



Intro into Machine Learning

Linear Models. Numerical optimization. Logistic Regression. Figures of Merits. Overfitting. Model Selection. Regularization.

Advanced Computing and Machine Learning Course 25-27 May 2020, IGFAE

Alexey Artemov^{1,2} Andrey Ustyuzhanin^{2,3}

¹ Skoltech ² NRU Higher School of Economics ³ NUST MISiS

Lecture overview

- > Linear models for regression
- > Numerical and stochastic optimization at a glance
- > Linear models for classification
- > Figures of merits
- > Overfitting: how to fool the linear regression
- > Regularization

> Some criteria for machine learning to be applied in a dependency recovery setting:

Some criteria for machine learning to be applied in a dependency recovery setting:
 Little prior knowledge of the dependency exists

- > Some criteria for machine learning to be applied in a dependency recovery setting:
 - > Little prior knowledge of the dependency exists
 - > The dependency has a complex form too hard for manual examination

- > Some criteria for machine learning to be applied in a dependency recovery setting:
 - > Little prior knowledge of the dependency exists
 - > The dependency has a complex form too hard for manual examination
 - > A sample from the dependency of sufficiently large size is available

> Would one want to apply machine learning for . . .

> Would one want to apply machine learning for . . .

> ... Newton's mechanics?

- > Would one want to apply machine learning for . . .
 - > ... Newton's mechanics?
 - > ... suggesting music to radio listeners?

- > Would one want to apply machine learning for . . .
 - > ... Newton's mechanics?
 - > ... suggesting music to radio listeners?
 - > ... sorting integers?

- > Would one want to apply machine learning for . . .
 - > ... Newton's mechanics?
 - > ... suggesting music to radio listeners?
 - > ... sorting integers?
 - > ... controlling steel production?

- > Would one want to apply machine learning for . . .
 - > ... Newton's mechanics?
 - > ... suggesting music to radio listeners?
 - > ... sorting integers?
 - > ... controlling steel production?
 - > ... sorting strawberries?

> An unknown distribution D generates instances ($\mathbf{x}_1, \mathbf{x}_2, \ldots$) independently

- > An unknown distribution D generates instances ($\mathbf{x}_1, \mathbf{x}_2, \ldots$) independently
- > An unknown function $f : \mathbb{X} \to \mathbb{Y}$ generates responses (y_1, y_2, \ldots) for them such that $y_i = f(\mathbf{x}_i), i = 1, 2, \ldots$

- > An unknown distribution D generates instances ($\mathbf{x}_1, \mathbf{x}_2, \ldots$) independently
- > An unknown function $f : \mathbb{X} \to \mathbb{Y}$ generates responses (y_1, y_2, \ldots) for them such that $y_i = f(\mathbf{x}_i), i = 1, 2, \ldots$
- > The machine learning problem: choose a plausible hypothesis $h:\mathbb{X}\to\mathbb{Y}$ from the hypothesis space \mathbb{H}

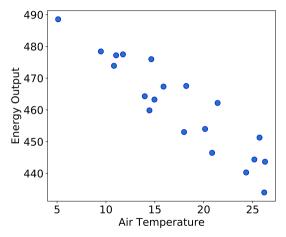
- > An unknown distribution D generates instances ($\mathbf{x}_1, \mathbf{x}_2, \ldots$) independently
- > An unknown function $f : \mathbb{X} \to \mathbb{Y}$ generates responses (y_1, y_2, \ldots) for them such that $y_i = f(\mathbf{x}_i), i = 1, 2, \ldots$
- > The machine learning problem: choose a plausible hypothesis $h:\mathbb{X}\to\mathbb{Y}$ from the hypothesis space \mathbb{H}
- > The error of a hypothesis *h* is the deviation from the true *f* measured by the loss function (an example for regression):

$$Q(h, X^{\ell}) = \frac{1}{\ell} \sum_{i=1}^{\ell} (f(\mathbf{x}_i) - h(\mathbf{x}_i))^2$$

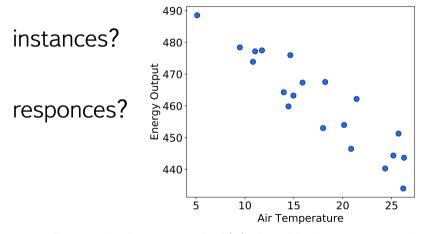
- > An unknown distribution D generates instances ($\mathbf{x}_1, \mathbf{x}_2, \ldots$) independently
- > An unknown function $f : \mathbb{X} \to \mathbb{Y}$ generates responses (y_1, y_2, \ldots) for them such that $y_i = f(\mathbf{x}_i), i = 1, 2, \ldots$
- > The machine learning problem: choose a plausible hypothesis $h:\mathbb{X}\to\mathbb{Y}$ from the hypothesis space \mathbb{H}
- > The error of a hypothesis h is the deviation from the true f measured by the loss function (an example for regression):

$$Q(h, X^{\ell}) = \frac{1}{\ell} \sum_{i=1}^{\ell} (f(\mathbf{x}_i) - h(\mathbf{x}_i))^2$$

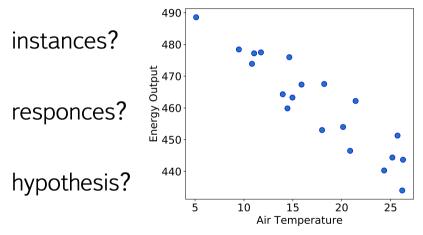
> Learning: the search for the optimal hypothesis $h \in \mathbb{H}$ w.r.t. the fixed loss function



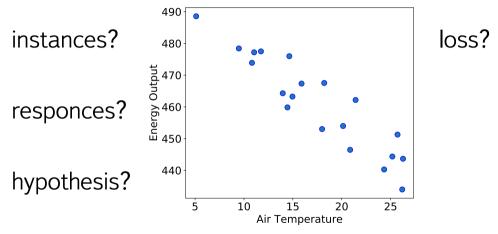
 \rightarrow The goal: obtain some fit f(x) plausible for every x_i and y_i



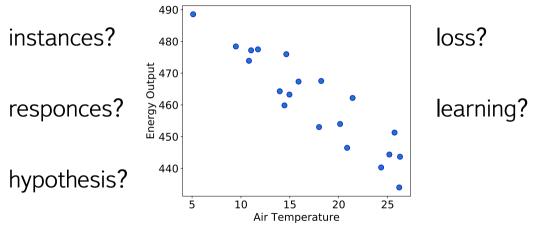
> The goal: obtain some fit f(x) plausible for every x_i and y_i



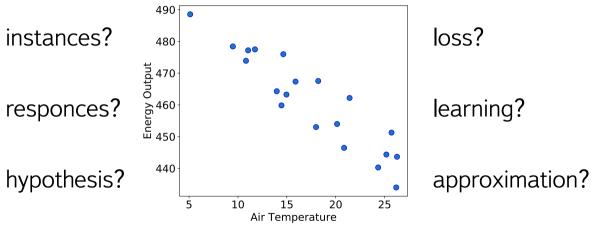
> The goal: obtain some fit f(x) plausible for every x_i and y_i



> The goal: obtain some fit f(x) plausible for every x_i and y_i



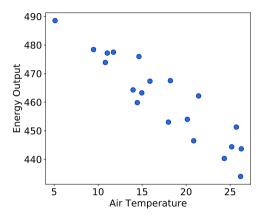
> The goal: obtain some fit f(x) plausible for every x_i and y_i



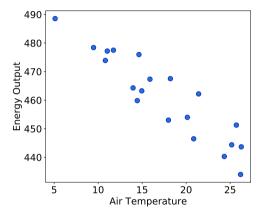
> The goal: obtain some fit f(x) plausible for every x_i and y_i

Linear models for regression

> A single feature (regressor) x:
 Air Temperature

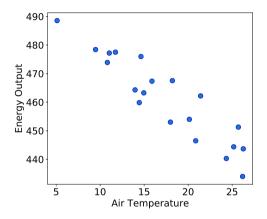


- A single feature (regressor) x:
 Air Temperature
- > A single dependent variable y: Energy Output



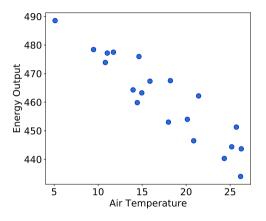
- A single feature (regressor) x:
 Air Temperature
- > A single dependent variable y: Energy Output

> Training set
$$X^{\ell} = \left\{ (x_i, y_i) \right\}_{i=1}^{20}$$



- > A single feature (regressor) x: Air Temperature
- A single dependent variable y:
 Energy Output
- > Training set $X^{\ell} = \left\{ (x_i, y_i) \right\}_{i=1}^{20}$
- > The regression model:

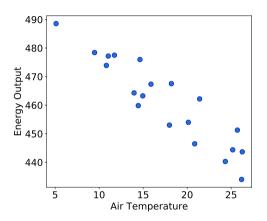
$$y_i = h(x_i; \mathbf{w}) + \varepsilon_i$$



- A single feature (regressor) x:
 Air Temperature
- > A single dependent variable y: Energy Output
- > Training set $X^{\ell} = \left\{ (x_i, y_i) \right\}_{i=1}^{20}$
- > The regression model:

$$y_i = h(x_i; \mathbf{w}) + \varepsilon_i$$

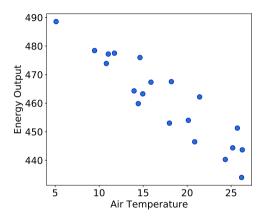
> Linear model: $y_i = w_1 x_i + w_0 + \varepsilon_i$



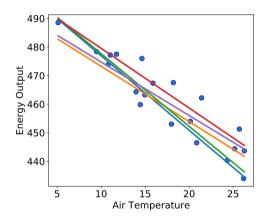
- A single feature (regressor) x:
 Air Temperature
- A single dependent variable y:
 Energy Output
- > Training set $X^{\ell} = \left\{ (x_i, y_i) \right\}_{i=1}^{20}$
- > The regression model:

$$y_i = h(x_i; \mathbf{w}) + \varepsilon_i$$

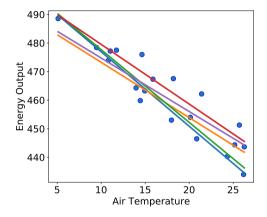
- > Linear model: $y_i = w_1 x_i + w_0 + \varepsilon_i$
- > The goal: given X^{ℓ} , find $\mathbf{w} = (w_1, w_0)$



> Which fit to choose?

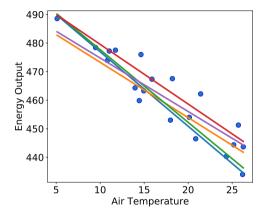


- > Which fit to choose?
- > With the linear model being fixed, depends on the data and the loss function!



- > Which fit to choose?
- > With the linear model being fixed, depends on the data and the loss function!
- > Mean square (L2) loss (MSE):

$$Q(h, X^{\ell}) = \frac{1}{\ell} \sum_{i=1}^{\ell} (y_i - h(x_i))^2$$



Some other evaluation metrics for regression

> Mean square (L2) loss (MSE):
$$MSE(h, X^{\ell}) = \frac{1}{\ell} \sum_{i=1}^{\ell} (y_i - h(x_i))^2$$

Some other evaluation metrics for regression

> Mean square (L2) loss (MSE): $MSE(h, X^{\ell}) = \frac{1}{\ell} \sum_{i=1}^{\ell} (y_i - h(x_i))^2$

> Root MSE: RMSE
$$(h, X^{\ell}) = \sqrt{\frac{1}{\ell} \sum_{i=1}^{\ell} (y_i - h(x_i))^2}$$

Some other evaluation metrics for regression

> Mean square (L2) loss (MSE): $MSE(h, X^{\ell}) = \frac{1}{\ell} \sum_{i=1}^{\ell} (y_i - h(x_i))^2$

> Root MSE: RMSE
$$(h, X^{\ell}) = \sqrt{\frac{1}{\ell} \sum_{i=1}^{\ell} (y_i - h(x_i))^2}$$

> Coefficient of determination: $R^2(h, X^{\ell}) = 1 - \frac{\sum_{i=1}^{\ell} (y_i - h(x_i))^2}{\sum_{i=1}^{\ell} (y_i - \mu_y)^2}$ with $\mu_y = \frac{1}{\ell} \sum_{i=1}^{\ell} y_i$

Some other evaluation metrics for regression

> Mean square (L2) loss (MSE): $MSE(h, X^{\ell}) = \frac{1}{\ell} \sum_{i=1}^{\ell} (y_i - h(x_i))^2$

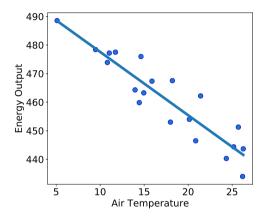
> Root MSE: RMSE
$$(h, X^{\ell}) = \sqrt{\frac{1}{\ell} \sum_{i=1}^{\ell} (y_i - h(x_i))^2}$$

- > Coefficient of determination: $R^2(h, X^{\ell}) = 1 \frac{\sum_{i=1}^{\ell} (y_i h(x_i))^2}{\sum_{i=1}^{\ell} (y_i \mu_y)^2}$ with $\mu_y = \frac{1}{\ell} \sum_{i=1}^{\ell} y_i$
- > Mean absolute error: MAE $(h, X^{\ell}) = \frac{1}{\ell} \sum_{i=1}^{\ell} |y_i h(x_i)|$

Univariate linear regression

> With the loss fixed, the linear problem reduces to optimization:

$$\frac{1}{\ell} \sum_{i=1}^{\ell} (y_i - w_1 x_i - w_0)^2 \to \min_{(w_0, w_1) \in \mathbb{R}^2},$$



Univariate linear regression

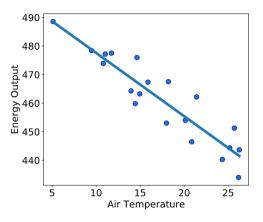
> With the loss fixed, the linear problem reduces to optimization:

$$\frac{1}{\ell} \sum_{i=1}^{\ell} (y_i - w_1 x_i - w_0)^2 \to \min_{(w_0, w_1) \in \mathbb{R}^2},$$

to which an analytical solution is available

$$\widehat{w}_1 = \frac{\sum_{i=1}^{\ell} (x_i - \mu_x)(y_i - \mu_y)}{\sum_{i=1}^{\ell} (x_i - \mu_x)^2},$$
$$\widehat{w}_0 = \mu_y - \widehat{w}_1 \mu_x$$

with
$$\mu_x = \frac{1}{\ell} \sum_{i=1}^{\ell} x_i, \quad \mu_y = \frac{1}{\ell} \sum_{i=1}^{\ell} y_i$$



Andrey Ustyuzhanin

Multivariate linear regression

> Multiple features (regressors) $\mathbf{x}_i = (x_{1i}, \dots x_{di})$ available for each y_i

. . .

> The model:

$$y_1 = w_1 x_{11} + \dots w_d x_{d1} + \varepsilon_1,$$

 $y_2 = w_1 x_{12} + \dots w_d x_{d2} + \varepsilon_2,$

$$y_{\ell} = w_1 x_{1\ell} + \dots w_d x_{d\ell} + \varepsilon_{\ell},$$

is often written in matrix-vector form as

$$egin{bmatrix} y_1\ dots\ y_\ell \end{bmatrix} = egin{bmatrix} x_{11} & x_{12} & \ldots & x_{d1}\ dots & dots & \ddots & dots\ x_{1\ell} & x_{2\ell} & \ldots & x_{d\ell} \end{bmatrix} egin{bmatrix} w_1\ dots\ w_d \end{bmatrix} + egin{bmatrix} arepsilon_1\ dots\ arepsilon_\ell \end{bmatrix} & \longleftrightarrow & oldsymbol{y} = oldsymbol{X} \mathbf{w} + oldsymbol{arepsilon} \end{cases}$$

Multivariate linear regression: the solution

> The problem: minimize MSE

$$Q(h, X^{l}) = \sum_{i=1}^{\ell} \left(y_{i} - \sum_{k=1}^{d} w_{k} x_{ki} \right)^{2} \equiv \| \boldsymbol{y} - \boldsymbol{X} \mathbf{w} \|^{2} \to \min_{\mathbf{w} \in \mathbb{R}^{d}}$$

Multivariate linear regression: the solution

> The problem: minimize MSE

$$Q(h, X^{l}) = \sum_{i=1}^{\ell} \left(y_{i} - \sum_{k=1}^{d} w_{k} x_{ki} \right)^{2} \equiv \| \boldsymbol{y} - \boldsymbol{X} \mathbf{w} \|^{2} \to \min_{\mathbf{w} \in \mathbb{R}^{d}}$$

> Solve analytically via computing the gradient

$$\nabla_{\mathbf{w}} \| \boldsymbol{y} - \boldsymbol{X} \mathbf{w} \|^2 = 2(\boldsymbol{y} - \boldsymbol{X} \mathbf{w}) \boldsymbol{X} = 0$$

Multivariate linear regression: the solution

> The problem: minimize MSE

$$Q(h, X^{l}) = \sum_{i=1}^{\ell} \left(y_{i} - \sum_{k=1}^{d} w_{k} x_{ki} \right)^{2} \equiv \| \boldsymbol{y} - \boldsymbol{X} \mathbf{w} \|^{2} \to \min_{\mathbf{w} \in \mathbb{R}^{d}}$$

> Solve analytically via computing the gradient

$$\nabla_{\mathbf{w}} \| \boldsymbol{y} - \boldsymbol{X} \mathbf{w} \|^2 = 2(\boldsymbol{y} - \boldsymbol{X} \mathbf{w}) \boldsymbol{X} = 0$$

> The solution

$$\mathbf{w}^* = (oldsymbol{X}^\intercal oldsymbol{X})^{-1} oldsymbol{X}^\intercal oldsymbol{y}$$

Numerical and stochastic optimization at a glance

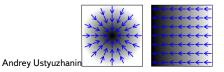
A quick intro into the Numerical Optimization

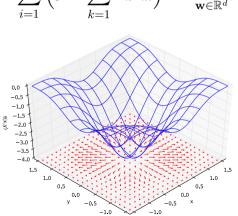
$$\text{Consider the optimization problem in } \mathbb{R}^d \\ f(\mathbf{x}) \to \min_{\mathbf{x} \in \mathbb{R}^d} \quad \text{(such as } f(\mathbf{w}) \equiv \sum_{i=1}^\ell \left(y_i - \sum_{k=1}^d w_k x_{ki} \right)^2 \to \min_{\mathbf{w} \in \mathbb{R}^d} \text{)}$$

A quick intro into the Numerical Optimization

- ightarrow Consider the optimization problem in \mathbb{R}^d
 - $f(\mathbf{x}) \to \min_{\mathbf{x} \in \mathbb{R}^d} \quad \text{(such as } f(\mathbf{w}) \equiv \sum_{i=1}^\ell \left(y_i \sum_{k=1}^d w_k x_{ki} \right)^2 \to \min_{\mathbf{w} \in \mathbb{R}^d} \text{)}$
- In general, solved using the numerical methods such as the gradient descent
- > Gradients: directions in \mathbb{R}^d pointing towards steepest function increase

$$\nabla_{\mathbf{x}} f(\mathbf{x}) \equiv \left(\frac{\partial f(\mathbf{x})}{\partial x_1}, \dots, \frac{\partial f(\mathbf{x})}{\partial x_d}\right)$$





The gradient descent algorithm

 $\,\,$ The gradient descent procedure iterates from ${\bf x}^{(0)}$ as

$$\mathbf{x}^{(k)} \leftarrow \mathbf{x}^{(k-1)} - \alpha_k \nabla_{\mathbf{x}} f(\mathbf{x}^{(k-1)})$$

with α_k controlling the *k*th step size

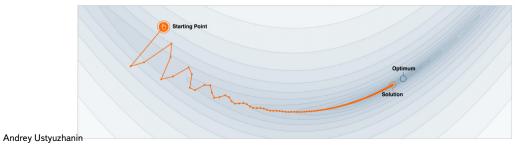
The gradient descent algorithm

 $\,\,$ The gradient descent procedure iterates from ${\bf x}^{(0)}$ as

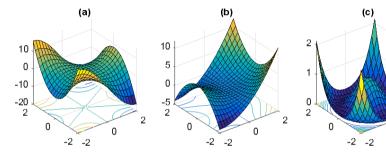
$$\mathbf{x}^{(k)} \leftarrow \mathbf{x}^{(k-1)} - \alpha_k \nabla_{\mathbf{x}} f(\mathbf{x}^{(k-1)})$$

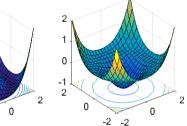
with α_k controlling the kth step size

> For smooth convex functions with a single minimum \mathbf{x}^* , k steps of gradient descent achieve accuracy $f(\mathbf{x}^{(k)}) - f(\mathbf{x}^*) = \mathcal{O}(1/k)$



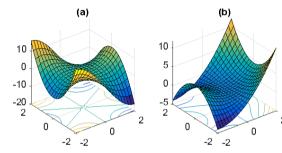
The gradient descent with non-convex targets

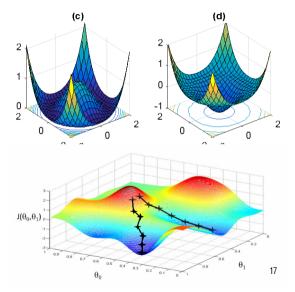




(d)

The gradient descent with non-convex targets





 Trajectories of gradient descent over non-convex functions may (and will) not always end up in a single optimum

Andrey Ustyuzhanin

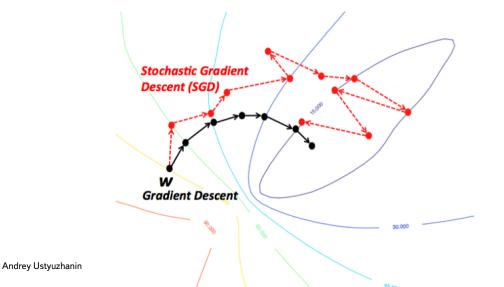
> Machine learning: many additive targets $f(\mathbf{w}) = \sum_{i=1}^{\ell} f_i(\mathbf{w})$, computationally inefficient for large ℓ

- > Machine learning: many additive targets $f(\mathbf{w}) = \sum_{i=1}^{\ell} f_i(\mathbf{w})$, computationally inefficient for large ℓ
- > Use subsamples for gradient estimation: the Stochastic Gradient Descent (SGD)
 - 1. Pick $i_k \in \{1, \ldots, \ell\}$ at random;
 - 2. Compute $\mathbf{w}^{(k)} \leftarrow \mathbf{w}^{(k-1)} \alpha_k \nabla_{\mathbf{w}} f_{i_k}(\mathbf{w}^{(k-1)})$

- > Machine learning: many additive targets $f(\mathbf{w}) = \sum_{i=1}^{\ell} f_i(\mathbf{w})$, computationally inefficient for large ℓ
- > Use subsamples for gradient estimation: the Stochastic Gradient Descent (SGD)
 - 1. Pick $i_k \in \{1, \ldots, \ell\}$ at random;
 - 2. Compute $\mathbf{w}^{(k)} \leftarrow \mathbf{w}^{(k-1)} \alpha_k \nabla_{\mathbf{w}} f_{i_k}(\mathbf{w}^{(k-1)})$
- > For smooth convex functions with a single minimum \mathbf{x}^* , k steps of SGD achieve accuracy $f(\mathbf{w}^{(k)}) f(\mathbf{w}^*) = \mathcal{O}(1/\sqrt{k})$

- > Machine learning: many additive targets $f(\mathbf{w}) = \sum_{i=1}^{\ell} f_i(\mathbf{w})$, computationally inefficient for large ℓ
- > Use subsamples for gradient estimation: the Stochastic Gradient Descent (SGD)
 - 1. Pick $i_k \in \{1, \ldots, \ell\}$ at random;
 - 2. Compute $\mathbf{w}^{(k)} \leftarrow \mathbf{w}^{(k-1)} \alpha_k \nabla_{\mathbf{w}} f_{i_k}(\mathbf{w}^{(k-1)})$
- > For smooth convex functions with a single minimum \mathbf{x}^* , k steps of SGD achieve accuracy $f(\mathbf{w}^{(k)}) f(\mathbf{w}^*) = \mathcal{O}(1/\sqrt{k})$
- > Batching, variance reduction, momentum hacks available to improve the convergence rate to $\mathcal{O}(1/k)$

Gradient descent VS stochastic gradient descent



19

An example: SGD for multivariate linear regression

- > Initialize with some $\mathbf{w}^{(0)}$
- > Gradient in i_k th object is

$$\nabla_{\mathbf{x}} f_{i_k}(\mathbf{w}) = 2(y_{i_k} - \mathbf{x}_{i_k}^{\mathsf{T}} \mathbf{w}) \mathbf{x}_{i_k} \qquad (\in \mathbb{R}^d)$$

> Compute updates using SGD: $\mathbf{w}^{(k)} \leftarrow \mathbf{w}^{(k-1)} - \alpha_k \nabla_{\mathbf{w}} f_{i_k}(\mathbf{w}^{(k-1)})$

> An unknown distribution D generates instances ($\mathbf{x}_1, \mathbf{x}_2, \ldots$)

- > An unknown distribution D generates instances ($\mathbf{x}_1, \mathbf{x}_2, \ldots$)
- > An unknown function $f : \mathbb{X} \to \mathbb{Y}$ generates labels (y_1, y_2, \ldots) for them such that $y_i = f(\mathbf{x}_i)$, and $y_i \in \{-1, +1\}$

- > An unknown distribution D generates instances ($\mathbf{x}_1, \mathbf{x}_2, \ldots$)
- > An unknown function $f:\mathbb{X} o \mathbb{Y}$ generates labels (y_1,y_2,\ldots) for them such that
 - $y_i = f(\mathbf{x}_i)$, and $y_i \in \{-1, +1\}$
- > Any examples of such functions? Implications?

- > An unknown distribution D generates instances ($\mathbf{x}_1, \mathbf{x}_2, \ldots$)
- > An unknown function $f:\mathbb{X} \to \mathbb{Y}$ generates labels (y_1, y_2, \ldots) for them such that

 $y_i = f(\mathbf{x}_i)$, and $y_i \in \{-1, +1\}$

> Any examples of such functions? Implications?



There exist sets A^+ , A^- such that $A^+ \equiv \{i : \mathbf{x}_i \in D : y_i = +1\}$ and $A^- \equiv \{i : \mathbf{x}_i \in D : y_i = -1\}$ with indicator functions $\chi_{A^+}(\cdot), \chi_{A^-}(\cdot)$ (displayed on the left)

- > An unknown distribution D generates instances ($\mathbf{x}_1, \mathbf{x}_2, \ldots$)
- > An unknown function $f:\mathbb{X} o \mathbb{Y}$ generates labels (y_1,y_2,\ldots) for them such that

$$y_i = f(\mathbf{x}_i)$$
, and $y_i \in \{-1, +1\}$

> The classification problem: choose a plausible hypothesis (classifier) $h : \mathbb{X} \to \mathbb{Y}$ from the hypothesis space \mathbb{H}

- > An unknown distribution D generates instances ($\mathbf{x}_1, \mathbf{x}_2, \ldots$)
- > An unknown function $f: \mathbb{X} \to \mathbb{Y}$ generates labels (y_1, y_2, \ldots) for them such that

$$y_i = f(\mathbf{x}_i)$$
, and $y_i \in \{-1, +1\}$

- > The classification problem: choose a plausible hypothesis (classifier) $h : \mathbb{X} \to \mathbb{Y}$ from the hypothesis space \mathbb{H}
- > The error of the classifier h is the probability (over D) that it will fail

$$Q(h, D) = \Pr_{\mathbf{x} \sim D}[f(\mathbf{x}) \neq h(\mathbf{x})]$$

usually estimated by the accuracy metric

$$Q(h, X^{\ell}) = \frac{1}{\ell} \sum_{i=1}^{\ell} [f(\mathbf{x}_i) \neq h(\mathbf{x}_i)]$$

> Linear model:
$$h(\mathbf{x}) = \operatorname{sign}\left(\sum_{i=1}^{d} w_i x_i + w_0\right) = \operatorname{sign}\left(\mathbf{w}^{\mathsf{T}}\mathbf{x} + w_0\right)$$



> Linear model:
$$h(\mathbf{x}) = \operatorname{sign}\left(\sum_{i=1}^{d} w_i x_i + w_0\right) = \operatorname{sign}\left(\mathbf{w}^{\mathsf{T}}\mathbf{x} + w_0\right)$$

> The learning problem is discrete over $\mathbf{w} \in \mathbb{R}^d$:

$$Q(h, X^{\ell}) = \frac{1}{\ell} \sum_{i=1}^{\ell} [\operatorname{sign}(\mathbf{w}^{\mathsf{T}} \mathbf{x}_i) \neq h(\mathbf{x}_i)] \to \min_{\mathbf{w} \in \mathbb{R}^d}$$

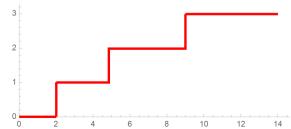


> Linear model:
$$h(\mathbf{x}) = \operatorname{sign}\left(\sum_{i=1}^{d} w_i x_i + w_0\right) = \operatorname{sign}\left(\mathbf{w}^{\mathsf{T}}\mathbf{x} + w_0\right)$$

> The learning problem is discrete over $\mathbf{w} \in \mathbb{R}^d$:

$$Q(h, X^{\ell}) = \frac{1}{\ell} \sum_{i=1}^{\ell} [\operatorname{sign}(\mathbf{w}^{\mathsf{T}} \mathbf{x}_i) \neq h(\mathbf{x}_i)] \to \min_{\mathbf{w} \in \mathbb{R}^d}$$

(cannot optimize using gradient descent)



Andrey Ustyuzhanin

> Linear model:
$$h(\mathbf{x}) = \operatorname{sign}\left(\sum_{i=1}^{d} w_i x_i + w_0\right) = \operatorname{sign}\left(\mathbf{w}^{\mathsf{T}}\mathbf{x} + w_0\right)$$

> The learning problem is discrete over $\mathbf{w} \in \mathbb{R}^d$:

$$Q(h, X^{\ell}) = \frac{1}{\ell} \sum_{i=1}^{\ell} [\operatorname{sign}(\mathbf{w}^{\mathsf{T}} \mathbf{x}_i) \neq h(\mathbf{x}_i)] \to \min_{\mathbf{w} \in \mathbb{R}^d}$$

> The solution: optimize a differentiable upper bound for $Q(h, X^{\ell})$!

> Linear model:
$$h(\mathbf{x}) = \operatorname{sign}\left(\sum_{i=1}^{d} w_i x_i + w_0\right) = \operatorname{sign}\left(\mathbf{w}^{\mathsf{T}}\mathbf{x} + w_0\right)$$

> The learning problem is discrete over $\mathbf{w} \in \mathbb{R}^d$:

$$Q(h, X^{\ell}) = \frac{1}{\ell} \sum_{i=1}^{\ell} [\operatorname{sign}(\mathbf{w}^{\mathsf{T}} \mathbf{x}_i) \neq h(\mathbf{x}_i)] \to \min_{\mathbf{w} \in \mathbb{R}^d}$$

- > The solution: optimize a differentiable upper bound for $Q(h, X^{\ell})$!
- → $Q(h, X^{\ell})$ can be written using $Q(h, X^{\ell}) = \frac{1}{\ell} \sum_{i=1}^{\ell} L(M_i)$ where $L(M_i) = [M_i < 0] \equiv [y_i \mathbf{w}^{\mathsf{T}} \mathbf{x}_i < 0]$
- > Upper-bounding L(M) yields upper bounds for $Q(h,X^\ell)$

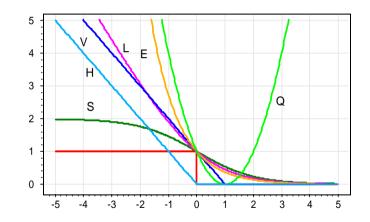
Andrey Ustyuzhanin

Linear models for classification: upper bounds

Multiple approximations to accuracy

> $L_{\mathsf{L}}(M) = \log(1 + e^{-M})$ > $L_{\mathsf{H}}(M) = \max(0, 1 - M)$ > $L_{\mathsf{P}}(M) = \max(0, -M)$ > $L_{\mathsf{E}}(M) = e^{-M}$ > $L_{\mathsf{S}}(M) = 2/(1 + e^{M})$

and their respective optimization procedures give rise to various learning algorithms



The logistic regression model

The logistic regression model

- > Training set $X^{\ell} = \left\{ (\mathbf{x}_i, y_i) \right\}_{i=1}^{\ell}$ where $y_i \in \{-1, +1\}$
- > We seek an algorithm h such that $h(\mathbf{x}) = P(y = +1|\mathbf{x})$ (model probability!)

The logistic regression model

- > Training set $X^{\ell} = \left\{ (\mathbf{x}_i, y_i) \right\}_{i=1}^{\ell}$ where $y_i \in \{-1, +1\}$
- > We seek an algorithm h such that $h(\mathbf{x}) = P(y = +1|\mathbf{x})$ (model probability!)
- > A probability that an instance (\mathbf{x}_i, y_i) is encountered in X^{ℓ}

$$h(\mathbf{x}_i)^{[y_i=+1]} + (1 - h(\mathbf{x}_i))^{[y_i=-1]}$$

- > Training set $X^{\ell} = \left\{ (\mathbf{x}_i, y_i) \right\}_{i=1}^{\ell}$ where $y_i \in \{-1, +1\}$
- > We seek an algorithm h such that $h(\mathbf{x}) = P(y = +1|\mathbf{x})$ (model probability!)
- > A probability that an instance (\mathbf{x}_i, y_i) is encountered in X^{ℓ}

$$h(\mathbf{x}_i)^{[y_i=+1]} + (1 - h(\mathbf{x}_i))^{[y_i=-1]}$$

> Entire X^{ℓ} likelihood:

$$L(X^{\ell}) = \prod_{i=1}^{\ell} h(\mathbf{x}_i)^{[y_i=+1]} + (1 - h(\mathbf{x}_i))^{[y_i=-1]}$$

- > Training set $X^{\ell} = \left\{ (\mathbf{x}_i, y_i) \right\}_{i=1}^{\ell}$ where $y_i \in \{-1, +1\}$
- > We seek an algorithm h such that $h(\mathbf{x}) = P(y = +1|\mathbf{x})$ (model probability!)
- > A probability that an instance (\mathbf{x}_i, y_i) is encountered in X^{ℓ}

$$h(\mathbf{x}_i)^{[y_i=+1]} + (1 - h(\mathbf{x}_i))^{[y_i=-1]}$$

> Entire X^{ℓ} likelihood:

$$L(X^{\ell}) = \prod_{i=1}^{\ell} h(\mathbf{x}_i)^{[y_i=+1]} + (1 - h(\mathbf{x}_i))^{[y_i=-1]}$$

is often written via log-likelihood (of which the negative is log-loss)

$$\log L(X^{\ell}) = \sum_{i=1}^{\ell} [y_i = +1] \log h(\mathbf{x}_i) + [y_i = -1] \log(1 - h(\mathbf{x}_i))$$

> The choice of h: sigmoid function

 $h(\mathbf{x}) = \sigma(\mathbf{w}^\intercal \mathbf{x})$

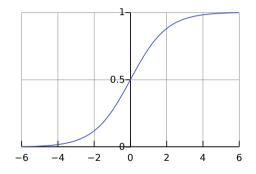
where $\sigma(x) \in [0,1]$

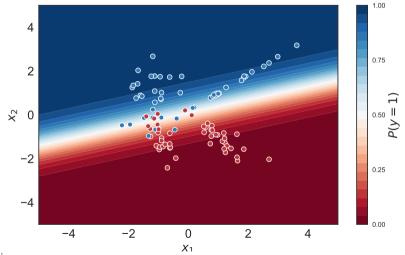
> Typical choice: the logistic function

$$\sigma(\mathbf{w}^\intercal \mathbf{x}) = \frac{1}{1 + \exp(-\mathbf{w}^\intercal \mathbf{x})}$$

> Plugging the logistic function into the loss yields an approximation of accuracy $_\ell$

$$\sum_{i=1} (1 + \exp(\mathbf{w}^{\mathsf{T}} \mathbf{x})) \to \min_{\mathbf{w} \in \mathbb{R}^d}$$





Figures of merits

Classification quality evaluation: accuracy

> Given a labeled sample $X^{\ell} = \left\{ (\mathbf{x}_i, y_i) \right\}_{i=1}^{\ell}$, $y_i \in \{-1, +1\}$, and some candidate h, how well does h perform on X^{ℓ} ?

Classification quality evaluation: accuracy

- > Given a labeled sample $X^{\ell} = \left\{ (\mathbf{x}_i, y_i) \right\}_{i=1}^{\ell}$, $y_i \in \{-1, +1\}$, and some candidate h, how well does h perform on X^{ℓ} ?
- > Let the thresholded decision rule be a(x) = [h(x) > t] (*t*: hyperparameter)

Classification quality evaluation: accuracy

- > Given a labeled sample $X^{\ell} = \{(\mathbf{x}_i, y_i)\}_{i=1}^{\ell}, y_i \in \{-1, +1\}$, and some candidate h, how well does h perform on X^{ℓ} ?
- > Let the thresholded decision rule be a(x) = [h(x) > t] (*t*: hyperparameter)
- > Obvious choice: accuracy

$$\mathsf{accuracy}(a, X^{\ell}) = \frac{1}{\ell} \sum_{i=1}^{\ell} [a(\mathbf{x}_i) = y_i]$$

- > Example: Higgs challenge selection of the interesting signal $H \rightarrow \tau \tau$ decay against the already known backround
- > 164,333 background, 85,667 signal events (66% background)

Higgs H

Classification quality evaluation: confusion matrix

	Label $y = 1$	Label $y = -1$
Decision $a(x) = 1$	True Positive (TP)	False Positive (FP)
Decision $a(x) = -1$	False negative (FN)	True Negative (TN)

Classification quality evaluation: confusion matrix

	Label $y = 1$	Label $y = -1$
Decision $a(x) = 1$	True Positive (TP)	False Positive (FP)
Decision $a(x) = -1$	False negative (FN)	True Negative (TN)

> Rates are often more informative:

False Positive Rate aka FPR =
$$\frac{FP}{FP + TN}$$
,
True Positive Rate aka TPR = $\frac{TP}{TP + FN}$,

Classification quality evaluation: confusion matrix

	Label $y = 1$	Label $y = -1$
Decision $a(x) = 1$	True Positive (TP)	False Positive (FP)
Decision $a(x) = -1$	False negative (FN)	True Negative (TN)

> Rates are often more informative:

False Positive Rate aka FPR
$$= rac{FP}{FP + TN}$$
,
True Positive Rate aka TPR $= rac{TP}{TP + FN}$,

> While accuracy can be expressed, too

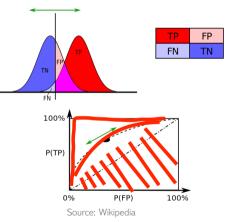
$$accuracy = \frac{TP + TN}{TP + FP + FN + TN}$$

> Often $h(\mathbf{x})$ is more valuable than its thresholded version a(x) = [h(x) > t]

- > Often $h(\mathbf{x})$ is more valuable than its thresholded version a(x) = [h(x) > t]
- Consider two-dimensional space with coordinates (TPR(t), FPR(t)), corresponding to various choices of the threshold t

- > Often $h(\mathbf{x})$ is more valuable than its thresholded version a(x) = [h(x) > t]
- Consider two-dimensional space with coordinates (TPR(t), FPR(t)), corresponding to various choices of the threshold t
- > The plot TPR(t) vs. FPR(t) is called the receiver operating characteristic (ROC) curve

- > Often $h(\mathbf{x})$ is more valuable than its thresholded version a(x) = [h(x) > t]
- Consider two-dimensional space with coordinates (TPR(t), FPR(t)), corresponding to various choices of the threshold t
- > The plot TPR(t) vs. FPR(t) is called the receiver operating characteristic (ROC) curve
- Area under curve (ROC-AUC) reflects classification quality



> Recall the Higgs: 164,333 background vs. 85,667 signal events (66% background)

- > Recall the Higgs: 164,333 background vs. 85,667 signal events (66% background)
- > TPR(*t*) vs. FPR(*t*) / ROC is bad for imbalanced data: for $\ell = 1000$, $n_{-} = 950$ (high background noise), $n_{+} = 50$ (low signal), a trivial rule $h(\mathbf{x}) = -1$ ("treat everything as background") would yield:

- > Recall the Higgs: 164,333 background vs. 85,667 signal events (66% background)
- > TPR(*t*) vs. FPR(*t*) / ROC is bad for imbalanced data: for $\ell = 1000$, $n_{-} = 950$ (high background noise), $n_{+} = 50$ (low signal), a trivial rule $h(\mathbf{x}) = -1$ ("treat everything as background") would yield:

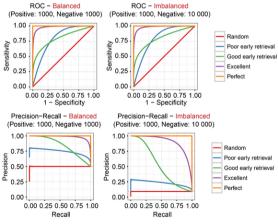
> accuracy $(a, X^{\ell}) = 0.95$ (bad)

- > Recall the Higgs: 164,333 background vs. 85,667 signal events (66% background)
- > TPR(*t*) vs. FPR(*t*) / ROC is bad for imbalanced data: for $\ell = 1000$, $n_{-} = 950$ (high background noise), $n_{+} = 50$ (low signal), a trivial rule $h(\mathbf{x}) = -1$ ("treat everything as background") would yield:
 - > accuracy $(a, X^{\ell}) = 0.95$ (bad)
 - > $\mathsf{TPR}(a, X^{\ell}) = 0.$ (OK)

- > Recall the Higgs: 164,333 background vs. 85,667 signal events (66% background)
- > TPR(*t*) vs. FPR(*t*) / ROC is bad for imbalanced data: for $\ell = 1000$, $n_{-} = 950$ (high background noise), $n_{+} = 50$ (low signal), a trivial rule $h(\mathbf{x}) = -1$ ("treat everything as background") would yield:
 - > accuracy $(a, X^{\ell}) = 0.95$ (bad)
 - > $\mathsf{TPR}(a, X^{\ell}) = 0.$ (OK)
 - > $\mathsf{FPR}(a, X^{\ell}) = 0.$ (bad)

- > Recall the Higgs: 164,333 background vs. 85,667 signal events (66% background)
- > TPR(*t*) vs. FPR(*t*) / ROC is bad for imbalanced data: for $\ell = 1000$, $n_{-} = 950$ (high background noise), $n_{+} = 50$ (low signal), a trivial rule $h(\mathbf{x}) = -1$ ("treat everything as background") would yield:
 - > accuracy $(a, X^{\ell}) = 0.95$ (bad)
 - > $\mathsf{TPR}(a, X^{\ell}) = 0.$ (OK)
 - > $\mathsf{FPR}(a, X^{\ell}) = 0.$ (bad)
- > Criteria better suited for imbalanced problems:

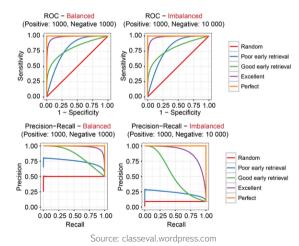
$$\label{eq:precision} \mathsf{precision} = \frac{\mathsf{TP}}{\mathsf{TP} + \mathsf{FP}}, \qquad \mathsf{recall} = \frac{\mathsf{TP}}{\mathsf{TP} + \mathsf{FN}}$$



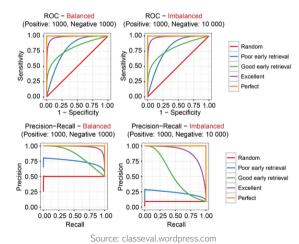
Source: classeval.wordpress.com

Andrey Ustyuzhanin

 The plot recall vs. precision is called the precision-recall (PR) curve



- The plot recall vs. precision is called the precision-recall (PR) curve
- > Recall(*t*) vs. Precision(*t*) is good for imbalanced data: for *l* = 1000,
 n₋ = 950 (high background noise),
 n₊ = 50 (low signal),
 a trivial rule *h*(**x**) = −1 would yield:



 The plot recall vs. precision is called the precision-recall (PR) curve

- > Recall(t) vs. Precision(t) is good for imbalanced data: for ℓ = 1000,
 - $n_{-}=950$ (high background noise),
 - $n_{\rm +}=50$ (low signal),

a trivial rule $h(\mathbf{x}) = -1$ would yield:

- > Recall $(a, X^{\ell}) = 0.$ (OK)
- > Precision $(a, X^{\ell}) = 0.$ (OK)

Overfitting: how to fool the linear regression

> Training set memorization: for seen $(\mathbf{x},y)\in X^\ell$, $h(\mathbf{x})=y$

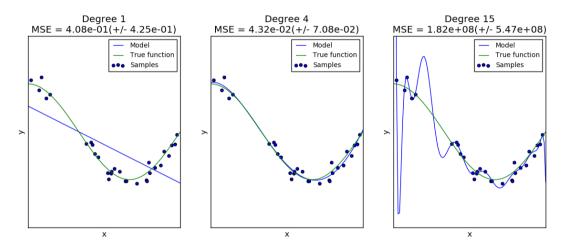
- > Training set memorization: for seen $(\mathbf{x}, y) \in X^{\ell}$, $h(\mathbf{x}) = y$
- > Generalization: equally good performance on both new and seen instances

- > Training set memorization: for seen $(\mathbf{x}, y) \in X^{\ell}$, $h(\mathbf{x}) = y$
- > Generalization: equally good performance on both new and seen instances
- > How to assess model's generalization ability?

- > Training set memorization: for seen $(\mathbf{x}, y) \in X^{\ell}$, $h(\mathbf{x}) = y$
- > Generalization: equally good performance on both new and seen instances
- > How to assess model's generalization ability?
- > Consider an example:
 - > $y = \cos(1.5\pi x) + \mathcal{N}(0, 0.01)$, $x \sim \text{Uniform}[0, 1]$
 - > Features: $\{x\}$, $\{x, x^2, x^3, x^4\}$, $\{x, \dots, x^{15}\}$
 - > The model is linear w.r.t. features: $f(\mathbf{x}) = \mathbf{w}^\mathsf{T} \phi(\mathbf{x})$

- > Training set memorization: for seen $(\mathbf{x}, y) \in X^{\ell}$, $h(\mathbf{x}) = y$
- > Generalization: equally good performance on both new and seen instances
- > How to assess model's generalization ability?
- > Consider an example:
 - > $y = \cos(1.5\pi x) + \mathcal{N}(0, 0.01)$, $x \sim \text{Uniform}[0, 1]$ > Features: $\{x\}$, $\{x, x^2, x^3, x^4\}$, $\{x, \dots, x^{15}\}$ > The model is linear w.r.t. features: $f(\mathbf{x}) = \mathbf{w}^{\mathsf{T}} \phi(\mathbf{x})$
- > How well do the regression models perform?

Polynomial fits of different degrees



> We have free parameters in models:

- > We have free parameters in models:
 - > polynomial degree *d*, subset of features in multivariate regression, kernel width in kernel density estimates, ...

- > We have free parameters in models:
 - > polynomial degree d, subset of features in multivariate regression, kernel width in kernel density estimates, ...
- > Model selection: how to select optimal hyperparameters for a given classification problem?

- > We have free parameters in models:
 - > polynomial degree d, subset of features in multivariate regression, kernel width in kernel density estimates, ...
- > Model selection: how to select optimal hyperparameters for a given classification problem?
- > Validation: how to estimate true model performance?

- > We have free parameters in models:
 - > polynomial degree d, subset of features in multivariate regression, kernel width in kernel density estimates, ...
- > Model selection: how to select optimal hyperparameters for a given classification problem?
- > Validation: how to estimate true model performance?
- > Can we use entire dataset to fit the model?

Model validation and selection

- > We have free parameters in models:
 - > polynomial degree *d*, subset of features in multivariate regression, kernel width in kernel density estimates, ...
- > Model selection: how to select optimal hyperparameters for a given classification problem?
- > Validation: how to estimate true model performance?
- > Can we use entire dataset to fit the model?
- > Yes, but we will likely get overly optimistic performance estimate

Model validation and selection

- > We have free parameters in models:
 - > polynomial degree *d*, subset of features in multivariate regression, kernel width in kernel density estimates, ...
- > Model selection: how to select optimal hyperparameters for a given classification problem?
- > Validation: how to estimate true model performance?
- > Can we use entire dataset to fit the model?
- > Yes, but we will likely get overly optimistic performance estimate
- > The solution: rely on held-out data to assess model performance

> Split training set into two subsets:

$$X^\ell = X^\ell_{\mathsf{TRAIN}} \cup X^\ell_{\mathsf{VAL}}$$

> Split training set into two subsets:

$$X^\ell = X^\ell_{\mathsf{TRAIN}} \cup X^\ell_{\mathsf{VAL}}$$

> Train a model h on X_{TRAIN}^{ℓ}

> Split training set into two subsets:

- > Train a model h on X^{ℓ}_{TRAIN}
- > Evaluate model h on $X^\ell_{\rm VAL}$

> Split training set into two subsets:

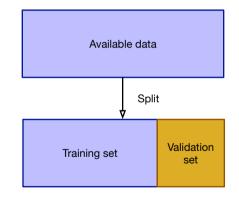
- > Assess quality using $Q(h, X^\ell_{\rm VAL})$

> Split training set into two subsets:

- > Evaluate model h on $X^{\ell}_{\rm VAL}$
- ${\boldsymbol{\succ}}$ Assess quality using $Q(h, X^\ell_{\rm VAL})$
- > Data-hungry: can we afford the "luxury" of setting aside a portion of the data for testing?

> Split training set into two subsets:

- $\,\,{\bf \succ}\,$ Evaluate model h on $X^\ell_{\rm VAL}$
- ${\boldsymbol{\succ}}$ Assess quality using $Q(h, X^\ell_{\rm VAL})$
- > Data-hungry: can we afford the "luxury" of setting aside a portion of the data for testing?
- May be imprecise: the holdout estimate of error rate will be misleading if we happen to get an "unfortunate" split



> Split training set into subsets of equal size

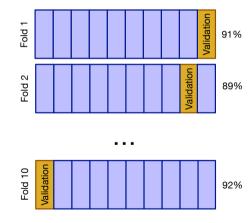
 $X^{\ell} = X_1^{\ell} \cup \ldots \cup X_K^{\ell}$

- > Split training set into subsets of equal size $X^\ell = X_1^\ell \cup \ldots \cup X_K^\ell$
- > Train K models h_1, \ldots, h_K where each model h_k is trained on all subsets but X_k^{ℓ}

- > Split training set into subsets of equal size $X^\ell = X_1^\ell \cup \ldots \cup X_K^\ell$
- > Train K models h_1, \ldots, h_K where each model h_k is trained on all subsets but X_k^{ℓ}
- > Assess quality using

$$\mathrm{CV} = rac{1}{K}\sum_{k=1}^{K}Q(h_k,X_k^\ell)$$
 (K-fold)

- > Split training set into subsets of equal size $X^\ell = X_1^\ell \cup \ldots \cup X_K^\ell$
- > Train K models h_1, \ldots, h_K where each model h_k is trained on all subsets but X_k^{ℓ}
- > Assess quality using
 - $\mathrm{CV} = rac{1}{K}\sum_{k=1}^{K}Q(h_k,X_k^\ell)$ (K-fold)
- > Leave-one-out cross-validation: $X_k^\ell = \{(\mathbf{x}_k, y_k)\} \text{ (yes, train } \ell \text{ models!)}$



Cross-validation method: drawbacks

$$CV = \frac{1}{K} \sum_{k=1}^{K} Q(h_k, X_k^{\ell})$$

Many folds:

- > Small bias: the estimator will be very accurate
- > Large variance: due to small split sizes
- > Costly: many experiments, large computational time

Cross-validation method: drawbacks

$$CV = \frac{1}{K} \sum_{k=1}^{K} Q(h_k, X_k^{\ell})$$

Many folds:

- > Small bias: the estimator will be very accurate
- > Large variance: due to small split sizes
- > Costly: many experiments, large computational time

Few folds:

- > Cheap, computationally effective: few experiments
- > Small variance: average over many samples
- > Large bias: estimated error rate conservative or smaller than the true error rate

Regularization

Ad-hoc regularization: motivation

> Consider the multivariate linear regression problem with $oldsymbol{X} \in \mathbb{R}^{d imes d}$

$$\|oldsymbol{y}-oldsymbol{X}\mathbf{w}\|^2
ightarrow \min_{\mathbf{w}\in\mathbb{R}^d}$$

Ad-hoc regularization: motivation

> Consider the multivariate linear regression problem with $oldsymbol{X} \in \mathbb{R}^{d imes d}$

$$\|oldsymbol{y}-oldsymbol{X}\mathbf{w}\|^2 o \min_{\mathbf{w}\in\mathbb{R}^d}$$

> Analytic solution involves computing the product $\boldsymbol{R} = (\boldsymbol{X}^{\intercal}\boldsymbol{X})^{-1}\boldsymbol{X}^{\intercal}$

Ad-hoc regularization: motivation

> Consider the multivariate linear regression problem with $oldsymbol{X} \in \mathbb{R}^{d imes d}$

$$\|oldsymbol{y}-oldsymbol{X}\mathbf{w}\|^2 o \min_{\mathbf{w}\in\mathbb{R}^d}$$

- > Analytic solution involves computing the product $m{R} = (m{X}^\intercal m{X})^{-1} m{X}^\intercal$
- > If $X = \text{diag}(\lambda_1, \dots, \lambda_d)$ with $\lambda_1 > \lambda_2 > \dots > \lambda_d \to 0$ (meaning we're in eigenbasis of X) then

$$\begin{split} & \boldsymbol{R} = (\boldsymbol{X}^{\mathsf{T}} \boldsymbol{X})^{-1} \boldsymbol{X}^{\mathsf{T}} = \\ & = \left(\mathsf{diag}(\lambda_1, \dots, \lambda_d) \mathsf{diag}(\lambda_1, \dots, \lambda_d) \right)^{-1} \mathsf{diag}(\lambda_1, \dots, \lambda_d) = \\ & = \mathsf{diag}\left(\frac{1}{\lambda_1}, \dots, \frac{1}{\lambda_d} \right), \quad \mathsf{leading to huge diagonal values in } \boldsymbol{R} \end{split}$$

> Regularization: replace fit with fit + penalty as in

$$Q(\mathbf{w}) \to Q_{\alpha}(\mathbf{w}) = Q(\mathbf{w}) + \alpha R(\mathbf{w})$$

> Regularization: replace fit with fit + penalty as in

$$Q(\mathbf{w}) \to Q_{\alpha}(\mathbf{w}) = Q(\mathbf{w}) + \alpha R(\mathbf{w})$$

> $R(\mathbf{w})$ is called the regularizer, $\alpha > 0$ – the regularization constant

> Regularization: replace fit with fit + penalty as in

$$Q(\mathbf{w}) \to Q_{\alpha}(\mathbf{w}) = Q(\mathbf{w}) + \alpha R(\mathbf{w})$$

- $\,\,\mathbf{>}\,\,R(\mathbf{w})$ is called the regularizer, $\alpha>0$ the regularization constant
- > Regularized multivariate linear regression problem

$$\|\boldsymbol{y} - \boldsymbol{X} \mathbf{w}\|^2 + \alpha \|\mathbf{w}\|_2^2 \to \min_{\mathbf{w} \in \mathbb{R}^d}$$

> Regularization: replace fit with fit + penalty as in

$$Q(\mathbf{w}) \to Q_{\alpha}(\mathbf{w}) = Q(\mathbf{w}) + \alpha R(\mathbf{w})$$

- $\,\,\mathbf{>}\,\,R(\mathbf{w})$ is called the regularizer, $\alpha>0$ the regularization constant
- > Regularized multivariate linear regression problem

$$\|\boldsymbol{y} - \boldsymbol{X} \mathbf{w}\|^2 + \alpha \|\mathbf{w}\|_2^2 \to \min_{\mathbf{w} \in \mathbb{R}^d}$$

> Regularized analytic solution available

$$\mathbf{w}^* = (\boldsymbol{X}^{\mathsf{T}} \boldsymbol{X} + \alpha \boldsymbol{I})^{-1} \boldsymbol{X}^{\mathsf{T}} \boldsymbol{y}$$

Why L2 regularization works

> Analytic solution: compute the regularized operator

$$\boldsymbol{R} = (\boldsymbol{X}^{\mathsf{T}}\boldsymbol{X} + \alpha \boldsymbol{I})^{-1}\boldsymbol{X}^{\mathsf{T}}$$

Why L2 regularization works

> Analytic solution: compute the regularized operator

$$\boldsymbol{R} = (\boldsymbol{X}^{\mathsf{T}}\boldsymbol{X} + \alpha \boldsymbol{I})^{-1}\boldsymbol{X}^{\mathsf{T}}$$

> If $X = \text{diag}(\lambda_1, \dots, \lambda_d)$ with $\lambda_1 > \lambda_2 > \dots > \lambda_d \to 0$ (meaning we're in eigenbasis of X) then

$$\begin{split} \boldsymbol{R} &= (\boldsymbol{X}^{\mathsf{T}}\boldsymbol{X} + \alpha \boldsymbol{I})^{-1}\boldsymbol{X}^{\mathsf{T}} = \\ &= \left(\mathsf{diag}(\lambda_1, \dots, \lambda_d) \mathsf{diag}(\lambda_1, \dots, \lambda_d) + \mathsf{diag}(\alpha, \dots, \alpha) \right)^{-1} \mathsf{diag}(\lambda_1, \dots, \lambda_d) = \\ &= \mathsf{diag}\left(\frac{\lambda_1}{\lambda_1^2 + \alpha}, \dots, \frac{\lambda_d}{\lambda_d^2 + \alpha} \right), \end{split}$$
smoothing diagonal values in \boldsymbol{R}

More regularizers!

> L2 regularized multivariate linear regression problem

$$\|\boldsymbol{y} - \boldsymbol{X} \mathbf{w}\|^2 + \alpha \|\mathbf{w}\|^2 \to \min_{\mathbf{w} \in \mathbb{R}^d}$$

> L1 regularized regression (LASSO)

$$\|\boldsymbol{y} - \boldsymbol{X} \mathbf{w}\|^2 + \alpha \|\mathbf{w}\|_1 \to \min_{\mathbf{w} \in \mathbb{R}^d}$$

> L1/L2 regularized regression (Elastic Net)

$$\|\boldsymbol{y} - \boldsymbol{X} \mathbf{w}\|^2 + \alpha_1 \|\mathbf{w}\|_1 + \alpha_2 \|\mathbf{w}\|_2^2 \to \min_{\mathbf{w} \in \mathbb{R}^d}$$

More regularizers!

> L2 regularized multivariate linear regression problem

$$\|\boldsymbol{y} - \boldsymbol{X} \mathbf{w}\|^2 + \alpha \|\mathbf{w}\|^2 \to \min_{\mathbf{w} \in \mathbb{R}^d}$$

> L1 regularized regression (LASSO)

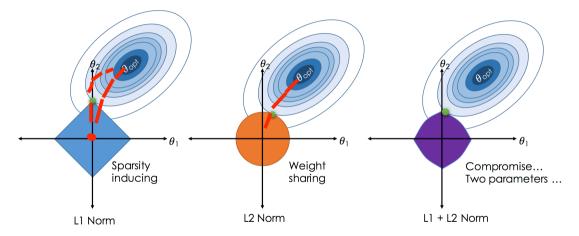
$$\|\boldsymbol{y} - \boldsymbol{X} \mathbf{w}\|^2 + \alpha \|\mathbf{w}\|_1 \to \min_{\mathbf{w} \in \mathbb{R}^d}$$

> L1/L2 regularized regression (Elastic Net)

$$\|\boldsymbol{y} - \boldsymbol{X} \mathbf{w}\|^2 + \alpha_1 \|\mathbf{w}\|_1 + \alpha_2 \|\mathbf{w}\|_2^2 \to \min_{\mathbf{w} \in \mathbb{R}^d}$$

> Convex $Q(\mathbf{w})$: unconstrained optimization $Q(\mathbf{w}) + \alpha \|\mathbf{w}\|_1$ is equivalent to constrained problem $Q(\mathbf{w})$ s.t. $\|\mathbf{w}\|_1 \leq C$

Geometric interpretation of regularizers



Picture credit: http://www.ds100.org/sp17/assets/notebooks/linear_regression/Regularization.html

Another interpretation of regularizers





C Pleated Jeans

Figure: Regularized models

Figure: Large parameter space

Conclusion

- > Linear models work both for regression and classification
- > Main optimization methods: numerical and stochastic optimization
- > Figures of merits is not a science is an art
- > Beware of overfitting! understand your data and tools
- > Cross-validation is the best technique to assess your model
- > Regularization is your best friend to fight overfitting