- (offline) configure
  - which events to listen in which VA
  - how to respond

#### **CWO-2** activities

- distribute and agree MTS requirements with all WP holders
- finalize MTS architecture
- define verification procedure; FAT/SAT
- set up mockup demo of MTS
- work towards final implementation

 $\odot$ 

### Sync or swim

- timing and synchronization system from 1917
- twin Vickers machine guns, synchronized to fire at 500 rounds/min between the blades of the propeller rotating in front of them
- In the event of a timing error, a few hits on the wooden blades were sufficient for the plane's own propeller to be shot away.



Sopwith Camel

cosvlab