



ALICE

Space-charge distortion calibration for the ALICE TPC in Run 3

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Motivation

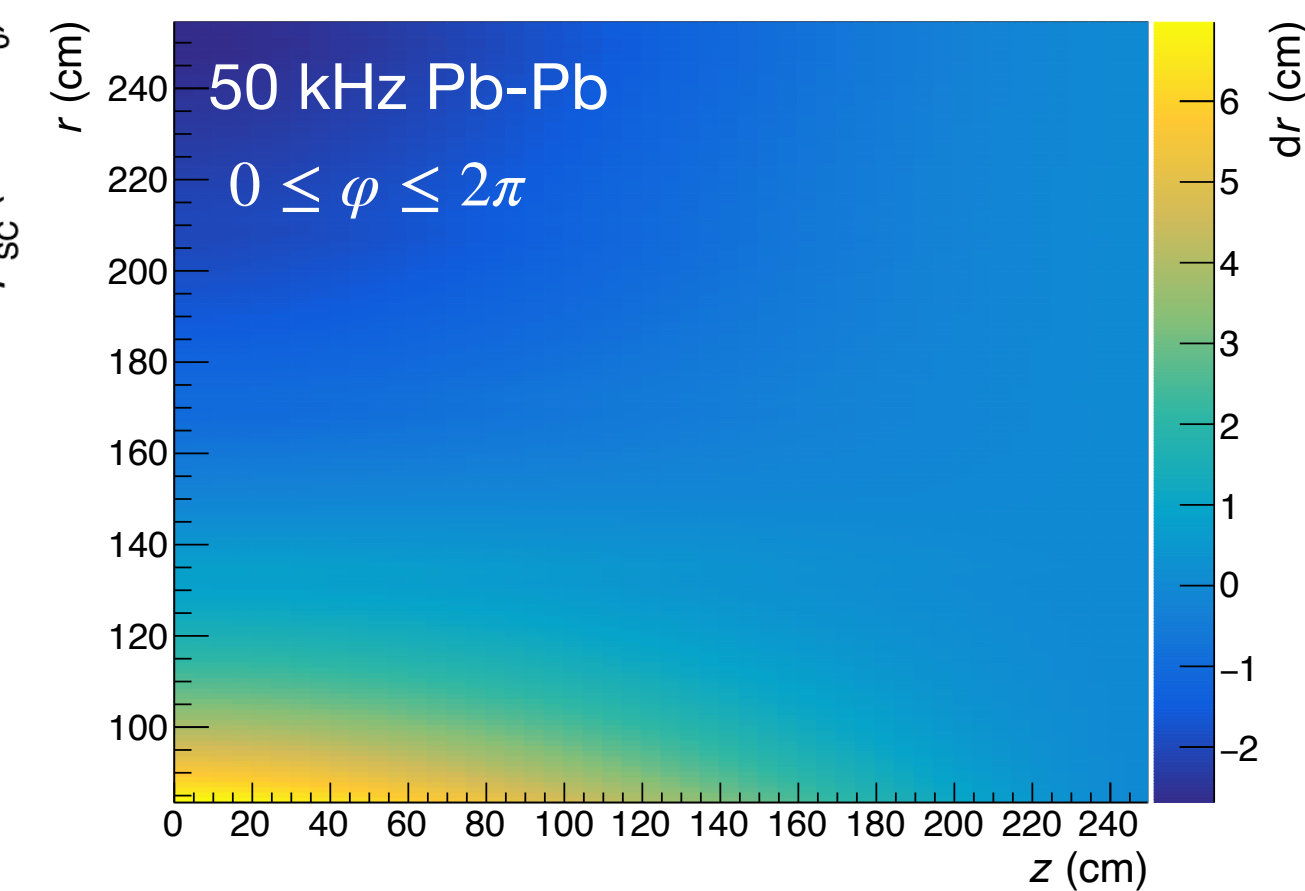
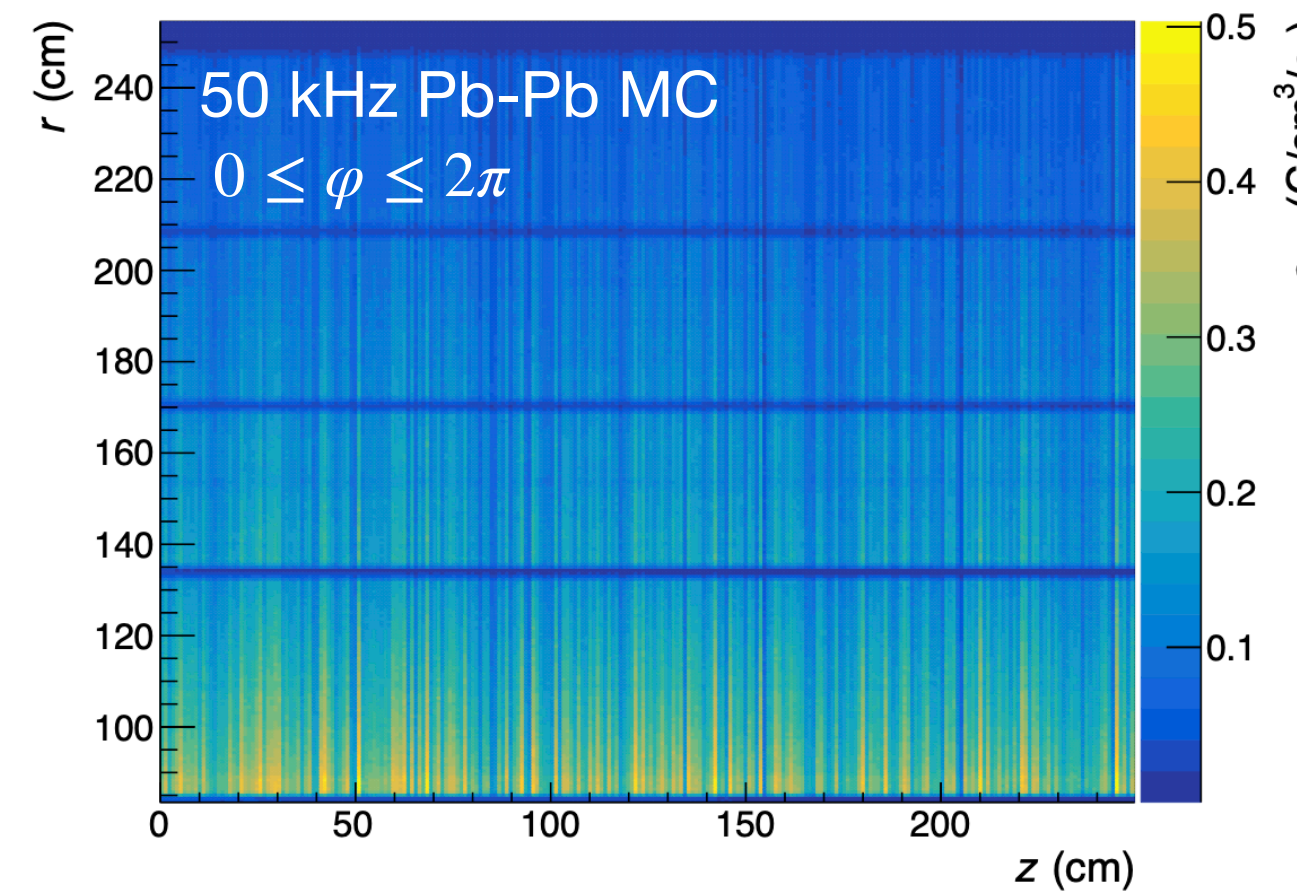
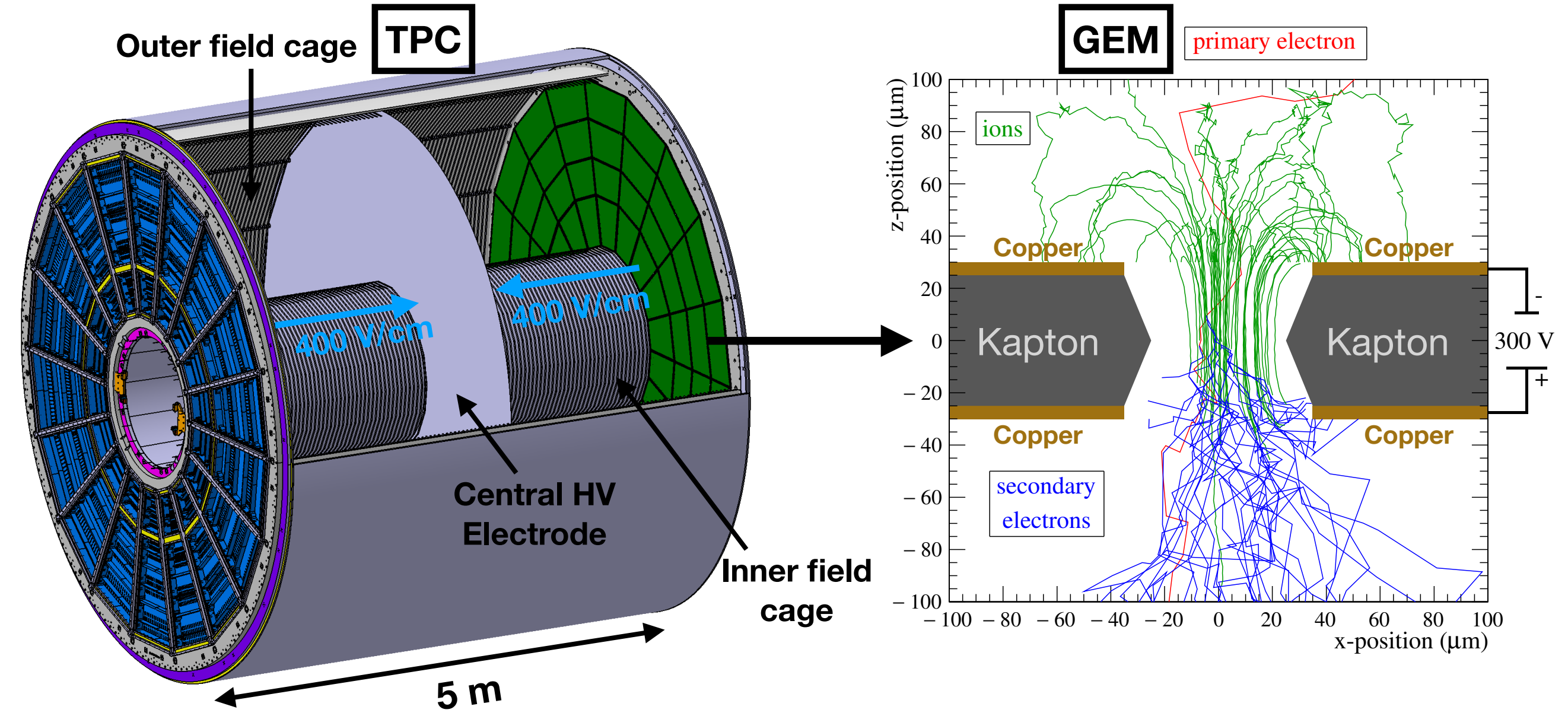
ALICE Time Projection Chamber (TPC)

Detection

- Multiplication of primary electrons
- TPC Upgrade: Stacks of four Gas Electron Multipliers (GEM)
 - ➔ See: [Technical Design Report](#)

Ion backflow (IBF)

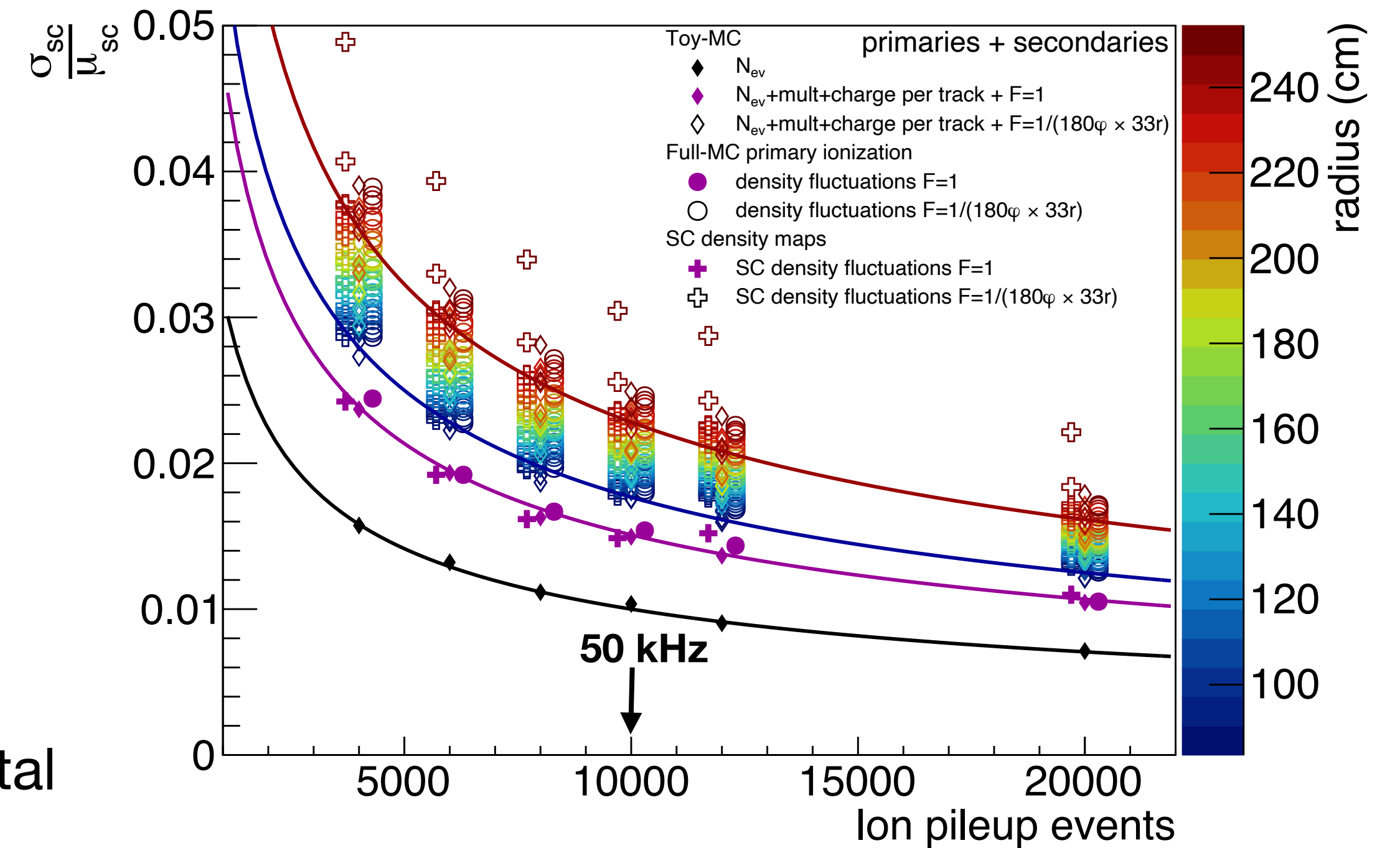
- Ions from amplification enter drift volume
- Slow drift velocity compared to electrons
 - ➔ Ions from n events piling up in the volume
 - ➔ Space-charge density ρ_{SC}
 - ➔ Distortion of electron drift path in r, φ, z
 - ➔ Distortion correction: $dr_{max} \approx 10 \text{ cm} \rightarrow 200 \mu\text{m}$



Space-charge density fluctuations

Space-charge density dependencies

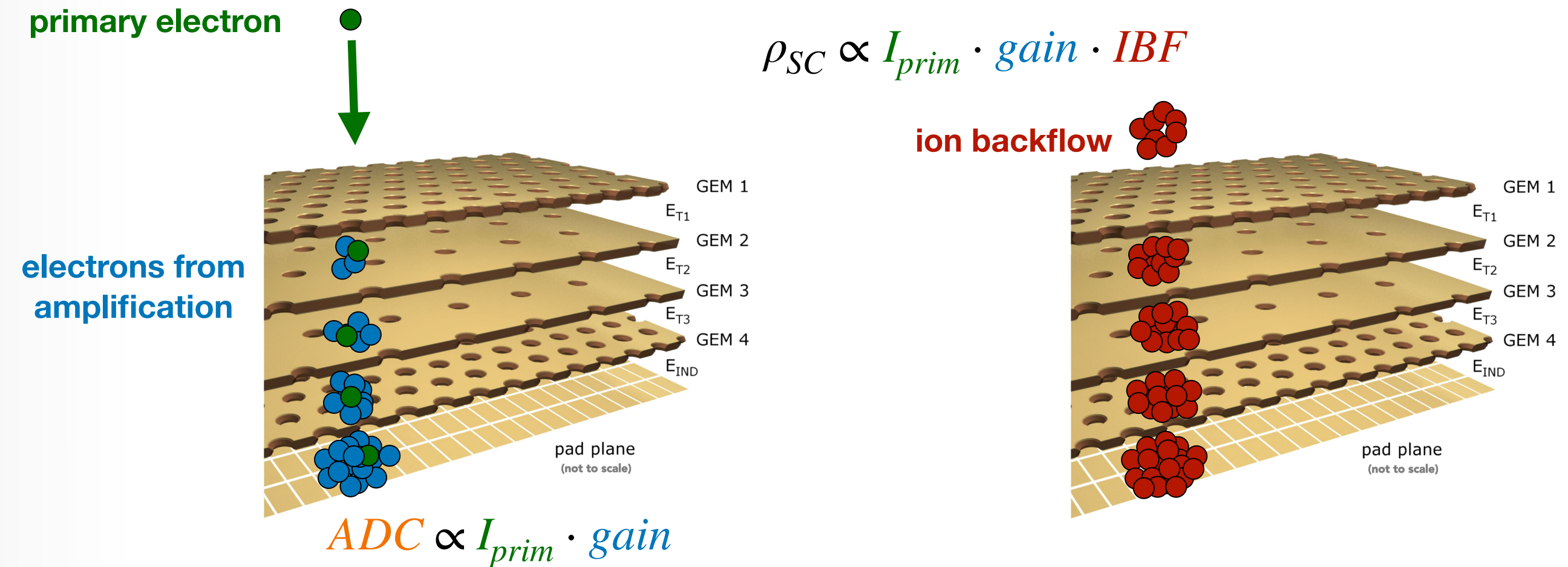
1. Number of ion pile-up events (Poisson distribution)
 2. Primary + secondary track multiplicity per event
 3. Number of tracks per volume element
 4. Energy loss per track
- Analytical formula agrees well with fluctuations from MC
 - Fluctuations of ~2% expected at 50 kHz Pb-Pb
- ➔ Distortion fluctuations ($\mathcal{O}(\text{mm} - \text{cm})$)
- ➔ Correction on time scales of 5ms – 10ms
- ➔ Approximation of density fluctuations with integrated digital currents (IDCs) required for correction procedures



$$\frac{\sigma_{sc}}{\mu_{sc}} = \underbrace{\frac{1}{\sqrt{N_{pileup}^{ion}}}}_{1} \sqrt{1 + \underbrace{\left(\frac{\sigma_{N_{mult,prim}}}{\mu_{N_{mult,prim}}} \right)^2 + \left(\frac{\sigma_{N_{mult,relsec}}}{\mu_{N_{mult,relsec}}} \right)^2}_{2} + \frac{1}{\left(F_{prim}(r) \cdot \mu_{N_{mult,prim}} + F_{sec}(r) \cdot \mu_{N_{mult,sec}} \right)} \left[\underbrace{1}_{3} + \underbrace{\left(\frac{\sigma_{Q_{track,prim}}(r)}{\mu_{Q_{track,prim}}(r)} \right)^2 + \left(\frac{\sigma_{Q_{track,sec}}(r)}{\mu_{Q_{track,sec}}(r)} \right)^2}_{4} \right]$$

Integrated digital currents (IDCs)

- Integration of *ADC* values over ~1ms
- $ADC \propto I_{prim} \cdot gain$
- $\rho_{SC} \propto I_{prim} \cdot gain \cdot IBF$
- Estimate for space-charge density fluctuations
- IDCs to be used for
 1. Input for corrections of distortions
 2. QA of detector



Storage in the CCDB

- Data reduction (1 GB/s → 46 MB/s)
 1. Factorisation of IDCs

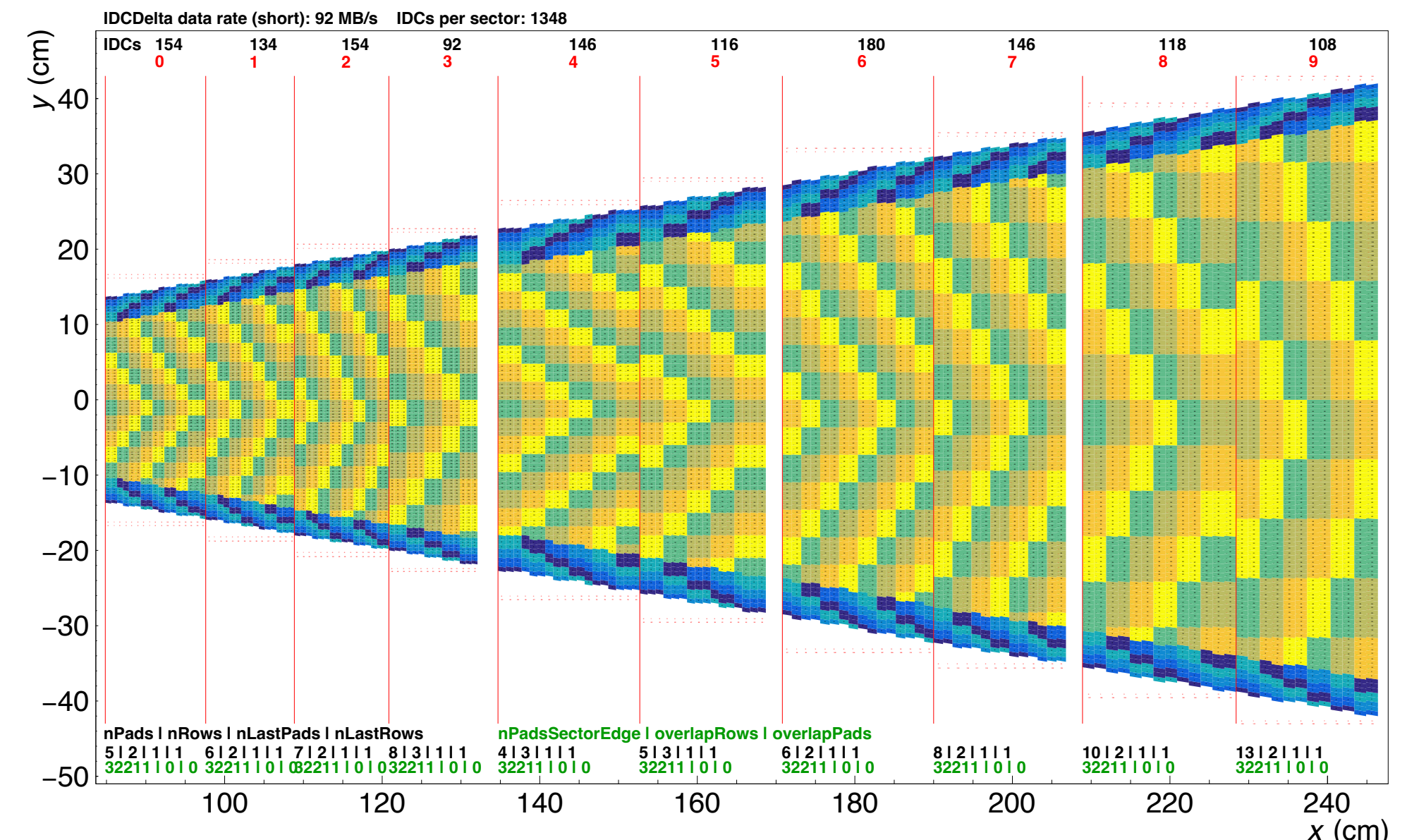
$$I(r, \varphi, t) = I_0(r, \varphi) \cdot I_1(t) \cdot \Delta I(r, \varphi, t)$$

$$I_0(r, \varphi) = \langle I(r, \varphi, t) \rangle_t$$

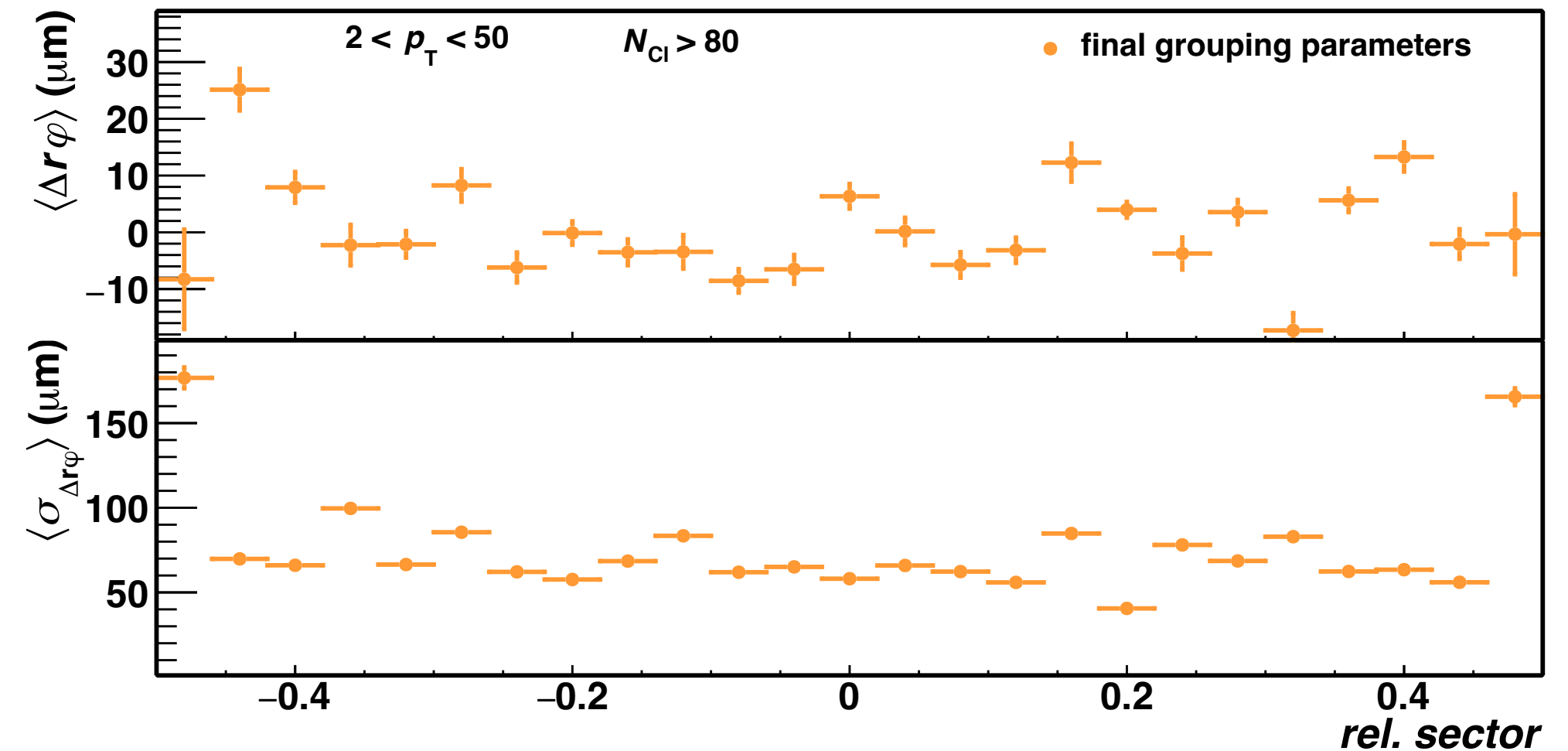
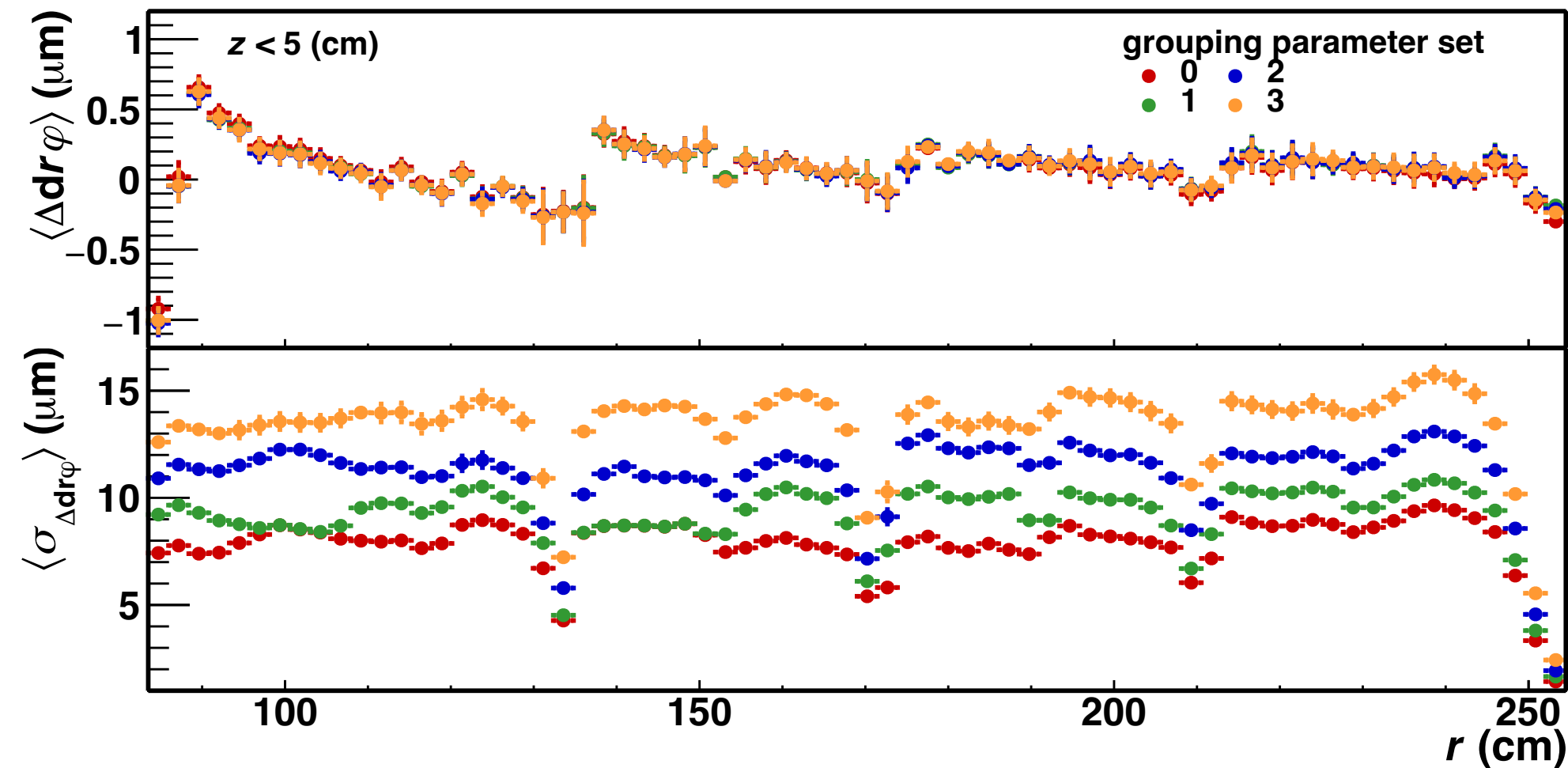
$$I_1(t) = \langle I(r, \varphi, t) / I_0(r, \varphi) \rangle_{r, \varphi}$$

$$\Delta I(r, \varphi, t) = I(r, \varphi, t) / (I_0(r, \varphi) \cdot I_1(t))$$

2. Averaging + compression (char) of $\Delta I(r, \varphi, t)$



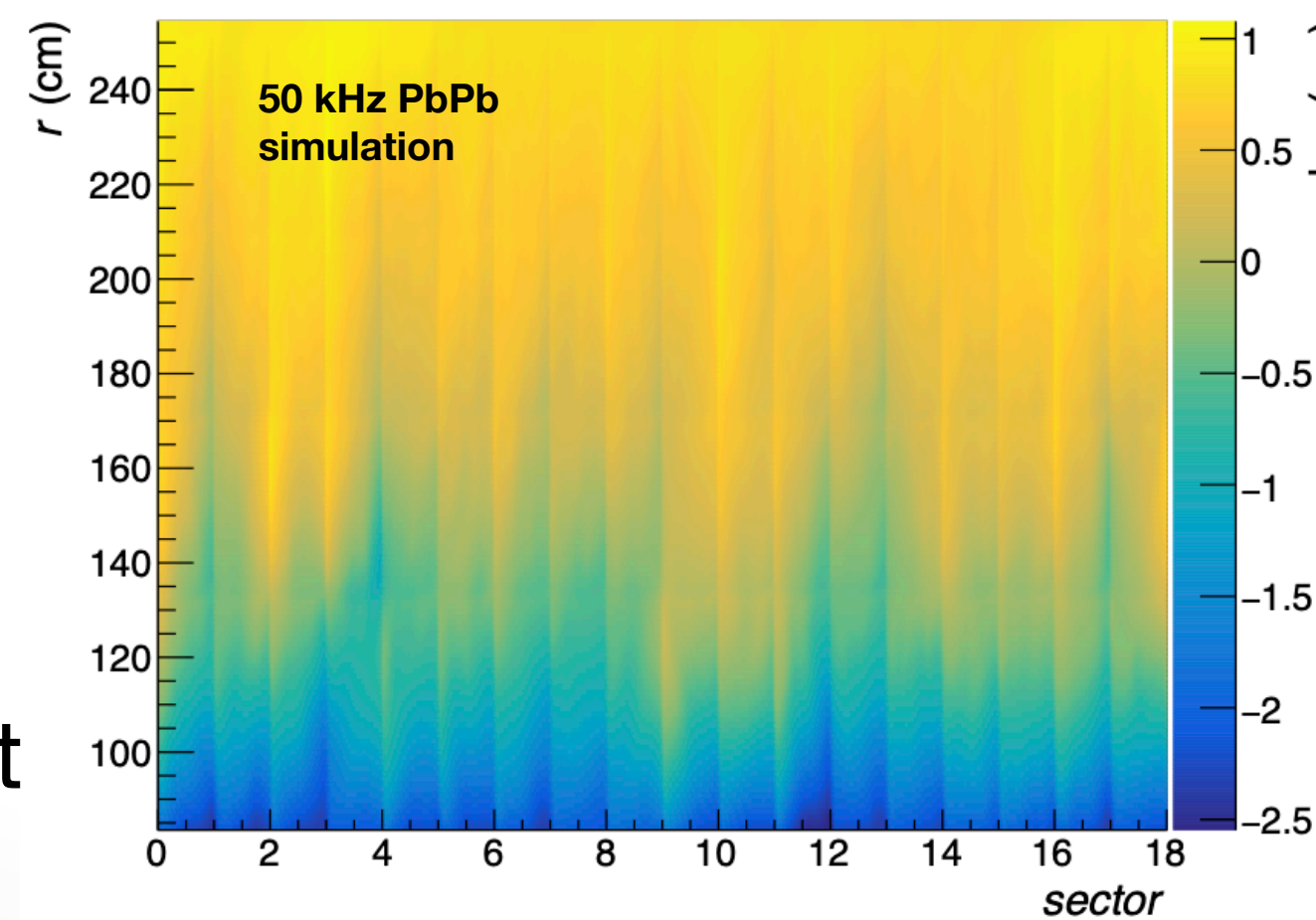
IDCs optimisation



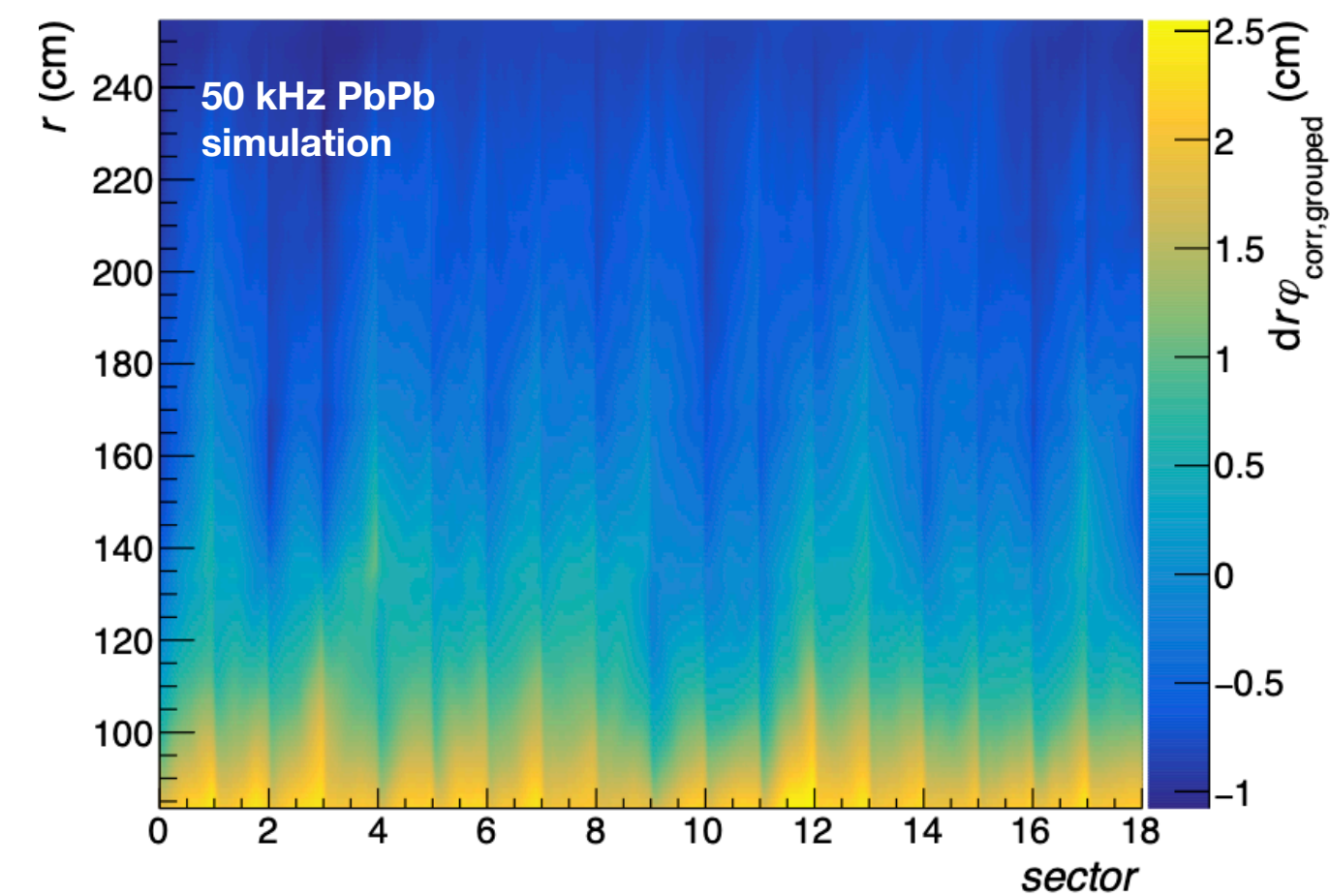
Grouping studies of IDCs

- Comparison of reference distortions with corrections after grouping
- Optimisation of the grouping parameters
 - ➔ Visualisation using RootInteractive
 - ➔ Radial dependency of grouping
 - ➔ Flat $\sigma_{\Delta r_\varphi}$ as a function of radius
 - ➔ Minimisation of track parameter residuals at sector edges

reference space-charge distortions



grouped space-charge corrections



Space-charge distortion calibration

Synchronous reconstruction

Online processing of data
Detector calibration and data compression

Correction of average distortions (calibration interval: $\mathcal{O}(\text{min})$)

Maps from previous calibration intervals

Distortion-fluctuation correction (calibration interval: (5-10 ms))

1D \rightarrow 3D

Asynchronous reconstruction

Offline processing of data
Generation of final reconstruction output

Correction map extracted from data

1D \rightarrow 3D for pp (200 kHz - 1000 kHz)

3D \rightarrow 3D for Pb-Pb

Precision of calibration

$\mathcal{O}(\text{mm})$: tracking

200 μm : intrinsic TPC resolution

1D \rightarrow 3D distortion-fluctuation correction

- Input
 - ➔ Numerical derivatives of the average correction at r, φ, z
 - ➔ Fourier coefficients c_k of 1D-IDCs
- Output
 - ➔ Correction of 1D distortion-fluctuations