Rubin Observatory

The Software Behind the Science















Rubin Observatory



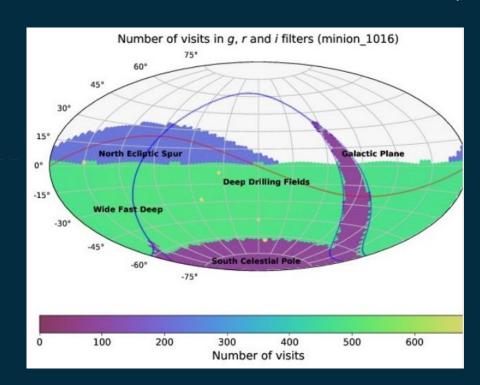


What is Rubin Obs?

Rubin Observatory

A facility that will conduct an optical/near-IR survey of half the sky over a 10 year period. This survey is called the legacy survey of space and time (LSST).

- 90% of the time spent on uniform survey, with 800-1000 observations a night with most observations repeated 20-30 min apart
- ~10 million transient events a night
- 3.2 GigaPixel Camera
- Will generate 100PB of data over the course of the survey, with catalogs for over 40 billion objects





Who are we?



The data management team began in 2008 with a handful of members and has grown to a group of ~100 developers split over 5 institutions today



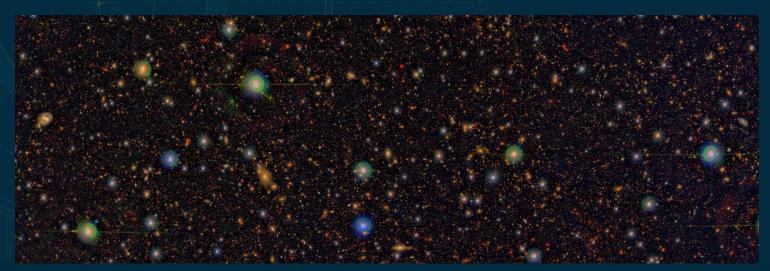




Data processing



- Nightly processing of transients, within 60s of every image taken on the telescope
- Yearly processing of all data to date

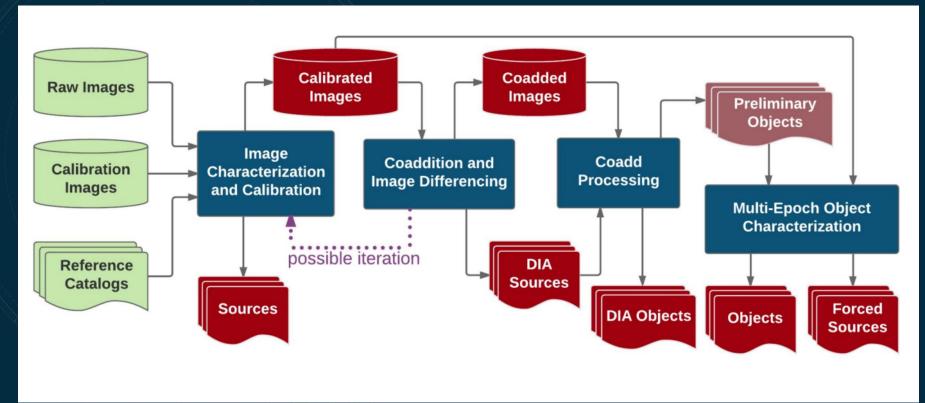






From pixels to catalogs







Science Platform



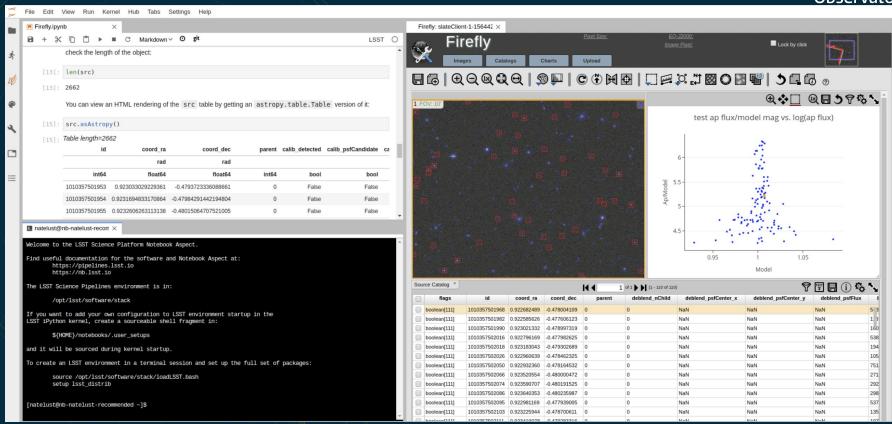
- Too much data to take to scientists, so bring scientists to data
- Allows analysis with same tools used to product the data
- Uses Jupyter lab
- Cloud based
- Per user containerized environments with persistent storage
- Choose from multiple versions of the software stack pre-setup in the environment
- Data visualization tools built in





Science Platform









Python as a language



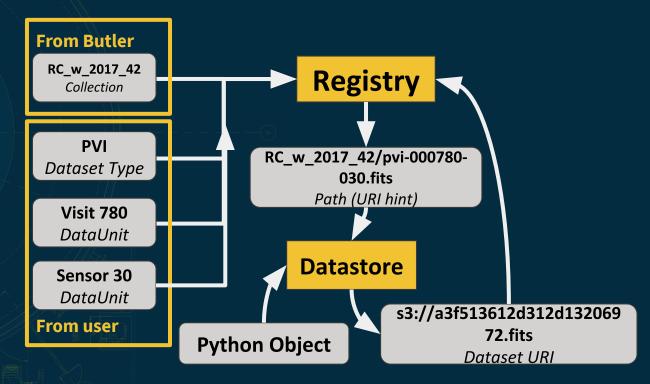
- Easy to write code such that beginners to advanced users all have what they need
- Great for getting things going quickly, but this can have software engineering costs when things scale up
- Python has started addressing some of these issues with things like abstract base classes, type annotations, python 3 being new-style class only, etc.
- Great for bringing together code written in lower level languages







A middleware system for storage indexing and retrieval (get just what you need, right when you need it)









```
class MergeDetectionsConfig(PipelineTaskConfig, pipelineConnections=MergeDetectionsConnections):
    @anchor MergeDetectionsConfig_
    @brief Configuration parameters for the MergeDetectionsTask.
    minNewPeak = Field(dtype=float, default=1,
                       doc="Minimum distance from closest peak to create a new one (in arcsec).")
    maxSamePeak = Field(dtype=float, default=0.3,
                        doc="When adding new catalogs to the merge, all peaks less than this distance "
                        " (in arcsec) to an existing peak will be flagged as detected in that catalog.")
    cullPeaks = ConfigField(dtype=CullPeaksConfig, doc="Configuration for how to cull peaks.")
    skyFilterName = Field(dtype=str, default="sky",
                          doc="Name of `filter' used to label sky objects (e.g. flag merge_peak_sky is set)\n"
                          "(N.b. should be in MergeMeasurementsConfig.pseudoFilterList)")
    skyObjects = ConfigurableField(target=SkyObjectsTask, doc="Generate sky Objects")
   priorityList = ListField(dtype=str, default=[],
                            doc="Priority-ordered list of bands for the merge.")
    coaddName = Field(dtype=str, default="deep", doc="Name of coadd")
    def setDefaults(self):
       Config.setDefaults(self)
       self.skvObjects.avoidMask = ["DETECTED"] # Nothing else is available in our custom mask
   def validate(self):
       super().validate()
       if len(self.priorityList) == 0:
            raise RuntimeError("No priority list provided")
```

Declarative (nestable) schema based configuration system that tracks what changed a config option, and when it was changed.

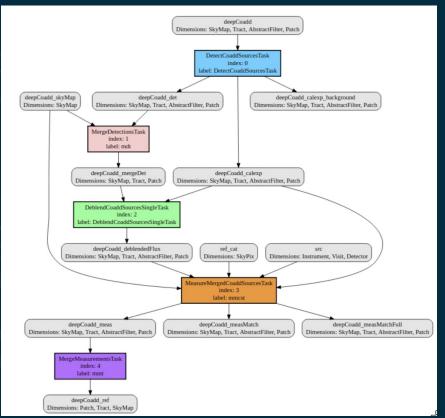
An example for this class may be:

```
config = MergeDetectionsConfig()
config.priorityList = \
   ["I-Band", "R-Band", "Z-Band"]
```



Rubin Observatory

Task based (nestable) operations that can be arranged into various "pipelines", with automatic execution ordering based on data-set dependency relations







Pluggable scientific algorithms with automatic runtime ordering

```
class SingleFrameFPPositionPlugin(SingleFramePlugin):
   """Algorithm to calculate the position of a centroid on the focal plane
   Parameters
   config : `SingleFrameFPPositionConfig`
       Plugin configuration.
   name : `str`
       Plugin name.
   schema : `lsst.afw.table.Schema`
       The schema for the measurement output catalog. New fields will be
       added to hold measurements produced by this plugin.
   metadata : `lsst.daf.base.PropertySet`
       Plugin metadata that will be attached to the output catalog
   ConfigClass = SingleFrameFPPositionConfig
   Oclassmethod
   def getExecutionOrder(cls):
       return cls.SHAPE ORDER
   def __init__(self, config, name, schema, metadata):
       SingleFramePlugin.__init__(self, config, name, schema, metadata)
       self.focalValue = lsst.afw.table.Point2DKey.addFields(schema, name, "Position on the focal plane",
       self.focalFlag = schema.addField(name + "_flag", type="Flag", doc="Set to True for any fatal failure")
       self.detectorFlag = schema.addField(name + "_missingDetector_flag", type="Flag",
                                           doc="Set to True if detector object is missing")
   def measure(self, measRecord, exposure):
       det = exposure.getDetector()
       if not det:
            measRecord.set(self.detectorFlag, True)
           fp = lsst.geom.Point2D(np.nan, np.nan)
           center = measRecord.getCentroid()
           fp = det.transform(center, lsst.afw.cameraGeom.PIXELS, lsst.afw.cameraGeom.FOCAL_PLANE)
       measRecord.set(self.focalValue, fp)
   def fail(self, measRecord, error=None):
       measRecord.set(self.focalFlag, True)
```







Extensive library of primitives



lsst.afw.math
Using lsst.afw.math

Contributing

Python API reference

Isst.afw.math Package

Functions

Classes

Class Inheritance Diagram

lsst.afw.math

lsst.afw.math provides mathematical functions such as convolution and image statistics. Key features:

- Function objects FunctionF and FunctionD
- Statistics
- · Background estimation of images.
- Interpolate
- Kernel
- Optimization of functions is handled by minimize()
- . Convolution of images is handled by convolve()
- Warping of images is handled by warpImage()
- · Manipulating spatially-distributed sets of objects (e.g. PSF candidates)

Using lsst.afw.math

- Example of lsst.afw.math.Background
- · Example of Isst.afw.math.SpatialCellSet
- · Example of lsst.afw.math.Statistics

Contributing

lsst.afw.math is developed at https://github.com/lsst/afw. You can find Jira issues for this module under the afw component.

Python API reference

lsst.afw.math Package

Functions

<pre>basicConvolve(*args, **kwargs)</pre>	Overloaded function.
binImage(*args, **kwargs)	Overloaded function.
convolve(*args, **kwargs)	Overloaded function.
<pre>convolveWithBruteForce(*args, **kwargs)</pre>	Overloaded function.
flipImage(*args, **kwargs)	Overloaded function.







Data Analysis code base



	C++	Python —	Total
# of flles	1,353	2,438	3,791
# lines of comments	80,613	158,342	238,955
# lines of code	145,830	275,045	420,875

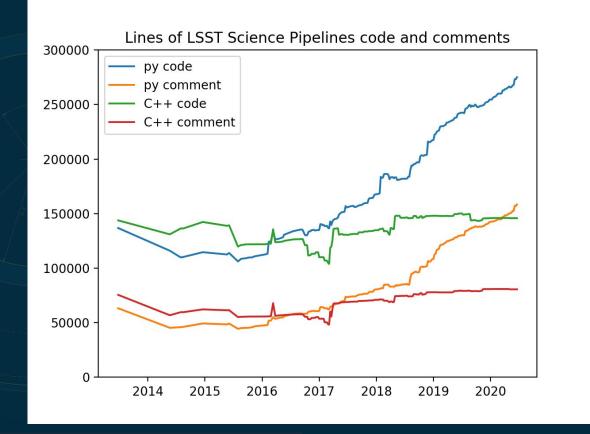
Split over ~80 packages





The codebase through time





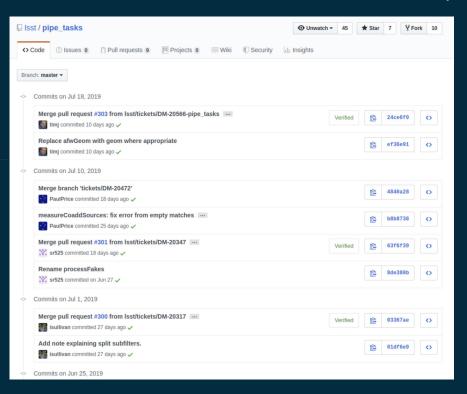




Development Process

Rubin Observatory

- All work managed through tickets
- Any developer can create tickets but, major changes subject to request for comment (RFC) discussions with whole project
- Code tracked with git, changes happen on "ticket" branches
- Code reviews done with Github
- Merges are done with no fast forward, to help associate with changes with tickets
- Commits are squashed to functioning logical units of work







Development Process



87d979c	some minor improvements	to coordinates landing docs
217c773	Merge pull request #6326	from adrn/coordinates/fix-separation-diffs
cb2458d	Merge pull request #15 f	rom eteq/coordinates/fix-separation-diffs
9ddc5b8	 Alternate implementati 	on using without_differentials
cfe918e	make frame.separation_3	d work even if frames have velocity data
acb4bfe	Merge pull request #6325	from astrofrog/fix-sphinx-templates-tarfile
ab6969d	Make sure we include the	e .rst templates from astropy-helpers in the
6deddbb	Merge pull request #633	0 from adrn/coordinates/fix-uvw
5a13166	add changelog entry fo	r 6330
5497f43	fix skycoord test that u	ses old ordering
45cb5db	update cartesian name	S
8fbb330	Merge pull request #63	329 from adrn/coordinates/fix-frame-slicing
2ad6fa0	O add test to check that	t slicing prserves diff class
e5f99d3	O fixes #6327 - carry a	long differential_cls inapply
f89f3d9	Merge pull request #6317	from adrn/coordinates/diff-class-init
e14210f	added bit about different	ial_cls to docstrings [docs only]
f3ab348	add test of setting differ	ential class in init
84e6532	allow passing a different	al class or dict of classes to basecoordinat
5155eb3	Merge pull request #6299 from	m eteq/add-numfocus-badge
beb613b	add alt texts	
5c8e88a	add Powered by NomFOCUS	badge
18a0950	Merge pull request #6305 fr	om pllim/fix-samp
0f93072	O Fix samp_hub entry-point.	Fix deprecation warning typo.
1240cda	Merge pull request #6296	from pllim/ignore-mask-comment
8ba70cb	Added inline comment at	oout removing MaskedArrayFutureWarning
f59119e	Merge pull request #630	6 from adrn/coordinates/fix-lsr-velocity
63d9e44	O fix in docstring example	e too
22097c1	fix UVW velocities	
2e8948d	Merge pull request #63	07 from dhomeier/lxml-getargspec
91fcb5c	O TST: fix non-intercep	ted warnings from lxml in Python 3.6
e176eff	Merge pull request #6295	from bsipocz/setup_add_cython_jinja
253f671	Adding Cython and Jinja	2 to setup_requires as in fact they are requi
ae7fdf1	Adding back python version lin	nitation to 3.5 for the RTD builds
28d2a0c	Merge pull request #6294 from	m saimn/travis-test-duration
c76ad73	O Show test duration for the sl	owest tests
d063d13	Merge pull request #6289 from	m adrn/coordinate/repr-fix
754 507		

All	Local "master"
Short SHA	
91bfccb	Walle 11 Marra hazara Malata/DM 420551
	w.2018.11 Merge branch 'tickets/DM-13655'
1d5fd08	tickets/DM-13655 origin/tickets/DM-13655 Phase out pex::exceptions::MemoryError.
c8ca3e2	Merge branch 'tickets/DM-13788'
6413135	tickets/DM-13788 origin/tickets/DM-13788 remove dependency on DbTsvStorage
62bd50a	remove dbStorage use from ExposureFormatter
fbf2208	Merge pull request #328 from lsst/tickets/DM-13750
c4da012	tickets/DM-13750 origin/tickets/DM-13750 Move BaseRecordstr_ implementation to C++.
c2958ee	Merge branch 'tickets/DM-13129'
cf3c4ef	tickets/DM-13129 origin/tickets/DM-13129 Stop trying to set None value if default unknown
2e4184d	v15.0.rc1 w.2018.10 Merge branch 'tickets/DM-13680'
0dae580	tickets/DM-13680 origin/tickets/DM-13680 Test the SkyWcs(FrameDict) constructor
ad45ac6	Update test_skyWcs.py to test TAN-SIP persistence
03b8c38	Add bbox arg to SkyWcsBaseTestCase.checkPersistance
a6b0709	Merge branch 'tickets/DM-13534'
bf9fc95	tickets/DM-13534 origin/tickets/DM-13534 Remove unnecessary NumPy C API usage.
af69380	Fix array template parameters.
d12f74c	Rewrite customization of Angle column conversions.
19103d3	w.2018.09 Merge branch 'tickets/DM-10411'
4f3b790	tickets/DM-10411 origin/tickets/DM-10411 Remove special TIMESYS handling in readFitsWcs
0115757	Merge branch 'tickets/DM-12447'
607a0d2	tickets/DM-12447 origin/tickets/DM-12447 Update cameraGeom.dox for new API
b16a45d	Implement RFC-392: Camera & Detector API changes
6b2845b	Fix doxygen warning in camera.py
055735b	O Clang-format detector.cc
	0

Another open source python package



Development Process



 DM Development Workflow with Git, GitHub, JIRA and Jenkins

Project Planning for Software Development

JIRA Agile Usage

JIRA Work Management Recipes

CODE STYLE GUIDES

☐ Introduction to DM's Code Style Guides

Style Guides

Stringency Levels

Deviating from the DM Style Guides

Software Unit Test Policy

C++

DM C++ Style Guide

Documenting C++ Code

Using clang-format for LSST Development

Unit-Testing Private C++ Functions

Using C++ Templates

Using Boost Using Eigen

C++ performance profiling

PYTHON

DM Python Style Guide

Python Unit Testing

Documenting Python APIs with docstrings

Using Astropy

Python performance profiling

Docs » Introduction to DM's Code Style Guides

C Edit on GitHub

Introduction to DM's Code Style Guides

The primary goal of the DM Code Style Guides is to improve readability and thereby the understanding, maintainability and general quality of the code. It is impossible to cover every specific situation in a general guide so programmer flexibility in interpreting the guidelines—in the spirit in which they were written—is essential. Experienced programmers have generally evolved a personal programming style which might have been based on textbook recommendations, other projects' style guides or recognition of the clarity that certain styles obtain. DM developers participated in the creation of the DM style guides; they brought their extensive programming experience into fabricating a uniform style for DM code. New DM developers should use these guidelines to understand and emulate the coding style adopted by DM.

Style Guides

- DM Python Style Guide
- DM C++ Style Guide

In addition, the follow coding guides may help you write code for DM:

Using C++ Templates

Stringency Levels

In our style guides we use RFC-2119-style vocabulary to rank the importance of conforming to a specific recommendation.

REQUIRED

The Rule is an absolute requirement of the specification. The developer needs to petition the DM Software Architect to acquire explicit approval to contravene the Rule.

PROHIBITED

The opposite of REQUIRED.

LIALIS bac TSUM

- Use of style guide for uniformity for both code and git practices
- Style guide itself is a repository subject to same change process as all code repos
- Travis + Jenkins for unit/integration tests
- developer.lsst.io





Lessons and musings



- Make objects (conceptually) immutable whenever you can, python shares everywhere, in big complex systems, it is likely a variable is "owned" elsewhere and hard to trace down side effects happen
- Use interfaces that are separate from implementations (ABCs for example). With the ease of Python programming, unintentional lock-in to a design happens, making refactoring and managing dependencies much harder
- Organize your code according to dependencies, not related ideas. I.E.
 not necessarily attaching functionality as methods or putting a
 function in a low level package to be shared just because it might be
 useful to someone

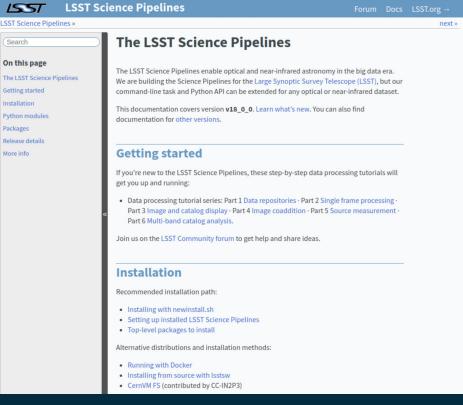




Lessons and musings

- Packages/ci/build systems always take more time than you expect
- Documentation is important, a community culture around docs is key to making sure they are written
- Documentation bit-rots faster than code.
- Test are important, unit tests are not always the best way to test code (note we do love our unit tests), integration tests are often more revealing of relevant behavior
- Linters and the like have really helped saved time, catch bit-rot, and enforce standards





Wrapping up

Rubin Observatory

- We continue to grow alongside the tools we use
- Our goals are to create a welcoming community environment
- All of our software is open source under GPL v3 and developed in the open
- This includes our infrastructure
- We welcome feedback and collaboration
- Best way to ask questions or get in contact is at community.lsst.org under Data Management, you can mention me with @natelust

