TORCH — simulation and reconstruction















Outline

- TORCH simulation and reconstruction
- Performance in **Upgrade Ib** conditions.
- Performance in **Upgrade II** conditions.
- Primary-vertex timing.
- Physics studies.

TORCH simulation

- A simulation of the TORCH has been developed in the LHCb software framework:
 - An XML detector geometry has been implemented in DDDB to describe the TORCH optical elements.
 - Code has been ported from Geant 4 to GaussRICH to implement surface roughness effects.
- We then persist photons reaching the MCP-PMTs at the output of Gauss and use a standalone reconstruction.

TORCH in LHCb



Module geometry



Data taking conditions

- Simulate $b\bar{b}$ events in **Upgrade Ib** conditions, i.e. an instantaneous luminosity of $\mathscr{L} = 2 \times 10^{33}$ cm⁻²s⁻¹ and a pile-up of μ =7.6.
 - ➡ Generate spill-over from ±2 bunch-crossings.
- Preliminaries studies have also been performed for the Upgrade II luminosity of $\mathscr{L} = 1.5 \times 10^{34} \text{ cm}^{-2} \text{s}^{-1}$.
 - Merge events from Upgrade Ib studies to simulate the conditions, assuming the tracking performance is unchanged.

Reconstruction

- Extrapolate tracks using the **Upgrade Ia** tracking to the front of the TORCH detectors.
 - Compute path length by a cubic spline interpolation between points on the tracks.
 - Assume we have input on the track t₀ from elsewhere (although this can be determined using the TORCH).

Detector performance

- Assume an 8-by-128 effective pixelisation with with 10ps TDC bins.
- Photon arrival time is smeared by an additional 55ps resolution to account for the MCP response and the effect of the readout electronics.
- Apply known efficiency losses, *e.g.* due to QE.



Reminder: pattern in a beam test

• Each track produces a three dimensional image in space and time, *e.g.* from beam test results:

Time projection with beam in center at bottom of plate



PID algorithm

• Use a similar approach to the RICH detectors and compare hypotheses directly using a likelihood calculation.

$$\log \mathcal{L}_h = \sum_{\text{hits}} \log P(\vec{x}_{\text{hit}}, t_{\text{hit}}, h)$$

Determine PDF for given hypothesis by "ray-tracing"

Currently use a "local" per-track algorithm.

• Photon arrival time depends on the track t_0 and particle hypothesis:



Upgrade Ib performance

• TORCH PID performance for module 3 at $\mathscr{L} = 2 \times 10^{33}$ cm⁻²s⁻¹:



• Excellent separation between $\pi/K/p$ in the 2 -10 GeV/c range.

Upgrade Ib performance

• TORCH PID performance for the **highest occupancy** module (module 5) at $\mathscr{L} = 2 \times 10^{33} \text{ cm}^{-2} \text{s}^{-1}$:



• Good separation between $\pi/K/p$ in the 2 -10 GeV/c range.

Combined PID performance

• Combining TORCH and RICH performance in Upgrade Ib scenario:



 TORCH performance dominates at low momentum (p ≤ 10 GeV/c) but we gain from combining TORCH and RICH 2 information at intermediate momentum.

Upgrade II performance

• TORCH PID performance for module 3 at $\mathscr{L} = 1.5 \times 10^{34} \text{ cm}^{-2} \text{s}^{-1}$:



Performance is robust against higher detector occupancies.
See only a small drop-off in performance in Upgrade II conditions.

Upgrade II performance

• TORCH PID performance for the **highest occupancy** module (module 5) at $\mathscr{L} = 1.5 \times 10^{34} \text{ cm}^{-2} \text{s}^{-1}$:



Performance comparison

- Comparison of performance between
 Upgrade Ib and
 Upgrade II scenarios.
- We are able to modify the pixelisation in the central region of the detector to recover the performance in Upgrade II. The optics would remain unchanged.



Primary vertex timing

- Per-track likelihood depends on the assumed particle hypothesis t₀.
- For a given hypothesis, can maximise the likelihood to determine t₀.
- Can combine individual track likelihoods to determine vertex level t_{0:}
 - Try each particle hypothesis in turn and pick the best hypothesis for each track.
- Combined resolution is ~15ps.



Physics studies

- Two benefits from TORCH:
 - Get improved π-K separation at low momentum due to positive kaon identification.
 - Gain *p-K* separation below 10 GeV/*c*.
- Illustrate performance in the **Upgrade Ib** scenario using:
 - 1. Baryonic decays.
 - 2. Semileptonic decays.
 - 3. Flavour tagging.





• Momentum distribution of stripped candidates in simulated $\Lambda_b \rightarrow J/\psi p K$ decays:



 Can increase efficiency by about 25% using RICH+TORCH PID rather than the PID requirements used in the current analysis.

+ $J/\psi pK$

• Gains at low-momentum improve the uniformity of Dalitz observables.





 Also expect to see significant gains at high q² in semileptonic decays, where the energy of the hadronic system is small:



 This is the q² range where the most precise theoretical predictions are available (from Lattice QCD).

Flavour tagging

- Develop simple cut-based tagging algorithms to test performance of the TORCH:
 - ➡ Taggers use momentum requirements, RICH and TORCH PID.
- Effective tagging power:

$$B_s^0 \to D_s^+ \pi^-$$

	Nominal	with TORCH	Perfect
SS Kaon	$1.20\pm0.05\%$	$1.52\pm0.05\%$	$1.61\pm0.05\%$
OS Kaon	$1.29\pm0.05\%$	$1.73\pm0.05\%$	$1.80\pm0.05\%$

 $B^+ \to J/\psi K^+$

	Nominal	with TORCH	Perfect
SS Kaon	$1.06\pm0.05\%$	$1.51\pm0.05\%$	$1.61\pm0.05\%$

Summary

- The TORCH detector provides particle identification in the 2-20 GeV/*c* momentum range.
- A simulation of the TORCH has been developed in the LHCb framework.
- Good performance is seen in **Upgrade Ib** and **Upgrade II** conditions.
- Work is ongoing to make the simulation more realistic and to understand what detector configuration is needed for **Upgrade II**.

Finally, we would welcome interest from anyone who would like to join the TORCH project.

Detector efficiency

- Accept-reject photons based on measured transmission/reflection/ QE of the detector.
- Additional losses in the simulation from packing of MCP-PMTs (53/60) and the geometry of the bar and focussing optics.



Detector occupancy

 In the Upgrade Ib data taking conditions the per-pixel occupancy is 5-20%, depending on the module (highest in the most central modules).



Material

• Material scan from Gauss:



- Increases the amount of material in the acceptance by ~0.1 X_0 .
- Note, no support structure is currently included.

Background photons

 Large number of background photons produced by charge particles from material interactions in the detector.



Acceptance behind RICH 2

• Extrapolated track position behind RICH 2:



• At least two additional modules per half needed to cover acceptance. Increase module height by 25% to accommodate detector.

TORCH behind RICH 2

 Comparison of true and reconstructed track entry position/angle.



Backscattering

- Implemented an ad-hoc model of photoelectron backscattering:
 - 1. Assume an MCP gap of 1.5mm and voltage of 200V between the photocathode and MCP foil to determine *t*_{max}.
 - 2. Smeared resulting time distribution with Gaussian.
 - 3. Assume a backscatter probability of 15% from the foil.
- Can also consider producing a more complete simulation of this effect in GEANT4.



PID performance: backscattering

- Backscattering model is applied to simulated photons but ignored in the likelihood calculation.
- Results in a small degradation of the PID performance.



PID performance: to smearing

 Re-evaluate performance smearing track t₀ by 15ps.



Dependence on photon yield

- Scaling the photon yield by 2/3 reduces slightly the separation.
- Still have a good $\pi/K/p$ separation at low momentum.



Dependence on resolution

 Performance is also robust against changing from 55ps to 70ps smearing (of the hits and the pattern).



Front-end emulation

- For pixel hit creation:
 - 1. Evaluate charge sharing (creates 0, 1 or 2 pixel hits).
 - 2. Smear each hit (independently) by 55ps.
- For deadtime:

Should we also consider a correlated component?

- 1. Consider hit pixels only if they are within desired 25ns window.
- 2. Reject hits if the pixel was hit by another photon in range $[t t_{deadtime}, t]$.
- For clustering follow similar approach to test beam:
 - 1. Loop through hits and create 1 pixel clusters.
 - 2. Merged clusters if hits are within 200ps.
 - 3. Repeat step (2.) until no more clusters can be merged.
 - 4. Take an (unweighted) average of the cluster position/time.

Front-end emulation

- Significant degradation in performance with a 25ns deadtime in high occupancy modules.
- There are several reasons for degraded performance:
 - Clustering merges photons together, biasing photon hit positions.



- 2. Deadtime reduces per-photon signal efficiency (and can bias photon position).
- 3. Effect of dead time is much worse at 25ns since hits from previous bunch-crossing can cause dead time in current bunch crossing.