

# THE CLICTD MONOLITHIC CMOS SENSOR

**Selected results from test-beam measurements**

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On behalf of the CLICdp collaboration

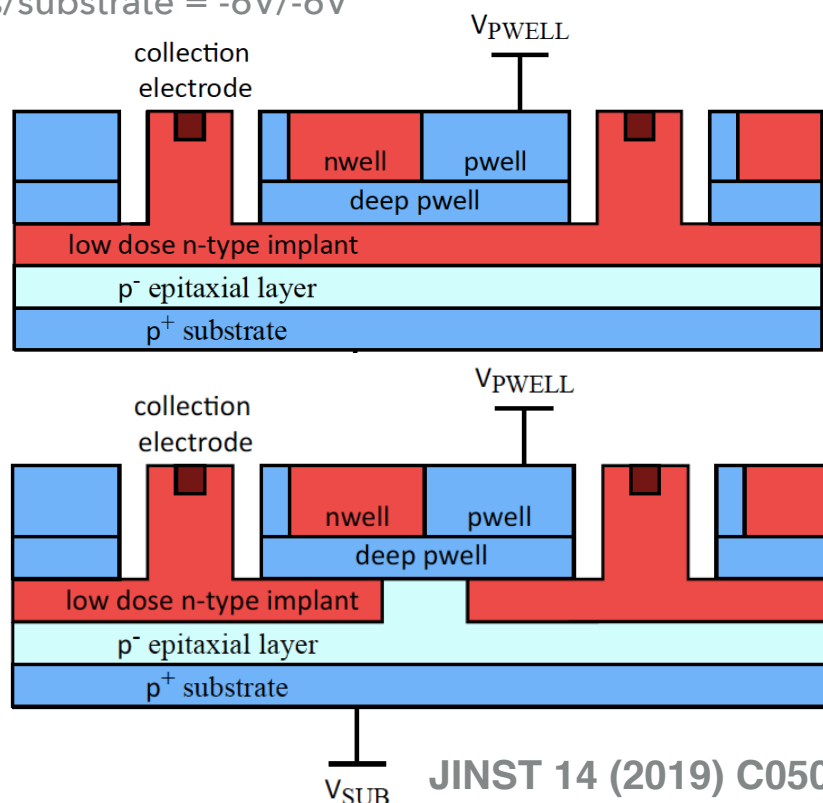
**Vertex 2020**

05/10/2020

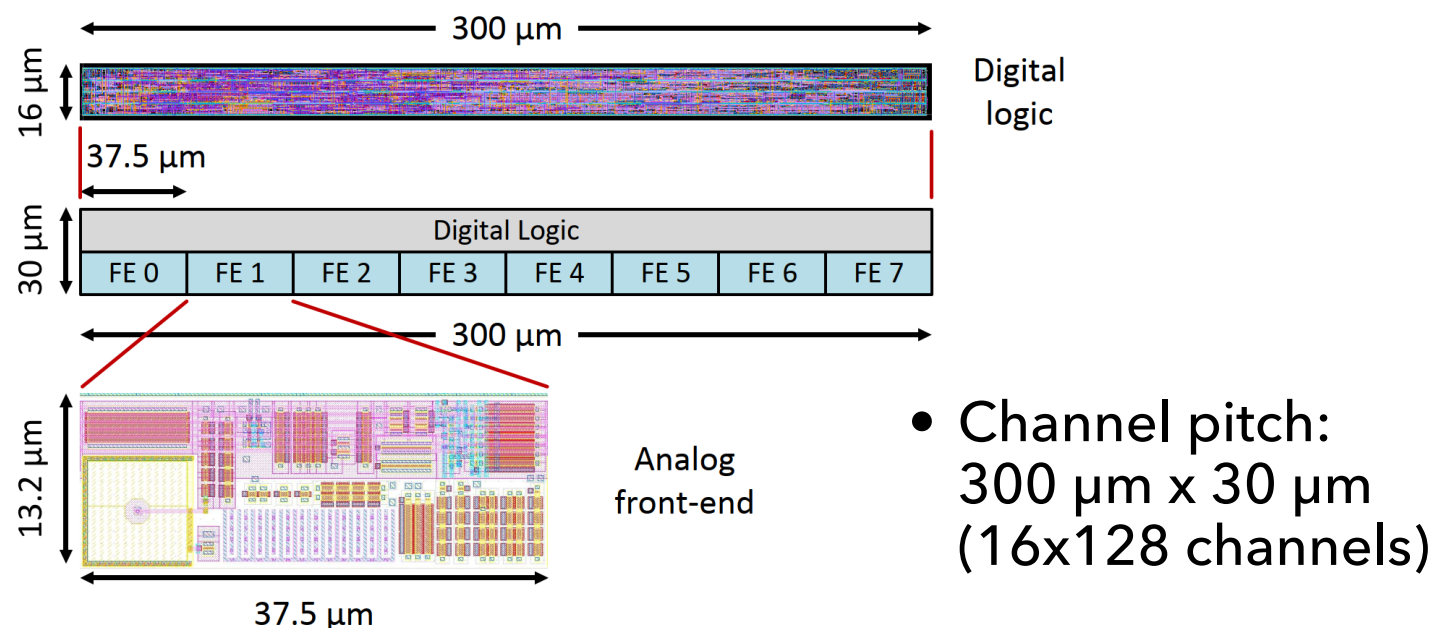


- Modified 180 nm CMOS imaging process with **small collection diode**
- **Full lateral depletion** in 30  $\mu\text{m}$  epitaxial layer
- Optional: **Gap in n-type implant** in one spatial direction:
  - **Speed up of charge collection**
  - Improved **timing resolution**
  - Reduced **charge sharing**

Applied bias voltages to p-wells/substrate = -6V/-6V



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- Channel pitch: 300  $\mu\text{m}$  x 30  $\mu\text{m}$  (16x128 channels)

- Collection electrode pitch: 37.5  $\mu\text{m}$  x 30.0  $\mu\text{m}$
- Detector channel consists of **8 sub-pixels (diode + analogue front-end)** that are processed by a **shared digital logic**
  - ➔ Save space for digital circuitry while maintaining small capacitance and fast charge collection
- 8-bit ToA (10 ns ToA bins) + 5-bit ToT (programmable from 0.6 - 4.8  $\mu\text{s}$ ) (combined ToA/ToT for every 8 sub-pixels in 300 $\mu\text{m}$  dimension)

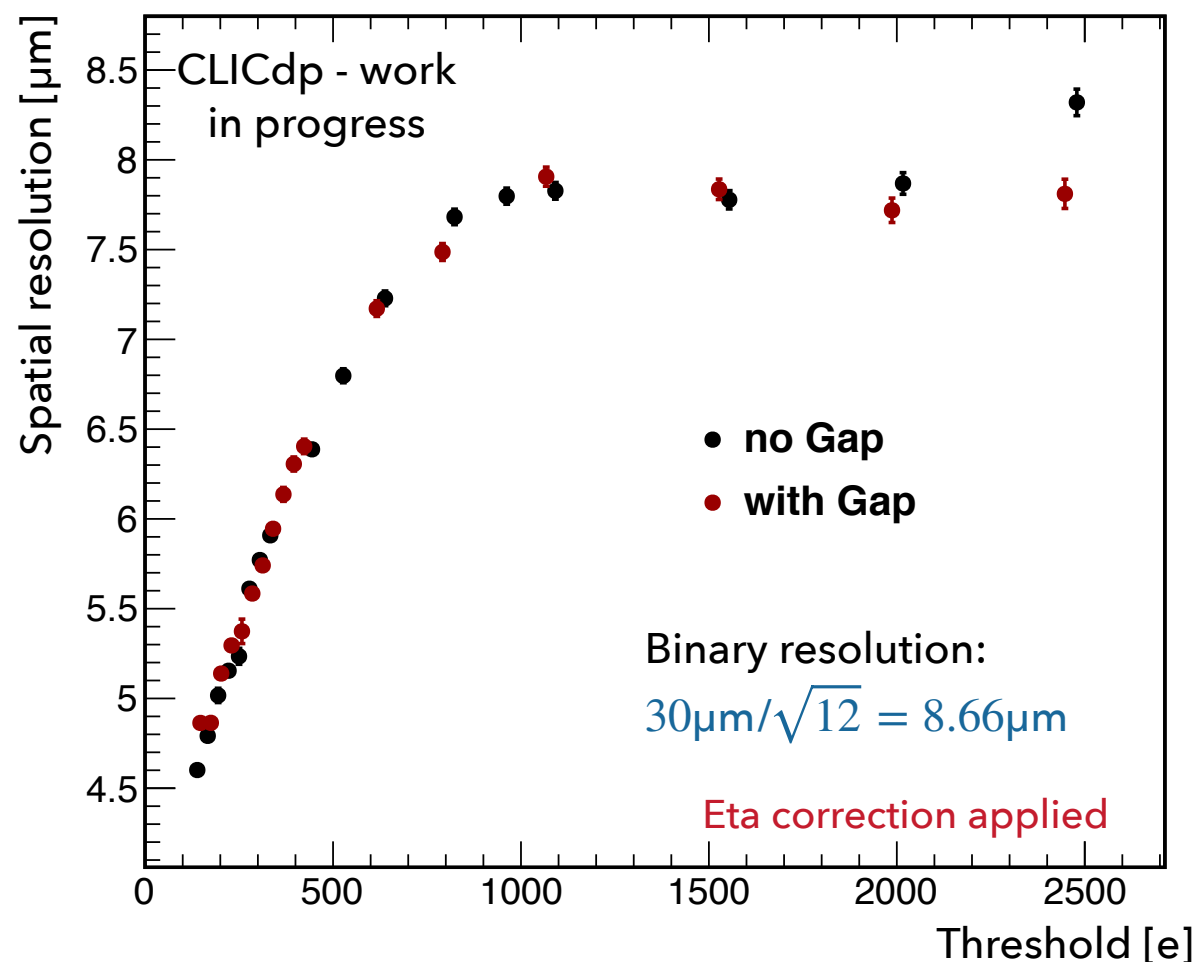
IEEE Tran. Nucl. Sci., August 2020

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# SPATIAL RESOLUTION IN TEST BEAM MEASUREMENTS

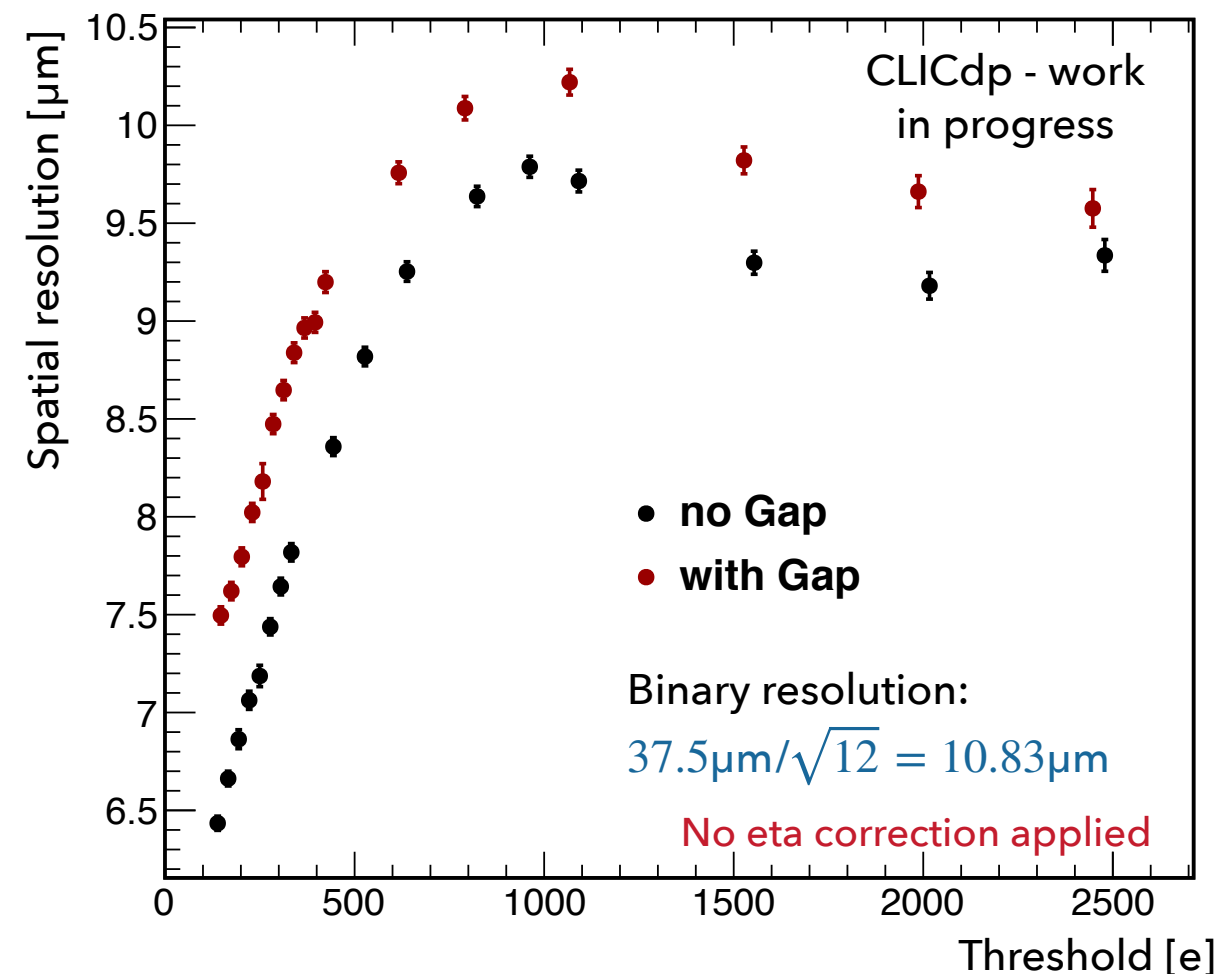
Resolution in short pixel direction (30  $\mu\text{m}$  pitch)

Detector requirement on spatial resolution:  $< 7 \mu\text{m}$



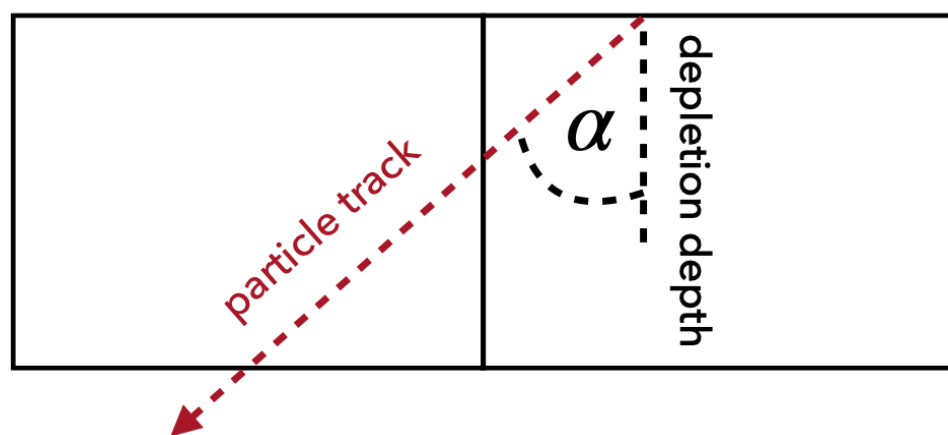
Resolution in long pixel direction (37.5  $\mu\text{m}$  pitch)

No stringent detector requirements in this direction



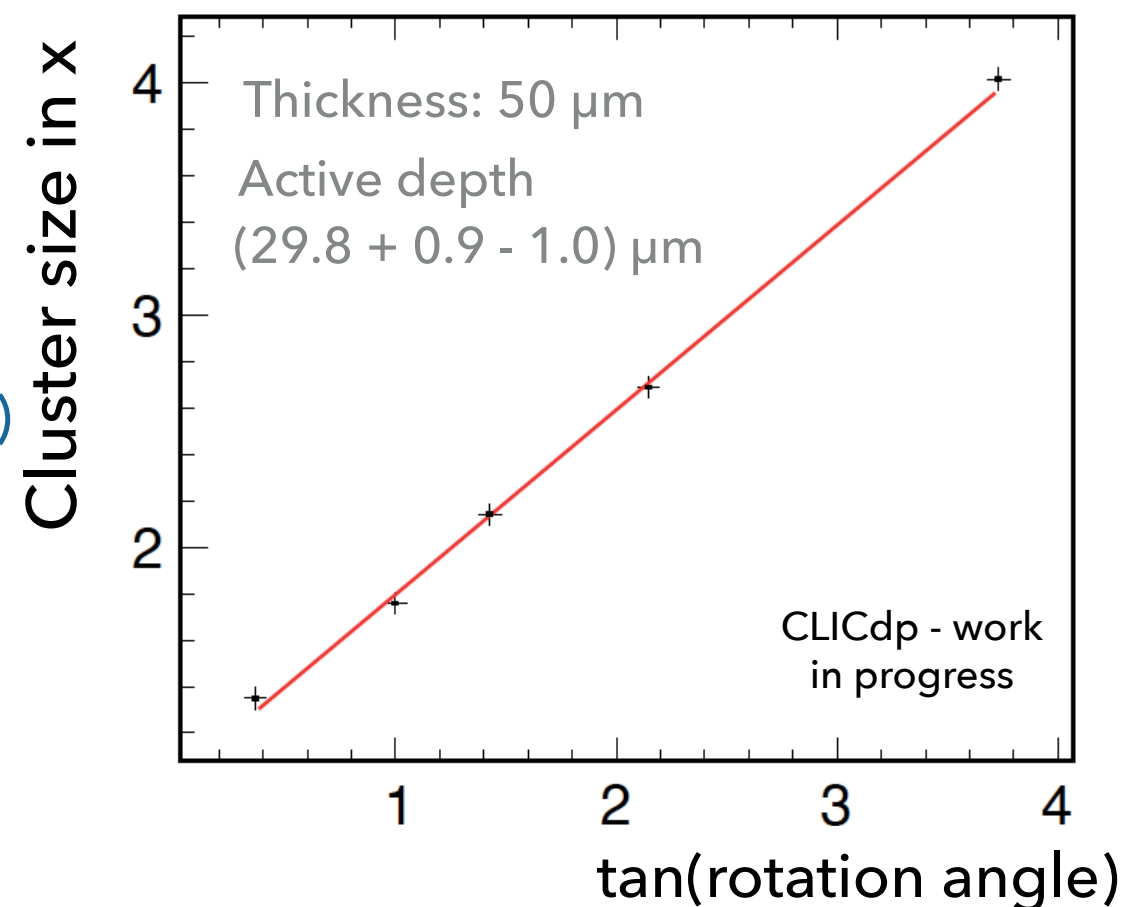
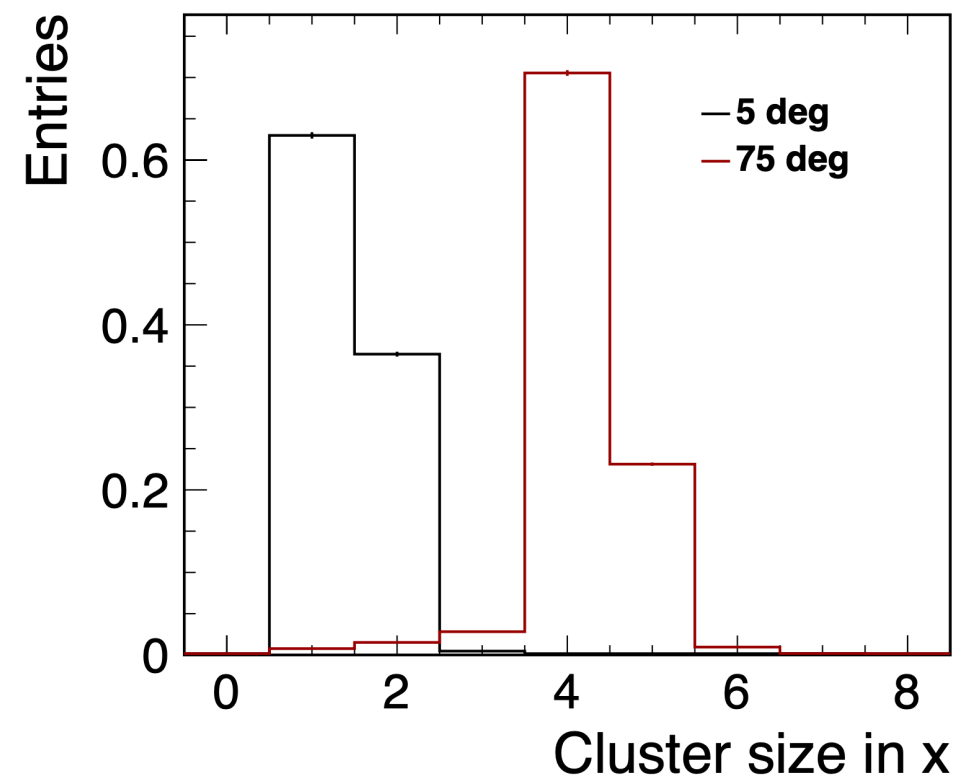
- **Spatial resolution at minimum threshold ( $\sim 140$  e):  $4.6 \mu\text{m}$**  (telescope resolution of  $2.5 \mu\text{m}$  quadratically subtracted)
- **Spatial resolution worsens** with increasing threshold due to **decreasing cluster size**
- **Less charge sharing due to gap in the n-implant** (only implemented in long pixel direction) leads to a smaller cluster size and decreasing spatial resolution
  - Still in line with detector requirements in this spatial dimension

- Cluster size increases for inclined particle tracks since energy is deposited in several adjacent pixel cells
- Active depth can be estimated by rotation-dependent cluster size



$$\text{size}_x = \frac{d_{\text{depl}} \cdot \tan(\alpha)}{\text{pitch}_x}$$

- Active depth of approximately 30  $\mu\text{m}$  was found for assemblies with different thicknesses (50  $\mu\text{m}$  - 300  $\mu\text{m}$ )
  - Thickness of epitaxial layer: 30  $\mu\text{m}$
  - Expected depletion depth: 23  $\mu\text{m}$  (estimated from 3D TCAD simulations)



- The **monolithic CLICTD HR CMOS sensor**
  - Is fabricated in two sensor process variants
  - features an innovative front-end design with a sub-pixel segmentation scheme
- In beam tests, the sensor achieved a **spatial resolution of down to 4.6  $\mu\text{m}$**  and a **timing resolution of 5.8 ns** which fulfil the CLIC tracking detector requirements
- CLICTD has shown to be **fully efficient** up to a threshold of  $\sim 450$  e (min. operational threshold  $\sim 140$ e)
- Optimization studies for **sensors in 65 nm CMOS designs** are currently on-going



Part of the measurements leading to these results have been performed at the Test Beam Facility at DESY Hamburg (Germany)



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